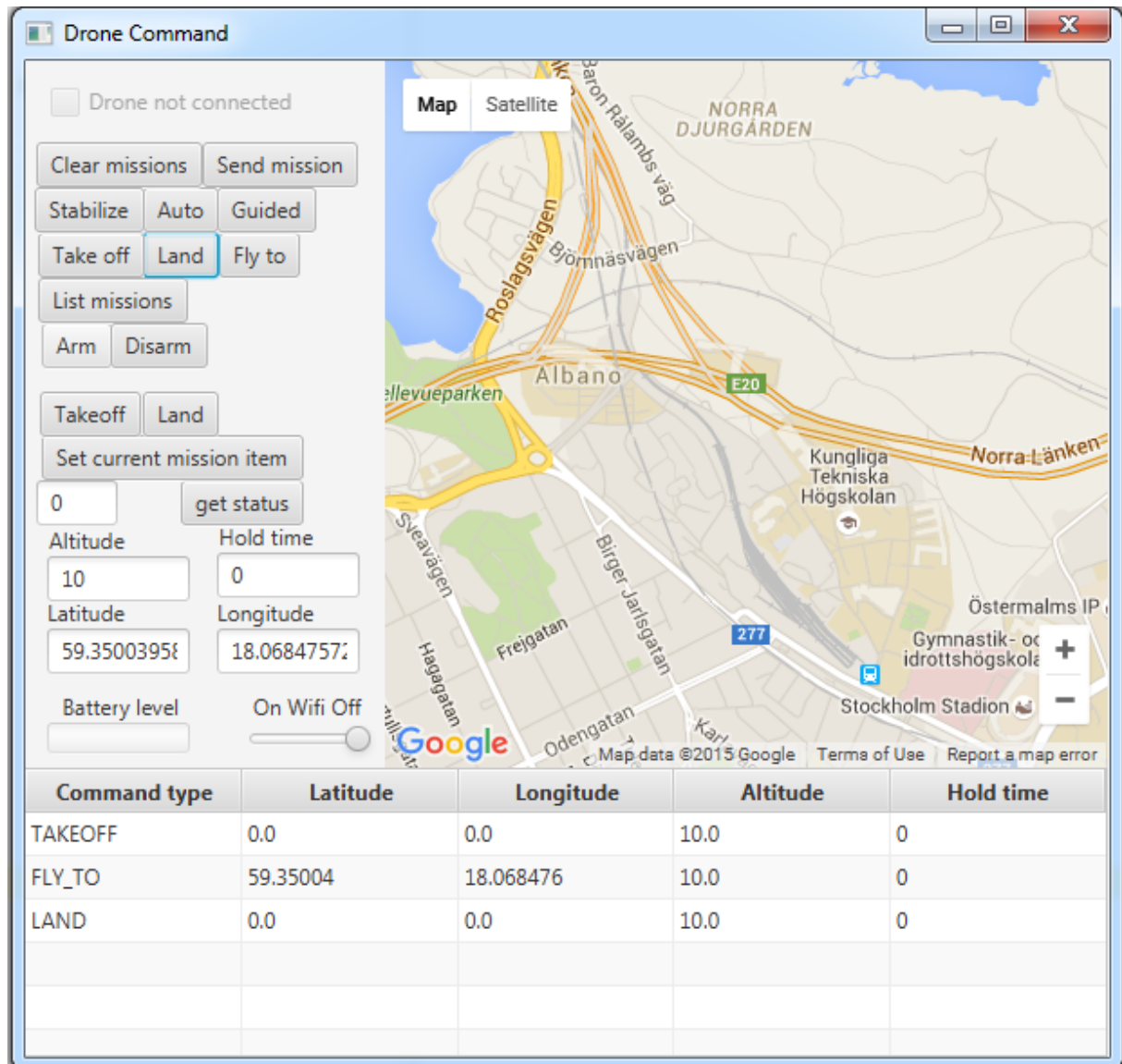


# Quickstart guide

## ‘Cloud’

When the ‘cloud’ is started it looks like in the image below, but with an empty list of mission items.



If there is a previous list of mission items in the drone or the content is not known, one should start with clearing the list by pressing “Clear missions”.

When the map is right clicked, the coordinates of the point clicked on is filled in to the text fields for latitude and longitude. A ‘0’ in either latitude or longitude means it will be unchanged during that command.

When clicking “Take off”, “Fly to” or “Land” in the top group of buttons the text fields’ values are used to create a mission item that appears in the list at the bottom. It can then be sent with the “Send mission” button. The hold time is only valid for “FLYTO” commands and is the time the drone will hold at that position.

After creating and sending a mission consisting of some mission items, one can start it by clicking "Takeoff" in the lower group of buttons. It requires the mission to have at least one "TAKEOFF" in it. During a mission, if one presses "Land" the drone may jump to the next mission item that is a "LAND"-command, it is untested though.

The "Arm" and "Disarm" buttons can be used for what the buttons say.

To change mode of the drone the "Stabilize", "Auto" or "Guided" buttons can be used. "Guided" mode is the one not requiring manual start from the remote.

The wifi slider can be used to turn the wifi on and off.

If "get status" is clicked the drone will with 1 Hz frequency send some information about battery and similar that is printed in the standard out.