Función Price

$$f(x) = (2x_0^3x_1 - x_1^3)^2 + (6x_0 - x_1^2 + x_1)^2$$

n=2

$$x = \begin{bmatrix} x_0 \\ x_1 \end{bmatrix}$$

$$\mathbf{z} = \begin{bmatrix} 2x_0^3 x_1 - x_1^3 \\ 6x_0 - x_1^2 + x_1 \end{bmatrix}$$

$f(\mathbf{x}) = \mathbf{z}'\mathbf{z}$

$$J_{x}\mathbf{z} = \begin{bmatrix} \frac{\partial z_{0}}{\partial x_{0}} & \frac{\partial z_{0}}{\partial x_{1}} \\ \frac{\partial z_{1}}{\partial x_{0}} & \frac{\partial z_{1}}{\partial x_{1}} \end{bmatrix} = \begin{bmatrix} 6x_{0}^{2}x_{1} & 2x_{0}^{3} - 3x_{1}^{2} \\ 6 & -2x_{1} + 1 \end{bmatrix}$$

$$\nabla f(\mathbf{x}) = 2 \left(\mathbf{J}_{\mathbf{x}}' \mathbf{z} \right) \mathbf{z}$$

Función de Rosenbrock

$$f(x) = \sum_{i=0}^{n/2-1} 100(x_{2i+1} - x_{2i}^2)^2 + (1 - x_{2i})^2$$

n=2

$$\boldsymbol{x} = \begin{bmatrix} x_0 \\ x_1 \end{bmatrix}$$

$$f(x) = 100(x_1 - x_0^2)^2 + (1 - x_0)^2$$

$$f(x) = [10(x_1 - x_0^2)]^2 + [1 - x_0]^2$$

$$\mathbf{z} = \begin{bmatrix} 10(x_1 - x_0^2) \\ 1 - x_0 \end{bmatrix}$$

$$f(\mathbf{x}) = \mathbf{z}'\mathbf{z}$$

$$J_{x}\mathbf{z} = \begin{bmatrix} \frac{\partial z_{0}}{\partial x_{0}} & \frac{\partial z_{0}}{\partial x_{1}} \\ \frac{\partial z_{1}}{\partial x_{0}} & \frac{\partial z_{1}}{\partial x_{1}} \end{bmatrix} = \begin{bmatrix} -20x_{0} & 10 \\ -1 & 0 \end{bmatrix}$$

$$\nabla f(\mathbf{x}) = 2 \left(\mathbf{J}_{\mathbf{x}}' \mathbf{z} \right) \mathbf{z}$$

n = 4

$$\boldsymbol{x} = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$f(x) = 100(x_1 - x_0^2)^2 + (1 - x_0)^2 + 100(x_3 - x_2^2)^2 + (1 - x_2)^2$$

$$f(x) = [10(x_1 - x_0^2)]^2 + [1 - x_0]^2 + [10(x_3 - x_2^2)]^2 + [1 - x_2]^2$$

$$\mathbf{z} = \begin{bmatrix} 10(x_1 - x_0^2) \\ 1 - x_0 \\ 10(x_3 - x_2^2) \\ 1 - x_2 \end{bmatrix}$$

$$f(\mathbf{x}) = \mathbf{z}'\mathbf{z}$$

$$J_{x}\mathbf{z} = \begin{bmatrix} \frac{\partial z_{0}}{\partial x_{0}} & \frac{\partial z_{0}}{\partial x_{1}} & \frac{\partial z_{0}}{\partial x_{2}} & \frac{\partial z_{0}}{\partial x_{3}} \\ \frac{\partial z_{1}}{\partial x_{0}} & \frac{\partial z_{1}}{\partial x_{1}} & \frac{\partial z_{1}}{\partial x_{2}} & \frac{\partial z_{1}}{\partial x_{3}} \\ \frac{\partial z_{2}}{\partial x_{0}} & \frac{\partial z_{2}}{\partial x_{1}} & \frac{\partial z_{2}}{\partial x_{2}} & \frac{\partial z_{2}}{\partial x_{3}} \\ \frac{\partial z_{3}}{\partial x_{0}} & \frac{\partial z_{3}}{\partial x_{1}} & \frac{\partial z_{3}}{\partial x_{2}} & \frac{\partial z_{3}}{\partial x_{3}} \end{bmatrix} = \begin{bmatrix} -20x_{0} & 10 & 0 & 0 \\ -1 & 0 & 0 & 0 \\ 0 & 0 & -20x_{2} & 0 \\ 0 & 0 & -1 & 0 \end{bmatrix}$$

$$\nabla f(\mathbf{x}) = 2 \left(\mathbf{J}_{\mathbf{x}}' \mathbf{z} \right) \mathbf{z}$$

$$n = 6$$

$$\mathbf{x} = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix}$$

$$f(x) = 100(x_1 - x_0^2)^2 + (1 - x_0)^2 + 100(x_3 - x_2^2)^2 + (1 - x_2)^2 + 100(x_5 - x_4^2)^2 + (1 - x_4)^2$$

$$f(x) = [10(x_1 - x_0^2)]^2 + [1 - x_0]^2 + [10(x_3 - x_2^2)]^2 + [1 - x_2]^2 + [10(x_5 - x_4^2)]^2 + [1 - x_4]^2$$

$$\mathbf{z} = \begin{bmatrix} 10(x_1 - x_0^2) \\ 1 - x_0 \\ 10(x_3 - x_2^2) \\ 1 - x_2 \\ 10(x_5 - x_4^2) \\ 1 - x_4 \end{bmatrix}$$

$$f(\mathbf{x}) = \mathbf{z}'\mathbf{z}$$

$$J_{x}\mathbf{z} = \begin{bmatrix} \frac{\partial z_{0}}{\partial x_{0}} & \frac{\partial z_{0}}{\partial x_{1}} & \frac{\partial z_{0}}{\partial x_{2}} & \frac{\partial z_{0}}{\partial x_{3}} & \frac{\partial z_{0}}{\partial x_{4}} & \frac{\partial z_{0}}{\partial x_{5}} \\ \frac{\partial z_{1}}{\partial x_{0}} & \frac{\partial z_{1}}{\partial x_{1}} & \frac{\partial z_{1}}{\partial x_{2}} & \frac{\partial z_{1}}{\partial x_{3}} & \frac{\partial z_{1}}{\partial x_{4}} & \frac{\partial z_{1}}{\partial x_{5}} \\ \frac{\partial z_{2}}{\partial x_{0}} & \frac{\partial z_{2}}{\partial x_{1}} & \frac{\partial z_{2}}{\partial x_{2}} & \frac{\partial z_{2}}{\partial x_{3}} & \frac{\partial z_{2}}{\partial x_{4}} & \frac{\partial z_{2}}{\partial x_{5}} \\ \frac{\partial z_{3}}{\partial x_{0}} & \frac{\partial z_{3}}{\partial x_{1}} & \frac{\partial z_{3}}{\partial x_{2}} & \frac{\partial z_{3}}{\partial x_{3}} & \frac{\partial z_{3}}{\partial x_{4}} & \frac{\partial z_{3}}{\partial x_{5}} \\ \frac{\partial z_{4}}{\partial x_{0}} & \frac{\partial z_{4}}{\partial x_{1}} & \frac{\partial z_{4}}{\partial x_{2}} & \frac{\partial z_{4}}{\partial x_{3}} & \frac{\partial z_{4}}{\partial x_{4}} & \frac{\partial z_{4}}{\partial x_{5}} \\ \frac{\partial z_{5}}{\partial x_{0}} & \frac{\partial z_{5}}{\partial x_{1}} & \frac{\partial z_{5}}{\partial x_{2}} & \frac{\partial z_{5}}{\partial x_{3}} & \frac{\partial z_{5}}{\partial x_{4}} & \frac{\partial z_{5}}{\partial x_{5}} \\ \frac{\partial z_{5}}{\partial x_{0}} & \frac{\partial z_{5}}{\partial x_{1}} & \frac{\partial z_{5}}{\partial x_{2}} & \frac{\partial z_{5}}{\partial x_{3}} & \frac{\partial z_{5}}{\partial x_{4}} & \frac{\partial z_{5}}{\partial x_{5}} \\ \frac{\partial z_{5}}{\partial x_{0}} & \frac{\partial z_{5}}{\partial x_{1}} & \frac{\partial z_{5}}{\partial x_{2}} & \frac{\partial z_{5}}{\partial x_{3}} & \frac{\partial z_{5}}{\partial x_{4}} & \frac{\partial z_{5}}{\partial x_{5}} \\ \frac{\partial z_{5}}{\partial x_{0}} & \frac{\partial z_{5}}{\partial x_{1}} & \frac{\partial z_{5}}{\partial x_{2}} & \frac{\partial z_{5}}{\partial x_{3}} & \frac{\partial z_{5}}{\partial x_{4}} & \frac{\partial z_{5}}{\partial x_{5}} \\ \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{1}} & \frac{\partial z_{5}}{\partial x_{2}} & \frac{\partial z_{5}}{\partial x_{3}} & \frac{\partial z_{5}}{\partial x_{4}} & \frac{\partial z_{5}}{\partial x_{5}} \\ \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{1}} & \frac{\partial z_{5}}{\partial x_{2}} & \frac{\partial z_{5}}{\partial x_{3}} & \frac{\partial z_{5}}{\partial x_{4}} & \frac{\partial z_{5}}{\partial x_{5}} \\ \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{1}} & \frac{\partial z_{5}}{\partial x_{2}} & \frac{\partial z_{5}}{\partial x_{3}} & \frac{\partial z_{5}}{\partial x_{4}} & \frac{\partial z_{5}}{\partial x_{5}} \\ \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{5}} \\ \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{5}} \\ \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{5}} \\ \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_{5}}{\partial x_{5}} & \frac{\partial z_$$

$$\nabla f(\mathbf{x}) = 2 \left(\mathbf{J}_{\mathbf{x}}' \mathbf{z} \right) \mathbf{z}$$

Analizando los índices del vector \boldsymbol{x} y \boldsymbol{z} . El vector \boldsymbol{z} tiene elementos con la expresión $[10(x_{2i+1}-x_{2i}^2)]$ para índices pares (l_2) y elementos con la expresión $[1-x_{2i}]$ para índices impares (l_1) , entonces, los índices impares los definimos como $l_1=1,3,5,...$ y los índices pares como $l_2=0,2,4,...$; los elementos de \boldsymbol{x} los agrupamos en elementos con índices impares y pares similar a los elementos de \boldsymbol{z} . Entonces el vector \boldsymbol{z} se define como:

$$z_{l_2} \equiv 10(x_{l_1} - x_{l_2}^2)$$

$$z_{l_1} \equiv 1 - x_{l_2}$$

Entonces la función de rosenbrock para n par en forma vectorizada es:

$$f(\mathbf{x}) = \mathbf{z}'\mathbf{z}$$

Analizando los elementos de la matriz jacobiana $J_x z$ para n=2,4 y 6 ; se observa que existen tres elementos distintos en las posiciones de la matriz jacobiana, es decir.

Renglón par y columna par : $-20x_{2i}$ Renglon par y columna impar: +10Renglon impar y columna par: -1

Entonces la matriz Jacobiana $J_x \mathbf{z}$ para n par en forma vectorizada es:

 $J_{x}z=\mathbf{0}_{n\times n}$

$$[J_x \mathbf{z}]_{2i,2i} = -20x_{2i}$$

$$[J_x \mathbf{z}]_{2i,2i+1} = +10$$

$$[J_x \mathbf{z}]_{2i+1,2i} = -1$$

$$para i = 0,2,...,n/2$$

Entonces el vector gradiente $\nabla f(x)$ para n par en forma vectorizada es:

$$\nabla f(\mathbf{x}) = 2 \left(\mathbf{J}_{\mathbf{x}}' \mathbf{z} \right) \mathbf{z}$$

```
# optimizer_adam_rosenbrock.py
# Adam optimization
Dr. Juan R. Castro
FCQI, UABC Campus Tijuana
# Importing Libraries
import numpy as np
```

```
# objective Extended Rosenbrock function

def objfcn(x):
    # Minima -> f=0 at (1,....,1)
    n = len(x) # n par
    z = np.zeros((n,1))
    l2 = np.array(range(0,n,2)) # indice par
    l1 = np.array(range(1,n,2)) # indice impar
    z[l2]=10.0*(x[l1]-(x[l2])**2.0)
    z[l1]=1.0-x[l2]
    f = z.T @ z
    return f[0,0]
```

```
# Extended Rosenbrock gradient function
def objfcngrad(x):
    n = len(x) # n even
    Jz = np.zeros((n,n))
    z = np.zeros((n,1))
    l2 = np.array(range(0,n,2)) # indice par
    l1 = np.array(range(1,n,2)) # indice impar
    z[l2]=10.0*(x[l1]-(x[l2])**2.0)
    z[l1]=1.0-x[l2]

for i in range(n//2):
        Jz[2*i,2*i] = -20.0*x[2*i]
        Jz[2*i,2*i+1] = 10.0
        Jz[2*i+1,2*i] = -1.0

gX = 2.0*Jz.T @ z
    return gX
```

```
def objfcnjac(x):
    # Extended Rosenbrock Jacobian Function
    n = len(x) # n even
    Jz = np.zeros((n,n))
    z = np.zeros((n,1))
    l2 = np.array(range(0,n,2)) # indice par
    l1 = np.array(range(1,n,2)) # indice impar
    z[l2]=10.0*(x[l1]-(x[l2])**2.0)
    z[l1]=1.0-x[l2]

for i in range(n//2):
        Jz[2*i,2*i] = -20.0*x[2*i]
        Jz[2*i,2*i+1] = 10.0
        Jz[2*i+1,2*i] = -1.0

gX = 2.0*Jz.T @ z
    normgX = np.linalg.norm(gX)
    return z, Jz, normgX
```