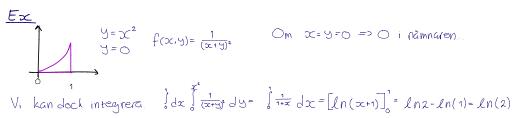
## Ex fren 14.2 [[(x+y)exy dxdy =

[[xex dxdy + ][yex dxdy = e-2+e-2= 1e-4

 $[1]_{ye}^{xy} dxdy = [[ye^{xy}]_{y}^{y}]dy = [e^{y}-1]_{x}^{y} = [e^{y}-y]_{z}^{y} = e-1-(1-0) = e-2$ 

## 14.3 Cheneraliserade integraler

IlfdA år riemannintegrerbara om Rår kompakt 1 fkontinuerlig. Om f disskont eller ej def i hela R eller R ej kompakt (Obegrånsad) blir det inte så bra



Detta är ett exempel på en generaliserad integral, en integral över antingen ett gi kompakt Område eller en funktion som inte är definierad overallt

## 14.41 Polära koordinater

I fix dx, Ofta vill man byta ut Variabler/koordinater Envariabelfallet: f:R→R  $x = g(u) \Rightarrow dx = g'(u)du$ . Vi får då nya gränser och:  $f(g(u)) \cdot g'(u)du \leftarrow \text{extra fixtor}$ Flervariabel ar svårwe.

Ex Singla slant n ggr. För varje krona +1, klave −1. Varje utfall markeras i et diagram. Vi forvantar oss ex normaldistribueret utfall runt noll. Om n→a kommer Kurvan likna e-x2 Vi vill tänka på e-x² som någon form av sannolikhetsfordelning borde [lex²dx=1, men Så blir det inte. Det blir en konstant C

 $C = \int_{0}^{\infty} e^{-x^{2}} dx$ r=radien På en cirkel. Om vi vill kunna täcka alla punkter i R° måste vi täcka cula punkter med en given area

Som dubbelintegral: [ ] e dady => [dady = rdrdo] => [ ] e r'rdrdo = [ 2tt e dr = [ du=2rdr ] = 2tt ] e du = T[ -e m] = T[  $\begin{array}{cccc}
(= \frac{3}{4}e^{x^2}d_{\pi}) \\
(^2 = \pi) & (>0 => ) & (=\pi)
\end{array}$ 

If  $f \in \mathbb{R}^d$ , vill gota et variabel byte: x = x(s,t), y = y(s,t), y(s,t) = f(x(s,t), y(s,t))

Kegleredel 1 32 = 3x 32 + 3x 92 92 92 94 9x 95 + 3x 92 95

Hur mycket andrer Sig  $\infty$  om vi andrer Sit?  $dx = \frac{\partial x}{\partial s} ds + \frac{\partial x}{\partial t} dt$  dt  $dx_1 dy_1 = \begin{bmatrix} \frac{\partial x}{\partial s} & \frac{\partial x}{\partial t} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial t} \end{bmatrix} \begin{bmatrix} dx_1 dy_1 & \frac{\partial x}{\partial s} & \frac{\partial x}{\partial t} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial t} \end{bmatrix} \begin{bmatrix} dx_1 dy_1 & \frac{\partial x}{\partial s} & \frac{\partial x}{\partial t} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial t} \end{bmatrix} \begin{bmatrix} dx_1 dy_1 & \frac{\partial x}{\partial s} & \frac{\partial x}{\partial t} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial t} \end{bmatrix} \begin{bmatrix} dx_1 dy_1 & \frac{\partial x}{\partial s} & \frac{\partial x}{\partial t} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial x}{\partial s} & \frac{\partial x}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial x}{\partial s} & \frac{\partial x}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial x}{\partial s} & \frac{\partial x}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial x}{\partial s} & \frac{\partial x}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial x}{\partial s} & \frac{\partial x}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \end{bmatrix} \begin{bmatrix} dx_1 & \frac{\partial y}{\partial s} & \frac{\partial y}{\partial s} \\ \frac{$ 

dxdy= det (Jacobianen) dsdt