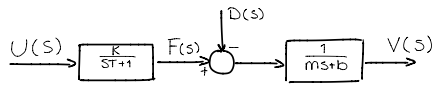


Förhållare

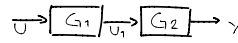
- 1) $m \frac{dv}{dt} = F(t) - b v(t) - d(t)$ $\mathcal{L}\{1\}: (ms+b)V(s) = F(s) - D(s) \Rightarrow V(s) = \frac{1}{ms+b} (F(s) - D(s))$
 2) $\frac{dE}{dt} = -\frac{1}{T} (F(t) - k u(t))$ $\mathcal{L}\{2\}: F(s) = \frac{k}{sT+1} U(s)$



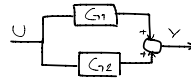
Poler i $s = -\frac{1}{T}$, $s = -\frac{b}{m}$
 Negativa \Rightarrow stabilt system

Blockschemaräkning

Seriekoppling: $Y(s) = G_1(s)G_2(s)U(s)$



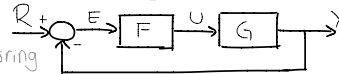
Parallellkoppling: $Y(s) = U(s)(G_1 + G_2)$



Återkoppling: $Y(s) = GF(R - Y)$

$$Y = \frac{GF}{1+GF} R = \frac{L}{1+L} R$$

Kretsöverföring



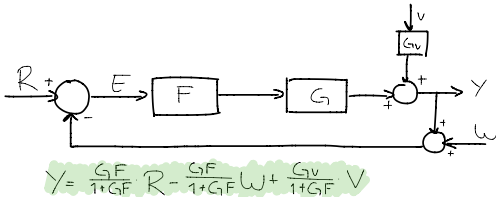
$$Y = UG + V G_v$$

$$U = EF$$

$$E = R - Y - W$$

$$Y = EF G + V G_v \Leftrightarrow Y = (R - Y - W) F G + V G_v \Leftrightarrow Y(1 + FG) = (R - W) F G + V G_v \Leftrightarrow$$

$$Y = \frac{(R - W) F G + V G_v}{1 + F G}$$



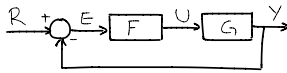
$$Y = \frac{GF}{1+GF} R - \frac{GF}{1+GF} W + \frac{G_v}{1+GF} V$$

Superpos: $W = V = 0 \Rightarrow Y = \frac{GF}{1+GF} R$

$V = R = 0 \Rightarrow Y = \frac{-GF}{1+GF} W$

$$W = R = 0 \Rightarrow Y = Y_1 + G_v V = G U + G_v V = G F E + G_v V = G F (R - Y) + G_v V = -G F Y + G_v V \Rightarrow Y = \frac{G_v}{1+GF} V$$

Kvarstående fel



Kom ihåg felet vid simuleringen av förhållaren. $E(s) = R(s) - Y(s) = R(s) - \frac{GF}{1+GF} R(s) = \left(1 - \frac{L}{1+L}\right) R(s) = \left(\frac{1}{1+L}\right) R(s)$ går även med $\frac{1}{1+k_{rets}} = \frac{1}{1+GF} = \frac{1}{1+L}$

Slutvärdessatsen

$t \rightarrow \infty$!

$$\lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} s E(s)$$

$$r(t): \text{enhetsssteg} \Rightarrow R(s) = \frac{1}{s} \quad \lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} s E(s) = \lim_{s \rightarrow 0} s \cdot \frac{1}{1+L(s)} \cdot \frac{1}{s} = \lim_{s \rightarrow 0} \frac{1}{1+L(s)} = \frac{1}{1+L(0)}$$

Ex Förhållare

$$G(s) = \frac{k}{(ms+b)(sT+1)}$$

$$P: F(s) = K_P$$

$$PI: F(s) = K_P + \frac{1}{s} K_I$$

$$P: U(t) = K_P e(t)$$

$$PI: U(t) = K_P e(t) + K_I \int e(\tau) d\tau = P + I$$

$$PID: K_P e(t) + K_I \int e(\tau) d\tau + K_D \frac{de(t)}{dt} = P + I + D$$

$$P: L = FG = \frac{K_P k}{(ms+b)(sT+1)}$$

$$\lim_{t \rightarrow \infty} e(t) = \lim_{s \rightarrow 0} s E(s) = \frac{1}{1+L(0)} = \frac{1}{1 + \frac{1}{T} \cdot \frac{1}{b}} = \frac{b}{b + K_P k}, \quad K_P \text{ stor} \rightarrow e \text{ litet men aldrig } 0$$

$$PI: L = FG = \frac{(K_P \frac{k}{s}) \cdot \frac{k}{(ms+b)(sT+1)}}{s(msb + sT + 1)} = \frac{(K_P k + K_I) k}{s(msb + sT + 1)}$$

$$\lim_{t \rightarrow \infty} e(t) = \dots = \frac{1}{1+L(0)} = \frac{1}{1+\infty} \rightarrow 0 \text{ "bättre valet"}$$