

1.15 If the main wing and horizontal stabilizer both have zero mounting angles, compute the angle of attack and elevator deflection required to trim the aircraft in a steady climb at an altitude of 5,000 ft and a climb angle of 20 deg at a speed of 200 mph.

$$\gamma = 20^\circ \quad V_\infty = 293.33 \text{ ft/s}$$

$$\gamma = 0.002048$$

$$\begin{bmatrix} C_{L,\alpha} & C_{L,\delta_e} \\ C_{m,\alpha} & C_{m,\delta_e} \end{bmatrix} \begin{bmatrix} \alpha \\ \delta_e \end{bmatrix} = \begin{bmatrix} C_L - C_{L_0} \\ -C_{m_0} \end{bmatrix}$$

$$C_{L_0} = 0$$

$$\alpha_{eh} = 0 \quad \alpha_{ow} = 0$$

$$C_L = \frac{\cos(20^\circ) 18375}{\frac{1}{2} (0.002048) (293.33)^2 244}$$

$$C_L = 0.366$$

$$C_{L_0} = C_{L_{wh}} (-\alpha_{ow}) = 4.62 \left( -2.2^\circ \cdot \frac{\pi}{180} \right) = -0.1774$$

$$C_L - C_{L_0} = 0.5434$$

$$C_{L,\alpha} = 5.13$$

$$C_{L,\delta_e} = \frac{S_{h,c_h}}{S_w} (1) C_{L_{h,\alpha}} \xi_e = \frac{31}{244} (4.06 (0.6)) = 0.30949$$

$$C_{m,\alpha} = \frac{S_{h,c_h}}{S_w C_w} = 1.4139$$

$$C_{m,\delta_e} = \frac{S_{h,c_h}}{S_w C_w} (1) C_{m_{h,\delta_e}} - \frac{S_{h,c_h}}{S_w C_w} (1) C_{L_{h,\alpha}} \xi_e = \frac{31 (2.913)}{244 (6.625)} (-0.55) - \frac{31 (18.16)}{244 (6.625)} 4.06 (0.6)$$

$$C_{m,\delta_e} = -0.879$$

$$C_{m_0} = C_{m_w} - \frac{l_w}{c_w} C_{m_{wd}} (\alpha_{ow} - \alpha_{eh}) - \frac{S_{h,c_h}}{S_w} (\alpha_{eh} - \epsilon_{db}) \quad C_{m_0} = 0$$

$$\begin{bmatrix} 5.13 & 0.3095 \\ 1.4139 & -0.879 \end{bmatrix} \begin{bmatrix} \alpha \\ \delta_e \end{bmatrix} = \begin{bmatrix} 0.5434 \\ 0 \end{bmatrix} \Rightarrow \alpha = 0.096 \text{ rad} \quad \delta_e = 0.1553$$

$$S_w = A_{ref} = \bar{C}_w \cdot L_w$$

$$R_{ow} = \frac{L_w}{c_w}$$

$$\alpha = 5.500^\circ$$

$$\delta_e = 8.898^\circ$$

$$n_h = \dots$$

1.10 Combine the solutions from problems 1.6, 1.7, 1.8, and 1.9 to develop equations for the lift coefficient and pitching-moment of the aircraft as a function of wing and horizontal stabilizer geometric and aerodynamic properties, as well as the elevator deflection.

$$C_L = \underbrace{[C_{Lw,\alpha} + n_h \frac{S_h}{S_w} C_{Lh,\alpha} (1 - \epsilon_{d,\alpha})]}_{C_{L,\alpha}} \alpha + \underbrace{[\frac{S_h}{S_w} n_h C_{Lh,\alpha} \epsilon_c]}_{C_{L,\delta_e}} \delta_e =$$

$$C_w \cos \delta - \underbrace{[C_{Lw,\alpha} (\alpha_{cw} - \alpha_{Lcw}) - \frac{S_h}{S_w} n_h C_{Lh,\alpha} (\alpha_{ch} - \alpha_{Lch} - \epsilon_{db})]}_{C_{L0} \text{ "geometric."}}$$

$$C_{mw} + \frac{S_h \bar{C}_m}{S_w \bar{C}_w} n_h C_{mh,\delta_e} \delta_e - \frac{h_w}{\bar{c}_w} C_{mw,\alpha} (\alpha + \alpha_{cw} - \alpha_{Lcw}) - \frac{S_h h_h}{S_w \bar{c}_w} n_h C_{mh,\alpha} [(1 - \epsilon_{d,\alpha}) \alpha + \alpha_{ch} - \epsilon_{db} + \epsilon_c \delta_e] = 0$$

1.11 Starting from the pitching-moment equation developed in problem 1.10, develop an expression for the pitch stability criteria as a function of the wing and horizontal stabilizer geometric and aerodynamic properties.

$$\left[ -\frac{h_w}{\bar{c}_w} C_{mw,\alpha} - \frac{S_h h_h}{S_w \bar{c}_w} n_h C_{mh,\alpha} (1 - \epsilon_{d,\alpha}) \right] \alpha + \left[ \frac{S_h \bar{C}_m}{S_w \bar{c}_w} n_h C_{mh,\delta_e} - \frac{S_h h_h}{S_w \bar{c}_w} n_h C_{mh,\alpha} \epsilon_c \right] \delta_e =$$

$$- \left[ C_{mw} - \frac{h_w}{\bar{c}_w} C_{mw,\alpha} (\alpha_{cw} - \alpha_{Lcw}) - \frac{S_h h_h}{S_w \bar{c}_w} n_h C_{mh,\alpha} (\alpha_{ch} - \epsilon_{db}) \right] C_{m,\alpha}$$

$$C_{m,\alpha} = \left[ \dots \right] < 0$$

1.12 For an aircraft to be trim, both equations in problem 1.10 must be satisfied. This provides a system of two equations that can be expressed in terms of two unknown operating parameters,  $\alpha$  and  $\delta_e$  as

$$\begin{bmatrix} C_{L,\alpha} & C_{L,\delta_e} \\ C_{m,\alpha} & C_{m,\delta_e} \end{bmatrix} \begin{Bmatrix} \alpha \\ \delta_e \end{Bmatrix} = \begin{bmatrix} C_L - C_{L0} \\ -C_{m0} \end{bmatrix}$$

where the known geometric and aerodynamic information of the aircraft is contained in the variables

$$C_{L,\alpha} = C_{Lw,\alpha} + \frac{S_h}{S_w} n_h C_{Lh,\alpha} (1 - \epsilon_{d,\alpha})$$

$$C_{L,\delta_e} = \frac{S_h}{S_w} n_h C_{Lh,\alpha} \epsilon_c$$

$$C_L = \frac{W}{\frac{1}{2} \rho V_{\infty}^2 S_w}$$

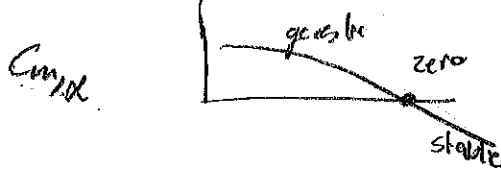
$$C_{L0} = \frac{W}{\frac{1}{2} \rho V_{\infty}^2 S_w}$$

$$C_{m,\alpha} = -\frac{h_w}{\bar{c}_w} C_{mw,\alpha} + \frac{S_h h_h}{S_w \bar{c}_w} n_h C_{mh,\alpha} (1 - \epsilon_{d,\alpha})$$

$$C_{m,\delta_e} = \frac{S_h \bar{C}_m}{S_w \bar{c}_w} n_h C_{mh,\delta_e} - \frac{S_h h_h}{S_w \bar{c}_w} n_h C_{mh,\alpha} \epsilon_c$$

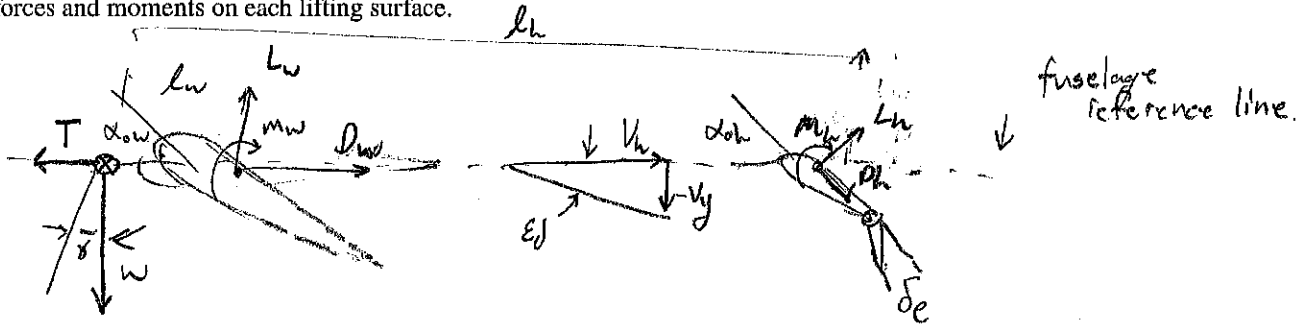
$$C_{m0} = C_{mw} - \frac{h_w}{\bar{c}_w} C_{mw,\alpha} (\alpha_{cw} - \alpha_{Lcw}) - \frac{S_h h_h}{S_w \bar{c}_w} n_h C_{mh,\alpha} (\alpha_{ch} - \epsilon_{db})$$

$$\begin{bmatrix} \frac{1}{2} \rho V_{\infty}^2 S_w \\ \frac{1}{2} \rho V_{\infty}^2 S_w \end{bmatrix} \begin{bmatrix} C_L \\ C_m \end{bmatrix} = \begin{bmatrix} W \\ -M \end{bmatrix}$$



$C_{m,d}$

1.3 Consider a conventional aircraft with a main wing and horizontal tail. Assume the main wing, horizontal stabilizer, and center of gravity all lie along the fuselage reference line, and that the thrust and fuselage reference line are aligned with the direction of flight. Draw a side view of the aircraft with the longitudinal forces and moments labeled including the forces and moments on each lifting surface.



$[w \ h]$

$$\alpha_{o,all} = \alpha_{oh} + \alpha_{dw}$$

$$\frac{1}{2} \rho V^2 C_w S_w$$

$\alpha_{oh}$

$$\sin(\theta) = \theta$$

4.3)

1.4 Using the aircraft given in problem 1.3 write an equation for the force balance in the direction of lift if the aircraft is trimmed with a climb angle of  $\gamma$ . Apply the small-angle approximation for the downwash angle and drop very small terms.

Eq 4.3.2

$\epsilon_d = \text{down wash}$

Small angle consideration

$$L = L_w + L_h \cos \epsilon_d - D_h \sin \epsilon_d = W \cos \gamma$$

$$L = L_w + L_h - D_h \epsilon_d = W \cos \gamma \quad 4.3.2$$

1.5 Using the aircraft given in problem 1.3, write an equation for the pitching-moment if the aircraft is trimmed with a climb angle of  $\gamma$ . Apply the small-angle approximation for the downwash angle and drop very small terms.

$$M = M_w + M_h - l_w L_w - l_h L_h \cos \epsilon_d + l_h D_h \sin \epsilon_d = 0$$

$$M = M_w + M_h - l_w L_w - l_h L_h + l_h D_h \epsilon_d = 0$$