



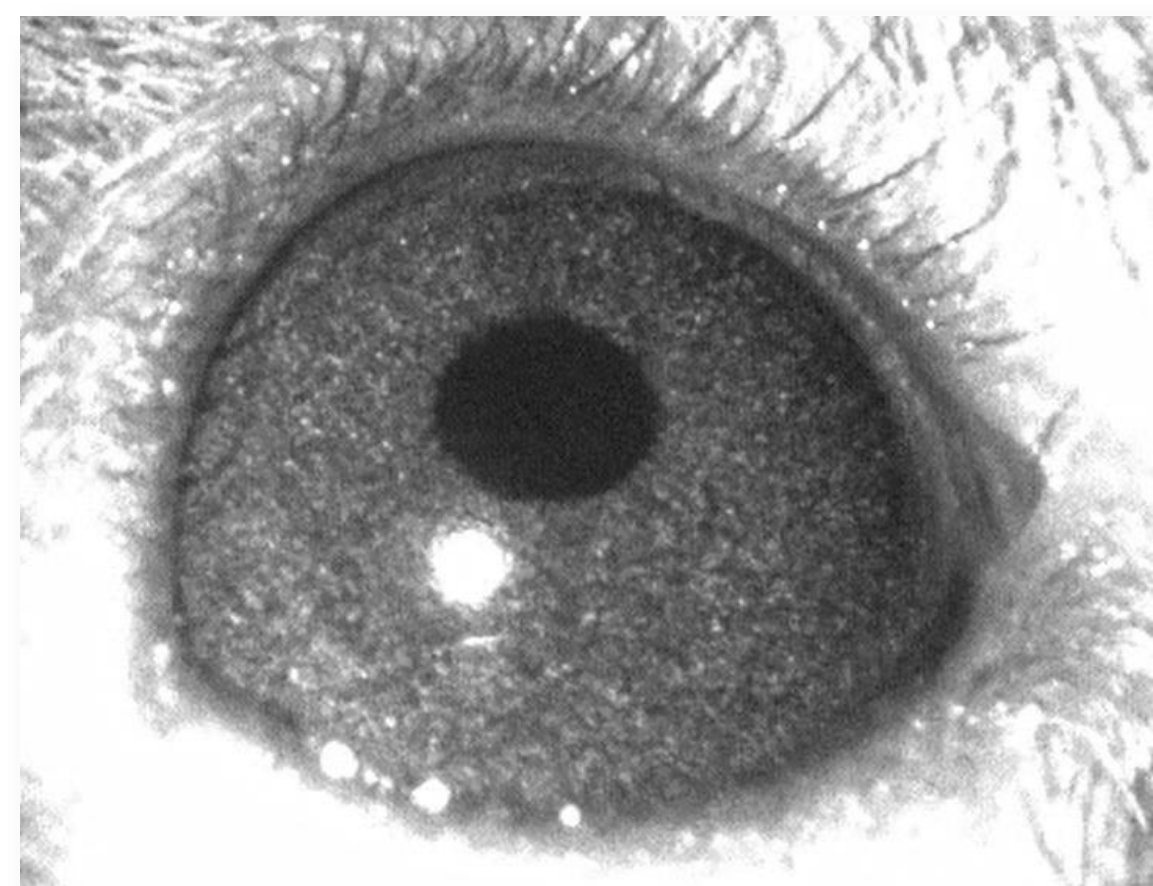
Summary and Motivations

To give precise context to experiments investigating the visual cortex, it is necessary to delineate the particular sub-image of the stimulus incident on the retina – this is accomplished by the incorporation of eye position information. Here we present the eye tracking package **iTracker** which we combine with our hardware to create an integrated platform to collect eye tracking data across multiple modalities in a standardized and scalable manner. We further demonstrate the importance of eye tracking incorporation as pertains to receptive fields.

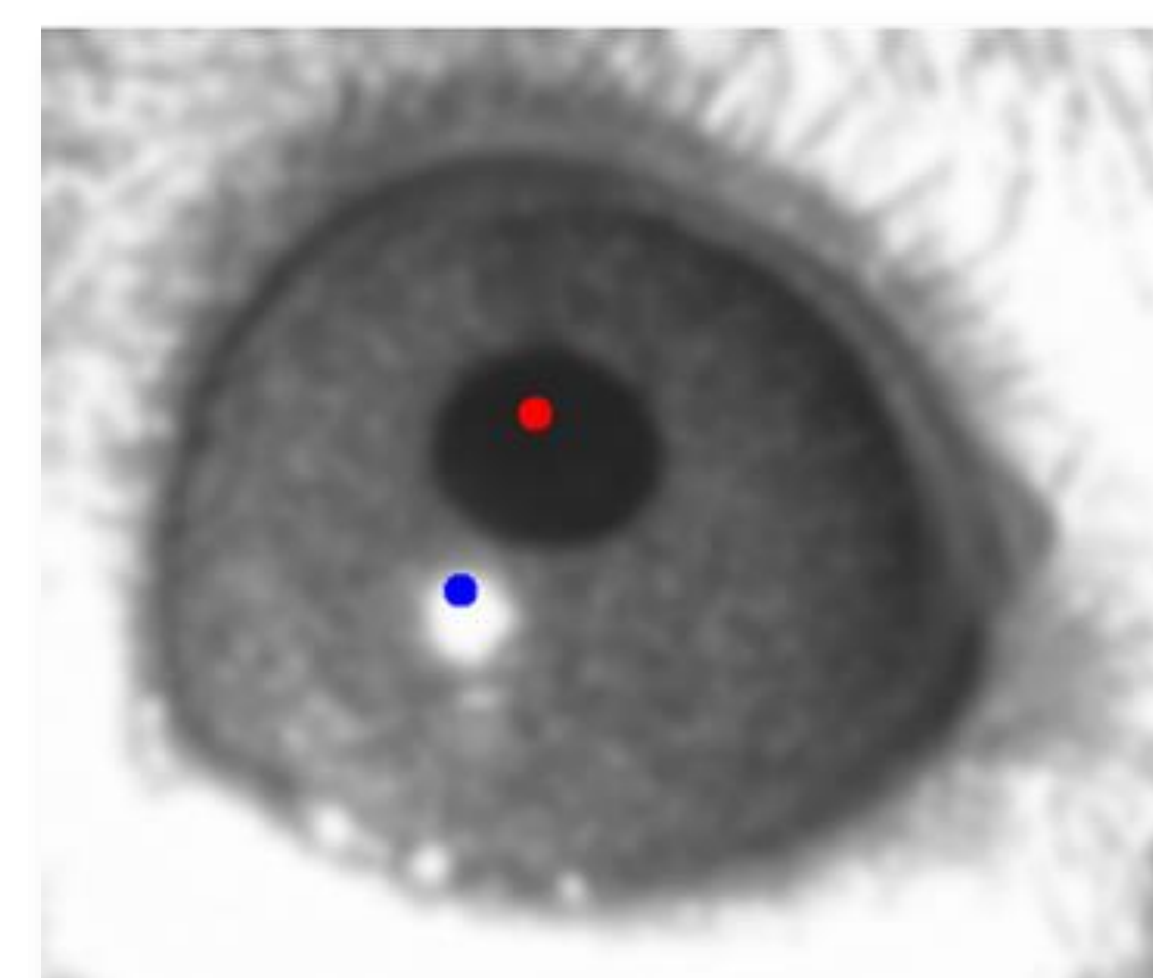
iTracker Software and Starburst Algorithm

For our pipeline, we adapted the **Starburst Algorithm** originally described by Li D., Winfield D., Parkhurst D.J. (2005).

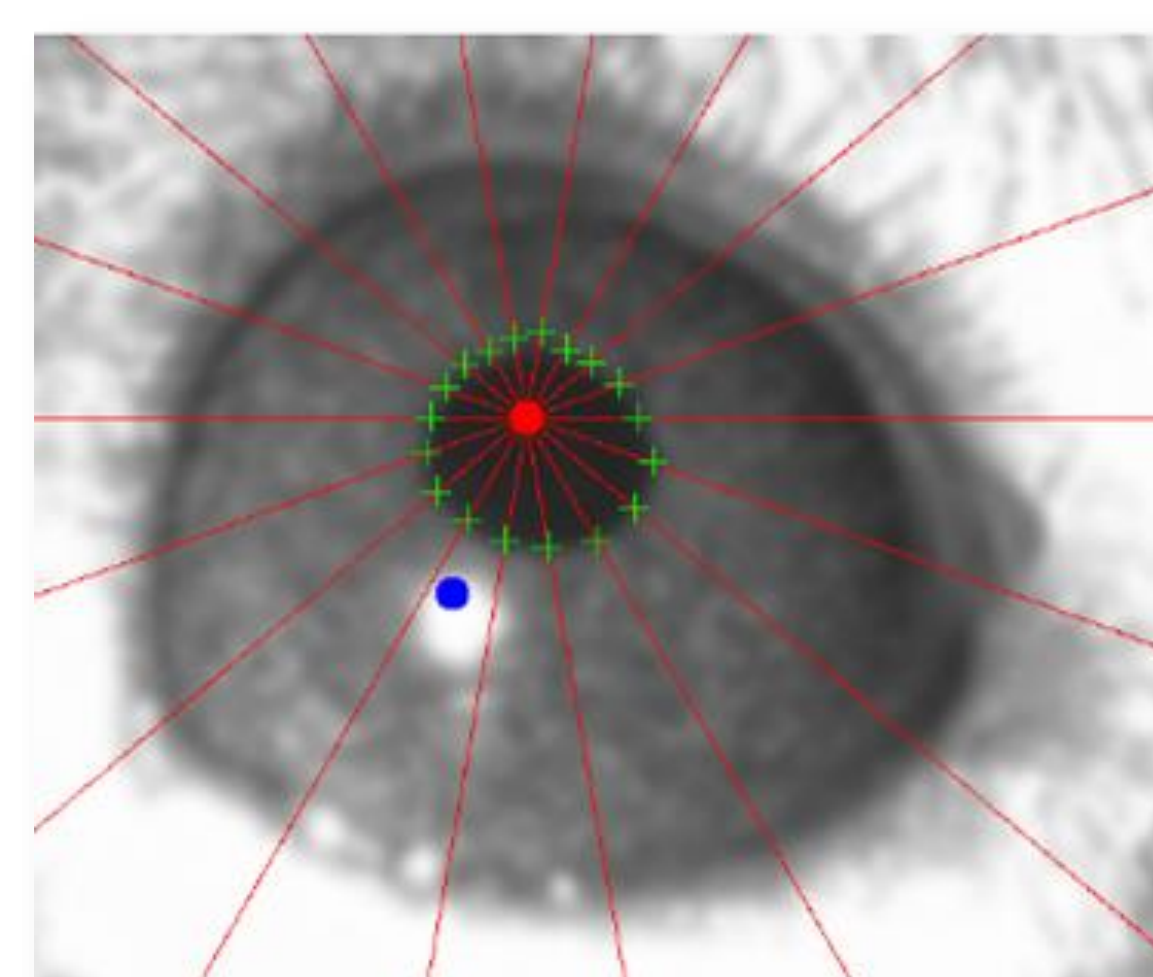
Figure 1: A visual flowchart of the iTracker processing pipeline



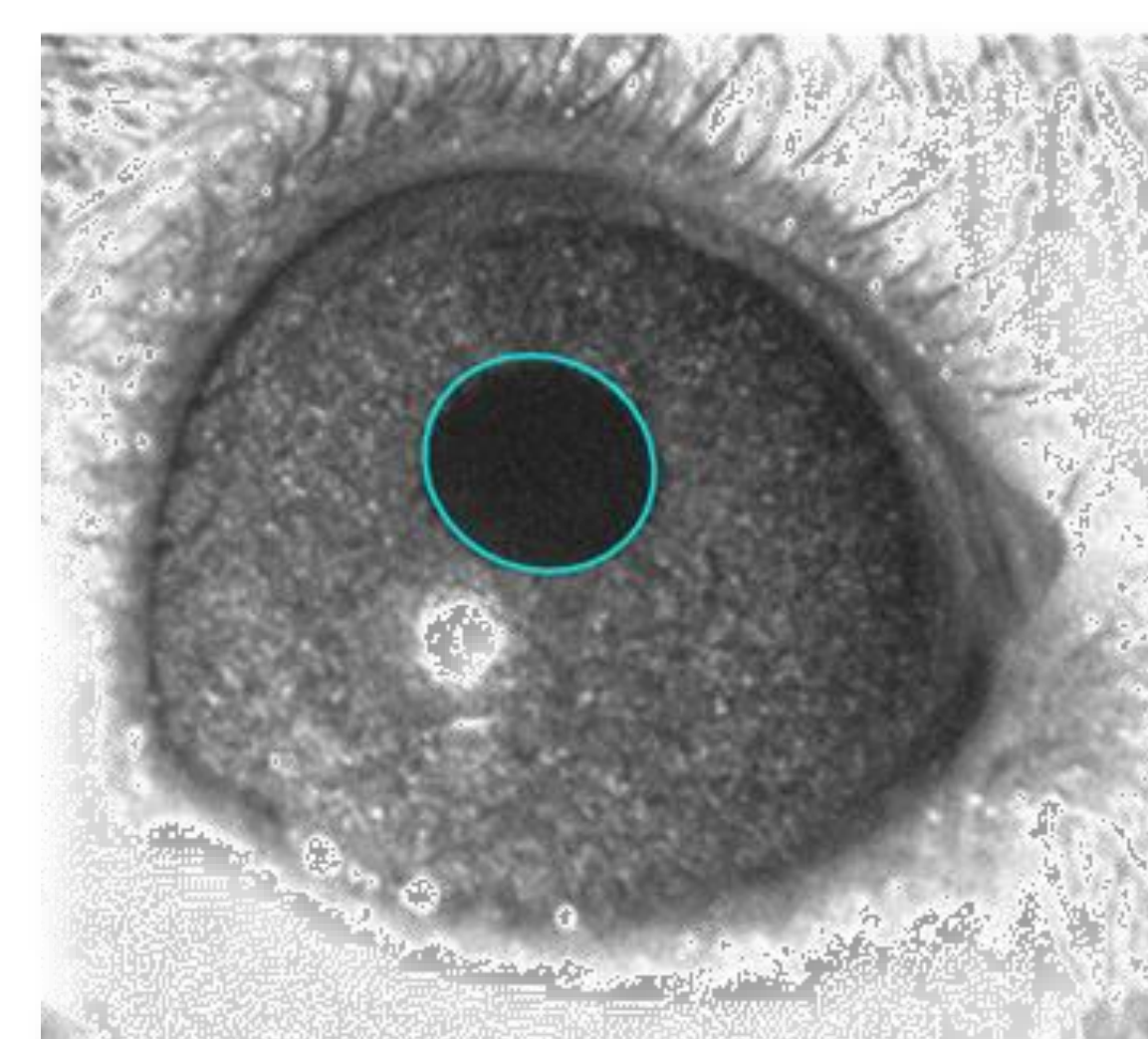
Images of the eye are obtained by the use of an IR-camera and IR-LED pointed at an IR-pass dichroic mirror that is coplanar with the mouse's eye. Each frame is extracted from the video and a bounding box is created around the eye and is used for all other frames.



The frame is then smoothed with a *median filter* and convolved with a black circle and white circle to find the pupil and corneal reflection (CR) respectively; the max convolution responses are the **seed points** for the *Starburst Algorithm* (red and blue dots for the pupil and CR respectively).



At each seed point, the Starburst Algorithm creates **rays**. Along each ray (from origin to radially outwards), a running average is calculated – when the pixel value exceeds some product of the running average pixel value μ_{pix} and a user supplied a parameter θ , a candidate point (small green cross) is marked (see equation below).

$$\tau = \theta * \mu_{pix}$$


Candidate points are passed to a *random sample consensus* (RANSAC) which fits an ellipse. Using the ellipse parameters for both seed points, and knowing the geometry of our experimental rigs, we can determine pupil position and radius.

2-Photon Hardware Set-up

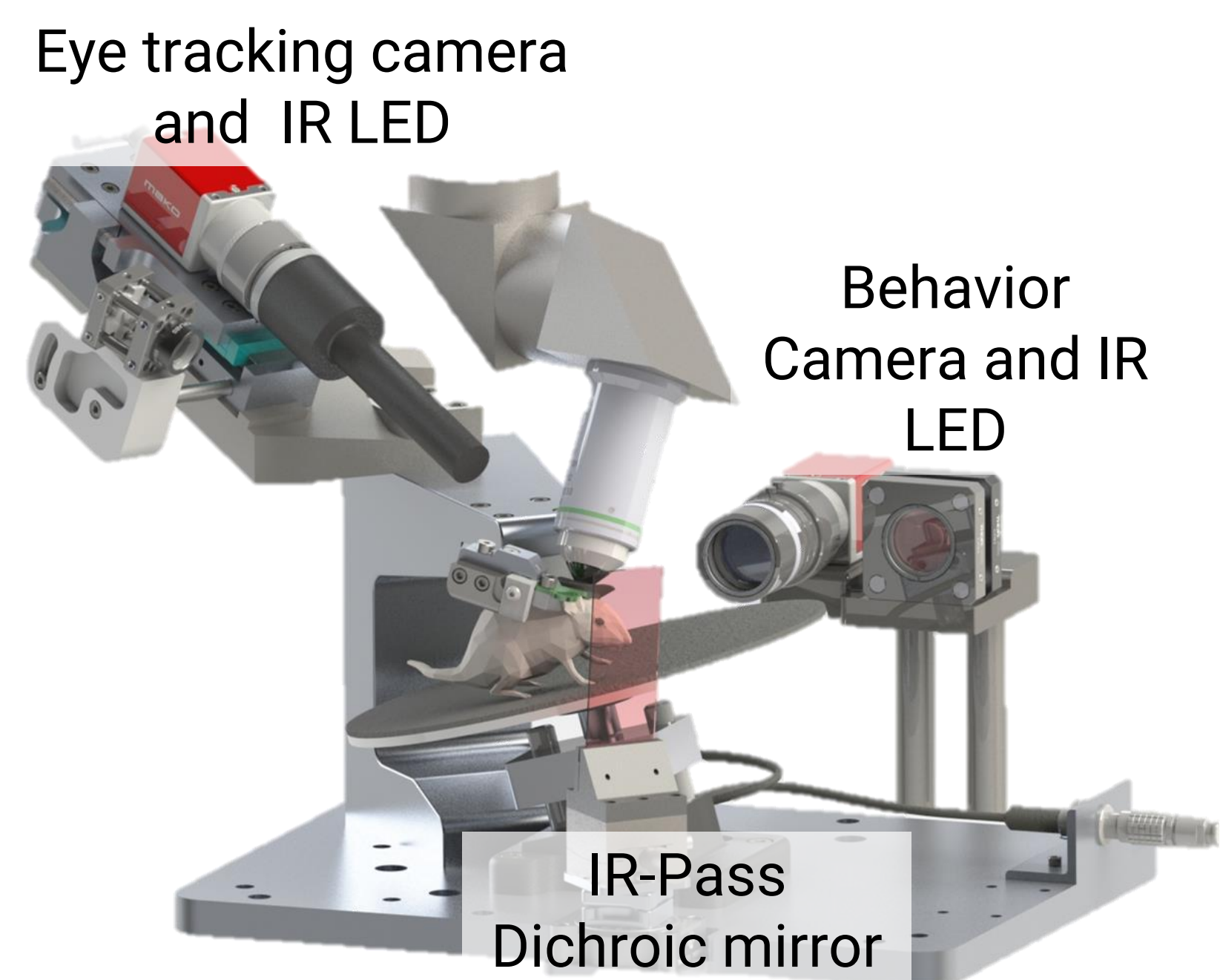
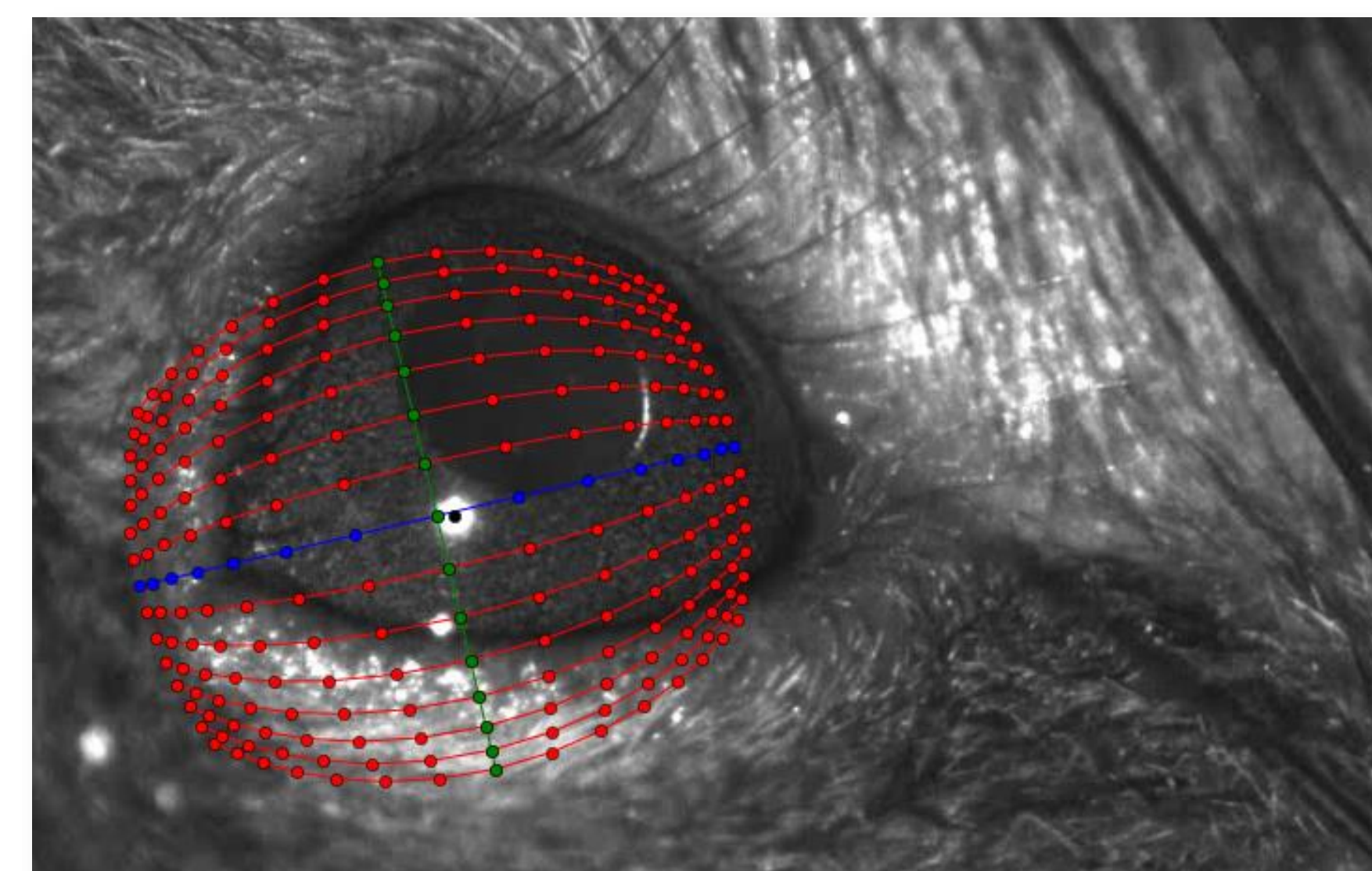


Diagram of standardized eye tracking set-up on the 2-photon platform

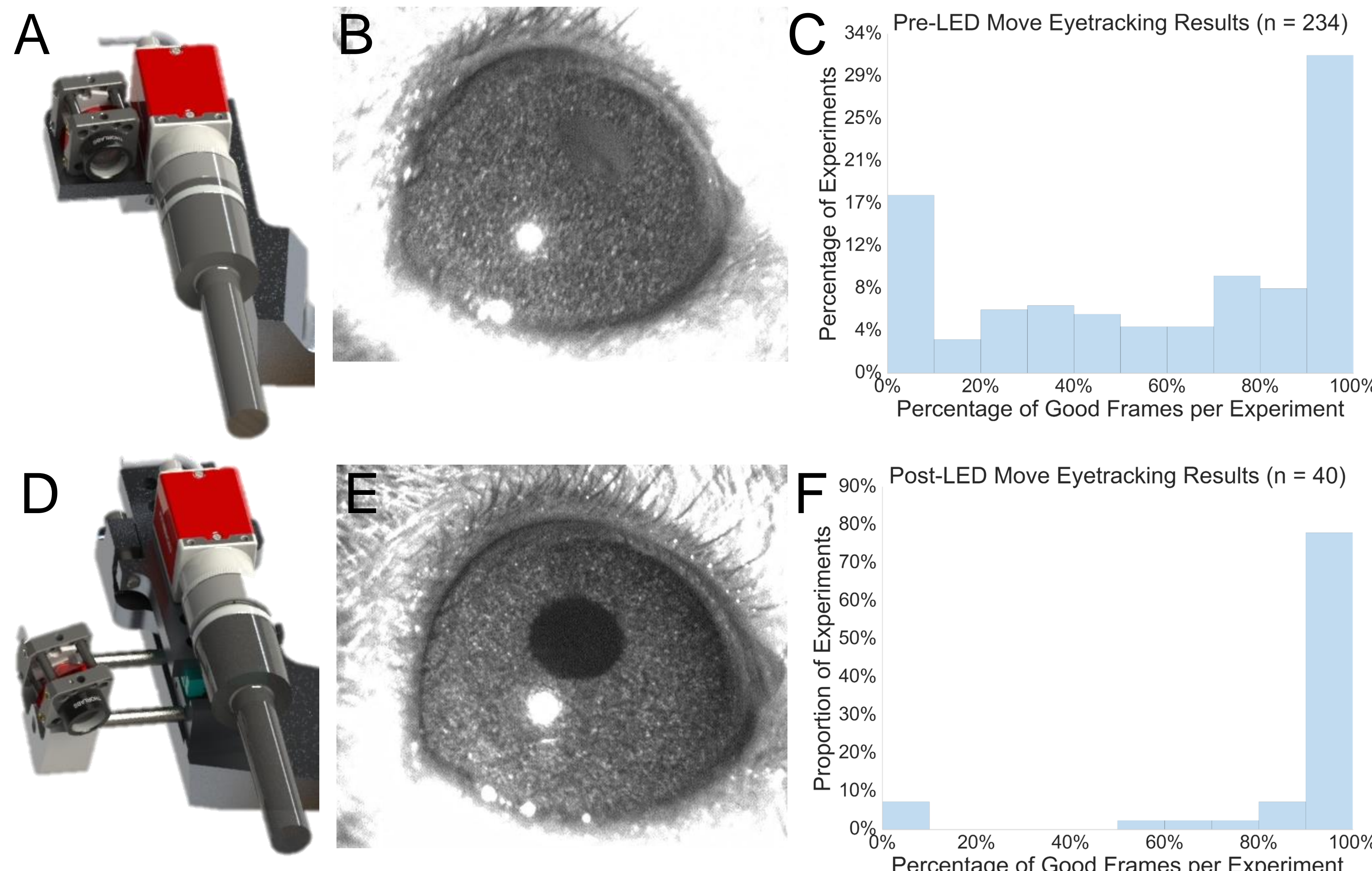
The eye tracking set-up has identical geometry across all five *in vivo* imaging rigs (and other modalities such as widefield and *in vivo* electrophysiology) of the Allen Brain Observatory pipeline enabling the collection of comparable data. It consists of an eye tracking IR-camera positioned 15° away from an IR-LED and directed at an IR-pass dichroic mirror. This mirror is positioned perpendicularly to the eye to allow for eye tracking while not impeding stimulus viewing.



Mapping pupil position to the center of gaze on the stimulus screen

The eye position of the mouse is inferred by taking the center of the pupil ellipse and finding its projection (using the spherical mirror equation) from the spherical eye onto the flat screen assuming an eye diameter of 0.17 cm. From this calculation, a grid can be created which can be used to calculate the position of gaze from the pupil position. The LED corneal reflection is used as a fiducial mark to align the center and orientation of the grid given the known angular offset between the LED and camera. From this, the center of the pupil can be used to estimate the position of gaze.

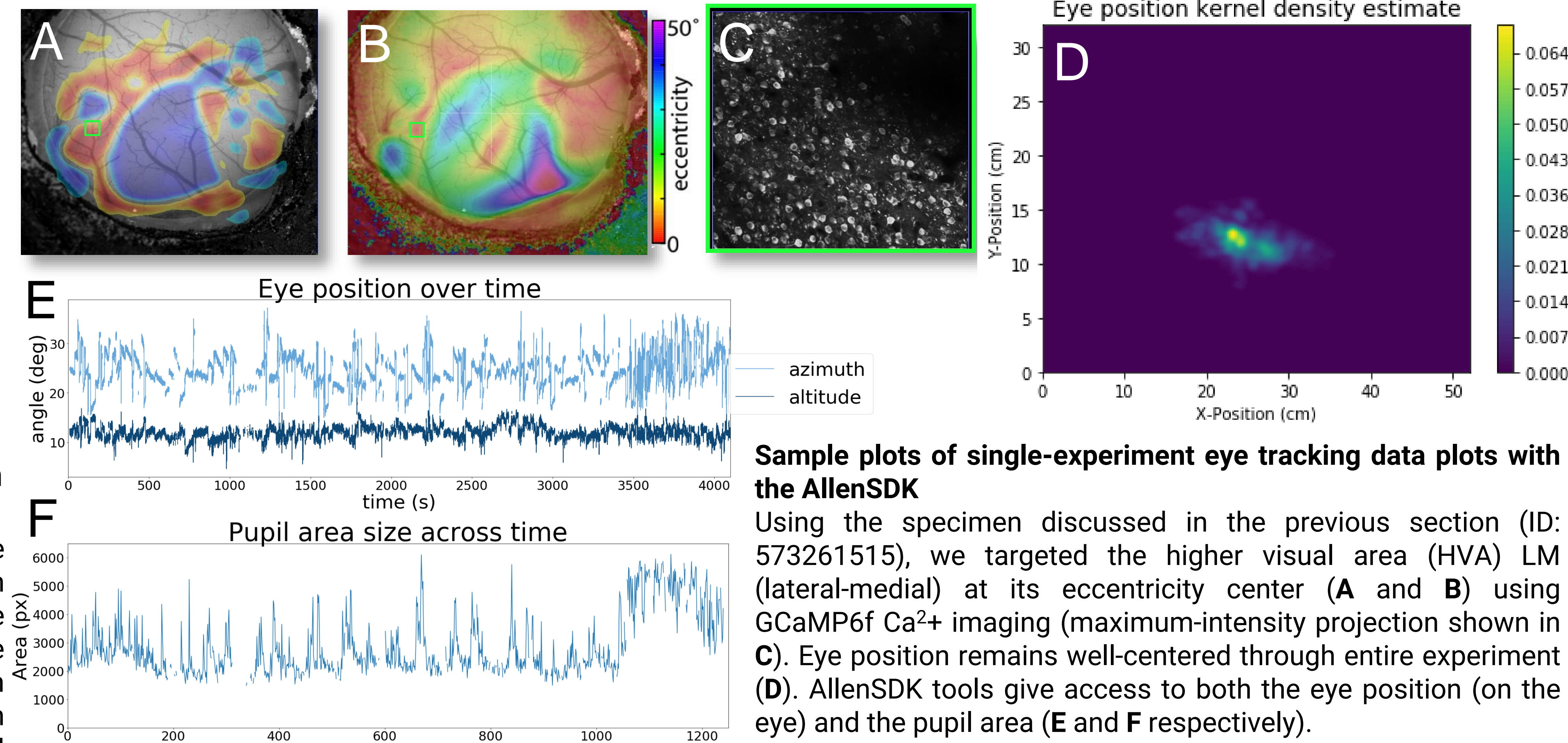
Eye tracking performance before and after LED angular offset



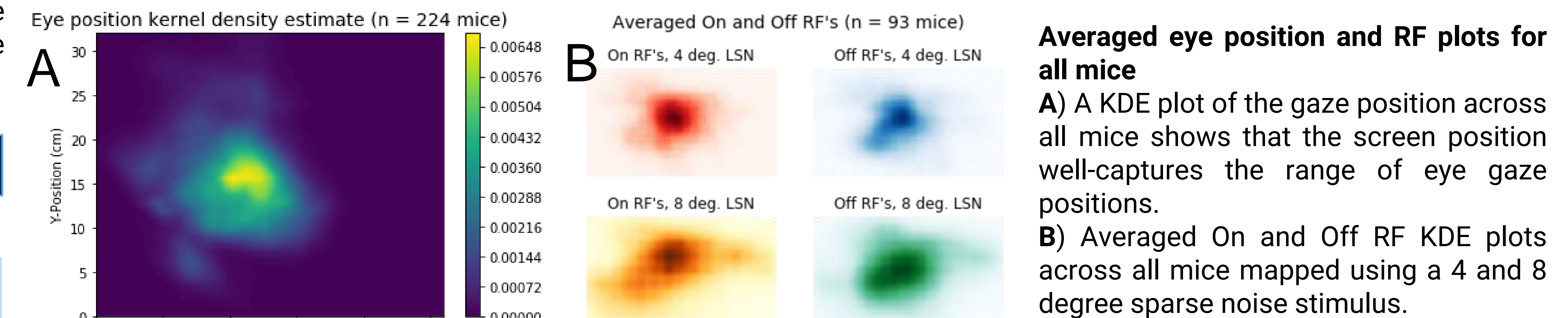
Previous hardware implementations contained an LED to camera offset of **5.5° (A)** which resulted in failures in eye tracking due to the *bright pupil effect* (**B**) – the pupil color shifts from black to gray as incident light rays reflect into the camera at certain angles. This throws off the eye tracking algorithm which then detects spurious “pupil” candidates such as shadows or the eyelid. **At the 5.5° offset, only 76/234 (32%) experiments have greater than 95% of frames correctly annotated (C).**

Increasing the angular offset of the LED to the camera from 5.5° to 15° (**D**) almost completely eliminates the *bright pupil effect* and consistently elicits the *dark pupil effect* (**E**) and the pupil is consistently identified (**F**) – **at the 15° angular offset, 32/40 (80%) of experiments have greater than 95% of frames correctly annotated (H).**

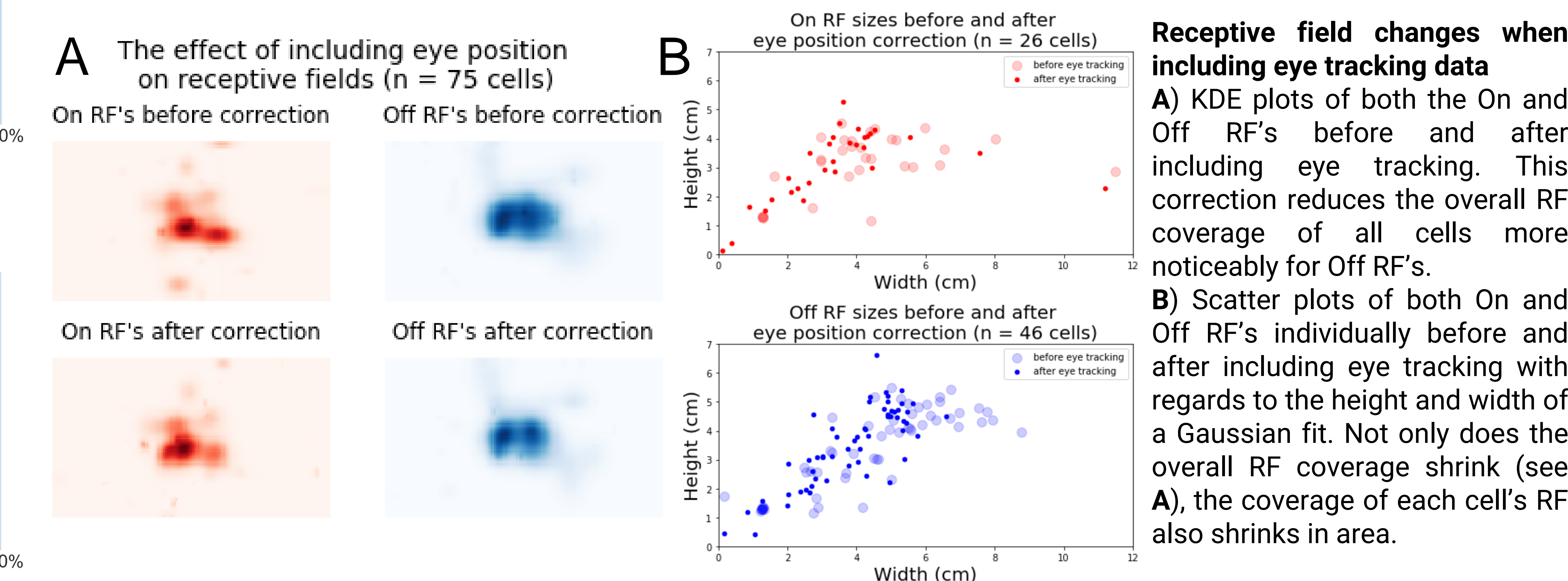
Eye tracking and Data Output



Averaged eye tracking data



Receptive field changes before and after including eye tracking



Conclusions and Acknowledgments

With this tool, we are able to establish more precisely the eye position and corresponding direction of gaze that is essential to the correct characterization of receptive fields especially when it comes to stimuli with high spatial frequencies (since different neurons have very different incident images). The algorithm also allows for assessments of pupil diameter which is useful in the pupillometric assessment of animal engagement. Because of this tools potential utility in the neuroscientific community, we intend to release this tool in the future also as documentation of how the Allen Brain Observatory's eye tracking data was collected.

We wish to thank all the work put into this by all the people whose names are too numerous to fit onto a single poster. We also wish to thank Paul G. Allen and Jody Allen for their generosity, vision, and support.