

W³(IR):

- · CONSIDER A SMALL ACTIVE ROTATION OF V AROUND W,
 By A CCW ANGLE AB (0 : AB «1)
- · VECTOR AFTER ROTATION = V

•
$$\overrightarrow{\nabla}' = \overrightarrow{\nabla} + \overrightarrow{\Delta \nabla}; \quad \overrightarrow{\Delta \nabla} = (\overrightarrow{\Pi_W} \times \overrightarrow{\nabla}) \Delta \Theta; \quad \overrightarrow{\Pi_W} = \frac{\overrightarrow{W}}{|\overrightarrow{W}|}$$

①
$$\Delta \vec{\nabla}$$
 is \perp to Both $\vec{W}, \vec{\nabla}$; PRESERVES NORM
$$\vec{\nabla}.\vec{\nabla}' = (\vec{\nabla} + (\vec{\Pi}_{\vec{W}} \vec{\nabla}) \Delta \Theta) \cdot (\vec{\nabla} + (\vec{\Pi}_{\vec{W}} \vec{\nabla}) \Delta \Theta)$$

$$= \vec{\nabla}^2 + \mathcal{O}(\Delta \Theta)^2$$

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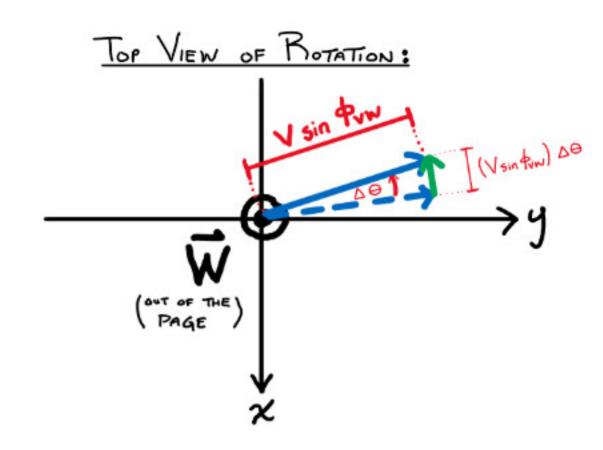
$$= \vec{\nabla}^2 + \mathcal{O}(\Delta \Theta)^2$$

2)
$$|\Delta \vec{\nabla}| = (V \sin \phi_{vw}) \cdot \Delta \theta$$
;

PROJECTION OF

V in Plane 1

To W



REWRITE USING LEVI-CIVITA:

· ASSUME ORTHONORMAL BASIS ETTA3; Ta. Th= Sab

- · LET US DEFINE $\overrightarrow{\Delta\Theta} = \Delta\Theta \overrightarrow{\sqcap}_{W}; \overrightarrow{\nabla} = \overrightarrow{\nabla} + \overrightarrow{\Delta\Theta} \times \overrightarrow{\nabla}$
- USING Eabc: $\overrightarrow{V} = \overrightarrow{V} + \epsilon_{bcd} \overrightarrow{\sqcap}_b (\overrightarrow{\Delta \theta})_c (\overrightarrow{V})_d$ EINSTEIN SUM ON b,c,d

 BASIS
 VECTOR

 COMPONENT COMPONENT LABEL

 LABEL

 LABEL

 WHICH

• SUPPOSE $V = \vec{\Pi}_{a}$, A PARTICULAR BASIS VECTOR

:
$$\vec{\Pi}_a = \vec{\Pi}_a + \vec{\Delta\Theta} \times \vec{\Pi}_a = \vec{\Pi}_a + \epsilon_{bcd} \vec{\Pi}_b (\vec{\Delta\Theta})_c (\vec{\Pi}_a)_d$$

BUT: (Ta)d = Sa,d

$$\vec{n}_a = \vec{n}_a + \epsilon_{bca} \vec{n}_b (\vec{\Delta \theta})_c$$

KET NOTATION: $|\vec{n}_a\rangle = |\vec{n}_a\rangle + \varepsilon_{bca} (\Delta \vec{\Theta})_c (\vec{n}_b) = \sum_{b,c} |\vec{n}_a\rangle + (\Delta \vec{\Theta} \times \vec{n}_a)_b |\vec{n}_b\rangle = \sum_{constens} |\vec{n}_a\rangle + (\Delta \vec{\Theta} \times \vec{n}_a)_b |\vec{n}_b\rangle = \sum_{constens} |\vec{n}_a\rangle + |\Delta \vec{\Theta} \times \vec{n}_a\rangle$

• GENERATOR VERSION (LEC. 19, P.3,4)
$$|\vec{n}_a\rangle = e^{\Delta \vec{\Theta} \cdot \hat{\vec{G}}} |\vec{n}_a\rangle \simeq (\hat{\mathbf{I}} + \Delta \vec{\Theta} \cdot \hat{\vec{G}})|\vec{n}_a\rangle$$

..
$$\Delta\Theta \cdot \hat{G} | \vec{n}_a \rangle = |\Delta\Theta \times \vec{n}_a \rangle = (\Delta\Theta \times \vec{n}_a)_b | \vec{n}_b \rangle$$

$$= \epsilon_{bca} (\Delta\Theta)_c (\vec{n}_a)_d | \vec{n}_b \rangle$$

$$= \epsilon_{bca} (\Delta\Theta)_c | \vec{n}_b \rangle$$