Autonomous Pool Playing Robot

Requirements Specification

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March 2, 2017

Contents

List of Tables

Date	Revision #	Comments	Authors
27/02/2017	0	- Initial document creation	Eric Le Fort

Table 1: Revision History

1 Introduction

This document will provide a specification of a test plan for an automated pool playing robot and report on the results of that plan.

1.1 Overview

This document breaks down the required testing for each domain of the system. It begins with the hardware aspect, then moves to the electrical side and then finishes with software. Each section will provide a traceability matrix to map the requirements to tests that check their completion and then go into further detail to describe each test case. Lastly, a summary of the results of testing will be provided to conclude the document.

1.2 Purpose

The aim of this document is to illuminate any design flaws, software bugs, or other issues in the system. Once these issues are discovered, the engineering team will be able to work on eliminating them or minimizing their frequency and consequences.

1.3 Naming Conventions & Definitions

This section outlines the various definitions, acronyms and abbreviations that will be used throughout this document in order to familiarize the reader prior to reading.

1.3.1 Definitions

Table 2 lists the definitions used in this document. The definitions given below are specific to this document and may not be identical to definitions of these terms in common use. The purpose of this section is to assist the user in understanding the requirements for the system.

Table 2: Definitions

Term	**Meaning**
X-axis	Distance along the length of the pool table
Y-axis	Distance across the width of the pool table
Z-axis	Height above the pool table
End-effector	The end of the arm that will strike the cue ball
θ	Rotational angle of end-effector
Cue	End-effector
Personal Computer	A laptop that will be used to run the more involved computational tasks such as visual recognition and the shot selection algorithm
Camera	Some form of image capture device (e.g. a digital camera, smartphone with a camera, etc.)
Table State	The current positions of all the balls on the table
Entity	Classes that have a state, behaviour and identity (e.g. Book, Car, Person, etc.)
Boundary	Classes that interact with users or external systems
Double	Double-precision floating point numbers

1.3.2 Acronyms & Abbreviations

Table 3 lists the acronyms and abbreviations used in this document.

Table 3: Acronyms and Abbreviations

Acronym/Abbreviation	**Meaning**
VR	Visual Recognition
PC	Personal Computer
μC	Micro-Controller
CRC	Class Responsibility Collaboration
TBT	To Be Tested

2 Mechanical Components

Test ID: 12.1	**Sychronious Motion in X Rail**	Status: TBT
Description: Verify that X-Rails can synchronously move to the same location at the same speed without getting stuck while loaded		
Pass/Fail Condition: If rail moves adequately and quickly as expected		
Pre-Conditions: None Input: Location along x-direction (i.e. 2000 steps)		
Expected Results: Smooth and consistent motion along axis until position is met. Followed by an immediate stop	Actual Results:	
Post-Conditions: Rails are stationary with no slip.		

Table 4: Sychronious Motion in X Rail

Test ID: 12.2	**Motion in Y Rail**	Status: TBT
Description:Verify that Y-Rail can move to a location without getting stuck while loaded		
Pass/Fail Condition: If rail moves adequately and quickly as expected		
Pre-Conditions: None Input: Location along y-direction		
Expected Results: Smooth and consistent motion along axis until position is met. Followed by an immediate stop	Actual Results:	
Post-Conditions: Rail is stationary with no slip.		

Table 5: Motion in Y Rail

Test ID: 12.3	**End-Effector Orientation**	Status: TBT
Description: Verify that EE-Base Motor can orient to a specific angle without getting stuck while loaded		
Pass/Fail Condition: If motor turns adequately and quickly as expected to correct angle		
Pre-Conditions: None Input: Angle of orientation with respect to the x-axis		
Expected Results: Smooth and consistent motion until orientation is met. Followed by an immediate stop	Actual Results:	
Post-Conditions: Motor is stationary.		

Table 6: End-Effector Orientation

Test ID: 13.2	**Shooting Mechanism Orientation**	Status: TBT
Description: EE is positioned correctly and waiting command to power piston		
Pass/Fail Condition: Piston is settled at correct oreintation, awaiting command to actuate piston		
Pre-Conditions: Motors orient piston to proper orentation Input: Position and orientation components sent to Arduino		
Expected Results: System moves to desired location and waits for piston signal	Actual Results:	
Post-Conditions: Piston can be safely actauted and strike cue ball		

Table 7: Shooting Mechanism Orientation

Test ID: 16.1	**Perimeter Coverage**	Status: TBT
Description: EE will be moved around the table to ensure that it is able to reach all locations and orientations		
Pass/Fail Condition: EE is capable of completing a full trip around the perimeter without stops		
Pre-Conditions: None Input: Motion command from Arduino		
Expected Results: EE will travel around perimeter of table. Inspection that its location is sufficient for shot-taking is required.	Actual Results:	
Post-Conditions: System awaits next command.		

Table 8: Perimeter Coverage

3 Electrical System

4 Software System

The software system is comprised of four main components: a control system running on an Arduino microcontroller, an automated image capture application running on an Android smartphone, as well a visual recognition program and smart shot selection program running on a PC. On top of the typical suite of unit tests to verify correctness of methods, rigorous system testing will also be crucial to adequately test this system.

The following traceability matrix will demonstrate that the tests to be performed prove that specified requirements have been met.

Test ID: 16.2	**Ball Avoidance**	Status: TBT
Description: As the EE is moving around the table it much avoid the balls to not interfere with gameplay		
Pass/Fail Condition: Able to move randomly around table without moving rolling or stationary balls		
Pre-Conditions: Ball in motion OR stationary Input: Random motion along table		
Expected Results: EE travels directly over balls and does not make contact	Actual Results:	
Post-Conditions: None		

Table 9: Ball Avoidance

Test ID: 14.1	**User Input to Arduino**	Status: TBT
Description: User applies input, then the Arduino indicates a message was received		
Pass/Fail Condition: Arduino output to console correct desired status		
Pre-Conditions: None Input: User pressed input button		
Expected Results: Related console output: make shot, cancel, or move, depending on the button pressed	Actual Results:	
Post-Conditions: None		

Table 10: User Input to Arduino

Test ID: n	Module: Ball	Status: TBT
Ball Constructor Good Inputs		
Pass/Fail Conditions: This test is passed if all the fields inside of Ball are correctly initialized.		
Pre-Conditions: None Input: 1, 0.7, 0		
Expected Results: A new ball with x-coordinate 1, y-coordinate 0.7, and the value 0.	Actual Results:	
Post-Conditions: A new Ball object should be available.		

Table 11: Ball Constructor Good Inputs

Test ID: n	Module: Ball	Status: TBT
Ball Constructor Large X		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown		
Pre-Conditions: None Input: 1.87658, 0.7, 0		
Expected Results: An IllegalArgumentException has been thrown.	Actual Results:	
Post-Conditions: There should not have been a Ball created.		

Table 12: Ball Constructor Large X

4.1 Unit Tests

This section will provide a plethora of test cases which aim to prove correctness of the program. Each individual class will be tested in order to make finding specific test cases easier.

4.1.1 PC Controller Program

Ball Tests

Test ID: n	Module: Ball	Status: TBT
Ball Constructor Large Y		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown		
Pre-Conditions: None Input: 1, 0.94958, 0		
Expected Results: An IllegalArgumentException has been thrown.	Actual Results:	
Post-Conditions: There should not have been a Ball created.		

Table 13: Ball Constructor Large Y

Test ID: n	Module: Ball	Status: TBT
Ball Constructor Small X		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown		
Pre-Conditions: None Input: -1.001, 0.7, 0		
Expected Results: An IllegalArgumentException has been thrown.	Actual Results:	
Post-Conditions: There should not have been a Ball created.		

Table 14: Ball Constructor Small X

Test ID: n	Module: Ball	Status: TBT
Ball Constructor Small Y		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown		
Pre-Conditions: None Input: 1, -1.001, 0		
Expected Results: An IllegalArgumentException has been thrown.	Actual Results:	
Post-Conditions: There should not have been a Ball created.		

Table 15: Ball Constructor Small Y

Test ID: n	Module: Ball	Status: TBT
Ball Constructor Small Value		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown		
Pre-Conditions: None Input: 1, 0.7, -1		
Expected Results: An IllegalArgumentException has been thrown.	Actual Results:	
Post-Conditions: There should not have been a Ball created.		

Table 16: Ball Constructor Small Value

Test ID: n	Module: Ball	Status: TBT
Ball Constructor Large Value		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown.		
Pre-Conditions: None Input: 1, 0.7, 16		
Expected Results: An IllegalArgumentException has been thrown.	Actual Results:	
Post-Conditions: There should not have been a Ball created.		

Table 17: Ball Constructor Large Value

Test ID: n	Module: InferenceEngine	Status: TBT
Updating Table State		
Pass/Fail Conditions: This test is passed if all post-conditions are met.		
Pre-Conditions: None Input: A 16-by-2 array of doubles that are valid positions, BallType.STRIPES		
Expected Results: None	Actual Results: None	
Post-Conditions: 1. Stored BallType is BallType.STRIPES. 2. The stored positions array is the same as the one passed in. 3. The stored best shot is null. 4. The stored table state reflects the positions passed in.		

Table 18: Updating Table State

Test ID: n	Module: InferenceEngine	Status: TBT
Selecting an Optimal Shot		
Pass/Fail Conditions: This test is passed if a reasonable Shot is returned.		
Pre-Conditions: The current table state is not null and the current ball type is not null or BallType.CUE. Input: None		
Expected Results: A reasonable Shot (no bank shots, shooting the right ball, valid x-/y-coordinates).	Actual Results:	
Post-Conditions: The best shot for the current table state is stored.		

Table 19: Selecting an Optimal Shot

Test ID: n	Module: PCCommunicator	Status: TBT
Read Valid Table State from File		
Pass/Fail Conditions: This test is passed if the output matches the data in the text file.		
Pre-Conditions: None. Input: A text file with 16 ball positions		
Expected Results: The 16 ball positions stored in the text file.	Actual Results:	
Post-Conditions: None.		

Table 20: Read Valid Table State from File

InferenceEngine Tests

PCCommunicator Tests

Shot Tests

Test ID: n	Module: PCCommunicator	Status: TBT
Read Table State from Non-Existent File		
Pass/Fail Conditions: This test is passed if a FileNotFoundException is thrown.		
Pre-Conditions: None. Input: None.		
Expected Results: A FileNotFoundException is thrown.	Actual Results:	
Post-Conditions: None.		

Table 21: Read Table State from Non-Existent File

Test ID: n	Module: PCCommunicator	Status: TBT
Read Table State from File with Invalid Data		
Pass/Fail Conditions: This test is passed if an InputMismatchException is thrown.		
Pre-Conditions: None. Input: A file containing the text “Bad data”.		
Expected Results: An InputMismatchException is thrown.	Actual Results:	
Post-Conditions: None.		

Table 22: Read Table State from File with Invalid Data

Test ID: n	Module: PCCommunicator	Status: TBT
Initiating the VR Program		
Pass/Fail Conditions: The test is passed if the VR Program has been run.		
Pre-Conditions: None. Input: None.		
Expected Results: Program is run and TableState.csv has been updated.	Actual Results:	
Post-Conditions: TableState.csv contains the results of the VR Program.		

Table 23: Initiating the VR Program

Test ID: n	Module: Shot	Status: TBT
Shot Constructor Good Inputs		
Pass/Fail Conditions: This test is passed if the Shot is successfully created and stores the correct information.		
Pre-Conditions: None Input: 1, 0.5, 3.5, 1		
Expected Results: A new Shot with an x-coordinate of 1, a y-coordinate of 0.5, an angle of 3.5, and a power of 1.	Actual Results:	
Post-Conditions: Shot has been created.		

Table 24: Shot Constructor Good Inputs

Test ID: n	Module: Shot	Status: TBT
Shot Constructor Large X		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown.		
Pre-Conditions: None Input: 1.87658, 0.5, 3.5, 1		
Expected Results: An IllegalArgumentException is thrown.	Actual Results:	
Post-Conditions: Shot has not been created.		

Table 25: Shot Constructor Large X

Test ID: n	Module: Shot	Status: TBT
Shot Constructor Small X		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown.		
Pre-Conditions: None Input: -0.001, 0.5, 3.5, 1		
Expected Results: An IllegalArgumentException is thrown.	Actual Results:	
Post-Conditions: Shot has not been created.		

Table 26: Shot Constructor Small X

Test ID: n	Module: Shot	Status: TBT
Shot Constructor Large Y		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown.		
Pre-Conditions: None Input: 1, 0.94958, 3.5, 1		
Expected Results: An IllegalArgumentException is thrown.	Actual Results:	
Post-Conditions: Shot has not been created.		

Table 27: Shot Constructor Large Y

Test ID: n	Module: Shot	Status: TBT
Shot Constructor Small Y		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown.		
Pre-Conditions: None Input: 1, -0.001, 3.5, 1		
Expected Results: An IllegalArgumentException is thrown.	Actual Results:	
Post-Conditions: Shot has not been created.		

Table 28: Shot Constructor Small Y

Test ID: n	Module: Shot	Status: TBT
Shot Constructor Large Angle		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown.		
Pre-Conditions: None Input: 1, 0.5, 6.284, 1		
Expected Results: An IllegalArgumentException is thrown.	Actual Results:	
Post-Conditions: Shot has not been created.		

Table 29: Shot Constructor Large Angle

Test ID: n	Module: Shot	Status: TBT
Shot Constructor Small Y		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown.		
Pre-Conditions: None Input: 1, 0.5, -0.01, 1		
Expected Results: An IllegalArgumentException is thrown.	Actual Results:	
Post-Conditions: Shot has not been created.		

Table 30: Shot Constructor Small Angle

Test ID: n	Module: Shot	Status: TBT
Shot Constructor Large Power		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown.		
Pre-Conditions: None Input: 1, 0.5, 3.5, 1.001		
Expected Results: An IllegalArgumentException is thrown.	Actual Results:	
Post-Conditions: Shot has not been created.		

Table 31: Shot Constructor Large Power

SimulationInstance Tests

Test ID: n	Module: Shot	Status: TBT
Shot Constructor Small Power		
Pass/Fail Conditions: This test is passed if an IllegalArgumentException is thrown.		
Pre-Conditions: None Input: 1, 0.5, 3.5, 0		
Expected Results: An IllegalArgumentException is thrown.	Actual Results:	
Post-Conditions: Shot has not been created.		

Table 32: Shot Constructor Small Power

Test ID: n	Module: SimulationInstance	Status: TBT
Simulation Instance Constructor Good Inputs Not Shooting 8-Ball		
Pass/Fail Conditions: This test is passed if the array of Balls is created, the 8-ball is not the target ball, and the initial velocity of the cue ball is set.		
Pre-Conditions: InferenceEngine.myBallType = BallType.SOLID Input: A 16-by-2 array of doubles with at least one ball of type "solid" on the table, 2, 0.4		
Expected Results: A SimulationInstance has been created with an array of Balls with positions corresponding to the array, the initial velocity vectors of the cue ball have been set according to the power and angle.	Actual Results:	
Post-Conditions: A SimulationInstance has been created.		

Table 33: Simulation Instance Constructor Good Inputs

Test ID: n	Module: SimulationInstance	Status: TBT
Simulation Instance Constructor Good Inputs Shooting 8-Ball		
Pass/Fail Conditions: This test is passed if the array of Balls is created, the 8-ball is the target ball, and the initial velocity of the cue ball is set.		
Pre-Conditions: InferenceEngine.myBallType = BallType.SOLID Input: A 16-by-2 array of doubles with no balls of type "solid" on the table, 2, 0.4		
Expected Results: A SimulationInstance has been created with an array of Balls with positions corresponding to the array, the initial velocity vectors of the cue ball have been set according to the power and angle.	Actual Results:	
Post-Conditions: A SimulationInstance has been created.		

Table 34: Simulation Instance Constructor Good Inputs

Test ID: n	Module: SimulationInstance	Status: TBT

Simulation Instance Constructor Large Power

Pass/Fail Conditions: This test is passed if an IllegalArgumentException has been thrown.	
Pre-Conditions: None Input: A 16-by-2 array of doubles, 2, 1.001	
Expected Results: An IllegalArgumentException has been thrown.	Actual Results:
Post-Conditions: An IllegalArgumentException has been thrown.	

Table 35: Simulation Instance Constructor Large Power

Test ID: n	Module: SimulationInstance	Status: TBT

Check for Walls

Pass/Fail Conditions: This test is passed if the expected results are equal to the actual results.	
Pre-Conditions: None Inputs: (0.07070, true) (0.07072, true) (0.866, true) (0.868, true) (0.980, true) (0.982, true) (1.776, true) (1.778, true) (0.07070, false) (0.07072, false) (0.849, false) (0.851, false)	
Expected Results: false true true false false true true false false true true false	Actual Results:
Post-Conditions: None.	

Table 36: Check for Walls

Test ID: n	Module: SimulationInstance	Status: TBT

Get Angle from Coordinates

Pass/Fail Conditions: This test is passed if the expected results are within 0.0001 of the actual results. Notably in the case where x = y = 0, the angle will be $\frac{3}{2}\pi$ which is not technically correct but that does not matter for this project.

Pre-Conditions: None

Inputs:
(1, 0)
(2, 1)
(0, 1)
(-1, 2)
(-1, 0)
(-1, -5)
(0, -1)
(2, -3)

Expected Results:	Actual Results:
0 0.463647609 $\frac{\pi}{2}$ 2.034443936 π 4.514993421 $\frac{3\pi}{2}$ 5.300391584	

Post-Conditions: None.

Table 37: Get Angle from Coordinates

Test ID: n	Module: SimulationInstance	Status: TBT

Ball-Wall Collision

Pass/Fail Conditions: This test is passed if the expected results are within 0.0001 of the actual results.

Pre-Conditions: None

Inputs:
(5, true)
(-1.2, false)

Expected Results:	Actual Results:
-4.33 -1.2	

Post-Conditions: None.

Table 38: Ball-Wall Collision

Test ID: n	Module: SimulationInstance	Status: TBT

Check if in Pocket

Pass/Fail Conditions: This test is passed if the expected results are equal to the actual results.

Pre-Conditions: None

Inputs:
(1, 0.5)
(0,0)
(0.06, 0.02)
(0, 0.921)
(0.03, 0.92)
(0.924,0)
(0.92, 0.02)
(0.924, 0.921)
(0.95, 0.921)
(1.848,0)
(1.84, 0.04)
(1.848, 0.921)
(1.84, 0.915)

Expected Results:	Actual Results:
false true false true false true false true false true false true false	

Post-Conditions: None.

Table 39: Check if in Pocket

Test ID: n	Module: TableState	Status: TBT
TableState Constructor Good Inputs		
Pass/Fail Conditions: This test is passed if the TableState is successfully created and stores the correct information.		
Pre-Conditions: None Input: A 16-by-2 array of doubles that hold the position of the balls		
Expected Results: A new TableState with 16 balls in positions corresponding to those passed in.	Actual Results:	
Post-Conditions: TableState has been created.		

Table 40: TableState Constructor Good Inputs

Test ID: n	Module: TableState	Status: TBT
TableState Constructor Too Many Elements		
Pass/Fail Conditions: This test is passed if the TableState is not created.		
Pre-Conditions: None Input: A 17-by-2 array of doubles		
Expected Results: An IllegalArgumentException has been thrown.	Actual Results:	
Post-Conditions: TableState has not been created.		

Table 41: TableState Constructor Too Many Elements

TableState Tests

4.1.2 PC VR Program

4.1.3 μC Program

4.2 System Tests

Test ID: n	Module: TableState	Status: TBT
TableState Constructor Not Enough Elements		
Pass/Fail Conditions: This test is passed if the TableState is not created.		
Pre-Conditions: None Input: A 15-by-2 array of doubles		
Expected Results: An IllegalArgumentException has been thrown.	Actual Results:	
Post-Conditions: TableState has not been created.		

Table 42: TableState Constructor Not Enough Elements

Test ID: n	Module: TableState	Status: TBT
TableState Constructor Elements Too Small		
Pass/Fail Conditions: This test is passed if the TableState is not created.		
Pre-Conditions: None Input: A 16-by-1 array of doubles		
Expected Results: An IllegalArgumentException has been thrown.	Actual Results:	
Post-Conditions: TableState has not been created.		

Table 43: TableState Constructor Elements Too Small

Test ID: n	Module: TableState	Status: TBT
TableState Constructor Elements Too Large		
Pass/Fail Conditions: This test is passed if the TableState is not created.		
Pre-Conditions: None Input: A 16-by-3 array of doubles		
Expected Results: An IllegalArgumentException has been thrown.	Actual Results:	
Post-Conditions: TableState has not been created.		

Table 44: TableState Constructor Elements Too Large

Test ID: n	Module: TableState	Status: TBT
TableState Deep Copy		
Pass/Fail Conditions: This test is passed if the array of Balls returned have the same values but are not the same Objects.		
Pre-Conditions: A TableState exists in memory. Input: None.		
Expected Results: An array of Balls that have the same positions as those in the TableState.	Actual Results:	
Post-Conditions: None.		

Table 45: TableState Deep Copy

Test ID: n	Module: System	Status: TBT
Aligned Shot		
Pass/Fail Conditions: This test is passed if the target ball is sunk by the machine 50% of the time and the shot should be made within 90 seconds (as per the *Summary and Goals* document).		
Pre-Conditions: Machine must not be currently moving or taking a shot. There are three balls on the table, the cue ball, the target ball, and the eight ball. The cue ball, target ball, and one of the pockets are aligned near perfectly along an imaginary line. The eight ball is not in a position to interfere with motion of the balls along that line. Input: *Take Shot* button pressed.		
Expected Results: Only the target ball should be sunk.	Actual Results:	
Post-Conditions: The eight ball should remain on the table. The target ball should be sunk. There are no requirements for the cue ball, but bonus points if it remains on the table.		

Table 46: Aligned Shot

Test ID: n	Module: System	Status: TBT
Angled Shot		
Pass/Fail Conditions: This test is passed if the target ball is sunk by the machine 50% of the time and the shot should be made within 90 seconds (as per the *Summary and Goals* document).		
Pre-Conditions: Machine must not be currently moving or taking a shot. There are three balls on the table, the cue ball, the target ball, and the eight ball. There should be a shot that can be made with a modest angle that will sink the target ball. The eight ball is not in a position to interfere with expected motion of the balls. Input: *Take Shot* button pressed.		
Expected Results: Only the target ball should be sunk.	Actual Results:	
Post-Conditions: The eight ball should remain on the table. The target ball should be sunk. There are no requirements for the cue ball, but bonus points if it remains on the table.		

Table 47: Angled Shot

Test ID: n	Module: System	Status: TBT
Shot Cancelled Before Motion		
Pass/Fail Conditions: This test is passed if the machine does not move.		
Pre-Conditions: None. Input: *Take Shot* button pressed, Then *Cancel* button pressed before machine moves.		
Expected Results: The machine should cancel the instruction and not move.	Actual Results:	
Post-Conditions: The machine should not have moved or be moving.		

Table 48: Shot Cancelled Before Motion

5 Summary of Results

Test ID: n	Module: System	Status: TBT
Shot Cancelled During Motion		
Pass/Fail Conditions: This test is passed if the machine ceases movement within 2 seconds.		
Pre-Conditions: None. Input: *Take Shot* button pressed, Then *Cancel* button pressed while machine is moving.		
Expected Results: The machine should cease movement.	Actual Results:	
Post-Conditions: The machine should not be moving.		

Table 49: Shot Cancelled During Motion

Test ID: n	Module: System	Status: TBT
Move Request (To Zero X-Coordinate)		
Pass/Fail Conditions: The machine moves to the zero x-coordinate within 20 seconds.		
Pre-Conditions: Machine's y-rail is located closer to the large x-coordinate. Input: *Move* button pressed		
Expected Results: The machine should move to the zero x-coordinate of the table.	Actual Results:	
Post-Conditions: The machine should be located at the zero x-coordinate.		

Table 50: Move Request (To Zero X-Coordinate)

Test ID: n	Module: System	Status: TBT
Move Request (To Largest X-Coordinate)		
Pass/Fail Conditions: The machine moves to the largest x-coordinate within 20 seconds.		
Pre-Conditions: Machine's y-rail is located closer to the zero x-coordinate. Input: *Move* button pressed		
Expected Results: The machine should move to the largest x-coordinate of the table.	Actual Results:	
Post-Conditions: The machine should be located at the largest x-coordinate.		

Table 51: Move Request (To Largest X-Coordinate)

Test ID: n	Module: System	Status: TBT
Check For Political Correctness		
Pass/Fail Conditions: All interviewees agree that there are no direct references to any religious or political groups.		
Pre-Conditions: None. Input: 20 colleagues will be asked to give their opinion on whether the system created has no direct reference to any religious or political groups.		
Expected Results: Colleagues decide that there are no direct references to any religious or political groups.	Actual Results:	
Post-Conditions: None.		

Table 52: Check For Legality and Political Correctness