TECHNICAL SPECIFICATION



Model Number: HTE029A1

Description: Screen Size: 2.9"

Color: Black and White

Display Resolution: 296*128



Version	Content	Date	Producer
1.0	New release	2015/01/10	
2.0	Modify Reference Circuit	2017/03/02	
3.0	Updating	2017/06/22	
3.1	Modify Reference Circuit	2017/08/04	
3.2	Modify Mechanical Drawing	2017/08/11	

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1 General Description

GDE029A1 is an Active Matrix Electrophoretic Display(AMEPD), with interface and a reference system design. The 2.9" active area contains 128×296 pixels, and has 1 -bit B/W full display capabilities. An integrated circuit contains gate buffer, source buffer, interface, timing control logic, oscillator, DC-DC. SRAM. LUT, VCOM, and border are supplied with each panel.

2 Features

- 128×296 pixels display
- White reflectance above 35%
- Contrast ratio 10:1
- Ultra wide viewing angle
- Ultra low power consumption
- Pure reflective mode
- Bi-stable display
- Commercial temperature range
- Landscape, portrait modes
- Hard-coat antiglare display surface
- Ultra Low current deep sleep mode
- On chip display RAM
- Waveform stored in On-chip OTP
- Serial peripheral interface available
- On-chip oscillator
- On-chip booster and regulator control for generating VCOM, Gate and Source driving voltage
- I2C signal master interface to read external temperature sensor

3 Application

Electronic Shelf Label System

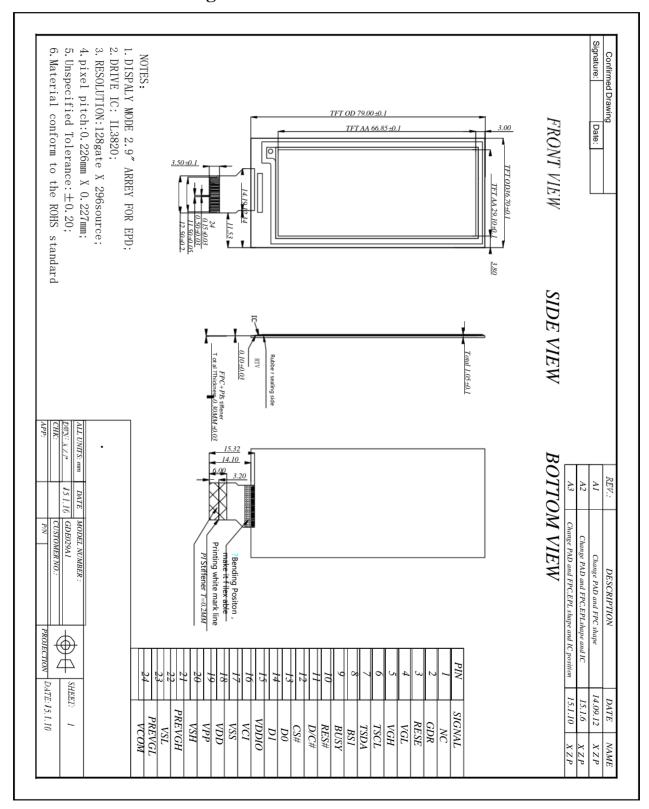
4 Mechanical Specifications

Parameter	Specifications	Unit	Remark
Screen Size	2.9	Inch	
Display Resolution	128(H)×296(V)	Pixel	dpi:112
Active Area	29.1×66.85	mm	
Pixel Pitch	0.226×0.227	mm	
Pixel Configuration	Rectangle		
Outline Dimension	36.7(H)×79.0 (V) ×1.05(D)	mm	
Weight	6.5 ± 0.2	g	

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5 Mechanical Drawing of EPD module



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6 Input/Output Terminals

6.1 Pin out List

Pin #	Single	Description	Remark
1	NC	No connection and do not connect with other NC pins	Keep Open
2	GDR	N-Channel MOSFET Gate Drive Control	
3	RESE	Current Sense Input for the Control Loop	
4	VGL	Negative Gate driving voltage	
5	VGH	Positive Gate driving voltage	
6	TSCL	I2C Interface to digital temperature sensor Clock pin	
7	TSDA	I2C Interface to digital temperature sensor Date pin	
8	BS1	Bus selection pin	Note 6-5
9	BUSY	Busy state output pin	Note 6-4
10	RES#	Reset	Note 6-3
11	D/C #	Data /Command control pin	Note 6-2
12	CS#	Chip Select input pin	Note 6-1
13	D0	serial clock pin (SPI)	
14	D1	serial data pin (SPI)	
15	VDDIO	Power for interface logic pins	
16	VCI	Power Supply pin for the chip	
17	VSS	Ground	
18	VDD	Core logic power pin	
19	VPP	Power Supply for OTP Programming	
20	VSH	Positive Source driving voltage	
21	PREVGH	Power Supply pin for VGH and VSH	
22	VSL	Negative Source driving voltage	
23	PREVGL	Power Supply pin for VCOM, VGL and VSL	
24	VCOM	VCOM driving voltage	

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Note 6-1: This pin (CS#) is the chip select input connecting to the MCU. The chip is enabled for MCU communication:only when CS# is pulled LOW.

Note 6-2: This pin (D/C#) is Data/Command control pin connecting to the MCU. When the pin is pulled HIGH, the data will be interpreted as data. When the pin is pulled LOW, the data will be interpreted as command.

Note 6-3: This pin (RES#) is reset signal input.
The Reset is active low.

Note 6-4: This pin (BUSY) is Busy state output pin. When Busy is high the operation of chip should not be interrupted and any commands should not be issued to the module. The driver IC will put Busy pin high when the driver IC is working such as:

- Outputting display waveform; or
- Communicating with digital temperature sensor

Note 6-5: This pin (BS1) is for 3-line SPI or 4-line SPI selection. When it is "Low", 4-line SPI is selected. When it is "High", 3-line SPI (9 bits SPI) is selected. Please refer to below Table.

Table: Bus interface selection

BS1	MPU Interface
L	4-lines serial peripheral interface (SPI)
Н	3-lines serial peripheral interface (SPI) - 9 bits SPI

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6.2 MCU Interface

6.2.1 MCU Serial Peripheral Interface (4-wire SPI)

The 4-wire SPI consists of SCLK (serial clock), SDIN (serial data), D/C# and CS#. D0 acts as SCLK and D1 acts as SDIN.

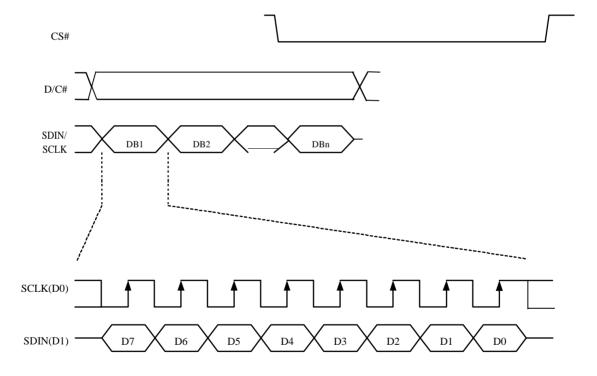
Table -1: Control pins of 4-wire Serial Peripheral interface

Function	CS# pin	D/C# pin	SCLK pin		
Write command	L	L	1		
Write data	L	Н	↑		

Note: ↑ stands for rising edge of signal

SDIN is shifted into an 8-bit shift register in the order of D7, D6, ... D0. The data byte in the shift register is written to the Graphic Display Data RAM (RAM) or command register in the same clock. Under serial mode, only write operations are allowed.

Figure 6-1: Write procedure in 4-wire Serial Peripheral Interface mode



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6.2.2 MCU Serial Peripheral Interface (3-wire SPI)

The 3-wire serial interface consists of SCLK (serial clock), SDIN (serial data) and CS#. In SPI mode, D0 acts as SCLK and D1 acts as SDIN. The operation is similar to 4-wire serial interface while D/C# pin is not used. There are altogether 9-bits will be shifted into the shift register in sequence: D/C# bit, D7 to D0 bit. The D/C# bit (first bit of the sequential data) will determine the following data byte in the shift register is written to the Display Data RAM (D/C# bit = 1) or the command register (D/C# bit = 0). Under serial mode, only write operations are allowed.

Table -2: Control pins of 3-wire Serial Peripheral interface

Function	CS# pin	D/C# pin	SCLK pin
Write command	L	Tie LOW	↑
Write data	L	Tie LOW	1

Note: ↑ stands for rising edge of signal

Figure 6-1: Write procedure in 3-wire Serial Peripheral Interface mode

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6.3 External Temperature Sensor operation

There are two ways to let the module get the ambient temperature,

- 1) use the external temperature sensor interface, The module provides two I/O lines [TSDA and TSCL] for connecting digital temperature sensor for temperature reading sensing. TSDA will be treated as SDA line and TSCL will be treated as SCL line. They are required connecting with the external pull-up resistors when they are used to connect to the temperature sensor, then the module will check the temperature automatically.
- 2) use any kinds of external temperature sensor to get the temperature value then converted to hex format, then use the spi interface send command 0x1A and the temperature value into the module. The temperature value how to converted to hex as the follow:
- 1. When the Temperature value MSByte bit D11 = 0, the temperature is positive and value (DegC) = + (Temperature value)/16
- 2. When the Temperature value MSByte bit D11 = 1, the temperature is negative and value (DegC) = \sim (2's complement of Temperature value)/16

12-bit binary	Hexadecimal	Decimal	Value
(2's complement)	Value	Value	[DegC]
0111 1111 0000	7F0	2032	127
0111 1110 1110	7EE	2030	126.875
0111 1110 0010	7E2	2018	126.125
0111 1101 0000	7D0	2000	125
0001 1001 0000	190	400	25
0000 0000 0010	002	2	0.125
0000 0000 0000	000	0	0
1111 1111 1110	FFE	-2	-0.125
1110 0111 0000	E70	-400	-25
1100 1001 0010	C92	-878	-54.875
1100 1001 0000	C90	-880	-55

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7 Command Table

Name		Com			ann	<u> </u>							
1	R/W #	D/C#	Hex	D7	D6	D5	D4	D3	D2	D1	D 0	Command	Description
O	0	0	01									Driver Output control	Gate setting
O	0	1		A7			A4						Set $A[8:0] = 0C7h$
O	0	1		0	0	0	0	0	0	0	A8		Set $B[2:0] = 0h$
O	0	1		0	0	0	0	0	B2	B1	B0		
O	0	0	0C	0	0	0	0	1	1	0	0	Booster Soft start	Set A[7:0] = CFh
Set C[7:0] = 8Dh	0	1		1	A ₆	A ₅	A_4		A_2	A_1	A_0		Set B[7:0] = CEh
1	0												Set C[7:0] = 8Dh
Deep Sleep mode	0	1		1							-		
A[0] : Description O Normal Mode [POR]	0	0	10	0								Deep Sleep mode	Deep Sleep mode Control
O Normal Mode [POR] 1 Enter Deep Sleep Mode	0	1		0	0	0	0	0	0	0	A_0		
1 Enter Deep Sleep Mode 0 0 11 0 0 0 1 0 0													
Data Entry mode setting Define data entry sequence A [1:0] = ID[1:0] Address automatic increment / decrement setting of incrementing or decrementing of the address counter can be made independently in each upper and lower bit of the address. O0 -Y decrement, X decrement, 10 -Y increment, X increment, 11 -Y increment, X increment, 11 -Y increment, X increment, 11 -Y increment, X increment [POR] A[2] = AM Set the direction in which the address counter is updated in the X direction. [POR] AM = 0, the address counter is updated in the Y direction. O 0 12 0 0 0 1 0 0 1 0 0 1 0 SWRESET It resets the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this													
A [1:0] = ID[1:0] Address automatic increment / decrement setting The setting of incrementing or decrementing of the address counter can be made independently in each upper and lower bit of the address. 00 —Y decrement, X decrement, 01 —Y decrement, X increment, 10 —Y increment, X increment, 11 —Y increment, X increment [POR] A[2] = AM Set the direction in which the address counter is updated at are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM= 1, the address counter is updated in the Y direction. It resets the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this													I Enter Deep Sleep Mode
Address automatic increment / decrement setting The setting of incrementing or decrementing of the address counter can be made independently in each upper and lower bit of the address. 00 —Y decrement, X decrement, 01 —Y decrement, X increment, 10 —Y increment, X increment, 11 —Y increment, X increment, 12 —Y increment, X increment [POR] A[2] = AM Set the direction in which the address counter is updated at are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM = 1, the address counter is updated in the Y direction. 0 0 12 0 0 0 1 0 0 1 0 SWRESET It resets the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this	0	0	11	0	0	0	1	0	0	0	1	Data Entry mode setting	
decrement setting The setting of incrementing or decrementing of the address counter can be made independently in each upper and lower bit of the address. 00 – Y decrement, X decrement, 01 – Y decrement, X increment, 11 – Y increment, X increment, 11 – Y increment, X increment [POR] A[2] = AM Set the direction in which the address counter is updated at are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM = 1, the address counter is updated in the Y direction. It resets the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this	0	1		0	0	0	0	0	A_2	A_1	A_0		
The setting of incrementing or decrementing of the address counter can be made independently in each upper and lower bit of the address. 00 —Y decrement, X decrement, 01 —Y decrement, X increment, 10 —Y increment, X increment, 11 —Y increment, X increment [POR] A[2] = AM Set the direction in which the address counter is updated automatically after data are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM = 1, the address counter isupdated in the Y direction. The setting of incrementing or decrementing of the address counter, and the properties of the address counter is updated in the X direction. The setting of incrementing or decrementing of the address counter, and the upper and lower bit of the address.													
decrementing of the address counter can be made independently in each upper and lower bit of the address. 00 –Y decrement, X decrement, 01 –Y decrement, X increment, 10 –Y increment, X increment, 11 –Y increment, X increment, 21 –Y increment, X increment [POR] A[2] = AM Set the direction in which the address counter is updated automatically after data are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM = 1, the address counter isupdated in the Y direction. It resets the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this													
can be made independently in each upper and lower bit of the address. 00 -Y decrement, X decrement, 01 -Y decrement, X increment, 110 -Y increment, X increment, 111 -Y increment, X increment [POR] A[2] = AM Set the direction in which the address counter is updated automatically after data are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM= 1, the address counter isupdated in the Y direction. The trest the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this													
00 –Y decrement, X decrement, 01 –Y decrement, X increment, 10 –Y increment, X decrement, 11 –Y increment, X decrement, 11 –Y increment, X increment [POR] A[2] = AM Set the direction in which the address counter is updated automatically after data are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM = 1, the address counter isupdated in the Y direction. Under the property of the propert													
01 -Y decrement, X increment, 10 -Y increment, X decrement, 11 -Y increment, X increment [POR] A[2] = AM Set the direction in which the address counter is updated automatically after data are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM= 1, the address counter isupdated in the Y direction. O 0 12 0 0 0 1 0 0 1 0 SWRESET It resets the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this													upper and lower bit of the address.
01 -Y decrement, X increment, 10 -Y increment, X decrement, 11 -Y increment, X increment [POR] A[2] = AM Set the direction in which the address counter is updated automatically after data are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM= 1, the address counter isupdated in the Y direction. O 0 12 0 0 0 1 0 0 1 0 SWRESET It resets the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this													00 V decrement V decrement
10 – Y increment, X decrement, 11 – Y increment, X increment [POR] A[2] = AM Set the direction in which the address counter is updated automatically after data are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM = 1, the address counter isupdated in the Y direction. The address counter isupdated in the Y direction. Swreset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this													
11 –Y increment, X increment [POR] A[2] = AM Set the direction in which the address counter is updated automatically after data are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM= 1, the address counter isupdated in the Y direction. Description of the image o													
Set the direction in which the address counter is updated automatically after data are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM = 1, the address counter isupdated in the Y direction. It resets the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this													·
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counter is updated automatically after data are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM = 1, the address counter isupdated in the Y direction. Description of the image of the i													
data are written to the RAM. AM= 0, the address counter is updated in the X direction. [POR] AM = 1, the address counter isupdated in the Y direction. Description of the image of the i													
in the X direction. [POR] AM = 1, the address counter isupdated in the Y direction. 0 0 12 0 0 0 1 0 0 1 0 SWRESET It resets the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this													
in the X direction. [POR] AM = 1, the address counter isupdated in the Y direction. 0 0 12 0 0 0 1 0 0 1 0 SWRESET It resets the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this													AM-0 the address counter is undated
AM = 1, the address counter isupdated in the Y direction. O													
in the Y direction. 0 0 12 0 0 0 1 0 0 1 0 SWRESET It resets the commands and parameters to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this													
to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this													
to their S/W Reset default values except R10h-Deep Sleep Mode Note: RAM are unaffected by this	0	0	12	0	0	0	1	0	0	1	Λ	SWRESET	It resets the commands and parameters
except R10h-Deep Sleep Mode Note: RAM are unaffected by this	U	U	14	U			1	U		1		D W KEDE I	
Note: RAM are unaffected by this													
command.													Note: RAM are unaffected by this
													command.

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R/W #	D /C#	Hex	D7	D6	D5	D4	D3	D2	D 1	D 0	Command	Description
0	0	1A	0	0	0	1	1	0	1	0		Write to temperature register.
0	1		A_7	A_6	A_5	A_4	A_3	A_2	A_1	A_0	Control (Write to temperature register)	A[7:0] – MSByte 01111111[POR]
0	1		\mathbf{B}_7	B_6	\mathbf{B}_5	\mathbf{B}_4	0	0	0	0	temperature register)	B[7:0] – LSByte 11110000[POR]
0	0	20	0	0	1	0	0	0	0	0	Master Activation	Activate Display Update Sequence
												The Display Update Sequence Option is located at R22h
												User should not interrupt this operation to avoid corruption of panel images.
0	0	21	0	0	1	0	0	0	0	1	Display Update Control	Option for Display Update
0	1		A_7	0	0	A_4	A_3	A_2	A_1	A_0	1	Bypass Option used for Pattern Display, which is used for display the
												RAM content into the Display
												OLD RAM Bypass option A [7] A[7] = 1: Enable bypass A[7] = 0: Disable bypass [POR] A[4] value will be used as for bypass. A[4] = 0 [POR] A[1:0] Initial Update Option - Source Control
												A[1:0] GSC GSD
												01 [POR] GS0 GS1

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R/W#	D/C#	Hex	D7	D6	D5	D4	D3	D2	D1	D0	Command	Description	
0	0	22	0	0	1	0	0	0	1	0	Display Update	Display Update Sequence Op	
0	1		A ₇	A_6	A_5	A_4	A_3	A_2	A_1	A_0	Control 2	Enable the stage for Master A	Activation
													Paramete (in Hex)
												Enable Clock Signal, Then Enable CP Then Load Temperature value Then Load LUT Then INIITIAL DISPLAY Then PATTERN DISPLAY Then Disable CP Then Disable OSC	FF [POR]
												To Enable Clock Signal (CLKEN=1)	80
												To Enable Clock Signal, then Enable CP (CLKEN=1, CPEN=1)	C0
												To INITIAL DISPLAY + PATTEN DISPLAY	0C
												To INITIAL DISPLAY	08
												To DISPLAY PATTEN	04
												To Disable CP, then Disable Clock Signal (CLKEN=1, CPEN=1)	03
												To Disable Clock Signal (CLKEN=1)	01
												Remark: CLKEN=1: If CLS=VDDIO then Enable If CLS=VSS then Enable Ex Clock CLKEN=0: If CLS=VDDIO then Disable AND INTERNAL CLOCK Signal	ternal e OSC = VSS,
0	0	24	0	0	1	0	0	1	0	0	Write RAM	After this command, data en be written into the RAM unti command is written. Address will advance accordingly.	tries will l another
0	0	2C	0	0	1	0	1	0	1	1	Write VCOM register	Write VCOM register from N	ИCU
0	1		A ₇	A_6	A_5	A_4	A_3	A_2	A_1	A_0	j	interface	

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R/W #	D/C#	Hex	D7	D6	D5	D4	D3	D2	D1	D 0	Command	Description
0	0	32	0	0	1	1	0	0	1	0	Write LUT register	Write LUT register from MCU [240
0	1											bits], (excluding the VSH/VSL and Dummy
0 0	1 1					11	JТ					bit)
							ytes]					
0	1						J 1					
0	1			1	ı	1	1	1	ı	1		
0	0	3A	0	0	1	1	1	0	1	0	Set dummy line period	Set $A[7:0] = 1Bh$
0	1		0	A_6	A_5	A_4	A_3	A_2	A_1	A_0		
0	0	3B	0	0	1	1	1	0	1	1	Set Gate line width	Set B[3:0] = Bh
0	1		0	0	0	0	A_3	A_2	A_1	A_0		
0	0	3C	0	0	1	1	1	1	0	0	Border Waveform	Select border waveform for VBD
0	1		A_7	A_6	A_5	A_4	0	0	A_1	A_0	Control	A [7] Follow Source at Initial Update
												Display A [7]=0: [POR]
												A [7]=1: Follow Source at Initial
												Update Display for VBD, A [6:0]
												setting are being overridden at Initial
												Display STAGE.
												A [6] Select GS Transition/ Fix Level
												for VBD
												A [6]=0: Select GS Transition A[3:0] for VBD
												A [6]=1: Select FIX level Setting
												A[5:4] for VBD [POR]
												A [5:4] Fix Level Setting for VBD
												A[5:4] VBD level
												00 VSS
												01 VSH 10 VSL
												11[POR] HiZ
												A [1:0] GS transition setting for VBD
												(Select waveform like data A[3:2] to data A[1:0])
												A[1:0] GSA GSB
												01 [POR] GS0 GS1

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R/W #	D /C#	Hex	D7	D6	D5	D4	D3	D2	D 1	D 0	Command	Description
0	0	44	0	1	0	0	0	1	0	0	Set RAM X - address	Specify the start/end positions of the
0	1		0	0	0	A_4	A_3	A_2	A_1	A_0	Start / End position	window address in the X direction by
0	1		0	0	0	\mathbf{B}_4	\mathbf{B}_3	\mathbf{B}_2	\mathbf{B}_1	\mathbf{B}_0		an address unit
												A[4:0]: XSA[4:0], XStart, POR = 00h B[4:0]: XEA[4:0], XEnd, POR = 1Dh
0	0	45	0	1	0	0	0	1	0	1	Set Ram Y- address	Specify the start/end positions of the
0	1		A_7	A_6	A_5	A_4	A_3	A_2	A_1	A_0	Start / End position	window address in the Y direction by
0	1		0	0	0	0	0	0	0	A_8		an address unit
0	1		\mathbf{B}_7	\mathbf{B}_6	\mathbf{B}_5	B_4	\mathbf{B}_3	\mathbf{B}_2	\mathbf{B}_1	\mathbf{B}_0		A[8:0]: YSA[8:0], YStart, POR =
0	1		0	0	0	0	0	0	0	\mathbf{B}_8		000h
												B[8:0]: YEA[8:0], YEnd, POR =
												13Fh
0	0	4E	0	1	0	0	1	1	1	0	Set RAM X address	Make initial settings for the RAM X
0	1		0	0	0	A_4	A_3	A_2	A_1	A_0	counter	address in the address counter (AC) A[4:0]: XAD[4:0], POR is 00h
0	0	4F	0	1	0	0	1	1	1	1	Set RAM Y address	Make initial settings for the RAM Y
0	1		A_7	A_6	A_5	A_4	A_3	A_2	A_1	A_0	counter	address in the address counter (AC) A[8:0]: YAD8:0], POR is 000h
0	1		0	0	0	0	0	0	0	A_8		A[8.0]. TAD8.0], FOR IS 00011
0	1	FF	1	1	1	1	1	1	1	1	NOP	This command is an empty command; it does not have any effect on the display module. However it can be used to terminate Frame Memory Write or Read Commands.

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8 Reference Circuit

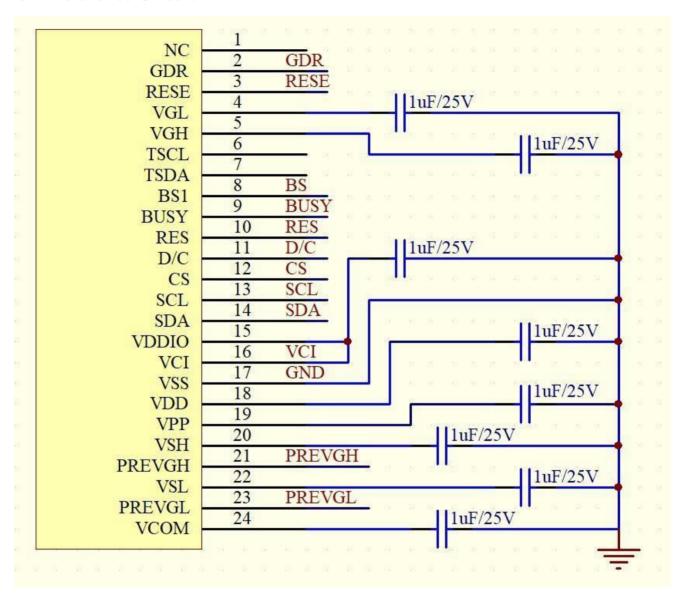


Figure . 8-1

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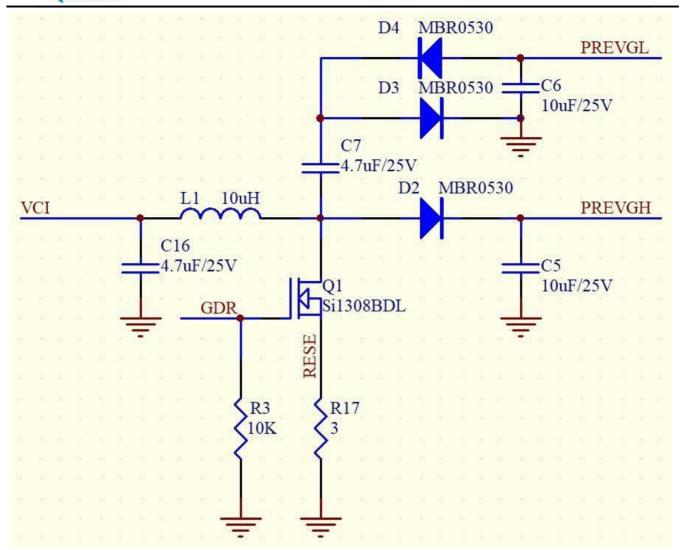


Figure . 8-2

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9 MAXIMUM RATINGS

Table 9-1: Maximum Ratings

Symbol	Parameter	Rating	Unit
V_{CI}	Logic supply voltage	-0.5 to +4.0	V
T_{OPR}	Operation temperature range	0~50	$\mathcal C$
T_{STG}	Storage temperature range	-25~60	$\mathcal C$

10 DC CHARACTERISTICS

The following specifications apply for: VSS=0V, VCI=3.3V, TOPR=25°C.

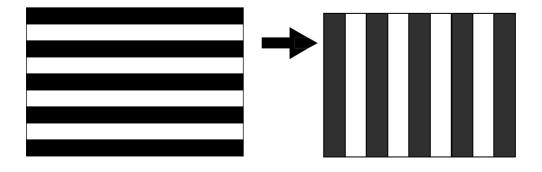
Table 10-1: DC Characteristics

Table 10-1. De characteristics									
Symbol	Parameter	Test Condition	Applicable pin	Min.	Тур.	Max.	Unit		
VCI	VCI operation voltage	-	VCI	2.4	3.3	3.7	V		
VIH	High level input voltage	-	D1 (SDIN), D0 (SCLK),	0.8VDDIO	-	-	V		
VIL	Low level input voltage	-	CS#, D/C#, RES#, BS1,	-	-	0.2VDDI	V		
						O			
VOH	High level output voltage	IOH = -100uA	BUSY, TSDA, TSCL	0.9VDDIO	-	-	V		
VOL	Low level output voltage	IOL = 100uA		-	-	0.1VDDI	V		
						O			
Iupdate	Module operating current	-	-	-	6.5	-	mA		
Isleep	Deep sleep mode	VCI=3.3V	-	-	0.6	1	uA		

- The Typical power consumption is measured using associated $25\,^{\circ}\text{C}\ }$ waveform with following pattern transition: from horizontal scan pattern to vertical scan pattern. (Note 10-1)
- The listed electrical/optical characteristics are only guaranteed under the controller & waveform provided by Qiyun Display.
- Vcom value will be OTP before in factory or present on the label sticker.

Note 10-1

The Typical power consumption



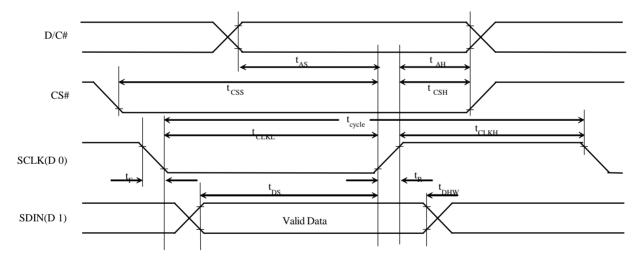
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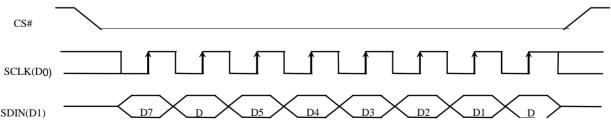


11 Serial Peripheral Interface Timing

The following specifications apply for: VSS=0V, VCI=2.4V to 3.7V, T_{OPR}=25°C

Symbol	Parameter	Min	Тур	Max	Unit
t _{cycle}	Clock Cycle Time	250	-	-	ns
t_{AS}	Address Setup Time	150	-	-	ns
t_{AH}	Address Hold Time	150	-	-	ns
t _{CSS}	Chip Select Setup Time	120	-	-	ns
t_{CSH}	Chip Select Hold Time	60	-	-	ns
$t_{ m DSW}$	Write Data Setup Time	50	-	-	ns
$t_{ m DHW}$	Write Data Hold Time	15	-	-	ns
t_{CLKL}	Clock Low Time	100	-	-	ns
t_{CLKH}	Clock High Time	100	-	-	ns
t_R	Rise Time [20% ~ 80%]	-	-	15	ns
$t_{\rm F}$	Fall Time [20% ~ 80%]	-	-	15	ns





12 Power Consumption

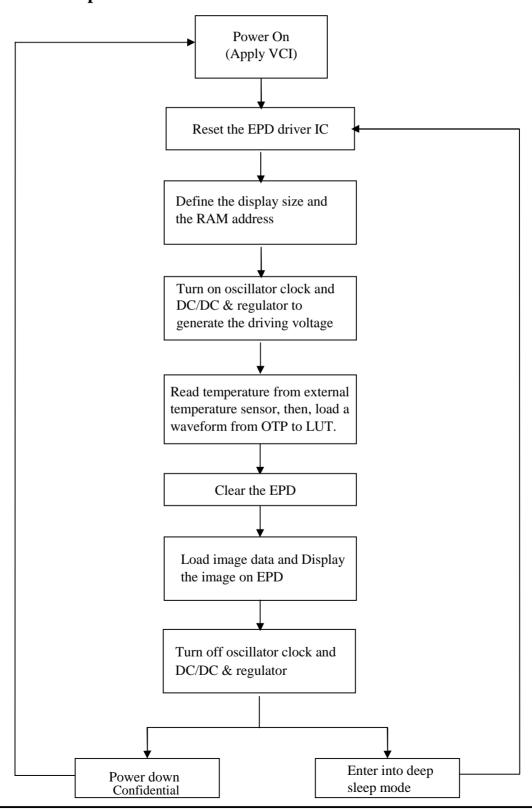
Parameter	Symbol	Conditions	TYP	Max	Unit	Remark
Panel power consumption during update	-	25℃	13	-	mAs	-
Deep sleep mode	-	25℃	0.6	-	uA	-

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13 Typical Operating Sequence

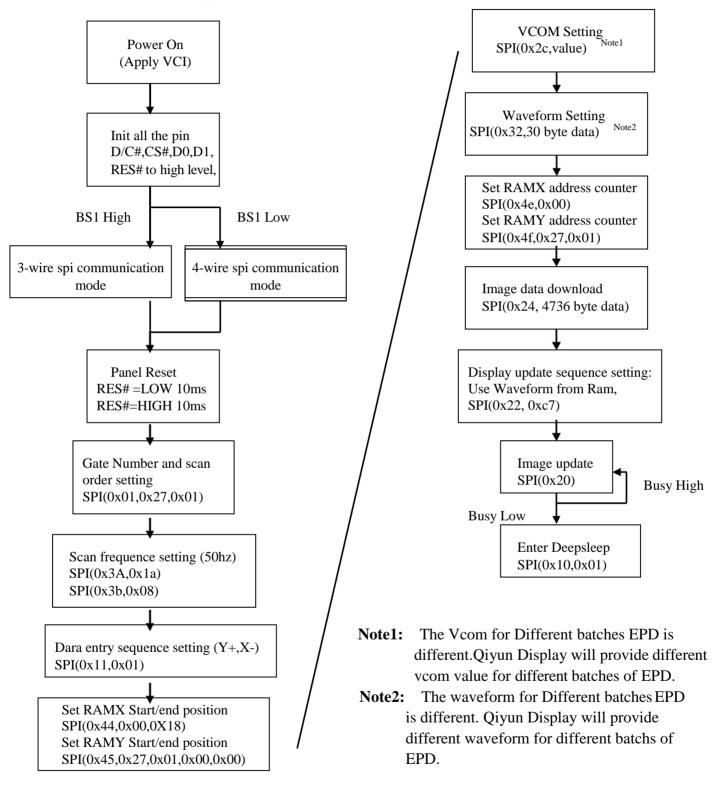
13.1 Normal Operation Flow



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13.2 Reference Program Code



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14 Optical characteristics

14.1 Specifications

Measurements are made with that the illumination is under an angle of 45 degrees, the detection is perpendicular unless otherwise specified.

T=25°C

SYMBOL	PARAMETER	CONDITIO NS	MIN	ТҮРЕ	MAX	UNIT	Note
R	Reflectance	White	30	35	-	%	Note 14-1
Gn	2Grey Level	-	-	$DS+(WS-DS)\times n(m-1)$	ı	L*	-
CR	Contrast Ratio	indoor	-	10	-	-	-
Panel's life	-	0°C∼50°C		5years or 1000000 times	-	-	Note 14-2

WS: White state, DS: Dark state

m: 2

Note 14-1: Luminance meter: Eye - One Pro Spectrophotometer

Note 14-2: We guarantee display quality from $10^{\circ}\text{C} \sim 30^{\circ}\text{C}$ generally, If operation ambient temperature from $0^{\circ}\text{C} \sim$

 50°C , will add external temperature sensor.

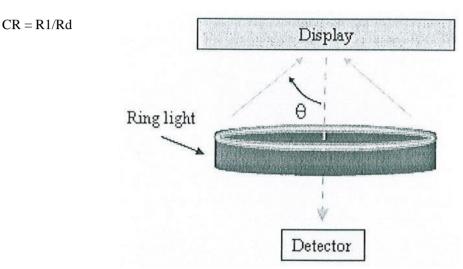
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14.2 Definition of contrast ratio

The contrast ratio (CR) is the ratio between the reflectance in a full white area (R1) and the reflectance in a dark area (Rd)():

R1: white reflectance Rd: dark reflectance

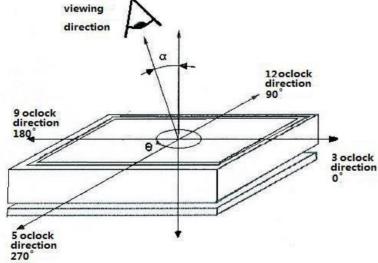


14.3 Reflection Ratio

The reflection ratio is expressed as:

R = Reflectance Factor white board x (L center / L white board)

L center is the luminance measured at center in a white area (R=G=B=1). L white board is the luminance of a standard white board. Both are measured with equivalent illumination source. The viewing angle shall be no more than 2 degrees.



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15 HANDLING, SAFETY AND ENVIROMENTAL REQUIREMENTS

WARNING

The display glass may break when it is dropped or bumped on a hard surface. Handle with care. Should the display break, do not touch the electrophoretic material. In case of contact with electrophoretic material, wash with water and soap.

CAUTION

The display module should not be exposed to harmful gases, such as acid and alkali gases, which corrode electronic components.

Disassembling the display module can cause permanent damage and invalidate the warranty agreements.

IPA solvent can only be applied on active area and the back of a glass. For the rest part, it is not allowed.

Observe general precautions that are common to handling delicate electronic components. The glass can break and front surfaces can easily be damaged. Moreover the display is sensitive to static electricity and other rough environmental conditions.

Mounting Precautions

- (1) It's recommended that you consider the mounting structure so that uneven force (ex. Twisted stress) is not applied to the module.
- (2) It's recommended that you attach a transparent protective plate to the surface in order to protect the EPD. Transparent protective plate should have sufficient strength in order to resist external force.
- (3) You should adopt radiation structure to satisfy the temperature specification.
- (4) Acetic acid type and chlorine type materials for the cover case are not desirable because the former generates corrosive gas of attacking the PS at high temperature and the latter causes circuit break by electro-chemical reaction.
- (5) Do not touch, push or rub the exposed PS with glass, tweezers or anything harder than HB pencil lead. And please do not rub with dust clothes with chemical treatment. Do not touch the surface of PS for bare hand or greasy cloth. (Some cosmetics deteriorate the PS)
- (6) When the surface becomes dusty, please wipe gently with absorbent cotton or other soft materials like chamois soaks with petroleum benzene. Normal-hexane is recommended for cleaning the adhesives used to attach the PS. Do not use acetone, toluene and alcohol because they cause chemical damage to the PS.
- (7) Wipe off saliva or water drops as soon as possible. Their long time contact with PS causes deformations and color fading.

Product specification The data sheet contains final product specifications.

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Limiting values

Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those given in the Characteristics sections of the specification is not implied.

Exposure to limiting values for extended periods may affect device reliability.

Application information

Where application information is given, it is advisory and dose not form part of the specification.

Product Environmental certification

ROHS

REMARK

All The specifications listed in this document are guaranteed for module only. Post-assembled operation or component(s) may impact module performance or cause unexpected effect or damage and therefore listed specifications is not warranted after any Post-assembled operation.

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16. Reliability test

10.	Kenabinty test	<u> </u>		
	TEST	CONDITION	METHOD	REMARK
1	High-Temperature Operation	T=50℃, RH=30%RH, For 240Hr	IEC 60 068-2-2Bb	
2	Low-Temperature Operation	$T = 0^{\circ}C$ for 240 hrs	IEC 60 068-2-2Ab	
3	High-Temperature Storage	T=70°C RH=40%RH For 240Hr Test in white pattern	IEC 60 068-2-2Bb	
4	Low-Temperature Storage	$T = -25^{\circ}$ C for 240 hrs Test in white pattern	IEC 60 068-2-2Ab	
5	High Temperature, High- Humidity Operation	T=40℃,RH=90%RH,For 168Hr	IEC 60 068-2-3CA	
6	High Temperature, High- Humidity Storage	T=60°C, RH=80%RH, For 480Hr Test in white pattern	IEC 60 068-2-3CA	
7	Temperature Cycle	-25 °C (30min)~70 °C (30min) , 50 Cycle Test in white pattern	IEC 60 068-2-14NB	
8	Package Vibration	1.04G,Frequency : 10~500Hz Direction : X,Y,Z Duration:1hours in each direction	Full packed for shipment	
9	Package Drop Impact	Drop from height of 122 cm on Concrete surface Drop sequence:1 corner, 3edges, 6face One drop for each.	Full packed for shipment	
10	UV exposure Resistance	765 W/ m² for 168hrs,40°C	IEC 60068-2-5 Sa	
11	Electrostatic discharge	Machine model: +/-250V,0Ω,200pF	IEC61000-4-2	

Actual EMC level to be measured on customer application. Note1:

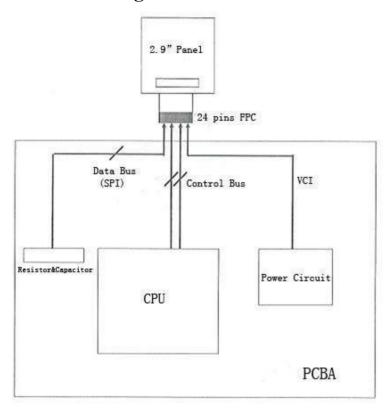
The protective film must be removed before temperature test. Note2:

Stay white pattern for storage and non-operation test.

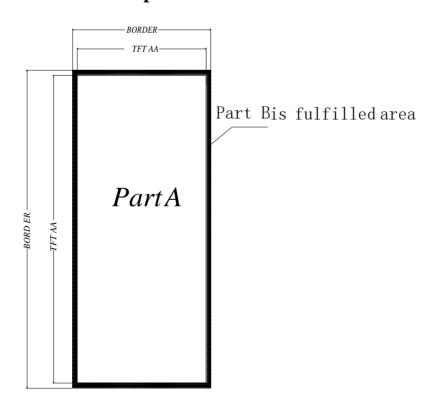
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17 Block Diagram



18 PartA/PartB specification



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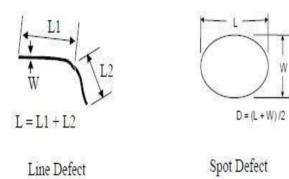


19 Point and line standard

	S	hipment Ins	pection Star	ndard					
Equipment: Electrical test fixture, Point gauge									
Outline dimension	36.7 (H) × 79(V) ×1.05(D)	Unit: mm Part-A		Active area	Part-B	Border area			
	Temperature	Humidity	Illuminance	Distance	Time	Angle			
Environment	19℃~25℃	55% ±5%RH	800~ 1300Lux	300 mm	35Sec				
Defet type	Inspection method	Standard		Part-A		Part-B			
		D≤0.	.25 mm	Ignor	re	Ignore			
Spot	Electric Display	0.25 mm<	D≤0.4 mm	N≤4		Ignore			
		D>0).4 mm	Not Allow		Ignore			
Display unwork	Electric Display	Not A	Allow	Not Allow		Ignore			
Display error	Electric Display	Not A	Allow	Not Allow		Ignore			
		L≤2 mm,	W≤0.2 mm	Ignore		Ignore			
Scratch or line defect(include dirt)	Visual/Film card	2.0mm <l≤5. ≤0.3</l≤5. 		N≤2		Ignore			
		L>5 mm,	W>0.3 mm	Not Al	Ignore				
		D≤0	.2mm	Ignor	Ignore				
PS Bubble	Visual/Film card	0.2mm≤D≤0	.35mm & N≤4	N≤	Ignore				
		D>0.	.35 mm	Not Al	Ignore				
		$X \le 5$ mm, $Y \le 0.5$ mm, Do not affect the electrode circuit							
Side Fragment	Visual/Film card		, Ignore						
Remark	1.Cannot be defect & failure cause by appearance defect;								
	2.Cannot be larger size cause by appearance defect;								
		L=long V	V=wide D=poin	t size N=Def	ects NO				

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L=long W=wide D=pointsize

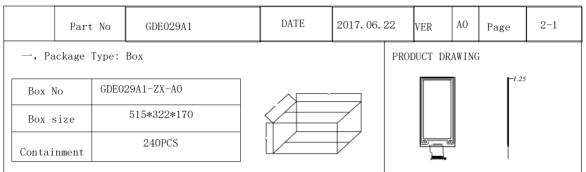
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20.Packing

Packing Spec

Sheet No:



__, Inside package type:Plastic

Trayunit: mm

1100		
Plastic Tray	465*280*15	13 pcs
Anti-static foil bags	700*530*0.1	1 pcs
EPE(inside)	408. 86*231. 5*2	12 pcs
EPE (Up-Down)	485*145*10	2 pcs
EPE(Left-Right)	285*480*10	2 pcs
EPE (Front-back)	310*145*10	2 pcs
Chip board	500*306*5	2 pcs
Quantity/tray	20 pcs	
Tray number/sheet	12+1 Sh	eets
Box	1	

Step 3:

1) In each case, put 2 bags of desiccant then seal the trays with adhesive tapes.

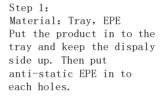
- 2) Put the trays into foil bags.
- 3) heat seal the foil bags.





Chip Board

-Chip Board





- 1) Must keep the angle 180 degree placed between Anti-static EPE the neighboring Plastic trays.
 - 2) There are 12 layers product, total 20*12=240 pcs.
 - 3) An empty Plastic tray intersects put on the top of the plastic trays.



1) Seal the box with adhensive tapes . 2) Paste the lable onto the exterior box, and the lable can't cover the safety , transfer and RoSH sign.



1) First put a chip board on the buttom of the box, then placed the down EPE, the left - right and front -back EPE.

- 2) Placed the sealed products into the box.
- 3) The last placed the up EPE on the top of the trays, and place a chip board on it.

Design	X. Z. P	Approve	J. P. F	Confirm	X.X.M
Date	2017. 06. 22	Date	2017. 06. 22	Date	2017. 06. 22

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