

# Vv255 Applied Calculus III

## Recitation II

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# Contents

Lecture 4: Parametric Equations, Equations of lines and planes

Lecture 5: Vector-valued functions; Derivatives and Integrals

Lecture 6: Arc Length and Curvature

Lecture 7: Planetary Motion in Polar coordinates

## Line in $\mathbb{R}^3$

- ▶ Vector equation:

$$\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}$$

- ▶ Parametric equations:

$$x = x_0 + at \quad y = y_0 + bt \quad z = z_0 + ct$$

- ▶ Symmetric equations:

$$\frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c}$$

- ▶ Line segments from  $\mathbf{r}_1$  to  $\mathbf{r}_2$  is given by:

$$\mathbf{r} = (1 - t)\mathbf{r}_1 + t\mathbf{r}_2 \quad 0 \leq t \leq 1$$

## Plane in $\mathbb{R}^3$

- ▶ Vector equation:

$$\mathbf{n} \cdot (\mathbf{r} - \mathbf{r}_0) = 0$$

- ▶ Scalar equation:

$$a(x - x_0) + b(y - y_0) + c(z - z_0) = 0$$

- ▶ Linear equation:

$$ax + by + cz + d = 0 \quad \text{where} \quad d = -ax_0 - by_0 - cz_0$$

- ▶ Distance  $D$  from a Point to a Line in Space:

$$D = \frac{|\overrightarrow{P_0 P_1} \times \mathbf{v}|}{|\mathbf{v}|}$$

- ▶ Distance  $D$  from a Point to a Plane:

$$D = \frac{|\overrightarrow{P_0 P_1} \cdot \mathbf{n}|}{|\mathbf{n}|}$$

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# Limit, Continuity, Derivative, Integral

- Limit (A practical way to calculate)

$$\lim_{t \rightarrow a} \begin{bmatrix} f(t) \\ g(t) \\ h(t) \end{bmatrix} = \begin{bmatrix} \lim_{t \rightarrow a} f(t) \\ \lim_{t \rightarrow a} g(t) \\ \lim_{t \rightarrow a} h(t) \end{bmatrix}$$

- Continuity:

A vector function  $\mathbf{r}(t)$  is continuous at a point  $t = a$  in its domain if

$$\lim_{t \rightarrow a} \mathbf{r}(t) = \mathbf{r}(a)$$

The function is **continuous** if it is **continuous** at every point in its domain.

- Derivative:

$$\mathbf{r}'(t) = \frac{d\mathbf{r}}{dt} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \mathbf{r}}{\Delta t} = \begin{bmatrix} f'(t) \\ g'(t) \\ h'(t) \end{bmatrix}$$

# Limit, Continuity, Derivative, Integral (cont.)

$\mathbf{r}'(t)$  is known as the **tangent vector**.

► Differentiation rules for vector-valued function.

Suppose  $\mathbf{u}$  and  $\mathbf{v}$  are differentiable vector functions of  $t$ .

1. Addition

$$\frac{d}{dt}[\mathbf{u} + \mathbf{v}] = \mathbf{u}' + \mathbf{v}'$$

2. Scalar multiplication

$$\frac{d}{dt}[f\mathbf{u}] = f'\mathbf{u} + f\mathbf{u}', \quad \text{where } f \text{ is a real-valued function of } t.$$

3. Dot product

$$\frac{d}{dt}[\mathbf{u} \cdot \mathbf{v}] = \mathbf{u}' \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{v}'$$

4. Cross product

$$\frac{d}{dt}[\mathbf{u} \times \mathbf{v}] = \mathbf{u}' \times \mathbf{v} + \mathbf{u} \times \mathbf{v}'$$

5. Chain rule

$$\frac{d}{dt}[\mathbf{u}(f(t))] = f'(t)\mathbf{u}'(f(t)), \quad \text{where } f \text{ is a real-valued function of } t.$$

# Limit, Continuity, Derivative, Integral (cont.)

- ▶ Indefinite integral

$$\int \mathbf{r}(t) dt = \mathbf{R}(t) + \mathbf{C}$$

- ▶ Definite integral

$$\int_a^b \mathbf{r}(t) dt = \begin{bmatrix} \int_a^b f(t) dt \\ \int_a^b g(t) dt \\ \int_a^b h(t) dt \end{bmatrix}$$

- ▶ The Fundamental Theorem of Calculus

$$\int_a^b \mathbf{r}(t) dt = \mathbf{R}(t) \Big|_a^b = \mathbf{R}(b) - \mathbf{R}(a)$$



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# T, B, N, and curvature $\kappa$

- **T**: unit tangent vector

$$\mathbf{T} = \frac{d\mathbf{r}}{ds} = \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{d\mathbf{r}/dt}{|d\mathbf{r}/dt|}$$

- $\kappa$ : curvature

$$\kappa = \left| \frac{d\mathbf{T}}{ds} \right| = \frac{|\mathbf{T}'(t)|}{|\mathbf{r}'(t)|} = \frac{|\mathbf{r}'(t) \times \mathbf{r}''(t)|}{|\mathbf{r}'(t)|^3} = \frac{|f''(x)|}{(1 + [f'(x)]^2)^{3/2}} = \frac{|x''y' - y''x'|}{((x')^2 + (y')^2)^{3/2}}$$

If  $\kappa$  is large, **T** turns sharply, otherwise **T** turns slowly.

- **N**: principal unit normal vector

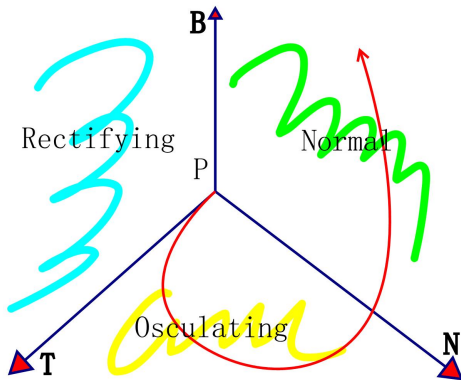
$$\mathbf{N} = \frac{1}{\kappa} \frac{d\mathbf{T}}{ds} = \frac{d\mathbf{T}/dt}{|d\mathbf{T}/dt|}$$

- **B**: binormal vector

$$\mathbf{B} = \mathbf{T} \times \mathbf{N}$$

# T, B, N, and curvature $\kappa$ (cont.)

- Three planes:



The curvature can be thought of as the rate at which the normal plane turns as  $P$  moves along its path.

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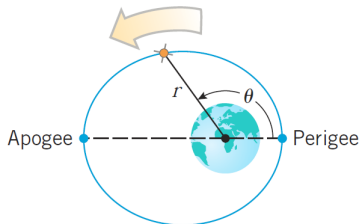
# Kepler's Law

## Kepler's Law

### 1. First law (Law of Orbits).

*The orbit of a planet is an ellipse with the Sun at one of the two foci.*

E.g. Satellite motion around the Earth:



## Kepler's Law (cont.)

### 2. Second law (Law of Areas).

*A line segment joining a planet and the Sun sweeps out equal areas during equal intervals of time.*

## Kepler's Law (cont.)

### 3. Third law (Law of Periods).

*The square of the orbital period of a planet is proportional to the cube of the semi-major axis of its orbit.*

$$T^2 = \frac{4\pi^2}{GM} a^3 \quad \Rightarrow \quad T = \frac{2\pi}{\sqrt{GM}} a^{\frac{3}{2}}$$