

EEC 645/745 MCE 693/793 Intelligent Control Systems

Spring 2018

Cleveland State University

General Information

Meeting time and place : M-W 4:00-5:50 PM in MC 401
Instructor: Dr. Eric Schearer, e.schearer@csuohio.edu, FH 237
Office Hours: M-W 2:30-3:45 in lounge on east side WH second floor
Textbook: None required
Student edition of Matlab installed on your laptop

Course Description

This course offers a survey of techniques to automatically improve control of dynamical systems. The main foci are techniques for model learning, planning, and learning complex behaviors that are relevant to robotics research. This course is intended to prepare students to do research in intelligent control systems.

Course Objectives

Upon completion of the course students will be able to

- Make simulations of dynamic systems in Matlab.
- Implement in Matlab various nonlinear regression techniques for both indirect and direct control of dynamical systems.
- Implement a nonlinear regression technique to control a physical robot.
- Implement in Matlab various motion planning techniques.
- Implement in Matlab various techniques for learning novel and complex behaviors.
- Read, understand, and explain to colleagues scholarly articles in the area of intelligent control.

Prerequisites

EEC 510 Linear Systems (required)

Competence in Matlab programming (essential)

EEC 512 Probability/Stochastic Processes (very helpful)

Grading

	MCE 541
Homework	7 assignments, 100 points each
Project Demonstration	200 points
Project Report	100 points
Total	1000 points

A	[93 – 100%]
A-	[90 – 93%)
B+	[88 – 90%)
B	[82 – 88%)
B-	[80 – 82%)
C	[70 – 80%)
F	<70%

Homework

All homework will be submitted via Blackboard. Turn in your homework before class starts on the day it is due. Otherwise it is late. You have three cumulative free days of late homework for the entire duration of the semester. If you turn in your homework after class starts on the due date, that counts as one day of lateness, and you only have two remaining days of free lateness for the rest of the semester. If you turn it in more than 24 hours after the start of class on the due date, you have used up two days of free lateness for the semester. Weekend days, university holidays, and spring break do not count towards your total. Once you have used up all three free days you will get zero points for any subsequent late homework assignment. Reasonable exceptions for circumstances outside your control (e.g., long-term illness, family emergencies) will be considered. Unreasonable exceptions (e.g., too much work in other classes, you slept in, couldn't find a parking space) will not be considered.

Unless I explicitly state that an assignment should be done in groups you should attempt each homework problem on your own before asking the advice of your classmates. At that point you are free to discuss solution strategies with classmates. Please do not offer an entire solution to a classmate. Give general suggestions to help your classmates to solve problems on their own.

Blackboard

All homework assignments, grades, and official course announcements will be posted to Blackboard. I will try to remind you of upcoming events in class, but please check Blackboard at least on a weekly basis.

I will open a discussion thread for each homework allowing you to post questions regarding the homework. My answers or the answers of a classmate will be available for everyone's benefit. I will not respond to emails with questions about homework.

Academic Integrity

Integrity is very important. Do your own work and give credit to people who helped you. If you received any help or ideas on a homework problem, note where you got help from (e.g., the name of a classmate or website) and what ideas leading to the solution were not your own in the comments box with your submission on Blackboard. You will not receive any less credit if you receive help on a homework problem as long as you state where the help came from. You are welcome to discuss ideas for solving problems with your classmates, but your homework submissions must be your own work. Do not turn in computer code that resembles some one else's code.

Here is a non-exhaustive list of things that are not allowed in this course

- Turning in some one else's computer code as your own.
- Giving an electronic or paper copy of computer code that partially or completely solves a homework problem or project to a classmate.
- Receiving from a classmate or anyone else an electronic or paper copy of computer code that partially or completely solves a homework problem or project.
- Giving another student access to view your code for the purpose of copying the code.
- Receiving access to view another student's code for the purpose of copying the code.
- Using computer code downloaded from the internet that partially or completely solves a homework problem or project.
- Representing someone else's work as your own on the project report.

If you do any of the things above on a homework assignment you will receive a grade of zero for that assignment, and I will write a letter of reprimand to be placed in your student record. If you do any of the things above more than once on your homework assignments or if you do any of the things above on the project assignment, you will receive a grade of F for the course, I will write a letter of reprimand to be placed in your student record, and a faculty committee will decide if you should be dismissed from CSU.

Students with Disabilities

I am available to discuss appropriate academic accommodations that you may require as a student with a disability. I encourage you to make requests for academic accommodations to me during the first week of class. Please work with the Office of Disability Services for determination of reasonable academic accommodations. For more information visit www.csuohio.edu/offices/disability/students/.

Tentative Schedule

Day	Date	Topic	Reading	Due	Events
Mon	1/15	MLK Day			no class
Wed	1/17	Course intro and Lagrange's method			
Mon	1/22	Dynamic simulations in Matlab			interactive
Wed	1/24	Intro to model learning and Bayesian estimation	Bishop Ch. 3	HW1	
Mon	1/29	Physics-based models and linear regression	Bishop Ch. 3		interactive
Wed	1/31	Adaptive/MRAC/ILC			
Mon	2/5	Locally-weighted regression	Atkeson, 1997		
Wed	2/7	Locally-weighted regression	Atkeson, 1997	HW2	interactive
Mon	2/12	Presidents' Day			no class
Wed	2/14	Gaussian process regression	Rasmussen Ch. 2		
Mon	2/19	Gaussian process regression	Rasmussen Ch. 2		interactive
Wed	2/21	Gaussian Mixture Models	Bishop Ch. 9	HW3	
Mon	2/26	Gaussian Mixture Models	Bishop Ch. 9		interactive
Wed	2/28	Other Regression Methods - RBF/ANN	Bishop Ch. 5		
Mon	3/5	Other Regression Methods - RBF/ANN	Bishop Ch. 5		interactive
Wed	3/7	Robot Demo		HW4	interactive
Mon	3/12	Spring Break			no class
Wed	3/14	Spring Break			no class
Mon	3/19	Advanced Implementations of LWR/GPR			
Wed	3/21	Advanced Implementations of LWR/GPR			interactive
Mon	3/26	Optimization-Based Motion Planning			
Wed	3/28	Optimization-Based Motion Planning		HW5	interactive
Mon	4/2	Sampling-Based Motion Planning	Lavalle '98/Amato '96		
Wed	4/4	Sampling-Based Motion Planning	Lavalle '98/Amato '96		interactive
Mon	4/9	Dynamic motion primitives	Ijspeert, 2013		
Wed	4/11	Dynamic motion primitives	Ijspeert, 2013	HW6	
Mon	4/16	Dynamic motion primitives	Ijspeert, 2013		interactive
Wed	4/18	Learning from demonstration	Argaal, 2009		
Mon	4/23	Learning from demonstration	Argaal, 2009		interactive
Wed	4/25	Reinforcement learning		HW7	
Mon	4/30	Reinforcement learning			interactive
Wed	5/2	Project Demonstrations and Course Eval		project report	
Mon	5/9	No Final Exam			