

DJI Tello 3D Hand Gesture control

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I certify that except where due acknowledgement has been given, the work presented in this thesis is that of the author alone; the work has not been submitted previously, in whole or in part, to qualify for any other academic award; and the content of the thesis is the result of work which has been carried out since the official commencement date of the approved research program.

Umberto Cocca
Lugano, 23 February 2022

This is a sentence for all my followers

“Gutta cavat lapidem, non vi sed
saepe cadendo.”

Abstract

Hello

Acknowledgements

Hello

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List of Acronyms

Bibliography

Zool Hilmi Ismail and Nohaidda Sariff. A survey and analysis of cooperative multi-agent robot systems: challenges and directions. In *Applications of Mobile Robots*. IntechOpen, 2018.