# Eric Zhang

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#### Education

## University of Michigan

Ann Arbor, MI

Bachelor of Science in Engineering in Computer Science

Expected Graduation May 2025

• GPA: 4.0/4.0

• Relevant Coursework: Data Structures & Algorithms, Computer Architecture, Theory of Computer Science, Software Engineering, Discrete Mathematics, Linear Algebra, Multivariable & Vector Calculus

#### Skills

**Languages**: C/C++, Python, MATLAB

Tools and Frameworks: git, Vue, pandas

## Work Experience

### Michigan Medicine

Ann Arbor, MI

Machine Learning Research Assistant

May 2023 - Aug 2023

- Developed a privileged logistic regression pipeline for identifying Acute Respiratory Distress Syndrome in chest x-ray embeddings, achieving an AUC over 84 percent
- Produced a localization map highlighting critical areas within chest x-rays used by Convolutional Neural Nets for identifying Acute Respiratory Distress Syndrome
- Leveraged 15 minute intervals of Apple Watch heart rate data to predict Atrial Fibrillation events 5 minutes in advance, attaining an accuracy over 69 percent
- Utilized Pandas and Excel to manipulate and analyze large amounts of patient data

# All Seasons Ann Arbor (Senior Living)

Ann Arbor, MI

Server

May 2022 - Aug 2022

• Provided personalized food service to elderly individuals, ensuring a comfortable and enjoyable dining experience

# Project Experience

## Michigan Mars Rover Team

Ann Arbor, MI

Teleoperation Team Member

Sep 2022 - Present

- Developed interactive user interface components for the rover's GUI using Vue.js, enabling remote control of the rover and real-time data visualization
- Utilized Django for publishing and subscribing to Robot Operating System (ROS) topics, enabling communication between the rover and the GUI

#### **Course Projects**

# Post Topic Identifier $\mid C++$

April 2023

• Implemented a Naive-Bayes classifier to identify the subject of posts in online question-answer forum Piazza, achieving an accuracy of over 85 percent

# Autonomous Drone Flight Controller | Python

Aug 2022 - Dec 2022

• Collaborated with a team to implement a PID flight controller capable of maintaining the drone's altitude within a 1 meter margin and detecting and avoiding obstacles at a rate above 98 percent

#### Activities