Autonomous Pool Playing Robot

Low-Level Software Design

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January 5, 2017

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Date	Revision #	Comments	Authors
05/01/2017	0	- Initial document creation	Eric Le Fort

Table 1: Revision History

1 Overview

1.1 Naming Conventions & Definitions

This section outlines the various definitions, acronyms and abbreviations that will be used throughout this document in order to familiarize the reader prior to reading.

1.1.1 Definitions

Table 2 lists the definitions used in this document. The definitions given below are specific to this document and may not be identical to definitions of these terms in common use. The purpose of this section is to assist the user in understanding the requirements for the system.

Table 2: Definitions

Term	Meaning
X-axis	Distance along the length of the pool
	table
Y-axis	Distance across the width of the pool
	table
Z-axis	Height above the pool table
End-effector	The end of the arm that will strike the
	cue ball
θ	Rotational angle of end-effector
Cue	End-effector
Personal Computer	A laptop that will be used to run the
	more involved computational tasks such
	as visual recognition and the shot selec-
	tion algorithm
Camera	Some form of image capture device (e.g.
	a digital camera, smartphone with a
	camera, etc.)
Table State	The current positions of all the balls on
	the table
Entity	Classes that have a state, behaviour
	and identity (e.g. Book, Car, Person,
	etc.)
Boundary	Classes that interact with users or ex-
	ternal systems

1.1.2 Acronyms & Abbreviations

Table 3 lists the acronyms and abbreviations used in this document.

Table 3: Acronyms and Abbreviations

Acronym/Abbreviation	Meaning
VR	Visual Recognition
PC	Personal Computer
μC	Micro-Controller
CRC	Class Responsibility Collaboration

2 Hazards

2.1 HAZARD-NAME

2.2 HAZARD-NAME