

example: helicoid to catenoid isometry

$$S = \text{helicoid } \sigma(\rho, t) = (\rho \cos t, \rho \sin t, t)$$

$$\tilde{S} = \text{catenoid } \eta(z, \theta) = (\cosh z \cos \theta, \cosh z \sin \theta, z)$$

$$\text{define } \ell \text{ by } \begin{matrix} z = \operatorname{arcsinh} \rho \\ \theta = t \end{matrix} \quad (\rho = \sinh z)$$

$$\text{check } \ell^*(d\tilde{S}^2) = dS^2$$

Area

Recall from calculus, for a surface patch $\sigma(u^1, u^2)$ area is computed by integrating

$$dA = \|\sigma_1 \times \sigma_2\| du^1 du^2$$

In terms of the 1st fund. form:

$$\begin{aligned} \|\sigma_1 \times \sigma_2\|^2 &= \|\sigma_1\|^2 \|\sigma_2\|^2 \sin^2 \theta \\ &= \|\sigma_1\|^2 \|\sigma_2\|^2 - (\sigma_1 \cdot \sigma_2)^2 \\ &= g_{11} g_{22} - g_{12}^2 \\ &= \det [g_{ij}] \end{aligned}$$

We write this as

$$dA = \sqrt{\det g} du^1 du^2$$

examples

$$1) \text{ cylinder } \sigma(z, \theta) = (\cos \theta, \sin \theta, z)$$

$$ds^2 = dz^2 + d\theta^2, \quad \det g = 1 \Rightarrow dA = dz d\theta$$

2) sphere in cylindrical coordinates $\{r^2 + z^2 = 1\}$

$$\sigma(z, \theta) = (\sqrt{1-z^2} \cos \theta, \sqrt{1-z^2} \sin \theta, z)$$

Check: $\det g = 1$

$$dA = dz d\theta \quad (\text{same as for cylinder!})$$

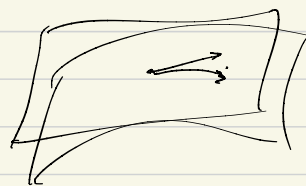
(Archimedes argued that this map preserves area)

Curvature of Surfaces

We start by measuring deviation from the tangent plane.

In a word patch, the tangent plane represents a linear approximation

$$\sigma(u + \Delta u) \rightarrow \sigma(u) + \underbrace{\sigma_i \Delta u^i}_{\vee} \in \mathbb{R}^3$$



let d = distance from $\sigma(u + \Delta u)$ to tangent plane

let N = unit normal to $T_p S$ $p = \sigma(u)$

$$\text{Then } d = [\sigma(u + \Delta u) - \sigma(u)] \cdot N$$

Since $\sigma_i \perp N$, the leading term is quadratic in Δu

$$\text{By Taylor expansion, } d = (\sigma_{ij} \cdot N) \Delta u^i \Delta u^j + O(\Delta u^3)$$

define: the second fundamental form is the family of quadratic forms represented in local coord's

$$\underline{II} := (\sigma_{ij} \cdot N) du^i du^j$$