

Say $\vec{b} = \begin{pmatrix} 6 \\ 8 \end{pmatrix}$.

$$\left(\begin{array}{cc|c} 2 & -1 & 6 \\ -1 & 2 & 8 \end{array} \right) \Rightarrow \left(\begin{array}{cc|c} 1 & -2 & -8 \\ 0 & 3 & 22 \end{array} \right) \Rightarrow \left(\begin{array}{cc|c} 1 & 0 & 20/3 \\ 0 & 1 & 22/3 \end{array} \right)$$

so $\vec{x}^* = \begin{pmatrix} 20/3 \\ 22/3 \end{pmatrix}$

Now use Jacobi:

Define $\begin{pmatrix} u_0 \\ v_0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$.

$$\begin{cases} u_1 = \frac{1}{2}v_0 + \frac{1}{2}b_1 = 0 + \frac{1}{2}(6) = 3 \\ v_1 = \frac{1}{2}u_0 + \frac{1}{2}b_2 = \frac{1}{2}(0) + \frac{1}{2}(8) = 4 \\ u_2 = \frac{1}{2}v_1 + \frac{1}{2}b_1 = \frac{1}{2}(4) + \frac{1}{2}(6) = 5 \\ v_2 = \frac{1}{2}u_1 + \frac{1}{2}b_2 = \frac{1}{2}(3) + \frac{1}{2}(8) = \frac{11}{2} \end{cases}$$

...

Process continues until $\|\vec{x}_{n+1} - \vec{x}_n\| < \epsilon$, a tolerance. Ideally $\epsilon = 0$.

Theorem: If A is dominant:

$$|a_{ii}| > \sum_{j \neq i} |a_{ij}|$$

and both iterative methods converge.

In general, eigenvalues of $S^T T$ determine convergence.

Recitation

Householder:

$$P(x) = (I - 2\vec{v}\vec{v}^T) \cdot \vec{x} = \|\vec{x}\| \vec{e}_1$$

$$\vec{x} - 2\vec{v}\vec{v}^T \vec{x} = \|\vec{x}\| \vec{e}_1$$

$$\vec{v} = \frac{\vec{x} - \|\vec{x}\| \vec{e}_1}{\|\vec{x} - \|\vec{x}\| \vec{e}_1\|}$$

$$A = (\vec{x}_1 | \vec{x}_2 | \vec{x}_3)$$

$$P_2 P_1 A = R$$

$$A = P_1^{-1} P_2^{-1} R = QR$$

Use this for #1 and #2 in Week 6 Homework.

1) $\vec{x} = \begin{pmatrix} 11 \\ 2 \end{pmatrix}$

$$\vec{v} = \vec{x} - \alpha \vec{e}_1 = \vec{x} + \|\vec{x}\| \vec{e}_1 = \begin{pmatrix} 11 \\ 2 \end{pmatrix} + 5\sqrt{5} \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\vec{q} = \frac{\vec{v}}{\|\vec{v}\|}$$

$$M = I - 2\vec{q}\vec{q}^T$$

3) a) $A = \begin{pmatrix} 3 & 5 \\ 4 & 2 \end{pmatrix}$

$$Q_1 A = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} Q_1 \cdot \vec{x}_2$$

$$\begin{pmatrix} 3 \\ 4 \end{pmatrix} = \alpha \begin{pmatrix} 2 \\ 0 \end{pmatrix}, \alpha = -\|\vec{x}\|$$

$$\vec{v} = \vec{x} + \|\vec{x}\| \vec{e}_1$$