Development and calibration of tumor models

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TEXAS ADVANCED COMPUTING CENTER









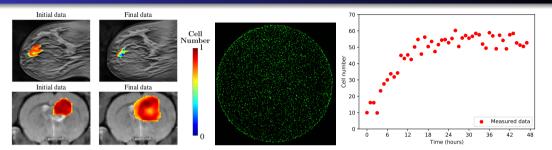


Model Calibration

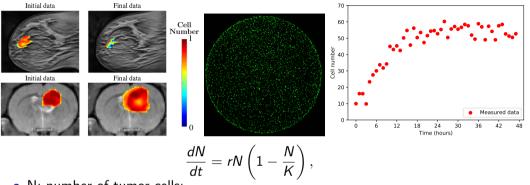
- Calibration Theory:
 - Maximum Likelihood Estimation
 - Bayesian Approach
- EMCEE Python Library¹

¹Foreman-Mackey, Daniel, et al. "emcee v3: A Python ensemble sampling toolkit for affine-invariant MCMC." arXiv preprint arXiv:1911.07688 (2019).

Motivation

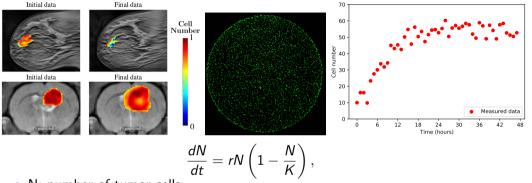


Motivation



- N: number of tumor cells:
- r: tumor growth rate;
- K: environment carrying capacity.

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Model Calibration

It is done to adjust the selected model parameters, such as growth and death rates, to obtain the best fit between the model predicted responses and the available data.

Model calibration: frequentist and Bayesian statistics²

Frequentist and maximum likelihood approaches

- there is an unknown but fixed parameter that represents the event;
- maximum likelihood approach: find the parameter that enables the model to deliver the best characterization of the true target distribution.

²Oden et al., Encyclopedia of Computational Mechanics Second Edition (2017)

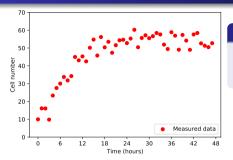
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Bayesian approach

- it maps prior beliefs about the parameters to new posterior beliefs in the light of observing the data;
- the estimated parameter is regarded as a random variable, and the true parameter is merely a realization of the random variable.

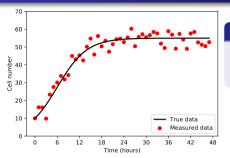


• **D**: measured data;

Mathematical model

$$rac{dN}{dt} = rN\left(1 - rac{N}{K}
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- θ : vector of model parameters, $\theta = (r, K)$;
- r: tumor growth rate;
- K: environmental carrying capacity;
- $Y(\theta)$: model prediction;

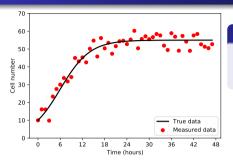


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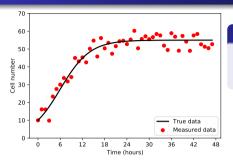
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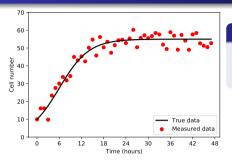
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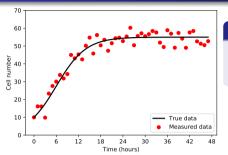
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Assuming:

- **1** the experimental noise is normally distributed $(\epsilon \sim \mathcal{N}(0_{N\times 1}, \sigma_{data}^2 I_{N\times N}));$
- ② the model inadequacy is normally distributed $(\gamma \sim \mathcal{N}(0_{N\times 1}, \sigma_{model}^2 I_{N\times N}));$
- **1** the variance of the total error (σ) is such as $\sigma^2 = \sigma_{data}^2 + \sigma_{model}^2$;
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$$\pi(oldsymbol{D}|oldsymbol{ heta}) = \prod_{i=1}^{N_t} rac{1}{\sqrt{2\pi\sigma^2}} e^{-rac{\left(D_i - Y_i(oldsymbol{ heta})
ight)^2}{2\sigma^2}},$$

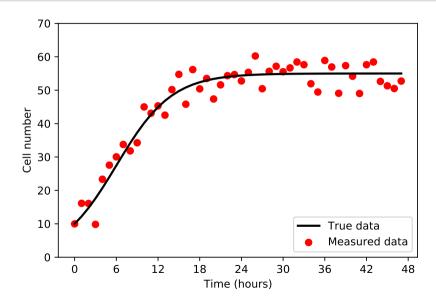
• N_t : the number of data points.

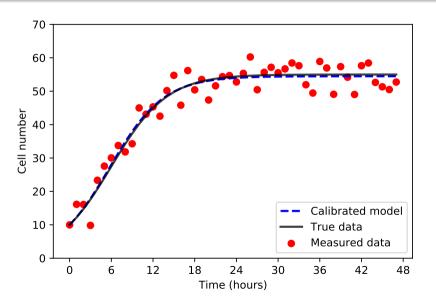


Find $\hat{\theta} \in \Theta$, where Θ is the parameter space, that maximize the likelihood.

It is customary to work with the more manageable log-likelihood function.

$$\begin{split} \hat{\boldsymbol{\theta}} &= \underset{\boldsymbol{\theta} \in \Theta}{\operatorname{argmax}} [\log \pi(\boldsymbol{D}|\boldsymbol{\theta})]; \\ &= \underset{\boldsymbol{\theta} \in \Theta}{\operatorname{argmax}} \left[-\frac{1}{2} \sum_{i=1}^{N_t} \left(\log(2\pi) + \log(\sigma^2) + \frac{(D_i - Y_i(\boldsymbol{\theta}))^2}{\sigma^2} \right) \right]. \end{split}$$





$$\frac{dN}{dt} = rN\left(1 - \frac{N}{K}\right),$$

$$r = 0.25$$

$$K = 59.14$$

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Given events A and B:

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Converting to probability densities π , if A represents the parameter θ of a model, and B the observational data D:

$$\underbrace{\pi(\boldsymbol{\theta}|\boldsymbol{D})}_{\text{posterior}} = \underbrace{\frac{\pi(\boldsymbol{D}|\boldsymbol{\theta})}{\pi(\boldsymbol{\theta})}}_{\text{evidence}} \underbrace{\frac{\pi(\boldsymbol{D}|\boldsymbol{\theta})}{\pi(\boldsymbol{\theta})}}_{\text{evidence}}; \qquad \pi(\boldsymbol{D}) = \int_{\boldsymbol{\Theta}} \pi(\boldsymbol{D}|\boldsymbol{\theta})\pi(\boldsymbol{\theta}) \, \mathrm{d}\boldsymbol{\theta}$$

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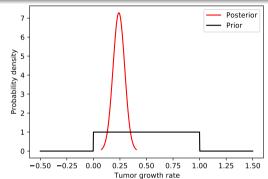
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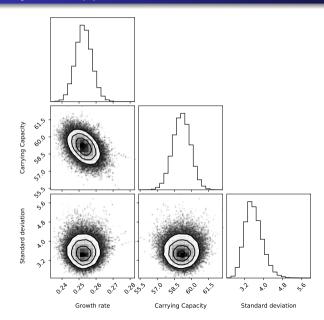
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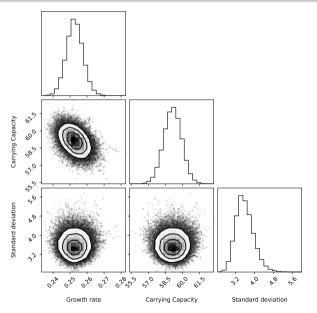
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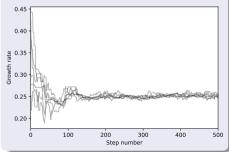
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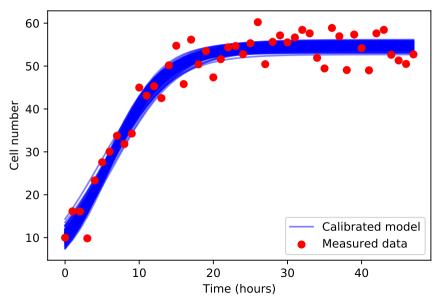




Markov Chain Monte Carlo:

Markov Chain Monte Carlo methods draw samples where the next sample is dependent on the existing sample, called a Markov Chain.





Jupyter Notebook - Binder and Discord

https://github.com/ernesto-lima/veraolncc2021

