

Signalmanipulering (Signaltransformering)

- Amplitudskalning

$$y(t) = a x(t) + b$$

$$y[n] = a x[n] + b \quad \begin{matrix} \text{Förstärkning} \\ \text{eller dämpning} \end{matrix} \quad a \& b \text{ är konstanter}$$

- Andra tidsskala

$$y(t) = x(at) \quad a \in \mathbb{R}$$

$$y[n] = x[kn] \quad x, k \in \mathbb{Z}$$

- Spegling

$$y(t) = x(-t) \quad \forall t$$

$$y[n] = x[-n]$$

- Skift

$$y(t) = x(t - t_0) \quad t_0 \text{ konstant}$$

$$y[n] = x[n - n_0] \quad n_0 \text{ konst}$$

Samtidiga Manipulationer

| | |
|--|---|
| $x(t)$ Andra tidsskala $t \rightarrow at \Rightarrow x(at)$ Skifta $t \rightarrow t - t_0 \Rightarrow x(a(t - t_0))$ Resultat: $x(at - at_0)$ | $x(t)$ Skifta $t \rightarrow t - t_0 \Rightarrow x(t - t_0)$ Andra tidsskala $t \rightarrow at \Rightarrow x(at - t_0)$ |
|--|---|

Ordning spelar rörelse!

Signalmodeller

Kontinuerliga

- Komplex exponential

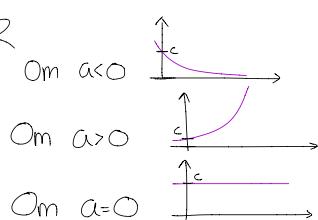
$$x(t) = C \cdot e^{at} \quad C, a \in \mathbb{C} \Rightarrow x \in \mathbb{C}$$

Kompleksa signaler förekommer ej i fysikaliska system men är mycket användbara som matematiska modeller.

Den fysikaliska signalen kan tex. fås som $\operatorname{Re}\{x(t)\}$.

Fall 1 $C, a \in \mathbb{R}$

$$x(t) = C \cdot e^{at} \quad \begin{matrix} \text{Om } a < 0 \\ \text{Om } a > 0 \\ \text{Om } a = 0 \end{matrix}$$



Diskreta

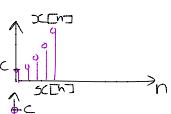
- Komplex exponential

$$x[n] = C \cdot a^n \quad C, a \in \mathbb{C} \Rightarrow x \in \mathbb{C} \quad n \in \mathbb{Z}$$

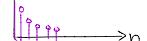
Fall 1 $C, a \in \mathbb{R}$

$$x[n] = C \cdot a^n$$

Låt $a > 1$



Låt $0 < a < 1$



Låt $a < 0$

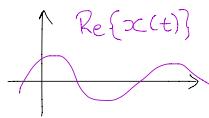
Tekniväxling

Fall 2 $C, \alpha \in \mathbb{C}$ $\operatorname{Re}\{\alpha\} = 0$

Låt $\alpha = j\omega_0$, $C = Ae^{j\frac{\pi}{2}}$

$$x(t) = Ae^{j\frac{\pi}{2}} \cdot e^{j\omega_0 t} = Ae^{j(\omega_0 t + \frac{\pi}{2})} = A \cos(\omega_0 t + \frac{\pi}{2}) + jA \sin(\omega_0 t + \frac{\pi}{2})$$

"Odämpad sinusformad signal"



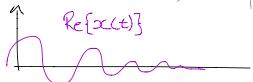
Fall 3 $C, \alpha \in \mathbb{C}$

Låt $C = Ae^{j\frac{\pi}{2}}$

$$\alpha = \sigma_0 + j\omega_0$$

$$x(t) = C e^{\alpha t} = Ae^{j\frac{\pi}{2}} \cdot e^{(\sigma_0 + j\omega_0)t} = Ae^{\sigma_0 t} \cdot e^{j(\omega_0 t + \frac{\pi}{2})} = Ae^{\sigma_0 t} (\cos(\omega_0 t + \frac{\pi}{2}) + j \sin(\omega_0 t + \frac{\pi}{2}))$$

Om $\sigma_0 < 0$, dämpad sinusformad svängning



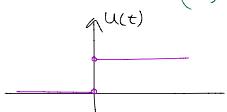
Om $\sigma_0 > 0$, förstärkt sinusformad svängning



Om $\sigma_0 = 0 \Rightarrow$ Fall 2

✗ Enhetssteg (kontinuerlig)

Def $u(t) = \begin{cases} 1, t \geq 0 \\ 0, t < 0 \end{cases}$



Vi låter $u(0)$ vara odef.

Det finns de som definierar $u(0)$ som 0, 1 eller $\frac{1}{2}$.

✗ Enhetsimpuls

(Ingen vanlig funktion, den sorteras under distributionen.)

Beskrivning-

$$\delta(t) = 0, \quad t \neq 0$$

$$\int_{-\infty}^{\infty} \delta(t) dt = 1$$

Amplituden vid $t=0$ är obegränsad

Fall 2 $C, \alpha \in \mathbb{C}$

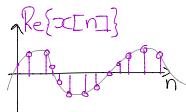
Låt $|a|=1$

Låt $a = e^{j\omega_0}$

$$C = Ae^{j\frac{\pi}{2}}$$

$$x[n] = Ae^{j\frac{\pi}{2}} \cdot e^{j\omega_0 n} = Ae^{j(\omega_0 n + \frac{\pi}{2})} = A \cos(\omega_0 n + \frac{\pi}{2}) + jA \sin(\omega_0 n + \frac{\pi}{2})$$

Diskret odämpad sinusformad Signal



Fall 3 $C, \alpha \in \mathbb{C}$

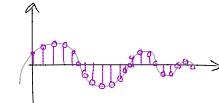
$$\text{Låt } C = Ae^{j\frac{\pi}{2}}$$

$$\alpha = e^{\sigma_0} e^{j\omega_0} = e^{\sigma_0 + j\omega_0}$$

$$x[n] = Ae^{j\frac{\pi}{2}} \cdot e^{(\sigma_0 + j\omega_0)n} = Ae^{\sigma_0 n} \cdot e^{j(\omega_0 n + \frac{\pi}{2})} = Ae^{\sigma_0 n} (\cos(\omega_0 n + \frac{\pi}{2}) + j \sin(\omega_0 n + \frac{\pi}{2}))$$

Diskret sinusformad svängning med n-beroende amplitud

Om $\sigma_0 < 0$, amplitud minskar



Om $\sigma_0 > 0$, amplitud ökar

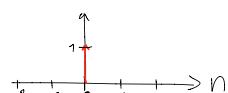
✗ Enhetssteg (diskret)

$$u[n] = \begin{cases} 1, n \geq 0 \\ 0, n < 0 \end{cases}, \quad u[n] = \underbrace{\dots, 0, 0}_{n=0}, 1, 1, \dots$$



✗ Diskret enhetsimpuls

$$\delta[n] = \begin{cases} 1, n=0 \\ 0, n \neq 0 \end{cases}$$

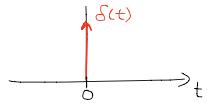


Samband

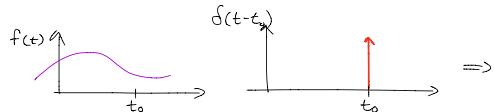
$$u[n] = \sum_{k=-\infty}^n \delta[k]$$

$$\delta[n] = u[n] - u[n-1]$$

Grafisk beskrivning



Enhetsimpulsen definieras genom sina egenskaper. Låt $f(t)$ vara en godtycklig funktion (signal) som är kontinuerlig för $t=t_0$.



$$f(t) \cdot \delta(t - t_0) = f(t_0) \delta(t - t_0)$$

vidare gäller även

$$\int_{-\infty}^{\infty} f(t) \delta(t - t_0) dt = \int_{-\infty}^{\infty} f(t_0) \delta(t - t_0) dt = f(t_0) \int_{-\infty}^{\infty} \delta(t - t_0) dt \\ = f(t_0) \cdot 1 = f(t_0)$$

Samband: $U(t) = \int_{-\infty}^t \delta(\tau) d\tau$
 $\delta(t) = \frac{dU(t)}{dt}$

Repetition

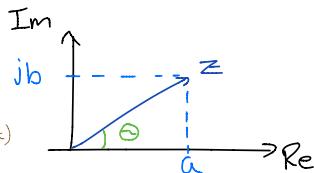
Eulers formel.

Polar form: $e^{j\theta} = \cos(\theta) - j \sin(\theta)$

$$Ae^{j\omega t} = A \cos(\omega t) - j A \sin(\omega t)$$

$$\cos \theta = \frac{e^{j\theta} + e^{-j\theta}}{2}$$

$$j \sin \theta = \frac{e^{j\theta} - e^{-j\theta}}{2}$$



$$z = \sqrt{a^2 + b^2}$$

$$\theta = \arctan\left(\frac{b}{a}\right) \quad \text{om } a > 0$$

$$\theta = \arctan\left(\frac{b}{a}\right) + \pi \quad \text{om } a < 0$$