

# Priority Queues(heaps)

delete the element with the highest \ lowest priority

## ADT Model

**Objects:** A finite ordered list with zero or more elements.

**Operations:**

👉 PriorityQueue Initialize( int MaxElements );

👉 void  Insert( ElementType X, PriorityQueue H );

👉 ElementType  DeleteMin( PriorityQueue H );

👉 ElementType FindMin( PriorityQueue H );

## Simple Implementation

 **Array :**

**Insertion** — add one item at the end  $\sim \Theta(1)$

**Deletion** — find the largest \ smallest key  $\sim \Theta(n)$   
remove the item and shift array  $\sim O(n)$

 **Linked List :**

**Insertion** — add to the front of the chain  $\sim \Theta(1)$

**Deletion** — find the largest \ smallest key  $\sim \Theta(n)$   
remove the item  $\sim \Theta(1)$

 **Ordered Array :**

**Insertion** — find the proper position  $\sim O(n)$   
shift array and add the item  $\sim O(n)$

**Deletion** — remove the first \ last item  $\sim \Theta(1)$

 **Ordered Linked List :**

**Insertion** — find the proper position  $\sim O(n)$   
add the item  $\sim \Theta(1)$

**Deletion** — remove the first \ last item  $\sim \Theta(1)$

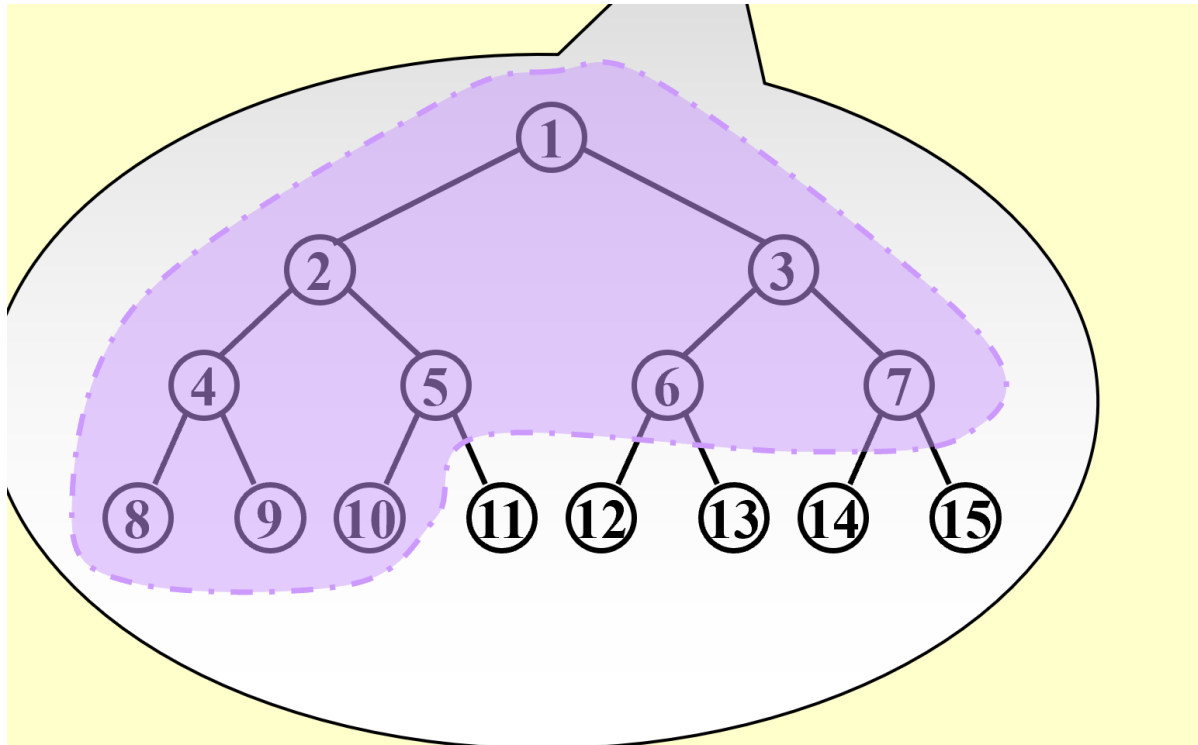
Linked list较优, 因为Insertion总是比Deletion多

# Binary Heap

## Structure Property

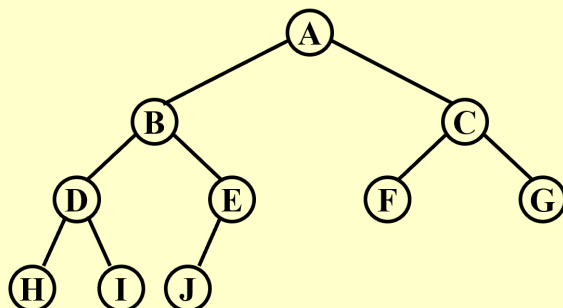
**【Definition】** A binary tree with  $n$  nodes and height  $h$  is **complete** iff its nodes correspond to the nodes numbered from 1 to  $n$  in the perfect binary tree of height  $h$ .

A complete binary tree of height  $h$  has between  $2^h$  and  $2^{h+1} - 1$  nodes.  $\rightarrow h = \lfloor \log N \rfloor$



- levelorder连续

❖ **Array Representation :  $BT[n+1]$  (  $BT[0]$  is not used )**



BT	0	1	2	3	4	5	6
		A	B	C	D	E	F

7	8	9	10	11	12	13
G	H	I	J			

**【Lemma】** If a complete binary tree with  $n$  nodes is represented sequentially, then for any node with index  $i$ ,  $1 \leq i \leq n$ , we have:

$$(1) \text{ index of } \textit{parent}(i) = \begin{cases} \lfloor i/2 \rfloor & \text{if } i \neq 1 \\ \text{None} & \text{if } i = 1 \end{cases}$$

$$(2) \text{ index of } \textit{left\_child}(i) = \begin{cases} 2i & \text{if } 2i \leq n \\ \text{None} & \text{if } 2i > n \end{cases}$$

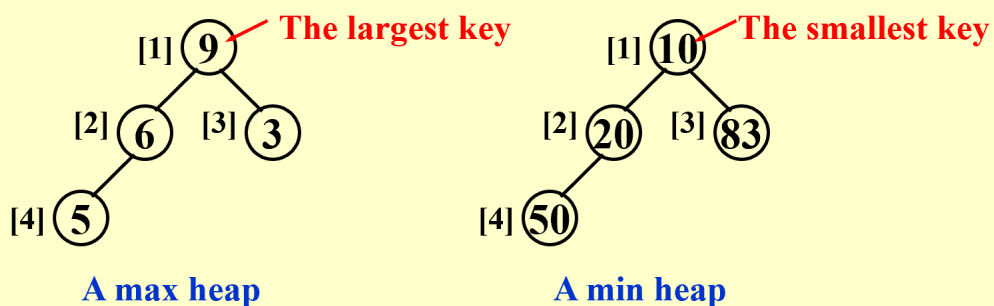
$$(3) \text{ index of } \textit{right\_child}(i) = \begin{cases} 2i + 1 & \text{if } 2i + 1 \leq n \\ \text{None} & \text{if } 2i + 1 > n \end{cases}$$

```
PriorityQueue Initialize( int MaxElements )
{
    PriorityQueue H;
    if ( MaxElements < MinPQSize )
        return Error( "Priority queue size is too small" );
    H = malloc( sizeof( struct HeapStruct ) );
    if ( H == NULL )
        return FatalError( "Out of space!!!" );
    /* Allocate the array plus one extra for sentinel */
    H->Elements = malloc(( MaxElements + 1 ) * sizeof( ElementType ));
    if ( H->Elements == NULL )
        return FatalError( "Out of space!!!" );
    H->Capacity = MaxElements;
    H->Size = 0;
    H->Elements[ 0 ] = MinData; /* set the sentinel */
    return H;
}
```

## Heap Order Property

**【Definition】** A **min tree** is a tree in which the key value in each node is no larger than the key values in its children (if any). A **min heap** is a **complete** binary tree that is also a min tree.

**Note:** Analogously, we can declare a **max** heap by changing the heap order property.



## Operations

- Insertion
  1. 先插入到正确位置，满足Structure Property
  2. 然后通过不断与parent比较、交换，满足Heap Order Property
- 加速swap：直接overwrite

```
/* H->Element[ 0 ] is a sentinel */  
void Insert( ElementType X, PriorityQueue H )  
{  
    int i;  
  
    if ( IsFull( H ) ) {  
        Error( "Priority queue is full" );  
        return;  
    }  
  
    for ( i = ++H->Size; H->Elements[ i / 2 ] > X; i /= 2 )  
        H->Elements[ i ] = H->Elements[ i / 2 ];  
  
    H->Elements[ i ] = X;  
}
```

H->Element[ 0 ] is a **sentinel** that is no larger than the minimum element in the heap.

Faster than *swap*

$T(N) = O(\log N)$

由于0放了最小值，因此一定会在根节点停下

- DeleteMin

1. 先把最末尾的元素换到根节点，确保Structure Property
2. 然后向下比较、交换，确保Heap Order Property
  - 子节点之间先比较，确定向下的路径
  - 交换
  - 继续向下重复过程

```

ElementType DeleteMin( PriorityQueue H )
{
    int i, Child;
    ElementType MinElement, LastElement;
    if ( IsEmpty( H ) ) {
        Error( "Priority queue is empty" );
        return H->Elements[ 0 ]; }
    MinElement = H->Elements[ 1 ]; /* save the min element */
    LastElement = H->Elements[ H->Size-- ]; /* take last and reset size */
    for ( i = 1; i * 2 <= H->Size; i = Child ) { /* Find smaller child */
        Child = i * 2;
        if ( Child != H->Size && H->Elements[Child+1] < H->Elements[Child])
            Child++;
        if ( LastElement > H->Elements[ Child ] ) /* Percolate one level */
            H->Elements[ i ] = H->Elements[ Child ];
        else break; /* find the proper position */
    }
    H->Elements[ i ] = LastElement;
    return MinElement;
}

```

## Other Operations

 **DecreaseKey ( P,  $\Delta$ , H )**

*Percolate up*



Lower the value of the key in the heap **H** at position **P** by a positive amount of  $\Delta$ .....so my programs can run with highest priority ☺.

 **IncreaseKey ( P,  $\Delta$ , H )**

*Percolate down*



Increases the value of the key in the heap **H** at position **P** by a positive amount of  $\Delta$ .....drop the priority of a process that is consuming excessive CPU time.

👉 **Delete ( P, H )**

DecreaseKey(P,  $\infty$ , H); DeleteMin(H)



sys. admin.

Remove the node at position **P** from the heap **H** ..... delete the process that is terminated (abnormally) by a user.

👉 **BuildHeap ( H )**

$N$  successive Insertions ?

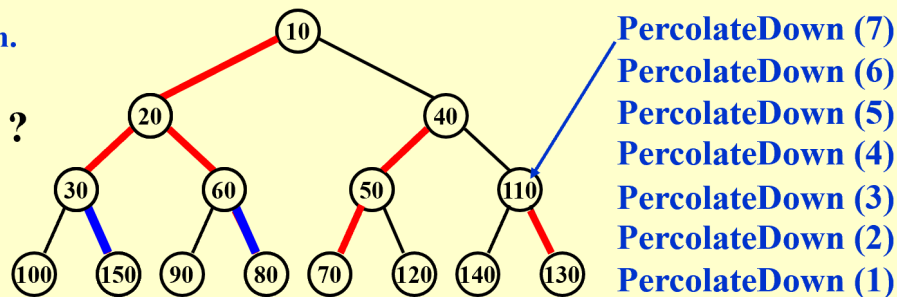


sys. admin.

Place  $N$  input keys into an empty heap **H**.

150, 80, 40, 30, 10, 70, 110, 100, 20, 90, 60, 50, 120, 140, 130

$T(N) = ?$



Insertions太慢了

先build tree 满足Structure Property

再从倒数第二层开始做PercolateDown

**【Theorem】** For the perfect binary tree of height  $h$  containing  $2^{h+1} - 1$  nodes, the sum of the heights of the nodes is  $2^{h+1} - 1 - (h + 1)$ .

➡  $T(N) = O(N)$

## Application

**【Example】** Given a list of  $N$  elements and an integer  $k$ . Find the  $k$ th largest element.

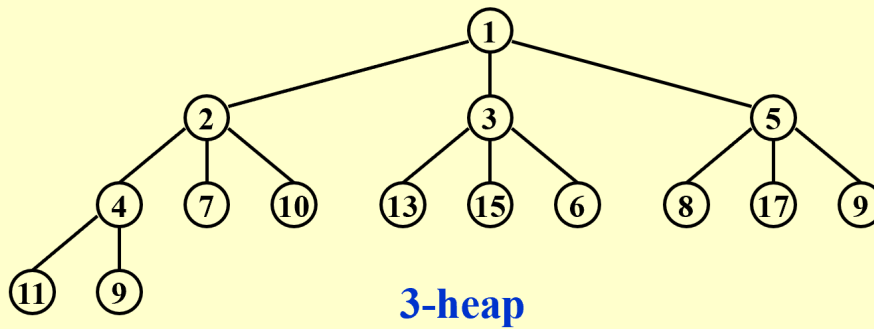
建堆+k次delete

- 与Qsort的选择

全排序用Qsort, 部分排序 (前1000项) 用heapSort

# d-Heaps

## § 5 $d$ -Heaps ---- All nodes have $d$ children



**Question:** Shall we make  $d$  as large as possible?

**Note:** ① DeleteMin will take  $d - 1$  comparisons to find the smallest child. Hence the total time complexity would be  $O(d \log_d N)$ .  
②  $*2$  or  $/2$  is merely a **bit shift**, but  $*d$  or  $/d$  is **not**.  
③ When the priority queue is too large to fit entirely in main memory, a  $d$ -heap will become interesting.

- pros: 高度减小
- cons: delete的比较次数会增多

2-3 分数 2

If a  $d$ -heap is stored as an array, for an entry located in position  $i$ , the parent, the first child and the last child are at:

- ☐ A.  $\lceil (i + d - 2)/d \rceil$ ,  $(i - 2)d + 2$ , and  $(i - 1)d + 1$
- ☐ B.  $\lceil (i + d - 1)/d \rceil$ ,  $(i - 2)d + 1$ , and  $(i - 1)d$
- ☒ C.  $\lfloor (i + d - 2)/d \rfloor$ ,  $(i - 1)d + 2$ , and  $id + 1$
- ☐ D.  $\lfloor (i + d - 1)/d \rfloor$ ,  $(i - 1)d + 1$ , and  $id$

答案正确: 2 分 [创建提问](#)