# Erik Mischiatti

# Mechatronic Engineer



### Experience

#### Master Thesis Researcher | Technincal University of Wien (TUW)

April 2024 to October 2024

 This project develops a robotic system for autonomous assembly tasks, leveraging kinesthetic demonstration, invariant trajectory learning, and behavior trees to handle rigid and deformable objects with flexibility and precision.

# Erasmus Activity | Linnaeus University (LNU)

August 2023 to January 2024

- I spent 6 months in Sweden, studying at Linnaeus University in Växjö.
- I attended courses in the field of robotics, automation and mechanics.

#### StartUp Lab | Trento University

(1 semester)

- CLab Trento is the interdepartmental laboratory of the University of Trento, managed with HIT (Hub Innovazione Trentino), where starting to create your professional future.
- Hachi team (our startup)

# Languages

- Italian native
- English B2/C1
- Swedish A1.1
- German started

#### **Contact Info**

erik.mischiatti@gmail.com +39 3341452271 Linkedin

My Portfolio

# Erik Mischiatti

# Mechatronic Engineer

#### Education

M.Sc. MECHATRONICS ENGINEERING ELECTRONICS and ROBOTICS University of Trento | 2021-2024 |

Thesis: Leveraging Acquired Knowledge and Invariant Representations for Cable Manipulation

 B.Sc. MECHATRONICS ENGINEERING INFORMATION ENGINEERING L-8 University of Padova | 2017-2021 Thesis: Detection of Human Arm

Muscle Activity Using EMG Sensors

#### Skills

- Computing: Python, Matlab, Docker, Git, Linux, Windows, LaTeX, Mathematica, VSC
- Robotics: ROS, Gazebo, OpenCV
- **3D modeling:** SolidWorks, Fusion 360, 3d printing
- Autonomous Systems

#### **Awards & Certifications**

- Modular Drone UWB communication
  Institution: Trento University
  IEEE Xplore: 2024 IEEE International
  Conference on Automation Science and
  Engineering
  2023-2024
- 2024 IEEE 20th International Conference on Automation Science and Engineering 2024
- MATLAB Onramp
- Cambridge Assessment English (B2)2021

Contact me

erik.mischiatti@gmail.com +39 3341452271