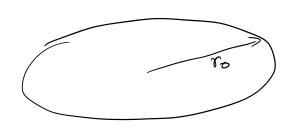
Problem 1 (24.15)

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for escape speed,
$$-\frac{GMm}{r} + \frac{1}{2}mv^2 = 0$$
 to equilibrium $v = \sqrt{\frac{2GM}{r_0}}$

$$\frac{V^{2} V_{0}}{2 G} = M = \frac{3 \times 10^{3} \times 10^{3} \text{ M/s} \times 3 \times 10^{5} \times 206265 \times 1.5 \times 10^{3}}{2 \times G}$$

$$= 8.36 \times 10^{10} M_{0}$$

b) let
$$V = 500$$

$$M = \frac{v^2 r_0}{2 G} = 2.32 \times 10^{11}$$
the extra mass from DM

c) Since by observation mass exist at $r > R_0$, which is not approximatable through solar someunding.

a)
$$\frac{a^3}{p^2} = 1$$
 $(a:AU, p:yr)$
 $\theta = R \frac{d\theta}{dt}$

$$P = \frac{277}{\sqrt{G(M_1 + M_2)}} R^{\frac{2}{2}}$$

$$\frac{27}{\sqrt{a(m_1 + m_2)}} R^{\frac{2}{2}} = \frac{27R}{4RR}$$

$$\sqrt{\frac{R}{a(m_1 + m_2)}} = \frac{1}{4R}$$

$$\mathcal{D}(R) = \sqrt{\frac{a(\omega_1 + \omega_2)}{R}}$$

b)
$$A = -\frac{1}{2} \left[\frac{d\Theta}{dR} \Big|_{R_0} - \frac{\Theta_0}{R_0} \right]$$

$$B = -\frac{1}{2} \left[\frac{d\Theta}{dR} \Big|_{Q_0} + \frac{\Theta_0}{R_0} \right]$$

$$\frac{Q}{dR} = \sqrt{G(M_1 + M_2)} \left(-\frac{1}{2} R^{-\frac{3}{2}} \right)$$

$$= -\frac{1}{2} \frac{\sqrt{G(M_1 + M_2)}}{\sqrt{R^3}} = -\frac{1}{2} \sqrt{G(M_1 + M_2)} R^{-\frac{3}{2}}$$

$$\frac{d}{dR}(\mathcal{D}_{R}) = -\frac{1}{2} \frac{\sqrt{\mathcal{U}_{mit}m_{2}}}{R^{\frac{1}{2}}}$$

$$A = -\frac{1}{2} \times \left(-\frac{3}{2} \sqrt{\frac{G(m_1 + m_2)}{R_0^2}}\right)$$

$$= \frac{3}{4} \sqrt{\frac{G(m_1 + m_2)}{R_0^3}}$$

$$B = -\frac{1}{2} \times \left(-\frac{1}{2} \sqrt{\frac{G(m_1 + m_2)}{R_0^3}} + \sqrt{\frac{G(m_1 + m_2)}{R_0^3}}\right)$$

$$= -\frac{1}{4} \sqrt{\frac{G(m_1 + m_2)}{R_0^3}}$$

Roblem 3 (24.21)

Use eg 24.5 estimuse from locally in

kg m-3, MOPC-3, MOAU-3

$$r = Ro = 8kpc \qquad \qquad P(r) = \frac{V^2}{4\pi G r^2}$$

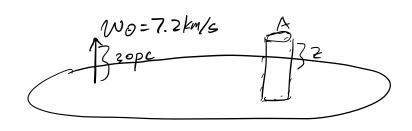
mm mm

= 9.47e-22
$$\frac{kg \times Mo}{kg} \times m^{-3} \times \frac{(Pc)^{-3}}{m}$$

= 9.47e-22 $\times 1.989$ e30 $Mo \times 3.085 \times 10^{-3}$

Problem 4 24.27

a)



b)
$$g = \frac{d^2z}{dt^2} = -4\pi Gtz$$

$$\frac{d^2z}{dt^2} + 4\pi G t = 0$$
 , $k = 4\pi G \rho$

C)
$$w_0^2 = 4\pi G f$$

$$Z = A \cos(\sqrt{4\pi G f} + f)$$

$$W = \frac{d}{d \epsilon^2} = -\sqrt{4\pi G f} A \sin(\sqrt{4\pi f G} + f)$$

d)
$$P = \frac{2\pi}{w} = \frac{2\pi}{\sqrt{4\pi} + a} = 2.15 \times 10^{15} \text{ s}$$

= 6.82 \tau 08 \text{ yr}

e) take
$$\phi_0 = 0$$

A
$$cos(wt) = 30pc$$

$$-wAsin(wt) = 7.2 km/s$$

$$A Sin(wt) = -79.95 pc$$

$$A^{2}\cos^{2}(wt_{0}) + A^{2}\sin^{2}(wt_{0}) = A^{2} = 7292.546$$
 pc
 $A = 65.4$ pc

$$f) \frac{2\pi R_0}{\Theta_0} = P_{orbit} = 7 \times 10^5 \text{ s}$$

Updown =
$$\frac{Porbit}{P} = \frac{7}{2.15} = 3.25$$
 repetitions