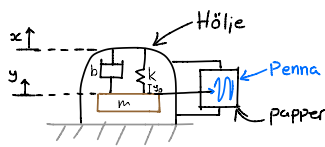


32



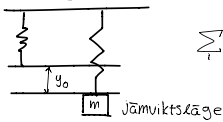
Givet

$x$  - Jordens läge ( $x=0$  i jämvikt)  
 $y$  - massans läge ( $y=0$  i jämvikt)  
 $m$  - massa  
 $b$  - dämpkonstant  
 $k$  - fjäderkonstant

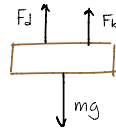
Sökt

$$G(s) = \frac{y(s)}{x(s)}$$

Lösning



$$\sum F_i = ma, \text{ jämvikt} \Rightarrow a=0$$



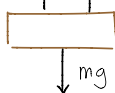
Hooks lag:  $F_k = kx$ ,  $x$  - utsträckning  $= y_0$

$$F_d = b \dot{x}$$

$$\uparrow: F_d + F_k - mg = 0 \Leftrightarrow 0 + ky_0 - mg = 0 \Leftrightarrow y_0 = \frac{mg}{k}$$

Inte jämvikt

$$b(\dot{x} - (\dot{y} - \dot{y}_0)) + k(x - (y - y_0))$$



$$\sum F_i = ma = m\ddot{y}$$

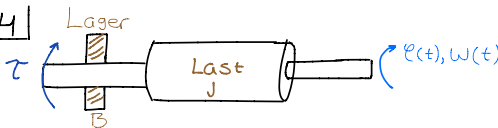
$$1: m\ddot{y} = b(\dot{x} - (\dot{y} - \dot{y}_0)) + k(x - (y - y_0)) - mg$$

$$m\ddot{y} = b(\dot{x} - \dot{y}) + k(x - y)$$

$$Y(s)(ms^2 + bs + k) = X(s)(bs + k)$$

$$G(s) = \frac{bs + k}{ms^2 + bs + k}$$

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Sökt

$$G_1(s) = \frac{\Omega(s)}{\tau(s)}$$

$$G_2(s) = \frac{\Phi(s)}{\tau(s)}$$

Lösning

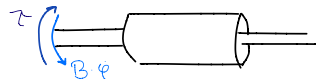
$$\sum M = J \cdot \alpha$$

$\alpha$ : vinkelacc

$J$ : Tröghetsmoment

$M$ : Vridande moment

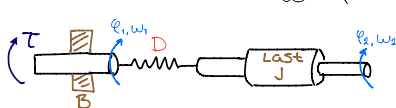
Friläggning



$$\sum M = \tau - B\phi \Rightarrow J\ddot{\phi} = \tau - B\phi \Rightarrow \Phi(s)(Js^2 + Bs) = \tau(s) \Leftrightarrow G_2(s) = \frac{1}{s(Js + B)}$$

$$\omega = \dot{\phi} \Rightarrow \Omega(s) = s\Phi(s) \Rightarrow \frac{\Omega(s)}{\tau(s)} = \frac{s}{s(Js + B)} = \frac{1}{Js + B} = G_1(s)$$

b)

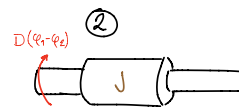


Sökt

$$\frac{\Omega_1(s)}{\tau(s)}, \frac{\Omega_2(s)}{\tau(s)}$$

Lösning

Frilägg!



$$J\alpha = \sum M_i \Rightarrow 0 = \tau - B\phi_1 - D(\phi_1 - \phi_2)$$

$$\Leftrightarrow 0 = \tau(s) - B\Omega_1(s) - \frac{D}{s}(\Omega_1(s) - \Omega_2(s))$$

$$J\ddot{\phi}_2 = D(\phi_1 - \phi_2)$$

$$Js\Omega_2(s) = \frac{D}{s}(\Omega_1(s) - \Omega_2(s))$$

$$2: \Omega_2(s)(Js^2 + D) = D\Omega_1(s) \Rightarrow \Omega_2(s) = \Omega_1(s) \frac{D}{Js^2 + D}$$

$$1: \Omega_1(s)(Bs + D) = \tau(s) + \frac{D}{s}\Omega_2(s) \Rightarrow \Omega_1(s) = \frac{\tau(s)s + D\Omega_2(s)}{Bs + D}$$

$$\frac{\Omega_1(s)}{\tau(s)} = \frac{Js^2 + D}{Js^2 + Bs + D}$$

$$\frac{\Omega_2(s)}{\tau(s)} = \frac{D}{s^2Bs + DJs + DB}$$

3.16]



$$q = \sigma (\Theta_0^4 - \Theta_1^4) \left[ \frac{\text{W}}{\text{m}^2} \right]$$

Givet

d: tjocklek [m]

ρ: densitet  $\left[ \frac{\text{kg}}{\text{m}^3} \right]$

c: Specifikt värme  $\left[ \frac{\text{J}}{\text{kgK}} \right]$

Θ₀: Ugentemp [K]

Θ₁: Plåt temp [K]

Sökt  
 $\frac{\Delta \Theta_1}{\Delta \Theta_0} (s)$

Lösning

Flödesbalans (5.126)

Energiflöde  $\left[ \frac{\text{J}}{\text{s}} = \text{W} \right]$ : Ändring av upplagrad energi per tidsenhet = {Effekt in - Effekt ut}

$$\text{Energi i plåten: } d \cdot \rho \cdot c \cdot \Theta_1 = [\text{m}] \left[ \frac{\text{kg}}{\text{m}^3} \right] \left[ \frac{\text{J}}{\text{kgK}} \right] [\text{K}] = \left[ \frac{\text{J}}{\text{m}^2} \right]$$

$$d \cdot \rho \cdot c \cdot \frac{d\Theta_1}{dt} = \left[ \frac{\text{J/s}}{\text{m}^2} \right] = \left[ \frac{\text{W}}{\text{m}^2} \right]$$

$$d \cdot \rho \cdot c \cdot \frac{d\Theta_1}{dt} = \sigma (\Theta_0^4 - \Theta_1^4) \Leftrightarrow \frac{d\Theta_1}{dt} = \frac{\sigma}{d \cdot \rho \cdot c} (\Theta_0^4 - \Theta_1^4) = f(\Theta_0, \Theta_1)$$

Vid arbetspunkten Θ antas jämvikt råda.

$$\Theta_{0,0} = \Theta, \quad \Theta_{1,0} = ?$$

$$f(\Theta_{0,0}, \Theta_{1,0}) = 0 \quad \text{ty jämvikt.}$$

$$\frac{\sigma}{d \cdot \rho \cdot c} (\Theta_{0,0}^4 - \Theta_{1,0}^4) = 0 \Rightarrow \Theta_{0,0}^4 = \Theta_{1,0}^4 \Rightarrow \Theta_{0,0} = \Theta_{1,0} = \Theta$$

$$\text{Arb pkt } (\Theta_{0,0}, \Theta_{1,0}) = (\Theta, \Theta)$$

$$\left. \begin{array}{l} \Theta_0 = \Theta + \Delta \Theta_0 \\ \Theta_1 = \Theta + \Delta \Theta_1 \end{array} \right\} \Rightarrow \begin{array}{l} \Delta \Theta_0 = \Theta_0 - \Theta \\ \Delta \Theta_1 = \Theta_1 - \Theta \end{array} \Rightarrow \Delta \Theta_1 = \frac{\partial f}{\partial \Theta_0} \bigg|_{(\Theta, \Theta)} \Delta \Theta_0 + \frac{\partial f}{\partial \Theta_1} \bigg|_{(\Theta, \Theta)} \Delta \Theta_1, \quad \begin{array}{l} \frac{\partial f}{\partial \Theta_0} = \frac{4\sigma}{d \cdot \rho \cdot c} \Theta_0^3 \bigg|_{(\Theta, \Theta)} = \frac{4\sigma}{d \cdot \rho \cdot c} \Theta^3 \\ \frac{\partial f}{\partial \Theta_1} = \frac{-4\sigma}{d \cdot \rho \cdot c} \Theta_1^3 \bigg|_{(\Theta, \Theta)} = \frac{-4\sigma}{d \cdot \rho \cdot c} \Theta^3 \end{array}$$

$$\Delta \Theta_1 = \frac{8\sigma \Theta^3}{d \cdot \rho \cdot c} (\Delta \Theta_0 - \Delta \Theta_1)$$

$$\text{Laplace} \Rightarrow \frac{d \cdot \rho \cdot c}{4 \sigma \Theta^3} \cdot 5 \Delta \Theta_1 + \Delta \Theta_1 = \Delta \Theta_0 \Rightarrow \frac{\Delta \Theta_1}{\Delta \Theta_0} = \frac{1}{\frac{d \cdot \rho \cdot c}{4 \sigma \Theta^3} \cdot 5 + 1} \quad T = \frac{d \cdot \rho \cdot c}{4 \sigma \Theta^3}, \quad \text{högre } \Theta \Rightarrow \text{snabbare sys}$$