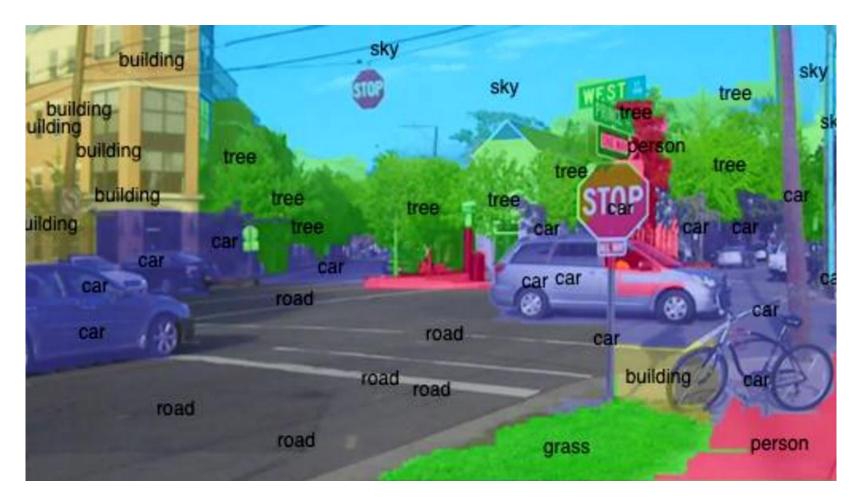
Intro to Computer Vision



Yoni Chechik

www.AlisMath.com

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- Course details
- What is computer vision (CV)?
- Course outline
- Intro to Python

References

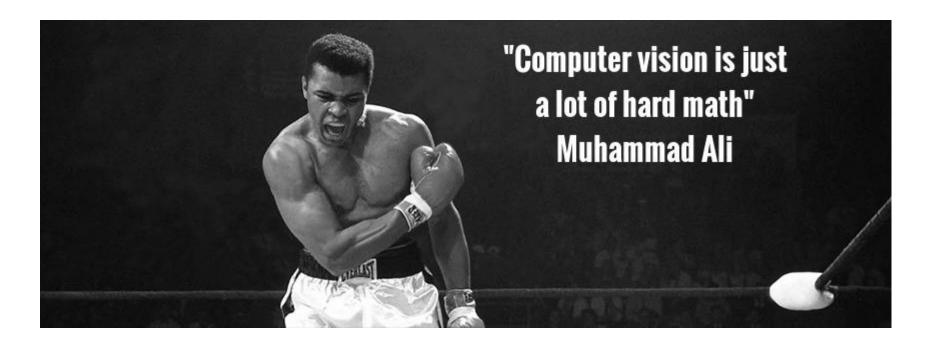
Lectures Based on the book: Computer Vision:
 Algorithms and Applications, 2010, Richard Szeliski (http://szeliski.org/Book/)

Course objectives

- The student will know and understand key algorithms in computer vision.
- The student will be familiar with the algorithmic R&D process, with an emphasis on understanding the advantages and disadvantages of various algorithms and building an algorithmic system that concentrates on computer vision and image processing.
- The student will be able to solve algorithmic problems with computer vision both at theoretical and practical level (in Python using NumPy, Matplotlib, OpenCV & TensorFlow packages).

Prerequisites

- No prior knowledge in signal/image processing is assumed.
- Heavy use in algebra and calculus- mathematical maturity is assumed.

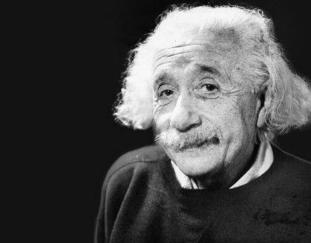


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Don't believe
everything you read
on the internet just
because there's a
picture with a quote
next to it.

ALBERT EINSTEIN

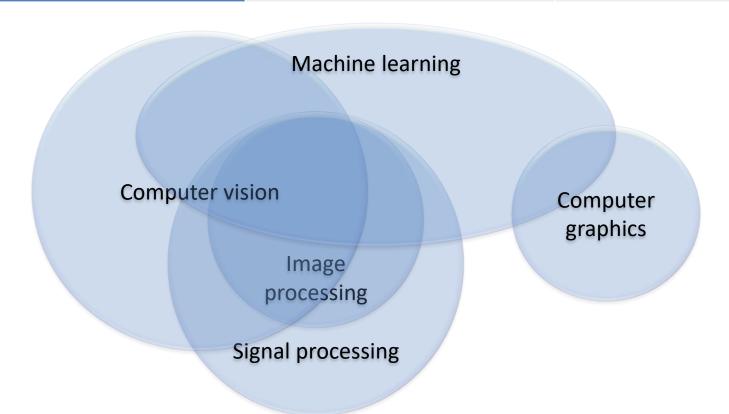


What is CV?

- Computer vision is an interdisciplinary scientific field that deals with how computers can be made to gain high-level understanding from digital images or videos. [Wikipedia]
- Image processing is an umbrella term for many functions that analyze images or convert one representation of an image into another.

What is CV?

Output	Data	Image
Input		
Data	Signal processing	Computer graphics
Image	Computer vision	Image processing



Why CV?

Top Public Company Acquirors



Embedded Vision/Computer Vision M&A Company & Moodstocks Alphabet DNNresearch Undecidable! October - 2012 March - 2013 July - 2016 October - 2016 \$45.0M NA NA NA PrimeSense **EMOTIENT** REALFACE November - 2013 January - 2016 February - 2017 January - 2016 \$360.0M NA NA NA Chiaro Assist Ware *Ao ense* COGNEX **Technologies** November - 2016 May - 2005 July - 2008 August-2016 \$115.0M \$3.0M \$2.4M \$4.7M **a**works Movidius 34 MOBILEYE April - 2012 May - 2016 September - 2016 September - 2017 \$31.0M NA \$392.1M \$15,300.0M



EUVISION

September - 2014

NA

SCYFER

August - 2017

NA

kooaba

January - 2014

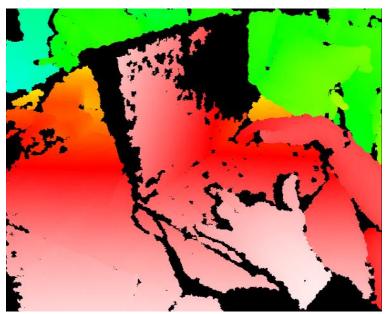
NA

PrimeSense == Kinect

- Kinect for Xbox 360: 3D scanner system using Light
 Coding approach for 3D reconstruction.
- KinectFusion [Newcombe et al., 2011] : https://www.youtube.com/watch?v=KOUSSIKUJ-A







Why CV?

Top Public Company Acquirors



Company

Embedded Vision/Computer Vision M&A

Alphabet





March - 2013

NA





July – 2016







\$45.0M





NA



November – 2013 \$360.0M



January – 2016 NA

AQ ense







ision Sensors
May – 2005
\$115.0M



July – 2008 August – 2016 \$3.0M \$2.4M



November – 2016 \$4.7M





April – 2012 \$31.0M



May – 2016 NA



September – 2016 \$392.1M



September – 2017 \$15,300.0M





January – 2014 NA



September – 2014 NA



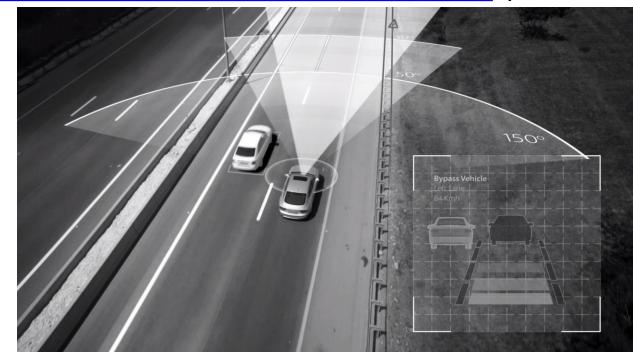
August – 2017 NA

Mobileye

- Mobileye is an Israeli subsidiary of Intel corporation that develops vision-based advanced driver-assistance systems (ADAS) providing warnings for collision prevention and mitigation. [Wikipedia]
- https://www.youtube.com/watch?v=JDUb6CurYJM

https://www.youtube.com/watch?v=fKXztwtXaGo (Tesla-

cooler!)



Why CV?

StartupHub.ai

ISRAEL'S COMPUTER VISION STARTUPS

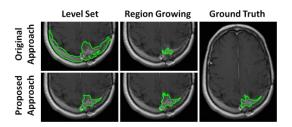


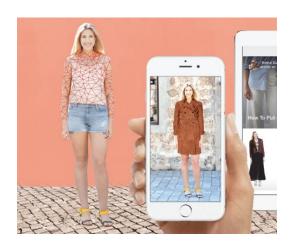
© DANIEL SINGER 2019

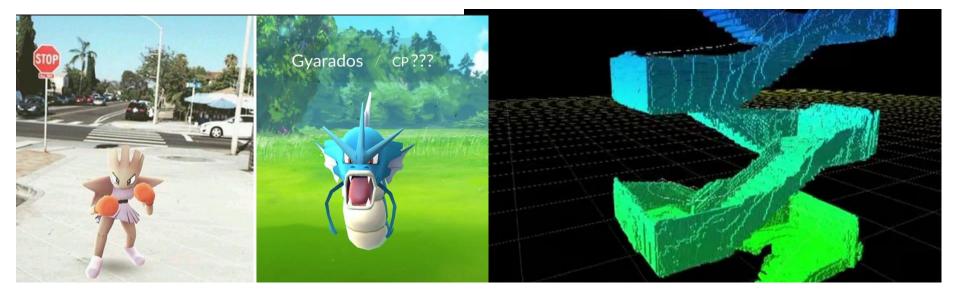
More CV related topics

- Virtual/augmented reality
- navigation
- Gaming
- medicine
- And much more...

Segmentation Results







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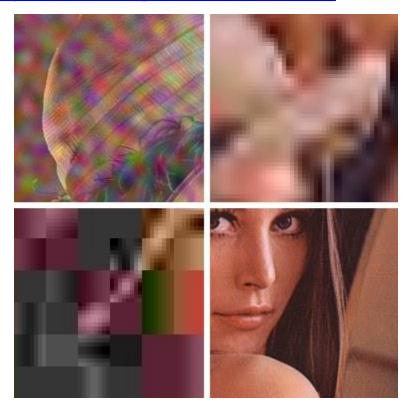
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Course outline

#	subject
1	Introduction to CV + Python: NumPy, Matplotlib, OpenCV
2	Image processing recap: convolutions, LPF, HPF, morphology, connected components, gamma correction, decimation, interpolation.
3	Edge detection: gradient (roberts, prewitt, sobel), Laplacian, DoG (derivative of Gaussian), canny edge detector.
4	Curve fitting: least squares, total least squares, RANSAC, Hough transform.
5	Image formation: BRDF, pinhole camera, digital camera
6	Geometric transformation: 2d->2d, 3d->3d, 3d->2d (perspective and homographic projection)
7	Camera calibration: extrinsic, intrinsic, radial distortion.
8	Stereo vision: dual camera rectification, triangulation.
9	Features: feature detection, feature description, matching, SIFT, panoramas.
10	Stereo: SfM, Epipolar geometry, rectification, triangulation, matching.
11	Neural networks 1: intro, perceptron, dense layers, MNIST.
12	Neural Networks 2: CNN, back-propagation, tensorflow.

Image processing

 Read more about Lenna – the standard test image: https://en.wikipedia.org/wiki/Lenna

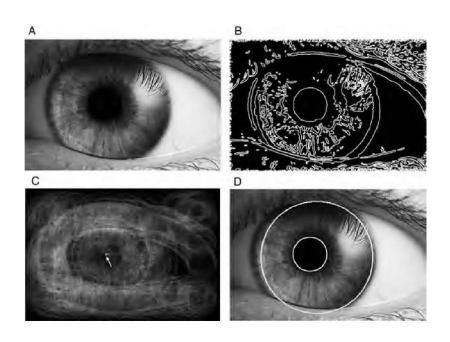


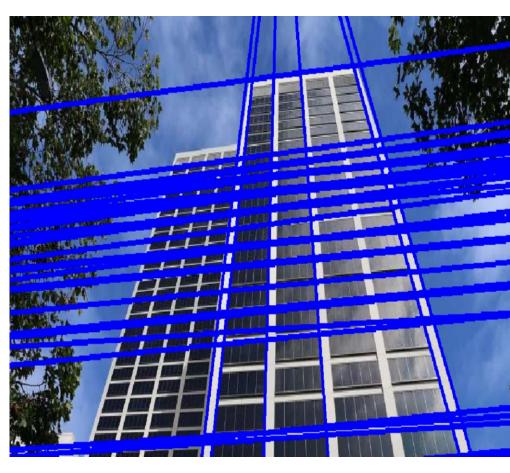
Edge Detection

- https://www.youtube.com/watch?v=hQ-bpfdWQh8
- https://pinetools.com/image-edge-detection



Curve fitting & Hough transform

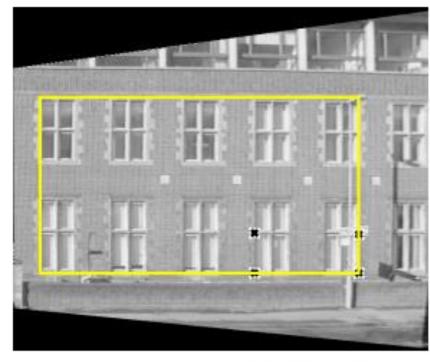




Digital cameras

- Image formation: https://www.youtube.com/watch?v=dY0K65eXhkA
 - 2D & 3D transformation.





from Hartley & Zisserman

Image calibration

• Fisheye correction from go-pro for example



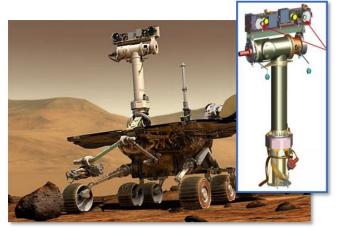
Stereo & 3d cameras

https://www.youtube.com/watch?v=PySBQ8Q_R8k

















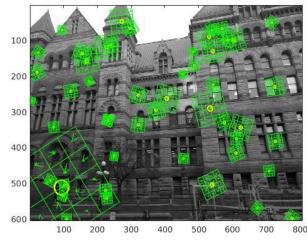




(a)

Features

- Extract interesting points from image for later recognition, stitching, learning and more.
- http://www.in2white.com/

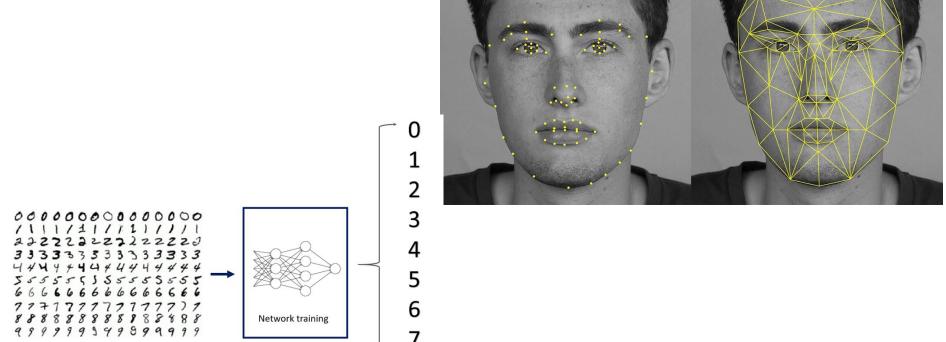




Neural networks

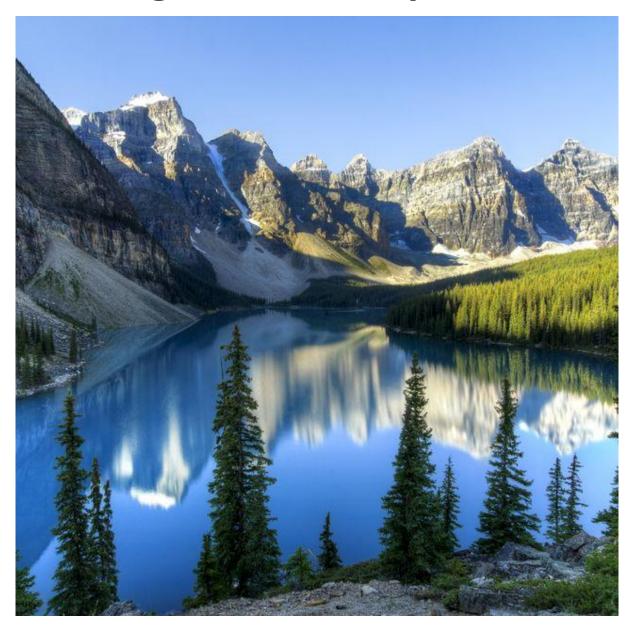
- https://deepdreamgenerator.com/generator
- https://quickdraw.withgoogle.com

Data & Labels

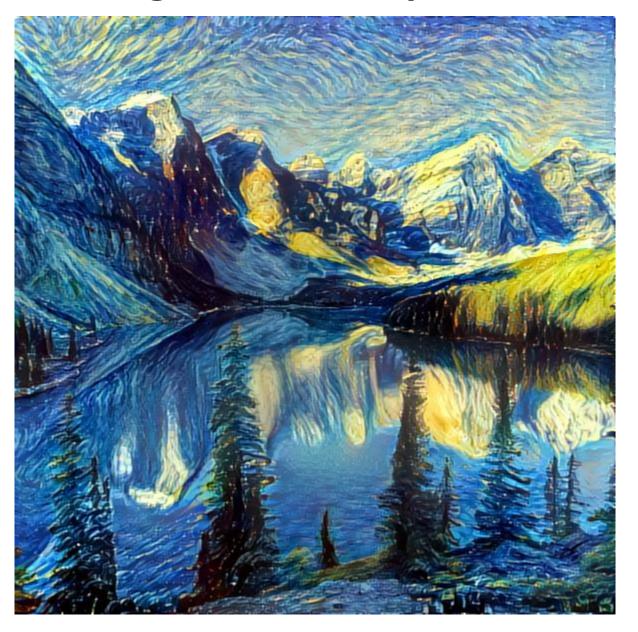


8

Dream generator- style transfer



Dream generator- style transfer



And some more AI stuff

- Deep fake
 - https://www.youtube.com/watch?v=cQ54GDm1eL0
 - https://www.youtube.com/watch?v=-QvIX3cY4lc
- Nvidia GauGAN
 - https://www.youtube.com/watch?v=p5U4NgVGAwg
 - http://nvidia-research-mingyuliu.com/gaugan

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