

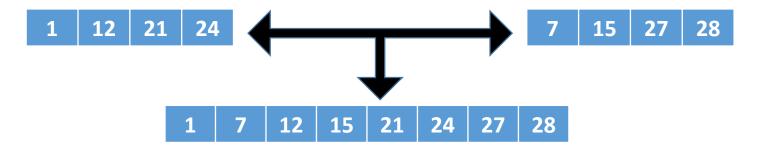
Algorithms and Data Structures (CSci 115)

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Learning outcomes

- Sorting algorithms
 - **≻**Mergesort
 - Merge 2 sorted arrays
 - Split then Merge
 - **≻Quicksort**
 - Order 2 arrays based on a pivot
 - Order then split

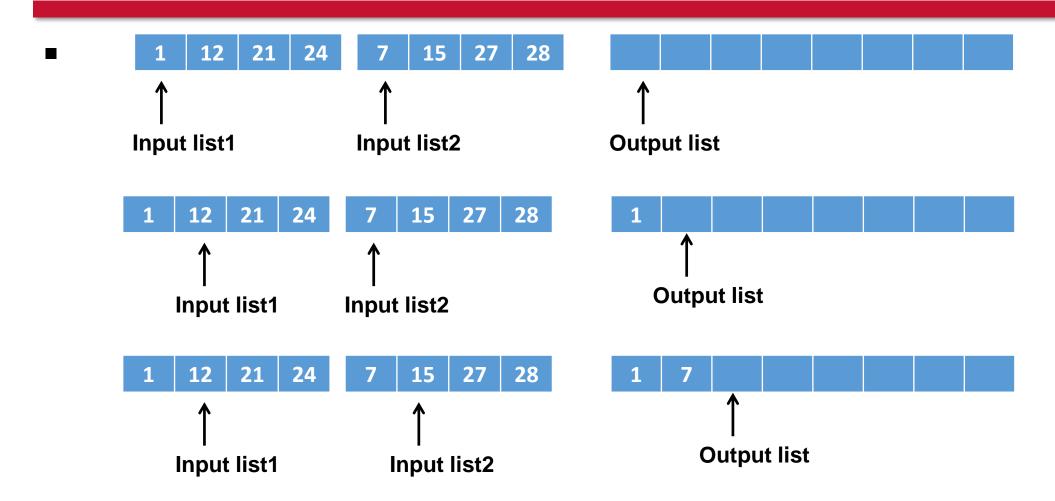
- Merging is a process whereby we combine two (or more) sorted arrays into a single sorted array
 - Start with a number of sorted (INPUT) arrays and create an OUTPUT array that is also sorted
- The Output array contains the values from the various Input arrays

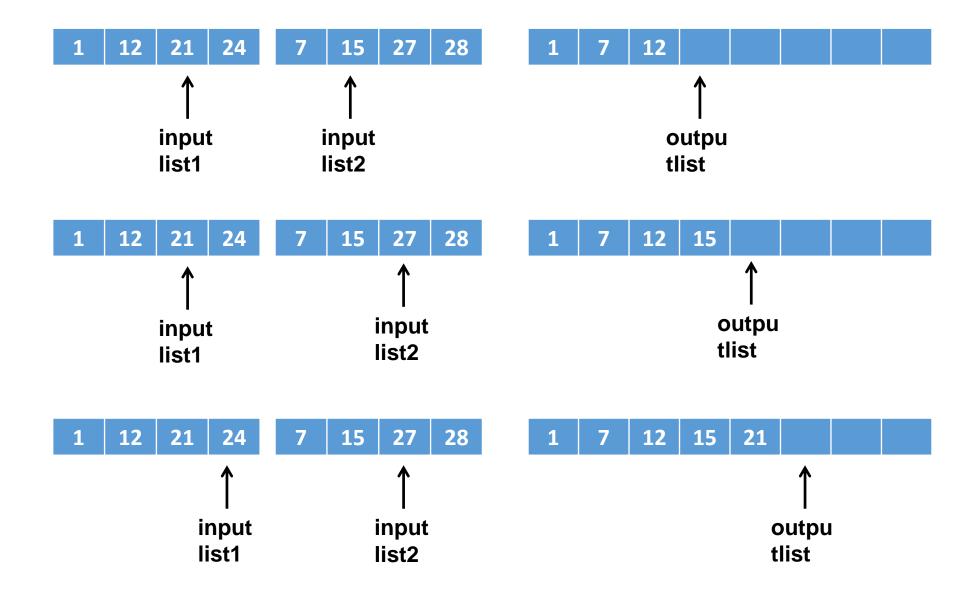


Merging Two Sorted Arrays

- Set markers at the 1st items of the 2 sorted (input) arrays AND the output array (the final SORTED array)
- COMPARE the 2 items at the markers of the input arrays to see which of them should be placed into the output array
- Place the identified item within the output array AND THEN ADVANCE the marker in the array from which the item was taken
- Advance the pointer in the output array
- Repeat the comparison until one of the input arrays is exhausted
- COPY all the remaining items from the array which is not exhausted into the output array to complete the operation

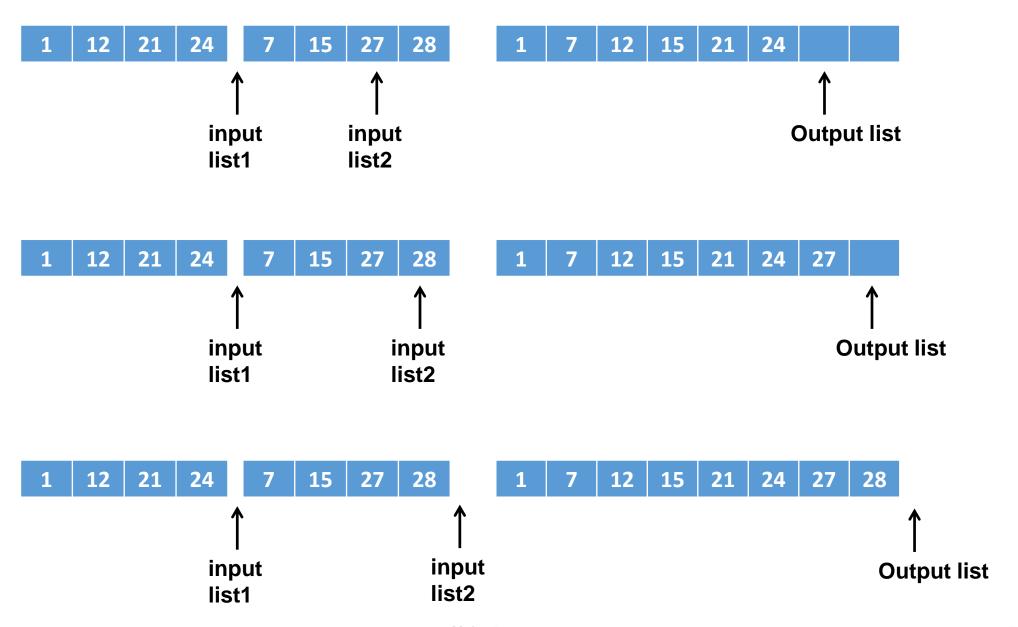
Merging - Example





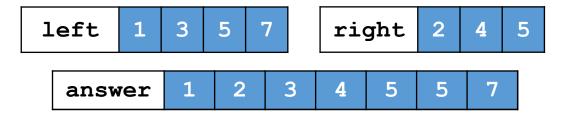
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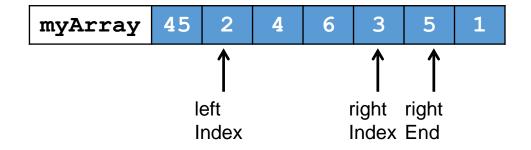
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```
WHILE ( (leftIndex <= leftEnd) AND (rightIndex <= rightEnd))
    IF (left[leftIndex] < right [rightIndex])</pre>
          answer [answerIndex] = left [leftIndex]
         Add 1 to answerIndex
         Add 1 to leftIndex
    ELSE
          answer [answerIndex] = right [rightIndex]
         Add 1 to answerIndex
         Add 1 to rightIndex
WHILE (leftIndex <= leftEnd)
          answer [answerIndex] = left [leftIndex]
         Add 1 to answerIndex
         Add 1 to leftIndex
WHILE (rightIndex <= rightEnd)
          answer [answerIndex] = right [rightIndex]
         Add 1 to answerIndex
         Add 1 to rightIndex
```

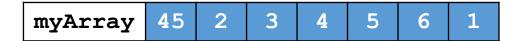
```
int leftIndex = 0;
int leftEnd = left.length - 1;
int rightIndex = 0;
int rightEnd = right.length - 1;
int answerIndex = 0;
```

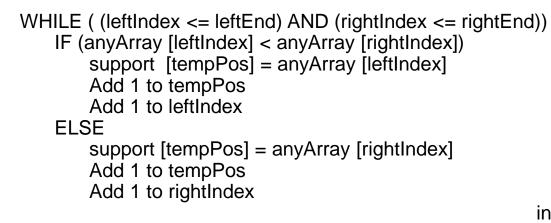




merge (int [] anyArray, int leftIndex, int rightIndex, int rightEnd)

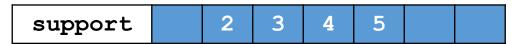
merge (myArray, 1, 4, 5);







int leftEnd = rightIndex - 1;
int [] support = new int
 [anyArray.length]
int tempPos = leftIndex;



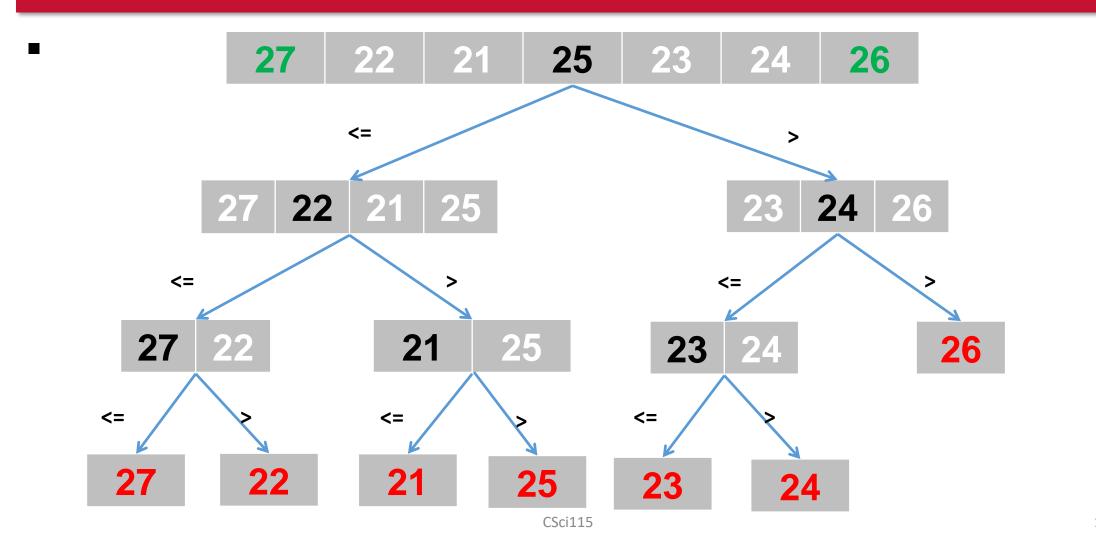
anyArray [rightEnd] = support [rightEnd]



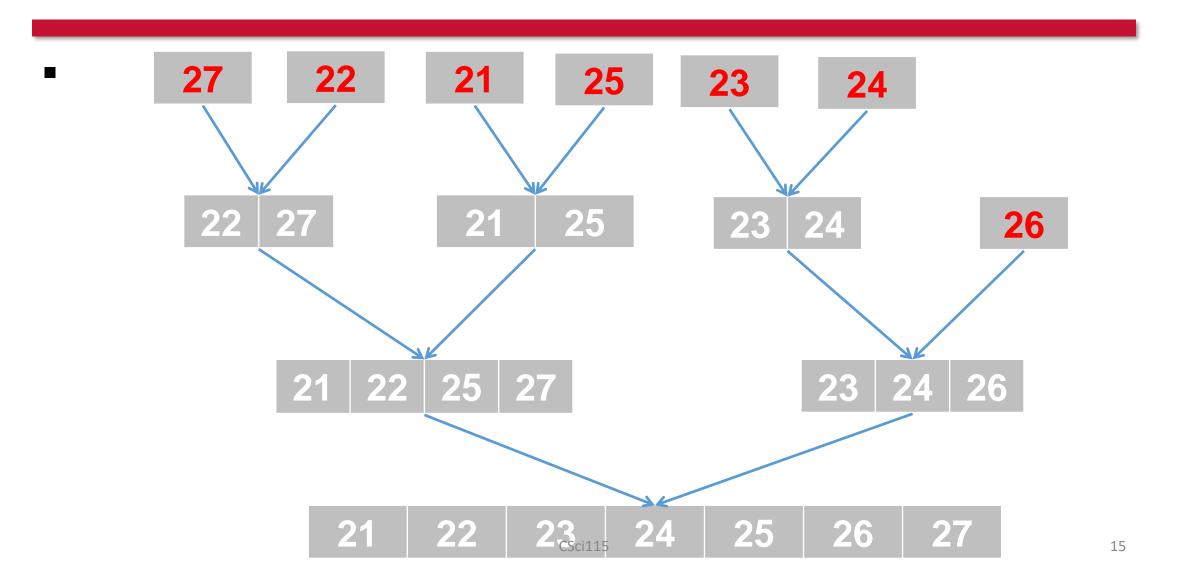
```
int numElements =
  rightEnd - leftIndex + 1;
```

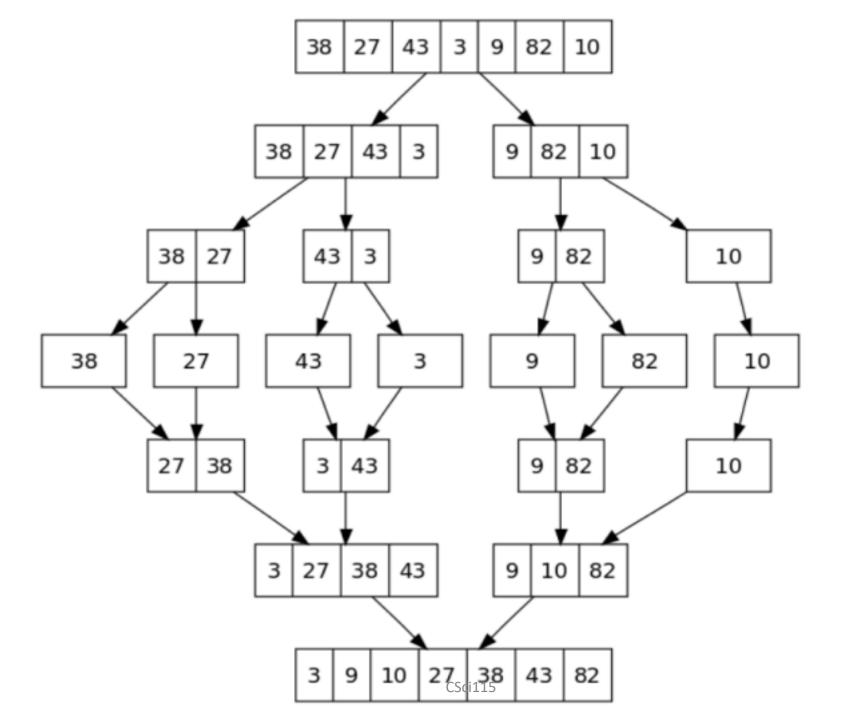
- Assume we are asked to sort an array into ascending order
 - The **MergeSort** of an array is based on the following observations:
- We can split the array into 2 "halves"
- We can sort each half into ascending order
- It is then easy to merge the two sorted halves into a single sorted array
 - We simply keep comparing the bottom element in each half and move the smallest into a new array
- Identical principles apply for the descending order problem

- The MergeSort algorithm involves 3 steps
 - 1. If the number of items to sort in an array is either 0 or 1 the array is (by definition) in order **FINISHED**
 - 2. We **recursively** sort the first and second halves separately
 - 3. Merge the two sorted halves into a sorted group
- The MergeSort algorithm is an O (N log N) algorithm



MergeSort (ordering as we merge)





Pseudo-code

Analysis

 \rightarrow Master theorem (case 2, c=1) \rightarrow O(n log n)

$$T(n) = \begin{cases} 1 & \text{if } n = 1, \\ T(\lceil n/2 \rceil) + T(\lfloor n/2 \rfloor) + n & \text{otherwise.} \end{cases}$$

QuickSort

- Fastest known sorting algorithm
 - > Average running time is: O (N log N)
 - ➤ Based on a "Divide and Conquer" approach
- Steps
 - ➤ We select a "pivot" value:
 - /!\ it is NOT the same as the value in the middle of the array!!
 - ➤ We use this "pivot" value to generate 2 sub-lists
 - List 1: Values less than the pivot
 - List 2: Values greater than or equal to the pivot
 - ➤ We sort the 2 sub-arrays and note that we can have the whole array sorted by arranging the components thus:

sorted sub-list 1, sorted sub-list 2

QuickSort

- Sorting of each of the 'sub-arrays' is once again performed in a recursive manner using the QuickSort technique
- The process continues until each sub-array contains only a single element

Pivot Selection

- ANY VALUE can be selected as the pivot.
- BETTER to make a 'educated' choice

OPTION 1. POPULAR CHOICE

- Use the FIRST element in the list
 - **≻**Simple
 - ➤ Acceptable if the input is random
 - ➤ However, if data is (say) pre-sorted or in reverse order this gives us a poor partitioning
 - > NOT NORMALLY RECOMMENDED

Pivot Selection

OPTION 2. SAFE CHOICE

- Use the MIDDLE element
 - \triangleright i.e. the element at position (low + high) / 2
 - ➤ This is a 'passive' choice
 - o we do not try to choose a 'good' pivot we are merely trying to avoid picking a bad pivot

OPTION 3. MEDIAN-OF-THREE partitioning

- >Attempts to pick a "better than average" pivot
- ➤ Pick the MEDIAN of the *first, middle* and *last* elements
- > Example:

With input: **8**, 11, 14, 19, **16**, 13, 15, 12, 17, 1**0**

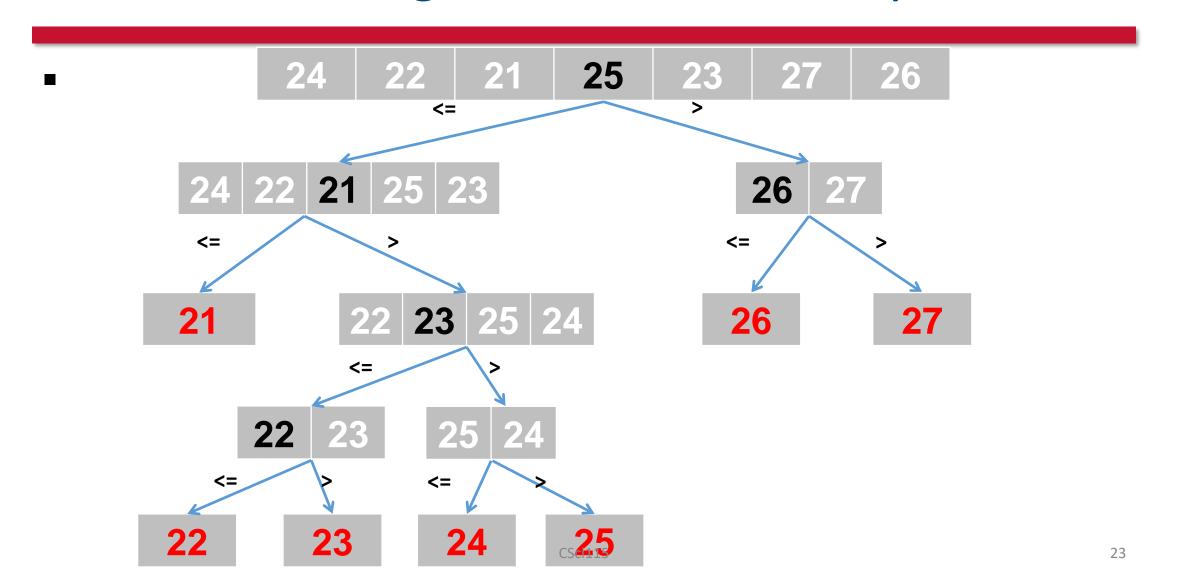
These three elements are: 8, 10 and 16

The value **10** is chosen as the pivot

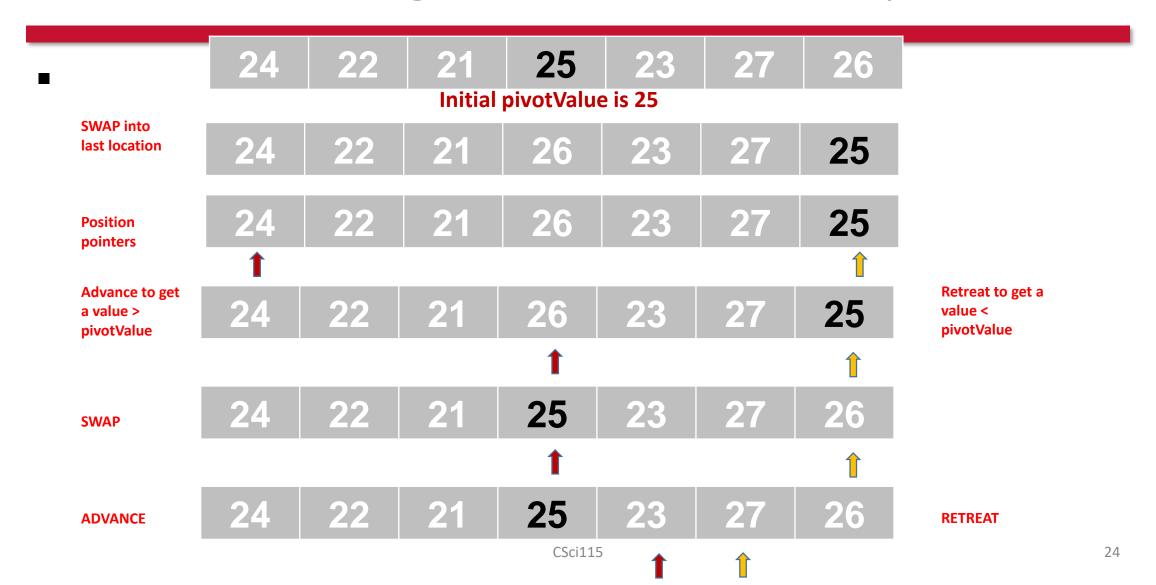
Partition function

- Rearrange the array A[p..r] into 2 (possibly empty) subarrays.
 - > From index p to index r
- 2 arrays as outputs: A[p..q-1] and A[q+1.. r] such that each element of A[p..q-1] is less than or equal to A[q] (the pivot), which is, in turn, less than or equal to each element of A[q+1..r].
- The index q is evaluated as part of this partitioning procedure.
- Partition function
 - ➤Input: Array A, int p, int r
 - ➤ Output: Array A, position of q,

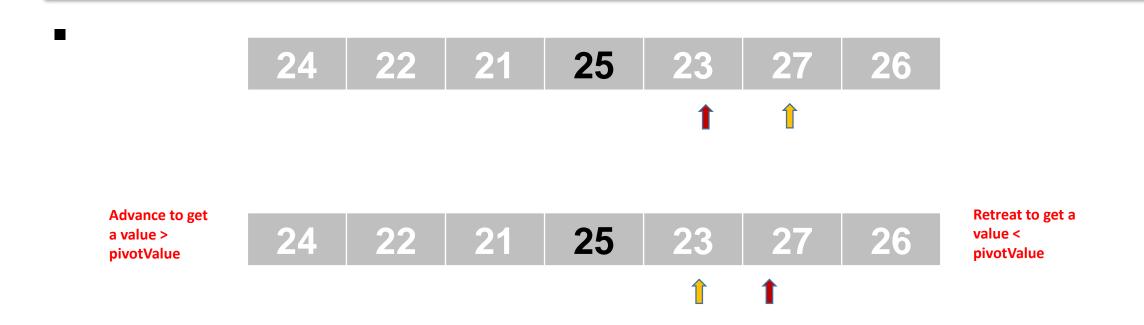
QuickSort: Using middle element as pivot



QuickSort: Using middle element as pivot



QuickSort: Using middle element as pivot



ARROWS HAVE CROSSED SO FINISHED THIS PHASE

Quicksort

where

- > A: the array
- > p: index of the first element
- r: index of the last element,
- > q: index of the pivot returned by the partition function. (index, not the value !!!)

QuickSort: Performance

- Average performance of QuickSort for both swaps and comparisons
 - **≻**Complexity: O(N log N)
- Major problem with QuickSort:
 - >Under certain conditions the partition phase fails to divide the list at all
- Therefore
 - \triangleright the QuickSort algorithm is far from quick in the <u>worst case</u> performance, degenerating to an $O(N^2)$ algorithm

Summary of Sorting

- Selection, Insertion and Bubble Sorts are O (N²) algorithms
 - ➤ Not so good
- MergeSort and QuickSort are O (N log N) for random lists
 - Quite Good
- This does not mean that MergeSort or QuickSort are always best for all your sorting problems
 - if we introduce immediate checking to see whether the list provided is already ordered the Insertion sort is one of the best algorithms
 - For data that is actually initially sorted, the QuickSort algorithm is one of the worst algorithms

Finally...

- If the elements of the array contain large data records, movement of this data is very expensive
- If this is the case, the Selection Sort (which involves few movements) is probably the <u>best</u> since is it linear **O(N)** for assignments.
 - ➤ Question: What is your view on this for the Bubble Sort?
 - Memory efficient (just swap values)
- If the data is stored as a linked list (see later) rather than an array, the MergeSort is one of the most efficient algorithms for sorting linked lists

Questions?

- Midterm question
 - ➤ Determine the initial conditions of an array so ...
 - It corresponds to the worst case of a given algorithm
 - It corresponds to the best case of an algorithm
- Reading
 - >See code in the CSci115 book

