

4-2 HOW THE EXAMPLE PROJECT WORKS

The code for `main()` is duplicated and shown in Listing 4-1 so that it is more readable.

```
int main (void)
{
    OS_ERR err;

    BSP_IntDisAll();                                (1)
    OSInit(&err);                                    (2)
    OSTaskCreate((OS_TCB *) &AppTaskStartTCB,        (3)
                (CPU_CHAR *) "App Task Start",
                (OS_TASK_PTR) AppTaskStart,
                (void *) 0,
                (OS_PRIO) APP_TASK_START_PRIO,
                (CPU_STK *) &AppTaskStartStk[0],
                (CPU_STK_SIZE) APP_TASK_START_STK_SIZE / 10,
                (CPU_STK_SIZE) APP_TASK_START_STK_SIZE,
                (OS_MSG_QTY) 5,
                (OS_TICK) 0,
                (void *) 0,
                (OS_OPT) (OS_OPT_TASK_STK_CHK | OS_OPT_TASK_STK_CLR),
                (OS_ERR) *) &err);
    OSStart(&err);                                    (4)
}
```

Listing 4-1 `main()` in `app.c`

- L4-1(1) `main()` starts by calling `BSP_IntDisAll()`. The code for this function is found in `bsp_int.c`. `BSP_IntDisAll()` simply calls `CPU_IntDis()` to disable all interrupts. The reason a `bsp.c` function is used instead of simply calling `CPU_IntDis()` is that on some processors, it is necessary to disable interrupts from the interrupt controller, which would then be appropriately handled by a `bsp.c` function. This way, the application code can easily be ported to another processor.
- L4-1(2) `OSInit()` is called to initialize $\mu\text{C}/\text{OS-III}$. Normally, you will want to verify that `OSInit()` returns without error by verifying that `err` contains `OS_ERR_NONE` (*i.e.* the value 0). You can do this with the debugger by single stepping through the code (step over) and stop after `OSInit()` returns. Simply 'hover' the mouse over `err` and the current value of `err` will be displayed.

`OSInit()` creates four internal tasks: the idle task, the tick task, the timer task, and the statistic task. The interrupt handler queue task is not created because in `os_cfg.h`, `OS_CFG_ISR_POST_DEFERRED_EN` set to 0.

L4-1(3) `OSTaskCreate()` is called to create an application task called `AppTaskStart()`. `OSTaskCreate()` contains 13 arguments described in Appendix A, *μC/OS-III API Reference Manual* in Part I of this book.

`AppTaskStartTCB` is the `OS_TCB` used by the task. This variable is declared in the 'Local Variables' section in `app.c`, just a few lines above `main()`.

`AppTaskStartStk[]` is an array of `CPU_STKs` used to declare the stack for the task. In μC/OS-III, each task requires its own stack space. The size of the stack greatly depends on the application. In this example, the stack size is declared through `APP_TASK_START_STK_SIZE`, which is defined in `app_cfg.h`. 128 `CPU_STK` elements are allocated, which, on the Cortex-M3, corresponds to 512 bytes (each `CPU_STK` entry is 4 bytes, see `cpu.h`), and this should be sufficient stack space for the simple code of `AppTaskStart()`.

`APP_TASK_START_PRIO` determines the priority of the start task and is defined in `app_cfg.h`.

L4-1(4) `OSStart()` is called to start the multitasking process. With the application task, μC/OS-III will be managing five tasks. However, `OSStart()` will start the highest priority of the tasks created. In our example, the highest priority task is the `AppTaskStart()` task. `OSStart()` is not supposed to return. However, it would be wise to still add code to check the returned value.

The code for `AppTaskStart()` is shown in Listing 4-2.

```

static void AppTaskStart (void *p_arg)
{
    CPU_INT32U  cpu_clk_freq;
    CPU_INT32U  cnts;
    OS_ERR      err;

    (void)&p_arg;
    BSP_Init();                                     (1)
    CPU_Init();                                     (2)
    cpu_clk_freq = BSP_CPU_ClkFreq();               (3)
    cnts         = cpu_clk_freq / (CPU_INT32U)OSCfg_TickRate_Hz;
    OS_CPU_SysTickInit(cnts);
    #if OS_CFG_STAT_TASK_EN > 0u
        OSStatTaskCPUUsageInit(&err);               (4)
    #endif
    CPU_IntDisMeasMaxCurReset();                   (5)
    BSP_LED_Off(0);                                 (6)
    while (DEF_TRUE) {                              (7)
        BSP_LED_Toggle(0);                           (8)
        OStimeDlyHMSM(0, 0, 0, 100,                 (9)
                      OS_OPT_TIME_HMSM_STRICT,
                      &err);
    }
}

```

Listing 4-2 **AppTaskStart()** in **app.c**

- L4-2(1) **AppTaskStart()** starts by calling **BSP_Init()** (See **bsp.c**) to initialize peripherals used on the μ C/Eval-STM32F107. **BSP_Init()** initializes different clock sources on the STM32F107. The crystal that feeds the μ C/Eval-STM32F107 runs at 25 MHz and the STM32F107's PLLs (Phase Locked Loops) and dividers are configured such that the CPU operates at 72 MHz.
- L4-2(2) **CPU_Init()** is called to initialize the μ C/CPU services. **CPU_Init()** initializes internal variables used to measure interrupt disable time, the time stamping mechanism, and a few other services.
- L4-2(3) The Cortex-M3's system tick timer is initialized. **BSP_CPU_ClkFreq()** returns the frequency (in Hz) of the CPU, which is 72 MHz for the μ C/Eval-STM32F107. This value is used to compute the reload value for the Cortex-M3's system tick timer. The computed value is passed to **OS_CPU_SysTickInit()**, which is part of the μ C/OS-III port (**os_cpu_c.c**). However, this file is not provided in

source form with the book. Once the system tick is initialized, the STM32F107 will receive interrupts at the rate specified by `OS_CFG_TICK_RATE_HZ` (See `os_cfg_app.c`), which in turn is assigned to `OSCfg_TickRate_Hz` in `os_cfg_app.c`. The first interrupt will occur in $1/\text{OS_CFG_TICK_RATE_HZ}$ second, since the interrupt will occur only when the system tick timer reaches zero after being initialized with the computed value, `cnts`.

- L4-2(4) `OSStatTaskCPUUsageInit()` is called to determine the ‘capacity’ of the CPU. µC/OS-III will run ‘only’ its internal tasks for 1/10 of a second and determine the maximum number of time the idle task loops. The number of loops is counted and placed in the variable `OSStatTaskCtr`. This value is saved in `OSStatTaskCtrMax` just before `OSStatTaskCPUUsageInit()` returns. `OSStatTaskCtrMax` is used to determine the CPU usage when other tasks are added. Specifically, as you add tasks to the application `OSStatTaskCtr` (which is reset every 1/10 of a second) is incremented less by the idle task because other tasks consume CPU cycles. CPU usage is determined by the following equation:

$$\text{OSStatTaskCPU Usage}_{(\%)} = \left(100 - \frac{100 \times \text{OSStatTaskCtr}}{\text{OSStatTaskCtrMax}}\right)$$

The value of `OSStatTaskCPUUsage` can be displayed at run-time by µC/Probe. However, this simple example barely uses any CPU time and most likely CPU usage will be near 0.

Note that as of V3.03.00, `OSStatTaskCPUUsage` has a range of 0 to 10,000 to represent 0.00 to 100.00%. In other words, `OSStatTaskCPUUsage` now has a resolution of 0.01% instead of 1%.

- L4-2(5) The µC/CPU module is configured (See `cpu_cfg.h`) to measure the amount of time interrupts are disabled. In fact, there are two measurements, total interrupt disable time assuming all tasks, and per-task interrupt disable time. Each task’s `OS_TCB` stores the maximum interrupt disable time when the task runs. These values can be monitored by µC/Probe at run time. `CPU_IntDisMeasMaxCurReset()` initializes this measurement mechanism.
- L4-2(6) `BSP_LED_Off()` is called to turn off (by passing 0) all user-accessible LEDs (red, yellow and green next to the STM32F107) on the µC/Eval-STM32F107.

- L4-2(7) A typical $\mu\text{C}/\text{OS-III}$ task is written as an infinite loop.
- L4-2(8) `BSP_LED_Toggle()` is called to toggle all three LEDs (by passing 0) at once. You can change the code and specify 1, 2 or 3 to toggle only the green, yellow and red LED, respectively.
- L4-2(9) Finally, a $\mu\text{C}/\text{OS-III}$ task needs to call a $\mu\text{C}/\text{OS-III}$ function that will cause the task to wait for an event to occur. In this case, the event to occur is the passage of time. `OSTimeDlyHMSM()` specifies that the calling task does not need to do anything else until 100 milliseconds expire. Since the LEDs are toggled, they will blink at a rate of 5 Hz (100 milliseconds on, 100 milliseconds off).

4-3 MONITORING VARIABLES USING $\mu\text{C}/\text{PROBE}$

Click the 'Go' button in the IAR C-Spy debugger in order to resume execution of the code.

Now start $\mu\text{C}/\text{Probe}$ by locating the $\mu\text{C}/\text{Probe}$ icon on your PC as shown in Figure 4-7. The icon, by the way, represents a 'box' and the 'eye' sees inside the box (which corresponds to your embedded system). In fact, at Micrium, we like to say, "Think outside the box, but see inside with $\mu\text{C}/\text{Probe}$!"



Figure 4-7 $\mu\text{C}/\text{Probe}$ icon

Figure 4-8 shows the initial screen when $\mu\text{C}/\text{Probe}$ is first started.