

LECTURE NOTES

Characteristic classes in topology, geometry, and algebra

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1. Introduction

Vector bundles can be thought of as vector spaces parametrized by a base space, where “space” can mean a topological space, an algebraic variety, or a manifold. They occurrence is abundant in topology, geometry, and algebra. Characteristic classes are cohomological invariants of vector bundles and the most important and powerful tools to study them. This course is an advanced level course on characteristic classes in topology, algebra, and geometry, including an introduction to vector bundles, cohomology, and differential geometry.

The course goal is to understand and be able to apply the concept of characteristic classes in a range of mathematical disciplines. At the end of the course, the student will be able to follow current research literature and, if desired, pursue own research projects in this area.

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2. Vector bundles

The theory of vector bundles can be described as linear algebra parametrized by a base space. The aim of this chapter is to make this slogan precise and give three equivalent but quite distinct definitions of what a vector bundle is. All three of these definitions have their advantages and disadvantages.

A vector bundle is, roughly speaking, an assignment of a vector space E_x to every point $x \in B$ of some topological space B . The space B is called the *base space*, and E_x is the *fiber at x* of the vector bundle. This assignment should satisfy two central conditions:

Continuity: The fibers E_x should vary continuously with the base point.

Local triviality: Over small open subsets $U \subset B$ of the base space, we should have $E_x = E_y$ for all $x, y \in U$.

The reader should be aware that both of these conditions make no mathematical sense as stated.

2.1. Bundles as spaces over a base space

Let B be a topological space. A *space over B* is another topological space E together with a map $p: E \rightarrow B$. We denote the category of spaces over B by Top/B . Here, a morphism from $p: E \rightarrow B$ to $p': E' \rightarrow B$ is a map $f: E \rightarrow E'$ such that the triangle

$$\begin{array}{ccc} E & \xrightarrow{f} & E' \\ & \searrow p \quad \swarrow p' & \\ & B & \end{array}$$

commutes, i. e. such that $p' \circ f = p$. We denote the set of morphisms over B by $\text{map}_B(E, E')$. If $E, E' \in \text{Top}/B$, we also define the *fiber product* $E \times_B E' \in \text{Top}/B$ to be

$$E \times_B E' = \{(e, e') \mid p(e) = p'(e')\} \xrightarrow{(e, e') \mapsto p(e)} B$$

It is customary to suppress the projection map p in the notation and denote the fiber $p^{-1}(x)$ of $x \in B$ by E_x .

Definition. Let B be a topological space and k a field (typically \mathbf{R} or \mathbf{C}). A *k -vector space over B* consists of:

- a space $E \in \text{Top}/B$,

2.1. Bundles as spaces over a base space

- a map $s_0 \in \text{map}_B(B, E)$, called the zero section,
- a map $+$ $\in \text{map}_B(E \times_B E, E)$, called addition, and
- a map $\cdot \in \text{map}_B(k \times E, E)$, called scalar multiplication

such that for each $x \in B$, E_x becomes a k -vector space with zero $s_0(x)$, addition $+$ $|_{E_x}$, and scalar multiplication $\cdot|_{E_x}$.

A morphism of vector spaces over B is a map $f \in \text{map}_B(E, E')$ compatible with s , $+$, and \cdot . In particular, $f|_{E_x}$ is a vector space homomorphism for all x .

The most obvious k -vector space over B is the product space $k^n \times B$, where the projection to B is simply the projection onto the second factor of the product.

Definition (local triviality of vector bundles). Let E be a k -vector space over B . Then E is called a k -vector bundle if every $x \in B$ has a neighborhood $U \subset B$ such that $E_U = p^{-1}(U)$ is isomorphic to a product space $k^n \times U$ for some $n \geq 0$. The category of k -vector bundles over B is denoted by $\text{Vect}_k(B)$ or just $\text{Vect}(B)$ if k is understood or irrelevant. A morphism of k -vector bundles is simply a morphism of the underlying k -vector spaces over B .

In a vector bundle $E \in \text{Vect}(B)$, the dimension of each fiber E_x must be finite, but it may vary with x . If it does not, and is constantly n , we say that E is *equidimensional* of dimension n . We denote the subcategory of n -dimensional vector bundles on B by $\text{Vect}^n(B)$.

Lemma 2.1.1. *If B is connected then any $E \in \text{Vect}(B)$ is equidimensional.*

Proof. For $n \in \mathbf{N}_0$, let $U_n = \{x \in B \mid \dim E_x = n\}$. By the local triviality condition, each U_n is open and closed, the U_n are disjoint, and they cover B . Thus $B = U_n$ for some n , and $U_i = \emptyset$ for $i \neq n$. \square

So far, the only vector bundles we have encountered are trivial vector bundles (product bundles). It is thus time for some more interesting examples.

Example 2.1.2 (The Möbius strip). Let $E = \mathbf{R} \times [0, 1]/\sim$, where the equivalence relation \sim is generated by $(x, 0) \sim (-x, 1)$. There is a map $p: E \rightarrow B = [0, 1]/\{0, 1\} \cong \mathbf{S}^1$ defined by $p(x, t) = t$. Then E is a 1-dimensional real vector bundle over B , an infinite cylinder with a half twist. The bundle E is known as the *Möbius strip*.

Explicitly, the zero section is given by $s_0(t) = (0, t)$, addition by

$$(x, t) + (y, t) = (x + y, t)$$

and scalar multiplication by

$$\lambda \cdot (x, t) = (\lambda x, t).$$

Note that the addition is well-defined.

To verify local triviality, let us first consider a point $t \neq \bar{0} \in B$, where $\bar{0}$ denotes the equivalence class of $0 = 1$. Then we can choose a neighborhood $U \ni t$ such that $\bar{0} \notin U$

2. Vector bundles

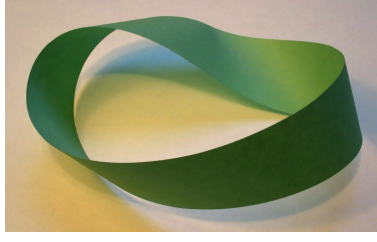


Figure 2.1.3.: The Möbius strip E

and $E_U \xrightarrow{(x,t) \mapsto (x,t)} \mathbf{R} \times U$ is a well-defined isomorphism of vector spaces over U . On the other hand, for $t = \bar{0}$, choose $U = B - \{\frac{1}{2}\}$ and define

$$E_U \xrightarrow{(x,t) \mapsto \begin{cases} (x,t); & t < \frac{1}{2} \\ (-x,t); & x > \frac{1}{2} \end{cases}} \mathbf{R} \times U$$

This is also an isomorphism of vector spaces over U , so we are done.

The Möbius strip is a nontrivial line bundle. This can be seen by observing that the total space of a trivial line bundle falls apart into two components when one removes the zero section, whereas the Möbius strip stays connected.

Example 2.1.4 (Projective space and the tautological bundle). Let k be any field or skew field (typically \mathbf{R} , \mathbf{C} , or the quaternions \mathbf{H}) and $P^n = kP^n$ the n -dimensional projective space over k . This is defined to be the quotient space

$$P^n = (k^{n+1} - \{0\}) / \sim,$$

where the equivalence relation \sim is given by $(x_0, \dots, x_n) \sim (\lambda x_0, \dots, \lambda x_n)$ for $\lambda \in k^\times$. We will think of P^n as the set of lines through the origin in k^{n+1} ,

$$P^n = \{L \subseteq k^{n+1} \mid L \text{ one-dimensional subspace}\},$$

although this description does not include what topology we want to have on P^n . We now define the *tautological line bundle* $\mathcal{O}(-1)$ on P^n by

$$E = \{(x, L) \mid L \in P^n, x \in L\}.$$

It is called tautological because the fiber E_L over a line $L \in P^n$ is *that line*. The notation $\mathcal{O}(-1)$ will become clear ???. The total space E_n is topologized as a subspace of $k^{n+1} \times P^n$, and the projection map is the obvious one, mapping (x, L) to L . Much as in Example 2.1.2, we see that the vector-space-over- P^n structure of the $(n+1)$ -dimensional trivial vector bundle $k^{n+1} \times P^n$ restricts to the subspace E , and it remains to show local triviality.

2.1. Bundles as spaces over a base space

Choose an arbitrary scalar product $\langle \cdot, \cdot \rangle$ on k^{n+1} , let $L \in P^n$ be a line in k^{n+1} , $x_0 \in L$ a point of norm 1, and choose $U = \{L' \in P^n \mid L, L' \text{ are not orthogonal}\}$. Then there is a bijective map

$$\phi: E_U \rightarrow k \times U, \quad \phi(x, L) = (\langle x, x_0 \rangle, L)$$

which constitutes a local trivialization of the tautological bundle near L .

Example 2.1.5. We give an example of a vector space over B which is not locally trivial and hence not a vector bundle. Let $E = \{(x, b) \in \mathbf{R}^2 \mid xb = 0\} \xrightarrow{(x,b) \mapsto b} \mathbf{R} = B$ be the projection of the coordinate cross to the b -axis. Then

$$E \times_B E = \{(x_1, x_2, b) \mid x_1 = x_2 = 0 \text{ if } b \neq 0\} \xrightarrow{(x_1, x_2, b) \mapsto (x_1 + x_2, b)} E$$

gives E the structure of a real vector space over B (the scalar multiplication is defined similarly). However, no neighborhood U of $0 \in B$ has $E_U \cong U \times \mathbf{R}^n$ for any n since the fiber over 0 is 1-dimensional, while all other fibers are 0-dimensional.

According to the definition, an isomorphism of vector bundles is a map $f \in \text{map}_B(E, E')$ of vector spaces over B which has an inverse $g \in \text{map}_B(E', E)$. The following characterization is less obvious than one might at first think:

Theorem 2.1.6. A map $f \in \text{map}_B(E, E')$ is an isomorphism of vector bundles iff $f|_{E_x}: E_x \rightarrow E'_x$ is an isomorphism on the fibers for every $x \in B$.

Proof. The “only if” direction is obvious, so assume that f induces a vector space isomorphism on all fibers. Then f is bijective and has an inverse map $f^{-1}: E'_x \rightarrow E_x$, but is f^{-1} continuous?

To show this, we will use local trivializations. Let $x \in B$ have a trivializing neighborhood $U \subset B$ for both E and E' and $\phi: E_U \rightarrow k^n \times U$, $\phi': E'_U \rightarrow k^n \times U$ be local trivializations. The restriction $f|_U$ can be written as the composition of isomorphisms

$$f|_{E_U}: E_U \xrightarrow{\phi} U \times k^n \xrightarrow{G} U \times k^n \xrightarrow{(\phi')^{-1}} E'_U$$

for some map $G \in \text{map}_U(U \times k^n, U \times k^n)$. As G is an isomorphism over U , it must be of the form

$$G(u, x) = (u, g(u)x) \quad \text{for some } g: U \rightarrow \text{GL}_n(k).$$

But then $f^{-1}|_{E'_U} = \phi^{-1} \circ (\text{id} \times g^{-1}) \circ \phi'$, where g^{-1} denotes the pointwise matrix inverse $u \mapsto g(u)^{-1}$, not the inverse map. As a composite of continuous maps, $f^{-1}|_{E'_U}$ is therefore continuous at x . \square

Exercise 1. Consider the spaces kP^n from Example 2.1.4 again. Choose a scalar product on k^{n+1} and define an n -dimensional vector bundle on them by

$$E = \{(x, L) \mid L \in kP^n, x \in L^\perp\}.$$

That is, the point x is in the hyperplane orthogonal to L . Shows that this defines a vector bundle, which we will call $\mathcal{O}(-1)^\perp$.

2. Vector bundles

Exercise 2. Let $k = \mathbf{R}, \mathbf{C}$, or \mathbf{H} . Show that there is a homeomorphism between kP^1 , the one-dimensional projective space over k , and $\mathbf{S}^{\dim_{\mathbf{R}}(k)}$, i. e. \mathbf{S}^1 , \mathbf{S}^2 , and \mathbf{S}^4 , respectively.

Show that the Möbius bundle μ of Example 2.1.2 is isomorphic to the tautological line bundle $\mathcal{O}(-1)$ on $\mathbf{R}P^1$.

2.2. Bundles as sheaves

Definition. Let $p: E \rightarrow B$ be a vector bundle and $U \subseteq B$. Then we define the set of *sections* of p to be

$$\Gamma_p(U) = \text{map}_U(U, E_U) = \{s: U \rightarrow E \mid p \circ s = \text{id}_U\}.$$

Using the vector space structure over B of E , we can define an addition and scalar multiplication on $\Gamma_p(U)$,

$$(s + s')(u) = s(u) + s'(u), \quad (\lambda s)(u) = \lambda \cdot s(u),$$

so that $\Gamma_p(U)$ is actually a (usually infinite-dimensional) k -vector space. Loaning a term from algebraic geometry, Γ_p is actually a *sheaf* of k -vector spaces.

Definition. Let B be a topological space. Let $\text{Open}(B)$ be the category whose objects are the open subsets $U \subseteq B$ and which has precisely one morphism $U \rightarrow U'$ iff $U \subseteq U'$. Then a contravariant functor F from $\text{Open}(B)$ to sets (or spaces, groups, k -vector spaces) is called a *presheaf* (of spaces, sets, groups, or k -vector spaces). That is, F assigns to each open U a set (space, group, vector space) $F(U)$, often called the sections of F over U , and for each inclusion $U \subseteq U'$ there is a map (homomorphism, linear map) $F(U') \rightarrow F(U)$, usually denoted by $s \mapsto s|_U$. This assignment of maps is required to be transitive for double inclusions $U \subseteq U' \subseteq U''$ and F must map the identity inclusion $U = U$ to the identity.

A *morphism of presheaves* is a natural transformation of functors. In other words, a morphism $f: F \rightarrow G$ consists of morphisms $f(U): F(U) \rightarrow G(U)$ for each $U \in \text{Open}(B)$ such that for any inclusion $V \subseteq U$ in $\text{Open}(B)$, $f(U)(s)|_V = f(V)(s|_V)$.

A presheaf F on B is called a *sheaf* if it satisfies the *gluing condition*: if $U \subseteq B$ is covered by open sets $\{U_\alpha\}_\alpha$ and we are given, for each α , a section $s_\alpha \in F(U_\alpha)$ in such a way that on intersections $U_{\alpha\beta} = U_\alpha \cap U_\beta$, we have that

$$s_\alpha|_{U_{\alpha\beta}} = s_\beta|_{U_{\alpha\beta}},$$

then there exists a unique section $s \in F(U)$ such that $s|_{U_\alpha} = s_\alpha$ for all α . In words, if we have separate sections over each element of the open cover, and they match up on intersections, then we can glue them together to obtain a section on all of U .

A morphism of sheaves is just a morphism of the underlying presheaves; in other words, sheaves are a full subcategory of presheaves.

It should come as no surprise that sections of a bundle actually form a sheaf:

Proposition 2.2.1. *Let $p: E \rightarrow B$ be a k -vector bundle. Then Γ_p is a sheaf of k -vector spaces on B .*

Proof. We begin by showing that Γ_p is a presheaf. Given an inclusion $U \subseteq U'$, we have a canonical restriction map

$$\Gamma_p(U') = \{s: U' \rightarrow E \mid p \circ s = \text{id}\} \xrightarrow{-|_U} \{s: U \rightarrow E \mid p \circ s = \text{id}\} = \Gamma_p(U),$$

and the functoriality is obvious. Now let us check the gluing condition. Let U_α be an open cover of U and $s_\alpha \in \Gamma_p(U_\alpha)$ such that $s_\alpha|_{U_{\alpha\beta}} = s_\beta|_{U_{\alpha\beta}}$. Then we define $s \in \Gamma_p(U)$ by

$$s(x) = s_\alpha(x) \quad \text{if } x \in U_\alpha$$

This is defined on all of U because $\{U_\alpha\}$ covers U , and it is well-defined by the matching condition on intersections. Furthermore, s is the only element of $\Gamma_p(U)$ which restricts to s_α on all U_α because if there was another $s' \in \Gamma_p(U)$, being a different function, it would have to disagree with s on some point x which lies in some U_α , but we must have $s(x) = s_\alpha(x) = s'_\alpha(x) = s'(x)$. \square

Example 2.2.2. A particular case is the sheaf \mathcal{O}_B of sections of the trivial line bundle $k \times B$ over B . In this case we have that $\mathcal{O}_B(U)$ is just the set of continuous functions from U to k , and this is in fact a sheaf of k -algebras, where the multiplication is given pointwise. We will sometimes omit the index and just write \mathcal{O} for this sheaf when the base space is obvious.

If R is a sheaf of rings (or k -algebras) on a space X then an R -module sheaf M is a sheaf of abelian groups (or k -vector spaces) with an action

$$R(U) \times M(U) \rightarrow M(U),$$

natural in U , that makes $M(U)$ an $R(U)$ -module for all U . A *morphism of R -module sheaves* $f: M \rightarrow N$ is a morphism of sheaves such that for every U , $f(U): M(U) \rightarrow N(U)$ is an $R(U)$ -module homomorphism.

Proposition 2.2.3. *Let $p: E \rightarrow B$ be a k -vector bundle. Then Γ_p is a sheaf of \mathcal{O}_B -modules. Moreover, Γ_p is locally free, i. e. if for every $x \in B$ there exists a neighborhood $U \ni x$ such that $\Gamma_p|_U \cong \mathcal{O}_U^n$ for some $n \geq 0$.*

Proof. The action

$$\begin{aligned} \mathcal{O}_B(U) \times \Gamma_p(U) &= \text{map}(U, k) \times \text{map}_U(U, E_U) = \text{map}_U(U, k \times E_U) \\ &\xrightarrow{\text{map}_U(U, \cdot)} \text{map}_U(U, E_U) = \Gamma_p(U) \end{aligned}$$

gives Γ_p the desired structure.

To show local freeness, let $x \in B$ and choose a trivializing neighborhood $U \ni x$ with $\phi: E_U \xrightarrow{\sim} k^n \times U$. Then for any $V \subseteq U$, we have $\Gamma_p(V) \cong \Gamma_{k^n \times U}(V) \cong \mathcal{O}_U(V)^n$, hence Γ_p is indeed locally free. \square

2. Vector bundles

It is natural to ask whether the sheaf of sections associated to a vector bundle suffices to completely describe the vector bundle, and moreover, whether any sheaf of vector spaces can be realized as the sections of some vector bundle. The best way to formulate this is by an equivalence of categories.

Theorem 2.2.4. *The functor*

$$\text{Vect}(B) \xrightarrow{p^* \rightarrow \Gamma_p} \{\text{finitely generated locally free } \mathcal{O}\text{-module sheaves on } B\}$$

is an equivalence of categories.

In order to give an inverse construction, we need in particular to extract the fiber over a single point $b \in B$ from a sheaf F .

Definition. The *stalk at $b \in B$* of a sheaf on F is

$$F_b = \text{colim}_{U \in \text{Open}_b(B)} F(U),$$

where $\text{Open}_b(X)$ denotes the poset of open sets in X containing b .

If $s \in F(U)$ is a section and $b \in U$ then the natural map $F(U) \rightarrow F_b$ sends s to an element $s_b \in F_b$, which is called the *germ* of s at b .

Since F_b is defined using the restriction maps of the sheaf F , the stalk of a sheaf F inherits whatever additional structure F has: the stalk of a sheaf of groups is a group, the stalk of a sheaf of k -vector spaces is a k -vector space, etc. Furthermore, taking stalks is functorial, i. e. a morphism of sheaves induces a morphism of stalks.

Example 2.2.5. Let B be a space and \mathcal{O} the sheaf of continuous functions on B . Then the stalk \mathcal{O}_b consists of *germs of continuous functions at b* . Those are function f defined in some neighborhood U of b modulo the equivalence relation generated by

$$(f, U) \sim (g, V) \quad \text{if} \quad f|_{U \cap V} = g|_{U \cap V}.$$

Note the \mathcal{O}_b has an ideal $(\mathcal{O}_b)_+$ consisting of those germs of functions that vanish at b . This is the kernel of the evaluation map

$$\mathcal{O}_b \xrightarrow{s \mapsto s(b)} k,$$

thus the quotient $\mathcal{O}_b/(\mathcal{O}_b)_+$ is isomorphic with k .

Given any sheaf M of \mathcal{O} -modules, the stalk M_b is a module over \mathcal{O}_b . We define the *fiber* of M at b to be the quotient

$$\overline{M}_b = M_b/(\mathcal{O}_b)_+ M_b.$$

This is a k -vector space in a natural way, and it is finite-dimensional if M was finitely generated.

Lemma 2.2.6. *Let $p: E \rightarrow B$ be a vector bundle and $\Gamma = \Gamma_p$ the associated locally free \mathcal{O} -module sheaf. Then for every $b \in B$ there is a natural isomorphism of k -vector spaces*

$$\Phi: \bar{\Gamma}_b \rightarrow E_b$$

Proof. For every $U \in \text{Open}_b(B)$, we have a surjective evaluation map

$$\Gamma_p(U) = \text{map}_U(U, E_U) \xrightarrow{s \mapsto s(b)} E_b.$$

These maps are compatible with inclusions of open sets in $\text{Open}_b(B)$ and hence give rise to an epimorphism of k -vector spaces

$$\Phi: \Gamma_b = \text{colim}_{U \in \text{Open}_b(B)} \text{map}_U(U, E_U) \rightarrow E_b.$$

whose kernel is $(\mathcal{O}_b)_+ \Gamma_b$. □

Proof of Thm. 2.2.4. To show that Γ is an equivalence of categories, it suffices to show that it is fully faithful and essentially surjective. Let $p: E \rightarrow B$ and $p': E' \rightarrow B$ be two vector bundles on B and Γ, Γ' their associated locally free \mathcal{O} -module sheaves of sections. For the functor Γ to be fully faithful in this setting means that the map

$$\text{map}_B(E, E') \xrightarrow{\Gamma} \text{Hom}_{\text{Mod}_{\mathcal{O}}}(\Gamma, \Gamma')$$

is bijective, where the right hand side denotes the set of morphisms of \mathcal{O} -module sheaves.

For injectivity, assume that two maps $f, g \in \text{map}_B(E, E')$ induce the same map on the right hand side. By applying the functor Φ from Lemma 2.2.6, they induce the same maps between the fibers of Γ and Γ' , which are the fibers $E_b \rightarrow E'_b$. Thus the maps agree on every fiber, hence $f = g$.

For surjectivity, by Lemma 2.2.6 again, any map $f: \Gamma \rightarrow \Gamma'$ of \mathcal{O} -module sheaves induces maps $f_b: E_b \rightarrow E'_b$ on every fiber, which almost shows surjectivity, except that we must show that the resulting map $f = \bigcup_{b \in B} f_b$ is continuous.

This can be checked locally, so let us assume that $E = B \times k^m$ and $E' = B \times k^n$ are trivial vector bundles, and correspondingly, $\Gamma = \mathcal{O}^m$ and $\Gamma' = \mathcal{O}^n$. Then

$$\text{Hom}_{\mathcal{O}}(\Gamma, \Gamma') = \text{Hom}_{\mathcal{O}}(\mathcal{O}^m, \mathcal{O}^n) = \text{Hom}(k^m, \mathcal{O}^n) = \text{map}(-, \text{Hom}_k(k^m, k^n)).$$

Since the induced map on the fibers of Γ and Γ' at b is just evaluation of an element of $\text{map}(-, \text{Hom}_k(k^m, k^n))$ at b , continuity is satisfied.

For essential surjectivity we must show that every finitely generated locally free \mathcal{O} -module sheaf M on B is isomorphic to Γ_p for some vector bundle $p: E \rightarrow B$. Let $\mathcal{U} = \{U_\alpha\}_\alpha$ be an open cover of B such that $M|_{U_\alpha}$ is trivial, i. e. such that there is an isomorphism

$$\phi_\alpha: M|_{U_\alpha} \rightarrow \mathcal{O}_{U_\alpha}^{n_\alpha}.$$

In particular, for every $u \in U_\alpha$, we have a natural homomorphism

$$\bar{\phi}_{\alpha,u}: M(U_\alpha) \rightarrow \bar{M}_u \rightarrow \text{map}(\{b\}, k^{n_\alpha}) = k^{n_\alpha}.$$

2. Vector bundles

Let

$$\tilde{E} = \coprod_{\alpha} k^{n_{\alpha}} \times U_{\alpha} \xrightarrow{\tilde{p}: (x_{\alpha}, y_{\alpha}) \mapsto y_{\alpha}} B.$$

We will construct the total space E of the desired vector bundle by gluing the disjoint summands of \tilde{E} together over all intersections $U_{\alpha\beta}$. Concretely, we define a relation \sim on \tilde{E} by

$$(x_{\alpha}, u_{\alpha}) \sim (x_{\beta}, u_{\beta}) \quad \text{iff} \quad \begin{cases} u_{\alpha} = u_{\beta} \in U_{\alpha\beta} & \text{and} \\ \exists s \in M(U_{\alpha\beta}): \bar{\phi}_{\alpha, u_{\alpha}}(s) = \phi_{\beta, u_{\beta}}(s). \end{cases}$$

Then $E = \tilde{E} / \sim$. Since only points in different components of the disjoint union are identified, we still have local triviality $E|_{U_{\alpha}} \cong k^{n_{\alpha}} \times U_{\alpha}$.

We now define a map of sheaves

$$\Phi: M \rightarrow \Gamma_p$$

by using the gluing condition. For U_{α} , we define

$$\Phi_{\alpha}: M|_{U_{\alpha}} \xrightarrow{\phi_{\alpha}} \mathcal{O}_{U_{\alpha}}^{n_{\alpha}} = \Gamma_{\tilde{p}}|_{U_{\alpha}} \rightarrow \Gamma_p|_{U_{\alpha}}.$$

using the local trivializations ϕ_{α} . To see that these maps glue, we need to verify that

$$\Phi_{\alpha}|_{U_{\alpha\beta}} = \Phi_{\beta}|_{U_{\alpha\beta}}.$$

Thus, let $s \in M(U_{\alpha\beta})$ be a section and $u \in U_{\alpha\beta}$. Then $\Phi_{\alpha}(s)(u) = (\phi_{\alpha, u}(s), u) \sim (\phi_{\beta, u}(s), u) = \Phi_{\beta}(s)(u)$. \square

Remark 2.2.7. The inverse construction of a vector bundle from a sheaf given above depends heavily on the local trivialization and is therefore not functorial. But this is not needed to show that the functor Γ is essentially surjective.

2.3. Bundles as cocycles

Let $p: E \rightarrow B$ be a k -vector bundle and choose an open cover U_{α} of B such that each U_{α} is a trivializing neighborhood, i. e. we so that can choose isomorphisms

$$\phi_{\alpha} \in \text{map}_{U_{\alpha}}(E|_{U_{\alpha}}, k^{n_{\alpha}} \times U_{\alpha}).$$

Now let $U_{\alpha\beta} = U_{\alpha} \cap U_{\beta}$. Then we can compose two such trivializations and obtain an isomorphism

$$\tilde{g}: k^{n_{\alpha}} \times U_{\alpha\beta} \xrightarrow{(\phi_{\alpha}|_{U_{\alpha\beta}})^{-1}} E|_{U_{\alpha\beta}} \xrightarrow{\phi_{\beta}|_{U_{\alpha\beta}}} k^{n_{\beta}} \times U_{\alpha\beta}.$$

Note that $n_{\alpha} = n_{\beta}$ if $U_{\alpha\beta} \neq \emptyset$. Let us assume this. Then since \tilde{g} is a map over B , we can write

$$\tilde{g}(x, u) = (g(u)(x), u) \tag{2.3.1}$$

for some function $g: U_{\alpha\beta} \rightarrow \text{map}(k^{n_\alpha}, k^{n_\beta})$. Furthermore, since \tilde{g} is a linear isomorphism on fibers, we actually have that $g: U_{\alpha\beta} \rightarrow \text{GL}_{n_\alpha}(k)$. Conversely, for any open subset U of B and any map $g: U \rightarrow \text{GL}_n(k)$, we denote by $\tilde{g} \in \text{map}_U(k^n \times U, k^n \times U)$ the map (2.3.1).

Lemma 2.3.2. *Let $p: E \rightarrow B$ be a k -vector bundle with a trivializing open cover $\{U_\alpha\}_\alpha$ and change-of-coordinates maps $g_{\alpha\beta}: U_{\alpha\beta} \rightarrow \text{GL}_{n_\alpha}(k)$ for each pair (α, β) such that $U_{\alpha\beta} \neq \emptyset$. Then we have:*

$$\text{(COC1)} \quad g_{\alpha\alpha} = \text{id}_{U_\alpha};$$

$$\text{(COC2)} \quad g_{\alpha\beta} = g_{\beta\alpha}^{-1};$$

$$\text{(COC3)} \quad g_{\alpha\beta}g_{\beta\gamma}g_{\gamma\alpha} = \text{id}_{U_{\alpha\beta\gamma}}.$$

Proof. Condition (COC2) is actually redundant and follows from (COC1) and (COC3) since

$$\text{id}_{U_{\alpha\beta}} \stackrel{\text{(COC3)}}{=} g_{\alpha\beta}g_{\beta\alpha}g_{\alpha\alpha} \stackrel{\text{(COC1)}}{=} g_{\alpha\beta}g_{\beta\alpha}.$$

For (COC1), $g_{\alpha\alpha} = \phi_\alpha^{-1}\phi_\alpha = \text{id}_{U_\alpha}$. Finally for (COC3),

$$g_{\alpha\beta}g_{\beta\gamma}g_{\gamma\alpha} = (\phi_\alpha^{-1}\phi_\beta)(\phi_\beta^{-1}\phi_\gamma)(\phi_\gamma^{-1}\phi_\alpha) = \text{id}_{U_{\alpha\beta\gamma}}.$$

□

Definition. Let $\mathcal{G} = \{G_n\}_{n \geq 0}$ be a sequence of topological groups and $\mathcal{U} = \{U_\alpha\}_{\alpha \in I}$ an open cover of some space B . Then a *cocycle g for \mathcal{U} with values in $\{G_n\}$* consists of a function

$$n: I \rightarrow \mathbf{N}$$

such that $n_\alpha = n_\beta$ whenever $U_{\alpha\beta} \neq \emptyset$, together with continuous maps

$$g_{\alpha\beta}: U_{\alpha\beta} \rightarrow G_{n_\alpha} \quad (\alpha, \beta \in I)$$

such that (COC1)–(COC3) hold. We denote the set of cocycles for \mathcal{U} with values in \mathcal{G} by $Z_{\mathcal{U}}^1(X, \mathcal{G})$.

A particular kind of cocycle is always easy to construct: given an $n: I \rightarrow \mathbf{N}$ and a collection of maps $c_\alpha: U_\alpha \rightarrow G_{n_\alpha}$, we can define $g_{\alpha\beta}(x) = c_\beta(x)c_\alpha(x)^{-1}$; this obviously satisfies the cocycle conditions. A cocycle of this form is called a *coboundary*. More generally, we say that two cocycles g, g' are *cohomologous* if there is such a c_α such that $g'_{\alpha\beta} = c_\beta g_{\alpha\beta} c_\alpha^{-1}$.

2. Vector bundles

2.3.1. Fiber bundles and principal G -bundles

If vector bundles give rise to cocycles with values in $\{\mathrm{GL}_n(k)\}_{n \geq 0}$, it is natural to ask if there is some geometric origin of cocycles with values in other sequences of topological groups $\{G_n\}_n$.

Definition. Let G be a topological group. A *free and transitive G -space over B* is a space E over B with a G -action $G \rightarrow \mathrm{map}_B(E, E)$ which is free and transitive on each fiber. A map of free and transitive G -spaces over B is a map $f \in \mathrm{map}_B(E, F)$ which is G -equivariant, i. e., for each $\phi \in \mathrm{map}_B(E, E)$, $f \circ (g \cdot \phi) = g \cdot (f \circ \phi) \in \mathrm{map}_B(E, F)$.

A *principal G -bundle over B* is a free and transitive G -space which is locally trivial, i. e. such that every point $x \in B$ has a neighborhood $U \ni x$ such that there exists a G -equivariant isomorphism

$$p^{-1}U \rightarrow U \times G$$

Denote the full subcategory of principal G -bundles over B by $\mathrm{Princ}_G(B)$.

Lemma 2.3.3. *The category $\mathrm{Princ}_G(B)$ is a groupoid, i. e., every morphism is an isomorphism.*

Proof. □

If $\phi: G \rightarrow \mathrm{GL}_n(k)$ is some homomorphism then any principal G -bundle $E \rightarrow B$ gives rise to a vector bundle $E \times_G k^n$, where G acts on k^n through $\mathrm{GL}_n(k)$. In fact, this is an equivalence of categories between principal $\mathrm{GL}_n(k)$ -bundles and n -dimensional vector bundles:

Proposition 2.3.4. *The functor Φ :*

Conversely, for $G = \mathrm{GL}_n(k)$, any vector bundle $E \rightarrow B$ gives rise to a principal G -bundle $\mathrm{Aut}_B(E) \rightarrow B$.

The assignment of a cocycle g to a vector bundle p is not well-defined as it depends both on a choice of trivializing neighborhoods and a choice of trivializations over the latter. The following proposition clarifies, among other things, what happens when we choose different trivializations.

Proposition 2.3.5. *Let $p: E \rightarrow B$ and $p': E' \rightarrow B$ two vector bundles. Let $\{U_\alpha\}_\alpha$ be a cover of B that trivializes both p and p' , and let g and g' be cocycles associated to p and p' , respectively. Then $p \cong p'$ iff and only g and g' are cohomologous.*

Note that one can always find a cover that trivializes both p and p' , for instance, by taking all intersections of trivializing neighborhoods of p with trivializing neighborhoods of p' .

Proof. We will show that “if” part first, so let us assume that

$$g'_{\alpha\beta} = c_\beta g_{\alpha\beta} c_\alpha^{-1} \in \mathrm{map}(U_{\alpha\beta}, G_{n_\alpha})$$

2.3. Bundles as cocycles

for some collection $c_\alpha: U_\alpha \rightarrow \mathrm{GL}_{n_\alpha}(k)$. For $\alpha \in I$, define a map

$$f_\alpha: E_{U_\alpha} \xrightarrow{\phi_\alpha} k^{n_\alpha} \times U_\alpha \xrightarrow{\tilde{c}_\alpha} k^{n_\alpha} \times U_\alpha \xrightarrow{(\phi'_\alpha)^{-1}} E'_{U_\alpha}.$$

As a composition of three linear isomorphisms over U_α , it is an isomorphism of vector bundles over U_α . Furthermore, if $U_{\alpha\beta} \neq \emptyset$, we have that

$$\begin{aligned} f_\beta \circ f_\alpha^{-1} &= (\phi'_\beta)^{-1} \circ \tilde{c}_\beta \circ \phi_\beta \circ (\phi_\alpha)^{-1} \circ \tilde{c}_\alpha^{-1} \circ \phi'_\alpha \\ &= (\phi'_\beta)^{-1} \circ \tilde{c}_\beta \tilde{g}_{\alpha\beta} \tilde{c}_\alpha^{-1} \circ \phi'_\alpha \\ &= (\phi'_\beta)^{-1} \circ \tilde{g}_{\alpha\beta} \circ \phi'_\alpha = \mathrm{id}, \end{aligned}$$

where all maps are understood as their restriction to $U_{\alpha\beta}$. Thus $f_\alpha|_{U_{\alpha\beta}} = f_\beta|_{U_{\alpha\beta}}$ and thus we can glue these functions together to a globally defined isomorphism of vector bundles

$$f: E \rightarrow E', \quad f(x) = f_\alpha(x) \quad \text{if } x \in U_\alpha.$$

Now assume that $f: E \rightarrow E'$ is an isomorphism of vector bundles. Define $c_\alpha: U_\alpha \rightarrow \mathrm{GL}_{n_\alpha}(k)$ by

$$\tilde{c}_\alpha = \phi'_\alpha \circ f \circ \phi_\alpha^{-1}.$$

Then

$$\tilde{c}_\beta \tilde{g}_{\alpha\beta} \tilde{c}_\alpha^{-1} = \phi'_\beta \circ f \circ \phi_\beta^{-1} \circ \phi_\beta \circ \phi_\alpha^{-1} \circ \phi_\alpha \circ f^{-1} \circ (\phi'_\alpha)^{-1} = \phi'_\beta (\phi'_\alpha)^{-1} = \tilde{g}'_{\alpha\beta},$$

hence g and g' are cohomologous. \square

Thus for a chosen trivializing cover, the cocycle of a vector bundle is unique up to cohomology. The following result gives the existence part of the characterization:

Proposition 2.3.6. *Let $\mathcal{U} = \{U_\alpha\}_\alpha$ be an open cover on a space B and $(n_\alpha, g_{\alpha\beta}) \in Z^1_{\mathcal{U}}(B, \{\mathrm{GL}_n(k)\})$. Then there is a vector bundle $p: E \rightarrow B$ and trivializations $\phi_\alpha \in \mathrm{map}_{U_\alpha}(E_{U_\alpha}, k^{n_\alpha} \times U_\alpha)$ whose associated cocycle is (n, g) .*

Proof. Let

$$\tilde{E} = \coprod_{\alpha} k^{n_\alpha} \times U_\alpha \xrightarrow{p: (x_\alpha, y_\alpha) \mapsto y_\alpha} B.$$

We will construct the total space E of the desired vector bundle by gluing the disjoint summands of \tilde{E} together over all intersections $U_{\alpha\beta}$. Concretely, we define a relation \sim on \tilde{E} by

$$(x_\alpha, u_\alpha) \sim (x_\beta, u_\beta) \quad \text{iff} \quad u_\alpha = u_\beta \in U_{\alpha\beta} \text{ and } g_{\alpha\beta}(x_\alpha) = x_\beta.$$

The cocycle conditions (COC1) – (COC3) are equivalent, in this order, to the reflexivity, symmetry, and transitivity of the relation \sim , thus \sim is an equivalence relation, and we define $E = \tilde{E} / \sim$. Since identifications under \sim only occur within a fiber, p factors through a projection map $p: E \rightarrow B$.

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We now define an addition

$$E \times_B E \rightarrow E, \quad ([x_\alpha, b], [y_\alpha, b]) \mapsto [x_\alpha + y_\alpha, b],$$

and a scalar multiplication in an analogous way. To see this is well-defined, observe that

$$[g_{\alpha\beta}(x_\alpha), b] + [g_{\alpha\beta}(y_\alpha), b] = [g_{\alpha\beta}(x_\alpha + y_\alpha), b]$$

since $g_{\alpha\beta}$ is linear. Thus E is a k -vector space over B . Since $g_{\alpha\beta}$ is bijective, \sim identifies distinct points in $k^{n_\alpha} \times U_\alpha$ with distinct points in $k^{n_\beta} \times U_\beta$, hence the map $k^{n_\alpha} \times U_\alpha \hookrightarrow \tilde{E} \rightarrow E$ is injective with image E_{U_α} . We define the local trivialization ϕ_α to be the inverse of this map. The clearly, $g_{\alpha\beta}$ is the change-of-coordinates map associated with ϕ_α and ϕ_β , and the proof is complete. \square

We can thus define a vector bundle up to isomorphism by specifying a cocycle for some cover. However, maps of vector bundles cannot be described in this way, thus we cannot make a category out of the cocycle description for vector bundles.

Example 2.3.7 (Real bundles on \mathbf{S}^1). The circle \mathbf{S}^1 has an open cover $\mathcal{U}_\epsilon = \{U_+, U_-\}$, where $U_+ = \{e^{it} \mid -\pi/2 - \epsilon < t < \pi/2 + \epsilon\}$ and $U_- = \{e^{it} \mid \pi/2 - \epsilon < t < 3\pi/2 + \epsilon\}$. The intersection $U_{+,-}$ consists of two small circle segments centered at i and $-i$.

A real-valued cocycle with respect to this cover is given by a single $g: U_{+,-} \rightarrow \mathrm{GL}_n(\mathbf{R})$. We want to be able to extend g to the boundary of $U_{+,-}$, which might of course not be possible if $\det(g(u)) \rightarrow 0$ as $u \rightarrow \partial U_{+,-}$. But we may restrict g to the smaller cover $\mathcal{U}_{\frac{1}{2}\epsilon} = \{V_+, V_-\}$ without changing the vector bundle. Denote by $V_{\pm i}$ the component of $V_+ \cap V_-$ which contains $\pm i$.

Two cocycles g, g' are cohomologous if there are maps $c_\pm: V_\pm \rightarrow \mathrm{GL}_n(\mathbf{R})$ such that $g'(x) = c_+(x)g(x)c_-(x)^{-1}$ for $x \in U_{+,-}$.

The Lie group $\mathrm{GL}_n(\mathbf{R})$ consists of two connected components, corresponding to the sign of the determinant. We may, without loss of generality, assume that $\det g(x) > 0$ for all $x \in V_i$; if not, we change g cohomologously by choosing constant maps c_+ and c_- of determinant 1 and -1 , respectively.

Now choose $c_+: V_+ \rightarrow \mathrm{GL}_n(\mathbf{R})$ such that $c_+|_{V_i} = g|_{V_i}^{-1}$ and $c_+|_{V_{-i}} = \mathrm{id}$. This is possible by the connectedness of the space of matrices of positive determinant. Similarly, choose $c_-: V_- \rightarrow \mathrm{GL}_n(\mathbf{R})$ such that $c_-|_{V_{-i}} = g|_{V_{-i}}$ and $c_-|_{V_i}$ either constant with value

the identity matrix, or constant with value $I_- = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \end{pmatrix}$, depending on the

determinant of $g|_{V_{-i}}$. Then $g' = c_+gc_-^{-1}$ has the following properties:

- g' is cohomologous to g ;
- $g'(x) = \mathrm{id}$ for $x \in V_{-i}$;
- $g'(x) = \mathrm{id}$ or $g'(x) = I_-$ for $x \in V_i$.

The n -dimensional vector bundle associated with g is either the n -dimensional trivial bundle or the Möbius bundle plus an $(n-1)$ -dimensional trivial bundle. (What it means to add vector bundles will be explained in more detail in Section 2.4.2.)

This does not quite lead to a classification of all real vector bundles over \mathbf{S}^1 since we only consider bundles which are trivial on half-circles.

Exercise 3. Classify all vector bundles on \mathbf{S}^1 for arbitrary coverings by trivializing neighborhoods. Tip: use compactness of \mathbf{S}^1 to reduce to the case where the cover consists of finitely many overlapping circle intervals.

2.3.2. Cocycles as functors

It is useful both conceptually and for what comes later to phrase the definition of a cocycle in the context of *topological categories*. A topological category, or more precisely, a small category object in topological spaces, is an ordinary category where the objects form a set (rather than a proper class) and where both objects and morphism sets carry a topology such that all the structure maps are continuous. We make this more precise in the following definition.

Definition. Let C be a category, such as the category of topological spaces, that has fiber products. A *category object* \mathcal{C} in C is a pair of objects $(\text{ob } \mathcal{C}, \text{mor } \mathcal{C})$ of C together with morphisms

- a *unit* $u: \text{ob } \mathcal{C} \rightarrow \text{mor } \mathcal{C}$;
- *source* and *target* maps $s, t: \text{mor } \mathcal{C} \rightarrow \text{ob } \mathcal{C}$;
- a composition map $\mu: \text{mor } \mathcal{C} \times_{\text{ob } \mathcal{C}} \text{mor } \mathcal{C} \rightarrow \text{mor } \mathcal{C}$, where the fiber product denotes the pullback of the diagram

$$\begin{array}{ccc} & \text{mor } \mathcal{C} & \\ & \downarrow t & \\ \text{mor } \mathcal{C} & \xrightarrow{s} & \text{ob } \mathcal{C}. \end{array}$$

These morphisms have to satisfy the following axioms:

(Associativity) $\mu(\mu(f, g), h) = \mu(f, \mu(g, h))$ for $(f, g, h) \in \text{mor } \mathcal{C} \times_{\text{ob } \mathcal{C}} \text{mor } \mathcal{C} \times_{\text{ob } \mathcal{C}} \text{mor } \mathcal{C}$;

(Identities) $s \circ u = t \circ u = \text{id}_{\text{ob } \mathcal{C}}$.

(Unitality) $\mu(f, u \circ s) = f = \mu(u \circ t, f)$ for all $f \in \text{mor } \mathcal{C}$;

A *functor* F between category objects \mathcal{C} and \mathcal{D} in C consists of two morphisms in C ,

$$F_0: \text{ob } \mathcal{C} \rightarrow \text{ob } \mathcal{D} \quad \text{and} \quad F_1: \text{mor } \mathcal{C} \rightarrow \text{mor } \mathcal{D},$$

2. Vector bundles

that are compatible with the unit, source, target, and composition maps. (The reader may spend a minute to think about this compatibility in the case of contravariant functors.)

A natural transformation $h: \mathcal{C} \rightarrow \mathcal{D}$ is a functor

$$h: \mathcal{C} \times [1] \rightarrow \mathcal{D},$$

where $[1]$ denotes the category with two objects 0, 1 and exactly one morphism $0 \rightarrow 1$ besides the identity morphisms. We say that the natural transformation goes from the functor $h_0: \mathcal{C} \cong \mathcal{C} \times \{0\} \rightarrow \mathcal{D}$ to the functor $h_1: \mathcal{C} \cong \mathcal{C} \times \{1\} \rightarrow \mathcal{D}$.

We call a category object in topological spaces just a *topological category*.

Note that a category object in sets is just an ordinary category whose objects form a set. (This is called a *small category*.)

A special case of a topological category is a category \mathcal{C} when $\text{ob } \mathcal{C}$ is just a discrete set (but the morphism sets do carry a nontrivial topology). Some authors call this a topological category, rather than our more general definition. An unambiguous name for this kind of category is a *category enriched in topological spaces*.

Example 2.3.8. If G is a Lie group, such as $\text{GL}_n(k)$ for $k = \mathbf{R}$ or \mathbf{C} , then we can consider G as a topological category with one object $*$ and $\text{mor} = \text{Hom}(*, *) = G$. We will not distinguish in notation between the group G and the one-object category thus defined.

This is the one-object case of the following more general construction:

Example 2.3.9. If $\{G_n\}_{n \geq 0}$ is a sequence of Lie groups, we can define a topological category \mathcal{G} with objects \mathbf{N} and $\text{mor } \mathcal{G} = \coprod_{n \geq 0} G_n$, where $G_n = \text{Hom}_{\mathcal{G}}(n, n)$. This is an example of a topological *groupoid*, i. e. a category where every morphism is invertible.

Example 2.3.10. Let $\mathcal{U} = \{U_\alpha\}_{\alpha \in I}$ be an open cover of a space X , and let $\mathbf{U} = \coprod_{\alpha \in I} U_\alpha$. Define the map $p: \mathbf{U} \rightarrow X$ to be the standard inclusion on every summand, so that in total, p is an open surjective map. The pair $(\mathbf{U}, \mathbf{U} \times_X \mathbf{U})$ becomes a topological category if we define

- $u: \mathbf{U} \rightarrow \mathbf{U} \times_X \mathbf{U}$ by $u(x) = (x, x)$;
- $s(x, y) = x$ and $t(x, y) = y$;
- $\mu: (\mathbf{U} \times_X \mathbf{U}) \times_{\mathbf{U}} (\mathbf{U} \times_X \mathbf{U}) = \mathbf{U} \times_X \mathbf{U} \times_X \mathbf{U} \rightarrow \mathbf{U} \times_X \mathbf{U}$ by $(x, y, z) \mapsto (x, z)$.

This is in fact a groupoid as well. We denote it by \mathbf{U} .

Proposition 2.3.11. Let \mathcal{U} be an open cover of X with associated groupoid \mathbf{U} , and \mathcal{G} the groupoid associated to a sequence of Lie groups $\{G_n\}_{n \geq 0}$. Assume that every set in the open cover \mathcal{U} is connected. Then the natural map

$$\text{Fun}(\mathbf{U}, \mathcal{G}) \rightarrow Z_{\mathcal{U}}^1(X, \mathcal{G}), \quad F \mapsto (n, g) \quad \text{where } n_\alpha = F_0|_{U_\alpha}, \quad g_{\alpha\beta} = F_1|_{U_{\alpha\beta}}$$

is a bijection.

Furthermore, two cocycles are cohomologous if and only if their associated functors are naturally isomorphic.

Proof. Note that $F_0: \coprod_{\alpha \in I} U_\alpha \rightarrow \mathbf{N}$ is continuous, hence constant on connected components. Since U_α was assumed connected, this means that $F_0|_{U_\alpha} = n_\alpha$ is constant. If $U_{\alpha\beta} \neq \emptyset$ then there is some morphism in \mathbf{U} with source in U_α and target in U_β . Thus this morphism must have an image in \mathcal{G} , i. e. a morphism from n_α to n_β . Since \mathcal{G} only has endomorphisms, we must have $n_\alpha = n_\beta$.

We now verify the cocycle axioms. The functor F has to map identity morphisms to identity morphisms. The identity morphism on $x \in \text{ob } \mathbf{U}$, say $x \in U_\alpha$, is $x \in U_{\alpha\alpha} \subset \mathbf{U} \times_X \mathbf{U}$. Thus we must have that its image $g_{\alpha\alpha} = \text{id}$ in \mathcal{G} as well, proving **(COC1)**. For **(COC2)**, note that the inverse of $x \in U_{\alpha\beta} \subseteq \mathbf{U} \times_X \mathbf{U}$ is $x \in U_{\beta\alpha}$. The functor must preserve inverses, hence $g_{\alpha\beta} = g_{\beta\alpha}^{-1}$. Finally, a functor must also satisfy $F_1(\mu(f, g)) = \mu(F_1(f), F_1(g))$. In our case, this is

$$g_{\alpha\gamma} = g_{\alpha\beta} g_{\beta\gamma}$$

Using **(COC2)**, this gives **(COC3)**.

Conversely, any cocycle defines a functor as described above.

Now let $h: \mathbf{U} \rightarrow \mathcal{G}$ be a natural transformation from a functor F to a functor F' , and that (n, g) and (n', g') are the cocycles associated to F and F' , respectively. Since $(x, 0 \rightarrow 1)$ is a morphism in $\mathbf{U} \times [1]$ for any $x \in U_\alpha$, there must be a morphism $h(x, 0 \rightarrow 1)$ between n_α and n'_α in \mathcal{G} , so $n_\alpha = n'_\alpha$ for all α .

Now define $c_\alpha: U_\alpha \rightarrow G_{n_\alpha}$ by $c_\alpha = h|_{U_\alpha}$. We want to show that

$$g'_{\alpha\beta} = c_\beta g_{\alpha\beta} c_\alpha^{-1} \in G_{n_\alpha} \quad \text{for all } \alpha, \beta \in I \text{ such that } U_{\alpha\beta} \neq \emptyset.$$

This can be reformulated as $g'_{\alpha\beta} c_\alpha = c_\beta g_{\alpha\beta}$. This follows from the functoriality of h because the above identity is the image under h of the true identity

$$(x \in U_{\alpha\beta}, 1 \rightarrow 1) \circ (x \in U_{\alpha\alpha}, 0 \rightarrow 1) = (x \in U_{\beta\beta}, 0 \rightarrow 1) \circ (x \in U_{\alpha\beta}, 0 \rightarrow 0) \text{ in } \mathbf{U} \times [1].$$

Conversely, if (n, g) and (n', g') are cohomologous by $c_\alpha: U_\alpha \rightarrow G_{n_\alpha}$ then $h(x \in U_\alpha, 0) = h(x \in U_\alpha, 1) = n_\alpha = n'_\alpha$ defines the object part of a natural transformation. On morphisms of the form $(x \in U_{\alpha\alpha}, 0 \rightarrow 1)$, $h = \coprod_\alpha c_\alpha: \mathbf{U} \rightarrow \mathcal{G}$. \square

We will pursue the cocycle characterization of vector bundles further in Chapter 4 and also clarifying the terms “cocycle”, “coboundary”, and “cohomologous.”

2.4. Operations on bundles

In this section we study the structure of the set of k -vector bundles on a space X and how to build new vector bundles from existing ones, mimicking standard constructions in linear algebra.

2. Vector bundles

2.4.1. Pullbacks and pushforwards

Given a vector bundle $p: E \rightarrow B$ and a map $f: B' \rightarrow B$, the fiber product

$$f^*E = E \times_B B' = \{(e, b) \in E \times B' \mid f(b) = p(e)\} \xrightarrow{(e, b) \mapsto b} B'$$

becomes a vector bundle f^*p over B' , called the *pullback* of p along f . That it is locally trivial is clear since $f^{-1}(U)$ is a trivializing neighborhood for f^*p if U is a trivializing neighborhood for p . This construction is functorial in the sense that $g^*f^*(p) \cong (f \circ g)^*(p)$ for maps $B'' \xrightarrow{g} B' \xrightarrow{f} B$.

In terms of \mathcal{O}_B -module sheaves, there are pushforward and pullback functors defined as follows. First, given any sheaf F on B' , we can define a sheaf f_*F on B by

$$(f_*F)(U) = F(f^{-1}U) \quad (U \subset B \text{ open});$$

this maps sheaves of algebras to sheaves of algebras, and in particular, it makes $f_*\mathcal{O}_{B'}$ a sheaf of rings on B . Moreover, there is a natural map of sheaves of rings

$$\mathcal{O}_B \rightarrow f_*\mathcal{O}_{B'}; \quad \mathcal{O}_B(U) = \text{map}(U, \mathbf{R}) \xrightarrow{\phi \mapsto \phi \circ f} \text{map}(f^{-1}U, \mathbf{R}) = (f_*\mathcal{O}_{B'})(U). \quad (2.4.1)$$

Given a $\mathcal{O}_{B'}$ -module sheaf F , the pushforward f_*F is naturally an $f_*\mathcal{O}_{B'}$ -module sheaf and hence, by (2.4.1), a \mathcal{O}_B -module sheaf.

However, for vector bundles F , f_*F is not usually a vector bundle, i. e., the local freeness condition is violated. For instance the pushforward of the constant sheaf \mathbf{R} along the inclusion $\{0\} \hookrightarrow \mathbf{R}$ is the so-called skyscraper sheaf S with $S(U) = \mathbf{R}$ if $0 \in U$ and $S(U) = 0$ otherwise. In terms of vector spaces over \mathbf{R} , this is precisely Example 2.1.5.

For the pushforward along f to preserve all vector bundles, it is necessary and sufficient that the map (2.4.1) makes $f_*\mathcal{O}_{B'}$ into a vector bundle, i. e., $\text{map}(f^{-1}U, \mathbf{R}) \cong \text{map}(U, \mathbf{R})^n$ for some n and sufficiently small open sets U . But that means that $f^{-1}U \cong U \times \{1, \dots, n\}$, and thus that B' is a finite covering space of B . We have thus proved:

Theorem 2.4.2. *If $f: B' \rightarrow B$ is a finite covering space map of degree n then f_* maps vector bundles of dimension k on B' to vector bundles of dimension kn on B .*

The sheaf-theoretic formulation of the pullback of a vector bundle is arguably most easily defined as the sheaf of sections of the pullback bundle associated to the sheaf, i. e., using the equivalence between locally free \mathcal{O}_B -module sheaves and vector bundles.

Example 2.4.3. Let $f: \mathbf{S}^1 \rightarrow \mathbf{S}^1$ be the map of degree 2 and $\mu: E \rightarrow \mathbf{S}^1$ the Möbius bundle. I claim that $f^*\mu$ is the trivial line bundle on \mathbf{S}^1 . Let us think of the Möbius bundle as defined by $E = \mathbf{R} \times [0, 1] \sim$, where $(x, 0) \sim (-x, 1)$. Then

$$f^*E \cong (\mathbf{R} \times \left[0, \frac{1}{2}\right] \sqcup \mathbf{R} \times \left[\frac{1}{2}, 1\right]) / \sim,$$

where $(x, \frac{1}{2})_1 \sim (-x, \frac{1}{2})_2$ and $(x, 0)_1 \sim (-x, 1)_2$. Here the subscripts denote whether the subscripted pair lies in the first or in the second disjoint summand. This is a cylinder with two half-twists, thus trivial. In fact, the map

$$\mathbf{R} \times [0, 1] / \{0, 1\} \rightarrow f^*E, \quad (x, t) \mapsto \begin{cases} (x, t)_1; & t \leq \frac{1}{2} \\ (-x, t)_2; & t \geq \frac{1}{2} \end{cases}$$

is an isomorphism over B .

2.4.2. Whitney sums

The generalization of the direct sum $V \oplus W$ of k -vector spaces is the Whitney sum of vector bundles.

Definition. Given two vector spaces over B , $p: E \rightarrow B$, and $p': E' \rightarrow B$, we define the (Whitney) sum $E \oplus E' \rightarrow B$ to be the vector space over B given by

$$E \times_B E' \xrightarrow{(e, e') \mapsto p(e)=p'(e')} B.$$

Lemma 2.4.4. *The Whitney sum of vector bundles E, E' is a vector bundle, and if $\dim E = m$ and $\dim E' = n$ then $\dim(E \oplus E') = m + n$.*

Proof. We only need to check the local triviality condition. Let $U \subset X$ be a trivializing neighborhood for both p and p' . Then

$$(E \times_B E')_U = E_U \times_U E'_U \xrightarrow{\cong} (U \times k^m) \times_U (U \times k^n) \cong U \times k^{m+n}.$$

□

Example 2.4.5. We will show that for the Möbius bundle μ on \mathbf{S}^1 of Example 2.1.2, the Whitney sum $2\mu = \mu \oplus \mu$ is a trivial bundle. For that, we define a global trivialization

$$\mathbf{R}^2 \times \mathbf{S}^1 \rightarrow \mu \oplus \mu, \quad (x, y, t) \mapsto (x \cos \pi t + y \sin \pi t, -x \sin \pi t + y \cos \pi t),$$

where, as before, \mathbf{S}^1 is considered as the quotient $[0, 1] / \{0, 1\}$.

An alternative definition of the Whitney sum in terms of locally free \mathcal{O}_B -module sheaves is implicit in the following Lemma:

Lemma 2.4.6. *For two vector bundles E, E' over B , we have an isomorphism of sheaves $\Gamma_{E \oplus E'} \cong \Gamma_E \oplus \Gamma_{E'}$.*

Proof.

$$\Gamma_{E \oplus E'}(U) = \text{map}_U(U, E_U \times_U E'_U) \cong \text{map}_U(U, E_U) \times \text{map}_U(U, E'_U) \cong \Gamma_E(U) \times \Gamma_{E'}(U).$$

□

Exercise 4. Let $f: \mathbf{S}^1 \rightarrow \mathbf{S}^1$ be the map $z \mapsto z^2$ of degree 2, and μ the Möbius bundle on \mathbf{S}^1 . Then $f_*\mu$ is isomorphic to the Whitney sum $\mathbf{R} \oplus \mu$ of a trivial line bundle and the Möbius bundle over \mathbf{S}^1 .

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2.4.3. Kernels and Cokernels*

Let $f: E \rightarrow E'$ be a morphism of vector bundles $E \xrightarrow{p} B$, $E' \xrightarrow{p'} B$. Then we can naively define:

$$\ker f = \{x \in E \mid f(x) = s'(p(x))\} \quad \text{and} \quad \text{coker } f = E' / \sim,$$

where $x \sim y$ iff $p'(x) = p'(y)$ and $x - y \in \text{im } f$. Since x and y are in the same fiber by the first condition, the expression $x - y$ in the second expression is well-defined. Since both are fiberwise kernels and cokernels of linear maps, it is clear that $\ker f$ and $\text{coker } f$ are vector spaces over B .

Warning 2.4.7. These constructions of $\ker f$ and $\text{coker } f$ are in general not locally trivial, so it is **not** a vector bundle. For instance, let $E = E' = \mathbf{R} \times \mathbf{R}$ be trivial bundles over \mathbf{R} , and define

$$f: E \rightarrow E'; \quad f(x, b) = (bx, b).$$

Then both $\ker f$ and $\text{coker } f$ are isomorphic to the vector space over B of Example 2.1.5, which is not locally trivial because it is one-dimensional over $b = 0$ and zero-dimensional everywhere else.

Exercise 5. The spaces $\ker f$ and $\text{coker } f$ are vector bundles over B if f has locally constant rank.

2.4.4. Hom bundles

Let M and N be vector bundles over B from the sheaf point of view. Define a new sheaf $\text{Hom}(M, N)$ by

$$\text{Hom}(M, N)(U) = \text{Hom}_{\text{Mod}_{\mathcal{O}_U}}(M|_U, N|_U).$$

This is a presheaf by restriction, and the gluing condition is clearly satisfied since M and N are sheaves. Moreover, $\text{Hom}_{\text{Mod}_{\mathcal{O}_U}}(M|_U, N|_U)$ is an $\mathcal{O}(U)$ -module by the restriction map $\mathcal{O}(U) \rightarrow \mathcal{O}_U$ from the constant presheaf to \mathcal{O}_U . It remains to show local freeness. For this we may assume that $M = \mathcal{O}_B^n$ and $N = \mathcal{O}_B^m$ since M and N are locally free. But then

$$\text{Hom}_{\text{Mod}_{\mathcal{O}_U}}(M|_U, N|_U) = \text{Hom}_{\text{Mod}_{\mathcal{O}_U}}(\mathcal{O}_U^m, \mathcal{O}_U^n) = \text{Hom}_k(k^m, \mathcal{O}_U^n),$$

which is free over \mathcal{O}_U of dimension mn .

Note that a global section of $\text{Hom}(M, N)$ is precisely a morphism of vector bundles $M \rightarrow N$. Thus the Hom bundle is an internal homomorphism object in $\text{Vect}(B)$.

A particular case is the bundle

$$M^* = \text{Hom}(M, \mathcal{O}_B),$$

called the dual vector bundle, whose fibers are the dual vector spaces of the fibers of M .

2.4.5. Tensor bundles

The previous constructions give a pattern to how one should define the tensor product $M \otimes N$ of two vector bundles. But instead of treating each such construction separately, we will now develop a general method of lifting functors from vector spaces to vector bundles.

Definition. An (p, q) -ary continuous functor of k -vector spaces is a functor $F: (\text{Vect}_k)^p \times (\text{Vect}_k^{\text{op}})^q \rightarrow \text{Vect}_k$ from $(p + q)$ -tuples of finite-dimensional k -vector spaces to finite-dimensional k -vector spaces which is continuous in the sense that for $V_1, \dots, V_{p+q}, W_1, \dots, W_{p+q} \in \text{Vect}_k$,

$$\begin{aligned} \text{Hom}_k(V_1, W_1) \times \dots \times \text{Hom}_k(V_p, W_p) \times \text{Hom}_k(W_{p+1}, V_{p+1}) \times \dots \times \text{Hom}_k(W_{p+q}, V_{p+q}) \\ \xrightarrow{F} \text{Hom}_k(F(V_1, \dots, V_{p+q}), F(W_1, \dots, W_{p+q})) \end{aligned}$$

is continuous, where the sets $\text{Hom}_k(V, W)$ carry the usual finite-dimensional vector space topology inherited from k .

Proposition 2.4.8. *Given any (p, q) -ary continuous functor F of k -vector spaces, there is an induced functor*

$$F: \text{Vect}_k(B)^p \times (\text{Vect}_k(B)^{\text{op}})^q \rightarrow \text{Vect}_k(B)$$

which restricts to F on each fiber.

Proof. Let E_1, \dots, E_{p+q} be vector bundles on B . Define

$$F(E_1, \dots, E_{p+q}) = \coprod_{b \in B} F((E_1)_b, (E_2)_b, \dots, (E_{p+q})_b).$$

Of course, we don't want the disjoint union topology on this space over B , but the construction is functorial and restricts to F on each fiber.

For the correct topology around $b \in B$, choose a trivializing neighborhood U containing b for all E_i at once. (Since there are finitely many, this exists.) Let $\phi_i: E_i \rightarrow k^{n_i} \times U$ be trivializations for E_i . Let $\phi_{b,i}: k^{n_i} \rightarrow (E_i)_b$ be the restriction of ϕ_i to the fiber over b . Now define a bijection

$$\Phi: F(k^{n_1}, \dots, k^{n_{p+q}}) \times U \rightarrow F(E_1, \dots, E_{p+q})|_U$$

by

$$\Phi(y, b) = T(\phi_{b,1}^{-1}, \dots, \phi_{b,p}^{-1}, \phi_{b,p+1}, \dots, \phi_{b,p+q})(y).$$

We define a subset V of $F(E_1, \dots, E_{p+q})|_U$ to be open iff $\Phi^{-1}(V)$ is open.

To see that this does not lead to conflicting definitions of open sets on intersections $U \cap U'$, note that the map

$$F(k^{n_1}, \dots, k^{n_{p+q}}) \times (U \cap U') \xrightarrow{\Phi} F(E_1, \dots, E_{p+q})|_{U \cap U'} \xrightarrow{\Phi'} F(k^{n_1}, \dots, k^{n_{p+q}})$$

is continuous because it is F applied to a product of (continuous) change-of-coordinate maps. \square

2. Vector bundles

We are now in a position to define the tensor product $E \otimes E'$ of two vector bundles by applying Proposition 2.4.8 to the $(2, 0)$ -ary functor $- \otimes_k -$.

Lemma 2.4.9. *For any line bundle E , $E \otimes E^* \cong k \times B$, the trivial bundle.*

Proof. The evaluation map $\text{ev}: V \otimes V^* \xrightarrow{(v \otimes \phi) \mapsto \phi(v)} k$ on vector spaces induces a map $E \otimes E^* \rightarrow k \times B$ of vector bundles. If V is one-dimensional then ev is an isomorphism, thus so is the induced map on line bundles. \square

It follows that the set of isomorphism classes of line bundles on a space B form a group with unit $k \times B$, called the *Picard group* $\text{Pic}(B)$ of line bundles on B .

Example 2.4.10. By Example 2.3.7 and Exercise 3, $\text{Pic}(\mathbf{S}^1) \cong \mathbf{Z}/2\mathbf{Z}$, generated by the Möbius bundle.

2.4.6. Tensor, symmetric, and exterior powers

The functor $T^n: \text{Vect}_k \rightarrow \text{Vect}_k$ given by $V \mapsto V^{\otimes n} = V \otimes_k V \otimes_k \cdots \otimes_k V$ is continuous and $(1, 0)$ -ary. A homomorphism $f: V \rightarrow W$ induces a homomorphism $f^{\otimes n}: V^{\otimes n} \rightarrow W^{\otimes n}$. It is not an additive functor if $n \neq 1$ because, for instance, $T(f + g) = f \otimes f + f \otimes g + g \otimes f + g \otimes g \neq T(f) + T(g)$, but this is not required in order to apply Proposition 2.4.8. We thus get an induced functor

$$T^n: \text{Vect}_k(B) \rightarrow \text{Vect}_k(B),$$

called the n th tensor power functor. This functor has an important subfunctor and an equally important quotient functor.

The symmetric group Σ_n on n letters acts linearly on the functor $\text{Sym}^n: \text{Vect}_k \rightarrow \text{Vect}_k$ by permuting the tensor factors: if $\sigma \in \Sigma_n$ and $v = v_1 \otimes \cdots \otimes v_n \in V^{\otimes n}$ then $\sigma.v = v_{\sigma(1)} \otimes \cdots \otimes v_{\sigma(n)}$. Since every element in $V^{\otimes n}$ is a linear combination of elementary tensors like v , this defines an action on all of $V^{\otimes n}$, which is also natural with respect to maps $V \rightarrow W$.

We define a subfunctor of T^n by

$$\text{Sym}^n(V) = \{v \in T^n(V) \mid \sigma.v = v \text{ for all } \sigma \in \Sigma_n\},$$

called the n th symmetric power of V , and a quotient functor

$$\bigwedge^n(V) = T^n(V) / (v - \sigma.v \mid \sigma \in \Sigma_n),$$

called the n th exterior power of V . Of course it suffices to restrict to permutations σ which are transpositions since those generate all of Σ_n . The latter definition is actually only correct if $\text{char}(k) \neq 2$, which need not concern us at the moment since we are mostly concerned with $k = \mathbf{R}$ and $k = \mathbf{C}$. The following exercise contains the “correct” definition.

Exercise 6. Define $I = \langle v_1 \otimes \cdots \otimes v_n \in T^n(V) \mid v_i = v_j \text{ for some } i \neq j \rangle$. Show that I is a sub-vector space of $T^n(V)$ and that

$$T^n(V)/I \cong \bigwedge^n(V)$$

as long as $\text{char}(k) \neq 2$.

The equivalence class of an elementary tensor $v_1 \otimes \cdots \otimes v_n$ in $\bigwedge^n V$ is denoted by $v_1 \wedge \cdots \wedge v_n$.

Both functors Sym^n and \bigwedge^n are continuous and $(1, 0)$ -ary, so they induce corresponding constructions on $\text{Vect}_k(B)$.

2.4.7. The determinant line bundle

If V is a vector space of dimension n . Choose a basis v_1, \dots, v_n of V . Then $\bigwedge^k(V)$ has dimension $\binom{n}{k}$: for any k -element subset $\{i_1 < \cdots < i_k\}$ of $\{1, \dots, n\}$, the element $v_{i_1} \wedge \cdots \wedge v_{i_k}$ is a basis vector for $\bigwedge^k(V)$. In particular, $\bigwedge^n(V)$ is one-dimensional. An isomorphism with k is given by

$$d: \bigwedge^n(V) \xrightarrow{v_1 \wedge \cdots \wedge v_n \mapsto \det(v_1, \dots, v_n)} k,$$

where the determinant is to be understood as the determinant of the square matrix with columns v_i .

Now if $V \in \text{Vect}_k^n(B)$ is an n -dimensional vector bundle, $\bigwedge^n(V)$ is a line bundle, called the *determinant line bundle* of V and denoted by $\det(V)$.

The map d of course depends on the choice of basis. If $k = \mathbf{R}$ then in fact, its sign only depends on the orientation of the basis. We can therefore *define* an orientation of a real vector space V as a choice of isomorphism $\mathbf{R} \rightarrow \bigwedge^n V$ up to scaling by positive numbers.

Definition. An n -dimensional real vector bundle $V \in \text{Vect}_{\mathbf{R}}^n(B)$ is *orientable* if $\det(V)$ is the trivial line bundle. An *orientation* of $V \in \text{Vect}_{\mathbf{R}}^n(B)$ is an isomorphism of $\det(V)$ with $B \times \mathbf{R}$ up to scaling with positive functions.

Thus a line bundle is orientable if and only if it is trivial; in particular, the Möbius bundle of Example 2.1.2 and the tautological bundles $\mathcal{O}(-1)$ on $\mathbf{R}P^n$ of Example 2.1.4 are not orientable.

2.5. Tangent and normal bundles

Many important vector bundles have their natural home on manifolds rather than arbitrary topological spaces. The most important one is probably the tangent bundle of a smooth manifold. We briefly recall the definition of a manifold, but the reader should consult other sources for a more in-depth treatment.

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Definition. A topological space M is called a (topological, real) manifold if it is Hausdorff, its topology has a countable basis (it is “second-countable”), and every point has a neighborhood homeomorphic to \mathbf{R}^n for some n .

We now return to the point of view of Section 2.2, where we thought of a vector bundle on a space B as a locally finite-dimensional free sheaf of \mathcal{O}_B -modules.

2.5.1. Smooth manifolds

Definition. A ring R is called *local* if it possesses a unique maximal ideal, which we will denote by R_+ in these notes. A *morphism of local rings* is a ring morphism $f: R \rightarrow S$ such that $f(R_+) \subseteq S_+$.

Example 2.5.1. Fields are local rings, as their unique maximal ideal is (0) . The ring of integers is not local since (p) is a maximal ideal for every prime p , but the ring $\mathbf{Z}_{(p)}$ of integers localized at p is local with maximal ideal (p) .

The ring C_0^0 of germs of continuous functions $\mathbf{R}^n \rightarrow \mathbf{R}$ at 0 is local with maximal ideal the ideal of germs which vanish at 0. This is true because the quotient ring $C_0^0/(C_0^0)_+$ is isomorphic with \mathbf{R} . Similarly, the rings C_0^n of germs at 0 of n -fold continuously differentiable functions, C_0^∞ of smooth (arbitrarily often differentiable) functions, C_0^ω of analytic functions, and C

Definition. A sheaf F of rings on a space X is called a *local sheaf of rings* if all stalks F_x , for $x \in X$, are local rings, i. e. rings possessing a unique maximal ideal, which we denote by $(F_x)_+$. A space with a local sheaf of rings on it is called a *locally ringed space*.

A morphism of locally ringed spaces $(X, \mathcal{O}_X) \rightarrow (Y, \mathcal{O}_Y)$ consists of a map $f: X \rightarrow Y$ together with a morphism of local sheaves of rings on Y , $\tilde{f}: \mathcal{O}_Y \rightarrow f_*\mathcal{O}_X$.

Note that a local sheaf of rings is not the same as a sheaf of local rings, i. e. a sheaf F of rings such that $F(U)$ is local for all $U \in \text{Open}(X)$. This would preclude C^0 from being an example.

In sheaf-theoretic terms, one could say that a manifold is a (second countable Hausdorff) space M together with a local sheaf of \mathbf{R} -algebras C^0 such that the locally ringed space (M, C^0) is locally isomorphic to (\mathbf{R}^n, C^0) for some n . That sounds like unwarranted complexity since the original definition just required M to be locally homeomorphic with \mathbf{R}^n , without the need to refer to sheaves. Indeed, in this case the additional data of local isomorphisms

$$\tilde{f}: C_{\mathbf{R}^n}^0 \rightarrow f_*C_U^0$$

just specifies an isomorphism of the sheaf C_U^0 with the sheaf of continuous functions on U . However, this suggests a viable definition of a smooth (or C^k -) manifold. Although the definition would make perfect sense, we will ignore C^k -manifolds and just consider smooth ($=C^\infty$ -) manifolds.

Definition. A *smooth structure* on a space M is a local sheaf of \mathbf{R} -algebras C^∞ on M , called the *structure sheaf*, such (M, C^∞) is locally isomorphic, as a locally ringed

2.5. Tangent and normal bundles

space, to (\mathbf{R}^n, C^∞) for some n . A *smooth manifold* is a second-countable Hausdorff space together with a smooth structure.

A smooth map $M \rightarrow N$ between smooth manifolds is a morphism of locally ringed spaces.

A more classical definition is via charts and atlases, and we will now show that these are equivalent.

Definition. Let M be a second-countable Hausdorff space. A *chart* on M is a pair (U, ϕ) consisting of an open set $U \subset M$ and a homeomorphism $\phi: U \rightarrow \mathbf{R}^n$, for some $n \geq 0$. An *atlas* is a collection $(U_\alpha, \phi_\alpha)_{\alpha \in I}$ such that the U_α cover M . An atlas is *smooth* if for each $\alpha, \beta \in I$ such that $U_{\alpha\beta} \neq \emptyset$, the map

$$g_{\alpha\beta}: \phi_\alpha(U_{\alpha\beta}) \xrightarrow{\phi_\alpha^{-1}} U_{\alpha\beta} \xrightarrow{\phi_\beta} \phi_\beta(U_{\alpha\beta}) \quad (2.5.2)$$

is a diffeomorphism between open subsets of \mathbf{R}^n .

Two smooth atlases $(U_\alpha, \phi_\alpha)_{\alpha \in I}$ and $(V_\beta, \psi_\beta)_{\beta \in J}$ are *equivalent* if for every pair (α, β) such that $W = U_\alpha \cap V_\beta \neq \emptyset$, the map

$$\phi_\alpha(W) \xrightarrow{\phi_\alpha^{-1}} W \xrightarrow{\psi_\beta} \psi_\beta(W)$$

is a diffeomorphism.

A map $f: M \rightarrow N$ of smooth manifolds is smooth if for every point $x \in M$ such that (U, ϕ) is a chart in M with $x \in U$ and (V, ψ) is a chart in N with $f(U) \subset V$, the composite

$$\mathbf{R}^n \xrightarrow{\phi^{-1}} U \xrightarrow{f} V \xrightarrow{\psi} \mathbf{R}^m$$

is smooth.

Theorem 2.5.3. *Every smooth manifold has a smooth atlas, and that atlas is unique up to equivalence. Conversely, an equivalence class of smooth atlases gives rise to a unique smooth structure.*

Proof. We begin by constructing a smooth atlas from a manifold M with smooth structure C^∞ .

Let $\mathcal{U} = \{U_\alpha\}_{\alpha \in I}$ be the set of all open subsets of M over which there is a local isomorphism $\Phi_\alpha: C^\infty|_{U_\alpha} \rightarrow C^\infty_{\mathbf{R}^n}$. By assumption, \mathcal{U} is a cover of M . Underlying the morphism Φ_α there is a homeomorphism $\phi_\alpha: U_\alpha \rightarrow \mathbf{R}^n$, which gives M the structure of a manifold. To see that the coordinate change functions $g_{\alpha\beta}$ of (2.5.2) are smooth, observe that they are covered by isomorphisms of local sheaves of rings

$$\tilde{g}_{\alpha\beta}: C^\infty_{\phi_\beta(U_{\alpha\beta})} \rightarrow (\phi_\beta)_* C^\infty|_{U_{\alpha\beta}} \rightarrow (\phi_\beta \circ \phi_\alpha^{-1})_* C^\infty_{\phi_\alpha(U_{\alpha\beta})},$$

which says that a function on $\phi_\alpha(U_{\alpha\beta})$ is smooth iff its composition with $\phi_\beta \circ \phi_\alpha^{-1}$ is a smooth function on $\phi_\beta(U_{\alpha\beta})$. This happens if and only if $\phi_\beta \circ \phi_\alpha^{-1}$ is smooth.

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Note that we have constructed what is called a “maximal smooth atlas”: all possible smooth charts are already in \mathcal{U} .

Conversely, let $(U_\alpha, \phi_\alpha)_{\alpha \in I}$ be a maximal smooth atlas on M . Using the gluing condition, we define a local sheaf of rings on M as follows: $C_{U_\alpha}^\infty = (\phi_\alpha^{-1})_* C_{\mathbf{R}^n}^\infty$. For an intersection $U_{\alpha\beta}$, we must show that

$$C_{U_\alpha}^\infty|_{U_{\alpha\beta}} = C_{U_\beta}^\infty|_{U_{\alpha\beta}},$$

that is,

$$(\phi_\alpha^{-1})_* C_{\phi_\alpha(U_{\alpha\beta})}^\infty = (\phi_\beta^{-1})_* C_{\phi_\beta(U_{\alpha\beta})}^\infty$$

but this is the same as showing that

$$(\phi_\beta \circ \phi_\alpha^{-1})_* C_{\phi_\alpha(U_{\alpha\beta})}^\infty = C_{\phi_\beta(U_{\alpha\beta})}^\infty,$$

which follows from the fact that $\phi_\beta \circ \phi_\alpha^{-1}$ is smooth. \square

The main tool to produce smooth manifolds is the implicit function theorem from multi-variable calculus:

Theorem 2.5.4. *Let $F: U \rightarrow \mathbf{R}^N$ be a smooth map, where $U \subseteq \mathbf{R}^{N+n}$ is open. Assume that 0 is a regular value of F , i. e., the differential $DF(x)$ has maximal rank N at every point $x \in F^{-1}(0)$. Then $F^{-1}(0)$ is a smooth n -dimensional submanifold of \mathbf{R}^{N+n} .*

Exercise 7. Verify that the above is indeed the implicit function theorem.

There are a number of pitfalls for our intuition regarding smooth structures, but the following remarks may help to circumnavigate them.

Let $M = \{(x, y) \in \mathbf{R}^2 \mid x \geq 0, y \geq 0, xy = 0\} \subseteq \mathbf{R}^2$ be the union of the nonnegative x - and y -axes. Since M has a corner, one might be tempted to assume that M is not a smooth manifold. But all this shows is that M is not a smooth submanifold of \mathbf{R}^2 , i. e. that the sheaf $C_{\mathbf{R}^2|_M}^\infty$ is not locally isomorphic to $C_{\mathbf{R}^1}^\infty$. Looking at M as an abstract manifold, it is homeomorphic to \mathbf{R}^1 and a smooth structure is given by pulling back $C_{\mathbf{R}^1}^\infty$ along this isomorphism.

Are there, then, any examples of topological manifolds which do not admit any smooth structure at all? This is a nontrivial question which we will answer in ???. The first example was given by Kervaire [Ker60]. However, all manifolds in dimensions less than 4 are smoothable.

A related question is whether a manifold can have nonisomorphic smooth structures. This was answered affirmatively by Milnor in [Mil56] where he showed that \mathbf{S}^7 admits exactly 28 nonisomorphic smooth structures, of which only one is the standard structure from the embedding $\mathbf{S}^7 \hookrightarrow \mathbf{R}^8$.

2.5.2. The tangent bundle of a smooth manifold

The sheaf-theoretic definition of a smooth manifold M allows for a concise construction of the tangent bundle.

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Definition. Let A be a k -algebra. A *derivation* on A is a k -linear function $D: A \rightarrow A$ such that $D(ab) = D(a)b + D(b)a$ (the so-called *Leibniz rule*). Denote the set of derivations on A be $\text{Der}(A)$; this is an A -module.

Note that $D(1) = 0$ since $D(1) = D(1 \cdot 1) = 2D(1)$.

Example 2.5.5. Let $A = C^\infty(\mathbf{R}^n)$ be the algebra of smooth real-valued functions on \mathbf{R}^n . For a chosen basis of \mathbf{R}^n , let $x_i: \mathbf{R}^n \rightarrow \mathbf{R}$ be the coordinate function $(x_1, \dots, x_n) \mapsto x_i$. Then $\frac{\partial}{\partial x_i}$ is a derivation on A .

In fact, this is a derivation on the quotient algebra C_0^∞ of germs of smooth functions at 0.

Definition. Let M be a smooth manifold. Define a sheaf TM by

$$TM(U) = \text{Der}(C_U^\infty).$$

Theorem 2.5.6. For an n -dimensional manifold M , TM is an n -dimensional real vector bundle.

Proof. We have to show that TM is a finitely generated, locally free sheaf of C_M^∞ -modules. This is a local question, so we may assume that $M = \mathbf{R}^n$. After choosing a basis of \mathbf{R}^n , the differential operators $\frac{\partial}{\partial x_i}$ are linearly independent global sections of TM . We will show that the map $(C_M^\infty)^n \rightarrow TM$ which sends (f_1, \dots, f_n) to the derivation $f_1 \frac{\partial}{\partial x_1} + \dots + f_n \frac{\partial}{\partial x_n}$ is an isomorphism of C_M^∞ -module sheaves. Let $X \in \text{Der}(C_{\mathbf{R}^n}^\infty)$ and $f \in C^\infty(\mathbf{R}^n)$. Then for any two points $x, p \in \mathbf{R}^n$ we have

$$\begin{aligned} f(x) &= f(p) + \int_0^1 \frac{d}{dt} f(tx + (1-t)p) dt = f(p) + \int_0^1 \sum_{i=1}^n \frac{\partial f}{\partial x_i} \Big|_{tx+(1-t)p} (x_i - p_i) dt \\ &= f(p) + \sum_{i=1}^n (x_i - p_i) \int_0^1 \frac{\partial f}{\partial x_i} \Big|_{tx+(1-t)p} dt. \end{aligned}$$

Applying X and evaluating at p using the Leibniz rule, we get

$$X(f)(p) = \sum_{i=1}^n X(x_i - p_i)(p) \frac{\partial f}{\partial x_i} \Big|_p.$$

Since $X(x_i - p_i)(p) = g(p)$ is a real-valued continuous function of p , we have shown that $X(f)$ is a linear combination of $\frac{\partial f}{\partial x_i}$. \square

Theorem 2.5.7. For any smooth map $f: M \rightarrow N$ of smooth manifolds, there is an induced map $Tf: f_*TM \rightarrow TN \in \text{Vect}(N)$ which is functorial in the sense that $T \text{id} = \text{id}$ and $T(f \circ g) = Tf \circ Tg$.

Proof. Given $D \in (f_*TM)(U) = \text{Der}(C_{f^{-1}U}^\infty)$ for $U \in \text{Open}(N)$, define $Tf(D) \in \text{Der}(C_U^\infty)$ by $Tf(D) = D \circ f$. \square

2. Vector bundles

The definition of the tangent bundle is quite abstract and it is maybe not immediately clear that this really carries tangential information. To see that it does, let us compare the tangent bundle with a more obvious construction when M is embedded in \mathbf{R}^N .

Definition. Let $M \subseteq \mathbf{R}^N$ be a smooth submanifold. Define a vector bundle $T^g M \rightarrow M$ (the “g” stands for “geometric”) by

$$T^g M = \{(m, v) \in M \times \mathbf{R}^N \mid v = \gamma'(0) \text{ for some smooth curve } \gamma: (-1, 1) \rightarrow M \text{ with } \gamma(0) = m\}.$$

This is obviously a vector space over M . Let $n = \dim M$. To verify local triviality, let $x \in M$ and $p: \mathbf{R}^N \rightarrow V$ be a projection onto an n -dimensional subspace V of \mathbf{R}^N such that $p(x) = 0$ and p is a chart in a neighborhood U of x in M . Now define

$$\tilde{p}: T^g M|_U \rightarrow V \times V; \quad \tilde{p}(m, v) = (p(m), p(v)).$$

This is an isomorphism of vector bundles covering the map p and therefore gives a local trivialization.

We now define a map

$$\Phi: \Gamma_{T^g M}(U) \rightarrow TM(U)$$

by $\Phi(s)(f)(x) = D_{s(x)}f$ for $s: U \rightarrow T^g M|_U$, $f \in C_U^\infty(V)$, $V \subseteq U$ open, and $x \in V$. Here D_v denotes the directional derivative in the direction $v \in \mathbf{R}^N$.

Proposition 2.5.8. *The map Φ is an isomorphism of vector bundles.*

Proof. It is clear that Φ is a map of vector spaces over B . Since isomorphism can be tested locally, we may assume that $M \cong \mathbf{R}^n \subseteq \mathbf{R}^N$ is the standard embedding. It suffices to show that Φ is an isomorphism on the fibers by Theorem 2.1.6. Without loss of generality we will consider the fiber over $0 \in \mathbf{R}^n$. But then

$$\Phi_x: \{\gamma'(0) \mid \gamma: (-1, 1) \rightarrow \mathbf{R}^n, \gamma(0) = 0\} = \mathbf{R}^n \rightarrow \text{Der}(C_{\mathbf{R}^n}^\infty)_0$$

is an isomorphism by the proof of Theorem 2.5.6. □

2.5.3. Normal bundles of embeddings

2.5.4. The cotangent bundle and differential forms

Let M be a smooth manifold. Then the cotangent bundle T^*M is the linear dual of the tangent bundle of M , that is, $T^*M = \text{Hom}_M(TM, \mathbf{R} \times M)$.

A section of T^*M can be considered a differential 1-form ω . There is a canonical derivation

$$d: C_M^\infty \rightarrow T^*M$$

given by $d(f)(D) = D(f)$. Locally, any section of T^*M is a C^∞ -linear combination of df .

The vector space of differential i -forms is the i th exterior power of T^*M :

$$\Omega^i(M) = \bigwedge^i T^*M.$$

We define $\Omega^0(M) = C_M^\infty$.

We can extend the derivation d to a chain complex of vector bundles, the *de Rham complex* of M ,

$$\Omega^0(M) \xrightarrow{d} \Omega^1(M) \xrightarrow{d} \cdots \xrightarrow{d} \Omega^n(M) \rightarrow 0$$

by inductively defining

$$d(\omega \wedge \tau) = d(\omega) \wedge \tau + (-1)^p \omega \wedge d(\tau)$$

where $\omega \in \Omega^p(M)$ and $\tau \in \Omega^q(M)$, and decreeing that $d^2 = 0$.

2.6. Bundles with more structure

When M is a smooth manifold, it is natural to consider vector bundles that are compatible with this smooth structure, as is modelled by the tangent bundle. To be more precise, we define

Definition. A *smooth vector bundle* on a smooth manifold M is a locally finitely generated free C_M^∞ -module sheaf.

The forgetful map of local sheaves of rings $u: C_M^\infty \rightarrow C_M^0$ allows us to construct an ordinary (continuous) vector bundle E' from a smooth vector bundle E by tensoring down:

$$E' = E \otimes_{C_M^\infty} C_M^0.$$

We can also interpret this definition in terms of vector spaces over M . A *smooth atlas* for a (ordinary, continuous) vector bundle $E \rightarrow M$ is a collection of local trivializations $(U_\alpha, \phi_\alpha)_{\alpha \in I}$ such that the change-of-coordinate functions

$$g_{\alpha\beta}: U_{\alpha\beta} \rightarrow \mathrm{GL}_n(k)$$

are smooth. A smooth vector bundle is a continuous vector bundle together with an equivalence class of smooth atlases much analogously to the definition of a smooth structure on a manifold.

The characterization of additional structure by change-of-coordinate functions is a powerful tool and lets us, among other things, make the following definitions:

Definition. An *orientation* on a vector bundle is a choice of equivalence class of atlases whose transition functions take values in $\mathrm{SL}_n(k) < \mathrm{GL}_n(k)$.

Definition. A *Euclidean structure* on a real vector bundle is a choice of equivalence class of atlases whose transition functions take values in $O(n) < \mathrm{GL}_n(\mathbf{R})$. A *Hermitian structure* on a complex vector bundle is an equivalence class of atlases whose transition functions take values in $U(n) < \mathrm{GL}_n(\mathcal{C})$.

We will see later (Cor. 3.6.3) that any vector bundle can be given a Euclidean resp. Hermitian structure under mild conditions on the topology of the base space.

3. Lie groups, Grassmannians, and universal bundles

Motivate by Gauss map and classifying map of tangent bundle on embedded manifolds. Question of universal bundle and construction for non-manifolds.

3.1. Stiefel and Grassmann manifolds

In this section we will construct spaces $G_n(k^N)$ whose points correspond to n -dimensional linear subspaces of k^N . Obviously, for this to be nonempty, we need that $N \geq n$. These spaces are called *Grassmann manifolds* or just *Grassmannians* after their discoverer, 19th century mathematician Hermann Graßmann. They are in fact compact manifolds (when $k = \mathbf{R}$ or \mathbf{C}) and, more generally, smooth projective varieties for any field k .

Closely related is another family of manifolds, the *Stiefel manifolds* $V_n(k^N)$, whose points correspond to n -frames in k^N . An n -frame is a sequence (v_1, \dots, v_n) of orthonormal vectors in k^N . One can thus think of a point in $V_n(k^N)$ as a point $V \in G_n(k^N)$, i. e. an n -dimensional linear subspace of k^N , together with a choice of orthonormal basis of V . Forgetting this basis gives a canonical projection map $V_n(k^N) \rightarrow G_n(k^N)$. If one does not want to (or cannot) use a scalar product on k^N to define V_n , one can look at *noncompact Stiefel varieties* V_n^{nc} , where one relaxes the requirement of orthonormality to mere linear independence.

Observe that we already know the spaces $V_1(k^N)$ and $G_1(k^N)$ by other names, namely:

$$\begin{aligned} V_1(\mathbf{R}^N) &= \mathbf{S}^{N-1} \\ V_1(\mathbf{C}^N) &= \mathbf{S}^{2N-1} \\ G_1(k^N) &= kP^{N-1}. \end{aligned}$$

A set of one orthonormal vector in k^N is just a unit vector in k^N , hence the first two equations, and a one-dimensional subspace in k^N is a point in kP^{N-1} by definition. The topologies we are about to define on V_1 and G_1 coincide with the familiar topologies.

We topologize $V_n(k^N)$ and $V_n^{\text{nc}}(k^N)$ as subspaces of a product $k^N \times \dots \times k^N$ of n copies of k^N , and $G_n(k^N)$ is endowed with the quotient topology. That is, we use the straightforward identifications

$$\begin{aligned} V_n(k^N) &= \{U \in k^{N \times n} \mid U \text{ has orthonormal columns}\} \\ &\subseteq V_n^{\text{nc}}(k^N) = \{U \in k^{N \times n} \mid U \text{ has maximal rank}\} \subseteq k^{N \times n} \end{aligned}$$

to define the topologies.

3.1. Stiefel and Grassmann manifolds

Lemma 3.1.1 (Gram-Schmidt). *The inclusion map $V_n(k^N) \rightarrow V_n^{\text{nc}}(k^N)$ is a homotopy equivalence for $k = \mathbf{R}$ or $k = \mathbf{C}$.*

Proof. The Gram-Schmidt orthonormalization process says that

$$V_n^{\text{nc}}(k^n) \cong V_n(k^n) \times T_n(k),$$

where $T_n(k)$ denotes the upper triangular matrices $n \times n$ -matrices with positive real diagonal. But $T_n(k)$ is contractible. \square

Lemma 3.1.2. *The group $O(n)$ of orthogonal $n \times n$ -matrices acts freely on $V_n(\mathbf{R}^N)$, and the canonical map $V_n(\mathbf{R}^N)/O(n) \rightarrow G_n(\mathbf{R}^N)$ is a homeomorphism.*

The same is true for over \mathbf{C} if one replaces $O(n)$ by the group $U(n)$ of unitary matrices.

Proof. The group $O(n)$ acts on the n orthonormal vectors of a point in $V_n(\mathbf{R}^N)$. The fiber of the projection map $V_n(\mathbf{R}^N) \rightarrow G_n(\mathbf{R}^N)$ over a point $V \in G_n(\mathbf{R}^N)$ is the set of orthonormal bases of V , on which $O(n)$ acts freely and transitively, thus the projection map factors through a homeomorphism $V_n(\mathbf{R}^N)/O(n) \rightarrow G_n(\mathbf{R}^N)$. The proof in the complex case is the same. \square

Picking the n first columns of an $N \times N$ -matrix gives us surjective maps

$$\phi: O(N) \rightarrow V_n(\mathbf{R}^N), \quad \phi: U(N) \rightarrow V_n(\mathbf{C}^N), \quad \phi: \text{GL}_N(k) \rightarrow V_n^{\text{nc}}(k^N).$$

Lemma 3.1.3. *Consider the group $O(n) \times O(N-n)$ as the subgroup of $O(N)$ of matrices of the form $\begin{pmatrix} A & 0 \\ 0 & B \end{pmatrix}$. Then ϕ factors through an $O(n)$ -equivariant homeomorphism*

$$\bar{\phi}: O(N)/O(N-n) \rightarrow V_n(\mathbf{R}^N).$$

In particular, there is a homeomorphism $\frac{O(n)}{O(n) \times O(N-n)} \rightarrow G_n(\mathbf{R}^N)$.

Analogous statements hold in the unitary and noncompact cases.

Proof. The group $O(N)$ acts on $V_n(\mathbf{R}^N)$ by mapping an orthogonal n -frame to another such n -frame. This action is transitive, and the stabilizer group of a frame $F = (v_1, \dots, v_n)$ is the orthogonal group $O(N-n)$ of the orthogonal complement of the span of F . Thus by the orbit-stabilizer theorem, $O(N)/O(N-n) \rightarrow V_n(\mathbf{R}^N)$ is a homeomorphism, which moreover is $O(n)$ -equivariant. \square

Corollary 3.1.4. *For $k = \mathbf{R}, \mathbf{C}$, we have that*

$$G_n(k^N) \cong G_{N-n}(k^N)$$

Proof. This follows directly from the $G_n(k^N) \cong \frac{O(N)}{O(n) \times O(N-n)}$. Geometrically, the homeomorphism $G_n(k^N) \rightarrow G_{N-n}(k^N)$ is given by mapping an n -dimensional subspace of k^N to its orthogonal (or unitary) complement. \square

Having exhibited $V_n(k^N)$ and $G_n(k^N)$ as homogeneous spaces, we get:

3. Lie groups, Grassmannians, and universal bundles

Theorem 3.1.5. *The spaces $V_n(k^N)$ and $G_n(k^N)$ are compact smooth manifolds for $k = \mathbf{R}, \mathbf{C}$, of the following real dimensions:*

- $\dim V_n(\mathbf{R}^N) = Nn - \binom{n+1}{2}$;
- $\dim V_n(\mathbf{C}^N) = 2Nn - n^2$;
- $\dim G_n(\mathbf{R}^N) = n(N - n)$;
- $\dim G_n(\mathbf{C}^N) = 2n(N - n)$.

Proof. By Lemma 3.1.3, they are quotients of compact Lie groups by closed compact subgroups, hence smooth manifolds. The claims about dimensions follow from the facts that $\dim O(n) = \binom{n}{2}$ and $\dim U(n) = n^2$. \square

To exhibit explicit charts for $G_n(k^N)$, it helps to do a little geometry. Let $V \in G_n(k^N)$ be a point, and let V^\perp be its orthogonal (or unitary) complement. Now consider the set

$$U_V = \{V' \in G_n(k^N) \mid V' \cap V^\perp = 0\}. \quad (3.1.6)$$

Clearly, $V \in U_V$ and U_V is open. The map

$$\phi_V: \text{Hom}(V, V^\perp) \cong k^{n(N-n)} \rightarrow U_V; \quad \alpha \mapsto \{v + \alpha(v) \mid v \in V\},$$

which can be thought of as sending a homomorphism α to its graph in $k^N = V \oplus V^\perp$, is a homeomorphism.

3.1.1. The tautological bundle

Let $E_n(k^N) = \{(V, v) \mid V \in G_n(k^N), v \in V\} \subseteq G_n(k^N) \times k^N$. The projection τ to the first coordinate gives a smooth surjection $E_n(k^N) \rightarrow G_n(k^N)$.

Proposition 3.1.7. *The map $\tau: E_n(k^N) \rightarrow G_n(k^N)$ is an n -dimensional vector bundle.*

Proof. It is clear from the definition that $E_n(k^N)$ is a vector space over $G_n(k^N)$ and that the dimension is n , but we need to show local triviality. Consider the open sets U_V of (3.1.6). We construct a trivialization over U_V by

$$\tau^{-1}(U_V) \rightarrow U_V \times V; \quad (V', v') \mapsto (V', p(v')),$$

where $p': V' \rightarrow V$ is the orthogonal projection of V' to V , which is an isomorphism over U_V since its kernel is V^\perp . \square

The vector bundle $\tau: E_n(k^N) \rightarrow G_n(k^N)$ is called the *tautological bundle* because the description of its fibers sounds like a tautology: the fiber of τ over a point $V \in G_n(k^N)$ is V .

Theorem 3.1.8. *Let $M \subseteq \mathbf{R}^N$ be an n -dimensional smooth submanifold of \mathbf{R}^N and $TM \rightarrow M$ its tangent bundle. Then there is a map $f: M \rightarrow G_n(\mathbf{R}^N)$ such that $TM \cong f^*\tau$.*

Proof. The map f is defined by $f(x) = T_x M \subseteq \mathbf{R}^N$, where $T_x M$ is the tangent space of M at x , considered as a linear subspace of \mathbf{R}^N . We thus get a vector bundle map $TM \rightarrow f^*\tau$ over M which is a fiberwise isomorphism, hence an isomorphism by Theorem 2.1.6. \square

3.2. Simplicial spaces

We have seen that the tangent bundle of a manifold embedded in Euclidean space has a “classifying map” to the Grassmannian $G_n(\mathbf{R}^N)$ in the sense that it is the pullback of the tautological bundle along this map. In the rest of this chapter, our aim is to make this construction independent of the embedding in Euclidean space, and to generalize it to arbitrary bundles. This requires the notion of a classifying space for a topological group, which is best understood in the context of *simplicial spaces*.

Definition. A *simplicial space* (or, more generally a simplicial object in a category C) is a functor

$$X: \Delta^{\text{op}} \rightarrow \text{Top} \quad (\text{or } C),$$

where Δ denotes the category with objects the totally ordered sets $[n] = \{0, \dots, n\}$ and morphisms the monotonic maps. Similarly, an *augmented simplicial space* is a functor

$$X: \Delta_+^{\text{op}} \rightarrow \text{Top} \quad (\text{or } C),$$

where Δ_+ is the same category but also including the empty set $\emptyset = [-1]$.

To specify a simplicial object, we thus need to define an object X_n for each n , and a morphism $X_n \rightarrow X_m$ for each monotonic map $[m] \rightarrow [n]$. Note that any such monotonic map can uniquely be written as a surjective monotonic map $[m] \rightarrow [k]$ followed by an injective monotonic map $[k] \rightarrow [n]$. Moreover, any injective monotonic map is some composite of the so-called *coface maps*

$$d_n^i: [n-1] \rightarrow [n], \text{ which is injective and omits } i \in [n],$$

and any surjective monotonic map is some composite of the so-called *codegeneracy maps*

$$s_n^i: [n+1] \rightarrow [n], \text{ which is surjective and maps } i \text{ and } i+1 \text{ to } i.$$

The main source of simplicial spaces is the nerve construction for a topological category.

Definition. Let \mathcal{C} be a topological category. The *nerve* \mathcal{NC} of \mathcal{C} is the simplicial space defined by $X_n = \text{mor } \mathcal{C} \times_{\text{ob } \mathcal{C}} \dots \times_{\text{ob } \mathcal{C}} \text{mor } \mathcal{C}$, where the fiber product has n factors. In particular, $X_0 = \text{ob } \mathcal{C}$. We specify the morphism by defining the *face maps* $d_i^n: X_n \rightarrow X_{n-1}$ induced by d_n^i and the *face maps* $s_i^n: X_n \rightarrow X_{n+1}$ induced by s_n^i :

- $d_i = \text{id}_{\text{mor } \mathcal{C}} \times \dots \times \mu \times \dots \times \text{id}_{\text{mor } \mathcal{C}}$, where μ appears in the i th place;
- $s_i = \text{id}_{\text{mor } \mathcal{C}} \times \dots \times u \times \dots \times \text{id}_{\text{mor } \mathcal{C}}$, where u appears in the i th place.

The associativity and unitality axioms guarantee that this is a well-defined simplicial space.

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If \mathcal{C} is an ordinary (small) category, we have explicitly that

$$X_n = \coprod_{X_0, \dots, X_n \in \mathcal{C}} \text{Hom}(X_{n-1}, X_n) \times \cdots \times \text{Hom}(X_1, X_2) \times \text{Hom}(X_0, X_1),$$

i. e., X_n is the space of composable chains of n morphisms.

Example 3.2.1. Let X be a space. We define the *translation category* $T(X)$ of X to have $\text{ob } T(X) = X$ and $\text{mor } T(X) = X \times X$, where the source and target maps are the two projections, the unit map is the diagonal, and the composition is the projection to the first and third factors:

$$(X \times X) \times_X (X \times X) = X \times X \times X \rightarrow X \times X.$$

For this category, $\mathcal{N}_n T(X) \cong X^{n+1}$, and we can describe the nerve functorially as the functor

$$\mathcal{N}T(X) = \text{map}(-, X): \Delta^{\text{op}} \rightarrow \text{Top}$$

where the argument is considered as a discrete topological space.

Example 3.2.2. Let G be a topological group. Then the translation category $T(G)$ has a natural action by G : it acts by left multiplication on $\text{ob } T(G) = G$ and by diagonal left multiplication on $\text{mor } T(G) = G \times G$. Thus by functoriality, G also acts on the nerve $\mathcal{N}T(G)$. That is, it acts on every space $\mathcal{N}_n T(G)$, and the structure maps f^* are G -equivariant for each $f: [m] \rightarrow [n]$. We denote the quotient of $\mathcal{N}T(G)$ by this action by $\mathcal{N}G$.

Exercise 8. Show that for a topological group G , $\mathcal{N}(G)$ is isomorphic to the nerve of the category with one object $*$ and endomorphisms $\text{map}(*, *) = G$. Here, the composition is defined by the group multiplication, and the identity morphism is the identity element of G . In particular, $\mathcal{N}_n G = G^n$. Describe the maps d_i and s_i explicitly.

Example 3.2.3. Let $\mathcal{U} = \{U_\alpha\}_{\alpha \in I}$ be an open cover of a space X , and let $\mathbf{U} = \coprod_{\alpha \in I} U_\alpha$. We denote the element $x \in U_\alpha \subseteq \mathbf{U}$ by x^α to make explicit in which disjoint summand x lies. Define the map $p: \mathbf{U} \rightarrow X$ to be the standard inclusion on every summand, so that in total, p is an open surjective map. The pair $(\mathbf{U}, \mathbf{U} \times_X \mathbf{U})$ becomes a topological category if we define

- $u: \mathbf{U} \rightarrow \mathbf{U} \times_X \mathbf{U}$ by $u(x^\alpha) = (x^\alpha, x^\alpha)$;
- $s(x^\alpha, y^\beta) = x^\alpha$ and $t(x^\alpha, y^\beta) = y^\beta$;
- $\mu: (\mathbf{U} \times_X \mathbf{U}) \times_{\mathbf{U}} (\mathbf{U} \times_X \mathbf{U}) = \mathbf{U} \times_X \mathbf{U} \times_X \mathbf{U} \rightarrow \mathbf{U} \times_X \mathbf{U}$ by $(x^\alpha, y^\beta, z^\gamma) \mapsto (x^\alpha, z^\gamma)$.

The $\mathcal{N}(\mathbf{U}, \mathbf{U} \times_X \mathbf{U})$ is called the *big nerve* of the covering \mathcal{U} , and we denote it by $\mathcal{N}\mathbf{U}$.

Note that

$$\mathcal{N}_n \mathbf{U} = \mathbf{U} \times_X \cdots \times_X \mathbf{U} = \coprod_{\alpha_0, \dots, \alpha_n \in I} U_{\alpha_0 \cdots \alpha_n};$$

we will denote an element in $\mathcal{N}_n \mathbf{U}$ by $x^{\alpha_0 \cdots \alpha_n}$.

Example 3.2.4. Let $\mathcal{U} = \{U_\alpha\}_{\alpha \in I}$ be an open cover of X as before. Denote by $b(\mathcal{U})$ the set of those finite subsets J of I such that $U_J = \bigcap_{\alpha \in J} U_\alpha$ is nonempty. We make $b(\mathcal{U})$ into a poset (and hence a category) by inclusion of subsets. Then the (small) nerve $\mathcal{N}b(\mathcal{U})$ of \mathcal{U} is the nerve of $b(\mathcal{U})$.

There is a simplicial map from $\mathcal{N}\mathbf{U}$ to $\mathcal{N}b(\mathcal{U})$ given by

$$\mathcal{N}_n \mathbf{U} \rightarrow \mathcal{N}_n b(\mathcal{U}); \quad x^{\alpha_0 \cdots \alpha_n} \mapsto \{\alpha_0, \dots, \alpha_n\}.$$

We will look at the differences between these two nerve constructions more closely later on, but we observe right now that we can recover the space X from the big nerve $\mathcal{N}\mathbf{U}$ as the coequalizer

$$\mathbf{U} \times_X \mathbf{U} \begin{matrix} \xrightarrow{s} \\ \xleftarrow{t} \end{matrix} \mathbf{U} \rightarrow X.$$

whereas we cannot, in general, recover X from the small nerve, as the example of the trivial cover $\mathcal{U} = \{X\}$ shows. The small nerve keeps track of which intersections of sets of the open cover are empty and which aren't, not more. We might guess that if all opens in the cover, along with all their finite nonempty intersections, are contractible, we might recover X up to homotopy. We will show in the next section that this is the case.??

We remark in passing that the nerve construction is functorial: a functor $F: \mathcal{C} \rightarrow \mathcal{D}$ between topological categories induces a simplicial map $\mathcal{N}F: \mathcal{N}\mathcal{C} \rightarrow \mathcal{N}\mathcal{D}$ in the obvious way.

What information do we lose by passing from a topological category to its nerve? The answer is nothing; a topological category can be considered as a special kind of simplicial space:

Proposition 3.2.5. *The nerve functor is full and faithful.*

Proof. We clearly have that $(\mathcal{N}\mathcal{C})_0 = \text{ob } \mathcal{C}$ and $(\mathcal{N}\mathcal{C})_1 = \text{mor } \mathcal{C}$. The unit maps are recovered as s_0^0 , the source and target maps by d_0^1 and d_1^1 . Finally, the composition map in \mathcal{C} is the map $d_1^2: (\mathcal{N}\mathcal{C})_2 \rightarrow (\mathcal{N}\mathcal{C})_1$ since $(\mathcal{N}\mathcal{C})_2 = \text{mor } \mathcal{C} \times_{\text{ob } \mathcal{C}} \text{mor } \mathcal{C}$. \square

Note that it is also easy to describe when a simplicial set X is the nerve of a category: precisely when it is determined by its 1-skeleton in the sense that

$$X_n \xrightarrow{(p_1, \dots, p_n)} X_1^{\times_{X_0} n} = X_1 \times_{X_0} \cdots \times_{X_0} X_1$$

is an isomorphism, where p_i is the map induced by the cosimplicial map $[1] \rightarrow [n]$ with image $\{i-1, i\}$.

In particular, Proposition 2.3.11 implies:

Corollary 3.2.6. *Let X be a space with an open cover \mathcal{U} and G a topological groupoid. Then there is a bijection between the set of cocycles for \mathcal{U} with values in G and the set of simplicial maps $\mathcal{N}\mathbf{U} \rightarrow \mathcal{N}G$.* \square

3. Lie groups, Grassmannians, and universal bundles

3.2.1. Simplicial homotopy

Denote by $I = \mathcal{N}[1]$ the nerve of the category which has two objects $\{0, 1\}$ and one non-identity morphism $0 \rightarrow 1$. In other words, I is the functor $\Delta^{\text{op}} \rightarrow \text{Set}$ which is represented by the object $[1] \in \Delta$, i. e.

$$I_n = \text{Hom}_{\Delta}([n], [1]).$$

Given any simplicial object X in a category C , we can form the *cylinder object* $X \times I$ as

$$(X \times I)_n = X_n \times I_n,$$

where we think of the cartesian product of an object Z of C with a set I as the coproduct $\coprod_I Z$. This is thus also a simplicial object in C .

Definition. A *simplicial homotopy* between two simplicial maps $f, g: X \rightarrow Y$ is a simplicial map $h: X \times [1] \rightarrow Y$ such that $h|_{X \times \{0\}} = f$ and $h|_{X \times \{1\}} = g$

The following proposition follows from the definition of natural transformations of functors of topological categories (Section 2.3.2) and Proposition 3.2.5.

Proposition 3.2.7. *Let $F, G: C \rightarrow D$ be functors of topological categories. Then the nerve functor gives a homeomorphism between the space of natural transformations from F to G and the space of simplicial homotopies from $\mathcal{N}F$ to $\mathcal{N}G$.* \square

3.2.2. Geometric realization

A simplicial space is called “simplicial” because one can use its functorial information to glue together simplices to produce a space. Let Δ^n denote the standard n -simplices, i. e. the convex hull of the standard basis vectors e_0, \dots, e_n of \mathbf{R}^{n+1} . The following definition is central:

Definition. Let X be a simplicial space. Its *geometric realization* $|X|$ is the coequalizer

$$\coprod_{f: [m] \rightarrow [n]} X_m \times \Delta^m \rightrightarrows \coprod_{n \geq 0} X_n \times \Delta^n \rightarrow |X|,$$

where the first coproduct is over the set of all monotonic maps from $[m]$ to $[n]$ (so $m \leq n$), and the two maps are given by

$$(x, t) \mapsto (f^*x, t) \in X_m \times \Delta^m \quad \text{and} \quad (x, t) \mapsto (x, f_*t) \in X_n \times \Delta^n.$$

Here f^* is the map induced on the simplicial set X by f , and $f_*: \Delta^m \rightarrow \Delta^n$ is the affine map from Δ^m to Δ^n with corners $e_{f(0)}, \dots, e_{f(m)}$.

It is clear from the definition that geometric realization is a functor:

Lemma 3.2.8. *The geometric realization is functorial, i. e. a map of simplicial spaces induces a map between their geometric realizations.* \square

The geometric realization $|X|$ can be given a somewhat smaller presentation by only considering *nondegenerate* simplices, i. e. elements $x \in X_n$ which are not in the image of s_i for any $0 \leq i \leq n$, or equivalently, which are not of the form $f^*(y)$ for some $y \in X_m$ and a non-injective map $f: [n] \rightarrow [m]$. The collection $X_n^{\text{nd}} \subseteq X_n$ of nondegenerate simplices forms a “semi-simplicial”¹ or “facial” set, i. e. a functor from the subcategory Λ of Δ with the same objects but only injective maps as morphisms. We then have a coequalizer diagram

$$\coprod_{f: [m] \hookrightarrow [n]} X_n^{\text{nd}} \times \Delta^m \rightrightarrows \coprod_{n \geq 0} X_n^{\text{nd}} \times \Delta^n \rightarrow |X|. \quad (3.2.9)$$

Moreover, every point in $|X|$ is represented by a unique pair $(x, t) \in X_n^{\text{nd}} \times \mathring{\Delta}^n$, where $\mathring{\Delta}^n$ denotes the interior of Δ^n . That is, the map

$$\coprod_{n \geq 0} X_n^{\text{nd}} \times \mathring{\Delta}^n \rightarrow |X|$$

is continuous and bijective (but clearly not a homeomorphism). Details can be found in [Mil57].

The following result is less obvious. It involves the set-theoretical notion of compactly generated weak Hausdorff spaces and k -products. We will not go into details here but remark that these spaces include all spaces of interest to us, and that for these spaces, the k -product coincides with the usual product.

Theorem 3.2.10 ([May72, Theorem 11.5]). *The geometric realization commutes with products in the category of Kelley spaces. In other words,*

$$|X \times Y| \cong |X| \times_k |Y|,$$

where \times_k denotes the Kelley product.

Definition. The geometric realization of the nerve of a topological group or category G is called the *classifying space* of G and is denoted by

$$BG = |\mathcal{N}G|.$$

Lemma 3.2.11. *A functor $F: \mathcal{C} \rightarrow \mathcal{D}$ between topological categories induces a map $BF: B\mathcal{C} \rightarrow B\mathcal{D}$ of classifying spaces. A natural transformation α between functors $F, G: \mathcal{C} \rightarrow \mathcal{D}$ induces a homotopy between BF and BG . In particular, $B\mathcal{C} \simeq B\mathcal{D}$ if \mathcal{C} and \mathcal{D} are equivalent categories.*

Proof. We have seen in the previous section that a functor $F: \mathcal{C} \rightarrow \mathcal{D}$ induces a map of nerves, and the geometric realization construction is functorial as well, so that B becomes a functor. Now let $\alpha: \mathcal{C} \times [1] \rightarrow \mathcal{D}$ be a natural transformation. By the above, it induces a map

$$B\alpha: B(\mathcal{C} \times [1]) \rightarrow \mathcal{D},$$

¹Historically, e. g. in [Mil57], the term “semisimplicial set” was used for what we nowadays call a simplicial set, freeing up the term “semisimplicial” for a new use.

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and by Thm 3.2.10, $B(\mathcal{C} \times [1]) \cong B\mathcal{C} \times B[1]$ by the projection maps. The proof is finished by noting that $B[1] \cong \Delta^1 \cong [0, 1]$. \square

Corollary 3.2.12. *For any nonempty space X , the space $EX := BT(X)$, i. e. the geometric realization of the nerve of the translation category of X , is contractible.*

Proof. By Lemma 3.2.11, it suffices to show that the category $T(X)$ is contractible, i. e. equivalent to the one-point category. This is true since every object in X is initial (and terminal): there is exactly one morphism between any two objects x, y , namely (x, y) . \square

3.3. Classifying spaces of Lie groups

Consider again the Grassmannians $G_n(k^N)$ for $k = \mathbf{R}$ or \mathbf{C} . There are maps $i: G_n(k^N) \rightarrow G_n(k^{N+1})$ given by a linear inclusion of k^N into k^{N+1} (for instance by letting the last coordinate be zero).

Theorem 3.3.1. *There are maps $j_n: G_n(\mathbf{R}^N) \rightarrow BO(n)$ and $j_n: G_n(\mathbf{C}^n) \rightarrow BU(n)$ such that*

- $j_n = j_{n+1} \circ i$, and
- *The induced maps $j_\infty: \operatorname{colim}_N G_n(\mathbf{R}^N) \rightarrow BO(n)$ and $j_\infty: \operatorname{colim}_N G_n(\mathbf{C}^N) \rightarrow BU(n)$ are homotopy equivalences.*

Proof. We'll deal with the real case, the complex case is analogous. For instructive reasons, we'll consider the case $n = 1$ first. In this case, $V_1(k^N) = \mathbf{S}^{N-1}$ and $EO(1) = E\{\pm 1\}$. Choose an orthogonal basis $\{e_1, e_2, \dots\}$ of \mathbf{R}^∞ (for instance, the standard basis vectors).

We define a $\mathbf{Z}/2$ -equivariant map

$$f: \{\pm 1\}^N \times \Delta^N \rightarrow \mathbf{S}^N$$

by sending $(\epsilon_1, \dots, \epsilon_N, s_1, \dots, s_N)$ to the point $P = \epsilon_1 s_1 e_1 + \epsilon_2 s_2 e_2 + \dots + \epsilon_N s_N e_N$, where $s_1 + \dots + s_N = 1$ and $s_i \geq 0$. This map is clearly surjective, and it is injective unless the point P lies on some coordinate hyperplane $s_k = 0$. In that case, the sign ϵ_k does not matter, which we can express by saying that

$$f(d_k \epsilon, s) = f(\epsilon, d^k s) \quad \text{for } \epsilon \in \{\pm 1\}^N, s \in \Delta^{N-1}.$$

here $d_k: \{\pm 1\}^N \rightarrow \{\pm 1\}^{N-1}$ is the projection map that forgets the k th factor. [.....Details?.....]

It follows that the inverse maps assemble to an equivariant homeomorphism

$$EO(1) \rightarrow \mathbf{S}^\infty;$$

in particular, by dividing out the $\mathbf{Z}/2$ -action, $BO(1) \cong \mathbf{R}P^\infty$. \square

3.4. Schubert cells

In ?? it was proved that $G_n(k^N)$ may be viewed as a compact smooth manifold over $k = \mathbf{R}, \mathbf{C}$. Now we will instead view points in $G_n(k^N)$ as certain natural orbits of $n \times N$ matrices of full rank and thereby decompose $G_n(k^N)$ into affine spaces known as *Schubert cells*. It is not a coincidence that these spaces are named *cells*, they in fact make up a CW-complex of $G_n(k^N)$. This allows for the computation of the cohomology ring of the Grassmannian via the cellular cohomology that comes along with CW-complexes. The cohomology ring of the Grassmannian in turn plays a role in the classification of the ring of characteristic classes.

Proposition 3.4.1. *There exists a one-to-one correspondence between points of $G_n(k^N)$ and orbits of the set $\text{Mat}_n(k^N)$ of $n \times N$ matrices full rank under the action of $GL_n(k)$.*

Proof. Let $V \in G_n(k^N)$. As soon as we fix a basis v_1, \dots, v_n of V we can represent V as an $n \times N$ row matrix $A = (v_{ij})$. The action of $GL_n(k)$ on A is free and transitive on the bases of V . Hence we get a one-to-one correspondence with the orbits of the action. \square

Remark 3.4.2. In each $GL_n(k)$ -orbit of $\text{Mat}_{n,N}(k)$ we have a unique canonical representative provided by the row reduced echelon form (which may be computed using Gaussian elimination). Thus we may identify points in $G_n(k^N)$ with rank n matrices in row-reduced echelon form.

Definition. A matrix $A \in \text{Mat}_{n,N}(k)$ in row reduced echelon form is said to be in I -echelon form if A has its pivots in columns $I = \{i_1 < \dots < i_n\}$. The sequence I is often referred to as the Schubert symbol.

Example 3.4.3. A point $A \in G_4(k^8)$ in $\{1, 2, 5, 7\}$ -echelon form has shape

$$A = \begin{pmatrix} 1 & 0 & * & * & 0 & * & 0 & * \\ 0 & 1 & * & * & 0 & * & 0 & * \\ 0 & 0 & 0 & 0 & 1 & * & 0 & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & * \end{pmatrix}$$

where $*$ denotes an arbitrary element in k .

Remark 3.4.4. If we remove columns with indices in the Schubert symbol I (i.e the pivot columns) and then reflect the remaining columns with respect to a vertical axis, we find that the patterns formed by the $*$'s is a Ferrers diagram of shape λ , that is, a pictorial representation of a partition λ of $N - n$ with n parts (or a weakly increasing sequence of n non-negative integers bounded by $N - n$). In Example 3.4.3 the corresponding Ferrers diagram of shape $\lambda = (4, 4, 2, 1)$ is

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Finally note that partitions of $N - n$ into n parts are in bijection with n -element subsets of $[N]$ so Schubert symbols are in correspondence with Ferrers diagrams of shape λ .

Definition. Let λ be an n -partition of $N - n$. The Schubert cell Ω_λ is the closure of the set of points in $G_n(K^N)$ with I -echelon form corresponding λ .

Remark 3.4.5. By Remark 3.4.2 it follows that

$$G_n(k^N) = \bigsqcup_{\lambda} \Omega_{\lambda}.$$

Furthermore each I -echelon matrix A has exactly $|\lambda| = \lambda_1 + \cdots + \lambda_n$ number of degrees of freedom in the entries (i.e the number of $*$'s in A). This gives a homeomorphism

$$\Omega_{\lambda} \simeq k^{|\lambda|}. \quad (3.4.6)$$

To see this more rigorously one can argue via the so called Plücker embedding of $G_n(k^N)$ into the projective space $P^{\binom{N}{n}-1}$. Label the projective coordinates of the points in $P^{\binom{N}{n}-1}$ by the n -element subsets $I \subseteq [N]$. This embedding works by sending each matrix A to the point determined coordinate-wise by the value of the $n \times n$ minor of A indexed by I . Note that the action of $GL_n(k)$ on A does not affect the projective coordinates since row-operations merely changes the minors up to a constant factor. Moreover the values under this map are indeed non-zero since A has rank n . The homeomorphism in 3.4.6 now follows by considering the image of Ω_{λ} under the embedding.

Example 3.4.7. Let us see how $G_2(\mathbf{R}^3)$ decomposes into Schubert cells. There are three possible Schubert symbols, namely $I_1 = \{1, 2\}$, $I_2 = \{1, 3\}$ and $I_3 = \{2, 3\}$ corresponding to 2-partitions of $3 - 2 = 1$ given by $\lambda_1 = (1, 1)$, $\lambda_2 = (1, 0)$ and $\lambda_3 = (0, 0)$. The three corresponding Schubert cells are parametrized by

$$\Omega_{\lambda_1} = \left\{ \begin{pmatrix} 1 & 0 & a \\ 0 & 1 & b \end{pmatrix} : a, b \in \mathbf{R} \right\}, \Omega_{\lambda_2} = \left\{ \begin{pmatrix} 1 & a & 0 \\ 0 & 0 & 1 \end{pmatrix} : a \in \mathbf{R} \right\} \text{ and } \Omega_{\lambda_3} = \left\{ \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \right\}$$

of dimension 2, 1 and 0 respectively. The two-dimensional subspaces in Ω_{λ_1} are given by planes through the origin intersecting the two lines passing through the points $(1, 0, 0)$, $(0, 1, 0)$ and parallel to the z -axis. Likewise Ω_{λ_2} consists of the two dimensional subspaces geometrically described by planes through the origin containing the point $(0, 0, 1)$ and intersecting the line passing through the point $(1, 0, 0)$ parallel to the y -axis. Finally Ω_{λ_3} consists of a single subspace given by the yz -plane. By inspecting the matrices it is easy to see that the Ω_{λ_i} are pairwise disjoint and cover $G_2(\mathbf{R}^3)$.

3.5. Paracompactness

Definition. Let $\mathcal{U} = \{U_{\alpha}\}_{\alpha \in I}$ be an open cover of a space X . We call \mathcal{U} *locally finite* if every $x \in X$ has a neighborhood that is contained in U_{α} for only finitely many $\alpha \in I$.

A *refinement* of \mathcal{U} is another open cover $\mathcal{V} = \{V_\beta\}_{\beta \in J}$ such that every V_β is contained in some U_α . A space X is called *paracompact* if every open cover has a locally finite refinement.

A *partition of unity* with respect to an open cover \mathcal{U} is a family of functions $f_\beta: X \rightarrow [0, 1]$, $\beta \in J$ such that $\sum_{\beta \in J} f_\beta = 1$ and such that for every $\beta \in J$, $\text{supp}(f_\beta) \subseteq U_\alpha$ for some $\alpha \in I$. Here the support $\text{supp}(f_\beta)$ is defined as the closure of $f_\beta^{-1}(0, 1]$.

The following is a standard fact of point-set topology (cf. for example [Bre97, Chapter I.12]):

Proposition 3.5.1. *A space X is paracompact iff every open cover has an associated partition of unity.* \square

Let us study the geometric realizations of big nerves of open covers.

Given a refinement $\{V_\beta\}_{\beta \in J}$ of an open cover $\{U_\alpha\}_{\alpha \in I}$, we can choose a function $\rho: J \rightarrow I$ such that $V_\beta \subseteq U_{\rho(\beta)}$ for all $\beta \in J$. This gives rise to a map $\rho: \mathbf{V} \rightarrow \mathbf{U}$ over X , hence a functor of topological groupoids $\mathbf{V} \rightarrow \mathbf{U}$.

Proposition 3.5.2. *Let $\{V_\beta\}_{\beta \in J}$ be a refinement of an open cover $\{U_\alpha\}_{\alpha \in I}$ of a space X , and let $\rho_1, \rho_2: J \rightarrow I$ be two functions such that $V_\beta \subseteq U_{\rho_i(\beta)}$ for all $\beta \in J$. Then ρ_1 and ρ_2 induce naturally isomorphic functors between the topological groupoids \mathbf{V} and \mathbf{U} .*

In particular, the map $|\rho_|: |\mathcal{N}\mathbf{V}| \rightarrow |\mathcal{N}\mathbf{U}|$ is independent of ρ up to homotopy.*

Proof. Let H be the map over X defined by

$$H: \mathbf{V} \rightarrow \mathbf{U} \times_X \mathbf{U}; \quad x^\beta \mapsto x^{\rho_1(\beta), \rho_2(\beta)}.$$

We use this map to define a natural transformation $h: (\mathbf{V}, \mathbf{V} \times_X \mathbf{V}) \times [1] \rightarrow (\mathbf{U}, \mathbf{U} \times_X \mathbf{U})$ between ρ_1 and ρ_2 . We define

$$h(-, 0) = \rho_1, \quad h(-, 1) = \rho_2, \quad h(x^\beta, 0 \rightarrow 1) = H(x^\beta).$$

It is straightforward to verify that h is a functor. Since its target is a groupoid, it is automatically a natural isomorphism (rather than just a natural transformation) between ρ_1 and ρ_2 . \square

If we consider the case of a trivial cover $\mathcal{X} = \{X \rightarrow X\}$, we find that $|\mathcal{N}\mathbf{X}| \cong X$, and we get a natural map

$$|\mathcal{N}\mathbf{V}| \rightarrow X$$

for any other open cover \mathcal{V} . In fact, this map is well-defined on the nose, not just up to homotopy, since there only is one map from the indexing set of \mathcal{V} to the indexing set of \mathcal{X} , which is a singleton.

Theorem 3.5.3. *The following are equivalent for a space X :*

1. X is paracompact

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2. For every open cover \mathcal{U} , the natural map $p: |\mathcal{N}\mathbf{U}| \rightarrow X$ has a section (i. e., a right inverse)
3. For every open cover \mathcal{U} , the natural map $p: |\mathcal{N}\mathbf{U}| \rightarrow X$ is a deformation retraction.

Proof. (1) \implies (2): First assume that X is paracompact and \mathcal{U} is an open cover. Choose a total order on the indexing set I of \mathcal{U} . We may assume that \mathcal{U} is locally finite and that $f_\alpha: X \rightarrow [0, 1]$ is a partition of unity such that $\overline{f_\alpha^{-1}(0, 1]} \subseteq U_\alpha$.

Define a map $r: X \rightarrow |\mathcal{N}\mathbf{U}|$ as follows. Every point $x \in X$ lies in finitely many U_α , say in U_J , where $J = \{\alpha_0 < \dots < \alpha_n\} \subset I$. Define $r(x)$ to be the equivalence class of the point $(x^J, f_J(x)) \in U_J \times \Delta^n$, where $x^J = x^{\alpha_0, \dots, \alpha_n} \in U_J \subseteq \mathcal{N}_n \mathbf{U}$ and $f_J(x) = (f_{\alpha_0}(x), \dots, f_{\alpha_n}(x)) \in \Delta^n$. We have to show that this map is continuous. Let $J' = \{\alpha \in I \mid x \in \overline{U_\alpha}\} \supseteq J$. By local finiteness, J' must have finite cardinality, say $m + 1$.

To show continuity at x when $m > n$, note that

$$V = U_J - \bigcup_{\beta \in J' - J} \overline{f_\beta^{-1}(0, 1]}$$

is an open neighborhood of x contained in U_J . For every $y \in V$, $f_\beta(y) = 0$ for $\beta \in J' - J$, hence there exists a monotonic map $\sigma: [n] \rightarrow [m]$ such that

$$(y^{J'}, f_{J'}(y)) = (y^{J'}, \sigma_*(f_J(y))) \sim (y^J, f_J(y)).$$

Thus any open neighborhood of x which is contained in V is contained in the equivalence class of $U_J \times \Delta^n$. Thus by continuity of the partition of unity, r is continuous at x . Since the map $p: |\mathcal{N}\mathbf{U}| \rightarrow X$ sends $(x^{\alpha_0, \dots, \alpha_n}, t_0, \dots, t_n)$ to x , we have that $p \circ r = \text{id}_X$, hence r is a section of p .

(2) \implies (1): Assume that $p: |\mathcal{N}\mathbf{U}| \rightarrow X$ has a section r , i. e. a right inverse. Define $f_\alpha: X \rightarrow [0, 1]$ as follows:

$$f_\alpha(x) = \begin{cases} t_i; & r(x) = [x^J, t_0, \dots, t_n] \in U_J \times \Delta^n \text{ and } \alpha \text{ is the } i\text{th index in } J \\ 0; & \text{otherwise.} \end{cases}$$

To see that f_α is well-defined, let $f: J \rightarrow J'$ be a monotonic map to another subset $J' \subseteq I$ and $x \in U_{J'}$. Then

$$(x^J, t_0, \dots, t_n) \sim (x^{J'}, f_*(t_0, \dots, t_n))$$

and f_α picks out the the same coefficient t_i .

Thus f_α is a partition of unity with $\overline{f_\alpha^{-1}(0, 1]} \subseteq U_\alpha$. However, we do not necessarily know that $\overline{f_\alpha^{-1}(0, 1]} \subseteq U_\alpha$. To fix this, define a refinement \mathbf{V} of \mathbf{U} with the same indexing set and

$$V_\alpha = f_\alpha^{-1}\left(\frac{1}{2}, 1\right].$$

Then $\bar{V}_\alpha \subset U_\alpha$, and repeating the above argument for \mathbf{V} , we get a partition of unity associated with \mathbf{U} .

(2) \implies (3): Let $r: X \rightarrow |\mathcal{N}\mathbf{U}|$ be any continuous section of p .

We want to produce a homotopy of the map $r \circ p$ to the identity map on $|\mathcal{N}\mathbf{U}|$.

By (3.2.9), any element of $|\mathcal{N}\mathbf{U}|$ has a unique representative $[x^J, t_0, \dots, t_n]$ where all $t_i > 0$ and x^J is nondegenerate. This means that J is the set of all the α such that $x \in U_\alpha$. This element is mapped under $r \circ p$ to $p(x) = [x^{J'}, u_0, \dots, u_m]$ where $J' \subseteq J$, but this element is equal to $[x^J, i_*(u_0, \dots, u_m)]$, where $i: J' \rightarrow J$ is the inclusion map. We may thus assume that $m = n$ and $J = J'$. We now define a linear homotopy

$$h: [0, 1] \times |\mathcal{N}\mathbf{U}| \rightarrow |\mathcal{N}\mathbf{U}|$$

from $r \circ p$ to the identity by

$$h(s, [x^J, t_0, \dots, t_n]) = [x^J, st_0 + (1-s)u_0, \dots, st_n + (1-s)u_n(x)].$$

(3) \implies (2): obvious.

□

Show that the homotopy is continuous.

3.5.1. Fiber bundles and homotopy invariance

[Define G -fiber bundles here and phrase the following in terms of general fiber bundles.]

Theorem 3.5.4. *Let $f, g: X \rightarrow B$ be homotopic maps, $p: E \rightarrow B$ a vector bundle, and assume that X is paracompact. Then $f^*p \cong g^*p$.*

To prove this, we need a technical result about covering homotopies:

Theorem 3.5.5. *Let B be a paracompact space and $p: E \rightarrow B \times [0, 1]$ a vector bundle. Denote by $E_t \rightarrow B$ the vector bundle $p^{-1}(B \times \{t\}) \rightarrow B \times \{t\} \cong B$. Then there exists a map $r \in \text{map}_B(E, E_1)$ with $r|_{E_1} = \text{id}$ (i. e. a retraction of the inclusion $E_1 \rightarrow E$ over B) such that the diagram*

$$\begin{array}{ccc} E & \xrightarrow{r} & E_1 \\ \downarrow p & & \downarrow p \\ B \times [0, 1] & \longrightarrow & B \end{array}$$

is a pullback diagram.

Proof. This proof follows tom Dieck [tDo8, Chapter 14.3]. By the compactness of $[0, 1]$ and paracompactness of B , there exists a locally finite cover $U_\alpha \times [0, 1]$ of trivializing neighborhoods for p . Let $f_\alpha: B \rightarrow [0, 1]$ be a partition of unity with respect to U_α . Now define

$$F(x) = \max_{\alpha \in I} f_\alpha(x) \quad \text{and} \quad u_\alpha(x) = \frac{f_\alpha(x)}{F(x)}.$$

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Then for every $x \in B$ there is an $\alpha \in I$ such that $f_\alpha(x) = 1$ and $\text{supp}(f_\alpha) \subset U_\alpha$. Now define

$$r_\alpha: B \times [0, 1] \rightarrow B \times [0, 1] \quad \text{by} \quad (x, t) \mapsto (x, \max(t, u_\alpha(x))).$$

This map r_α is covered by a map $\tilde{r}_\alpha: E \rightarrow E$ which is the identity outside of $E_{U_\alpha \times [0, 1]}$ and on the the trivial piece $E_{U_\alpha \times [0, 1]} \cong U_\alpha \times [0, 1] \times k^n$, \tilde{r}_α is given by $(x, t, v) \mapsto (x, \max(t, u_\alpha(x)), v)$. Then $\tilde{r}_\alpha|_{E_1} = \text{id}$ and the diagram

$$\begin{array}{ccc} E & \xrightarrow{\tilde{r}_\alpha} & E \\ \downarrow p & & \downarrow p \\ B \times [0, 1] & \xrightarrow{r_\alpha} & B \times [0, 1] \end{array}$$

is a pullback. Choose a total ordering on I and let r be the (infinite) composition of all the maps \tilde{r}_α . This is well-defined since for every $x \in E$, only finitely many α have $\tilde{r}_\alpha(x) \neq x$. Since $\max(u_\alpha) = 1$, r takes values in E_1 . \square

In particular, we have a bundle isomorphism $r \in \text{map}_{B \times [0, 1]}(E, E_1 \times [0, 1])$ which is the identity on E_1 .

Proof of Theorem 3.5.4. Let $h: X \times [0, 1] \rightarrow B$ be a homotopy from f to g and denote by $H = h^*p$ the pullback bundle over $X \times [0, 1]$. Then $f^*p = H_0$, $g^*p = H_1$, and by Theorem 3.5.5, $H \cong H_1 \times [0, 1]$. Hence $H_0 \cong H_1$. \square

Corollary 3.5.6. *Let B be a paracompact, contractible space. Then any vector bundle $E \rightarrow B$ is trivial.*

Proof. The identity map on B is homotopic to a constant map. The pullback of E along a constant map is a trivial vector bundle. By Theorem 3.5.4, E is thus trivial. \square

3.6. Universal bundles

In the Section 3.3 we constructed a family of spaces EG with a free G -action and which are furthermore (nonequivariantly) contractible, for any Lie group G . If G acts linearly on some vector space V , we can use the free G -action on EG to define a vector space over BG by defining

$$E = EG \times_G V.$$

.....Take up principal bundles

Lemma 3.6.1. *For Lie groups G , $EG \rightarrow BG$ is a principal G -bundle. Hence the vector space $u: E \rightarrow BG$ over BG is a vector bundle.*

Proof. Segal notes in [Seg68] that this fails to be true for a general topological group G , but it does hold for Lie groups. See, for instance, [May75], where May shows that it suffices for a topological group G to be well-pointed for this to hold. \square

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For $G = O(n)$ and $V = \mathbf{R}^n$ with the standard action, or for $G = U(n)$ and $V = \mathbf{C}^n$ with the standard action, the vector bundle $u: E \rightarrow BG$ is called the *universal bundle* for the following reason:

Theorem 3.6.2. *Let $G = O(n)$, $k = \mathbf{R}$, and $V = \mathbf{R}^n$ with the standard action, or for $G = U(n)$, $k = \mathbf{C}$, and $V = \mathbf{C}^n$ with the standard action. Then for any paracompact space X , there is a bijection*

$$\Phi: [X, BG] \rightarrow \text{Vect}_k^n(X)/\text{iso}, \quad [f] \mapsto f^*u,$$

where $\text{Vect}_k^n(X)/\text{iso}$ denotes the set of isomorphism classes of n -dimensional k -vector bundles.

Proof. by Thm. 3.5.4, Φ is well-defined, that is, that it maps homotopic maps to isomorphic vector bundles over X .

To construct an inverse map $\Psi: \text{Vect}_k^n(X) \rightarrow [X, BG]$, let $p: E \rightarrow X$ be an n -dimensional vector bundle. Choose a cover \mathcal{U} of X consisting of trivializing neighborhoods for p . The cocycle corresponding to p with respect to \mathcal{U} gives us a simplicial map

$$\mathcal{N}\mathbf{U} \rightarrow \mathcal{N}G$$

and thus a map on realizations

$$X \simeq |\mathcal{N}\mathbf{U}| \rightarrow |\mathcal{N}G| = BG.$$

□

Corollary 3.6.3. *Any real vector bundle over a paracompact space can be given a Euclidean structure, and any complex vector bundle a Hermitian structure.*

Proof. The inclusion maps $O(n) \rightarrow \text{GL}_n(\mathbf{R})$ and $U(n) \rightarrow \text{GL}_n(\mathbf{C})$ are homotopy equivalences, hence so are $BO(n) \rightarrow B\text{GL}_n(\mathbf{R})$ and $BU(n) \rightarrow B\text{GL}_n(\mathbf{C})$. Thus

$$[X, BO(n)] \rightarrow [X, B\text{GL}_n(\mathbf{R})] \quad \text{and} \quad [X, BU(n)] \rightarrow [X, B\text{GL}_n(\mathbf{C})]$$

are isomorphisms.

□

We can also use universal bundles to compare BG with Grassmannians up to homotopy.

Corollary 3.6.4. *Let G be a Lie group and E a contractible paracompact space with a free $G = \text{GL}_n(k)$ -action. Then $E/G \simeq BG$ and, moreover, the vector bundle $E \times_G k^n \rightarrow E/G$ is universal.*

Proof. By Theorem 3.6.2, there is a map $f: E/G \rightarrow BG$ such that $E \times_G k^n \cong f^*u$. By looking at automorphisms of this vector bundle, we see that this bundle map must come from a G -equivariant map $\tilde{f}: E \rightarrow EG$ which induces f when taking G -quotients. Since both E and EG are contractible, \tilde{f} is a homotopy equivalence. Since E and EG are G -free, \tilde{f} induces an isomorphism on all fibers. It follows that $E/G \rightarrow BG$ is a homotopy equivalence. (It's true locally and hence globally by paracompactness.)

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Corollary 3.6.5. *The maps $G_n(\mathbf{R}^\infty) \rightarrow BGL_n(\mathbf{R})$ and $G_n(\mathbf{C}^\infty) \rightarrow BGL_n(\mathcal{C})$ are homotopy equivalences.*

Proof. It suffices by Corollary 3.6.4 to show that the infinite-dimensional Stiefel “manifolds” $V_n(\mathbf{R}^\infty)$ of n -frames in \mathbf{R}^∞ are contractible. This follows from the observation that the linear homotopy

$$V_n(k^N) \times [0, 1] \rightarrow V_n(k^{N+n})$$

from an n -frame in k^N to the constant map which takes as value the standard n -frame in the last n coordinates of k^{N+n} , is well-defined. \square

4. Cohomology

4.1. Čech cohomology

In order to turn the cocycle characterization into an alternative definition for vector bundles, we need to get rid of the dependence on a particular open cover $\{U_\alpha\}$. A good approach to doing this is via *Čech cohomology*, which has the added benefit of being a suitable definition of singular cohomology. This is where characteristic classes live.

Let $\mathcal{U} = \{U_\alpha\}_{\alpha \in I}$ be an open cover of a space X . As before, we denote by $\mathbf{U} = \coprod_{\alpha \in I} U_\alpha$ the disjoint union of all elements of the cover, by $p: \mathbf{U} \rightarrow X$ the canonical projection. We also abuse notation and write \mathbf{U} for the topological groupoid $(\mathbf{U}, \mathbf{U} \times_X \mathbf{U})$ (cf. Example 2.3.10). The nerve $\mathcal{N}\mathbf{U}$ is thus a simplicial space whose geometric realization is homotopy equivalent with X (Theorem 3.5.3) as long as X is paracompact.

Now let F be a sheaf on X , i. e. a functor from $\text{Open}(X)$ to some category C . If $U, V \in \text{Open}(X)$ are disjoint then $U \sqcup V \in \text{Open}(X)$ is their categorical coproduct in $\text{Open}(X)$. The sheaf condition implies that $F(U \sqcup V) \cong F(U) \times F(V)$. However, if U and V are not disjoint, their categorical coproduct does not exist. This is impractical for what follows; we therefore extend the functor $F: \text{Open}(X) \rightarrow C$ to a larger category.

Definition. A map $f: Y \rightarrow X$ of topological spaces is called a *partial cover* if it is a disjoint union of open inclusions. It is called a *cover* if it is also surjective. Define a category $S(X)$ with objects the partial covers of X and morphisms commuting triangles

$$\begin{array}{ccc} Y_1 & \xrightarrow{f} & Y_2 \\ & \searrow & \swarrow \\ & X & \end{array}$$

Such a map is called a *cover* if f is a cover.

We can now extend the definition of a sheaf:

Definition. A *sheaf on X with values in C* is a contravariant functor $F: S(X) \rightarrow C$ which sends coproducts to products and such that for each cover $f \in \text{Hom}_{S(X)}(U, Y)$, the diagram

$$F(Y) \rightarrow F(U) \rightrightarrows F(U \times_Y U)$$

is an equalizer.

The reason for this extension is that we can now apply the sheaf F to the simplicial space $\mathcal{N}\mathbf{U}$ to get a cosimplicial object in C .

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Definition. The *category of cosimplicial objects in C* is the functor category from the cosimplicial category Δ (cf. Section 3.2) to C . Similarly, the category of *coaugmented* cosimplicial objects in C is the functor category from Δ_+ to C . We denote the images of the standard coface and codegeneracy maps d_n^i and s_n^i in C by the same names.

Definition. For a cover \mathcal{U} , we define the *Čech n -cochains* of X with respect to the cover \mathcal{U} and values in the sheaf $F: S(X) \rightarrow C$ to be

$$C_{\mathcal{U}}^n(X; F) = F(\mathcal{N}_n(\mathbf{U})).$$

Since $\mathcal{N}\mathbf{U}$ is a simplicial object in $S(X)$ and F is a contravariant functor, the Čech cochains form a cosimplicial object in C , coaugmented by $F(X)$:

$$F(X) \rightarrow F(\mathbf{U}) \rightrightarrows F(\mathbf{U} \times_X \mathbf{U}) \cdots$$

Example 4.1.1. We have that $C_{\mathcal{U}}^0(X; F) = \prod_{\alpha} F(U_{\alpha})$. The homomorphism $d_0^0: C^{-1} \rightarrow C^0$ is just restriction: $d_0^0(c)_{\alpha} = c|_{U_{\alpha}}$. In dimension 1, we have

$$C_{\mathcal{U}}^1(X; F) = \prod_{\alpha, \beta} F(U_{\alpha\beta})$$

and the two maps d_0^1 and d_1^1 are given by

$$d_0^1((c_{\alpha}))_{\alpha, \beta} = c_{\beta}|_{U_{\alpha\beta}} \quad \text{and} \quad d_1^1((c_{\alpha}))_{\alpha, \beta} = c_{\alpha}|_{U_{\alpha\beta}}$$

We see that the diagram

$$1 \rightarrow C_{\mathcal{U}}^{-1}(X; F) \xrightarrow{d_0^0} C_{\mathcal{U}}^0(X; F) \begin{matrix} \xrightarrow{d_0^1} \\ \xleftarrow{d_1^1} \end{matrix} C_{\mathcal{U}}^1(X; F)$$

is an equalizer diagram.

Definition. Given a cosimplicial abelian group A , we define maps

$$d^n: A^n \rightarrow A^{n+1} \text{ by } d^n(x) = d_n^0(x) - d_n^1(x) + d_n^2(x) - \cdots \pm d_n^n(x)$$

and groups

$$\begin{aligned} Z^n(A) &= \ker(d^n: A^n \rightarrow A^{n+1}), \\ B^n(A) &= \text{im}(d^{n-1}: A^{n-1} \rightarrow A^n), \end{aligned}$$

and

$$H^n(A) = Z^n(A)/B^n(A)$$

If A is merely a cosimplicial (possible nonabelian) group, we can still define

$$Z^1(A) = \{x \in A^1 \mid d^0(x)d^1(x)^{-1}d^2(x) = 1\}$$

and

$$H^1(A) = Z^1(A)/A^0,$$

where A^0 acts on $Z^1(A)$ by $a_0.a_1 = d_0^1(a_0)a_1d_1^1(a_0)^{-1}$. Note that for abelian A , the two definitions of $H_{\mathcal{U}}^1$ coincide.

If A is just a cosimplicial set, we can only define

$$H^0(A) = Z^0(A) = \{x \in A^0 \mid d_0^0(x) = d_0^1(x)\}.$$

Definition. Let F be a sheaf of abelian groups on a space X and \mathcal{U} an open cover of X . Then the Čech n -cocycles, Čech n -coboundaries, and the n th Čech cohomology groups with respect to the cover \mathcal{U} are defined by

$$Z_{\mathcal{U}}^n(X; F) = Z^n(F(\mathcal{N}\mathbf{U})); \quad B_{\mathcal{U}}^n(X; F) = B^n(F(\mathcal{N}\mathbf{U})); \quad H^n_{\mathcal{U}}(X; F) = H^n(F(\mathcal{N}\mathbf{U})).$$

If F is merely a sheaf of groups, we can still define $Z_{\mathcal{U}}^i$ and $H_{\mathcal{U}}^i$ for $i \leq 1$; for F a sheaf of sets only for $i = 0$.

Definition. A *cosimplicial homotopy* from a cosimplicial object X to a cosimplicial object Y in a category \mathcal{C} is a cosimplicial map $h: X \rightarrow \text{hom}([1], Y)$, where $\text{hom}(S, Y)$ for a simplicial set S and a cosimplicial object Y denotes the cosimplicial object $\text{hom}(S, Y)^n = \text{hom}(S_n, Y^n)$. We say that h is a homotopy from f to g if $h(x)(0) = f(x)$ and $h(x)(1) = g(x)$ and that f and g are *cosimplicially homotopic* if such a homotopy exists.

Lemma 4.1.2. *Cosimplicially homotopic maps induce the same maps in cohomology.*

Proof. For the sake of simplicity, we will show the proof for a sheaf with values in abelian groups, leaving the cases of H^1 for groups and H^0 for sets to the reader.

Given a cosimplicial homotopy $h: X \rightarrow \text{hom}([1], Y)$, denote by $\tilde{h}: X^{n+1} \rightarrow Y^n$ the map defined by $\tilde{h}(x) = \sum_{i=0}^n (-1)^i s^i h(x)(\alpha_i)$, where $\alpha_i: [n] \rightarrow [1]$ is the map that sends $i \rightarrow 0$ and $i+1 \rightarrow 1$. Then \tilde{h} is a homotopy of cochain complexes, i. e. $f - g = d\tilde{h} + \tilde{h}d$. Thus f and g induce the same map in cohomology. □

Check signs and details.

Given a refinement $\{V_{\beta}\}$ of an open cover $\{U_{\alpha}\}$ of X , the map of nerves $\mathcal{N}\mathbf{V} \rightarrow \mathcal{N}\mathbf{U}$ is well-defined up to simplicial homotopy by Proposition 3.5.2 and therefore the map induced on $C_{\mathcal{U}}(X) \rightarrow C_{\mathcal{V}}(X)$ is well-defined up to cosimplicial homotopy and thus induces a well-defined map on Čech cohomology. We have proved:

Theorem 4.1.3. *Let $\{U_{\alpha}\}_{\alpha \in I}$ be an open cover of X with a refinement $\{V_{\beta}\}_{\beta \in J}$. Let $\rho, \sigma: J \rightarrow I$ be two functions such that $V_{\beta} \subseteq U_{\rho(\beta)}$, $V_{\beta} \subseteq U_{\sigma(\beta)}$. Denote by ρ^* and $\sigma^*: C_{\text{mathcal{U}}}^n(X; G) \rightarrow C_{\mathcal{V}}^n(X; G)$ the induced maps on Čech cochains. Then on cohomology,*

$$\rho^* = \sigma^*: H_{\mathcal{U}}^*(X; G) \rightarrow H_{\mathcal{V}}^*(X; G).$$

□

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Definition. The n th Čech cohomology group of X with coefficients in G ($n \in \mathbf{N}_0, n \leq 1$ if G is nonabelian) is the colimit

$$H^n(X; G) = \operatorname{colim}_{\mathcal{U}} H_{\mathcal{U}}^n(X; G),$$

where \mathcal{U} runs over the poset $\operatorname{Cov}(X)$ of open covers of X with a morphism from \mathcal{U} to \mathcal{V} if \mathcal{V} is a refinement of \mathcal{U} .

Lemma 4.1.4. *The poset $C = \operatorname{Cov}(X)$ is directed, i. e. for every two elements $\mathcal{U}, \mathcal{V} \in C$ there is a third element \mathcal{W} with $\mathcal{U} \leq \mathcal{W} \leq \mathcal{V}$.*

Proof. If $\mathcal{U} = \{U_\alpha\}_{\alpha \in I}$ and $\mathcal{V} = \{V_\beta\}_{\beta \in J}$, define $\mathcal{W} = \{U_\alpha \cap V_\beta\}_{(\alpha, \beta) \in I \times J}$. \square

Lemma 4.1.5. *Let $F: C \rightarrow \operatorname{Set}$ be a functor, where C is a directed ordered set. Then*

1. *For every $x \in \operatorname{colim}_C F$, there exists $c \in C$ and $x_c \in F(c)$ such that $\iota_c(c) = x$.*
2. *If $x \in F(c)$ and $y \in F(d)$ are such that $\iota_c(x) = \iota_d(y) \in \operatorname{colim}_C F$ then there exists $e \in C, c \leq e \leq d$ such that $x \mapsto e$ and $y \mapsto e$ in $F(e)$.*

Proof. The first part is obvious. For the second part, we may assume $c = d$ since we can otherwise pass to a common upper bound of c and d in C because C is directed. If $\alpha_*(x) \neq \alpha_*(y)$ for all $\alpha: c \rightarrow e$ then we can construct compatible maps from $F(a)$ to $\{0, 1\}$ for all $a \in C$ with $\alpha(c) \mapsto 0$ and $\alpha(d) \mapsto 1$ and hence the induced map from the colimit must map $\iota_c(x)$ to 0 and $\iota_c(y)$ to 1, which is a contradiction. \square

Theorem 4.1.6. *Let X be a paracompact space and $\mathcal{GL} = \coprod_{n \geq 0} \operatorname{GL}_n(k)$ be the groupoid of general linear groups. Then the natural map*

$$\Phi: \{\text{vector bundles on } X\}/\text{iso} \rightarrow H^1(X, \mathcal{GL})$$

which sends a vector bundle to the equivalence class of its cocycle, is a bijection.

Proof. By Propositions 2.3.5 and 2.3.6, the map

$$\{\text{vector bundles on } X \text{ with trivializing cover } \mathcal{U}\}/\text{iso} \rightarrow H_{\mathcal{U}}^1(X, \mathcal{GL})$$

is a bijection and induces a well-defined map Φ as in the statement of the theorem. For injectivity, assume two vector bundles induce the same cohomology class in the colimit. Then by the above lemma, they have to agree already for some cover \mathcal{U} . Hence the cocycles are cohomologous for the cover \mathcal{U} and the corresponding vector bundles are isomorphic. For surjectivity, any cohomology class lies in $H_{\mathcal{U}}^1$ for some \mathcal{U} by the above lemma and hence comes from a vector bundle trivialized over \mathcal{U} . \square

4.2. The long exact sequence

Lemma 4.2.1. *Let $F', F, F'': C \rightarrow \text{Ab}$ be functors from a directed set C to abelian groups and assume there are natural transformations $F' \rightarrow F \rightarrow F''$ such that $F'(c) \rightarrow F(c) \rightarrow F''(c)$ is exact for all c . Then $\text{colim}_C F' \rightarrow \text{colim}_C F \rightarrow \text{colim}_C F''$ is also exact.*

Proof. Let $x \in \text{colim}_C F$ map to 0 in $\text{colim}_C F''$. Choose a representative $x_c \in F(c)$, which exists by Lemma 4.1.4. While x_c might not map to 0 in $F''(c)$, it maps to 0 in $F''(d)$ for some $d \geq c$ by Lemma 4.1.4 again. Replacing c by d , we can thus assume without loss of generality that it does map to 0 in $F''(c)$. By exactness at c , there is thus a preimage in $F'(c)$, which maps to a preimage in $\text{colim}_C F'$. \square

Lemma 4.2.2. *Let $0 \rightarrow A' \xrightarrow{i} A \xrightarrow{j} A'' \rightarrow 0$ be a short exact sequence of cosimplicial abelian groups. Then there is a long exact sequence in cohomology*

$$0 \rightarrow H^0(A') \xrightarrow{j^*} H^0(A) \xrightarrow{i^*} H^0(A'') \xrightarrow{\delta} H^1(A') \xrightarrow{j^*} H^1(A) \xrightarrow{i^*} H^1(A'') \xrightarrow{\delta} \dots$$

If $0 \rightarrow A' \xrightarrow{i} G \xrightarrow{j} G'' \rightarrow 1$ is merely a short exact sequence of groups with A' abelian (and normal in A), we still have a somewhat long exact sequence of pointed sets

$$0 \rightarrow H^0(A') \xrightarrow{j^*} H^0(G) \xrightarrow{i^*} H^0(G'') \xrightarrow{\delta} H^1(A') \xrightarrow{j^*} H^1(G) \xrightarrow{i^*} H^1(G'') \xrightarrow{\delta} H^2(A').$$

Proof. The first statement is a standard result from homological algebra once we notice that a short exact sequence of cosimplicial abelian groups gives rise to a short exact sequence of cochain complexes.

The second part is a good exercise. \square

Corollary 4.2.3. *Let $0 \rightarrow A' \xrightarrow{i} A \xrightarrow{j} A'' \rightarrow 0$ be a sequence of sheaves of abelian groups which is exact as a sequence of presheaves. Then for any space X , there is a natural long exact sequence of Čech cohomology groups*

$$0 \rightarrow H_{\mathcal{U}}^0(X; A') \rightarrow H_{\mathcal{U}}^0(X; A) \rightarrow H_{\mathcal{U}}^0(X; A'') \xrightarrow{d} H_{\mathcal{U}}^1(X; A') \rightarrow \dots$$

as well as their colimits

$$0 \rightarrow H^0(X; A') \rightarrow H^0(X; A) \rightarrow H^0(X; A'') \xrightarrow{d} H^1(X; A') \rightarrow \dots$$

Proof. By assumption, $0 \rightarrow C_{\mathcal{U}}^n(X; A') \rightarrow C_{\mathcal{U}}^n(X; A) \rightarrow C_{\mathcal{U}}^n(X; A'') \rightarrow 0$ is exact for each n . By Lemma 4.2.2, the first part follows. The second claim follows from the first by Lemma 4.2.1. \square

Counterexample for short exact sequences of sheaves? Cf. Godement 5.10/11

4.3. The Mayer-Vietoris sequence

Let $X = U \cup V$ be a union of two open sets and A a sheaf of abelian groups on X . By the gluing axiom of sheaves, we have that

$$0 \rightarrow A(X) \rightarrow A(U) \oplus A(V) \rightarrow A(U \cap V)$$

4. Cohomology

is exact, where the right hand side map is the difference of the restriction maps. Let us assume in addition that for every inclusion of open sets $U' \subseteq U''$, the induced map of sheaves $A(U'') \rightarrow A(U')$ is surjective. Then the above sequence is also right exact.

Now let \mathcal{U} be an open cover of X with $\mathbf{U} = \bigsqcup \mathcal{U}$. For a subspace $Y \subset X$, denote by $\mathbf{U}|_Y$ the cover $\bigsqcup_{U \in \mathcal{U}} U \cap Y$. Then

$$0 \rightarrow A(\mathcal{N}\mathbf{U}) \rightarrow A(\mathcal{N}(\mathbf{U}|_U)) \oplus A(\mathcal{N}(\mathbf{U}|_V)) \rightarrow A(\mathcal{N}(\mathbf{U}|_{U \cap V})) \rightarrow 0$$

is a short exact sequence of chain complexes and therefore gives rise to a long exact sequence in Čech cohomology:

$$0 \rightarrow H^0(U \cap V, A) \rightarrow H^0(U, A) \oplus H^0(V, A) \rightarrow H^0(X, A) \rightarrow H^1(U \cap V, A) \rightarrow \dots$$

This is known as the Mayer-Vietoris sequence.

4.4. The product in cohomology

Let X, Y be spaces and A, B sheaves of abelian groups on X resp. Y . Furthermore let \mathcal{U} and \mathcal{V} be open covers of X resp. Y .

We can now consider the presheaf on $X \times Y$ given by

$$U \times V \mapsto A(U) \otimes B(V),$$

and extended to all opens of $X \times Y$ by the gluing condition. This, unfortunately, is often not a sheaf due to the fact that the tensor product does not preserve the equalizer diagram in the sheaf condition. We need to “sheafify”.

Proposition 4.4.1. *Let X be a topological space and $F: B^{\text{op}} \rightarrow C$ a presheaf defined on some basis $B \subseteq \text{Open}(X)$ of the topology of X with values in a category C that has all limits and directed colimits. As for sheaves, let F_x denote the stalk of F at $x \in B$ and, for $t \in F(V)$ and $x \in V$, let t_x denote the image of t in F_x . Let $\mathcal{U} = \{U_\alpha\}_{\alpha \in I} \subseteq B$ be an open cover of $U \subseteq X$. Define*

$$\tilde{F}: \text{Open}(X)^{\text{op}} \rightarrow C$$

by $F(U) = \text{colim}_{\mathcal{U}} F_{\mathcal{U}}(U)$ over all open covers of U , where $F_{\mathcal{U}}(U)$ is the equalizer

$$F_{\mathcal{U}}(U) \rightarrow \prod_{\alpha} F(U_{\alpha}) \rightrightarrows \prod_{\alpha, \beta \in I, x \in U_{\alpha\beta}} F_x,$$

where the maps are given by $t^{\alpha} \mapsto (t_x)^{\alpha, \beta}$ and $t^{\alpha} \mapsto (t_x)^{\beta, \alpha}$, respectively.

Then \tilde{F} is a sheaf on X and the map of presheaves $F \rightarrow \tilde{F}$ given by restriction has the universal property that for any other sheaf G on X ,

$$\text{Hom}(F, G|_B) \cong \text{Hom}(\tilde{F}, G).$$

Proof. Exercise. □

4.5. De Rham cohomology of manifolds

We apply this proposition for the basis $B = \{U \times V\}$ of $X \times Y$ to construct the sheaf $A \otimes B$ on $X \times Y$ as

$$A \otimes B = (U \times V \mapsto A(U) \otimes B(V))^\sim$$

Now write $\mathcal{U} \times \mathcal{V}$ for the open cover of $X \times Y$ by the open sets $U \times V$ with $U \in \mathcal{U}$ and $V \in \mathcal{V}$.

Then we can define an “external product”

$$C_{\mathcal{U}}^m(X; A) \otimes C_{\mathcal{V}}^n(Y; B) \rightarrow C_{\mathcal{U} \times \mathcal{V}}^{m+n}(X \times Y; A \otimes B)$$

by sending $\alpha \otimes \beta$ to the cochain $\alpha \times \beta$ defined on the summand $(U_{i_0} \times V_{j_0}) \cap \cdots \cap (U_{i_{m+n}} \times V_{j_{m+n}})$ by

$$\alpha \times \beta = \alpha|_{U_{i_0 \dots i_m}} \otimes \beta|_{V_{j_m \dots j_{m+n}}}.$$

This product is compatible with the differentials d^n in the sense that

$$d^{m+n}(\alpha \times \beta) = d^m(\alpha) \times \beta + (-1)^m \alpha \times d^n(\beta)$$

as can be seen directly from the definition. In particular, it induces a well-defined product

$$H_{\mathcal{U}}^m(X; A) \otimes H_{\mathcal{V}}^n(Y; B) \xrightarrow{\times} H_{\mathcal{U} \times \mathcal{V}}^{m+n}(X \times Y; A \otimes B)$$

since if α and β are cycles then so is $\alpha \times \beta$, and if $\alpha = d^{m-1}(\gamma)$ and β is a cycle then $d^{m+n-1}(\gamma \times \beta) = \alpha \times \beta + (-1)^{m-1} \gamma \times 0$, thus $\alpha \times \beta$ is a boundary, and similarly if β is a boundary.

Since the product \times is natural with respect to refinements of coverings, it thus induces an external product in Čech cohomology.

Now if R is a sheaf of rings on a space X , we can construct a product

$$H^m(X; R) \otimes H^n(X; R) \xrightarrow{\times} H^{m+n}(X \times X; R \times R) \xrightarrow{\Delta^*} H^{m+n}(X; R \otimes R) \xrightarrow{\text{mult.}} H^{m+n}(X; R).$$

This turns $H^*(X; R)$ into a graded ring.

4.5. De Rham cohomology of manifolds

Let M be a smooth manifold and $E \rightarrow M$ a real vector bundle. Then we define the sheaf of alternating k -forms with values in E as

$$\Omega^k(M; E) = \bigwedge_{i=1}^k T^*M \otimes E,$$

where $T^*M = \text{Hom}(TM, \mathbf{R})$ is the cotangent bundle, i. e. the linear dual of the tangent bundle. These sheaves fit into a chain complex

$$0 \rightarrow \Omega^0(M; E) = E \xrightarrow{d} \Omega^1(M; E) \xrightarrow{d} \cdots, \quad (4.5.1)$$

where $d: \Omega^k(M; E) \rightarrow \Omega^{k+1}(M; E)$ is the exterior differential:

$$d(\omega \otimes x) = (d\omega) \otimes x.$$

Note that $\Omega^k(M; E) = 0$ if $k > \dim(M)$.

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Lemma 4.5.2 (Poincaré lemma). *The sequence (4.5.1) is exact.*

Definition. The k th de Rham cohomology of M with coefficients in E is the k th cohomology of the chain complex of global sections of (4.5.1):

$$H_{dR}^k(M; E) = H^k(\Gamma(\Omega^\bullet(M; E))).$$

Theorem 4.5.3. *There is a natural isomorphism $H^k(M; E) \rightarrow H_{dR}^k(M; E)$ between Čech cohomology and de Rham cohomology on a smooth manifold M .*

Proof. Since the sequence (4.5.1) is exact, we have short exact sequences of sheaves

$$0 \rightarrow d\Omega^{k-1}(M; E) \rightarrow \Omega^k(M; E) \rightarrow d\Omega^k(M; E) \rightarrow 0.$$

Since $\Omega^k(M; E)$ is a module sheaf over $C^\infty(M)$, its Čech cohomology vanishes by ???. Thus the long exact sequence in Čech cohomology induced by the above short exact sequence splits up into a sequence of isomorphisms

$$H^n(M; d\Omega^k(M; E)) \xrightarrow{\sim} H^{n+1}(M; d\Omega^{k-1}(M; E)).$$

In particular,

$$H^0(M; \Omega^n(M; E))$$

□

5. Characteristic classes

5.1. Stiefel-Whitney classes

5.2. Chern classes

5.3. Pontryagin classes

6. Chern-Weil theory

6.1. Riemannian manifolds

6.2. Connections

Definition. Let E be a smooth k -vector bundle on a smooth manifold M , considered as a sheaf of locally free C_M^∞ -modules. A *connection* on E is a map of sheaves

$$\nabla: E \rightarrow \Omega_M^1 \otimes_{\mathbf{R}} E$$

which satisfies the following Leibniz rule for $f \in C_M^\infty(U)$, $s \in E(U)$:

$$\nabla(fs) = df \otimes s + f\nabla(s) \in \Omega_M^1(U) \otimes E(U).$$

Note that ∇ is *not* a map of vector bundles: the target is not a vector bundle as we're tensoring over \mathbf{R} , not over C^∞ .

Definition. A connection ∇ on $\Omega_M^1 = (TM)^*$ is called *torsion-free* if the following diagram of C_M^∞ -module sheaves commutes:

$$\begin{array}{ccc} \Omega_M^1 & \xrightarrow{\nabla} & \Omega_M^1 \otimes \Omega_M^1 \\ & \searrow d & \downarrow \wedge \\ & & \Omega_M^2 \end{array}$$

Definition. Let M be a smooth manifold and E a smooth vector bundle with metric \langle, \rangle . A connection on E is called *compatible with \langle, \rangle* if the following diagram of C_M^∞ -module sheaves commutes:

$$\begin{array}{ccc} E \otimes E & \xrightarrow{\langle, \rangle} & C_M^\infty \\ \nabla \otimes \text{id} + \text{id} \otimes \nabla \downarrow & & \downarrow d \\ \Omega_M^1 \otimes E \otimes E & \xrightarrow{\text{id} \otimes \langle, \rangle} & \Omega_M^1 \end{array}$$

A connection on TM compatible with a Riemannian metric is called a *Riemannian connection*.

Theorem 6.2.1. *On every Riemannian manifold, there exists exactly one Levi-Civita connection.*

6.3. Curvature

Lemma 6.3.1. *The morphism $\nabla^2: E \rightarrow \Omega_M^2 \otimes E$ is a map of vector bundles.*

6.4. Characteristic classes from curvature

6.5. The generalized Gauß-Bonnet theorem

Theorem 6.5.1. *Let E be an oriented n -dimensional real vector bundle, where n is even. Choose a Euclidean metric on E and a compatible connection, and let $K: E \rightarrow \Omega_M^2 \otimes E$ denote the corresponding curvature tensor. Then*

$$\text{Pf}(K) = e(E).$$

7. Characteristic classes in algebraic geometry

7.1. Varieties and algebraic vector bundles

7.2. Chow groups

7.3. Chern classes

7.4. Segre classes

A. Notions from category theory

In this appendix, we collect some basic notions of category theory needed in these notes. A much more thorough and comprehensive treatment can be found in, e.g., [ML98, Bor94]. If the reader is completely unfamiliar with the language of category theory, he or she may find it helpful to consider one of these sources.

Definition. A category \mathcal{C} consists of a class $\text{ob } \mathcal{C}$ of *objects* and, for each pair $x, y \in \text{ob } \mathcal{C}$, a set $\text{Hom}_{\mathcal{C}}(x, y)$ of *morphisms*, together with the following structure:

- for each $x \in \text{ob } \mathcal{C}$, a distinguished element $\text{id}_x \in \text{Hom}_{\mathcal{C}}(x, x)$, called the *identity*,
- for each triple (x, y, z) of objects, a *composition map* $\mu: \text{Hom}_{\mathcal{C}}(y, z) \times \text{Hom}_{\mathcal{C}}(x, y) \rightarrow \text{Hom}_{\mathcal{C}}(x, z)$.

Usually, composition $\mu(g, f)$ is denoted suggestively by $g \circ f$. These have to satisfy the axioms that composition must be associative and unital with respect to the identities.

A (covariant) *functor* $F: \mathcal{C} \rightarrow \mathcal{D}$ between two categories \mathcal{C} and \mathcal{D} is a collection of maps

$$F: \text{ob } \mathcal{C} \rightarrow \text{ob } \mathcal{D} \quad \text{and} \quad F: \text{Hom}_{\mathcal{C}}(x, y) \rightarrow \text{Hom}_{\mathcal{D}}(F(x), F(y)) \quad \text{for each } x, y \in \text{ob } \mathcal{C}$$

such that $F(\text{id}_x) = \text{id}_{F(x)}$ for each $x \in \text{ob } \mathcal{C}$, and $F(g \circ f) = F(g) \circ F(f)$ for each composable pair of morphisms f, g .

Examples of categories abound: sets and functions, ordered sets and monotonic maps, vector spaces and linear maps, groups and homomorphisms, topological spaces and continuous maps, and so on. These are all examples of so-called *large* categories, where the class $\text{ob } \mathcal{C}$ of objects indeed is a proper class, not a set. A category where this is not the case, i. e., where $\text{ob } \mathcal{C}$ is a set, is called *small*. An example of a small category is the category Δ whose objects are the totally ordered sets $[n] = \{0, \dots, n\}$ and whose morphisms are monotonic maps. In this case, $\text{ob } \Delta$ is countable.

Example A.0.1. Partially ordered sets (posets) can be thought of as small categories. If (X, \leq) is a poset, we construct a category with object set X and

$$\text{Hom}(x, y) = \begin{cases} \{*\}; & x \leq y \\ \emptyset; & \text{otherwise} \end{cases}$$

Note that reflexivity of the order relation corresponds to the existence of identities, transitivity gives a unique composition rule, and antisymmetry translates to the fact that there are no non-identity isomorphisms. The category thus obtained is also denoted by X .

A. Notions from category theory

Example A.0.2. There are plenty of ways to construct new categories from old. Here follows some common constructions:

- a) Let \mathcal{C} be a category. The category \mathcal{C}^{op} , called the *opposite category* of \mathcal{C} , has the same objects as \mathcal{C} , but it has $\text{Hom}_{\mathcal{C}^{\text{op}}}(x, y) = \text{Hom}_{\mathcal{C}}(y, x)$. The identities are the same, but composition is defined in the opposite order:

$$\mu_{\mathcal{C}^{\text{op}}}(g, f) = \mu_{\mathcal{C}}(f, g).$$

This also gives a trivial yet important *duality principle* in category theory: “If some statement P holds in a category, then so does the dualized statement P^{op} with the direction of morphisms reversed”.

- b) \mathcal{D} is a *subcategory* of \mathcal{C} if $\text{ob } \mathcal{D} \subseteq \text{ob } \mathcal{C}$ and for $x, y \in \text{ob } \mathcal{D}$ we have $\text{Hom}_{\mathcal{D}}(x, y) \subseteq \text{Hom}_{\mathcal{C}}(x, y)$. For example the category of abelian groups form a subcategory of the category of groups, the category of sheaves form a subcategory of the category of presheaves and the category of n -dimensional vector bundles over a space B forms a subcategory of the category of all vector bundles over B etc.
- c) Given categories \mathcal{C} and \mathcal{D} the *product category* $\mathcal{C} \times \mathcal{D}$ has objects (x, y) where $x \in \text{ob } \mathcal{C}$ and $y \in \text{ob } \mathcal{D}$, and morphisms $(f, g) : (x, y) \rightarrow (u, v)$ where $f : x \rightarrow u$ in \mathcal{C} and $g : y \rightarrow v$ in \mathcal{D} .
- d) Let \mathcal{C} be a category and $b \in \text{ob } \mathcal{C}$. The *slice category* \mathcal{C}/b is the category with $\text{ob } \mathcal{C}/b = \text{Hom}_{\mathcal{C}}(\text{ob } \mathcal{C}, b)$, that is, the morphisms in \mathcal{C} with codomain b . The morphisms $(f : x \rightarrow b) \rightarrow (g : y \rightarrow b)$ in \mathcal{C}/b are given by morphisms $h \in \text{Hom}_{\mathcal{C}}(x, y)$ making below triangle commute

$$\begin{array}{ccc} x & \xrightarrow{h} & y \\ & \searrow f & \swarrow g \\ & b & \end{array}$$

Examples of slice categories include the category of topological spaces over a base space B which forms part of the definition of the category of vector bundles. Dually one may define the *coslice category* $\mathcal{C} \backslash b$ with objects $\text{Hom}_{\mathcal{C}}(b, \text{ob } \mathcal{C})$ and morphisms defined analogously.

Example A.0.3. Basic examples of functors include:

- a) The *identity functor* $\text{id}_{\mathcal{C}} : \mathcal{C} \rightarrow \mathcal{C}$ is the functor sending every object to itself and every morphism to itself.
- b) A *contravariant functor* $F : \mathcal{C} \rightarrow \mathcal{D}$ is simply a covariant functor $\mathcal{C}^{\text{op}} \rightarrow \mathcal{D}$. Presheaves are examples of contravariant functors, as is the functor from the category of vector spaces over a field k to its opposite category, assigning to every vector space its dual space and every linear map to its dual linear map.

- c) If \mathcal{D} is a subcategory of \mathcal{C} then there is an *inclusion functor* $\mathcal{D} \hookrightarrow \mathcal{C}$. Likewise if $\mathcal{C} \times \mathcal{D}$ is a product category we have *projection functors* $\pi_1 : \mathcal{C} \times \mathcal{D} \rightarrow \mathcal{C}$ and $\pi_2 : \mathcal{C} \times \mathcal{D} \rightarrow \mathcal{D}$.
- d) A *forgetful functor* $F : \mathcal{C} \rightarrow \mathcal{D}$ is a functor which “forgets” part of the structure in \mathcal{C} . For example we can define a functor F from the category of groups to the category of sets by mapping every group to its underlying set and every homomorphism to its underlying function, forgetting the group structure. Similarly we have a functor from the category of rings to the category of groups by forgetting the ring multiplication.
- e) A functor between partially ordered sets is an order-preserving map.
- f) Let \mathcal{C} be a category and $x \in \text{ob } \mathcal{C}$, the *Hom-functor* $\text{Hom}(x, -) : \mathcal{C} \rightarrow \text{Set}$ sends each object $y \in \text{ob } \mathcal{C}$ to the set $\text{Hom}_{\mathcal{C}}(x, y)$ and every morphism $g \in \text{Hom}_{\mathcal{C}}(y, z)$ to the morphism

$$\begin{aligned} \text{Hom}(x, g) : \text{Hom}_{\mathcal{C}}(x, y) &\rightarrow \text{Hom}_{\mathcal{C}}(x, z) \\ x \xrightarrow{f} y &\mapsto x \xrightarrow{f} y \xrightarrow{g} z \end{aligned}$$

Note that this functor simply post-composes morphisms with g .

A.1. Natural transformations and equivalences

One can perfectly well talk about isomorphism of categories, but often this is a notion too strict to be useful in practice. One therefore mimicks homotopy theory and defines “homotopies” between functors (natural transformations) and “homotopy equivalences” of categories (equivalences).

Definition. Let $F, G : \mathcal{C} \rightarrow \mathcal{D}$ be two functors between categories. A *natural transformation* $\eta : F \rightsquigarrow G$ consists of a morphism $\eta_x : F(x) \rightarrow G(x)$ for each $x \in \text{ob}(\mathcal{C})$ such that the following diagram commutes for each morphism $f \in \text{Hom}_{\mathcal{C}}(x, y)$:

$$\begin{array}{ccc} F(x) & \xrightarrow{\eta_x} & G(x) \\ \downarrow F(f) & & \downarrow G(f) \\ F(y) & \xrightarrow{\eta_y} & G(y) \end{array}$$

If η_x is an isomorphism for each x , we call η a natural isomorphism and the functors F, G isomorphic. A pair of functors $F : \mathcal{C} \rightarrow \mathcal{D}$ and $G : \mathcal{D} \rightarrow \mathcal{C}$ together with natural isomorphisms $\text{id}_{\mathcal{C}} \rightarrow G \circ F$ and $\text{id}_{\mathcal{D}} \rightarrow F \circ G$ is called an *equivalence of categories*.

If \mathcal{C} is a small category then the *functor category* $[\mathcal{C}, \mathcal{D}]$ has as objects the functors $F : \mathcal{C} \rightarrow \mathcal{D}$ and as morphisms the natural transformations between them.

Often, one loosely says that a certain map is “natural.” Note that this has a very concrete meaning, as opposed to “canonical” maps.

A. Notions from category theory

Definition. Let $F: \mathcal{C} \rightarrow \mathcal{D}$ be a functor. We say that F is *faithful* if for every pair of objects $x, y \in \mathcal{C}$, $F: \text{Hom}_{\mathcal{C}}(x, y) \rightarrow \text{Hom}_{\mathcal{D}}(Fx, Fy)$ is injective, and that F is *full* if that map is surjective. The functor F is called *essentially surjective (on objects)* if for every $y \in \text{ob } \mathcal{D}$ there exists $x \in \text{ob } \mathcal{C}$ such that $Fx \cong y$.

Proposition A.1.1. Let $F: \mathcal{C} \rightarrow \mathcal{D}$ be a functor. Then F is part of an equivalence (F, G, α, β) if and only if F is full, faithful, and essentially surjective on objects.

Proof. Suppose the data (F, G, α, β) gives an equivalence between the categories \mathcal{C} and \mathcal{D} .

F faithful: Let $f, g \in \text{Hom}_{\mathcal{C}}(x, y)$ with $Ff = Fg$. By naturality of the isomorphism $\alpha: \text{id}_{\mathcal{C}} \rightarrow GF$ we have the following commutative squares

$$\begin{array}{ccc} x & \xrightarrow[\cong]{\alpha_x} & GFx \\ f \downarrow & & \downarrow GFf \\ y & \xrightarrow[\alpha_y]{\cong} & GFy \end{array} \quad \begin{array}{ccc} x & \xrightarrow[\cong]{\alpha_x} & GFx \\ g \downarrow & & \downarrow GFg \\ y & \xrightarrow[\alpha_y]{\cong} & GFy \end{array}$$

Thus $f = \alpha_y^{-1} \circ GFf \circ \alpha_x = \alpha_y^{-1} \circ GFg \circ \alpha_x = g$. Hence F is faithful. By a similar argument one shows G is faithful.

F full: Let $h: Fx \rightarrow Fy$ be a morphism in \mathcal{D} . Define $f: x \rightarrow y$ via the composition

$$\begin{array}{ccc} x & \xrightarrow[\cong]{\alpha_x} & GFx \\ f \downarrow & & \downarrow Gh \\ y & \xrightarrow[\alpha_y]{\cong} & GFy \end{array}$$

so that $f = \alpha_y^{-1} \circ Gh \circ \alpha_x$. By naturality of α , f also makes below diagram commute

$$\begin{array}{ccc} x & \xrightarrow[\cong]{\alpha_x} & GFx \\ f \downarrow & & \downarrow GFf \\ y & \xrightarrow[\alpha_y]{\cong} & GFy \end{array}$$

Therefore $\alpha_y^{-1} \circ GFf \circ \alpha_x = \alpha_y^{-1} \circ Gh \circ \alpha_x \implies GFf = Gh \implies Ff = h$ since G is faithful. Hence F is full.

F essentially surjective: Let $y \in \text{ob } \mathcal{D}$. Since $\beta: \text{id}_{\mathcal{D}} \rightarrow FG$ is a natural isomorphism we have that $y \xrightarrow{\beta_y} FGy$. Thus letting $x := Gy \in \text{ob } \mathcal{C}$ we get that $y \cong Fx$ as required. Hence F is essentially surjective. Conversely suppose $F: \mathcal{C} \rightarrow \mathcal{D}$ is full, faithful and essentially surjective on objects. We construct a functor G and a natural isomorphism $\beta: \text{id}_{\mathcal{D}} \rightarrow FG$ as follows: For each $y \in \text{ob } \mathcal{D}$ choose a pair (Gy, β_y) such that $\beta_y: y \rightarrow$

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FGy is an isomorphism. Such an isomorphism exists since F is essentially surjective on objects. Next we define what G should do on morphisms. Given a morphism $h : y \rightarrow z$ in \mathcal{D} the composite

$$\begin{array}{ccc} y & \xrightarrow{h} & z \\ \beta_y^{-1} \uparrow \cong & & \cong \downarrow \beta_z \\ FGy & \xrightarrow{F(Gh)} & FGz \end{array}$$

can be written $F(Gh)$ for a unique morphism $Gh : Gy \rightarrow Gz$ since F is full and faithful. We have left to check that G is a functor. Clearly if $h = \text{id}_y$ then

$$\begin{array}{ccc} y & \xrightarrow{\text{id}_y} & y \\ \beta_y^{-1} \uparrow \cong & & \cong \downarrow \beta_y \\ FGy & \xrightarrow{F(G \text{id}_y)} & FGy \end{array}$$

so $F(G \text{id}_y) = \beta_y \circ \text{id}_y \circ \beta_y^{-1} = \text{id}_{FGy} = F(\text{id}_{Gy}) \implies G \text{id}_y = \text{id}_{Gy}$ since F is faithful. Moreover if $h' : z \rightarrow u$ is a morphism in \mathcal{D} then both $G(h' \circ h)$ and $G(h') \circ G(h)$ are the unique f making below square commute

$$\begin{array}{ccc} y & \xrightarrow{h' \circ h} & w \\ \beta_y \downarrow & & \downarrow \beta_w \\ FGy & \xrightarrow{Ff} & FGw \end{array}$$

Therefore $G(h' \circ h) = G(h') \circ G(h)$. Thus G is a functor. Now $\beta : \text{id}_{\mathcal{D}} \rightarrow FG$ is natural by construction. We obtain α_x from the component $\beta_{Fx} : Fx \rightarrow FGFx$ since $\beta_{Fx} = F(\alpha_x)$ for unique $\alpha_x : x \rightarrow GFx$ because F is full and faithful. Similarly $\beta_{Fx}^{-1} : FGFx \rightarrow Fx$ can be written as $\beta_{Fx}^{-1} = Ff$ for some morphism $f : GFx \rightarrow x$ since F is full and faithful. Thus $F \text{id}_x = \text{id}_{Fx} = \beta_{Fx}^{-1} \circ \beta_{Fx} = Ff \circ F(\alpha_x) = F(f \circ \alpha_x) \implies \text{id}_x = f \circ \alpha_x$ since F is faithful. Similarly $\alpha_x \circ f = \text{id}_{GFx}$ so α_x is an isomorphism. Finally α is natural since by naturality of β below square commutes

$$\begin{array}{ccc} Fx & \xrightarrow{\beta_{Fx} = F\alpha_x} & FGFx \\ Ff \downarrow & & \downarrow FGFf \\ Fy & \xrightarrow{\beta_{Fy} = F\alpha_y} & FGFy \end{array}$$

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so $F\alpha_y \circ Ff = FGFf \circ F\alpha_x \implies F(\alpha_y \circ f) = F(GFf \circ \alpha_x) \implies \alpha_y \circ f = GFf \circ \alpha_x$ since F is faithful. Hence α is natural giving the equivalence (F, G, α, β) between categories \mathcal{C} and \mathcal{D} . \square

A.2. Limits and colimits

One of the most powerful concepts of category theory is the notions of (co)limits. Let I be any small category, which we will call the *indexing category*, and let $F: I \rightarrow \mathcal{C}$ be a functor into another, not necessarily small, category \mathcal{C} . We sometimes refer to F as a *diagram* in \mathcal{C} .

Definition. An object $X \in \mathcal{C}$ together with morphisms $p_i: X \rightarrow F(i)$ for each $i \in \text{ob}(I)$ is called a *cone* for F if for each $\alpha \in \text{Hom}_I(i, j)$, $\alpha \circ F(p_i) = F(p_j)$, i. e. if the maps p_i are compatible with the maps in the diagram. A cone (X, p_i) is called a *limit* for F if it is universal. This means that for any other cone (Y, q_i) there is a unique morphism $f \in \text{Hom}_{\mathcal{C}}(Y, X)$ such that $q_i = p_i \circ f$ for all $i \in I$.

A *cocone* resp. *colimit* of F is defined as a cone resp. limit of the functor $F^{\text{op}}: I^{\text{op}} \rightarrow \mathcal{C}^{\text{op}}$; however, since we will be using this quite often, here is what this means explicitly:

Definition. An object $X \in \mathcal{C}$ together with morphisms $\iota_i: F(i) \rightarrow X$ for each $i \in \text{ob}(I)$ is called a *cocone* for F if for each $\alpha \in \text{Hom}_I(i, j)$, $\iota_j \circ \alpha = \iota_i$. A cocone (X, ι_i) is called a *colimit* for F if for any other cocone (Y, η_i) there is a unique morphism $f \in \text{Hom}_{\mathcal{C}}(X, Y)$ such that $\iota_i = f \circ \eta_i$ for all $i \in I$.

(Co)limits need not exist, but if they do exist, they are unique up to unique isomorphism. One denotes the unique limit by $\lim F = \lim_{i \in I} F(i)$, neglecting the cone maps p_i in the notation, and the colimit by $\text{colim } F = \text{colim}_{i \in I} F(i)$.

A category that has (co)limits for all diagrams is called (co)complete.

The limit for the empty diagram ($\text{ob } I = \emptyset$) is called a *initial object*, if it exists, and the colimit a *terminal object*. By definition, an object x is initial if $\text{Hom}(x, y)$ is a singleton for every $y \in \mathcal{C}$; analogously x is terminal if $\text{Hom}(y, x)$ is a singleton for every $y \in \mathcal{C}$.

A category I is called *discrete* if

$$\text{Hom}_{\mathcal{C}}(x, y) = \begin{cases} \emptyset; & x \neq y \\ \{\text{id}_x\}; & x = y. \end{cases}$$

Small discrete categories are thus the same as sets (and functors between small discrete categories the same as functions). A diagram $F: I \rightarrow \mathcal{C}$ indexed by a small discrete category I is just a collection x_i of objects of \mathcal{C} . A (co)limit of such a functor, if it exists, is called a (co)product and denoted by

$$\lim F = \prod_{i \in I} X_i \quad \text{and} \quad \text{colim } F = \prod_{i \in I} X_i.$$

Products of two objects are usually denoted as $X \times Y$.

Another special kind of limit that deserves a name is that of a diagram of the shape

$$X \rightrightarrows Y,$$

i. e. where I consists of two objects a and b and $\text{Hom}_I(a, b) = \{f, g\}$, whereas $\text{Hom}_I(a, a) = \{\text{id}_a\}$, $\text{Hom}_I(b, b) = \{\text{id}_b\}$, and $\text{Hom}_I(b, a) = \emptyset$. One can, for instance, think of this category as the category whose objects are the ordered sets $[0]$ and $[1]$ and the morphisms the strictly monotonic maps. If the limit of a functor $F: I \rightarrow \mathcal{C}$ exists for such a diagram, it is called the *equalizer* of $F(f)$ and $F(g)$ and denoted by $\text{eq}(X \rightrightarrows Y)$. Unsurprisingly, the dual notion is called the *coequalizer* $\text{coeq}(X \rightrightarrows Y)$.

In the special case of set-valued functors, limits and colimits have useful element-wise descriptions:

Lemma A.2.1. *Let $F: I \rightarrow \text{Set}$ be a functor. Then*

1. *For every $x \in \text{colim } F$ there is an $i \in I$ and an $x_i \in F(i)$ such that $\iota_i(x_i) = x$.*
2. *For every pair $x, y \in \lim F$ such that $p_i(x) = p_i(y)$ for all i , we have that $x = y$.*

Proof. For (1), let $\pi: \text{colim } F \rightarrow \{0, \text{frm}[o]--\}$ be the map that sends x to 1 and every other element to 0. Then $\pi \circ \iota_i$ is a cocone for F . If $\pi \circ \iota_i$ is not constantly 0 for some $i \in I$ then there is an $x_i \in F(i)$ such that $\pi(\iota_i(x_i)) = 1$, hence $\iota_i(x_i) = x$. Otherwise, if $\pi \circ \iota_i \equiv 0$ for all i , the map $\pi' \equiv 0: \text{colim } F \rightarrow \{0, 1\}$ is another map such that $\pi' \circ \iota_i$ is a cocone, contradicting the uniqueness in the definition of colimit.

For (2), we employ a similar argument. Let $f, g: \{0\} \rightarrow \lim F$ be given by $f(0) = x$, $g(0) = y$. Since $p_i \circ f = p_i \circ g$ for all i by assumption, $p_i \circ f$ and $p_i \circ g$ are identical cones for F , hence the maps f and g are the same. Hence $x = y$. \square

Finally, we will consider a special case of (co)limits whose usefulness is not that apparent.

Definition. A category I is called *cofiltered* if it is small and:

- (Fi1) For every $i, j \in \text{ob}(I)$ there is another object $k \in \text{ob}(I)$ with morphisms $i \leftarrow k \rightarrow j$;
- (Fi2) For every two morphisms $f, g: i \rightarrow j$ there is another object k with a morphism $h: k \rightarrow i$ such that $f \circ h = g \circ h$.

The category I is called *filtered* if I^{op} is filtered.

A complete category is clearly cofiltered since one can take $k = i \times j$ in (Fi1) and $k = \text{eq}(f, g)$ in (Fi2). However, small categories are almost never complete by a theorem of Freyd (they will be complete lattices).

A particular kind of filtered category is a poset (Ex. A.o.1) which is filtered. This goes by the name of a *directed set*:

Definition. A poset (X, \leq) is called *inverse* if for all pairs $x, y \in X$ there is a $z \in X$ such that $x \leq z$ and $y \leq z$ (in other words, if any finite subset has an upper bound). The dual notion is called an *inverse set*.

A. Notions from category theory

The reason filtered categories have a special place when computing limits and colimits are the following results:

Lemma A.2.2. *Let I be a filtered category and $F: I \rightarrow \mathbf{Set}$ a functor to the category of sets. Denote the structure maps $F(i) \rightarrow \operatorname{colim} F$ by ι_i . Then*

1. *For any $x, x' \in \operatorname{colim} F$ there is some $i \in \operatorname{ob}(I)$ and $x_i, x'_i \in F(i)$ such that $\iota_i(x_i) = x$ and $\iota_i(x'_i) = x'$.*
2. *If $x_i, x'_i \in F(i)$ are such that $\iota_i(x_i) = \iota_i(x'_i) \in \operatorname{colim} F$ then there is a $j \in I$ and a morphism $\alpha \in \operatorname{Hom}_I(i, j)$ such that $F(\alpha)(x_i) = F(\alpha)(x'_i) \in F(j)$.*

Proof. For (1), Lemma A.2.1(1) guarantees the existence of i' and $i'' \in I$ with elements $y_{i'} \in F(i')$ and $y_{i''} \in F(i'')$ such that $\iota_{i'}(y_{i'}) = x$ and $\iota_{i''}(y_{i''}) = x'$. By (Fi1), choose morphisms $i' \xrightarrow{\alpha} i \xleftarrow{\beta} i''$ and define $x_i = F(\alpha)(y_{i'})$ and $x'_i = F(\beta)(y_{i''})$. Then $\iota_i(x_i) = x$ and $\iota_i(x'_i) = x'$.

For (2),

□

Lemma A.2.3. *Filtered colimits commute with finite limits in sets. More precisely:*

Let I be a filtered category and J a finite category (that is, with finitely many morphisms). Let $F: I \times J \rightarrow \mathbf{Set}$ be a functor to the category of sets. Then there is a natural bijection

$$\phi: \operatorname{colim}_{i \in I} \lim_{j \in J} F(i, j) \rightarrow \lim_{j \in J} \operatorname{colim}_{i \in I} F(i, j).$$

Proof. The natural map ϕ exists for any kind of indexing categories I and J and is constructed as follows:

Abbreviate

$$F_i = \lim_{j \in J} F(-, j): I \rightarrow \mathbf{Set} \quad \text{and} \quad F_2 = \operatorname{colim}_{i \in I} F(i, -): J \rightarrow \mathbf{Set}$$

By the universal property of limits and colimits, a map ϕ as above is given by a compatible collection of maps $\phi_{ij}: F_1(i) \rightarrow F_2(j)$. Here compatibility means that for any $\alpha \in \operatorname{Hom}_J(i, i')$ and any $\beta \in \operatorname{Hom}_I(j, j')$ we have that

$$F_2(\beta) \circ \phi_{ij'} = \phi_{i'j} \circ F_1(\alpha): F_1(i) \rightarrow F_2(j').$$

Such a collection is naturally given as

$$\phi_{ij}: F_1(i) \xrightarrow{p_j} F(i, j) \xrightarrow{\iota_i} F_2(j).$$

Indeed, the compatibility condition then reads

$$F_2(\beta) \circ p_{j'} \circ \iota_i = p_j \circ \iota_i = \iota_{i'} \circ p_j \circ F_1(\alpha).$$

Surjectivity of ϕ : Given $y \in \lim_j \operatorname{colim}_i F(i, j) = \lim F_2$, the element $p_j(y) \in F_2(j) = \operatorname{colim}_i F(i, j)$ has to be in the image of ϕ_{ij} for some $i_j \in I$ by Lemma A.2.1(1). Let

$x_j \in F_1(i_j)$ be such a preimage. The surjectivity of ϕ is equivalent to asking that we can find an $i \in I$ independent of j such that $p_j(y) \in \text{im}(\phi_{ij})$ for all j . But since J is finite and I filtered, there is an object $i \in I$ with maps $\alpha_j: i_j \rightarrow i$. Then $\alpha_j(x_j) \in F_1(i)$ for all j , and $\phi_{ij}(\alpha_j(x_j)) = p_j(y)$.

Injectivity of ϕ : Let $x, x' \in \text{colim}_i F_1$ be two elements such that $\phi(x) = \phi(x')$. By Lemma A.2.2 there are elements x_i and $x'_i \in F_1(i)$ such that $\iota_i(x_i) = x$ and $\iota_i(x'_i) = x'$. Then for all $j \in J$, the elements $y = p_j(\phi(x)) = \phi_{ij}(x_i)$ and $p_j(\phi(x')) = \phi_{ij}(x'_i)$ in $F_2(j)$ are equal. By Lemma A.2.2, there is an $\alpha \in \text{Hom}_I(i, i')$ and $y_j \in F(i', j)$ such that $p_j(\alpha(x_i)) = p_j(\alpha(x'_i)) = y_j$ and $\iota_{i'}(y_j) = y$ for all j . Since this is true for all j , $\alpha(x_i) = \alpha(x'_i)$ by Lemma A.2.1(2) and hence $x = x'$. \square

A.3. Exactness

Let \mathcal{A} denote the category of abelian groups (or R -modules for some ring R). Then for any small category I , the category \mathcal{A}^I of functors $I \rightarrow \mathcal{A}$ is also abelian; kernels and cokernels are computed objectwise. In particular, a sequence $X \rightarrow Y \rightarrow Z$ in \mathcal{A}^I is exact if and only if for each $i \in I$, $X(i) \rightarrow Y(i) \rightarrow Z(i)$ is exact.

Theorem A.3.1. *If I is filtered then the functor*

$$\text{colim}_I: \mathcal{A}^I \rightarrow \mathcal{A}$$

is exact, i. e. it maps exact sequences to exact sequences.

Proof. We only have to show left exactness, i. e. that colim_I preserves kernels. But the kernel of a map $f: X \rightarrow Y$ is the limit of the finite diagram $X \xrightarrow{f} Y \leftarrow 0$ in any abelian category, hence by Lemma A.2.3, colim_I preserves them. \square

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