

RDS WORKSHOP DAY 2

10.12.2024



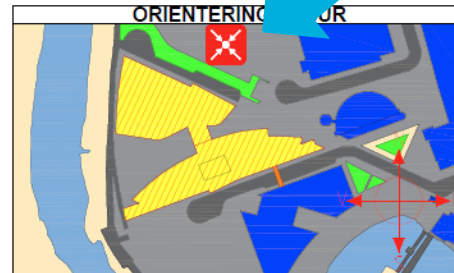
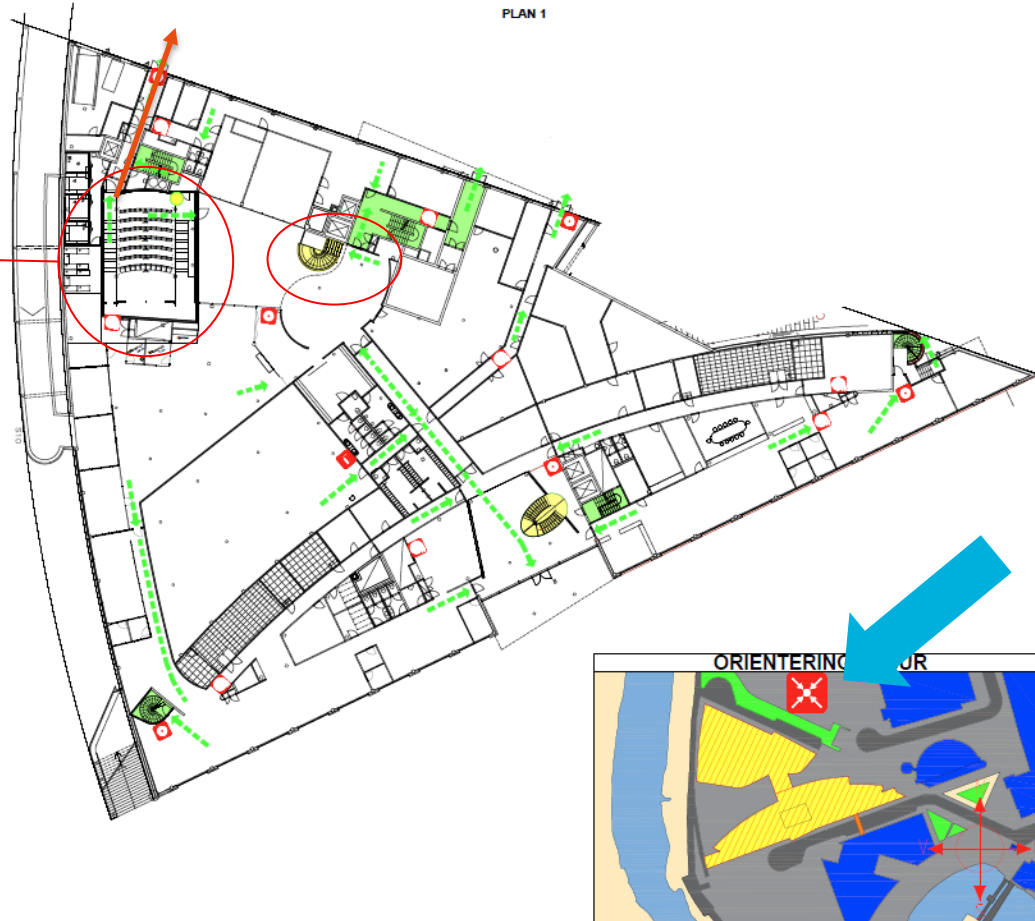


- ▶ Fire exits
- ▶ Meeting points

RØMNINGSPLAN / EVACUATIONPLAN

Mustad Eiendom
Lilleakerveien 6
PLAN 1

You are here



Her står du
You are here

Brannslange
Fire hose

Møteplass
Meeting point

Slokkeapparat
Fire extinguisher

Brannmelder
Fire alarm

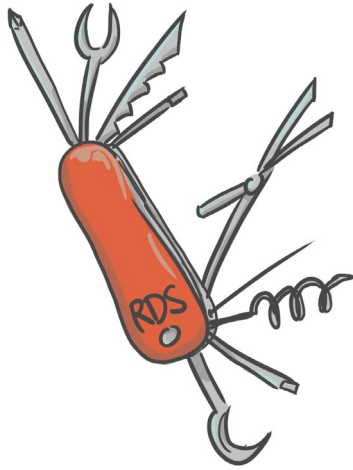
Rømningsvei
Emergency exit

Trapp
Stairway

Interntrapp
Internal stairway

Agenda

- ▶ 101
- ▶ Cases
- ▶ Lunch
- ▶ More cases



81346-101

Repetition



Figure 5-1— Illustration of the receiver ownership principle

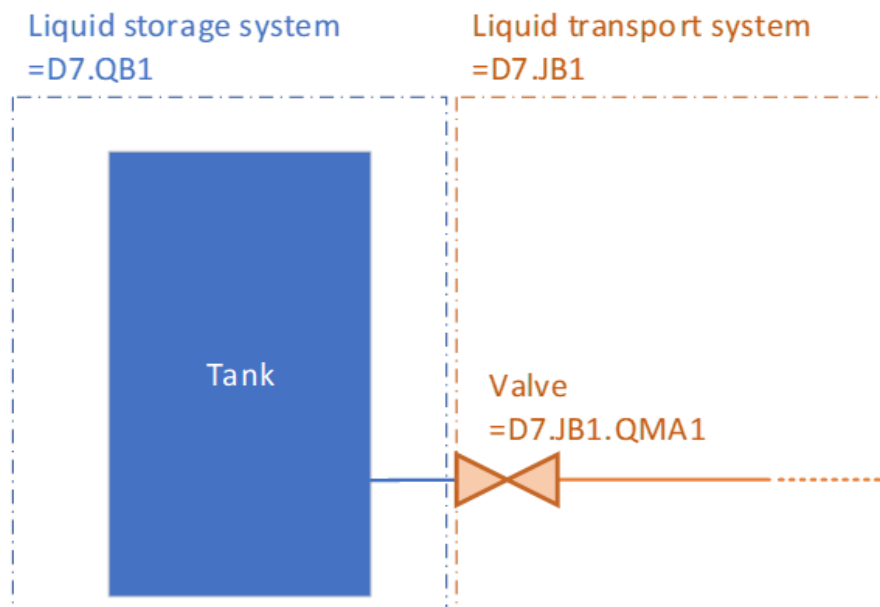
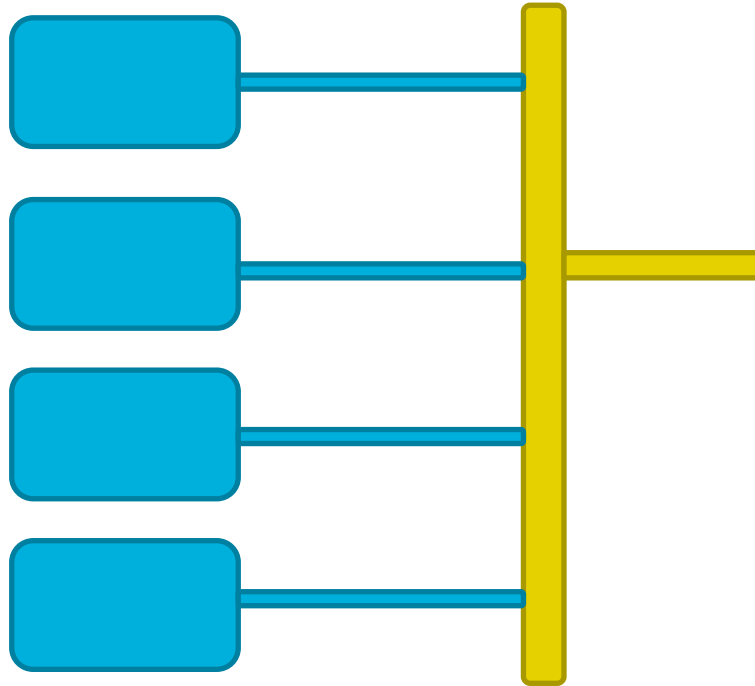
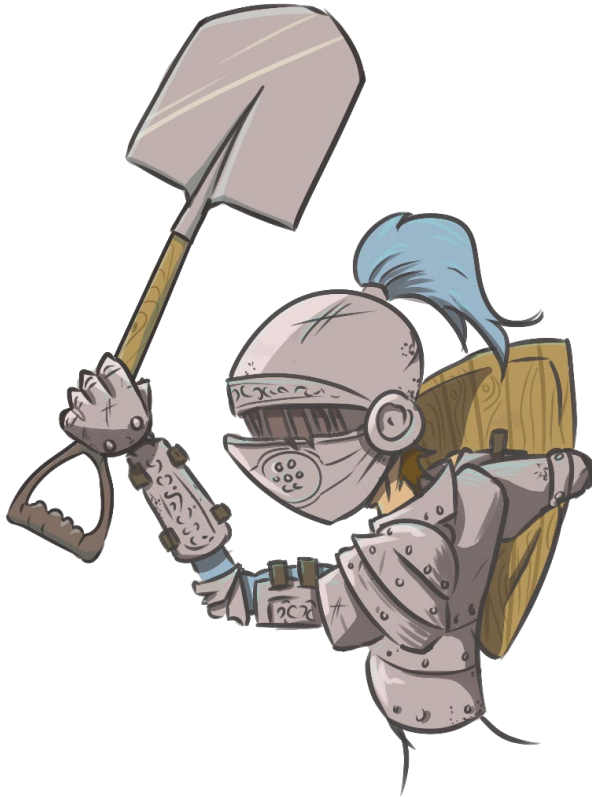


Figure 5-2— Example of the receiver ownership principle

The exception:
The collecting system principle

- Busbars
- Waterways





QPS

A tool used for digging

FHG

A tool used for saving princesses

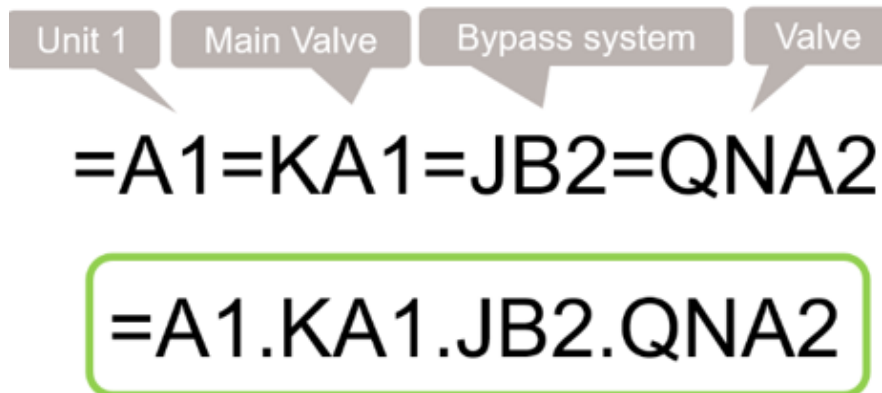
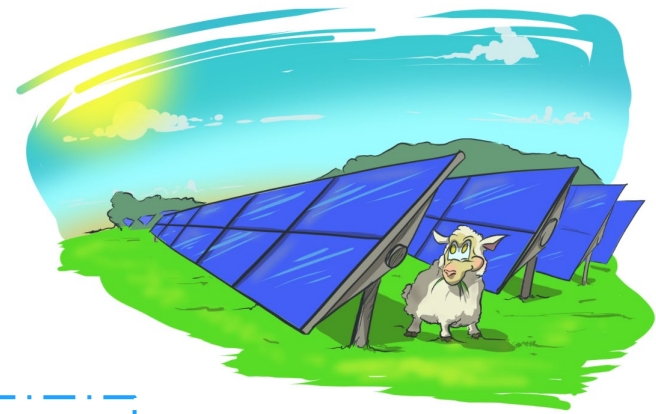


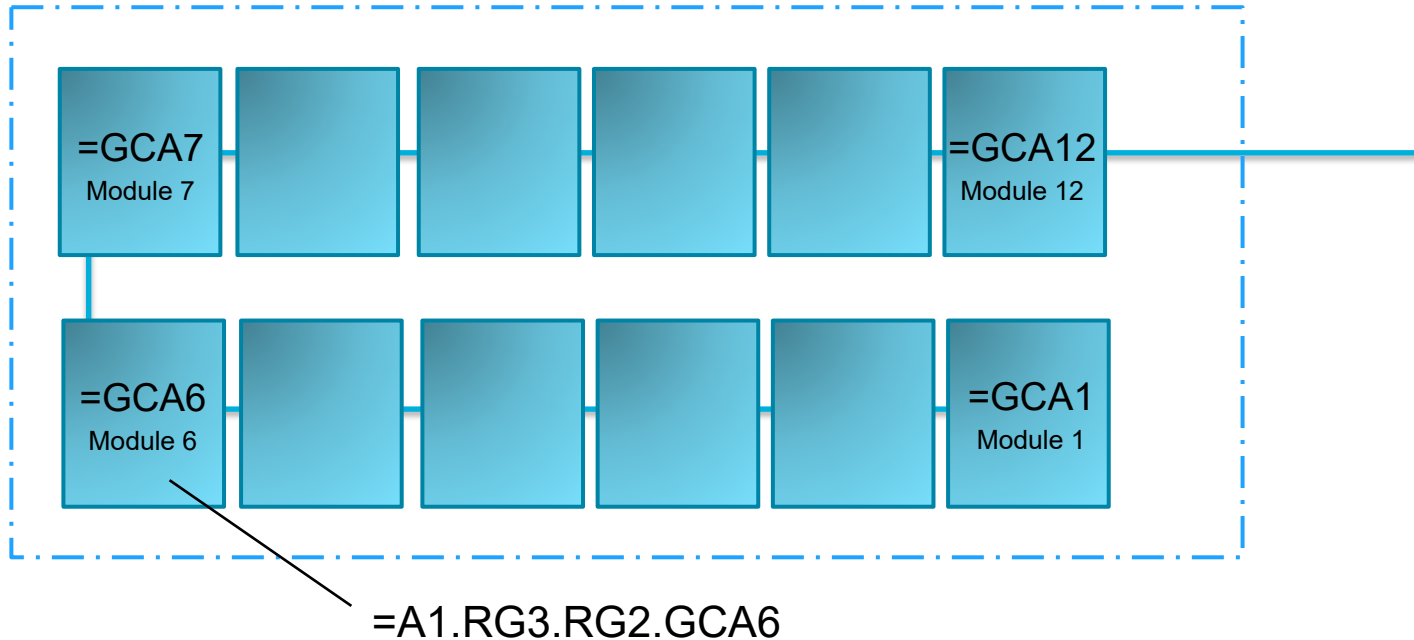
Figure 5-5 - Preferred syntax

|Association|



=A1.RG3.RG2

PV block 1, Generator 3 ("inverter system"), String 2





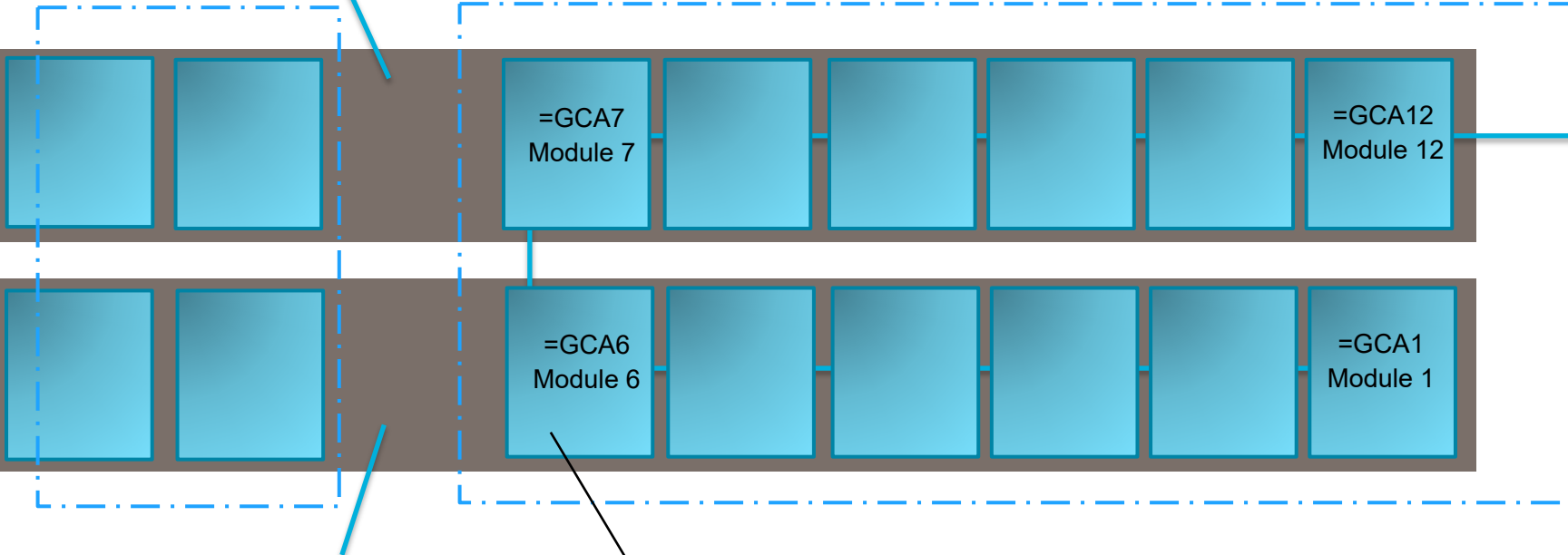
“Tracker”

-A1.AA2

Tracker 1

=A1.RG3.RG2

PV block 1, Generator 3, String 2



-A1.AA2

Tracker 2

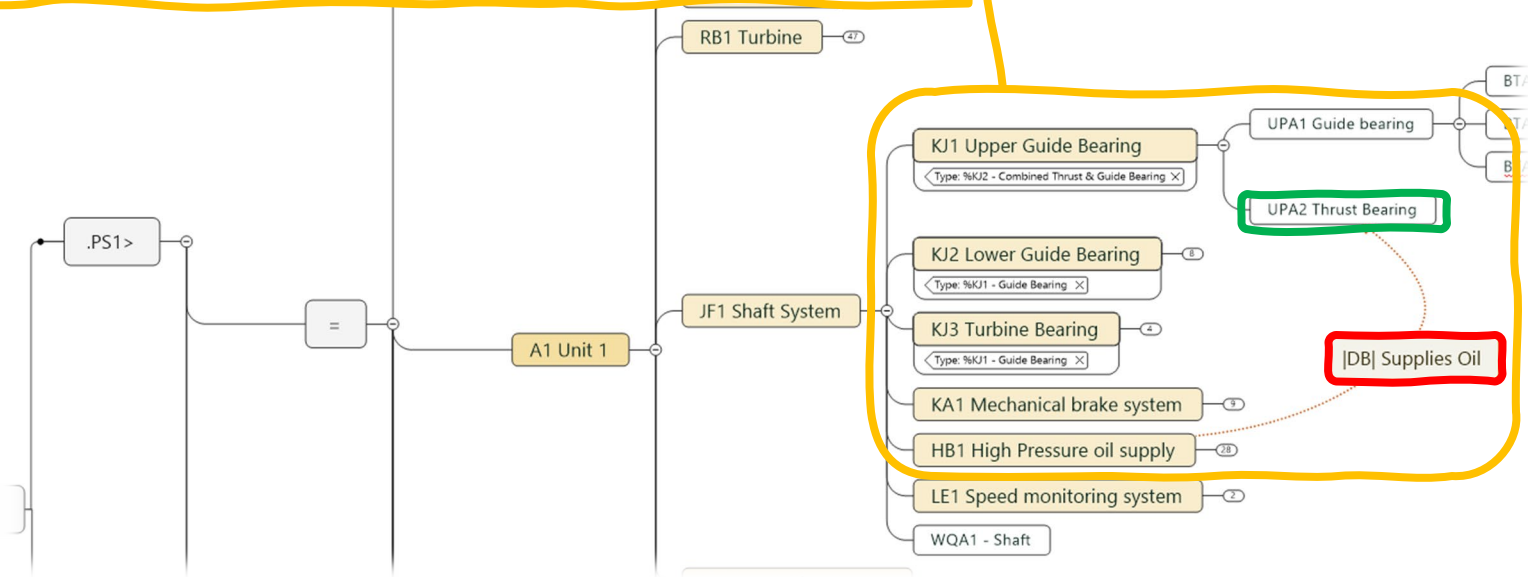
=A1.RG3.RG2.GCA6|NA|-A1.AA2

Module"1326", is being positioned by tracker 2

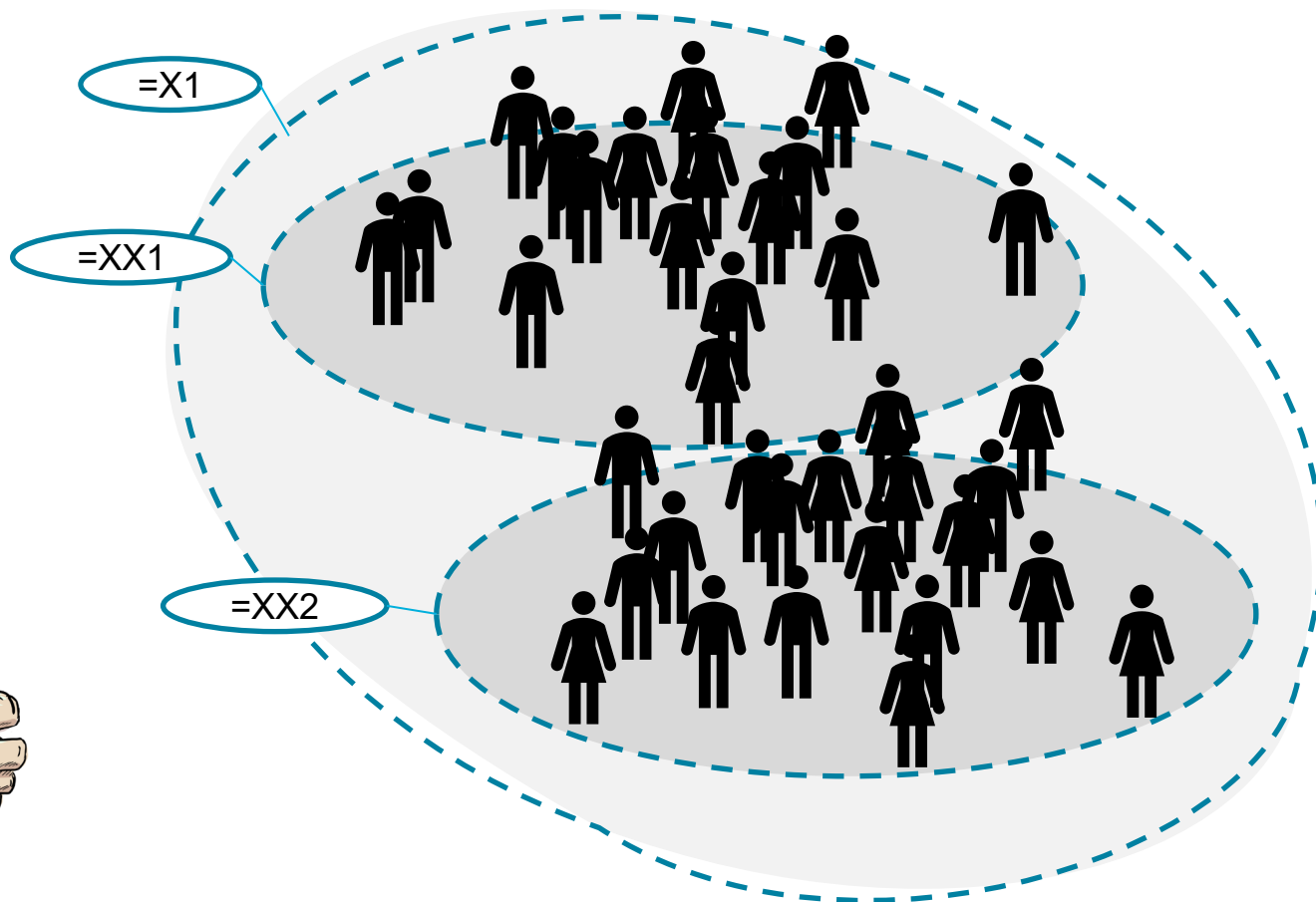
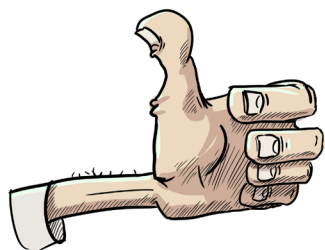
1	Sub-	Class	class	Class name	Definition	Note/Example
2	A			Transfer of software	point where two systems affect each other for data exchange by means of software	
3		AA		Data transfer	point where two systems affect each other for data exchange by means of software in the form of complex data	Protocols, Device drivers, registers are supplied/exchanged
4	B			transfer of signal	point where two systems affect each other for signal supply	
5		BA		Alarm signal transfer	point where two systems affect each other for signal supply in the form of alarm object	Alarm signal is exchanged E.g. "Motor temperature high"
6		BB		Command signal transfer	point where two systems affect each other for signal supply in the form of command object	Command signal is exchanged E.g. "Start motor", ref IEC 61175 def
7		BC		Event signal transfer	point where two systems affect each other for signal supply in the form of event object	Event signal is exchanged E.g. "Motor started"
8		BD		Indication signal transfer	point where two systems affect each other for signal supply in the form of indication object	Indication signal is exchanged E.g. power on/off or breaker open/closed
9		BE		Power signal	point where two systems affect each other for signal supply in the form of power signal	
10		BF		Measuring signal transfer	point where two systems affect each other for signal supply in the form of measuring object	Measurement is sent to another system E.g. measured motor speed value
11		BG		Set value signal transfer	point where two systems affect each other for signal supply in the form of set value object	A set value is sent to another system E.g. set motor speed
12	C			transfer of energy	point where two systems affect each other for energy supply	
17	D			transfer of material	point where two systems affect each other for material movement	
22	E			structural support	point where two systems affect each other for structural support	
25	F			transport and routing infrastructure support	point where two systems affect each other for provision of transportation infrastructure	
30	G			allocation of space	point where two systems affect each other for provision of space	footprint
33	H			field and potential interaction	point where two systems affect each other for field and potential interaction	
36	I			(Not to be used)		
37	J			transfer of ionizing non-radiation	point where two systems affect each other for supply of ionizing radiation	
43	L			transfer of ionizing radiation	point where two systems affect each other for supply of ionizing radiation	
50	M			transfer of acoustic waves	point where two systems affect each other for supply of acoustic waves	
53	N			Mechanical interaction	point where a system affect another mechanically	
54		NA		Positioning	point where one system affects the other mechanically, by physically changing the position of the other, relative to an external reference	Setting, governing, positioning
55		NB		Guiding	point where one system affects the other mechanically, by physically changing the position of the other, relative to itself	Lifting, pushing, hoisting, lowering dragging, pulling
56	End					

=A1.JF1.HB1|DB|=A1.JF1.KJ1.UPA1

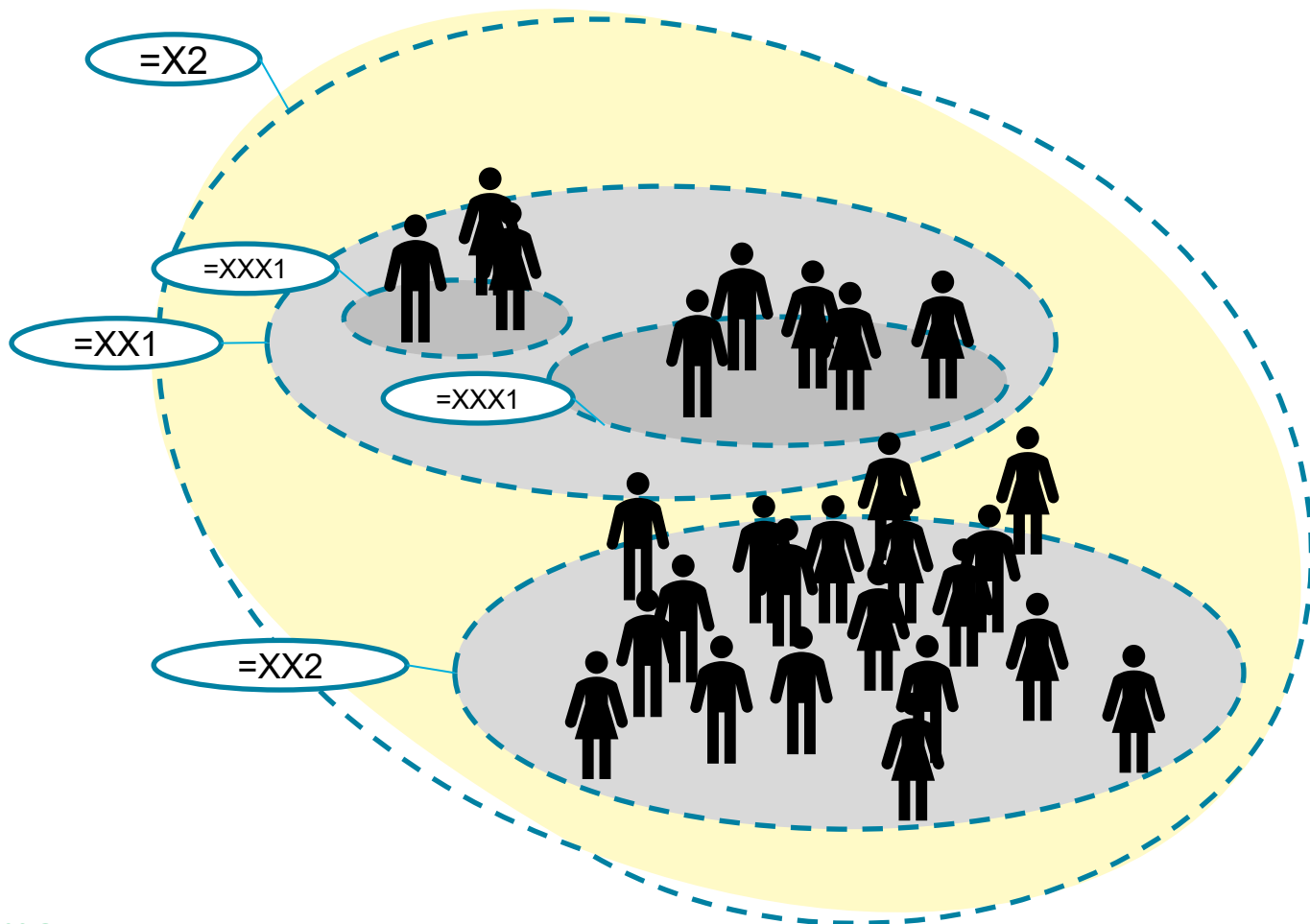
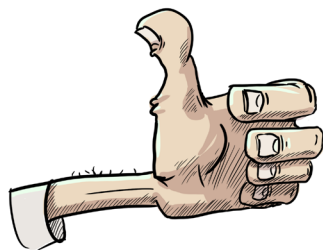
The unit HP Oil system supplies liquid matter to the unit thrust bearing



Modelling principles:
How many levels?



5-25 sibling systems



5-25 sibling systems

"No more complicated than it has to be!"



- E1 (Reservoir 1)
- E1.LE1 (Monitoring syst. 1)
- E1.LE1.BLA1 (Level monitoring syst. 1)
- E1.LE1.BLA1.BLA1 (Level sensor 1)
- E1.LE1.BLA1.BLA2 (Level sensor 2)



-E1 (Reservoir 1)

Only for level
monitoring

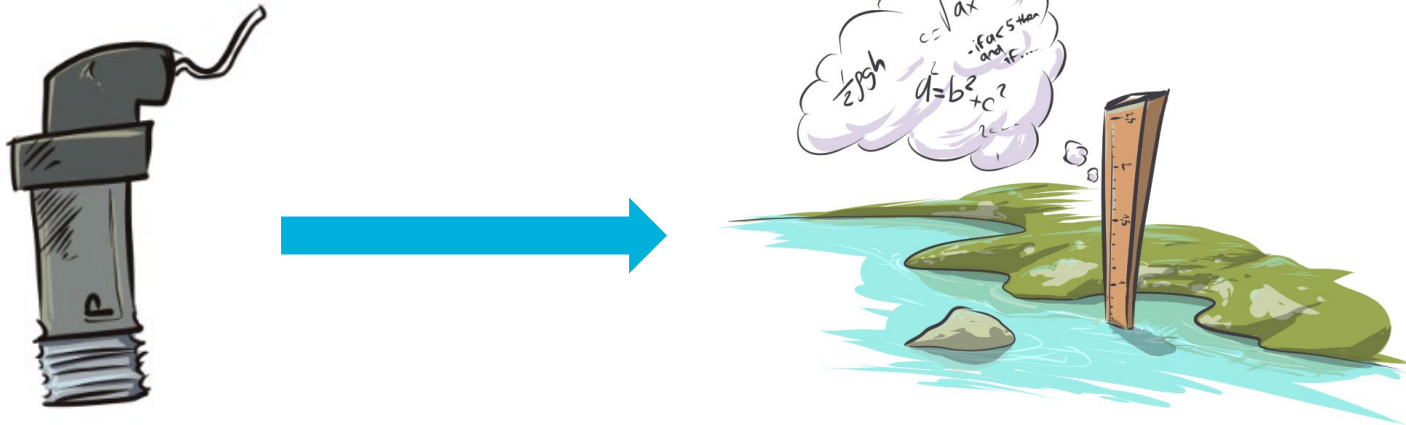
-E1 .BLA1 (Level monitoring syst. 1)

-E1 .BLA1.BLA1 (Level sensor 1)

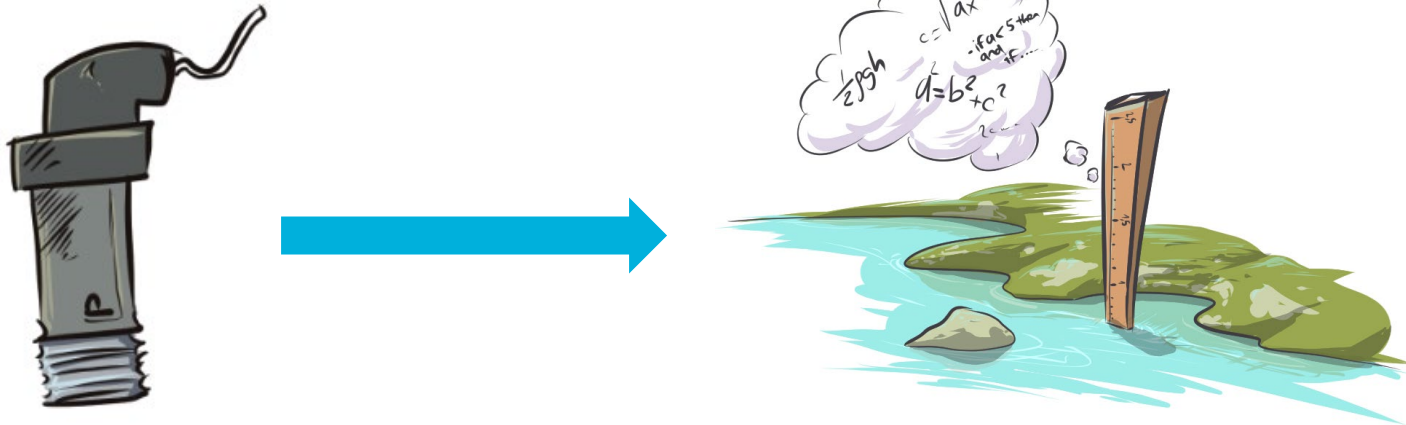
-E1 .BLA1.BLA2 (Level sensor 2)



- E1 (Reservoir 1)
- E1.BLA1 (Level monitoring syst. 1)
- E1.BLA1.BLA1 (Level sensor 1)
- E1.BLA1.BLA2 (Level sensor 2)



- E1 (Reservoir 1)
- E1.BLA1 (Level monitoring syst. 1)
- E1.BLA1.BPA1 (Pressure sensor 1)
- E1.BLA1.BPA2 (Pressure sensor 2)



Annex D (Informative)

Classification of Association, suggested classes

Class	Sub-class	Class name	Definition
A		Transfer of software	Relationship where two systems exchange digital information
	AA	Software transfer	Relationship where two systems exchange software in the form of complex data
B		Transfer of signal	Relationship where two systems exchange signals and/or data
	BA	Event signal transfer	Relationship where two systems exchange signals and/or data in the form of an event
	BB	Control signal transfer	Relationship where two systems exchange signals and/or data in the form of a control
	BC	Status information signal transfer	Relationship where two systems exchange signals and/or data in the form of indication
	BD	Measuring signal transfer	Relationship where two systems exchange signals and/or data in the form of measurements
	BE	Setting value signal transfer	Relationship where two systems exchange signals and/or data in the form of set values
C		transfer of energy	Relationship where energy flows between two systems
	CA	Electrical energy transfer	Relationship where energy flows between two systems in electrical form
	CB	Thermal energy transfer	Relationship where energy flows between two systems in the form of thermal energy
	CC	Kinetic energy transfer	Relationship where energy flows between two systems in the form of kinetic energy
D		transfer of material	Relationship where matter flows between two systems
	DA	Gas material transfer	Relationship where matter flows between two systems in gaseous form

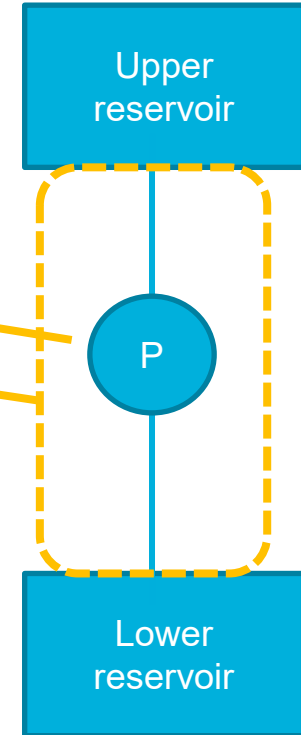
Modelling principles:
This or that?



KE – Pump system

JB – Liquid transport system

Pumps are often used for lifting/transport,
but that is an assumption. KE increases
pressure



A battery system is:

- ❑ Electrical power supply (HD)
- ❑ Electrical energy storage system (QD)

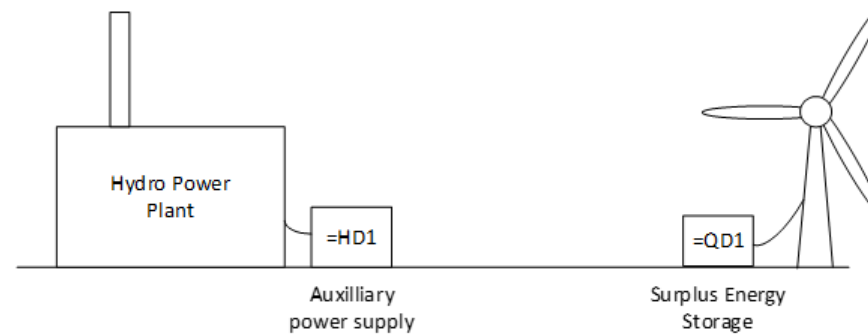


Figure 9-4 HD or QD illustration

10. Classification Guideline - CW

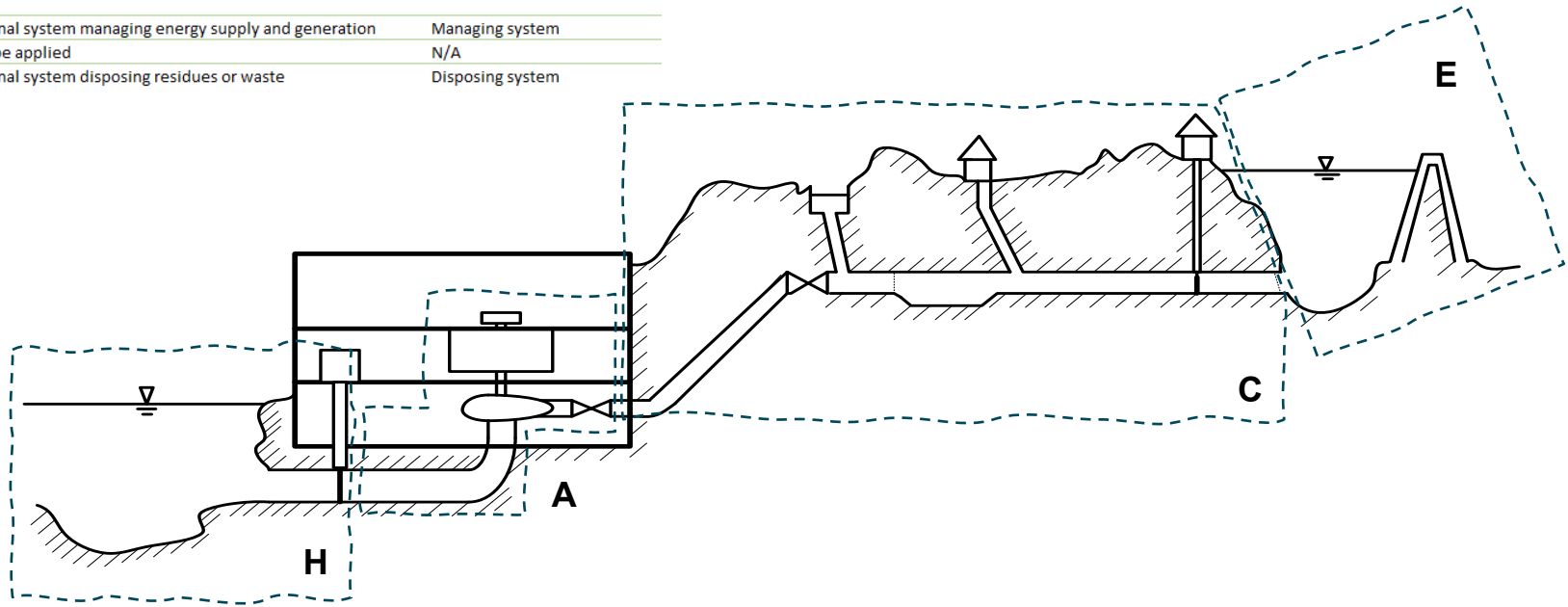
Modelling principles:

CW: Construction identification

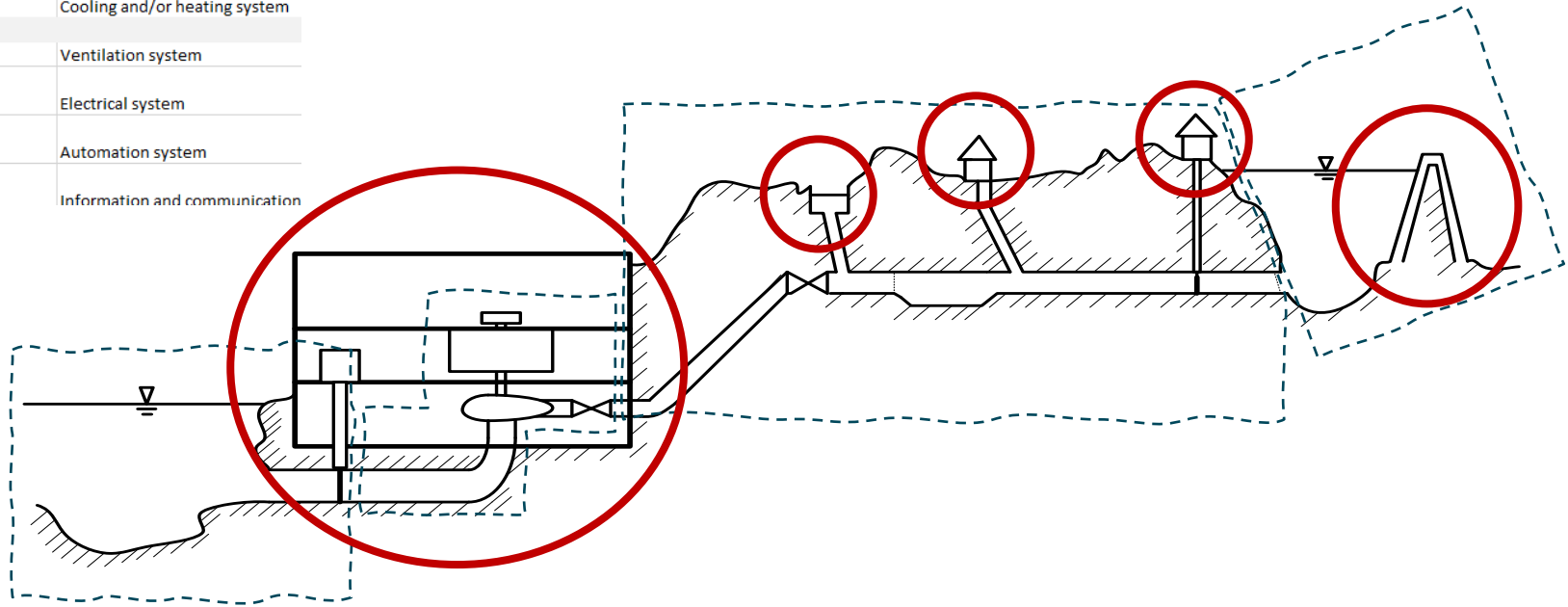
Skip
→

Modelling principles:
Finally

A	Functional system transforming energy or energy carrier	Transforming system
B	Functional system transporting electric power	Electrical transporting system
C	Functional system transporting energy or energy carrier, excluding electric energy	Transporting system
D	Functional system supporting the energy production process	Supporting system
E	Functional system for collecting and storing energy for subsequent retrieval	Storing system
F	Functional system managing energy supply and generation	Managing system
G	Not to be applied	N/A
H	Functional system disposing residues or waste	Disposing system

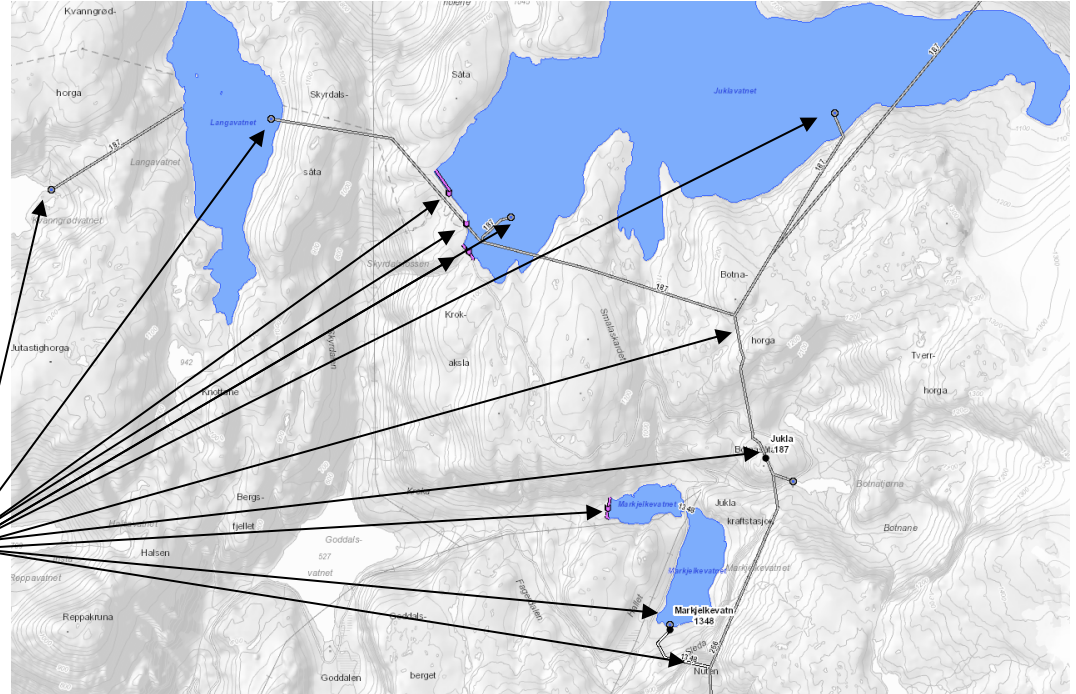


Space systems	
A	Ground system
B	Wall system
C	Slab system
D	Roof system
Installations systems	
E	Gas and air system
F	Water and fluid system
G	Drainage and waste system
H	Cooling and/or heating system
I	
J	Ventilation system
K	Electrical system
L	Automation system
M	Information and communication



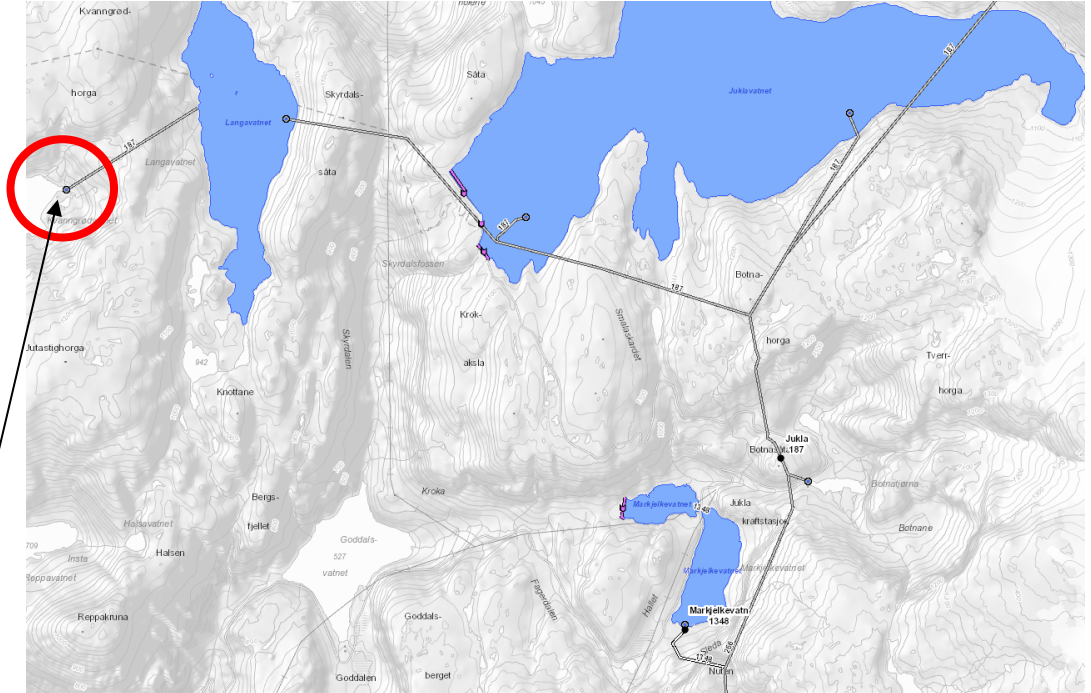
Main System: «Wall 45»

<PowerPlant.CW1>=B45



Main System: «Wall 45»

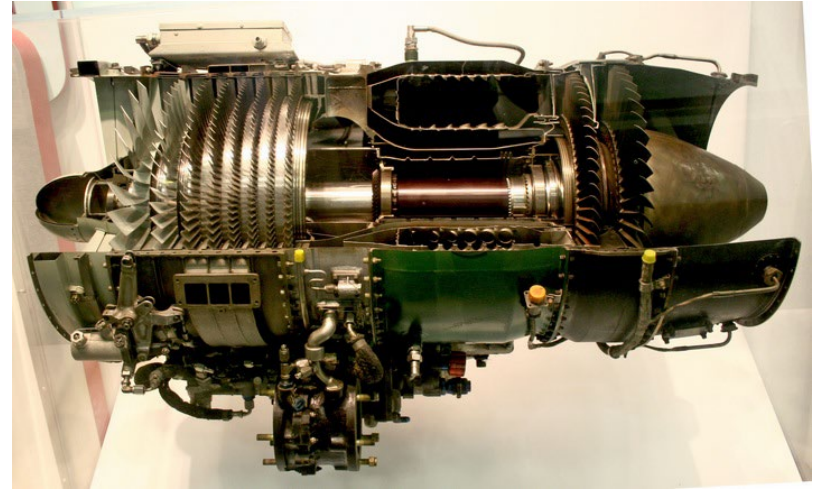
<PowerPlant.CW1>=B45[#]
(Wall between the
lavatory and the main
hall)



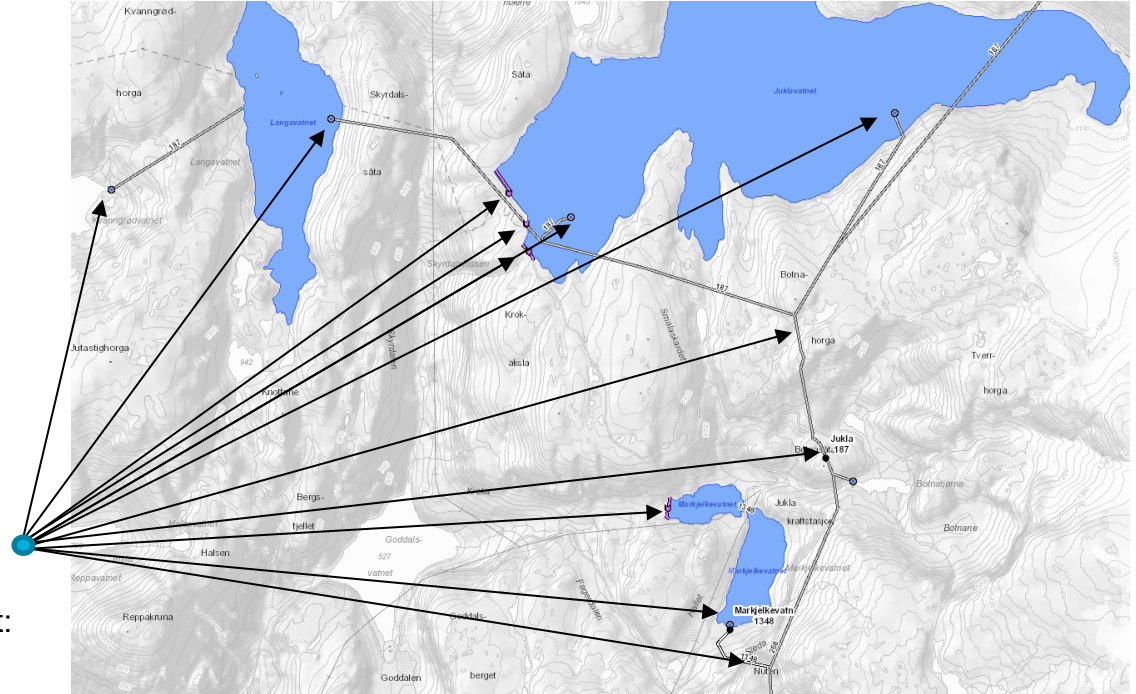
Main System



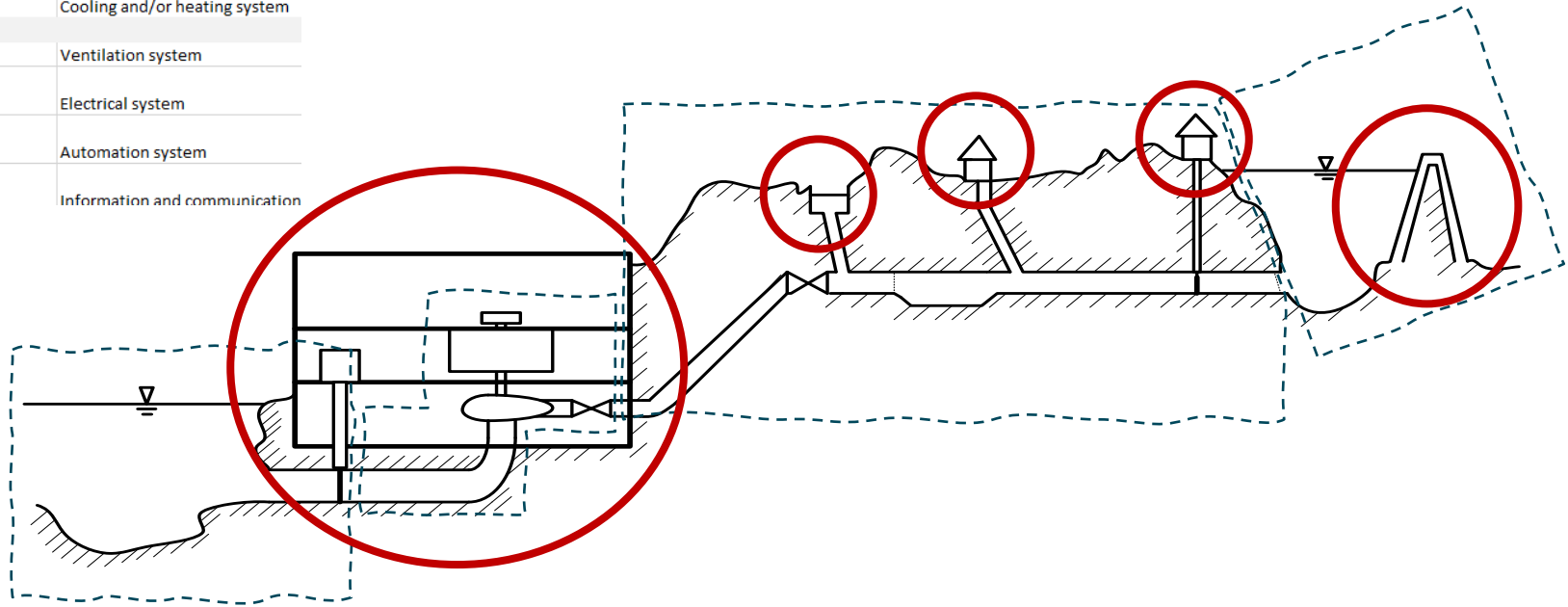
Sub-system



We need something to identify the
construction entities around the plant:
"Construction-ID"



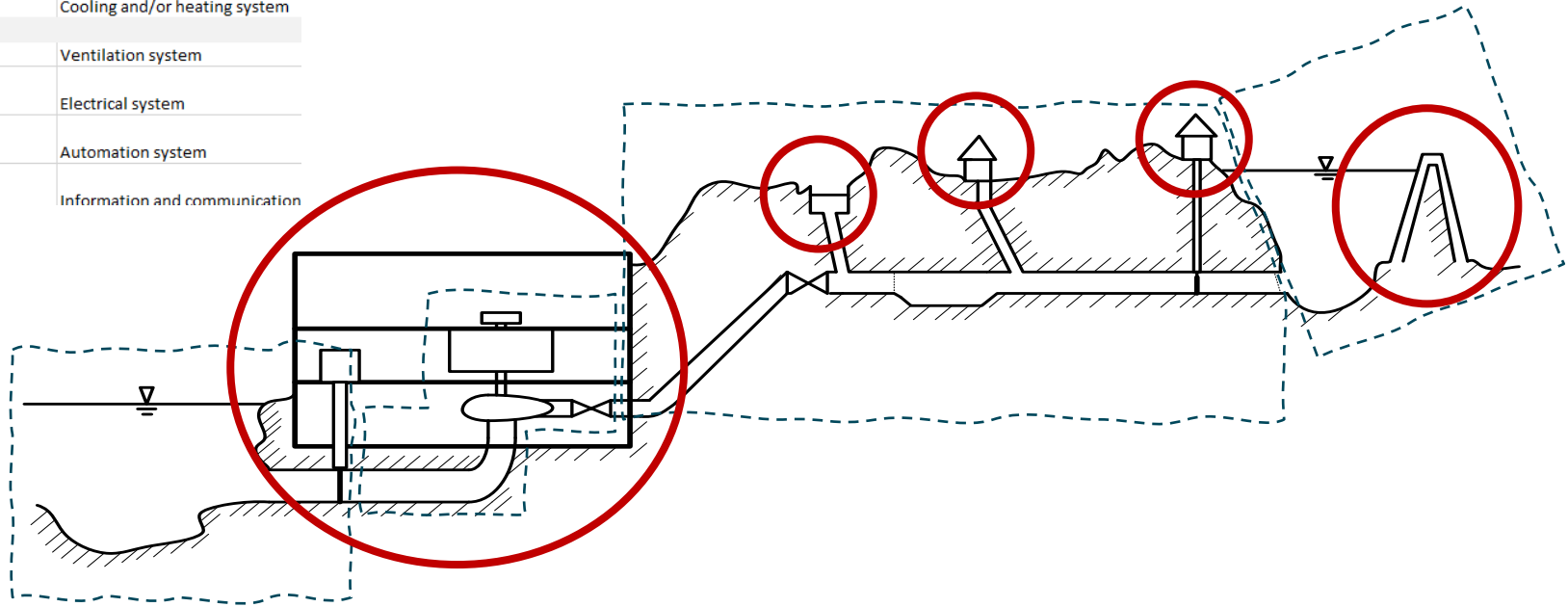
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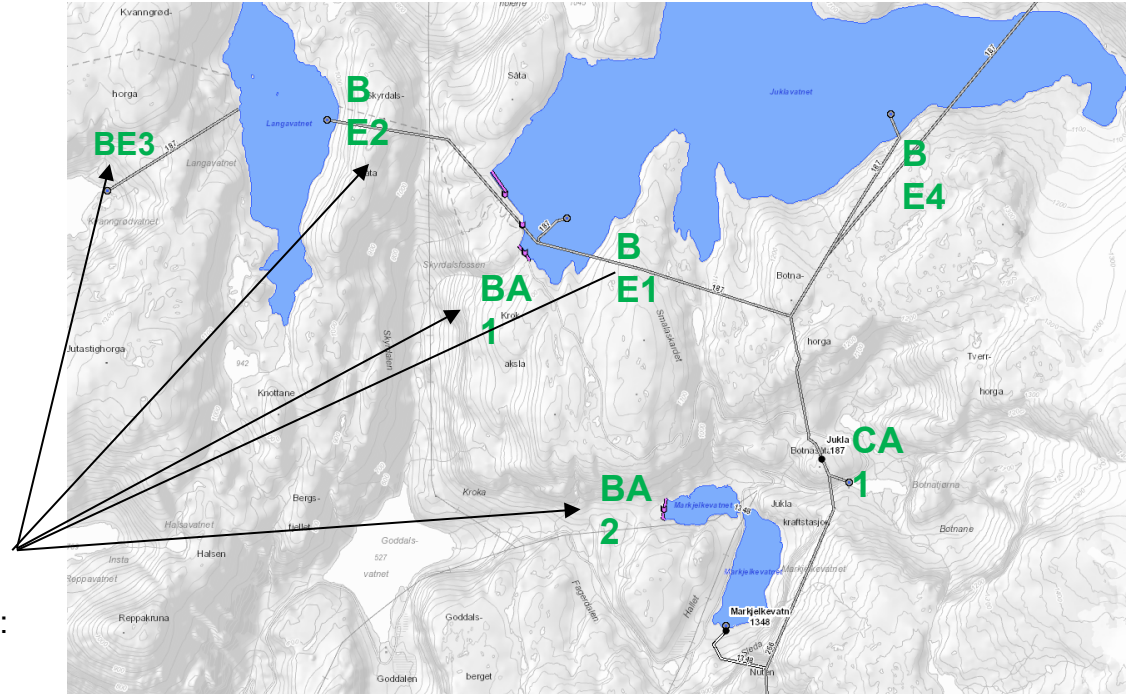
81346 already has classes to identify construction entities. It is used for the ++ site of location aspect!

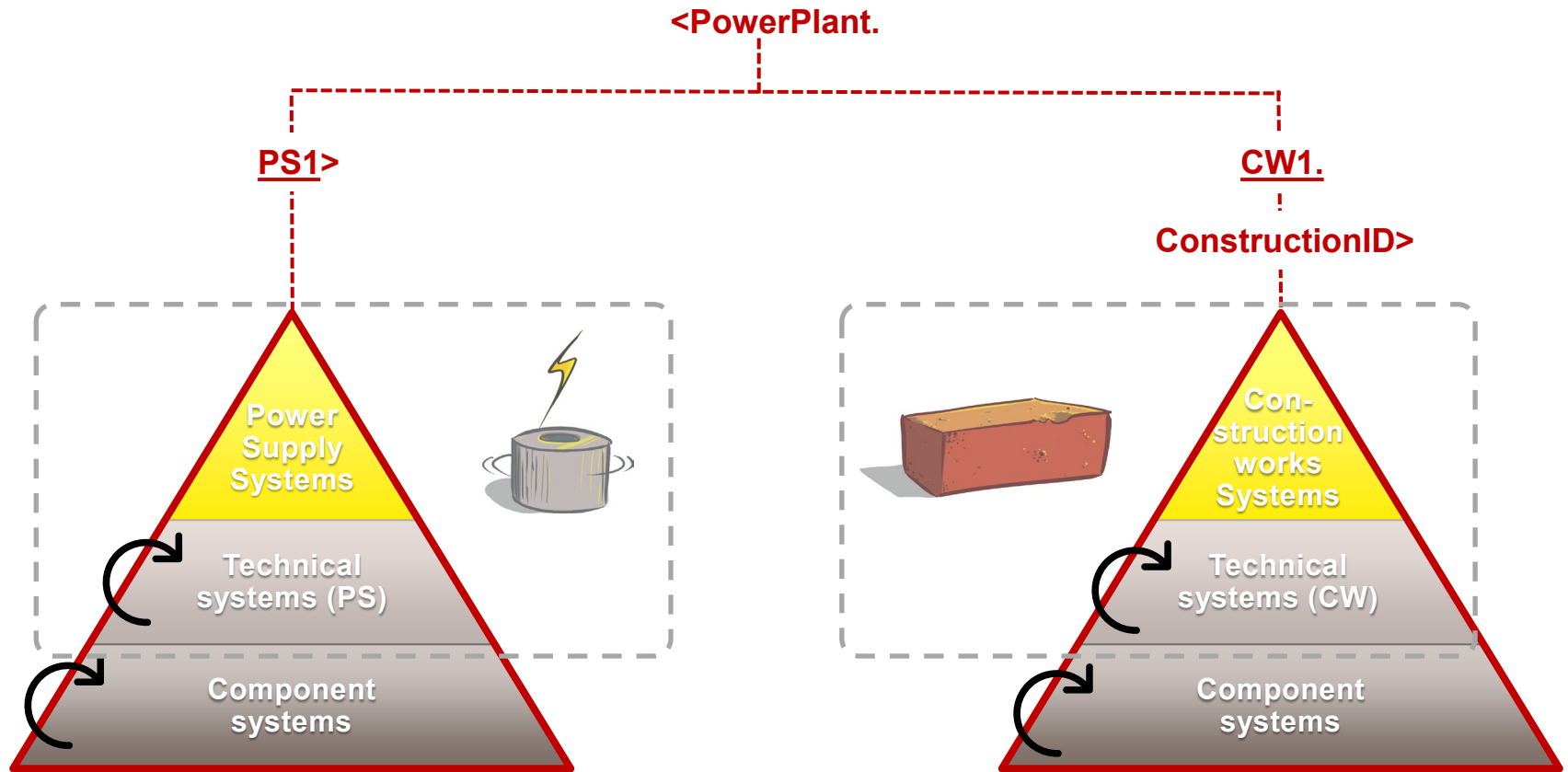
B_		Entity preventing matter from spilling or flowing in an open environment	Dam
	BA	Entity preventing matter from spilling or flowing in an open environment	Dam
	BB	Entity guiding matter in a closed environment	Piping
	BC	Entity guiding matter in a open environment	Canal
	BD	Control entity adjusting matter level	Sluice system
	BE	control entity controlling a flow of matter	Gate
D_		Construction entity for storage	Storage facility
	DA	storage entity for resources	Materials store
	DB	storage entity for moveable technical equipment	Equipment entity (garage)
	DC	Storage entity outside of a building	Open outdoor storage facility
	DD	storage entity for liquids, gas or masses in sealed environment	Silo
	DE	storage entity for liquids or masses in open environment	Reservoir
C_		Construction entity for production and maintenance	Production facility
	CA	production entity for production of electrical energy	Power station

Space systems	
A	Ground system
B	Wall system
C	Slab system
D	Roof system
Installations systems	
E	Gas and air system
F	Water and fluid system
G	Drainage and waste system
H	Cooling and/or heating system
I	
J	Ventilation system
K	Electrical system
L	Automation system
M	Information and communication



We need something to identify the construction entities around the plant:
"Construction-ID"





And we're off,
CASES!!

Modelling principles:
Finally

Confession time



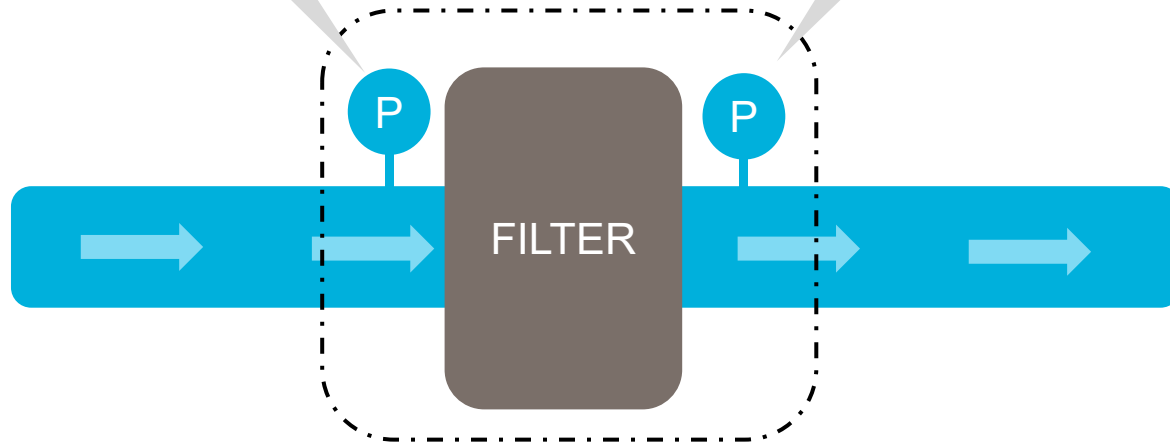
Instantiation (numbering) ^{mostly} shall not hold any meaning

BPA1

Pressure
measurement
upstream

BPA2

Pressure
measurement
downstream



=A1.KA1 (MIV)

