

# Problem 1 (25.2)

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a)  $M_a = -21.51$

$$\log(R_{25}) = -0.249 M_B - 4$$

$$R_{25} = 10^{0.249 \times 21.51 - 4}$$

$$= 22.7 \text{ kpc}$$

b)  $S_e$ :

$$M_B = -11 \log(V_{\max}) + 3.31$$

$$10^{\left(\frac{M_B - 3.31}{-11}\right)} = V_{\max}$$

$$V_{\max} = 180 \text{ km/s}$$

c)  $P = \frac{2\pi R}{V}$

$$\omega = \frac{2\pi}{P} = \frac{V}{R} = \frac{180}{22.7}$$

$$= 2.569742 \text{ rad/s}$$

$$= 8.1 \times 10^{-9} \text{ rad/y}$$

$$= 0.001673 \text{ ''/yr}$$

d)  $T = \frac{1}{\omega} = \frac{1}{0.001673} \approx 598 \text{ yr}$

The separation in Hawaii is  $0.2''$ , if good  $0.1''$

which, might be possible, if all fortunes on the world is in you.

## Problem 2 (25.6)

$$L(R, z) = L_0 e^{-\frac{R}{h_R} \operatorname{sech}^2(z/z_0)}$$

$$z=0:$$

$$\log\left[\frac{L(R)}{L_0}\right] = -\left(\frac{R}{h_R}\right) \log e = -0.434\left(\frac{R}{h_R}\right)$$

$$\log\left(\frac{L}{L_0}\right) = -0.434\left(\frac{R}{h_R}\right)$$

$$\frac{M_0 - M}{2.5} = -0.434\left(\frac{R}{h_R}\right)$$

$$\mu_0 - \mu = -1.09\left(\frac{R}{h_R}\right)$$

$$\mu = \mu_0 + 1.09\left(\frac{R}{h_R}\right)$$

## Problem 3 (25.7)

$$a) \text{ eq 24.13: } \log\left(\frac{I}{I_0}\right) = -3.3307\left(\left(\frac{r}{r_e}\right)^{\frac{1}{4}} - 1\right)$$

$$\frac{\ln\left(\frac{I}{I_0}\right)}{\ln(10)} = -3.3307\left(\left(\frac{r}{r_e}\right)^{\frac{1}{4}} - 1\right)$$

$$\frac{\ln\left(\frac{I}{I_0}\right)}{2.3} = -3.3307\left(\left(\frac{r}{r_e}\right)^{\frac{1}{4}} - 1\right)$$

$$\ln\left(\frac{I}{I_0}\right) = -7.66 \left( \left( \frac{r}{r_e} \right)^{\frac{1}{4}} - 1 \right)$$

$$I = I_0 e^{-7.66 \left( \left( \frac{r}{r_e} \right)^{\frac{1}{4}} - 1 \right)}$$

↑  
(little off)

$$b) \quad L_{tot} = \int_0^\infty 2\pi r I dr$$

$$\text{let } x = \left( \frac{r}{r_e} \right)^{\frac{1}{4}} = r^{\frac{1}{4}} r_e^{-\frac{1}{4}}$$

$$\frac{dx}{dr} = \frac{1}{4} r^{-\frac{3}{4}} r_e^{-\frac{1}{4}}$$

$$dr = 4 r^{\frac{3}{4}} r_e^{\frac{1}{4}} dx$$

$$= 4 \frac{r^{\frac{3}{4}}}{r_e^{\frac{3}{4}}} r_e dx$$

$$= 4 x^3 r_e dx$$

$$x^4 = \frac{r}{r_e}$$

$$r = x^4 r_e$$

$$\therefore L_{tot} = \int_0^\infty 2\pi x^4 r_e e^{-7.66 x} I_0 e^{7.66} 4x^3 r_e dx$$

$$= 8\pi r_e^2 e^{7.67} I_0 \int_0^\infty e^{-7.67 x} x^7 dx$$

$$= 8! \pi r_e^2 \frac{e^{7.67}}{(7.66)^8} I_0 \approx 7.22 \pi r_e^2 I_0$$

$$c) \quad r=0 \sim r=r_e \quad \checkmark \quad \text{let } x = 7.67 \left( \frac{r}{r_e} \right)^{\frac{1}{4}} \text{ instead so no consider extra terms.}$$

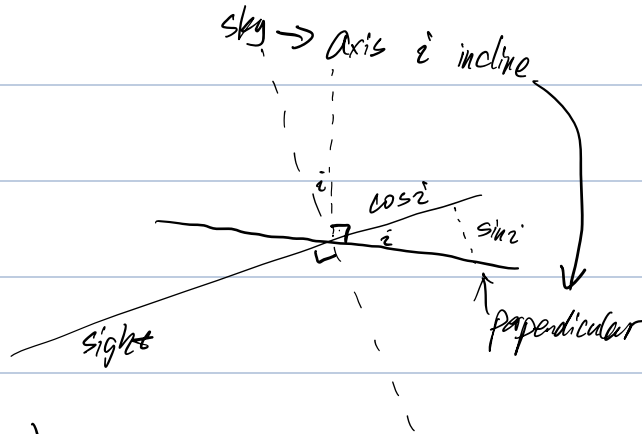
$$\int_0^{7.67} x^7 e^{-x} = 7! e^{-x} \sum_{i=0}^7 (-1)^i \frac{x^{7-i}}{(7-i)! (-1)^{i+1}} \Big|_0^b = 0.57! = \frac{1}{2} \int_0^\infty x^7 e^{-x}$$

$$= \frac{1}{2} L_{tot}$$

# Problem 4

$$\oplus(R)$$

$$v = \oplus(R)$$



$$\text{Ca II} \quad F_{\lambda} \propto \delta(\lambda - \lambda_0)$$

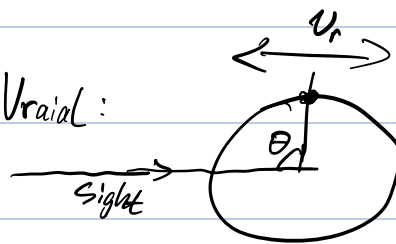
$$a) \quad \frac{\Delta \lambda}{\lambda_0} = \frac{v_r}{c} = z$$

$$b) \quad \text{broaden} = F_{\lambda b} = \delta(\lambda - \lambda_{\text{new}})$$

first we adjust the velocity to  $v_{\text{radial}}$ :

$$v_r = \underset{\substack{\text{inclined} \\ \downarrow}}{V \cos(i)} \times \underset{\substack{\text{rotation component} \\ \downarrow}}{\sin(\theta)}$$

$$= \oplus(R) \cos(i) \sin(\theta)$$



$$\text{We want } F_b(\lambda, R)$$

which for each displacement  $\frac{\Delta \lambda}{\lambda_0} = \frac{v_r}{c}$ , the new line is at  $\lambda_{\text{new}} = \lambda_0 + \Delta \lambda$

$$\lambda_{\text{new}} = \lambda_0 + \frac{v_r}{c} \lambda_0$$

$$= (1 + \frac{v_r}{c}) \lambda_0$$

$$\therefore F_b(\lambda, R) = \epsilon \delta(\lambda - (1 + \frac{v_r}{c}) \lambda_0)$$

$$= \int_{\theta=0}^{2\pi} \delta(\lambda - (1 + \frac{\oplus(R)}{c} \cos(i) \sin(\theta)) \lambda_0) d\theta$$

$$x = \sin \theta$$

$$\frac{dx}{d\theta} = \cos \theta$$

$$dx = \cos \theta d\theta$$

$$1 - x^2$$

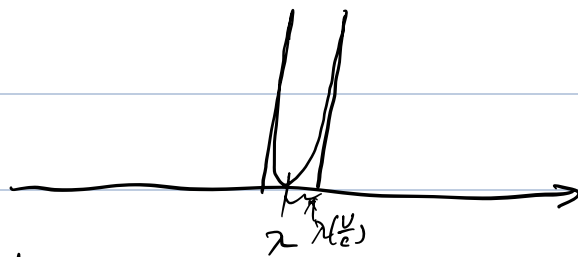
$$F_b(\lambda, R) = \int_{-1}^1 \delta(\lambda - (1 + \frac{\Theta(R)}{c} \cos(i) x) \lambda_0) \frac{1}{\sqrt{1-x^2}} dx \quad \text{integrand} > 0$$

$$\lambda = (1 + \frac{\Theta(R)}{c} \cos(i) x) \lambda_0$$

$$(\frac{\lambda}{\lambda_0} - 1) = \cos(i) \frac{\Theta}{c} x$$

$$(\frac{\lambda}{\lambda_0} - 1) \frac{c}{\Theta \cos(i)} = x$$

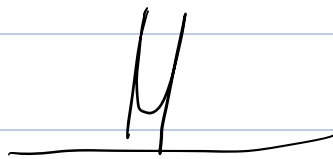
$$F_b(\lambda, R) = \lambda \left( 1 + \frac{1}{\sqrt{1 - (\frac{\lambda}{\lambda_0} - 1)^2 \left( \frac{c}{\Theta \cos(i)} \right)^2}} \right)$$



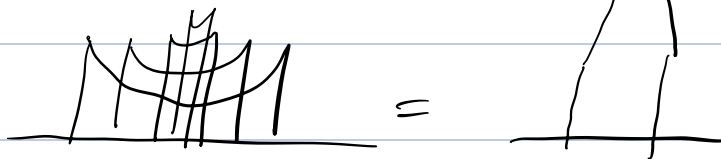
c) Consider opacity,

The more edge on, the more light blocked from smaller R.

Thus: more edge on:



less edge on:



Also, velocity dispersion adds a gaussian convolution to the shape, so will be blurry.

d) in such case, from the shape <sup>of lines</sup>  $\gamma$  it is possible to determine  $i$ , by how clear the two peaks of red and blue shifts are.

c)  $E_k = \frac{3}{2} k_B T = \frac{1}{2} m v^2$ , take  $m$  to be hydrogen

$$m = 1.67 \times 10^{-27} \text{ kg}$$

$$k_B = 1.383 \times 10^{-23}$$

$$v = 220 \times 10^3 \text{ m/s}$$

$$T = \frac{m v^2}{3 k_B}$$

$$= 1.95 \text{ MT}, \text{ a little too high}$$

$\therefore$  probably not dominate.