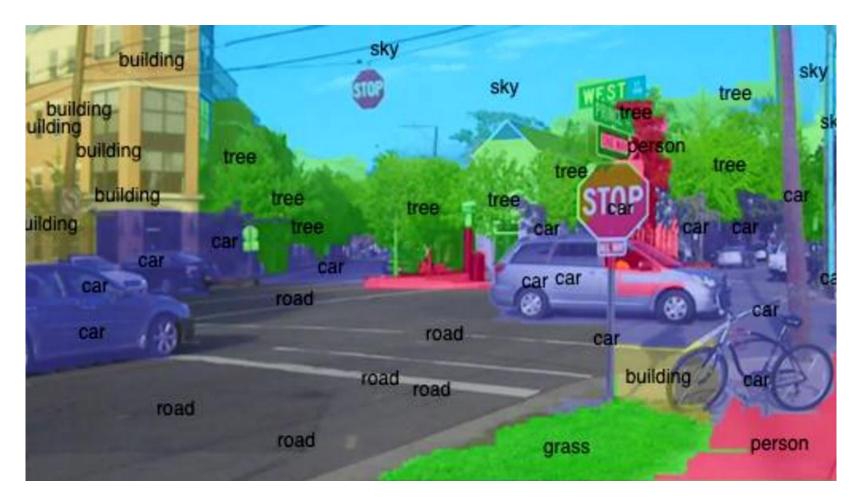
Intro to Computer Vision



Yoni Chechik

www.AlisMath.com

contents

- Course details
- What is computer vision (CV)?
- Course outline
- Intro to Python

References

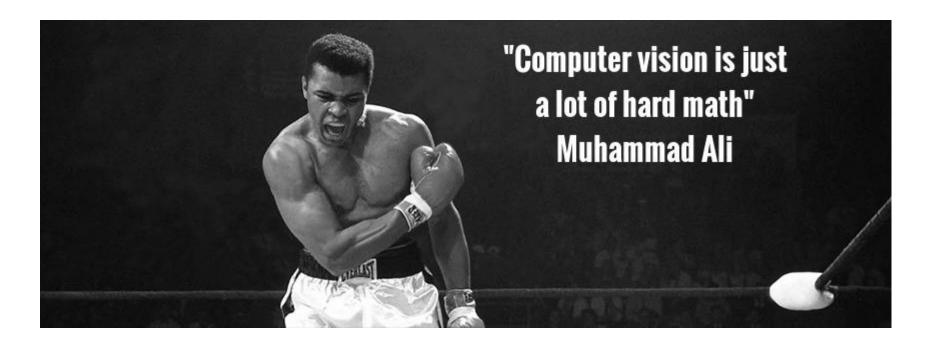
Lectures Based on the book: Computer Vision:
 Algorithms and Applications, 2010, Richard Szeliski (http://szeliski.org/Book/)

Course objectives

- The student will know and understand key algorithms in computer vision.
- The student will be familiar with the algorithmic R&D process, with an emphasis on understanding the advantages and disadvantages of various algorithms and building an algorithmic system that concentrates on computer vision and image processing.
- The student will be able to solve algorithmic problems with computer vision both at theoretical and practical level (in Python using NumPy, Matplotlib, OpenCV & TensorFlow packages).

Prerequisites

- No prior knowledge in signal/image processing is assumed.
- Heavy use in algebra and calculus- mathematical maturity is assumed.

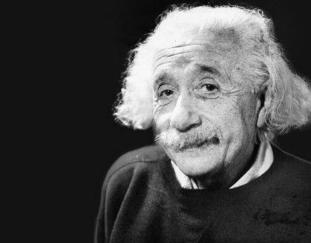


contents

- Course details
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Don't believe
everything you read
on the internet just
because there's a
picture with a quote
next to it.

ALBERT EINSTEIN

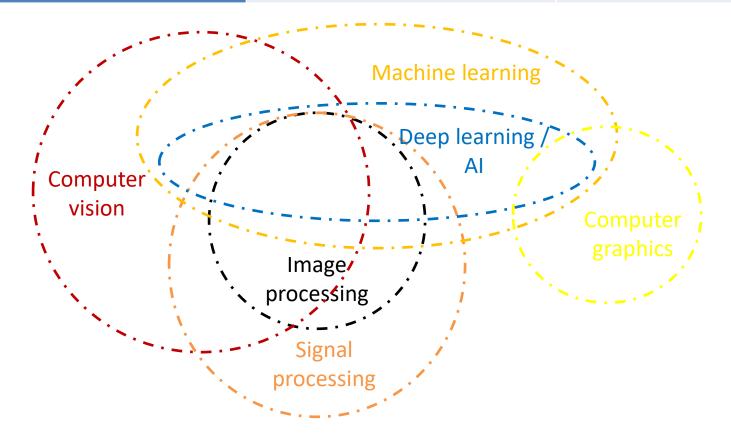


What is CV?

- Computer vision is an interdisciplinary scientific field that deals with how computers can be made to gain high-level understanding from digital images or videos. [Wikipedia]
- Image processing is an umbrella term for many functions that analyze images or convert one representation of an image into another.

What is CV?

| Output | Data | Image |
|--------|-------------------|-------------------|
| Data | Signal processing | Computer graphics |
| Image | Computer vision | Image processing |



Why CV?

Top Public Company Acquirors



Embedded Vision/Computer Vision M&A Company & Moodstocks Alphabet DNNresearch Undecidable! October - 2012 March - 2013 July - 2016 October - 2016 \$45.0M NA NA NA PrimeSense **EMOTIENT** REALFACE November - 2013 January - 2016 February - 2017 January - 2016 \$360.0M NA NA NA Chiaro Assist Ware *Ao ense* COGNEX **Technologies** November - 2016 May - 2005 July - 2008 August-2016 \$115.0M \$3.0M \$2.4M \$4.7M **a**works Movidius 34 MOBILEYE April - 2012 May - 2016 September - 2016 September - 2017 \$31.0M NA \$392.1M \$15,300.0M



EUVISION

September - 2014

NA

SCYFER

August - 2017

NA

kooaba

January - 2014

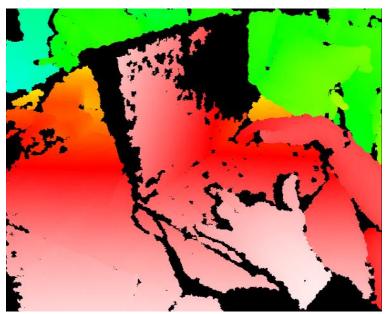
NA

PrimeSense == Kinect

- Kinect for Xbox 360: 3D scanner system using Light
 Coding approach for 3D reconstruction.
- KinectFusion [Newcombe et al., 2011] : https://www.youtube.com/watch?v=KOUSSIKUJ-A







Why CV?

Top Public Company Acquirors



Company

Embedded Vision/Computer Vision M&A

Alphabet





March - 2013

NA





July – 2016







\$45.0M





NA



November – 2013 \$360.0M



January – 2016 NA

AQ ense







ision Sensors
May – 2005
\$115.0M



July – 2008 August – 2016 \$3.0M \$2.4M



November – 2016 \$4.7M





April – 2012 \$31.0M



May – 2016 NA



September – 2016 \$392.1M



September – 2017 \$15,300.0M





January – 2014 NA



September – 2014 NA



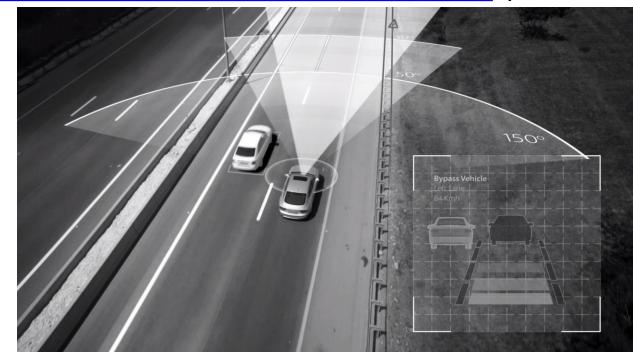
August – 2017 NA

Mobileye

- Mobileye is an Israeli subsidiary of Intel corporation that develops vision-based advanced driver-assistance systems (ADAS) providing warnings for collision prevention and mitigation. [Wikipedia]
- https://www.youtube.com/watch?v=JDUb6CurYJM

https://www.youtube.com/watch?v=fKXztwtXaGo (Tesla-

cooler!)



Why CV?

StartupHub.ai

ISRAEL'S COMPUTER VISION STARTUPS

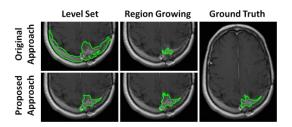


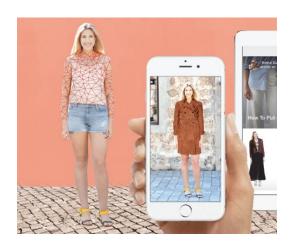
© DANIEL SINGER 2019

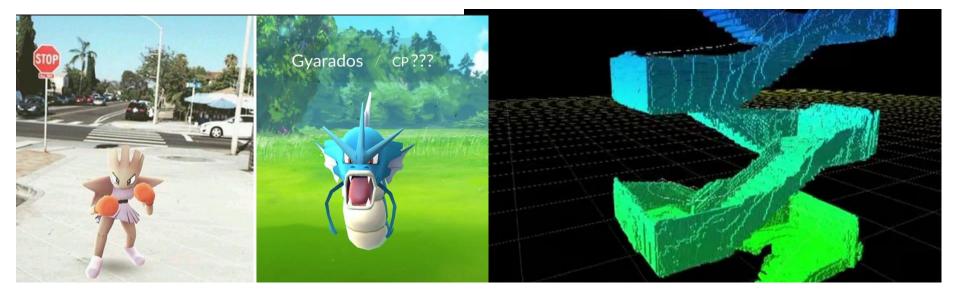
More CV related topics

- Virtual/augmented reality
- navigation
- Gaming
- medicine
- And much more...

Segmentation Results







contents

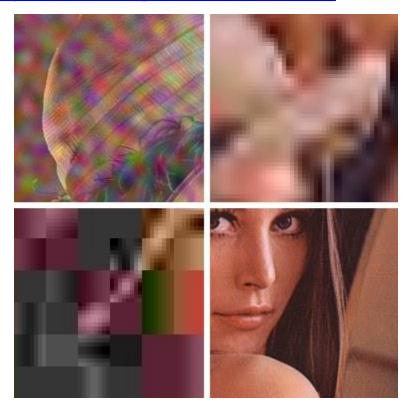
- Course details
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- Course outline
- Intro to Python

Course outline

| # | subject |
|----|--|
| 1 | Introduction to CV + Python: NumPy, Matplotlib, OpenCV |
| 2 | Image processing recap: convolutions, LPF, HPF, morphology, connected components, gamma correction, decimation, interpolation. |
| 3 | Edge detection: gradient (roberts, prewitt, sobel), Laplacian, DoG (derivative of Gaussian), canny edge detector. |
| 4 | Curve fitting: least squares, total least squares, RANSAC, Hough transform. |
| 5 | Image formation: BRDF, pinhole camera, digital camera |
| 6 | Geometric transformation: 2d->2d, 3d->3d, 3d->2d (perspective and homographic projection) |
| 7 | Camera calibration: extrinsic, intrinsic, radial distortion. |
| 8 | Stereo vision: dual camera rectification, triangulation. |
| 9 | Features: feature detection, feature description, matching, SIFT, panoramas. |
| 10 | Stereo: SfM, Epipolar geometry, rectification, triangulation, matching. |
| 11 | Neural networks 1: intro, perceptron, dense layers, MNIST. |
| 12 | Neural Networks 2: CNN, back-propagation, tensorflow. |

Image processing

 Read more about Lenna – the standard test image: https://en.wikipedia.org/wiki/Lenna

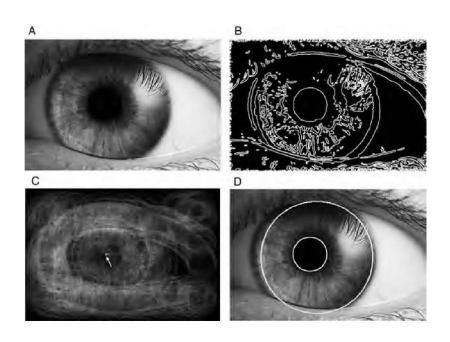


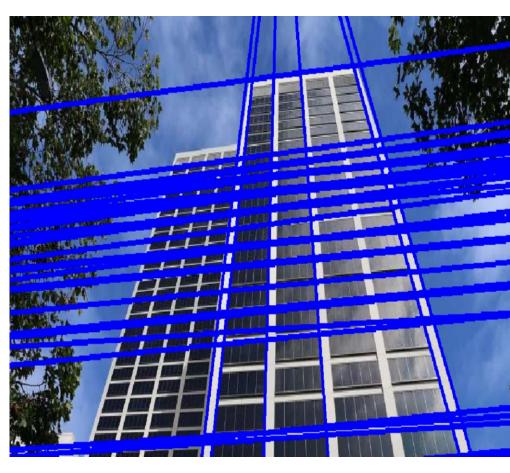
Edge Detection

- https://www.youtube.com/watch?v=hQ-bpfdWQh8
- https://pinetools.com/image-edge-detection



Curve fitting & Hough transform

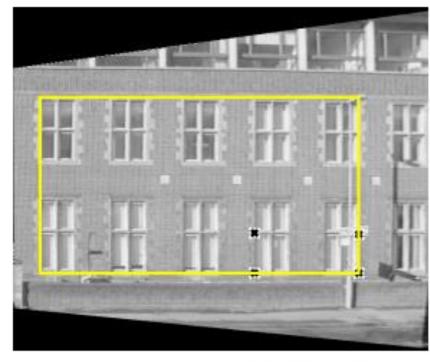




Digital cameras

- Image formation: https://www.youtube.com/watch?v=dY0K65eXhkA
 - 2D & 3D transformation.





from Hartley & Zisserman

Image calibration

• Fisheye correction from go-pro for example



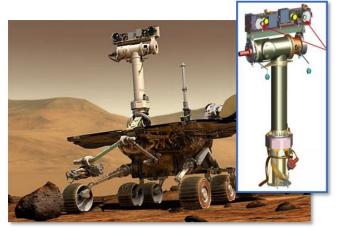
Stereo & 3d cameras

https://www.youtube.com/watch?v=PySBQ8Q_R8k

















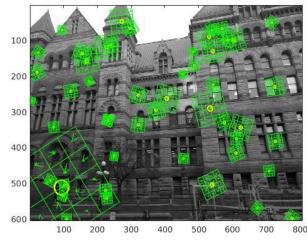




(a)

Features

- Extract interesting points from image for later recognition, stitching, learning and more.
- http://www.in2white.com/

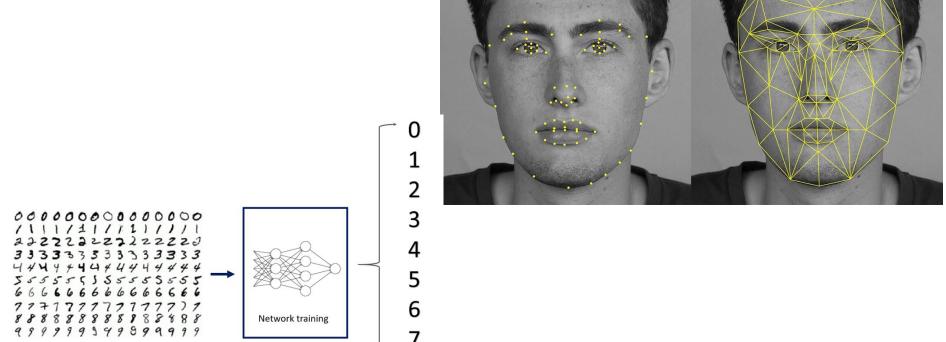




Neural networks

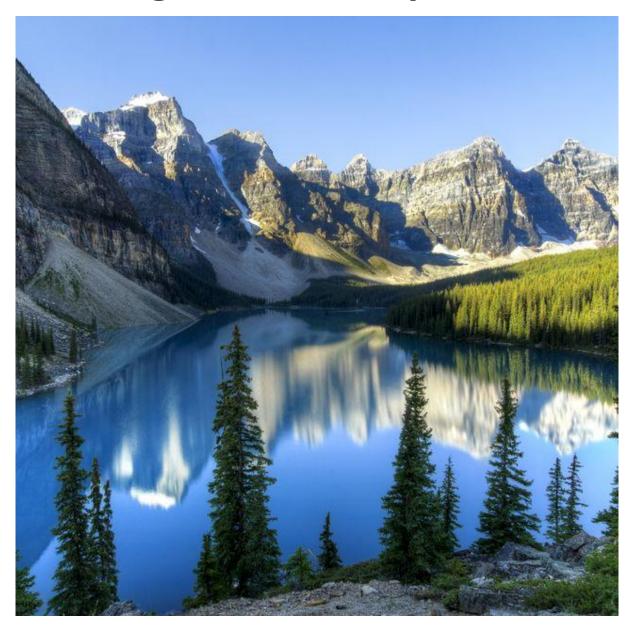
- https://deepdreamgenerator.com/generator
- https://quickdraw.withgoogle.com

Data & Labels

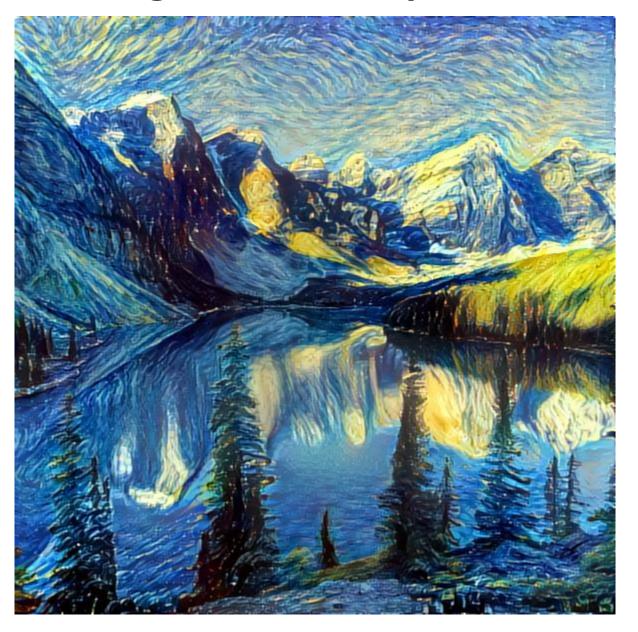


8

Dream generator- style transfer



Dream generator- style transfer



And some more AI stuff

- Deep fake
 - https://www.youtube.com/watch?v=cQ54GDm1eL0
 - https://www.youtube.com/watch?v=-QvIX3cY4lc
- Nvidia GauGAN
 - https://www.youtube.com/watch?v=p5U4NgVGAwg
 - http://nvidia-research-mingyuliu.com/gaugan

contents

- Course details
- What is computer vision (CV)?
- Course outline
- Intro to Python