Laboratory work: «Numerecial methods, lab4 »

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2022

Contents

Purposes

 $1. \ \, {\rm Solve\ the\ boubdary\ value\ problem\ for\ a\ second-order\ differential\ equation} \\ on\ one-dimension\ segment\ using\ TDMA\ algorith$

Problem statement

Mathematical model

$$\begin{cases} \frac{\partial u}{\partial t} = a \frac{\partial^2 u}{\partial x^2} + \sin(\pi x) \\ u(0, t) = 0 \\ u(1, t) = 0 \\ u(x, 0) = 0 \end{cases}$$
 (1)

 $x \in [0, 1]$ $h = \frac{\pi}{400}$ N=100

Exact solution:

$$U(x,t) = \frac{1}{\pi^2} (1 - \exp(-\pi^2 t)) \sin(\pi x)$$
 (2)

Implict

$$\begin{cases} \frac{u_i^{k+1} - u_i^k}{\tau} = a \frac{u_{i+1}^{k+1} - 2u_i^{k+1} + u_{i-1}^{k+1}}{h^2} + \sin(\pi x_i) \\ u_i^0 = 0 \\ u_0^{k+1} = 0 \\ u_N^{k+1} = 0 \end{cases}$$
(3)

$$\begin{cases}
 a_i = \left(1 + \frac{2a\tau}{h^2}\right) \\
 b_i = \frac{a\tau}{h^2} \\
 c_i = \frac{a\tau}{h^2} \\
 f_i = \sin(\pi x_i)
\end{cases} \tag{4}$$

Explicit

$$\begin{cases} \frac{u_i^{k+1} - u_i^k}{\tau} = a \frac{u_{i+1}^k - 2u_i^k + u_{i-1}^k}{h^2} + \sin(\pi x_i) \\ u_i^0 = 0 \\ u_0^{k+1} = 0 \\ u_N^{k+1} = 0 \end{cases}$$

$$(5)$$

Krank-Nikolson

$$\begin{cases}
\frac{u_i^{k+1} - u_i^k}{\tau} = a^{\frac{u_{i+1}^{k+1} - 2u_i^{k+1} + u_{i-1}^{k+1}}{2h^2}} + a^{\frac{u_{i+1}^k - 2u_i^k + u_{i-1}^k}{2h^2}} + \sin(\pi x_i) \\
u_i^0 = 0 \\
u_i^{k+1} = 0 \\
u_N^{k+1} = 0
\end{cases}$$
(6)

а

$$\begin{cases}
 a_{i} = \left(\frac{1}{\tau} + \frac{2a}{h^{2}}\right) \\
 b_{i} = \frac{a}{2h^{2}} \\
 c_{i} = \frac{a}{2h^{2}} \\
 f_{i} = u_{i}^{k} \left(\frac{1}{\tau} - \frac{a}{h^{2}}\right) + \frac{a}{2h^{2}} \left(u_{i+1}^{k} + u_{i-1}^{k}\right) sin(\pi x_{i})
\end{cases} \tag{7}$$

$$\begin{cases}
 a_0 = 1 \\
 b_0 = 0 \\
 c_0 = 0 \\
 f_0 = 0
\end{cases}$$
(8)

$$\begin{cases}
 a_N = 1 \\
 b_N = 0 \\
 c_N = 0 \\
 f_N = 0
\end{cases}$$
(9)

$$u_i = 0$$

TDMA

$$\begin{aligned} a_i y_i &= b_i y_{i+1} + c_i y_{i-1} + f_i \\ P_0 &= \frac{b_0}{a_0} \\ Q_0 &= \frac{f_0}{a_0} \\ P_i &= \frac{b_i}{a_i - c_i P_{i-1}} \\ Q_i &= \frac{f_i + c_i Q_{i-1}}{a_i - c_i P_{i-1}} \\ y_N &= Q_N \\ y_i &= P_i y_{i+1} + Q_i \end{aligned}$$

Program code

link to code in github: github.

Results

The graphs almost coincide, the error is small, therefore the methods can be considered accurate

Figure 1: result of program

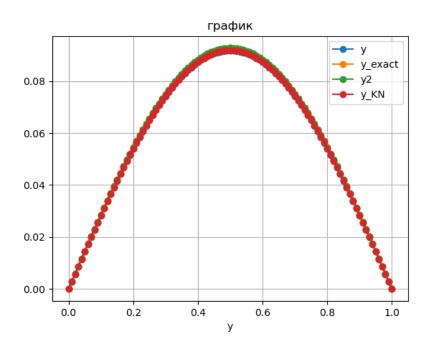


Figure 2: result of program