

PROPOSITIONAL LOGIC 2

ARTIFICIAL INTELLIGENCE | COMP 131

TODAY ON AI

- Automated reasoning
- Efficient satisfiability
- Questions?

Automated reasoning

Logical inference is used to create new sentences that logically follow from a given knowledge base.

- The most used inference rules:

RULE	PREMISE	CONCLUSION
Modus Ponens	$p, p \rightarrow q$	q
AND elimination	$p \wedge q$	p, q
Double negation	$\neg\neg p$	p
Unit resolution	$p \vee q, \neg q$	p
AND introduction	p, q	$p \wedge q$
Modus Tollens	$\neg q, p \rightarrow q$	$\neg p$

- There are two directions of search: **forward** and **backward** chaining.
- There is also the **DPLL**, a complete algorithm for deciding if a sentence is satisfiable.

Forward chaining: answer queries using a knowledge base to determine new facts until we find that our query is **true**, or until we've run out of new facts to generate.

QUERY

INFERENCE

KNOWLEDGE BASE

- 1 person_in_front_of_car → brake
- 2 (yellow_light ∨ policeman) ∧ ¬slippery → brake
- 3 police_car → policeman
- 4 snow → slippery
- 5 slippery → ¬dry
- 6 red_light → brake
- 7 winter → snow


FACTS

yellow_light	¬red_light	¬snow
police_car	¬person_in_front_of_car	dry

NEW FACTS

Forward chaining: answer queries using a knowledge base to determine new facts until we find that our query is **true**, or until we've run out of new facts to generate.

KNOWLEDGE BASE

- 
- 1

person_in_front_of_car → brake
- 2

$(\text{yellow_light} \vee \text{policeman}) \wedge \neg \text{slippery} \rightarrow \text{brake}$
- 3

police_car → policeman
- 4

snow → slippery
- 5

slippery → ¬dry
- 6

red_light → brake
- 7

winter → snow

FACTS

yellow_light	¬red_light	¬snow
<div>police_car</div>	¬person_in_front_of_car	dry

NEW FACTS

policeman

QUERY

Do we need to *Brake*?

INFERENCE

KNOWN

MP R3


police_car

police_car → policeman

policeman

Forward chaining: answer queries using a knowledge base to determine new facts until we find that our query is **true**, or until we've run out of new facts to generate.

KNOWLEDGE BASE

- 
- 1 person_in_front_of_car \rightarrow brake
 - 2 (yellow_light \vee policeman) \wedge \neg slippery \rightarrow brake
 - 3 police_car \rightarrow policeman
 - 4 snow \rightarrow slippery
 - 5 slippery \rightarrow \neg dry
 - 6 red_light \rightarrow brake
 - 7 winter \rightarrow snow

FACTS

yellow_light	\neg red_light	\neg snow
police_car	\neg person_in_front_of_car	dry

NEW FACTS

policeman \neg slippery

QUERY

Do we need to *Brake*?

INFERENCE

KNOWN	police_car
MP R3	police_car \rightarrow policeman
	policeman
KNOWN	dry
MT R5	slippery \rightarrow \neg dry
DN	\neg \neg dry \rightarrow \neg slippery
MP	dry \rightarrow \neg slippery
	\negslippery

Forward chaining: answer queries using a knowledge base to determine new facts until we find that our query is **true**, or until we've run out of new facts to generate.

KNOWLEDGE BASE

- ➡
- 1

person_in_front_of_car → brake
- 2

$(\text{yellow_light} \vee \text{policeman}) \wedge \neg \text{slippery} \rightarrow \text{brake}$
- 3

police_car → policeman
- 4

snow → slippery
- 5

slippery → ¬dry
- 6

red_light → brake
- 7

winter → snow

FACTS

yellow_light

¬red_light

¬snow

police_car

¬person_in_front_of_car

dry

NEW FACTS

policeman

¬slippery

QUERY

Do we need to *Brake*?

INFERENCE

KNOWN **police_car**
MP R3 police_car → policeman
policeman

KNOWN **dry**
MT R5 slippery → ¬dry
DN ¬¬dry → ¬slippery
MP dry → ¬slippery
¬slippery

KNOWN **yellow_light**
KNOWN **policeman**
KNOWN **¬slippery**
MP R2 $((\text{yellow_light} \vee \text{policeman}) \wedge \neg \text{slippery}) \rightarrow \text{brake}$
brake

CONCLUSION **brake**

Backward chaining: an approach alternative to forward chaining in which the query is **explicitly proven** with the given knowledge and work **backward** until all the facts are known.

KNOWLEDGE BASE

- 1 $\text{person_in_front_of_car} \rightarrow \text{brake}$
- 2 $(\text{yellow_light} \vee \text{policeman}) \wedge \neg \text{slippery} \rightarrow \text{brake}$
- 3 $\text{police_car} \rightarrow \text{policeman}$
- 4 $\text{snow} \rightarrow \text{slippery}$
- 5 $\text{slippery} \rightarrow \neg \text{dry}$
- 6 $\text{red_light} \rightarrow \text{brake}$
- 7 $\text{winter} \rightarrow \text{snow}$

QUERY

Do we need to *Brake*?

FACTS

yellow_light

$\neg \text{red_light}$

$\neg \text{snow}$

police_car

$\neg \text{person_in_front_of_car}$

dry

brake

KNOWLEDGE BASE

- ➔ 1 $\text{person_in_front_of_car} \rightarrow \text{brake}$
- ➔ 2 $(\text{yellow_light} \vee \text{policeman}) \wedge \neg \text{slippery} \rightarrow \text{brake}$
- 3 $\text{police_car} \rightarrow \text{policeman}$
- 4 $\text{snow} \rightarrow \text{slippery}$
- 5 $\text{slippery} \rightarrow \neg \text{dry}$
- ➔ 6 $\text{red_light} \rightarrow \text{brake}$
- 7 $\text{winter} \rightarrow \text{snow}$

QUERY

Do we need to *Brake*?

FACTS

yellow_light

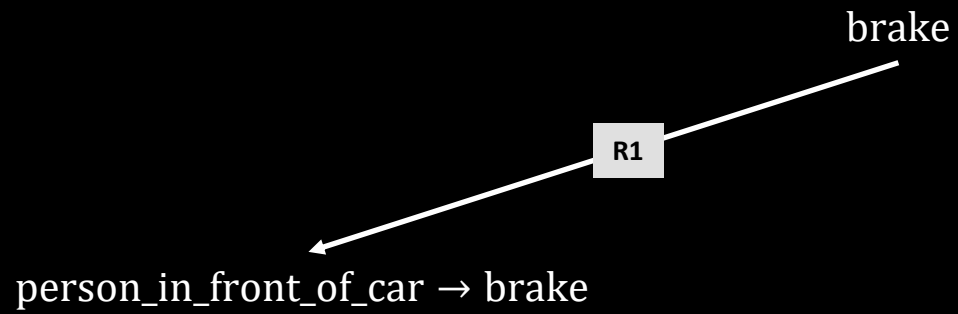
$\neg \text{red_light}$

$\neg \text{snow}$

police_car

$\neg \text{person_in_front_of_car}$

dry



KNOWLEDGE BASE

- 1 person_in_front_of_car \rightarrow brake
- 2 (yellow_light \vee policeman) \wedge \neg slippery \rightarrow brake
- 3 police_car \rightarrow policeman
- 4 snow \rightarrow slippery
- 5 slippery \rightarrow \neg dry
- 6 red_light \rightarrow brake
- 7 winter \rightarrow snow

QUERY

Do we need to *Brake*?

FACTS

yellow_light

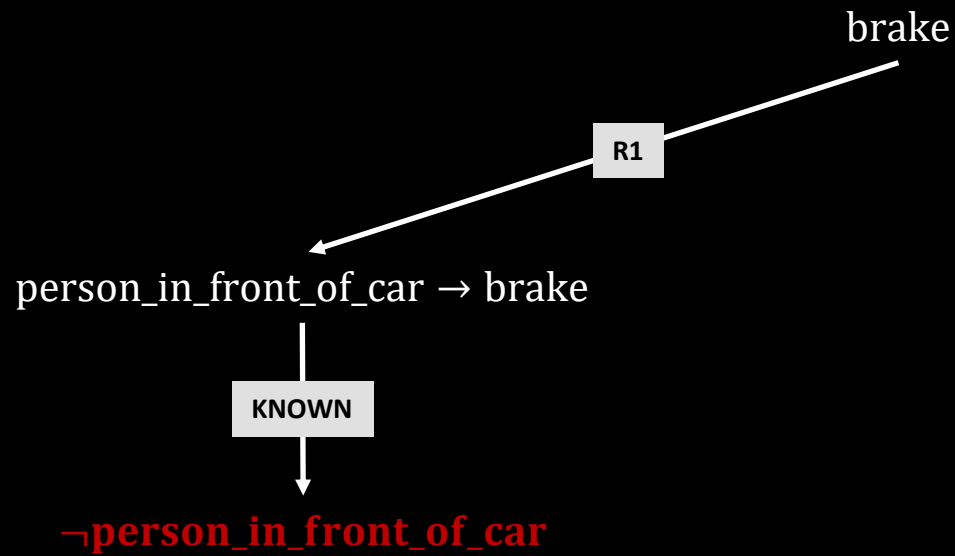
\neg red_light

\neg snow

police_car

\neg person_in_front_of_car

dry



KNOWLEDGE BASE

- 1 $\text{person_in_front_of_car} \rightarrow \text{brake}$
- 2 $(\text{yellow_light} \vee \text{policeman}) \wedge \neg \text{slippery} \rightarrow \text{brake}$
- 3 $\text{police_car} \rightarrow \text{policeman}$
- 4 $\text{snow} \rightarrow \text{slippery}$
- 5 $\text{slippery} \rightarrow \neg \text{dry}$
- 6 $\text{red_light} \rightarrow \text{brake}$
- 7 $\text{winter} \rightarrow \text{snow}$

QUERY

Do we need to *Brake*?

FACTS

yellow_light

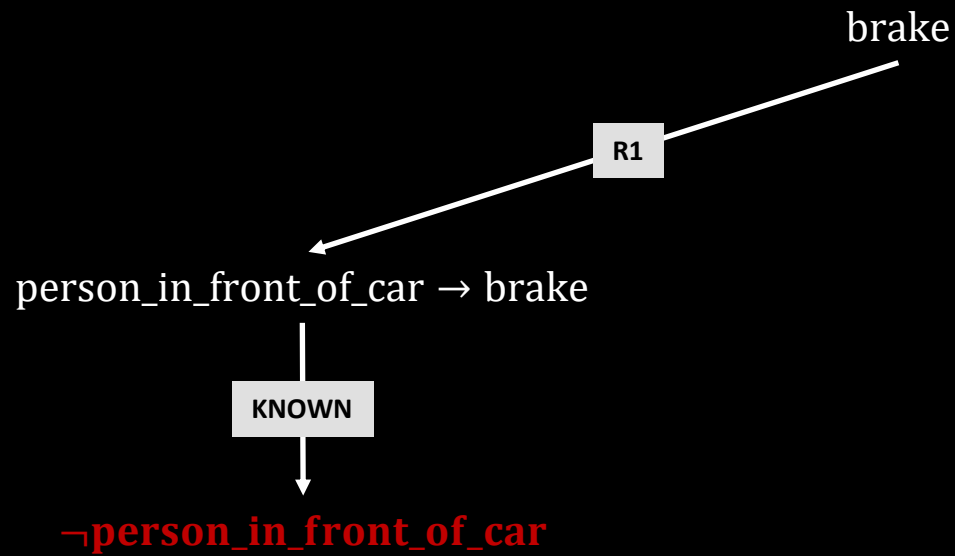
$\neg \text{red_light}$

$\neg \text{snow}$

police_car

$\neg \text{person_in_front_of_car}$

dry



KNOWLEDGE BASE

- ➔ 1 ~~person_in_front_of_car → brake~~
- ➔ 2 (yellow_light ∨ policeman) ∧ ¬slippery) → brake
- 3 police_car → policeman
- 4 snow → slippery
- 5 slippery → ¬dry
- ➔ 6 red_light → brake
- 7 winter → snow

QUERY

Do we need to *Brake*?

FACTS

yellow_light

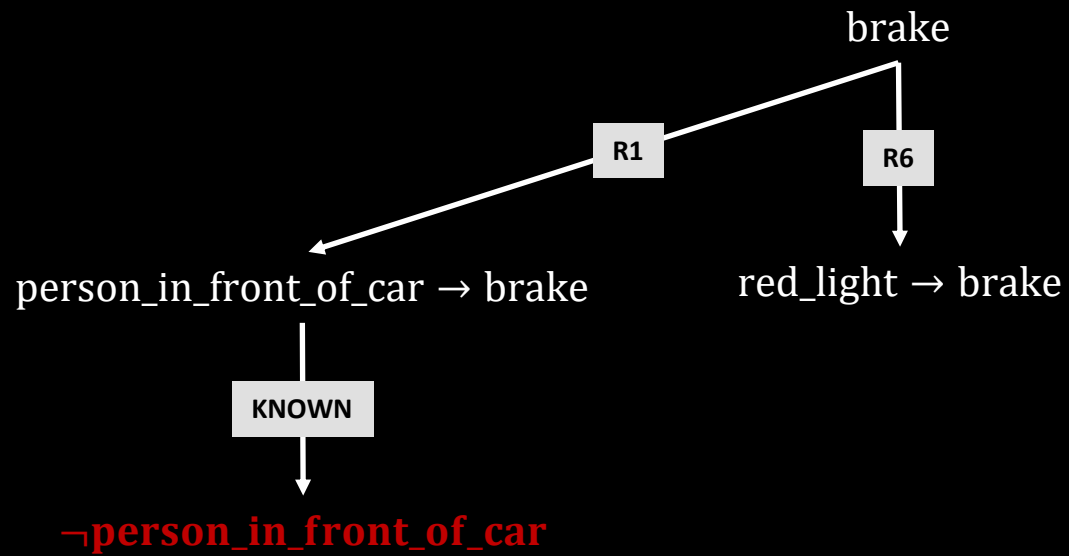
¬red_light

¬snow

police_car

¬person_in_front_of_car

dry



KNOWLEDGE BASE

- 1 person_in_front_of_car → brake
- 2 (yellow_light ∨ policeman) ∧ ¬slippery) → brake
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- 4 snow → slippery
- 5 slippery → ¬dry
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- 7 winter → snow

QUERY

Do we need to *Brake*?

FACTS

yellow_light

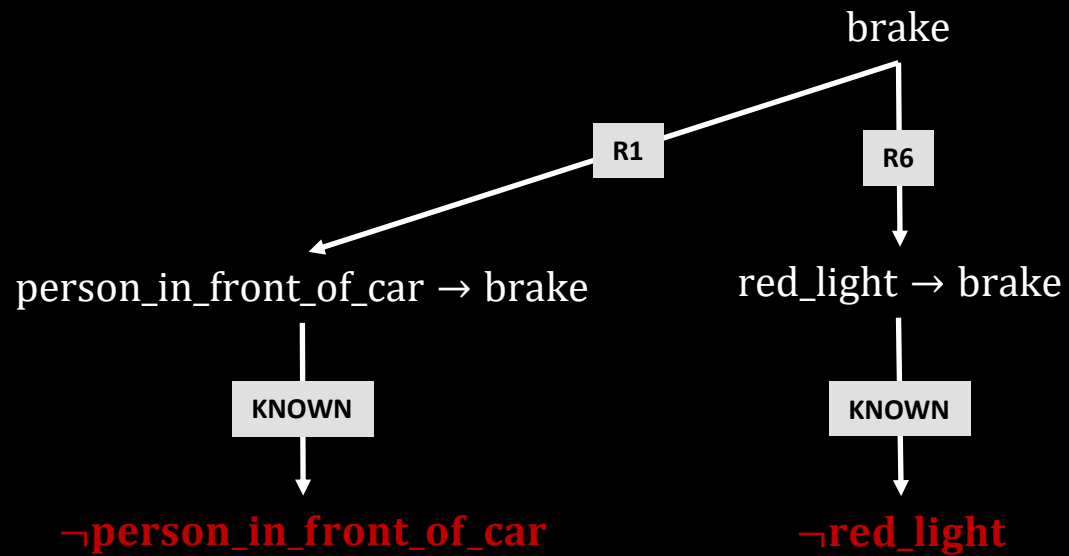
¬red_light

¬snow

police_car

¬person_in_front_of_car

dry



KNOWLEDGE BASE

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- 4 snow → slippery
- 5 slippery → ¬dry
- 6 red_light → brake
- 7 winter → snow

QUERY

Do we need to *Brake*?

FACTS

yellow_light

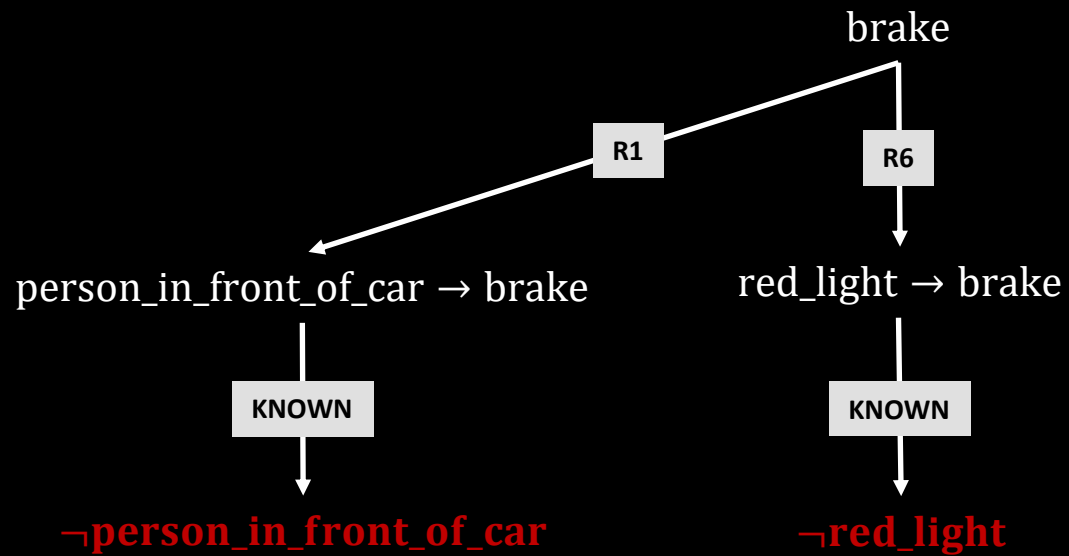
police_car

¬red_light

¬person_in_front_of_car

¬snow

dry



KNOWLEDGE BASE

- 1 ~~person_in_front_of_car → brake~~
- 2 (yellow_light ∨ policeman) ∧ ¬slippery → brake
- 3 police_car → policeman
- 4 snow → slippery
- 5 slippery → ¬dry
- 6 ~~red_light → brake~~
- 7 winter → snow

QUERY

Do we need to *Brake*?

FACTS

yellow_light

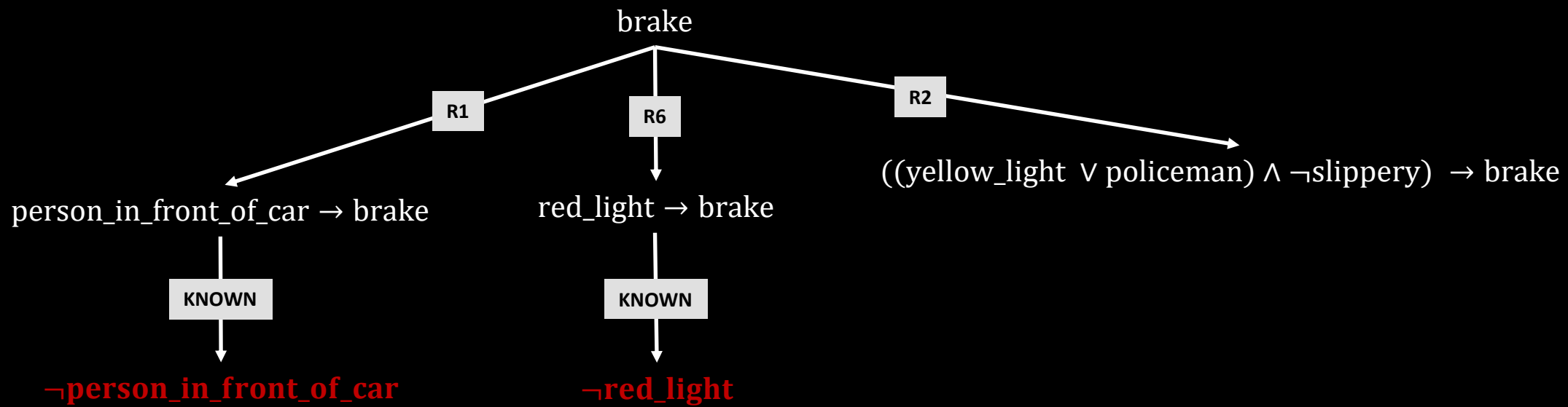
¬red_light

¬snow

police_car

¬person_in_front_of_car

dry



KNOWLEDGE BASE

- 1 person_in_front_of_car → brake
- ➡ 2 (yellow_light ∨ policeman) ∧ ¬slippery → brake
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- 4 snow → slippery
- 5 slippery → ¬dry
- 6 red_light → brake
- 7 winter → snow

QUERY

Do we need to *Brake*?

FACTS

yellow_light

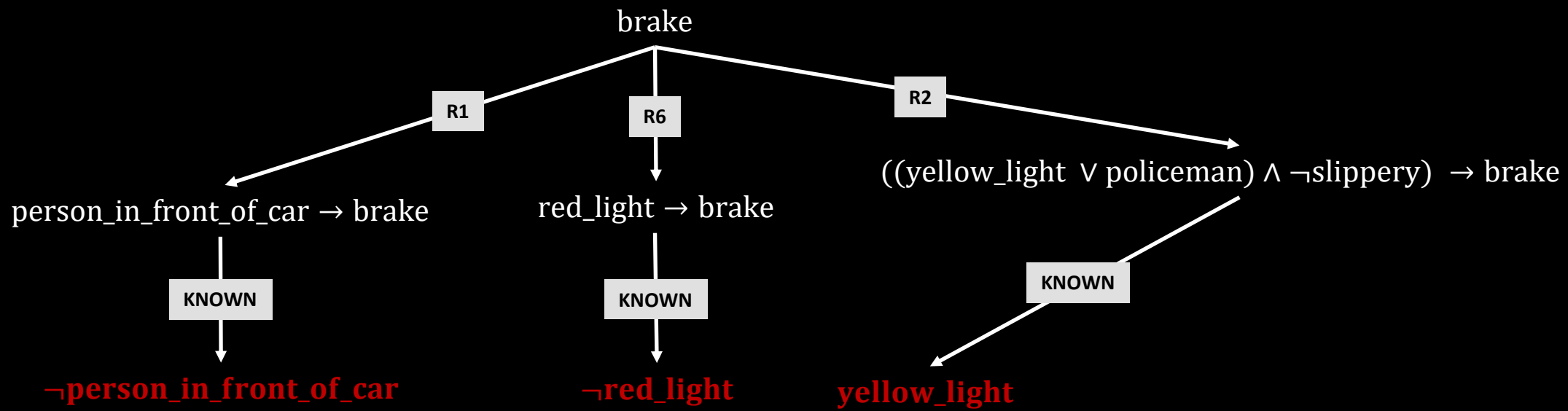
¬red_light

¬snow

police_car

¬person_in_front_of_car

dry



KNOWLEDGE BASE

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- 7 winter → snow

QUERY

Do we need to *Brake*?

FACTS

yellow_light

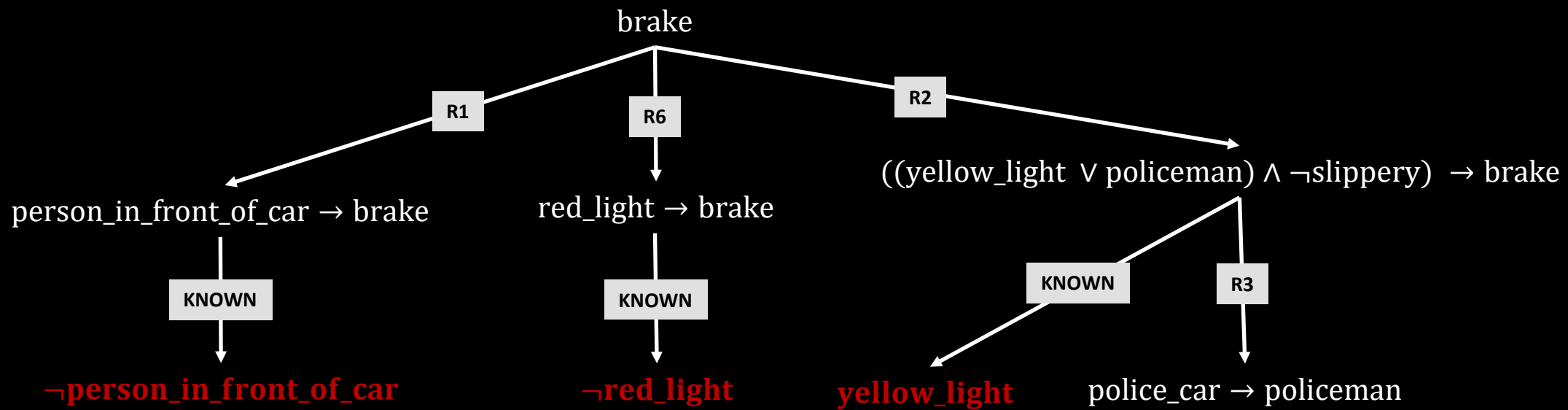
police_car

¬red_light

¬person_in_front_of_car

¬snow

dry



KNOWLEDGE BASE

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- 7 winter → snow

QUERY

Do we need to *Brake*?

FACTS

yellow_light

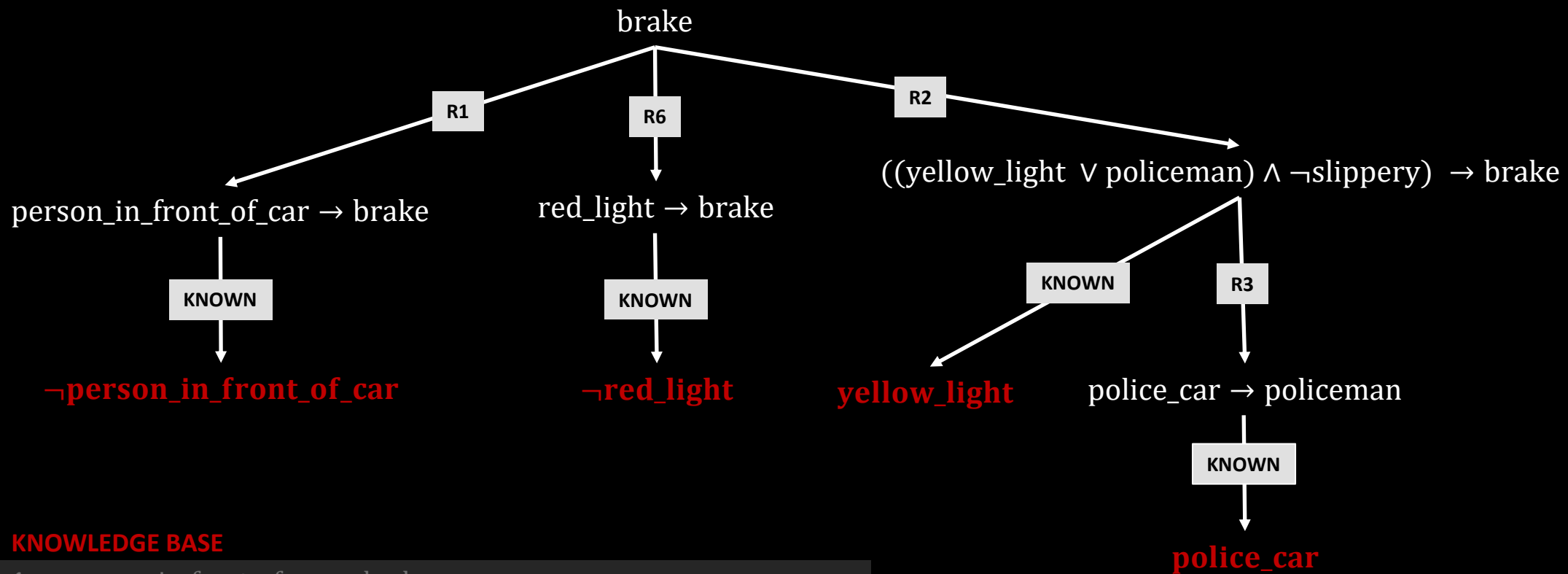
¬red_light

¬snow

police_car

¬person_in_front_of_car

dry



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- 7 winter → snow

QUERY

Do we need to *Brake*?

FACTS

yellow_light

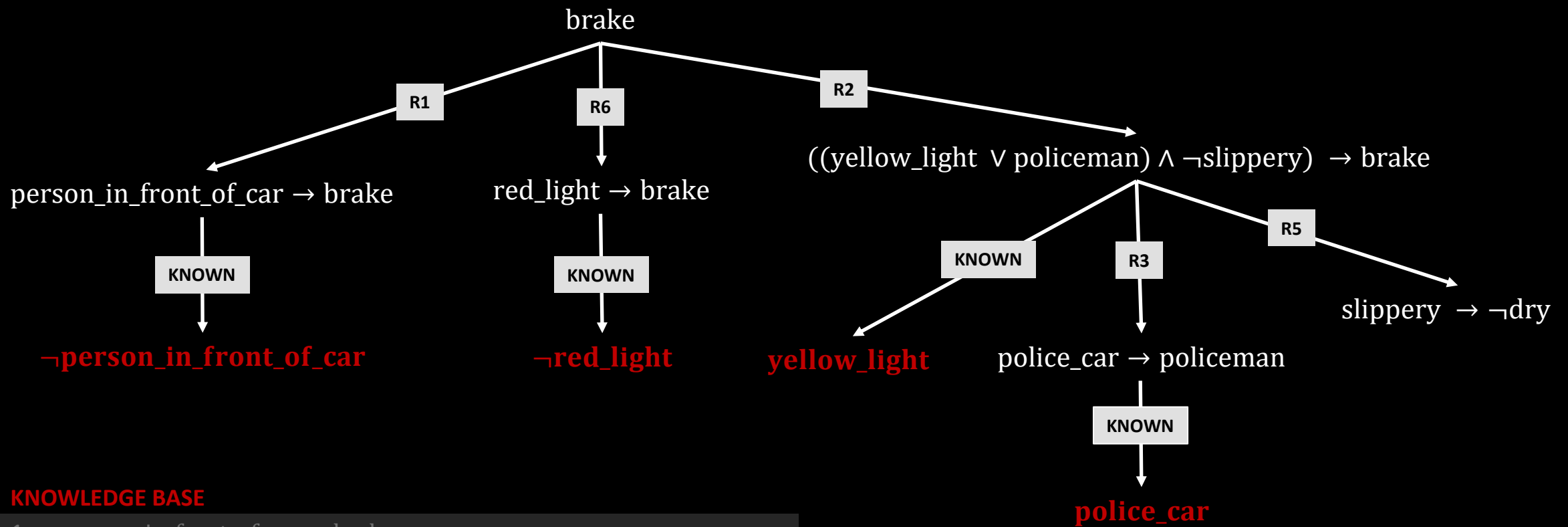
police_car

¬red_light

¬person_in_front_of_car

¬snow

dry



KNOWLEDGE BASE

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QUERY

Do we need to *Brake*?

FACTS

yellow_light

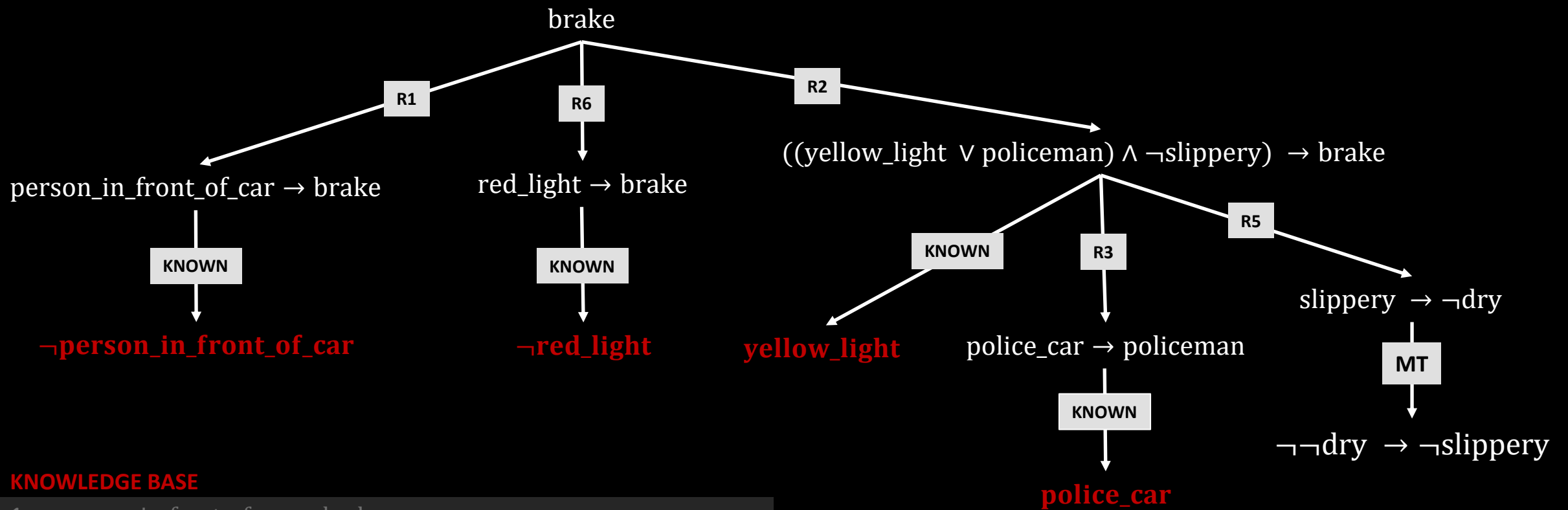
police_car

¬red_light

¬person_in_front_of_car

¬snow

dry



KNOWLEDGE BASE

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- 6 red_light → brake
- 7 winter → snow

QUERY

Do we need to *Brake*?

FACTS

yellow_light

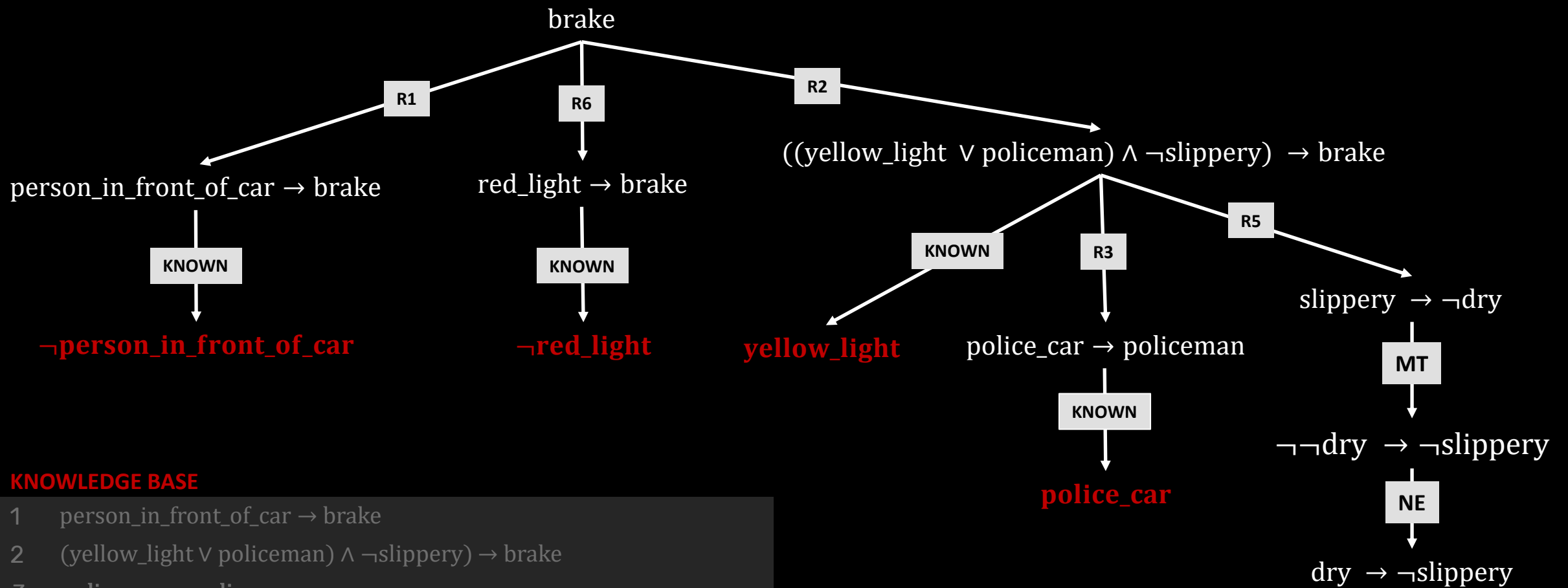
police_car

¬red_light

¬person_in_front_of_car

¬snow

dry



KNOWLEDGE BASE

- 1 $\text{person_in_front_of_car} \rightarrow \text{brake}$
- 2 $((\text{yellow_light} \vee \text{policeman}) \wedge \neg \text{slippery}) \rightarrow \text{brake}$
- 3 $\text{police_car} \rightarrow \text{policeman}$
- 4 $\text{snow} \rightarrow \text{slippery}$
- 5 $\text{slippery} \rightarrow \neg \text{dry}$
- 6 $\text{red_light} \rightarrow \text{brake}$
- 7 $\text{winter} \rightarrow \text{snow}$

QUERY

Do we need to *Brake*?

FACTS

yellow_light

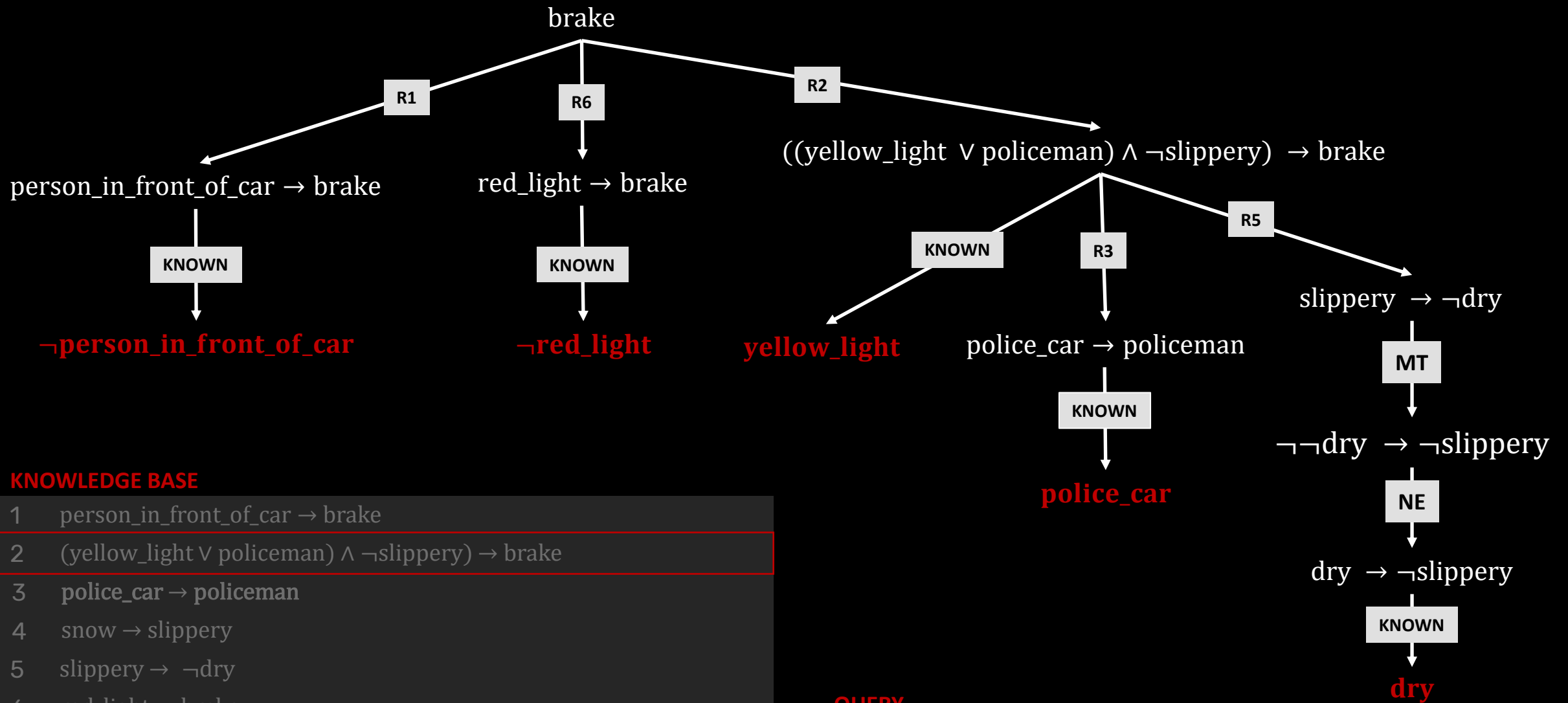
$\neg \text{red_light}$

$\neg \text{snow}$

police_car

$\neg \text{person_in_front_of_car}$

dry



KNOWLEDGE BASE

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- 6 $\text{red_light} \rightarrow \text{brake}$
- 7 $\text{winter} \rightarrow \text{snow}$

QUERY

Do we need to *Brake*?

FACTS

yellow_light

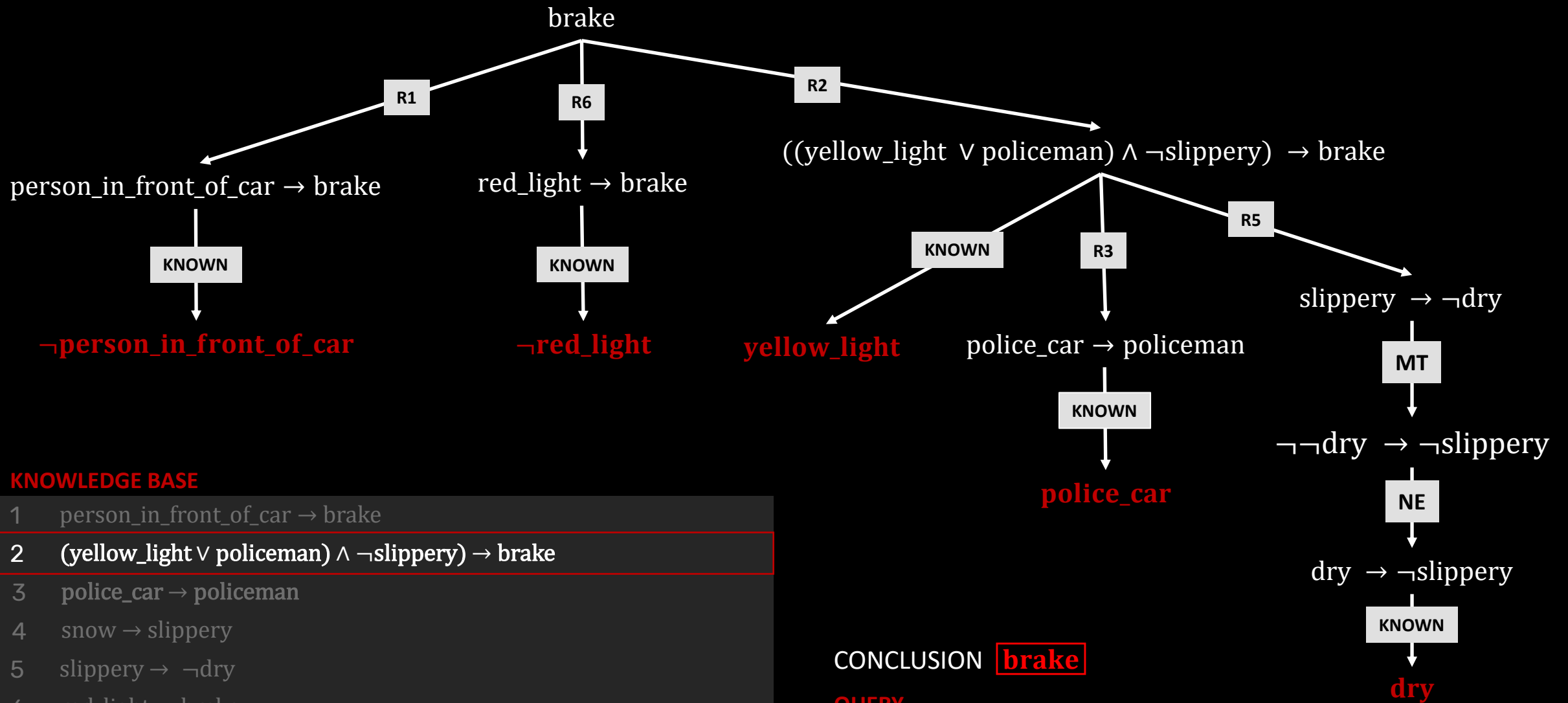
police_car

$\neg \text{red_light}$

$\neg \text{person_in_front_of_car}$

$\neg \text{snow}$

dry



KNOWLEDGE BASE

- 1 $\text{person_in_front_of_car} \rightarrow \text{brake}$
- 2 $((\text{yellow_light} \vee \text{policeman}) \wedge \neg \text{slippery}) \rightarrow \text{brake}$
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- 4 $\text{snow} \rightarrow \text{slippery}$
- 5 $\text{slippery} \rightarrow \neg \text{dry}$
- 6 $\text{red_light} \rightarrow \text{brake}$
- 7 $\text{winter} \rightarrow \text{snow}$

CONCLUSION **brake**

QUERY

Do we need to *Brake*?

FACTS

yellow_light

police_car

$\neg \text{red_light}$

$\neg \text{person_in_front_of_car}$

$\neg \text{snow}$

dry

Efficient satisfiability

The **Davis-Putman-Logemann-Loveland** is a complete search algorithm for deciding if sentences are satisfiable:

- It uses Depth-First Search for backtracking
- DPLL requires that the knowledge base is represented in a CNF form
- It uses improvements to shorten the search:
 - **Early possible** termination
 - **Pure symbol** heuristic: the symbol appears only with one polarity (T or F)
 - **Unit clause** heuristic: the symbol appears alone in a sentence

$DPLL(C, S, M)$:

1. If (every $c \in C$ is **T**) \vee (C is empty),
return **T**
2. If C contains an empty clause,
return **F**
3. If there is a $(t, \text{polarity } v) = \text{pure symbol}(C)$,
return $DPLL(C, S - t, M \cup \{t = v\})$
4. If there is a $(u, \text{polarity } v) = \text{unit clause}(C)$,
return $DPLL(C, S - u, M \cup \{u = v\})$
5. $P = \text{first}(S)$; $R = \text{rest}(S)$;
6. Return
 $DPLL(C, R, M \cup \{P = \text{T}\})$
 \vee
 $DPLL(C, R, M \cup \{P = \text{F}\})$

DPLL(C, S, M):

1. If (every $c \in C$ is **T**) \vee (C is empty),
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5. $P = \mathbf{first}(S); R = \mathbf{rest}(S);$
6. Return
 $\text{DPLL}(C, R, M \cup \{P = \mathbf{T}\})$
 \vee
 $\text{DPLL}(C, R, M \cup \{P = \mathbf{F}\})$

$S = \{s, r, q, p\} \quad M = \{\}$

CLAUSES

$p \vee q \vee r \vee s \quad \wedge$

$\neg p \vee q \vee \neg r \quad \wedge$

$\neg q \vee \neg r \vee s \quad \wedge$

$p \vee \neg q \vee r \vee s \quad \wedge$

$q \vee \neg r \vee \neg s \quad \wedge$

$\neg p \vee \neg s \quad \wedge$

$p \vee \neg q \quad \wedge$

{ }

0

DPLL(C, S, M):

$S = \{s, r, q, p\}$ $M = \{\}$

1. If (every $c \in C$ is **T**) \vee (C is empty),
return **T**
2. If C contains an empty clause,
return **F**
3. If there is a $(t, \text{polarity } v) = \text{pure symbol}(C)$,
return DPLL($C, S - t, M \cup \{t = v\}$)
4. If there is a $(u, \text{polarity } v) = \text{unit clause}(C)$,
return DPLL($C, S - u, M \cup \{u = v\}$)
5. $P = \text{first}(S); R = \text{rest}(S);$
6. Return
 $\text{DPLL}(C, R, M \cup \{P = \mathbf{T}\})$
 \vee
 $\text{DPLL}(C, R, M \cup \{P = \mathbf{F}\})$

CLAUSES

$p \vee q \vee r \vee s \quad \wedge$

$\neg p \vee q \vee \neg r \quad \wedge$

$\neg q \vee \neg r \vee s \quad \wedge$

$p \vee \neg q \vee r \vee s \quad \wedge$

$q \vee \neg r \vee \neg s \quad \wedge$

$\neg p \vee \neg s \quad \wedge$

$p \vee \neg q \quad \wedge$

{ }

0

DPLL(C, S, M):

1. If (every $c \in C$ is **T**) \vee (C is empty),
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 \vee
 $\text{DPLL}(C, R, M \cup \{P = \text{F}\})$

$S = \{s, r, q, p\} \quad M = \{\}$

CLAUSES

$p \vee q \vee r \vee s \quad \wedge$

$\neg p \vee q \vee \neg r \quad \wedge$

$\neg q \vee \neg r \vee s \quad \wedge$

$p \vee \neg q \vee r \vee s \quad \wedge$

$q \vee \neg r \vee \neg s \quad \wedge$

$\neg p \vee \neg s \quad \wedge$

$p \vee \neg q \quad \wedge$

{ }

0

DPLL(C, S, M):

1. If (every $c \in C$ is **T**) \vee (C is empty),
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$S = \{s, r, q, p\} \quad M = \{\}$

CLAUSES

$p \vee q \vee r \vee s \quad \wedge$

$\neg p \vee q \vee \neg r \quad \wedge$

$\neg q \vee \neg r \vee s \quad \wedge$

$p \vee \neg q \vee r \vee s \quad \wedge$

$q \vee \neg r \vee \neg s \quad \wedge$

$\neg p \vee \neg s \quad \wedge$

$p \vee \neg q \quad \wedge$

{ }

0

DPLL(C, S, M):

1. If (every $c \in C$ is **T**) \vee (C is empty),
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5. $P = \text{first}(S); R = \text{rest}(S);$
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 $\text{DPLL}(C, R, M \cup \{P = \text{T}\})$
 \vee
 $\text{DPLL}(C, R, M \cup \{P = \text{F}\})$

$S = \{s, r, q, p\} \quad M = \{\}$

CLAUSES

$p \vee q \vee r \vee s \quad \wedge$

$\neg p \vee q \vee \neg r \quad \wedge$

$\neg q \vee \neg r \vee s \quad \wedge$

$p \vee \neg q \vee r \vee s \quad \wedge$

$q \vee \neg r \vee \neg s \quad \wedge$

$\neg p \vee \neg s \quad \wedge$

$p \vee \neg q \quad \wedge$

{ }

0

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6. Return
 $\text{DPLL}(C, R, M \cup \{P = \text{T}\})$
 \vee
 $\text{DPLL}(C, R, M \cup \{P = \text{F}\})$

$S = \{s, r, q, p\} \quad M = \{\}$

$P = \{s\} \quad R = \{r, q, p\}$

CLAUSES

$p \vee q \vee r \vee s$	\wedge
$\neg p \vee q \vee \neg r$	\wedge
$\neg q \vee \neg r \vee s$	\wedge
$p \vee \neg q \vee r \vee s$	\wedge
$q \vee \neg r \vee \neg s$	\wedge
$\neg p \vee \neg s$	\wedge
$p \vee \neg q$	\wedge

{ }

0

DPLL(C, S, M):

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$S = \{s, r, q, p\} \quad M = \{\}$

$P = \{s\} \quad R = \{r, q, p\}$

$M \cup \{s = \text{T}\}$

CLAUSES

$p \vee q \vee r \vee s \quad \wedge$

$\neg p \vee q \vee \neg r \quad \wedge$

$\neg q \vee \neg r \vee s \quad \wedge$

$p \vee \neg q \vee r \vee s \quad \wedge$

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$S = \{r, q, p\} \quad M = \{s = \text{T}\}$

CLAUSES

$p \vee q \vee r \vee s \quad \wedge$

$\neg p \vee q \vee \neg r \quad \wedge$

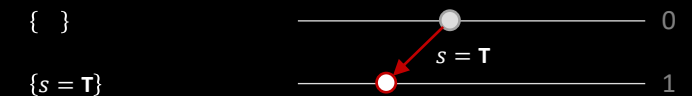
$\neg q \vee \neg r \vee s \quad \wedge$

$p \vee \neg q \vee r \vee s \quad \wedge$

$q \vee \neg r \vee \neg s \quad \wedge$

$\neg p \vee \neg s \quad \wedge$

$p \vee \neg q \quad \wedge$



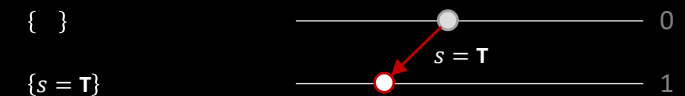
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CLAUSES

$p \vee q \vee r \vee \textcolor{red}{s}$	\wedge
$\neg p \vee q \vee \neg r$	\wedge
$\neg q \vee \neg r \vee \textcolor{red}{s}$	\wedge
$p \vee \neg q \vee r \vee \textcolor{red}{s}$	\wedge
$q \vee \neg r \vee \neg \textcolor{red}{s}$	\wedge
$\neg p \vee \neg \textcolor{red}{s}$	\wedge
$p \vee \neg q$	\wedge



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CLAUSES

$p \vee q \vee r \vee s \quad \wedge \quad = \text{T}$

$\neg p \vee q \vee \neg r \quad \wedge$

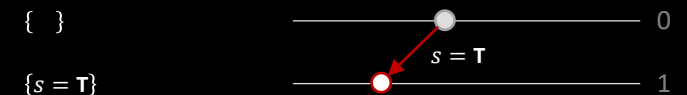
$\neg q \vee \neg r \vee s \quad \wedge \quad = \text{T}$

$p \vee \neg q \vee r \vee s \quad \wedge \quad = \text{T}$

$q \vee \neg r \vee \neg s \quad \wedge$

$\neg p \vee \neg s \quad \wedge$

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CLAUSES

$p \vee q \vee r \vee s \quad \wedge \quad = \text{T}$

$\neg p \vee q \vee \neg r \quad \wedge$

$\neg q \vee \neg r \vee s \quad \wedge \quad = \text{T}$

$p \vee \neg q \vee r \vee s \quad \wedge \quad = \text{T}$

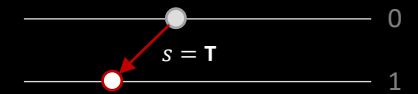
$q \vee \neg r \quad \wedge$

$\neg p \quad \wedge$

$p \vee \neg q \quad \wedge$

$\{ \}$

$\{s = \text{T}\}$



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$S = \{r, q, p\} \quad M = \{s = \mathbf{T}\}$

CLAUSES

$p \vee q \vee r \vee s \quad \wedge \quad = \mathbf{T}$

$\neg p \vee q \vee \neg r \quad \wedge$

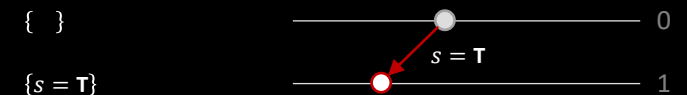
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$\neg p \quad \wedge$

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CLAUSES

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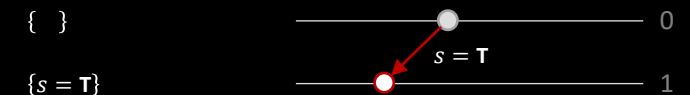
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CLAUSES

$p \vee q \vee r \vee s \quad \wedge \quad = \text{T}$

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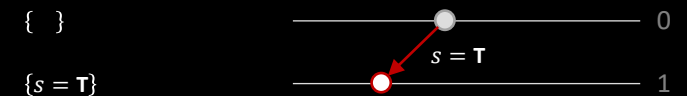
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$S = \{r, q, p\} \quad M = \{s = \text{T}\}$

(r, F)

CLAUSES

$p \vee q \vee r \vee s \quad \wedge \quad = \text{T}$

$\neg p \vee q \vee \neg r \quad \wedge$

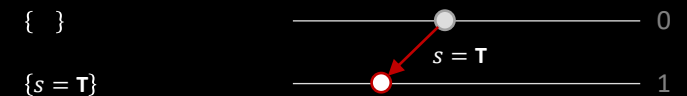
$\neg q \vee \neg r \vee s \quad \wedge \quad = \text{T}$

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(r, F)

CLAUSES

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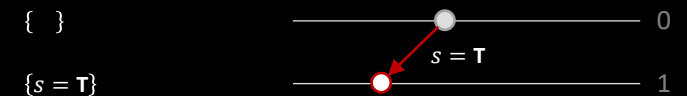
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CLAUSES

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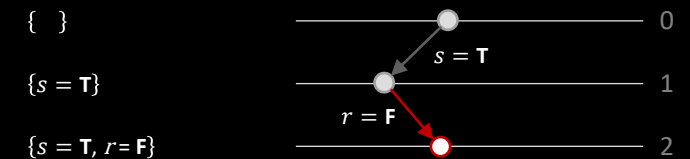
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CLAUSES

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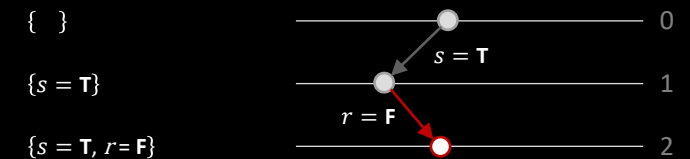
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CLAUSES

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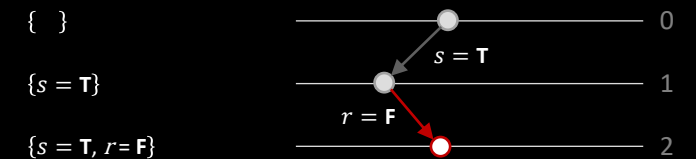
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CLAUSES

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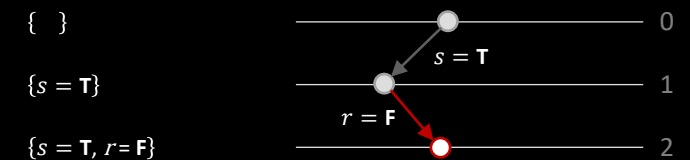
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CLAUSES

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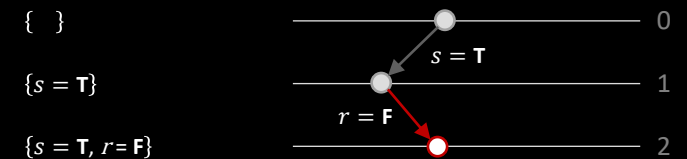
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CLAUSES

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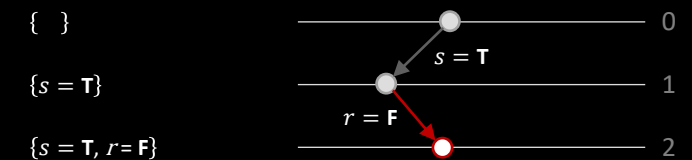
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$S = \{q, p\} \quad M = \{s = \mathbf{T}, r = \mathbf{F}\}$

(q, \mathbf{F})

CLAUSES

$p \vee q \vee r \vee s \quad \wedge \quad = \mathbf{T}$

$\neg p \vee q \vee \neg r \quad \wedge \quad = \mathbf{T}$

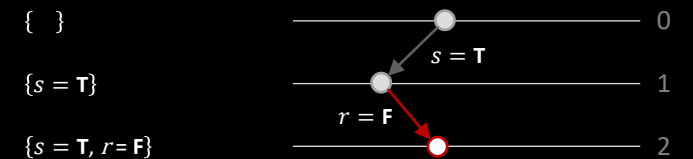
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$\neg p \quad \wedge$

$p \vee \neg q \quad \wedge$



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(q, F)

CLAUSES

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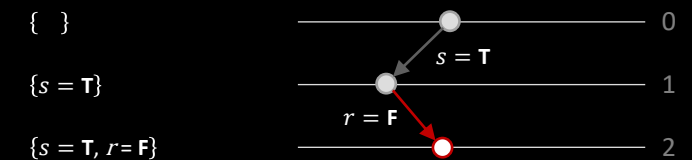
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CLAUSES

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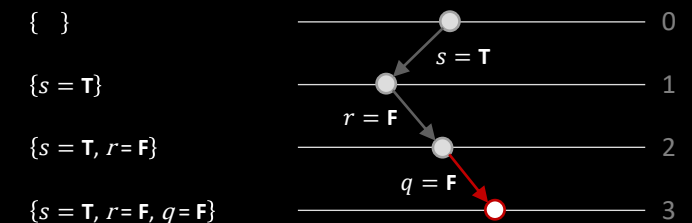
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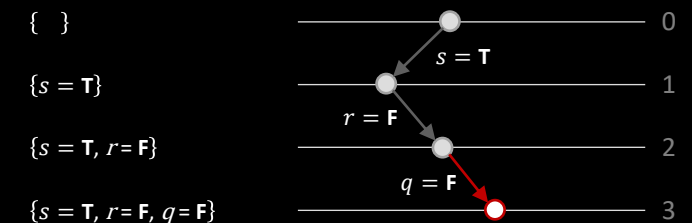
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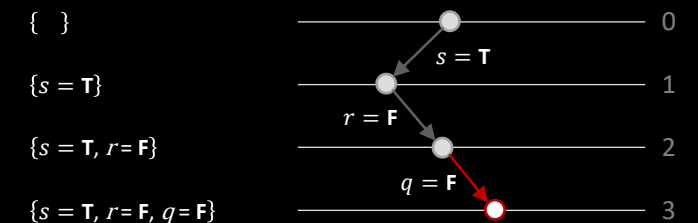
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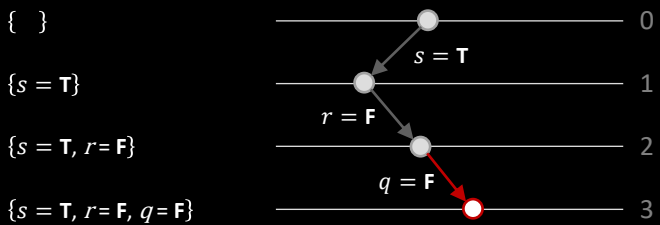
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CLAUSES

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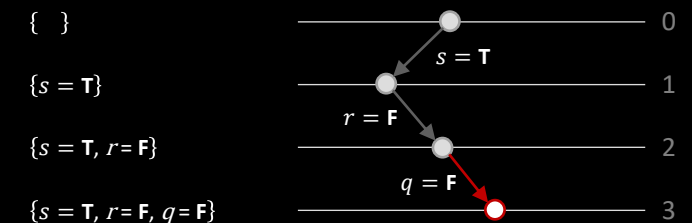
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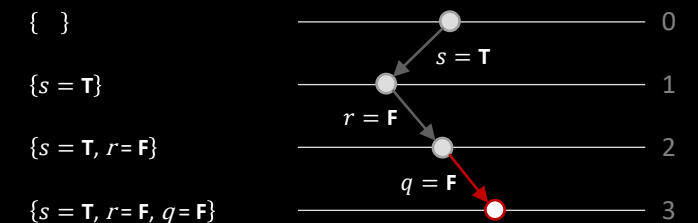
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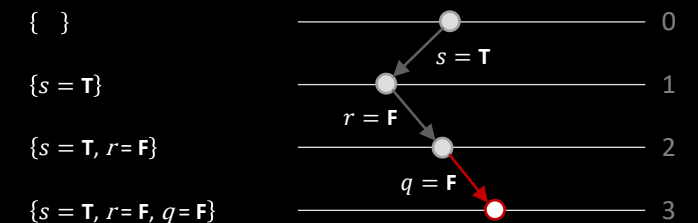
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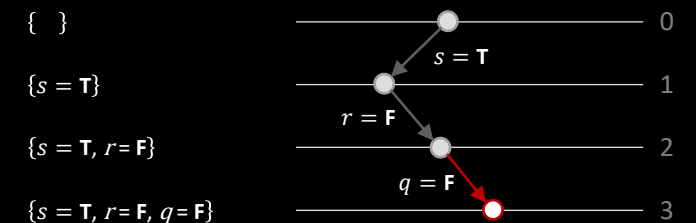
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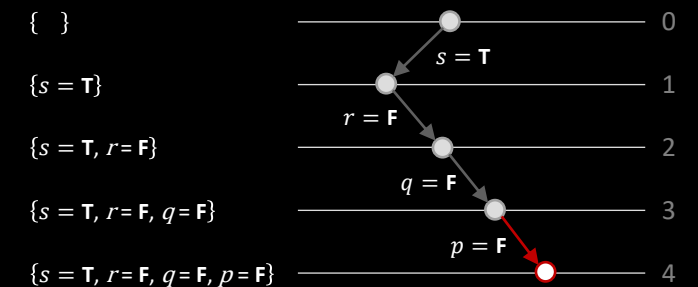
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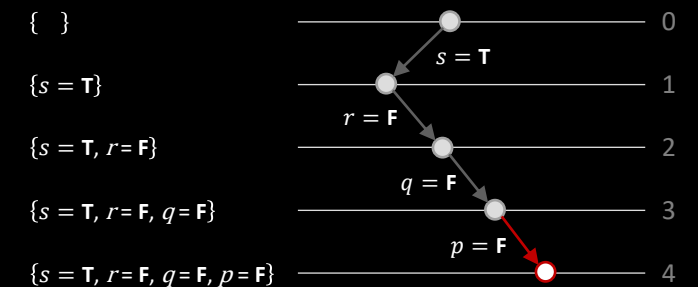
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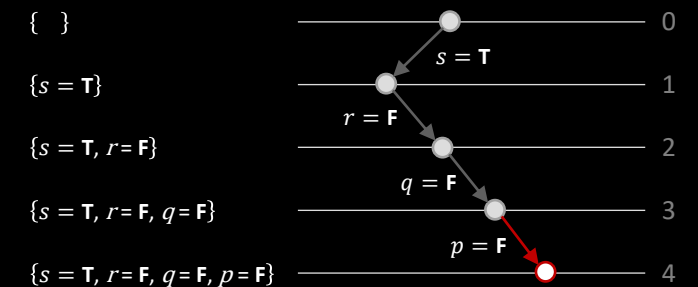
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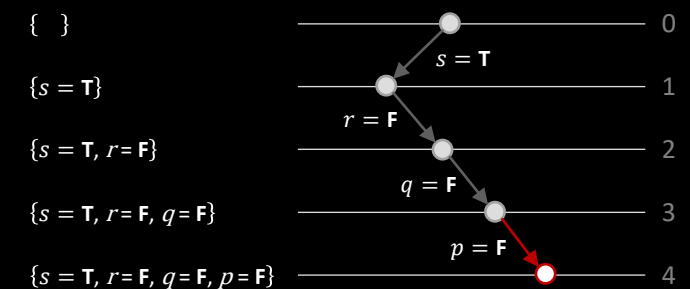
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CLAUSES

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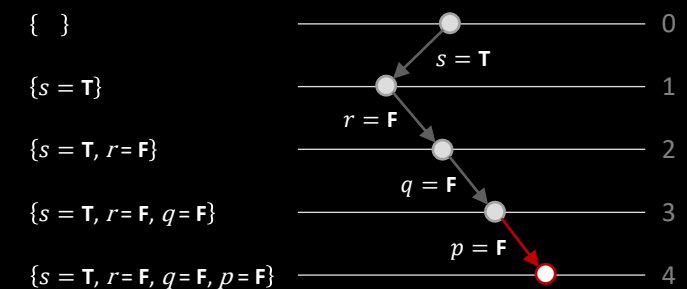
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PRACTICE

Exercises from the textbook (chapter 7):
7.1, 7.4, 7.5, 7.7, 7.10

QUESTIONS ?

ARTIFICIAL INTELLIGENCE

COMP 131

FABRIZIO SANTINI

VERSION 4.1