	Ор	pdatert Fr	emdriftspl	an for res	ten av ser	nesteret	
	М	Т	w	R	F	Sat	Sun
Uke 13		Ferdigstill ny fremdriftsplan	Sim. difference between having and not having prediction	Veiledningsmøte	Create simulation files for scenarios.	Create simulation files for scenarios.	Create simulation files for scenarios.
OKE 15	COLREGs Classification	Work on Introduction, backgound and theory chapters	Work on Introduction, backgound and theory chapters	Research (les minst to artikkler)	Work on Introduction, backgound and theory chapters	Work on Introduction, backgound and theory chapters	Work on Introduction, backgood and theory chapters
	Sim, evaluate, and tune:	Sim, evaluate, and tune:	Sim, evaluate, and tune:				
	dyamic constraints	dyamic constraints	dyamic constraints	Create functinality to allow TS	Create functinality to allow TS	BUG SQUASHING	BUG SQUASHING
Uke 14	dCPA and tCPA limits for COLREGs classification.	dCPA and tCPA limits for COLREGs classification.	dCPA and tCPA limits for COLREGs classification.	velocity vector to be drawn on simulation plots	velocity vector to be drawn on simulation plots		
	Cost function	Cost function	Cost function		Find someone to compare results with	Research (les minst to artikkler)	Research (les minst to artikkl
Uke 15	Create simulation files for scenarios.	Create simulation files for scenarios.	Veliedningsmøte		Work on Method, results and discussion chapters	Work on Method, results and discussion chapters	Work on Method, results and discussion chapters
	Run sims, gather data, tune parameters	Run sims, gather data, tune parameters	Research (les minst to artikkler)			Research (les minst to artikkler)	Research (les minst to artikkle
Uke 16	Create simulation files for scenarios.	Create simulation files for scenarios.	Work on Introduction, backgound and theory chapters	Work on Introduction, backgound and theory chapters	Work on Introduction, backgound and theory chapters	Work on Method, results and discussion chapters	Work on Method, results and discussion chapters
	Run sims, gather data, tune parameters	Run sims, gather data, tune parameters	Work on Method, results and discussion chapters	Work on Method, results and discussion chapters	Work on Method, results and discussion chapters	Research (les minst to artikkler)	Research (les minst to artikkl
Uke 17	Create simulation files for scenarios.	Create simulation files for scenarios.	Veiledningsmøte				
	Run sims, gather data, tune parameters	Run sims, gather data, tune parameters	Research (les minst to artikkler)	TBD	TBD	TBD	TBD
Uke 18							
	TBD	TBD	TBD	TBD	TBD	TBD	TBD
Uke 19			Veiledningsmøte				
	TBD	TBD	Research (les minst to artikkler)	TBD	TBD	TBD	TBD
Uke 20							
	TBD	TBD	TBD	TBD	TBD	TBD	TBD
Uke 21							
	TBD	TBD	Veliedningsmøte	TBD	TBD	TBD	TBD
Uke 22		Finishing touches	Finishing touches	Finishing touches	Finishing touches	Finishing touches	Finishing touches
	Write conclusion, abstract						
Uke 23	DEADLINE						

Code	Sims	Research	Admin	Writing
Placement of Dynamic Constraints	Create more scenarios to simulate. Currently aiming for 8-12 different scenarios	Read at least two articles for each relevant topic. Some relevant topics might be:	Find someone to compare algorithm performance with	Yes
More thorough evaluation of dCPA and tCPA limits for COLREGs classification	Some Scenarios should be simple, some should be complex. Some scenarios should be tailored to showcase the algorithm, some should be real life locations	COLREGs	Schedule full scale test	
Static obstacles interpolation	Run each scenario simulation with three different settings: full TS prediction. Linear interpolation of Target Ship trajectory, and lastly Linear interpolation with Line of Sight blocked by static obstacles.	MPC	Design performance criteria for full scale test	
Strange index out of bounds error when using dynamic horizon (bug that needs to be squashed)	Make the plots look nicer :)	ASV	Run full scale test	
More thorough evaluation of Dynamic Horizon imits		Motion prediction		
Velocity vectors on Target ships when plotting simulations in NED		And more!		
Optimized runtime for full dyamic model				
More thorough evaluation of when a COLREGs ituation should be reclassified as "safe"				
Never ending tuning of the cost function				
Examine if it's doable to make slowing down a viable collision avoidance strategy				