

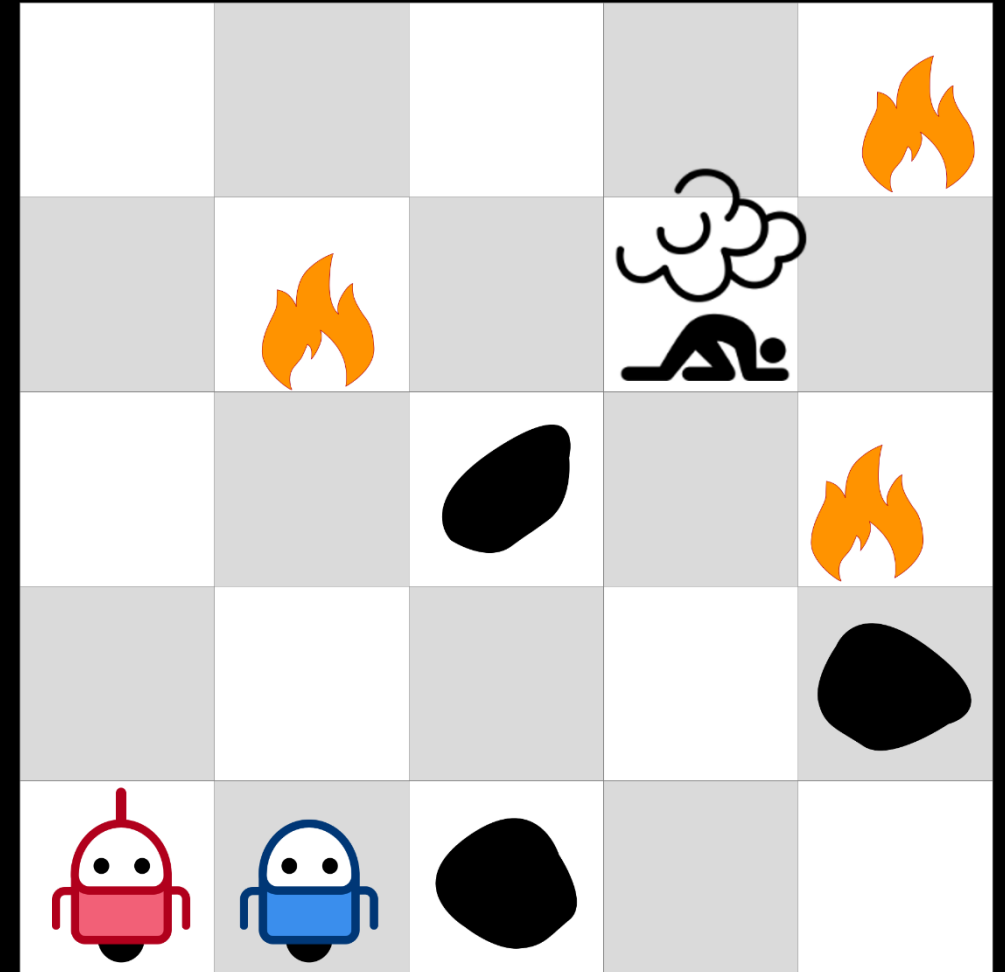
FIRST-ORDER LOGIC

ARTIFICIAL INTELLIGENCE | COMP 131

TODAY ON AI

- Disaster zone
- Propositional Logic is a weak language
- First-order Logic
- Questions?

- A building of size **WIDTH** × **LENGTH**
- RR1 starts in square (1, 1)
- BR2 starts in square (2, 1)
- There is a **victim** somewhere
- Robots of type SRR have sensors that can detect **heat** and **drop-offs**
 - They reliably sense drop-offs and victims from exactly one (non-diagonal) block away
 - They are not good enough to say in what direction the victim or hole was



- Propositional Logic is **declarative**
- Propositional Logic is **compositional**: the meaning of $p \wedge q$ is derived from meaning of p and of q
- Propositional Logic is **context-independent** (unlike natural language)
- Propositional Logic assumes that the world contains **only facts**

Unfortunately, Propositional Logic has very **limited** expressive power (unlike natural language):

- Hard to identify **individuals**:
Every pit causes breeze in adjacent squares
- Can't directly talk about **properties** and relations between individuals:
RR1 is red
- **Generalizations, patterns, regularities** can't easily be represented:
All SRR robots have a left arm

First-order Logic

First-order Logic is a powerful evolution of Propositional Logic. It models the world in terms of:

- **Objects**: things with individual identities
- **Properties**: properties of objects that distinguish them from other objects
- **Relations**: relationships that hold among sets of objects
- **Functions**: a subset of relations where there is only one value for any given input

■ Examples:

- **Objects**: *Victim, Robot, RR1, RB2, Sq11, Sq12, ...*
- **Properties**: *blue(Robot), red(Robot)*
- **Relations**: *color(x , Red), same_type(RR1, RB2)*
- **Functions**: *location(Robot, Step0) = Sq11*

- **Term:** Objects, functions, or variables

- **Proposition:** Relations, or property

- **Connectives:**

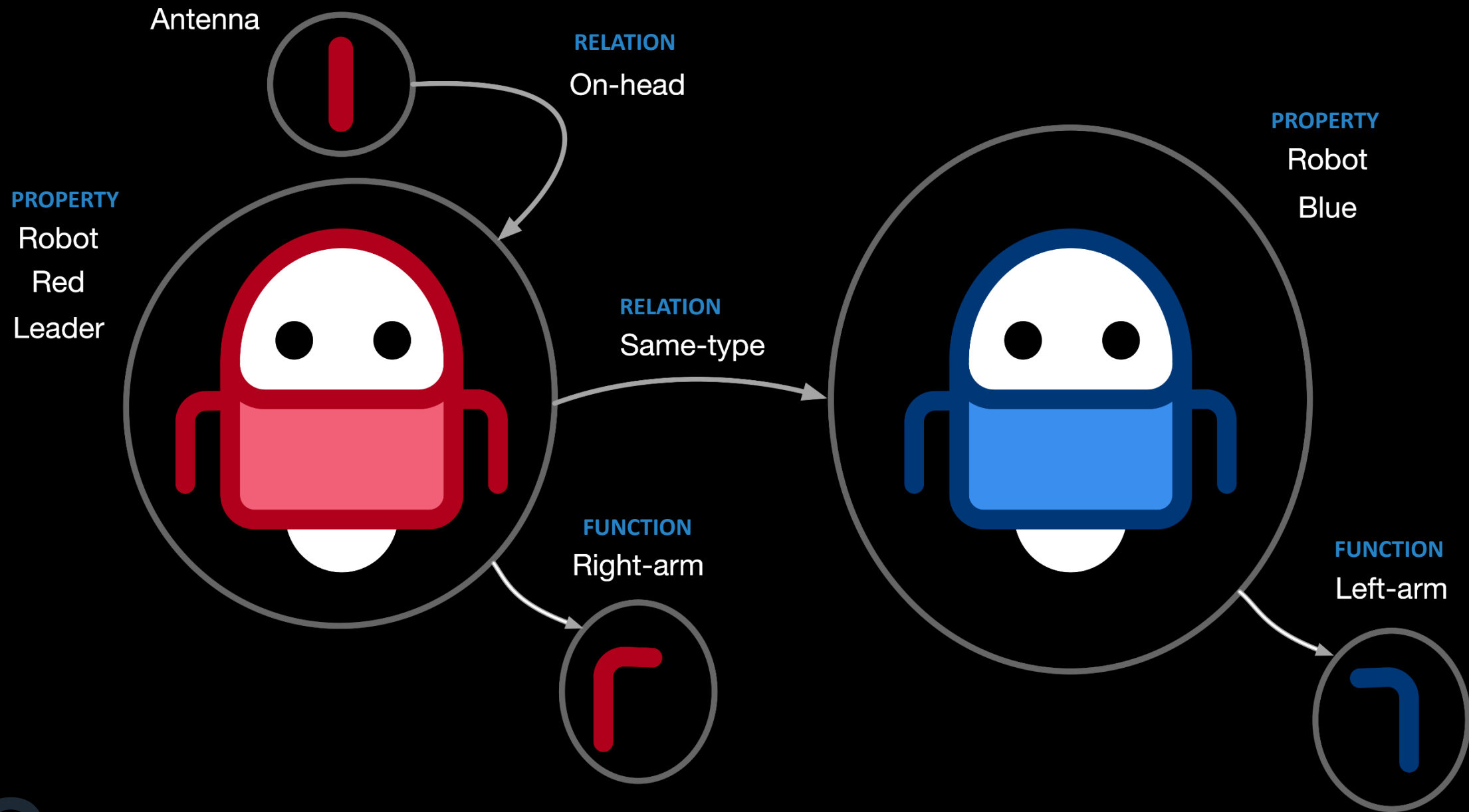
\wedge	AND	Conjunction
\vee	OR	Disjunction
\rightarrow	IMPLIES	Implication / conditional
\leftrightarrow	IS EQUIVALENT	Biconditional
\neg	NOT	Negation

- **Quantifiers:**

\exists	EXISTS	Existential quantifier
\forall	FOR ALL	Universal quantifier

- **Operator precedence:** $\neg = \wedge \vee \rightarrow \leftrightarrow$

- Sentences are **true** with respect to a **model** and an **interpretation**
- Model contains objects (**domain elements**) and relations among them
- Interpretation specifies referents for:
 - constant symbols** → objects
 - predicate symbols** → relations
 - function symbols** → functional relations
- A sentence $predicate(term_1, \dots, term_n)$ is **true** iff the **objects** referred to by $term_1, \dots, term_n$ are in the **relation** referred to by **predicate**



10 Example of First-order Logic application

Existential quantification:

- $\exists x: P(x)$ **means** that P holds for some value of x in the domain associated with that variable:

$\exists x: \text{square}(x) \wedge \text{unsafe}(x)$ means **There is an unsafe square**

- It permits one to make a statement about some object without naming it
- The existential quantifier is equivalent to the **disjunction** of **instantiations** of $P(x)$ for all the objects defined in the domain:

$\text{square}(x_1) \wedge \text{unsafe}(x_1) \vee$

$\text{square}(x_2) \wedge \text{unsafe}(x_2) \vee$

$\text{square}(x_3) \wedge \text{unsafe}(x_4) \vee$

\vdots

Existential quantifiers are normally used with **and** (\wedge) to specify a list of properties about that object:

$\exists x: \text{square}(x) \wedge \text{free}(x)$ means **There is an object that is square and free**

A common mistake is to use it with an implication (\rightarrow):

$\exists x: \text{square}(x) \rightarrow \text{free}(x)$ means **There is a square object, and it is also free**

Universal quantification:

- $\forall x: P(x)$ means that P holds for all values of x in the domain associated with that variable:

$$\forall x: \text{adjacent}(x, \text{Sq12}) \wedge \text{unsafe}(x) \rightarrow \text{dropoff-detected}(x)$$

- The universal quantifier is equivalent to the **conjunction** of **instantiations** of $P(x)$ for all the objects defined in the domain:

$$\begin{aligned} &\text{adjacent}(x_1, \text{Sq12}) \wedge \text{unsafe}(x_1) \rightarrow \text{dropoff-detected}(x_1) \wedge \\ &\text{adjacent}(x_2, \text{Sq12}) \wedge \text{unsafe}(x_2) \rightarrow \text{dropoff-detected}(x_2) \wedge \\ &\text{adjacent}(x_3, \text{Sq12}) \wedge \text{unsafe}(x_3) \rightarrow \text{dropoff-detected}(x_3) \wedge \\ &\quad \vdots \end{aligned}$$

Universal quantifiers are often used with " \rightarrow " to form **rules**.

Universal quantification is rarely used to make blanket statements about every individual in the world:

$\forall x: \text{unsafe}(x)$ means **Every object [in the world] is unsafe**

$\forall x: \text{square}(x) \wedge \text{unsafe}(x)$ means **Every object [in the world] is square and unsafe**

Switching the order of universal quantifiers does not change the meaning:

$$\forall x \forall y: P(x, y) \leftrightarrow \forall y \forall x P(x, y)$$

Switching the order of existential quantifiers does not change the meaning:

$$\exists x \exists y: P(x, y) \leftrightarrow \exists y \exists x P(x, y)$$

Switching the order of existential and universal quantifiers does change the meaning:

$\forall x \exists y: \text{loves}(x, y)$ or $\forall x (\exists y: \text{loves}(x, y))$ means ...?

$\exists y \forall x: \text{loves}(x, y)$ or $\exists y (\forall x: \text{loves}(x, y))$ means ...?

- We can relate sentences involving \forall and \exists using De Morgan's laws:

SENTENCE	EQUIVALENT
$\forall x: \neg P(x)$	$\nexists x: P(x)$
$\neg \forall x: P(x)$	$\exists x: \neg P(x)$
$\forall x: P(x)$	$\nexists x: \neg P(x)$
$\exists x: P(x)$	$\neg \forall x: \neg P(x)$

FOL introduces the concept of equality:

- At timestep 0, the robot was at Square (1, 1).
 $\text{location}(\text{Robot}, \text{T0}) = \text{Sq11}$
- The robot was located at different places in timestep 0 and timestep 1.
 $x = \text{location}(\text{Robot}, \text{T0}) \wedge y = \text{location}(\text{Robot}, \text{T1}) \wedge \neg (x = y)$
 $x = \text{location}(\text{Robot}, \text{T0}) \wedge y = \text{location}(\text{Robot}, \text{T1}) \wedge (x \neq y)$
- The robot is different from the victim.
 $\neg(\text{Robot} = \text{Victim})$
 $\text{Robot} \neq \text{Victim}$

- Every gardener likes the sun.
 $\forall x: \text{gardener}(x) \rightarrow \text{likes}(x, \text{Sun})$
- You can fool some of the people all the time.
 $\exists x \forall t: (\text{person}(x) \wedge \text{time}(t)) \rightarrow \text{can-fool}(x, t)$
- You can fool all the people some of the time.
 $\forall x \exists t: (\text{person}(x) \wedge \text{time}(t)) \rightarrow \text{can-fool}(x, t)$
- All purple mushrooms are poisonous.
 $\forall x: (\text{mushroom}(x) \wedge \text{purple}(x)) \rightarrow \text{poisonous}(x)$

- No purple mushroom is poisonous.

$\nexists x: \text{purple}(x) \wedge \text{mushroom}(x) \wedge \text{poisonous}(x)$

$\forall x: (\text{mushroom}(x) \wedge \text{purple}(x)) \rightarrow \neg \text{poisonous}(x)$

- There are exactly two purple mushrooms.

$\exists x \exists y: \text{mushroom}(x) \wedge \text{purple}(x) \wedge \text{mushroom}(y) \wedge \text{purple}(y) \wedge \neg(x = y) \wedge$
 $\forall z: (\text{mushroom}(z) \wedge \text{purple}(z)) \rightarrow ((x = z) \vee (y = z))$

- John is not tall.

$\neg \text{tall}(\text{John})$

PRACTICE

Exercises from the textbook (chapter 8):
8.6, 8.10, 8.11, 8.23, 8.24

QUESTIONS ?

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