

The minimal need-to-know about arrays

- Arrays are a generalization of vectors where we can have multiple indices: $A_{i,j}$, $A_{i,j,k}$ – in code this is nothing but nested lists, accessed as `A[i][j]`, `A[i][j][k]`
- Example: table of numbers, one index for the row, one for the column

$$\begin{bmatrix} 0 & 12 & -1 & 5 \\ -1 & -1 & -1 & 0 \\ 11 & 5 & 5 & -2 \end{bmatrix} \quad A = \begin{bmatrix} A_{0,0} & \cdots & A_{0,n-1} \\ \vdots & \ddots & \vdots \\ A_{m-1,0} & \cdots & A_{m-1,n-1} \end{bmatrix}$$

- The no of indices in an array is the *rank* or *number of dimensions*
- Vector = one-dimensional array, or rank 1 array
- In Python code, we use Numerical Python arrays instead of lists to represent mathematical arrays (because this is computationally more efficient)

Storing (x,y) points on a curve in lists/arrays

- Collect (x,y) points on a function curve $y = f(x)$ in a list:

```
>>> def f(x):  
...     return x**3          # sample function  
...  
>>> n = 5                    # no of points in [0,1]  
>>> dx = 1.0/(n-1)          # x spacing  
>>> xlist = [i*dx for i in range(n)]  
>>> ylist = [f(x) for x in xlist]  
  
>>> pairs = [[x, y] for x, y in zip(xlist, ylist)]
```

- Turn lists into Numerical Python (NumPy) arrays:

```
>>> import numpy as np  
>>> x2 = np.array(xlist)      # turn list xlist into array  
>>> y2 = np.array(ylist)
```

Make arrays directly (instead of lists)

- Instead of first making lists with x and $y = f(x)$ data, and then turning lists into arrays, we can make NumPy arrays directly:

```
>>> n = 5                                # number of points
>>> x2 = np.linspace(0, 1, n)           # n points in [0, 1]
>>> y2 = np.zeros(n)                    # n zeros (float data type)
>>> for i in xrange(n):
...     y2[i] = f(x2[i])
... 
```

- `xrange` is similar to `range` but faster (esp. for large n – `xrange` does not explicitly build a list of integers, `xrange` just lets you loop over the values)
- List comprehensions create lists, not arrays, but we can do

```
>>> y2 = np.array([f(xi) for xi in x2]) # list -> array
```

The clue about NumPy arrays (part 1)

- Lists can hold any sequence of any Python objects
- Arrays can only hold objects of the same type
- Arrays are most efficient when the elements are of basic number types (`float`, `int`, `complex`)
- In that case, arrays are stored efficiently in the computer memory and we can compute very efficiently with the array elements

The clue about NumPy arrays (part 2)

- Mathematical operations on whole arrays can be done without loops in Python

- For example,

```
x = np.linspace(0, 2, 10001)    # numpy array
for i in xrange(len(x)):
    y[i] = sin(x[i])
```

can be coded as

```
y = np.sin(x)                  # x: array, y: array
```

and the loop over all elements is now performed in a very efficient C function

- Operations on whole arrays, instead of using Python for loops, is called *vectorization* and is very convenient and very efficient (and an important programming technique to master)

Vectorizing the computation of points on a function curve

- Consider the loop with computing x coordinates (x_2) and $y = f(x)$ coordinates (y_2) along a function curve:

```
x2 = np.linspace(0, 1, n)    # n points in [0, 1]
y2 = np.zeros(n)             # n zeros (float data type)
for i in xrange(n):
    y2[i] = f(x2[i])
```

- This computation can be replaced by

```
x2 = np.linspace(0, 1, n)    # n points in [0, 1]
y2 = f(x2)                   # y2[i] = f(x[i]) for all i
```

- Advantage: 1) no need to allocate space for y_2 (via `np.zeros`), 2) no need for a loop, 3) *much* faster computation
- Next slide explains what happens in `f(x2)`

How a vectorized function works

- Consider

```
def f(x):  
    return x**3
```

- $f(x)$ is intended for a number x , called *scalar* – contrary to vector/array
- What happens with a call $f(x_2)$ when x_2 is an array?
- The function then evaluates $x**3$ for an array x
- Numerical Python supports arithmetic operations on arrays, which correspond to the equivalent operations on each element

```
from numpy import cos, exp  
x**3           # x[i]**3           for all i  
cos(x)         # cos(x[i])        for all i  
x**3 + x*cos(x) # x[i]**3 + x[i]*cos(x[i]) for all i  
x/3*exp(-x*a)  # x[i]/3*exp(-x[i]*a) for all i
```

- Functions that can operate on vectors (or arrays in general) are called vectorized functions (containing vectorized expressions)
- Vectorization is the process of turning a non-vectorized expression/algorithm into a vectorized expression/algorithm
- Mathematical functions in Python without `if` tests automatically work for both scalar and array (vector) arguments (i.e., no vectorization is needed by the programmer)

More explanation of a vectorized expression

- Consider $y = x**3 + x*\cos(x)$ with array x
- This is how the expression is computed:

```
r1 = x**3      # call C function for x[i]**3 loop
r2 = cos(x)    # call C function for cos(x[i]) loop
r3 = x*r2      # call C function for x[i]*r2[i] loop
y = r1 + r3    # call C function for r1[i]+r3[i] loop
```
- The C functions are highly optimized and run very much faster than Python for loops (factor 10-500)
- Note: `cos(x)` calls numpy's `cos` (for arrays), not `math`'s `cos` (for scalars) if we have done `from numpy import cos` or `from numpy import *`

Summarizing array example

- Make two arrays x and y with 51 coordinates x_i and $y_i = f(x_i)$ on the curve $y = f(x)$, for $x \in [0, 5]$ and $f(x) = e^{-x} \sin(\omega x)$:

```
from numpy import linspace, exp, sin, pi
```

```
def f(x):  
    return exp(-x)*sin(omega*x)
```

```
omega = 2*pi  
x = linspace(0, 5, 51)  
y = f(x)      # or y = exp(-x)*sin(omega*x)
```

- Without numpy:

```
from math import exp, sin, pi
```

```
def f(x):  
    return exp(-x)*sin(omega*x)
```

```
omega = 2*pi  
n = 51  
dx = (5-0)/float(n)  
x = [i*dx for i in range(n)]  
y = [f(xi) for xi in x]
```

Assignment of an array does not copy the elements!

- Consider this code:

```
a = x  
a[-1] = q
```

- Is `x[-1]` also changed to `q`? Yes!
- `a` refers to the same array as `x`
- To avoid changing `x`, `a` must be a copy of `x`:

```
a = x.copy()
```

- The same yields slices:

```
a = x[r:]  
a[-1] = q    # changes x[-1]!  
a = x[r:].copy()  
a[-1] = q    # does not change x[-1]
```

In-place array arithmetics

- We have said that the two following statements are equivalent:

$a = a + b$ # a and b are arrays
 $a += b$

- Mathematically, this is true, but not computationally
- $a = a + b$ first computes $a + b$ and stores the result in an intermediate (hidden) array (say) $r1$ and then the name a is bound to $r1$ – the old array a is lost
- $a += b$ adds elements of b *in-place* in a , i.e., directly into the elements of a without making an extra $a+b$ array
- $a = a + b$ is therefore less efficient than $a += b$

More on useful array operations

- Make a new array with same size as another array:

```
# x is numpy array
a = x.copy()
# or
a = zeros(x.shape, x.dtype)
```

- Make sure a list or array is an array:

```
a = asarray(a)
b = asarray(somearray, dtype=float)
```

- Test if an object is an array:

```
>>> type(a)
<type 'numpy.ndarray'>
>>> isinstance(a, ndarray)
True
```

- Generate range of numbers with given spacing:

```
>>> arange(-1, 1, 0.5)
array([-1. , -0.5,  0. ,  0.5]) # 1 is not included!
>>> linspace(-1, 0.5, 4)         # equiv. array

>>> from scitools.std import *
>>> seq(-1, 1, 0.5)               # 1 is included
array([-1. , -0.5,  0. ,  0.5,  1. ])
```

Example: vectorizing a constant function

- Constant function:

```
def f(x):  
    return 2
```

- Vectorized version must return array of 2's:

```
def fv(x):  
    return zeros(x.shape, x.dtype) + 2
```

- New version valid both for scalar and array x:

```
def f(x):  
    if isinstance(x, (float, int)):  
        return 2  
    elif isinstance(x, ndarray):  
        return zeros(x.shape, x.dtype) + 2  
    else:  
        raise TypeError\  
        ('x must be int/float/ndarray, not %s' % type(x))
```

Generalized array indexing

- Recall slicing: `a[f:t:i]`, where the slice `f:t:i` implies a set of indices
- Any integer list or array can be used to indicate a set of indices:

```
>>> a = linspace(1, 8, 8)
>>> a
array([ 1.,  2.,  3.,  4.,  5.,  6.,  7.,  8.])
>>> a[[1,6,7]] = 10
>>> a
array([ 1., 10.,  3.,  4.,  5.,  6., 10., 10.])
>>> a[range(2,8,3)] = -2 # same as a[2:8:3] = -2
>>> a
array([ 1., 10., -2.,  4.,  5., -2., 10., 10.])
```

- Boolean expressions can also be used (!)

```
>>> a[a < 0] # pick out all negative elements
array([-2., -2.])
>>> a[a < 0] = a.max() # if a[i]<10, set a[i]=10
>>> a
array([ 1., 10., 10.,  4.,  5., 10., 10., 10.])
```

Summary of vectors and arrays

- Vector/array computing: apply a mathematical expression to every element in the vector/array
- Ex: `sin(x**4)*exp(-x**2)`, `x` can be array or scalar, for array the `i`'th element becomes `sin(x[i]**4)*exp(-x[i]**2)`
- Vectorization: make scalar mathematical computation valid for vectors/arrays
- Pure mathematical expressions require no extra vectorization
- Mathematical formulas involving `if` tests require manual work for vectorization:

```
scalar_result = expression1 if condition else expression2  
vector_result = where(condition, expression1, expression2)
```


Array functionality

<code>array(1d)</code>	copy list data 1d to a numpy array
<code>asarray(d)</code>	make array of data d (copy if necessary)
<code>zeros(n)</code>	make a vector/array of length n, with zeros (float)
<code>zeros(n, int)</code>	make a vector/array of length n, with int zeros
<code>zeros((m,n), float)</code>	make a two-dimensional with shape (m,n)
<code>zeros(x.shape, x.dtype)</code>	make array with shape and element type as x
<code>linspace(a,b,m)</code>	uniform sequence of m numbers between a and b
<code>seq(a,b,h)</code>	uniform sequence of numbers from a to b with step h
<code>iseq(a,b,h)</code>	uniform sequence of integers from a to b with step h
<code>a.shape</code>	tuple containing a's shape
<code>a.size</code>	total no of elements in a
<code>len(a)</code>	length of a one-dim. array a (same as <code>a.shape[0]</code>)
<code>a.reshape(3,2)</code>	return a reshaped as 2×3 array
<code>a[i]</code>	vector indexing
<code>a[i,j]</code>	two-dim. array indexing
<code>a[1:k]</code>	slice: reference data with indices $1, \dots, k-1$
<code>a[1:8:3]</code>	slice: reference data with indices $1, 4, \dots, 7$
<code>b = a.copy()</code>	copy an array
<code>sin(a), exp(a), ...</code>	numpy functions applicable to arrays
<code>c = concatenate(a, b)</code>	c contains a with b appended
<code>c = where(cond, a1, a2)</code>	<code>c[i] = a1[i]</code> if <code>cond[i]</code> , else <code>c[i] = a2[i]</code>
<code>isinstance(a, ndarray)</code>	is True if a is an array
