## EigenValue\_Project\_PartIV

## April 12, 2024

```
[]: #import packages
     import scipy.linalg as scilin
     import numpy as np
     import json
     import pandas as pd
     import os
     import matplotlib.pyplot as plt
[]: #Functions Section
     def EigenPrint_TwoMat(A,B):
         C = np.matmul(np.linalg.inv(B),A)
         eigen_vals,eigen_vects = scilin.eig(C)
         id_list = eigen_vals.argsort()[::-1]
         eigen_vals = eigen_vals[id_list]
         eigen_vects = eigen_vects[:,id_list]
         for i in range(len(eigen_vals)):
             print(f'Eigen Value: {eigen_vals[i]}')
         for j in range(len(eigen_vects)):
             print(f'Eigenvector: {eigen_vects[j]}')
     def directory_check(directory_name):
         if not os.path.exists(directory_name):
             os.makedirs(directory name)
             print(f"Directory '{directory_name}' created.")
         else:
             print(f"Directory '{directory_name}' already exists.")
[]: #Read in the data from the JSON file
     filename_load = "6917_new.json"
     base_name = os.path.basename(filename_load).split('.')[0]
     directory_check(base_name)
     Output_File_Long = base_name +'/'+base_name +"_Eigen_Long.txt"
     Output_File_Lat = base_name +'/'+base_name +"_Eigen_Lat.txt"
     Output_File_Long_mat = base_name +'/'+base_name +'_Matrices_Long.txt'
     Output_File_Lat_mat = base_name +'/'+base_name +'_Matrices_Lat.txt'
```

J\_string = open(filename\_load).read()

J\_vals = json.loads(J\_string)

```
#Get the moment information of aircraft
I_xx = J_vals['aircraft']['Ixx[slug-ft^2]']
I_yy = J_vals['aircraft']['Iyy[slug-ft^2]']
I zz = J vals['aircraft']['Izz[slug-ft^2]']
I_xy = J_vals['aircraft']['Ixy[slug-ft^2]']
I xz = J vals['aircraft']['Ixz[slug-ft^2]']
#Name
#Plane_name = J_vals['aircraft']['name']
#Wing Information
Wing_Area = J_vals['aircraft']['wing_area[ft^2]']
Wing_Span = J_vals['aircraft']['wing_span[ft]']
Wing_MeanChord = Wing_Area/Wing_Span
#aircraft weight
Weight = J_vals['aircraft']['weight[lbf]']
#Launch Energy
#Launch_Energy = J_vals['aircraft']['launch_kinetic_energy[ft-lbf]']
#densitu
Air Density = J vals['analysis']['density[slugs/ft^3]']
#CL values
CL_0 = J_vals['aerodynamics']['CL']['0']
CL_alpha = J_vals['aerodynamics']['CL']['alpha']
CL_qbar = J_vals['aerodynamics']['CL']['qbar']
CL_alpha_hat = J_vals['aerodynamics']['CL']['alpha_hat']
#CY values
CY beta = J vals['aerodynamics']['CS']['beta']
CY_pbar = J_vals['aerodynamics']['CS']['pbar']
CY_rbar = J_vals['aerodynamics']['CS']['rbar']
#CD values
CD_L0 = J_vals['aerodynamics']['CD']['L0']
CD_L1 = J_vals['aerodynamics']['CD']['L']
CD_L2 = J_vals['aerodynamics']['CD']['L2']
CD_0 = CD_L0 + CD_L1*CL_0+CD_L2*CL_0**2
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CD_alpha = CD_L1*CL_alpha + 2*CD_L2*CL_0*CL_alpha
    CD_qbar = J_vals['aerodynamics']['CD']['qbar']
    #Cl Values
    Cl_beta = J_vals['aerodynamics']['Cl']['beta']
    Cl_pbar = J_vals['aerodynamics']['Cl']['pbar']
    Cl_rbar = J_vals['aerodynamics']['Cl']['rbar']
    #Cm Values
    Cm 0 = J vals['aerodynamics']['Cm']['0']
    Cm alpha = J vals['aerodynamics']['Cm']['alpha']
    Cm_qbar = J_vals['aerodynamics']['Cm']['qbar']
    Cm_alpha_hat = J_vals['aerodynamics']['Cm']['alpha_hat']
    #Cn values
    Cn_beta = J_vals['aerodynamics']['Cn']['beta']
    Cn_pbar = J_vals['aerodynamics']['Cn']['pbar']
    Cn_rbar = J_vals['aerodynamics']['Cn']['rbar']
    #Gravity at location
    g = 32.17 #gravity at logan elevation used for design
    #Solve for the inital velocity given the launch conditions
    #V 0 = np.sqrt(2*Launch Energy*q/Weight) #Need to check if this is correct,
     ⇔don't do this, but we can do this later
    #Get V_O from the CL
    V_0 = np.sqrt((Weight)/(0.5*Wing_Area*Air_Density*CL_0))
    \#V_0 = J_vals['initial']['airspeed[ft/s]']
    #CW of aircraft
    CW = Weight/(0.5*Wing_Area*Air_Density*V_0**2)
    print(f'Velocity: {V_0}')
    Directory '6917_new' already exists.
    Velocity: 11.573374411266089
[]: #Solving for all the Base Components found in eqs. 10.70-10.76 to then put intou
     → the matrices in 10.77 and 10.78, all variable must be unitless
    #10.70 -10.72 not required because we don't know these variables and this is a
     \rightarrow glider
    #10.73
    R_gx = (g*Wing_MeanChord)/(2*V_0**2)
```

```
R_gy = (g*Wing_Span)/(2*V_0**2)

#10.74
R_rhox = (4*Weight/g)/(Air_Density*Wing_Area*Wing_MeanChord)
R_rhoy = (4*Weight/g)/(Air_Density*Wing_Area*Wing_Span)

#10.75
R_xx = (8*I_xx)/(Air_Density*Wing_Area*Wing_Span**3)
R_yy = (8*I_yy)/(Air_Density*Wing_Area*Wing_MeanChord**3)
R_zz = (8*I_zz)/(Air_Density*Wing_Area*Wing_Span**3)
R_xz = (8*I_xz)/(Air_Density*Wing_Area*Wing_Span**3)

#10.76

#Not required since there is no thrust given this aircraft is a glider
```

```
[]: #Generating the Matrices, going for the nondimensional form, Longitudinal
     \hookrightarrowEquations
     #10.77 B mat is the LHS matrix, A mat is the RHS matrix
     A mat long = np.zeros([6,6])
     B mat long = np.identity(6)
     #Variables that could be changed, but assumed to be zero
     CD_mu = 0
     CL_mu_hat = 0
     Cm \ mu \ hat = 0
     CD_alpha_hat = 0
     alpha deg = 0
     alpha_rad = alpha_deg*np.pi/180
     #Fill in the A Matrix given what is known
         #Single Row
     A_{mat}long[0,0] = -2*CD_0 #+ CT_V*np.cos(alpha_rad)
     A_mat_long[0,1] = CL_0-CD_alpha
     A_mat_long[0,2] = -CD_qbar
     A_mat_long[0,5] = -R_rhox*R_gx*np.cos(alpha_rad)
         #Second Row
     A_{mat_long}[1,0] = -2*CL_0 \#+ CT_V*np.sin(alpha_rad)
     A_mat_long[1,1] = -CL_alpha-CD_0 #Variable is not correct currently, CD_0 is_
      ⇔not correct
     A_mat_long[1,2] = -CL_qbar+R_rhox
     A_mat_long[1,5] = -R_rhox*R_gx*np.sin(alpha_rad)
         #Third Row
     A_mat_long[2,0] = 2*Cm_0
     A_mat_long[2,1] = Cm_alpha
     A_{mat_long}[2,2] = Cm_qbar
         #Fourth Row
     A mat long[3,0] = np.cos(alpha rad)
     A_mat_long[3,1] = np.sin(alpha_rad)
     A_mat_long[3,5] = -np.sin(alpha_rad)
         #Fifth Row
     A_mat_long[4,0] = -np.sin(alpha_rad)
```

```
A_mat_long[4,1] = np.cos(alpha_rad)
A_mat_long[4,5] = -np.cos(alpha_rad)
    #Sixth Row
A_{mat_long}[5,2] = 1
#Fill in the B Matrix given what is known
B_mat_long[0,0] = R_rhox+CD_mu
B_mat_long[0,1] = CD_alpha_hat
B_mat_long[1,0] = CL_mu_hat
B_mat_long[1,1] = R_rhox+CL_alpha_hat
B_mat_long[2,0] = -Cm_mu_hat
B_mat_long[2,1] = -Cm_alpha_hat
B_{mat_long[2,2]} = R_{yy}
#Create a New matrix using the A and B matrix to do the Eigen value solve
C_mat_long = np.matmul(np.linalg.inv(B_mat_long),A_mat_long)
#Generating the Matrices, going for the nondimensional form, Lateral Equations
#10.77 B mat is the LHS matrix, A mat is the RHS matrix
A_mat_lat = np.zeros([6,6])
B_mat_lat = np.identity(6)
#Variables that could be changed, but assumed to be zero
CD mu = 0
CL mu hat = 0
Cm_mu_hat = 0
CD_alpha_hat = 0
alpha_deg = 0
alpha_rad = alpha_deg*np.pi/180
#Fill in the A Matrix given what is known
    #Single Row
A_mat_lat[0,0] = CY_beta
A_mat_lat[0,1] = CY_pbar
A_{mat_lat[0,2]} = (CY_{rbar-R_rhoy})
A_mat_lat[0,4] = R_rhoy*R_gy*np.cos(alpha_rad)
    #Second Row
A_mat_lat[1,0] = Cl_beta
A_mat_lat[1,1] = Cl_pbar
A_mat_lat[1,2] = Cl_rbar
    #Third Row
A_{mat_lat[2,0]} = Cn_{beta}
A_mat_lat[2,1] = Cn_pbar
A_mat_lat[2,2] = Cn_rbar
    #Fourth Row
A_{mat_lat[3,0]} = 1
A_mat_lat[3,5] = np.cos(alpha_rad)
```

```
#Fifth Row
A_mat_lat[4,1] = 1
A_mat_lat[4,2] = np.tan(alpha_rad)
    #Sixth Row
A_mat_lat[5,2] = 1/np.cos(alpha_rad)

#Fill in the B Matrix given what is known
B_mat_lat[0,0] = R_rhoy
B_mat_lat[1,1] = R_xx
B_mat_lat[1,2] = -R_xz
B_mat_lat[2,1] = -R_xz
B_mat_lat[2,2] = R_zz

#Create a New matrix using the A and B matrix to do the Eigen value solve

C_mat_lat = np.matmul(np.linalg.inv(B_mat_lat), A_mat_lat)

#pd.DataFrame(C_mat_lat).head(6)
```

```
[]: #Getting the actual Eigenvalues and Eigenvectors
     eigen_vals_long,eigen_vects_long = scilin.eig(C_mat_long)
     # Print eigenvalues and eigenvectors
     print("Eigenvalues:")
     for i, val in enumerate(eigen_vals_long):
        print(f"Eigenvalue {i + 1}: {val.real:.4f} + {val.imag:.4f}j")
     print("\nEigenvectors:")
     for i in range(2,len(eigen_vects_long)):
        print(f"Eigenvector {i + 1}:")
        for j in range(len(eigen_vects_long)):
            print(f"
                      {eigen_vects_long[j, i].real:.4f} + {eigen_vects_long[j, i].
      ⇔imag:.4f}j")
             #Getting the actual Eigenvalues and Eigenvectors
     eigen_vals_lat,eigen_vects_lat = scilin.eig(C_mat_lat)
     # Print eigenvalues and eigenvectors
     print("Eigenvalues:")
     for i, val in enumerate(eigen_vals_lat):
        print(f"Eigenvalue {i + 1}: {val.real:.4f} + {val.imag:.4f}j")
    print("\nEigenvectors:")
```

```
for i in range(2,len(eigen_vects_lat)):
    print(f"Eigenvector {i + 1}:")
    for j in range(len(eigen_vects_lat)):
        print(f"
                   {eigen_vects_lat[j, i].real:.4f} + {eigen_vects_lat[j, i].
  →imag:.4f}j")
Eigenvalues:
Eigenvalue 1: 0.0000 + 0.0000j
Eigenvalue 2: 0.0000 + 0.0000j
Eigenvalue 3: -0.3674 + 0.0000j
Eigenvalue 4: -0.1223 + 0.0000j
Eigenvalue 5: -0.0019 + 0.0323j
Eigenvalue 6: -0.0019 + -0.0323j
Eigenvectors:
Eigenvector 3:
   -0.0440 + 0.0000j
  0.3315 + 0.0000j
  0.0044 + 0.0000j
  0.1198 + 0.0000j
  -0.9347 + 0.0000j
   -0.0119 + 0.0000j
Eigenvector 4:
  0.0512 + 0.0000j
   -0.0501 + 0.0000i
   -0.0074 + 0.0000j
   -0.4186 + 0.0000j
  0.9033 + 0.0000j
  0.0604 + 0.0000j
Eigenvector 5:
  0.0017 + -0.0287j
   -0.0003 + 0.0074j
   -0.0001 + -0.0005j
   -0.8886 + 0.0000j
  0.0318 + -0.4563j
   -0.0150 + 0.0055j
Eigenvector 6:
  0.0017 + 0.0287j
  -0.0003 + -0.0074j
   -0.0001 + 0.0005j
   -0.8886 + -0.0000j
  0.0318 + 0.4563j
   -0.0150 + -0.0055j
Eigenvalues:
Eigenvalue 1: 0.0000 + 0.0000j
Eigenvalue 2: 0.0000 + 0.0000j
Eigenvalue 3: -34.5173 + 0.0000j
Eigenvalue 4: -0.8185 + 0.0000j
```

```
Eigenvalue 5: -0.4256 + 0.7548j
    Eigenvalue 6: -0.4256 + -0.7548j
    Eigenvectors:
    Eigenvector 3:
       -0.0303 + 0.0000j
       -0.9984 + 0.0000i
       0.0388 + 0.0000j
       0.0009 + 0.0000j
       0.0289 + 0.0000j
       -0.0011 + 0.0000j
    Eigenvector 4:
       -0.3738 + 0.0000j
       0.0869 + 0.0000j
       -0.5380 + 0.0000j
       -0.3464 + 0.0000j
       -0.1062 + 0.0000j
       0.6573 + 0.0000j
    Eigenvector 5:
       0.6593 + 0.0000j
       -0.2947 + -0.0147j
       0.1036 + -0.1264j
       -0.3011 + -0.4575j
       0.1523 + 0.3046j
       -0.1858 + -0.0325j
    Eigenvector 6:
       0.6593 + -0.0000j
       -0.2947 + 0.0147j
       0.1036 + 0.1264j
       -0.3011 + 0.4575j
       0.1523 + -0.3046j
       -0.1858 + 0.0325j
[]: #Get the amplitude and phase of each component as a numpy array from the
      ⇔eigenvectors
     #long amp and phase matrices
     amplitude_long = np.zeros_like(eigen_vects_long)
     phase_long = np.zeros_like(eigen_vects_long)
     #loop through columns
     for j in range(eigen_vects_long.shape[0]):
          #loop through rows
          for i in range(eigen_vects_long.shape[1]):
               amplitude_long[i,j] = np.sqrt(eigen_vects_long[i,j].real**2 +__
      →eigen_vects_long[i,j].imag**2)
               phase_long[i,j] = np.arctan2(eigen_vects_long[i,j].

→imag,eigen_vects_long[i,j].real)*(180/np.pi)
```

```
[]: #Going through the damping rate
     variable_symbols_lat = ['\Delta', '\Deltap_bar', '\Deltar_bar', '\Delta_y', '\Delta\Phi', '\Delta']
     variable_symbols_long = ['\Delta', '\Delta', '\Delta q_{bar'}, '\Delta_x', '\Delta_z', '\Delta\Theta']
     for z in range(len(eigen_vals_long)):
         i = eigen_vals_long[z]
         print(f'Dimensionless Eigen Value: {i.real:8.6f}+{i.imag:12.8f}j')
         sigma = -i.real
         #Rigid Body mode
         if i.real == 0:
              print('\t Rigid Body Mode: Eigen Value: 0 ')
             print('\t No analysis required currently\n')
         #Convergent Modes Sigma > 0
         if sigma > 0:
              #Damping rate
             Damp_rate = sigma*2*V_0/Wing_MeanChord
              #99 Damping Time
              Damp_time_99 = np.log(0.01)/-Damp_rate
              #Damped natural frequency and Period
              if i.imag != 0:
                  W_d = abs(i.imag)*2*V_0/Wing_MeanChord
                  Period = (2*np.pi)/W_d
                  #Damping Ratio
                  Damp_Ratio = -i.real/(np.sqrt(i.real**2 + i.imag**2))
             print(f'\t Damping Rate [1/s]: {Damp rate:12.6f}')
             print(f'\t 99% Damping Time [s]: {Damp_time_99:12.6f}')
              if i.imag != 0:
                  print(f'\t Damped Nat Freq: {W_d:12.6f}')
                  print(f'\t Period: {Period:12.6f}')
```

```
print(f'\t Damping Ratio: {Damp_Ratio:12.6f}')
      print('')
  #Divergent Modes Sigma < 0
  if sigma < 0:</pre>
  #Damping rate
      Damp_rate = sigma*2*V_0/Wing_MeanChord
      #99 Damping Time
      Double_time = np.log(2.00)/-Damp_rate
      #Damped natural frequency and Period
      if i.imag != 0:
          W_d = abs(i.imag)*2*V_0/Wing_MeanChord
         Period = (2*np.pi)/W_d
          #Damping Ratio
         Damp_Ratio = -i.real/(np.sqrt(i.real**2 + i.imag**2))
      print(f'\t Damping Rate [1/s]: {Damp_rate:12.6f}')
      print(f'\t Doubling Time [s]: {Double_time:12.6f}')
      if i.imag != 0:
          print(f'\t Damped Nat Freq: {W_d:12.6f}')
          print(f'\t Period: {Period:12.6f}')
          print(f'\t Damping Ratio: {Damp_Ratio:12.6f}')
      print('')
  #Print the Eigen Vector
oprint(f'-----
  print(f'{"Variable":<15} {"Real Part":<15} {"Imaginary Part":<20}__
→{"Amplitude":<15} {"Phase":<15}')</pre>
  eigen_vects_long = np.asarray(eigen_vects_long)
  for j in range(6):
      real = eigen_vects_long[j,z].real
      imag = eigen_vects_long[j,z].imag
      amp = amplitude_long[j,z].real
      phase_deg = phase_long[j,z].real
      symbol = variable_symbols_long[j]
      print(f'{symbol:<15} {real:<15.6f} {imag:<20.6f} {amp:<15.6f}
\hookrightarrow{phase_deg:<15.6f}')
oprint(f'-----
```

```
Dimensionless Eigen Value: 0.000000+ 0.00000000j
Rigid Body Mode: Eigen Value: 0
No analysis required currently
```

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Variable Real Part Imaginary Part Amplitude Phase

Δ	0.00000	0.00000	0.000000	0.000000
Δ	0.00000	0.00000	0.000000	0.000000
Δq_bar	0.000000	0.000000	0.000000	0.000000
Δ_x	1.000000	0.00000	1.000000	0.000000
Δ_z	0.00000	0.00000	0.000000	0.000000
ΔΘ	0.000000	0.000000	0.000000	0.000000

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Dimensionless Eigen Value: 0.000000+ 0.00000000j

Rigid Body Mode: Eigen Value: 0 No analysis required currently

Variable Real Part Imaginary Part Amplitude Phase Δ 0.000000 0.000000 0.000000 0.000000 Δ 0.000000 0.000000 0.000000 0.000000 ∆q\_bar 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 0.000000 Δ\_x 1.000000 0.000000 1.000000 0.000000 Δ\_z 0.000000 0.000000 0.000000 0.000000

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Dimensionless Eigen Value: -0.367433+ 0.00000000j

Damping Rate [1/s]: 16.199771 99% Damping Time [s]: 0.284274

Variable Real Part Imaginary Part Amplitude Phase Δ -0.044019 0.000000 0.044019 180.000000 0.331499 0.000000 0.331499 0.000000 ∆q\_bar 0.004387 0.000000 0.004387 0.000000 Δ\_x 0.119802 0.000000 0.119802 0.000000 Δ\_z -0.934696 0.000000 0.934696 180.000000 -0.011939 0.000000 0.011939 180.000000

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Dimensionless Eigen Value: -0.122344+ 0.00000000j

Damping Rate [1/s]: 5.394041 99% Damping Time [s]: 0.853751

Variable Real Part Imaginary Part Amplitude Phase Δ 0.051212 0.000000 0.051212 0.000000 Δ -0.0501070.000000 0.050107 180.000000 ∆q\_bar -0.007390 0.000000 0.007390 180.000000 Δ\_x -0.4185880.000000 0.418588 180.000000 Δ\_z 0.903298 0.000000 0.903298 0.000000 ΔΘ 0.060407 0.000000 0.060407 0.000000

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Dimensionless Eigen Value: -0.001947+ 0.03233351j

Damping Rate [1/s]: 0.085822 99% Damping Time [s]: 53.659487 Damped Nat Freq: 1.425554

Period: 4.407540

Damping Ratio: 0.060094

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Variable	Real Part	Imaginary Part	Amplitude	Phase
Δ	0.001730	-0.028733	0.028785	-86.554800
Δ	-0.000306	0.007426	0.007432	92.355894
Δq_bar	-0.000149	-0.000496	0.000518	-106.728901
Δ_x	-0.888634	0.000000	0.888634	180.000000
Δ_z	0.031786	-0.456267	0.457372	-86.014944
ΔΘ	-0.014996	0.005510	0.015977	159.825900

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Dimensionless Eigen Value: -0.001947+ -0.03233351j

Damping Rate [1/s]: 0.085822 99% Damping Time [s]: 53.659487

Damped Nat Freq: 1.425554

Period: 4.407540

Damping Ratio: 0.060094

Variable Real Part Imaginary Part Amplitude Phase Δ 0.001730 0.028785 86.554800 0.028733 -0.000306 -0.007426 0.007432 -92.355894 -0.000149 ∆q\_bar 0.000496 0.000518 106.728901 Δ\_x -0.888634 -0.000000 0.888634 -180.000000 Δ\_z 0.031786 0.456267 0.457372 86.014944 -0.014996 ΔΘ -0.005510 0.015977 -159.825900

```
print('\t No analysis required currently\n')
  #Convergent Modes Sigma > 0
  if sigma > 0:
      #Damping rate
      Damp_rate = sigma*2*V_0/Wing_Span
      #99 Damping Time
      Damp_time_99 = np.log(0.01)/-Damp_rate
      #Damped natural frequency and Period
      if i.imag != 0:
          W_d = abs(i.imag)*2*V_0/Wing_Span
          Period = (2*np.pi)/W_d
          #Damping Ratio
          Damp_Ratio = -i.real/(np.sqrt(i.real**2 + i.imag**2))
      print(f'\t Damping Rate [1/s]: {Damp_rate:12.6f}')
      print(f'\t 99% Damping Time [s]: {Damp_time_99:12.6f}')
      if i.imag != 0:
          print(f'\t Damped Nat Freq: {W_d:12.6f}')
          print(f'\t Period: {Period:12.6f}')
          print(f'\t Damping Ratio: {Damp_Ratio:12.6f}')
      print('')
  #Divergent Modes Sigma < 0
  if sigma < 0:</pre>
  #Damping rate
      Damp_rate = sigma*2*V_0/Wing_Span
      #99 Damping Time
      Double_time = np.log(2.00)/-Damp_rate
      #Damped natural frequency and Period
      if i.imag != 0:
          W_d = abs(i.imag)*2*V_0/Wing_Span
          Period = (2*np.pi)/W_d
          #Damping Ratio
          Damp_Ratio = -i.real/(np.sqrt(i.real**2 + i.imag**2))
      print(f'\t Damping Rate [1/s]: {Damp_rate:12.6f}')
      print(f'\t Doubling Time [s]: {Double_time:12.6f}')
      if i.imag != 0:
          print(f'\t Damped Nat Freq: {W_d:12.6f}')
          print(f'\t Period: {Period:12.6f}')
          print(f'\t Damping Ratio: {Damp_Ratio:12.6f}')
      print('')
  #Print the Eigen Vector
oprint(f'-----
  print(f'\{"Variable":<15\} \ \{"Real Part":<15\} \ \{"Imaginary Part":<20\}_{\sqcup}
```

```
eigen_vects_lat = np.asarray(eigen_vects_lat)
for j in range(6):
    real = eigen_vects_lat[j,z].real
    imag = eigen_vects_lat[j,z].imag
    amp = amplitude_lat[j,z].real
    phase_deg = phase_lat[j,z].real
    symbol = variable_symbols_lat[j]
    print(f'{symbol:<15} {real:<15.6f} {imag:<20.6f} {amp:<15.6f}_{\subseteq}
$\frac{15.6f}{1}$ }
$\frac{15.6f}{1}$
```

-----

Dimensionless Eigen Value: 0.000000+ 0.00000000j

Rigid Body Mode: Eigen Value: 0 No analysis required currently

Variable Real Part Imaginary Part Amplitude Phase

Variable	Real Part	Imaginary Part	Amplitude	Phase
Δ	0.000000	0.000000	0.000000	0.000000
Δp_bar	0.000000	0.000000	0.00000	0.00000
∆r_bar	0.000000	0.000000	0.00000	0.00000
Δ_y	1.000000	0.000000	1.000000	0.000000
$\Delta\Phi$	0.000000	0.00000	0.00000	0.00000
Δ	0.000000	0.000000	0.000000	0.000000

\_\_\_\_\_

Dimensionless Eigen Value: 0.000000+ 0.00000000j

Rigid Body Mode: Eigen Value: 0 No analysis required currently

-----

Variable	Real Part	Imaginary Part	Amplitude	Phase
Δ	0.000000	0.000000	0.00000	0.000000
Δp_bar	0.000000	0.000000	0.00000	0.000000
∆r_bar	0.000000	0.000000	0.00000	0.000000
Δ_у	-1.000000	0.000000	1.000000	180.000000
$\Delta\Phi$	0.000000	0.000000	0.00000	0.000000
Δ	0.000000	0.000000	0.000000	0.000000

Dimensionless Eigen Value: -34.517298+ 0.00000000j

Damping Rate [1/s]: 63.917059 99% Damping Time [s]: 0.072049 -----

Variable	Real Part	Imaginary Part	Amplitude	Phase
Δ	-0.030333	0.000000	0.030333	180.000000
Δp_bar	-0.998368	0.000000	0.998368	180.000000
∆r_bar	0.038768	0.000000	0.038768	0.000000
Δ_y	0.000911	0.000000	0.000911	0.000000
$\Delta\Phi$	0.028924	0.000000	0.028924	0.000000
Δ	-0.001123	0.000000	0.001123	180.000000

Dimensionless Eigen Value: -0.818540+ 0.00000000j

Damping Rate [1/s]: 1.515724 99% Damping Time [s]: 3.038265

-----

Variable	Real Part	Imaginary Part	Amplitude	Phase
Δ	-0.373762	0.000000	0.373762	180.000000
Δp_bar	0.086944	0.000000	0.086944	0.000000
∆r_bar	-0.538015	0.000000	0.538015	180.000000
Δ_y	-0.346377	0.000000	0.346377	180.000000
$\Delta\Phi$	-0.106218	0.000000	0.106218	180.000000
Δ	0.657285	0.000000	0.657285	0.000000

\_\_\_\_\_

Dimensionless Eigen Value: -0.425593+ 0.75475346j

Damping Rate [1/s]: 0.788088 99% Damping Time [s]: 5.843473

Damped Nat Freq: 1.397607

Period: 4.495674

Damping Ratio: 0.491177

-----

Variable	Real Part	Imaginary Part	Amplitude	Phase
Δ	0.659280	0.000000	0.659280	0.000000
Δp_bar	-0.294734	-0.014701	0.295100	-177.144517
∆r_bar	0.103626	-0.126428	0.163470	-50.660266
Δ_y	-0.301057	-0.457519	0.547685	-123.345749
$\Delta\Phi$	0.152296	0.304626	0.340575	63.437539
Δ	-0.185839	-0.032507	0.188660	-170.078211

\_\_\_\_\_

Dimensionless Eigen Value: -0.425593+ -0.75475346j

Damping Rate [1/s]: 0.788088 99% Damping Time [s]: 5.843473

Damped Nat Freq: 1.397607

Period: 4.495674

Damping Ratio: 0.491177

Variable Real Part Imaginary Part Amplitude Phase 0.659280 -0.000000 0.659280 -0.000000 Δ ∆p\_bar -0.294734 0.014701 0.295100 177.144517 ∆r bar 0.103626 0.126428 0.163470 50.660266 Δ\_у -0.301057 0.457519 0.547685 123.345749 ΔΦ 0.152296 -0.304626 0.340575 -63.437539 -0.185839 0.032507 0.188660 170.078211

```
[]: #Longitude write file to txt to use
     def write_info_file_long(output_file, eigen_vals, eigen_vects, amplitude, u
      →phase, V_0, Wing_MeanChord):
         # Define the variable symbols list manually
         variable_symbols_long = ['\Delta', '\Delta', '\Deltaq_bar', '\Delta_x', '\Delta_z', '\Delta0']
         # Open the output file for writing with UTF-8 encoding
         with open(output_file, 'w', encoding='utf-8') as file:
             file.
      ⇔write('----
                                                                                                --\n')
             file.write('Linearized Longitudinal Equation Results \n')
             for z in range(len(eigen_vals)):
                 i = eigen_vals[z]
                 file.
      ⇔write('-----
                 file.write(f'Dimensionless Eigen Value: {i.real:8.6f}+{i.imag:12.
      \hookrightarrow 8f}j\n')
                 sigma = -i.real
                 # Rigid Body mode
                 if i.real == 0:
                     file.write('\t Rigid Body Mode: Eigen Value: 0 \n')
                      file.write('\t No analysis required currently\n\n')
                 # Convergent Modes Sigma > 0
                 if sigma > 0:
                      # Damping rate
                     Damp_rate = sigma*2*V_0/Wing_MeanChord
                      # 99 Damping Time
                     Damp_time_99 = np.log(0.01)/-Damp_rate
                      # Damped natural frequency and Period
                      if i.imag != 0:
                          W_d = abs(i.imag)*2*V_0/Wing_MeanChord
                          Period = (2*np.pi)/W_d
                          #Damping Ratio
                          Damp_Ratio = -i.real/(np.sqrt(i.real**2 + i.imag**2))
                      file.write(f'\t Damping Rate [1/s]: {Damp_rate:12.6f}\n')
                      file.write(f'\t 99% Damping Time [s]: {Damp_time_99:12.6f}\n')
```

```
if i.imag != 0:
                     file.write(f'\t Damped Nat Freg: {W d:12.6f}\n')
                     file.write(f'\t Period: {Period:12.6f}\n')
                     file.write(f'\t Damping Ratio: {Damp_Ratio:12.6f}\n\n')
            # Divergent Modes Sigma < 0
            if sigma < 0:</pre>
                # Damping rate
                Damp_rate = sigma*2*V_0/Wing_MeanChord
                # 99 Damping Time
                Double time = np.log(2.00)/-Damp rate
                # Damped natural frequency and Period
                if i.imag != 0:
                     W_d = abs(i.imag)*2*V_0/Wing_MeanChord
                     Period = (2*np.pi)/W_d
                     #Damping Ratio
                     Damp_Ratio = -i.real/(np.sqrt(i.real**2 + i.imag**2))
                file.write(f'\t Damping Rate [1/s]: {Damp_rate:12.6f}\n')
                file.write(f'\t Doubling Time [s]: {Double_time:12.6f}\n')
                if i.imag != 0:
                     file.write(f'\t Damped Nat Freq: {W_d:12.6f}\n')
                     file.write(f'\t Period: {Period:12.6f}\n')
                     file.write(f'\t Damping Ratio: {Damp_Ratio:12.6f}\n\n')
            # Print the Eigen Vector
            file.
                                _____
 ⇔write('----
            file.write(f'{"Variable":<15} {"Real Part":<15} {"Imaginary Part":</pre>

<<20} {"Amplitude":<15} {"Phase":<15}\n')
</pre>
            eigen_vects = np.asarray(eigen_vects)
            for j in range(6):
                real = eigen_vects[j,z].real
                imag = eigen_vects[j,z].imag
                amp = amplitude[j,z].real
                phase_deg = phase[j,z].real
                symbol = variable symbols long[j]
                file.write(f'{symbol:<15} {real:<15.6f} {imag:<20.6f} {amp:<15.
 \hookrightarrow6f} {phase_deg:<15.6f}\n')
            file.
 ⇔write('-----
#Lateral write file to txt to use
def write_info_file_lat(output_file, eigen_vals, eigen_vects, amplitude, phase, u
 \rightarrowV_0, Wing_Span):
    # Define the variable symbols list manually
    variable_symbols_long = ['\Delta', '\Delta', '\Delta q_{bar'}, '\Delta_x', '\Delta_z', '\Delta\Theta']
```

```
# Open the output file for writing with UTF-8 encoding
  with open(output_file, 'w', encoding='utf-8') as file:
      file.
⇔write('-----\n')
      file.write('Linearized Lateral Equation Results \n')
      for z in range(len(eigen vals)):
          i = eigen_vals[z]
         file.
                         -----\n')
          file.write(f'Dimensionless Eigen Value: {i.real:8.6f}+{i.imag:12.
\hookrightarrow 8f}j(n')
          sigma = -i.real
          # Rigid Body mode
          if i.real == 0:
              file.write('\t Rigid Body Mode: Eigen Value: 0 \n')
             file.write('\t No analysis required currently\n\n')
          # Convergent Modes Sigma > 0
          if sigma > 0:
              # Damping rate
             Damp_rate = sigma*2*V_0/Wing_Span
              # 99 Damping Time
             Damp_time_99 = np.log(0.01)/-Damp_rate
              # Damped natural frequency and Period
              if i.imag != 0:
                 W_d = abs(i.imag)*2*V_0/Wing_Span
                 Period = (2*np.pi)/W_d
                 #Damping Ratio
                 Damp_Ratio = -i.real/(np.sqrt(i.real**2 + i.imag**2))
              file.write(f'\t Damping Rate [1/s]: {Damp_rate:12.6f}\n')
              file.write(f'\t 99% Damping Time [s]: {Damp_time_99:12.6f}\n')
              if i.imag != 0:
                 file.write(f'\t Damped Nat Freq: {W_d:12.6f}\n')
                 file.write(f'\t Period: {Period:12.6f}\n')
                 file.write(f'\t Damping Ratio: {Damp_Ratio:12.6f}\n\n')
          # Divergent Modes Sigma < 0
          if sigma < 0:</pre>
              # Damping rate
             Damp_rate = sigma*2*V_0/Wing_Span
              # 99 Damping Time
             Double_time = np.log(2.00)/-Damp_rate
              # Damped natural frequency and Period
              if i.imag != 0:
                 W_d = abs(i.imag)*2*V_0/Wing_Span
                 Period = (2*np.pi)/W_d
                 #Damping Ratio
                 Damp_Ratio = -i.real/(np.sqrt(i.real**2 + i.imag**2))
              file.write(f'\t Damping Rate [1/s]: {Damp_rate:12.6f}\n')
```

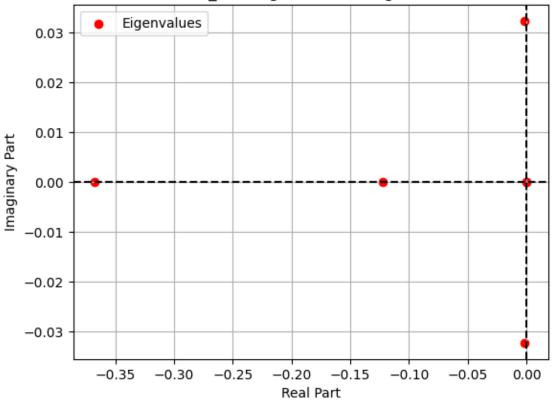
```
file.write(f'\t Doubling Time [s]: {Double_time:12.6f}\n')
                  if i.imag != 0:
                      file.write(f'\t Damped Nat Freq: {W_d:12.6f}\n')
                      file.write(f'\t Period: {Period:12.6f}\n')
                      file.write(f'\t Damping Ratio: {Damp_Ratio:12.6f}\n\n')
               # Print the Eigen Vector
               file.
     -write('-----\n')
               file.write(f'{"Variable":<15} {"Real Part":<15} {"Imaginary Part":</pre>
     \hookrightarrow<20} {"Amplitude":<15} {"Phase":<15}\n')
               eigen_vects = np.asarray(eigen_vects)
               for j in range(6):
                  real = eigen_vects[j,z].real
                  imag = eigen_vects[j,z].imag
                  amp = amplitude[j,z].real
                  phase_deg = phase[j,z].real
                  symbol = variable_symbols_lat[j]
                  file.write(f'{symbol:<15} {real:<15.6f} {imag:<20.6f} {amp:<15.
     \hookrightarrow6f} {phase_deg:<15.6f}\n')
              file.
     ⇔write('-----
[]: # Write the results to a file
    write info file lat(Output File Lat, eigen vals lat, eigen vects lat, amplitude lat, phase lat, V (
    write_info_file_long(Output_File_Long,eigen_vals_long,eigen_vects_long,amplitude_long,phase_long)
[]: def mat_to_file(matrix_A, matrix_B, matrix_C, file_name, Mode_type=str):
       with open(file_name, 'w') as file:
           file.
     write('-----\n')
           file.write(f'{Mode_type} A and B matrix Results:\n')
     uwrite('-----\n')
           file.write("Matrix A:\n")
           file.
     write('----\n')
           for row in matrix A:
               formatted_row = ["{:12.7f}".format(element) for element in row]
               file.write(" ".join(formatted_row) + '\n')
           file.
           file.write("Matrix B:\n")
           file.
```

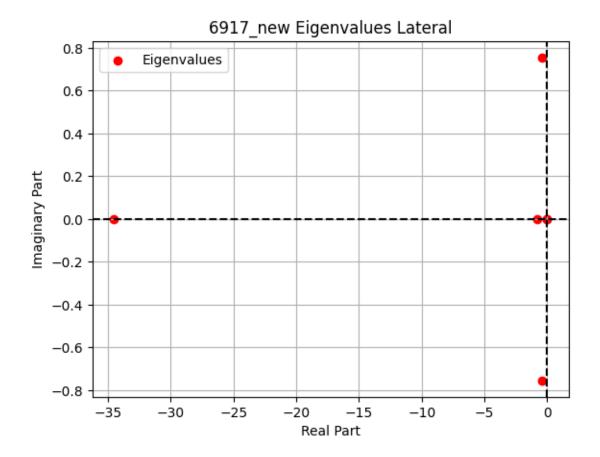
```
for row in matrix_B:
                formatted_row = ["{:12.7f}".format(element) for element in row]
               file.write(" ".join(formatted_row) + '\n')
            file.
      ⇔write('-----\n')
            file.write("Matrix C:\n")
            file.
      -write('-----\n')
            for row in matrix_C:
               formatted_row = ["{:12.7f}".format(element) for element in row]
                file.write(" ".join(formatted_row) + '\n')
[]: #Write the matrices to a file, long is one file lat is another file should have
     → the long matrices
    mat_to_file(A_mat_long,B_mat_long,C_mat_long,Output_File_Long_mat,"Longitudinal")
    mat_to_file(A_mat_lat,B_mat_lat,C_mat_lat,Output_File_Lat_mat,"Lateral")
[]: #Creating the EigenValuePlots
    print(eigen_vals_long)
    print(eigen_vals_lat)
    #Eigenvals #needs to be dimensional eigenvalues for plot, shows more
    long_real = [val.real for val in eigen_vals_long]
    long_imag = [val.imag for val in eigen_vals_long]
    lat_real =[val.real for val in eigen_vals_lat]
    lat_imag = [val.imag for val in eigen_vals_lat]
    #Longitudinal
    Long_plot = plt.figure()
    plt.scatter(long_real,long_imag,color='red',label='Eigenvalues')
    plt.axhline(0, color='black', linestyle='--')
    plt.axvline(0, color='black', linestyle='--')
    plt.xlabel('Real Part')
    plt.ylabel('Imaginary Part')
    plt.title(f'{base_name} Eigenvalues Longitudinal')
    plt.legend()
    plt.grid(True)
    Long_plot.savefig(f'{base_name}/Long_Eig_plot.png',dpi=200)
    plt.show()
    #Lateral
    Lat_plot = plt.figure()
    plt.scatter(lat_real,lat_imag,color='red',label='Eigenvalues')
```

plt.axhline(0, color='black', linestyle='--')

```
plt.axvline(0, color='black', linestyle='--')
plt.xlabel('Real Part')
plt.ylabel('Imaginary Part')
plt.title(f'{base_name} Eigenvalues Lateral')
plt.legend()
plt.grid(True)
Lat_plot.savefig(f'{base_name}/Lat_Eig_plot.png',dpi=200)
plt.show()
```

## 6917\_new Eigenvalues Longitudinal





```
print(f'Double Time: {np.log(2.00)/Damp_rate_sp}')
     else:
         print(f'Damp Time 99%: {np.log(0.01)/(-Damp_rate_sp)}')
     if Frequency_sp != 0:
         print(f'Damped Frequency[rad/s]: {Frequency_sp}')
         print(f'Period [s]: {2*np.pi/Frequency_sp}')
     #Phugoid Mode
     sigma_D = (g/V_0)*(CD_0/CL_0)
     sigma_q = (g/V_0)*((Cm_qbar*(CL_0-CD_alpha))/
      → (R_rhox*Cm_alpha+(CD_0+CL_alpha)*Cm_qbar))
     R ps = (R rhox*Cm alpha)/(R rhox*Cm alpha + Cm qbar*(CD 0 + CL alpha))
     sigma_phi = -(g/V_0)*R_gx*R_ps*((R_rhox*Cm_qbar-R_yy*(CD_0+CL_alpha))/
      →(R_rhox*Cm_alpha + (CD_0+CL_alpha)*Cm_qbar))
     Damp_rate_phug = sigma_D + sigma_q + sigma_phi
     Frequency_phug = np.sqrt(2*R_ps*(g/V_0)**2 - (sigma_D+sigma_q)**2)
     print(f'\nPhugoid Mode:\n')
     print(f'Damping Rate: {Damp_rate_phug}')
     if Damp_rate_phug < 0:</pre>
         print(f'Double Time: {np.log(2.00)/Damp_rate_phug}')
     else:
         print(f'Damp Time 99%: {np.log(0.01)/(-Damp_rate_phug)}')
     if Frequency_phug != 0:
         print(f'Damped Frequency[rad/s]: {Frequency phug}')
         print(f'Period [s]: {2*np.pi/Frequency_phug}')
    Long. Mode Approximation
    Short Period Mode:
    Damping Rate: 10.795802372184895
    Damp Time 99%: 0.42657044166102864
    Damped Frequency[rad/s]: 6.156358534650823
    Period [s]: 1.0206009399574316
    Phugoid Mode:
    Damping Rate: 0.03567998429740071
    Damp Time 99%: 129.06872793449008
    Damped Frequency[rad/s]: 1.4748504198606485
    Period [s]: 4.260218678836091
[]: # Lateral Mode Approximations
```

```
print(f'Lateral Mode Approximation \n')
#Roll Mode
sigma_r = ((-V_0*Air_Density*Wing_Area*Wing_Span**2)/(4*I_xx))*Cl_pbar
print(f'\nDamping Rate Roll Mode: {sigma_r}')
if sigma r > 0:
    print(f'Damping Time 99%: {np.log(0.01)/-sigma_r}')
else:
    print(f'Doubling Time: {np.log(2)/sigma_r}')
#spiral mode
sigma_spiral = (g/V_0)*((Cl_beta*Cn_rbar - Cl_rbar*Cn_beta)/(Cl_beta*Cn_pbar - U_0)

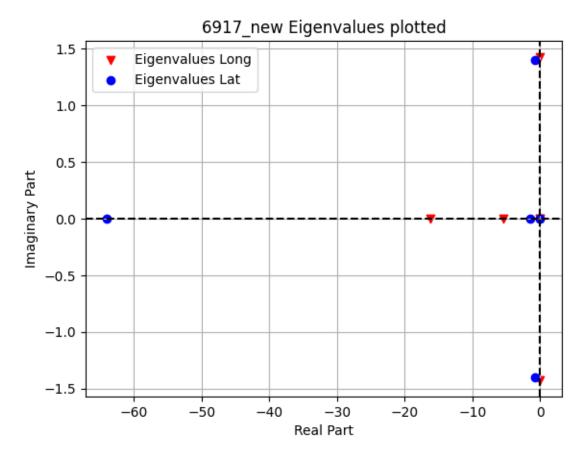
GCl_pbar*Cn_beta))
print(f'\nDamping Rate Spiral Mode: {sigma_spiral}')
if sigma spiral > 0:
    print(f'Damping Time 99%: {np.log(0.01)/-sigma_spiral}')
else:
    print(f'Doubling Time: {np.log(2)/-sigma_spiral}')
#Dutch Roll Approx
R_Ds = (Cl_beta*(R_gy*R_rhoy*R_zz-(R_rhoy-CY_rbar)*Cn_pbar)_
 ←-CY_beta*Cl_rbar*Cn_pbar)/(R_rhoy*R_zz*Cl_pbar)
sigma_dr = (-V_0/Wing_Span)*(CY_beta/R_rhoy + Cn_rbar/R_zz - (Cl_rbar*Cn_pbar)/
 →(Cl_pbar*R_zz) + (R_gy*(Cl_rbar*Cn_beta - Cl_beta*Cn_rbar))/
Gl pbar*(Cn beta+CY beta*Cn rbar/R rhoy)) - R xx*(R Ds/Cl pbar))
Frequency_dr = (2*V_0/Wing_Span)*np.sqrt((1-CY_rbar/R_rhoy)*(Cn_beta/R_zz) +__
 GY_beta*Cn_rbar)/(R_rhoy*R_zz) + R_Ds -0.25*(CY_beta/R_rhoy + Cn_rbar/
\rightarrow R_zz)**2
print(f'\nDamping Rate Dutch Roll Mode: {sigma dr}')
if sigma_dr > 0:
    print(f'Damping Time 99%: {np.log(0.01)/-sigma_dr}')
else:
    print(f'Doubling Time: {np.log(2)/-sigma_dr}')
if Frequency dr != 0:
    print(f'Damped Frequency[rad/s]: {Frequency_dr}')
    print(f'Period [s]: {2*np.pi/Frequency_dr}')
#print results
```

Lateral Mode Approximation

```
Damping Time 99%: 0.07345229071931689
    Damping Rate Spiral Mode: 4.846484274436409
    Damping Time 99%: 0.950208424337376
    Damping Rate Dutch Roll Mode: 1.7671176647259874
    Damping Time 99%: 2.6060348316998896
    Damped Frequency[rad/s]: 1.1592683527698955
    Period [s]: 5.419957589773645
[]: #Problem A14: Print the dimensional eigenvalues for the short period, phugoid,
     ⇔roll, spiral and dutch roll modes
     #On a single graph
     long_co = 2*V_0/Wing_MeanChord
     lat_co = 2*V_0/Wing_Span
     print(eigen_vals_long)
     print(eigen_vals_lat)
     eigen_vals_long_dim = np.asarray(eigen_vals_long)*long_co
     eigen_vals_lat_dim = np.asarray(eigen_vals_lat)*lat_co
     #Eigenvals #needs to be dimensional eigenvalues for plot, shows more
     long_real = [val.real for val in eigen_vals_long_dim]
     long_imag = [val.imag for val in eigen_vals_long_dim]
     lat_real =[val.real for val in eigen_vals_lat_dim]
     lat_imag = [val.imag for val in eigen_vals_lat_dim]
     #Longitudinal
     Eig_both = plt.figure()
     plt.scatter(long_real,long_imag,color='red',label='Eigenvalues Long',marker='v')
     plt.scatter(lat_real,lat_imag,color='blue',label='Eigenvalues Lat',marker='o')
     plt.axhline(0, color='black', linestyle='--')
     plt.axvline(0, color='black', linestyle='--')
     plt.xlabel('Real Part')
     plt.ylabel('Imaginary Part')
     plt.title(f'{base_name} Eigenvalues plotted')
     plt.legend()
     plt.grid(True)
     Eig_both.savefig(f'{base_name}/Eig_both_plot.png',dpi=200)
    plt.show()
    [ 0.
                +0.j
                                        +0.j
                                                     -0.36743301+0.j
                             -0.00194656+0.03233351j -0.00194656-0.03233351j]
     -0.12234424+0.j
    Γ 0.
                                0.
                                          +0.j
     -34.51729821+0.j
                               -0.81854038+0.j
```

Damping Rate Roll Mode: 62.696073068514906

## -0.42559321+0.75475346j -0.42559321-0.75475346j]



Undamped Natural Frequency: 9.34784611423023

CAP Value: 13.222627365519735

```
[]: #A 16, compute the handling qualities for the baseline glider Category B flight
      \hookrightarrowphases
     #Get all the needed values for each mode
     #shortperiod
     def shortperiod_B_handleval(eigenvalue1,eigenvalue2,vel,chord,CL_alpha,CW):
         #get the cap value
         wn_sp = np.sqrt((eigenvalue1*eigenvalue2))*(2*vel/chord)
         print(wn_sp)
         print(CL_alpha/CW)
         CAP = wn_sp**2/(CL_alpha/CW)
         print(f'Short Period CAP value: {round(CAP.real,4)}\n')
         #now we need the squiggle of the Short period
         num = -(eigenvalue1+eigenvalue2)
         denom = np.sqrt((eigenvalue1*eigenvalue2))
         squiggle = num/denom
         #give value dependent on CAP and Squiggle
         if 0.30 < squiggle < 2.00:</pre>
             print(f'Short Period Handling Level: 1\n')
         elif 0.20 < squiggle < 2.00:</pre>
             print(f'Short Period Handling Level: 2\n')
         elif 0.16 < squiggle:</pre>
             print(f'Short Period Handling Level: 3\n')
         else:
             print(f'Short Period Handling Level: 4, Iteration of Design Required\n')
     #phugoid
     def phugoid_B_handleval(eigenvalue1,eigenvalue2):
         sigma = -eigenvalue1.real
         #evaluate the squiggle
         num = -(eigenvalue1+eigenvalue2)
         denom = np.sqrt((eigenvalue1.real*eigenvalue2.real))
         squiggle = num/denom
         if sigma > 0:
             if sigma > 0.04:
                 print(f'Phugoid Handling Level: 1\n')
             else:
                 print(f'Phugoid Handling Level: 2\n')
         else:
             #check the doubling time
```

```
double_time = -np.log(2.00)/sigma
        print(f'Divergent Mode: Doubling Time {round(double time,2)}[sec]\n')
        if double_time > 55:
            print(f'Phugoid Handling Level: 3\n')
        else:
            print(f'Phugoid Handling Level: 4, Iteration of Design Required\n')
#Roll
def roll_B_handleval(eigenvalue):
    sigma = -eigenvalue.real
    HandlingQual = 1/sigma
    #give rating dependent on this value
    if HandlingQual > 0:
        if HandlingQual < 1.4:</pre>
            print(f'Roll Handling Level: 1\n')
        if 1.4 < HandlingQual < 3.0:</pre>
            print(f'Roll Handling Level: 2\n')
        if 3.0 < HandlingQual < 10.0:</pre>
            print(f'Roll Handling Level: 3\n')
        if HandlingQual > 10.0:
            print(f'Roll Handling Level: 4, Iteration of Design Required\n')
    else:
        print(f'Roll Handling Level: 4 Iteration of Design Required\n')
#dutch roll
def dutch_roll_B_handlevel(eigenvalue1, eigenvalue2, vel, span):
    #qet the cap value
    wn_dutch = np.sqrt((eigenvalue1*eigenvalue2))*(2*vel/span)
    #now we need the squiggle of the Short period
    num = -(eigenvalue1+eigenvalue2)
    denom = np.sqrt((eigenvalue1.real*eigenvalue2.real))
    squiggle = num/denom
    cond_1 = squiggle
    cond_2 = squiggle*wn_dutch
    cond_3 = wn_dutch
    #Conditions for handling
    #first is it is divergent it is unacceptable
    if squiggle < 0:</pre>
        print(f'Ducth Roll Handling Level: 4, Iteration of Design Required\n')
    else:
        if cond_1 > 0.08 and cond_2 > 0.15 and cond_3 > 0.4:
```

```
print(f'Dutch Roll Handling Level: 1\n')
        elif cond_1 > 0.02 and cond_2 > 0.05 and cond_3 > 0.4:
            print(f'Dutch Roll Handling Level: 2\n')
        elif cond_1 > 0.00 and cond_3 > 0.4:
            print(f'Dutch Roll Handling Level: 3\n')
        else:
            print(f'Dutch Roll Handling Level: 4, Iteration of Design
 ⇔Required\n')
#spiral
def spiral_B_handlevel(eigenvalue):
    sigma_spiral = -eigenvalue.real
    if sigma_spiral < 0:</pre>
        double_time = np.log(2.00)/-sigma_spiral
        if double_time > 20:
            print(f'Spiral Handling Level: 1\n')
        elif 20 > double_time > 12:
            print(f'Spiral Handling Level: 2\n')
        elif 12 > double_time > 4:
            print(f'Spiral Handling Level: 3\n')
        else:
            print(f'Spiral Handling Level: 4, Interation of Design Required\n')
    else:
        print(f'Spiral Handling Level: 1\n')
```

```
#Body the Eigenvalues to each mode

#phugoid mode

Phugoid_eigenvalue_1 = eigen_vals_long[4]
Phugoid_eigenvalue_2 = eigen_vals_long[5]
phugoid_B_handleval(Phugoid_eigenvalue_1,Phugoid_eigenvalue_2)
#short period mode

Short_pred_eigenvalue_1 = eigen_vals_long[3]
Short_pred_eigenvalue_2 = eigen_vals_long[2]

shortperiod_B_handleval(Short_pred_eigenvalue_1,Short_pred_eigenvalue_2,vel=V_0,chord=Wing_Mea
#Roll

Roll_eigenval = eigen_vals_lat[2]
roll_B_handleval(Roll_eigenval)
```

#spiral

```
Spiral_eigenval = eigen_vals_lat[5]
     spiral_B_handlevel(Spiral_eigenval)
     #dutchroll
     dutch_eigenval_1 = eigen_vals_lat[3]
     dutch_eigenval_2 = eigen_vals_lat[4]
     dutch_roll_B_handlevel(dutch_eigenval_1,dutch_eigenval_2,vel=V_0,span=Wing_Span)
    Phugoid Handling Level: 2
    (9.34784611423023+0j)
    6.608537362490705
    Short Period CAP value: 13.2226
    Short Period Handling Level: 3
    Roll Handling Level: 1
    Spiral Handling Level: 1
    Dutch Roll Handling Level: 1
[]: #Plot of all the eigenvalues with the modes labeled
     #get the dimensional eigenvalues
     #Phuqoid
     Phugoid_eigenvalue_1 = eigen_vals_long_dim[4]
     Phugoid_eigenvalue_2 = eigen_vals_long_dim[5]
     #short period mode
     Short_pred_eigenvalue_1 = eigen_vals_long_dim[3]
     Short_pred_eigenvalue_2 = eigen_vals_long_dim[2]
     #Roll
     Roll_eigenval = eigen_vals_lat_dim[2]
     #spiral
     Spiral_eigenval = eigen_vals_lat_dim[5]
     #dutchroll
     dutch_eigenval_1 = eigen_vals_lat_dim[4]
```

```
dutch_eigenval_2 = eigen_vals_lat_dim[3]
#Put everyything into one figure to see
Eigen_dim_plot = plt.figure()
plt.scatter(Phugoid_eigenvalue_1.real,Phugoid_eigenvalue_1.
 plt.scatter(Phugoid eigenvalue 2.real,Phugoid eigenvalue 2.
 →imag,color='red',marker='v')
plt.scatter(Short_pred_eigenvalue_2.real,Short_pred_eigenvalue_2.

→imag,color='orange',label='Short Period',marker='x')
plt.scatter(Short_pred_eigenvalue_1.real,Short_pred_eigenvalue_1.
 →imag,color='orange',marker='x')
plt.scatter(dutch_eigenval_1.real,dutch_eigenval_1.
 →imag,color='blue',label='Dutch Roll',marker='o')
plt.scatter(dutch_eigenval_2.real,dutch_eigenval_2.imag,color='blue',marker='o')
plt.scatter(Spiral_eigenval.real,Spiral_eigenval.
 plt.scatter(Roll_eigenval.real,Roll_eigenval.
 →imag,color='cyan',label='Roll',marker='^')
plt.axhline(0, color='black', linestyle='--')
plt.axvline(0, color='black', linestyle='--')
plt.xlabel('Real Part')
plt.ylabel('Imaginary Part')
plt.title(f'{base_name} Eigenvalues plotted')
plt.legend()
plt.grid(True)
Eigen_dim_plot.savefig(f'{base_name}/Eig_Model_labeled.png',dpi=200)
plt.show()
```

