Krigeage avec R

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Résumé

Techniques pour interpoler les valeurs d'une variable continue.

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	Pour	r cartographier facilement une variable continue, 4 méthodes sont dispo
nił		dans les packages akima, spatial, gstat et automap.
		méthodes plus élaborées ne sont pas traitées ici :
		estimation d'un modèle de prédiction de la valeur à partir de variable
		eplicatives (krigeage ordinaire ou krigeage universel). Voir l'aide de l
		nction gstat pour leur utilisation.
		estimation bayesienne de ces modèles ou le co-krigeage (estimation d
		usieurs variables non indépendantes). Les packages $RGeostats$ 1 ou INL
		permettent une modélisation complexe, mais au prix d'un effort bie
	S11	mérieur

¹ http://rgeostats.free.fr/ 2 http://www.r-inla.org/spde-book

1 Interpolation et cartographie locales

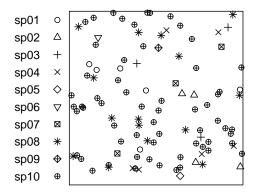
1.1 Création des données

Les données représentent le niveau de la biodiversité locale au voisinages des arbres d'une forêt. La diversité est calculée avec le package SpatDiv disponible sur GitHub, à installer. Le package nécessite une compilation, donc les Rtools sont nécessaires sous Windows.

```
# Package sur GitHub
devtools::install_github("EricMarcon/SpatDiv")
```

Création d'une communauté de 100 individus de 10 espèces dans une placettes carrée de 1x1.

spCommunity <- rSpCommunity(n = 1, size = 100, S = 10)



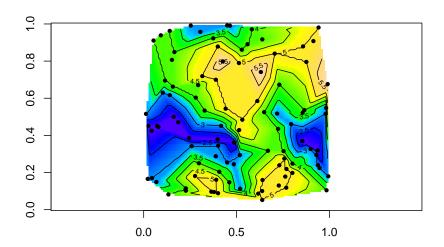
Calcul de la SAC (courbe d'accumulation des espèces) en fonction du nombre de voisins. La valeur obtenue est le nombre d'espèces différentes parmi les 10 plus proches voisins de chaque arbre.

1.2 Cartographie

1.2.1 akima

La méthode d'Akima est une interpolation entre les valeurs des points, faite dans chaque triangle constitué par les triplets de points les plus proches. La valeur des points est conservée. L'interpolation se limite au polygone convexe contenant les points.

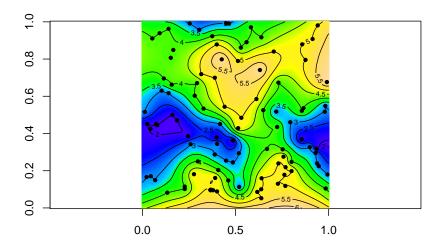
```
library("akima")
Interpole <- with(divAccum, interp(x = SpCommunity$x,
    y = SpCommunity$y, z = Neighborhoods["0", "10",
    ], xo = seq(from = 0, to = 1, by = 0.01), yo = seq(from = 0, to = 1, by = 0.01)))
image(Interpole, col = topo.colors(128, alpha = 1),
    asp = 1)
contour(Interpole, add = TRUE)
with(divAccum, points(x = SpCommunity$x, y = SpCommunity$y,
    pch = 20))</pre>
```



1.2.2 spatial

La librairie *spatial* permet krieger, mais renvoie des erreurs si la méthode de calcul de la covariance n'est pas exponentielle. L'ordre du polynome du modèle et la distance de dépendance doivent être choisis explicitement.

```
Krieg <- prmat(Carte, xl = 0, xu = 1, yl = 0, yu = 1,
    n = 128)
image(Krieg, col = topo.colors(128, alpha = 1), asp = 1)
contour(Krieg, add = TRUE)
with(divAccum, points(x = SpCommunity$x, y = SpCommunity$y,
    pch = 20))</pre>
```



1.2.3 gstat

La librairie gstat étend les possibilités de kriegeage en permettant de spécifier un modèle de tendance pour la variable cartographiée (inutile ici, on utilise formula=Richness~1). Le variogramme doit être calculé et un modèle ajusté (dans l'exemple, un modèle gaussien et non exponentiel).

```
library("sp")

# Création d'un SpatialPointsDataFrame avec les

# données

sdfCommunity <- with(divAccum, SpatialPointsDataFrame(coords = data.frame(x = SpCommunity$x, y = SpCommunity$y), data = data.frame(Richness = Neighborhoods["0", "10", ])))

library("gstat")

# Variogramme empirique

vgmEmpirique <- gstat::variogram(Richness ~ 1, data = sdfCommunity)

# Ajustement d'un modèle gaussien

vgmX <- fit.variogram(vgmEmpirique, vgm("Gau"))

# Objet geostat qui décrit toutes les

# caractéristiques de la modélisation. La formule

# donne le modèle de tendance

geoX <- gstat(formula = Richness ~ 1, locations = sdfCommunity,

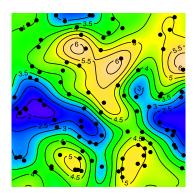
model = vgmX)

# Préparation d'une grille de 128 points de côté

xy <- expand.grid((0:128)/128)
```

```
names(xy) <- c("x", "y")
gridded(xy) <- ~x + y
# Calcul de la valeur de Richness sur les points de
# la grille (kriegeage)
geoXprd <- predict(geoX, newdata = xy)</pre>
```

[using ordinary kriging]



1.2.4 automap

La librairie automap s'appuie sur gstat mais automatise toutes les étapes de sélection du modèle de covariance (celui qui s'ajuste le mieux aux données est choisi). Le modèle sélectionné est affiché dans le variogramme. La grille précédente peut être utilisée, mais une grille calculée à partir de la fenêtre de l'objet ppp (librairie spatstat) est plutôt utilisée ici.

```
library("spatstat")

# Préparation d'une grille de 128 points de côté

xy <- gridcentres(spCommunity, 128, 128)

# Filtrage des noeuds de la grille à l'intérieur de

# la fenêtre (inutile ici)

ok <- inside.owin(xy$x, xy$y, spCommunity)

# Formatage de la grille

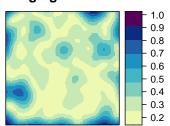
Grille <- SpatialPoints(cbind(xy$x[ok], xy$y[ok]))
```

[using ordinary kriging]

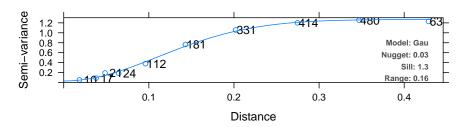
```
# Résultat du krigeage
plot(AutoKrige)
```

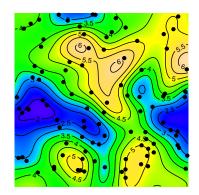
Kriging prediction 6 -5 -4 -3 -2

Kriging standard error



Experimental variogram and fitted variogram model





2 Utilisation de fonds de carte

L'objectif est ici d'interpoler une variable continue du même type sur les centroïdes de polygones d'une carte vectorielle (un shapefile) plutôt que sur une grille.

2.1 Obtention des cartes

Le package *raster* permet de télécharger des fonds de carte administratifs, des modèles numériques de terrain, des cartes de climat : voir l'aide de la fonction getData.

```
## Warning in showSRID(uprojargs, format = "PROJ",
## multiline = "NO", prefer_proj = prefer_proj):
## Discarded datum Reseau_Geodesique_Francais_1993 in
## CRS definition
```

plot(France)

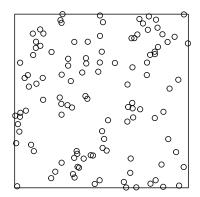


2.2 Fabrication des données

Les données sont 100 points placés aléatoirement dans un rectangle contenant la France. Leur marque est une valeur numérique continue, augmentant linéairement de l'ouest vers l'est et avec la distance à la latitude moyenne, et contenant un bruit gaussien.

```
library("spatstat")
# Tirage d'un processus de Poisson, 1000 points
# attendus, dans une fenêtre de 1x1
plot(X <- rpoispp(100))
```

X <- rpoispp(100)



```
# Valeur de la marque

X$marks <- X$x + 3 * abs(X$y - 0.5) + rnorm(X$n, sd = 0.1)

# Calage sur Lambert 93 (pas très propre, la

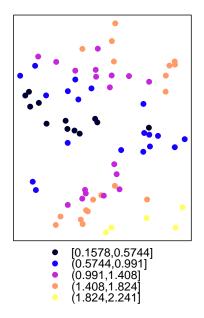
# fenêtre n'est pas modifiée...)

X$x <- 8e+05 * X$x + 3e+05

X$y <- 9e+05 * X$y + 6200000
```

2.3 Interpolation

Les valeurs de x, y et z doivent être intégrées dans un objet Spatial.



L'interpolation est faite avec gstat.

```
library("gstat")
# Variogramme empirique
vgmEmpirique <- variogram(m ~ 1, data = SpatialX)
# Ajustement d'un modèle gaussien
vgmX <- fit.variogram(vgmEmpirique, vgm("Gau"))</pre>
# Objet geostat qui décrit toutes les
# caractéristiques de la modélisation
geoX <- gstat(formula = m ~ 1, locations = SpatialX,</pre>
   model = vgmX)
# Calcul de la valeur de m sur les centroides des
# polygones
geoXprd <- predict(geoX, newdata = France)</pre>
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## Warning in proj4string(newdata): CRS object has
## comment, which is lost in output
## Warning in showSRID(uprojargs, format = "PROJ",
## multiline = "NO", prefer_proj = prefer_proj):
## Discarded datum Unknown based on GRS80 ellipsoid
## in CRS definition
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## Warning in proj4string(obj): CRS object has
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# Carte finale
spplot(geoXprd, "var1.pred")
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- ## Warning in SpatialPointsDataFrame(spp, data.frame(Lines.NR = L3, Lines.ID = L2, : If the
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