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Principles of AI Planning

Exercise Sheet 11

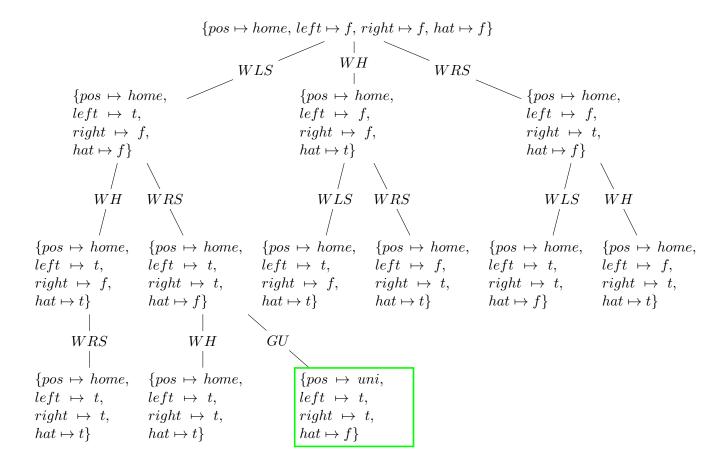
24.01.2020

Exercise 11.1 - Strong stubborn sets

Consider the SAS^+ planning task Π with variables $V = \{pos, left, right, hat\}, \mathcal{D}_{pos} = \{home, uni\}$ and $\mathcal{D}_{left} = \mathcal{D}_{right} = \mathcal{D}_{hat} = \{t, f\}$. The initial state $I = \{pos \mapsto home, left \mapsto f, right \mapsto f, hat \mapsto f\}$ and the goal specification is $\gamma = \{pos \mapsto uni\}$. There are four operators in O, namely

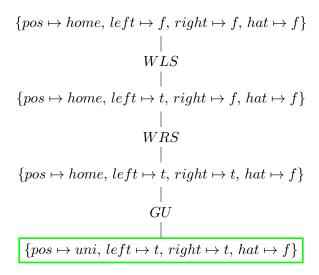
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wear-left-shoe (WLS) = \langle pos = home \land left = f, left := t \rangle
wear-right-shoe (WRS) = \langle pos = home \land right = f, right := t \rangle
wear-hat (WH) = \langle pos = home \land hat = f, hat := t \rangle
go-to-university (GU) = \langle pos = home \land left = t \land right = t, pos := uni \rangle
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(a) Draw the breadth-first search graph (with duplicate detection) for planning task Π without any form of partial-order reduction.



(b) Draw the breadth-first search graph (with duplicate detection) for planning task Π using strong stubborn set pruning. For each expansion of a node for a state s, specify in detail how T_s (and thus $T_{app(s)}$) are computed, i.e., explain how the initial disjunctive action landmark is chosen and how operators are iteratively added to T_s as part of necessary enabling sets or interfering operators, respectively. Break ties in favor of wear-left-shoe over wear-right-shoe.

How many node expansion do you save with strong stubborn sets compared to plain breadthfirst search? What about the lengths of the resulting solutions?



Exercise 11.2 - Weak vs. strong stubborn sets

Show that weak stubborn sets admint exponentially more pruning than strong stubborn sets.