



## Fixed Point Iteration Method

Mehmet Karakaş

Sakarya University Vocational School of Sakarya 54100, Sakarya / TURKEY

*Received:01.05.2013; Reviewed:10.06.2013; Accepted:23.09.2013*

**Abstract** Our aim is to discuss the problem of finding approximate solutions of the equation. Sometimes we can find the exact roots of the equation 1, for example, when  $(f_x)$  is a quadratic or cubic polynomial then, in general, is convenient finding approximate solutions using same numerical methods. Here, we will discuss a method called fixed point iteration method and particular case of this method called Newton's Method.

*Keywords:* Numerical , Iteration , Algorithm , Variant

## 1. INTRODUCTION

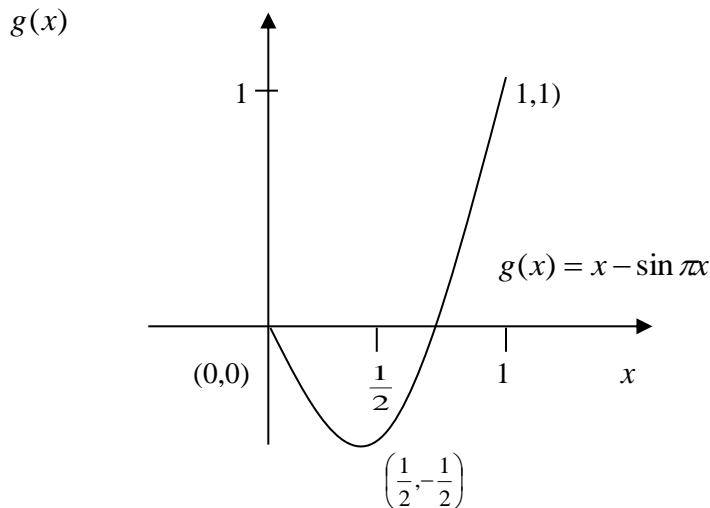
In this section we consider methods for determining the solution to an equation expressed, for some functions  $g$  in the form

$$g(x) = x \quad (2)$$

A solution to such an equation is said to be a fixed point of the function  $g$ . Let's we found a fixed point for any given  $g$ . Then every root finding problem could also be solved for example. The root finding problem  $f(x) = 0$  has solutions that correspond precisely to the fixed points of  $g(x) = x$  when  $g(x) = x - f(x)$ . The first task, then, is to decide when a function will have a fixed point and how the fixed points can be determined. (In numerical analysis, "determined" generally means approximated to a sufficient degree of accuracy.)

### EXAMPLE 1.

- (a) The function  $g(x) = x$ ,  $0 \leq x \leq 1$  has a fixed point at each  $x$  in  $[0, 1]$ .  
 (b) The function  $g(x) = x - \sin \pi x$  has exactly two fixed points in  $[0, 1]$ .  $x = 0$  and  $x = 1$ . (see figure 1.1)



**Figure 1.1.**

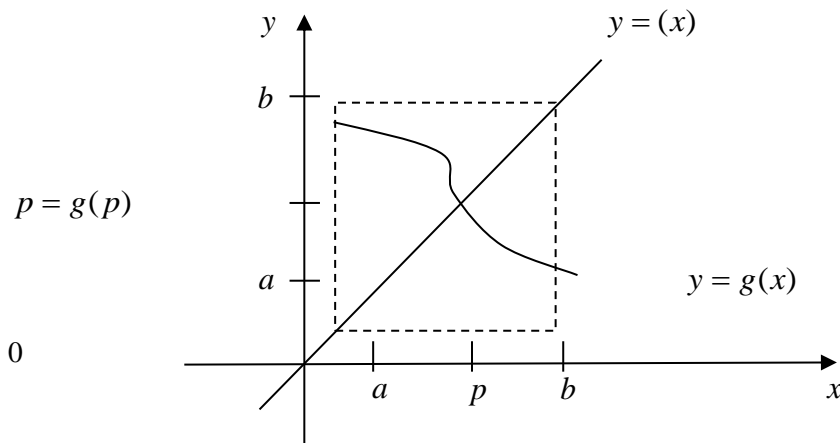
The following theorem gives sufficient conditions for the existence and uniqueness of a fixed point.

### Theorem 1.1.

If  $g \in [a, b]$  and  $g(x) \in [a, b]$ , then  $g$  has a fixed point in  $[a, b]$ . Further, suppose  $g'(x)$  exists on  $[a, b]$  and then a positive constant  $k < 1$  exists with

$$(1.1) \quad |g'(x)| \leq k < 1 \quad \text{for all } x \in (a, b).$$

Then  $g$  has a unique fixed point  $p$  in  $[a, b]$ . (see figure 1.1)



**Figure 1.1.**

Proof: if  $g(a) = a$  or  $g(b) = b$ , the existence of a fixed point is obvious. Suppose not; then it must be true that  $g(a) > a$  and  $g(b) < b$ . Define  $h(x) = g(x) - x$ . Then  $h$  is continuous on  $[a, b]$  and

$$h(a) = g(a) - a > 0, h(b) = g(b) - b < 0$$

The intermediate value theorem implies that there exists  $p \in (a, b)$  for which  $h(p) = 0$  thus,  $g(p) - p = 0$  and  $p$  is a fixed point of  $g$ .

Suppose in addition that inequality (1.1) holds and that  $p$  and  $q$  are both fixed points in  $[a, b]$  with  $p \neq q$ . By the mean value theorem a number  $\xi$  exists between  $p$  and  $q$ . And hence in  $[a, b]$  with.

$$|p - q| = |g(p) - g(q)| = |g'(\xi)| |p - q| \leq k |p - q| < |p - q|$$

Which is a contradiction this contradiction must come from the only supposition  $p \neq q$ . Hence  $p = q$  and the fixed point in  $[a, b]$  is unique

### EXAMPLE 2.

(a) Let  $g(x) = (x^2 - 1)/3$  on  $[-1, 1]$  using the extreme value theorem, it is easy to show that the absolute minimum of  $g$  occurs at  $x = 0$  and  $g(0) = -1/3$ . Similarly. The absolute maximum of  $g$  occurs at  $x = \pm 1$  and has the value  $g(\pm 1) = 0$ . Moreover,  $g$  is continuous and

$$|g'(x)| = \left| \frac{2x}{3} \right| \leq \frac{2}{3} \quad \text{for all } x \in [-1, 1].$$

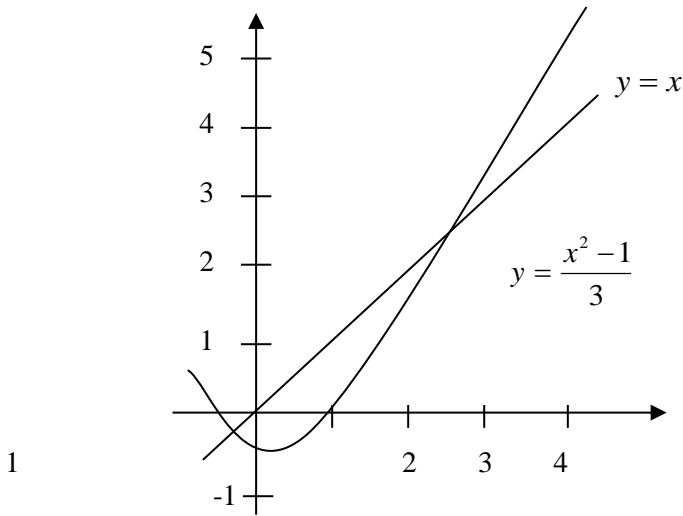
So  $g$  satisfies the hypotheses of theorem 1.1 and has a unique fixed in  $[-1, 1]$ .

In this example the unique fixed point  $p$  in the interval  $[-1, 1]$  can be determined exactly. If

$$p = g(p) = \frac{p^2 - 1}{3}, \text{ then } p^2 - 3p - 1 = 0$$

Which by the quadratic Formula implies that?

$$p = \frac{3 - \sqrt{13}}{2}.$$



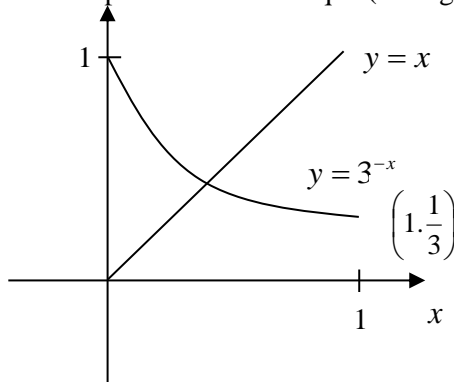
**Figure 1.2.**

That  $g$  also has a unique fixed point  $p = (3 + \sqrt{13})/2$  for interval  $[3,4]$  forever  $g(4) = 5$  and  $g'(4) = \frac{1}{3} > 1$ : so  $g$  does not satisfy their hypotheses of theorem 1.1 this shows that the hypotheses of theorem 1.1 sufficient guarantee a unique fixed point, but are not necessary. (see figure 1.2).

$G(x) = 3^{-x}$ . since  $g'(x) = -3^{-x} \ln 3 < 0$  on  $[0,1]$ , the function this decreasing  $[0,1]$  hence  $g(1) = \frac{1}{3} \leq g(x) \leq 1 = g(0)$  for  $0 \leq x \leq 1$ . this for  $x \in [0,1]$   $g(x) \in [0,1]$  therefore,  $g$  has a fixed point in  $[0,1]$  since

$$g'(0) = -\ln 3 = -1.098612289$$

$f(x) \not\leq 1$  on  $[0,1]$  theorem 1.1 cannot be used determinant unequation forever  $g$  is decreasing so it is clear that the fixed point must the unique (see figure 1.3)



**Figure 1.3.**

Approximate point of a function  $g$ , we choose an initial information  $p$  and sequence  $\{p_n\}_n = 0$  by letting  $p_n = g(p_{n-1})$   $n \geq 1$  if the for  $p$  and  $g$  is continuous then by

### Theorem 1.2

$$p = \lim_{n \rightarrow \infty} p_n = \lim_{n \rightarrow \infty} g(p_{n-1}) = g(\lim_{n \rightarrow \infty} p_{n-1}) = g(p)$$

and a solution to  $x = g(x)$  is obtained this technique is called fixed – point or functional iteration the procedure is detailed in algorithm 1.2 and described in figure 1.4

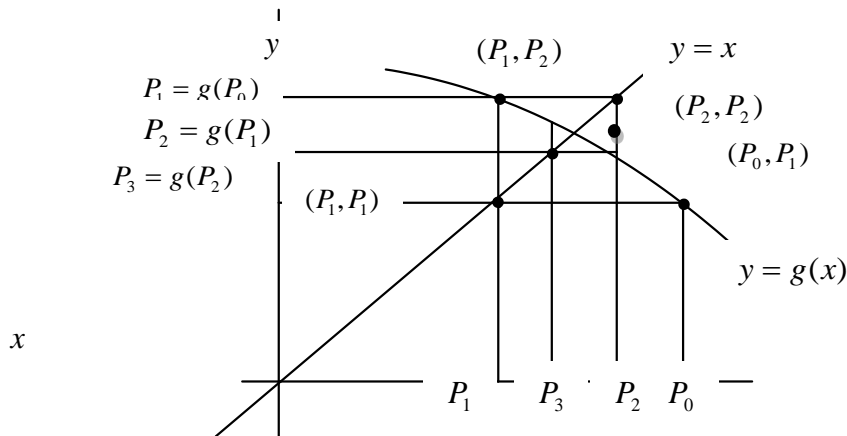


Figure 1.4

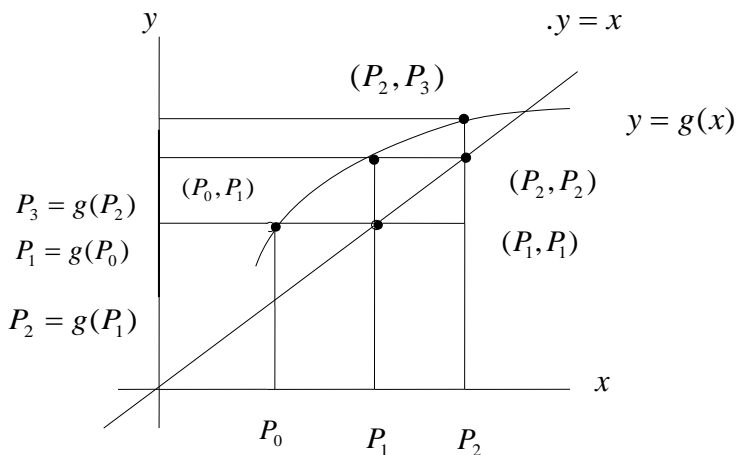


Figure 1.5

### FIXED – POINT ALGORITHM 1

To find a solution to  $p = g(p)$  given an initial approximation  $p_0$ : INPUT initial approximation  $p_0$ ; tolerance TOL; maximum number of iterations no: OUTPUT approximate solution  $p$  or message failure.

Step 1 set  $i = 1$ .

Step 2 while  $i \leq N_0$

Step 3 set  $p = g(p_0)$ . (compare p.)

Step 4 if  $|p - p_0| < TOL$  then

OUTPUT (P), (Procedure completed successfully)

STOP.

Step 5 set  $i = i + 1$ .

Step 6 set  $p_0 = p$ . (Update  $p_0$ )

Step 7 OUTPUT (Method failed after  $N_0$  iterations  $N_0 = N_0$ ;

(Procedure completed unsuccessfully.)

STOP.

To illustrate the technique of functional iteration consider the following example.

### EXAMPLE 3.

a) Let us take the problem given where  $g(x) = \frac{1}{7}(x^3 + 2)$ . Then  $g : [0,1] \rightarrow [0,1]$  and

$|g'(x)| < \frac{3}{7}$  for all  $x \in [0,1]$ . Hence by the previous theorem sequence  $P_n$  defined by the process

$P_{n+1} = \frac{1}{7}(P_n^3 + 2)$  converges to a root of  $x^3 - 7x + 2 = 0$

b) Consider  $f : [0,2] \rightarrow R$  defined by  $f(x) = (1+x)^{\frac{1}{5}}$ . Observe that  $f$  maps  $[0, 2]$  onto itself. Moreover  $|f'(x)| \leq \frac{1}{5} < 1$  for  $x \in [0,2]$ . By the previous theorem the sequence  $(P_n)$

defined by  $P_{n+1} = (1 + P_n)^{1/5}$  converges to a root of  $x^2 - x - 1 = 0$  in the interval  $[0,2]$

In practice, it is often difficult to check the condition  $f([a,b] \leq [a,b])$  given in the previous theorem. We now present a variant of theorem.

Theorem 1.2. (Fixed point theorem) let  $g \in [a,b]$  and suppose that  $g(x) \in [a,b]$  for all  $x$  in  $[a,b]$ . further,

Suppose  $g'$  exists on  $[a,b]$  with

$$|g'(x)| \leq k < 1 \quad \text{for all } x \in (a,b)$$

If  $p_0$  is any number in  $[a,b]$  then the sequence defined by

$$p_n = g(p_{n-1}) \quad n \geq 1.$$

Converges to the unique fixed point  $p$  in  $[a,b]$

Proof by theorem 1.1 a unique fixed point exist in  $[a,b]$  since  $g$  maps  $[a,b]$  into itself the sequence  $\{p_n\}_{n=0}^{\infty}$  is defined for all  $n \geq 0$  and  $p_n \in [a,b]$  for all  $n$ . Using inequality and the mean value theorem.

$$|p_n - p| = |g(p_{n-1}) - g(p)| = |g'(\xi)| |p_{n-1} - p| \leq k |p_{n-1} - p|.$$

Where  $\xi \in (a,b)$  applying inequality (1.3) inductively gives:

$$|p_n - p| \leq k |p_{n-1} - p| \leq k^2 |p_{n-2} - p| \leq \dots \leq k^n |p_0 - p|.$$

Since  $k < 1$ ,

$$\lim_{n \rightarrow \infty} |p_n - p| \leq \lim_{n \rightarrow \infty} k^n |p_0 - p| = 0$$

$$n \rightarrow \infty \quad n \rightarrow \infty$$

and  $\{p_n\}_{n=0}^{\infty}$  converges to  $p$ .

Corollary 1.3 If  $g$  satisfies the hypotheses of theorem 1.2 a bound for the error involve in using  $p_n$  to apporoximate  $p$  is given by.

$$|p_n - p| \leq k^n \max\{p_0 - a, b - p_0\} \quad \text{for all } n \geq 1.$$

Proof from inequality,

$$|p_n - p| \leq k^n |p_0 - p| \leq k^n \max\{p_0 - a, b - p_0\},$$

Since  $p \in [a, b]$

Corollary 1.4 If  $g$  satisfies the hypotheses of theorem 1.2, then

$$|p_n - p| \leq \frac{k^n}{1-k} |p_0 - p_1| \quad \text{for all } n \geq 1$$

Proof for  $n \geq 1$  the procedure used in the proof of theorem 1.2 implies that

$$|p_{n+1} - p_n| = |g(p_n) - g(p_{n-1})| \leq k |p_n - p_{n-1}| \leq \dots \leq k^n |p_1 - p_0|$$

Thus, for  $m > n \geq 1$

$$\begin{aligned} |p_m - p_n| &= |p_m - p_{m-1} + p_{m-1} - \dots + p_{n+1} - p_n| \\ &\leq |p_m - p_{m-1}| + |p_{m-1} - p_{m-2}| + \dots + |p_{n+1} - p_n| \\ &\leq k^{m-1} |p_1 - p_0| + k^{m-2} |p_1 - p_0| + \dots + k^n |p_1 - p_0| \\ &= k^n (1 + k + k^2 + \dots + k^{m-n-1}) |p_1 - p_0| \end{aligned}$$

By theorem 1.2,  $\lim_{m \rightarrow \infty} p_m = p$  so

$$m \rightarrow \infty$$

$$|p - p_n| = \lim_{m \rightarrow \infty} |p_m - p_n| \leq k^n |p_1 - p_0| \sum_{p=0}^{\infty} k^p = \frac{k^n}{1-k} |p_1 - p_0|$$

$$m \rightarrow \infty$$

Both corollaries relate the rate of convergence to the bound  $k$  on the first derivate it is clear that the rate of convergence depends on the factor  $k^n(1-k)$  and that the smaller  $k$  can be made the faster the convergence the convergence may be very slow if  $k$  is close to 1. In the following example the fixed-point methods in example 3 are reconsidered in light of the results described in theorem 1.2.

#### EXAMPLE 4.

(a) When  $g_1(x) = x - x^3 - 4x^2 + 10$ ,  $g'_1(x) = 1 - 3x^2 - 8x$ . Then is no interval  $[a, b]$  containing  $p$  for which  $|g'_1(x)| < 1$  though theorem (1.2) does not guarantee that the method must fail for this choice of  $g$ , there is no reason to expect convergence.

(b) With  $g_2(x) = [(10/x) - 4x]^{1/2}$ , we can see that  $p_2$  does not map  $[1, 5]$  into  $[1, 2]$  and the sequence  $\{p_n\}_{n=0}^{\infty}$  is not defined with  $p = 1.5$  moreover there is no interval containing such that  $|g'_2(x)| < 1$ , since  $|g'_2(p)| \approx 3.4$

(c) for the function  $g_3(x) = \frac{1}{2}(10 - x^3)^{1/2}$

$$g_3(x) = -\frac{3}{4}x^2(10-x^3)^{-1/2} < 0 \quad \text{on } [1,2],$$

So  $g$  is strictly decreasing on  $[1,2]$  however,  $|g'_3(2)| \approx 2.12$ , so inequality (1.2) does not hold on  $[1,2]$ . A closer examination of the sequence  $\{p_n\}_{n=0}^{\infty}$  starting with  $p_0 = 1.5$  will show  $g'_3(x) < 0$  and  $g$  is strictly decreasing but additionally,

$$1 < 1.28 \approx g_3(1.5) \leq g_3(x) \leq g_3(1) = 1.5$$

For all  $x \in [1,1.5]$  this shows that  $g_3$  maps the interval  $[1,1.5]$  into itself. Since it is also true that  $|g'_3(x)| \leq |g'_3(1.5)| \approx 0.66$  on this interval, theorem 1.2 configures the convergence which we were already aware

$$(c) \quad \text{for } g_4(x) = \left( \frac{10}{4+x} \right)^{1/2},$$

$$|g'_4(x)| = \left| \frac{-5}{\sqrt{10}(4+x)^{3/2}} \right| < \frac{5}{\sqrt{10}(5)^{3/2}} < 0.15 \quad \text{for all } [1,2]$$

The bound on the magnitude  $g'_4(x)$  is much smaller than the bound on the magnitude of  $g'_3(x)$  which explains the more rapid convergence using  $g_4$  the other part of example 3 can be handled in a similar manner.

**REMARK:** If  $g$  is invertible then  $P$  is a fixed point of  $g$  if and only if  $q$  is a fixed point of  $g^{-1}$ , in view of this fact, sometimes we can apply the fixed point iteration method for  $g^{-1}$  instead of  $g$ . For understanding, consider  $g(x) = 3x - 21$  then  $|g'(x)| = 3$  for all  $x$ . So the fixed point iteration method may not work. However,  $g^{-1}(x) = \frac{1}{3}x + 7$  and in this case  $|(g^{-1})'(x)| = \frac{1}{3}$  for all  $x$ .

## REFERENCES

- [1] Aho A.V., Hopcroft J.E. and Ullman J.D. (1974) The design and analysis of computer algorithms Addison Wesley, Reading Mass. 470 pp. QA76.6.A.36
- [2] Ames W.F (1977) Numerical methods for partial differential equations (second edition). Academic Press. New York: 365 pp. QA374 A46
- [3] Bailey N.I.J (1967) The mathematical approach to biology and medicine John Wiley & Sons London: 296 pp. QH324 B28
- [4] Bailey N.T.J (1957) The mathematical theory of epidemics C. Griffin London: 194 pp. RA652.B3
- [5] Bailey P.B., Shampine L.F and Waltman P.E. (1968) Nonlinear two-point boundary value problems Academic Press New York: 171 pp. QA372 B27
- [6] Bartle R (1976) The elements of real analysis (second edition) John Wiley & Sons New York: 480 pp. QA300.B29
- [7] Bekker R.G. (1969) Introduction to terrain vehicle systems. University of Michigan Press Ann Arbor, Mich: 846 pp. TL243.B39



- [8] Barnadelli H. (1941) "Population Waves" journal of the Burma Research society: 31, 1-18
- [9] Birkhoff G. and C.De Boor (1964) "Error bounds for spline interpolation" Journal of mathematics and mechanics 13.827-836
- [10] Birkhoff G. and Lynch R.E. (1984) Numerical solution of elliptic problems SIAM publications Philadelphia. Pa: 320 pp. QA374.B57
- [11] Birkhoff G. and Rota G. (1978) Ordinary differential equations.john wiley&sons New York: 342 pp. QA372.B58
- [12] Bracewel R. (1978) The fourier transform and its application (second edition). McGaw Hill.New York: 444 pp. QA403.5.B7
- [13] Brent R. (1973) Algorithms for munimization without derivatives. prentice-hall. Englewood cliffs.n.j. 195 pp. QA403.5.B7
- [14] Brigham E.O. (1974) The fast fourier transform prentice-hall.Englewood cliffs.NJ; 252 pp. QA403.B74
- [15] Brogan W.L. (1982) Modern control theory prentice-hall.Englewood cliffs.N.J; 393 pp. QA402.3.B76
- [16] Brown K.M. (1969) "A quadratically convergent Newton-like method based upon Gaussian elimination" SIAM journal on numerical analysis 6.no 4.560-569.
- [17] Broyden C.G. (1965)"A class of methods for solving nonlinear simultaneous equations."mathematics of computation.19.577-593
- [18] Belirsch R (1964) "Bemerkungen zur romberg-integration" numerische mathematik 6.6.16
- [19] Fehlberg E. (1964) "New high-order Runge-Kutta formulas with step-size control for systems of first-and second-order differential equations" Zeitschrift für angewandte mathematic and mechanic. 44.17-29.
- [20] Fehlberg E. (1966) "New high-order Runge-Kutta formulas with an arbitrarily small truncation error" Zeitschrift für angewandte mathematic and mechanic. 46.1-16.
- [21] Fehlberg E. (1970) "Klassche Runge-kutta formeln vierter und niedrierer ordnung mit schrittweiten-kontrolle und ihre anwendung auf warmeileitungsprobleme" Computing 6.61-71.
- [22] Fix G. (1975) "A survey of numerical methods for selected problems in continuum mechanics"proceedings of a conference on numerical methods of ocean circulation national academy of sciences durham N.H.october 17.20. 1972, 268-283
- [23] Forsythe G.E., Malcolm M.A. and Moler C.A. (1977) Computer methods for mathematical comtations.Prentice-hall.Englewood cliffs NJ: 259 pp. QA297.F568.
- [24] Forsythe G.E. and Moler C.B. (1967) Computer solution of linear algebraic systems.prentice-hall.Englewood cliffs.NJ; 148 pp. QA297.F57
- [25] Fulks W. (1978) Advanced calculus (third edition). john wiley&sons. New York; 731 pp. QA303 F568
- [26] Garcia C.B. and Gould F.J. (1980) "Relations between several path-following algorithms and local and global Newton methods" SIAM Review; 22, No.3, 263-274.
- [27] Gear C.W. (1971) Numarical initial-value problems in ordinary differential equations.pretice-hall, Englewood cliffs, N.J: 253 pp. QA372.G4
- [28] Gear C.W. (1981) "Numerical solution of ordinary differential equations: Is there anything left to do?" SIAM review; 23 No.1, 10-24
- [29] George J.A. (1973) "Nested dissection of a regular finite-element mesh" SIAM journal on numerical analysis 10, No.2, 345-362
- [30] George J.A. and Liu J.H. (1981) Computer solution of large sparse positive difinite systems. prentice-hall englewood cliffs NJ; 324 pp. QA188.G46

- [31] Gladwell I. and Wait R. (1979) A survey of numerical methods for partial differential equations. oxford university pres; 424 pp. QA377.S96
- [32] Golub G.H. and Van Loan C.F. (1963) Matrix computations john Hopkins university press Baltimore; 476 pp. QA188.G65
- [33] Gragg W.B. (1965) "On extrapolation algorithms for ordinary initial-value problems" SIAM Journal on numerical analysis, 2, 284-403.
- [34] Hageman L.A. and Young D.M. (1981) Applied iterative methods. Acedemic pres. New York; 386 pp. QA297.8.H34
- [35] Hamming R.W. (1973) Numerical methods for scientists and engineers (second edition). McGraw-hill, New York; 721 pp. QA297.H28
- [36] Hatcher T.R. (1982) "An error bound for certain successive overrelaxation schems" SIAM journal on numerical analysis.19. No.5.930-941.
- [37] Henrici P. (1962) Discrete variable methods in ordinary differential equations john Wiley&sons New York; 407 pp. QA372.H48
- [38] Householder A.S. (1970) The numerical treatment of a single nonlinear equation McGraw-Hill, New York; 216 pp. QA218.H68
- [39] Watkins D.S. (1982) "Understanding the QR algorithm" SIAM review. 24. No.4, 427-44
- [40] Wendroff B. (1966) Theoretical numerical analysis academic pres New York; 2 pp.QA297.W43
- [41] Wilkinson J.H. (1963) Rounding errors in algebraic processes H.M. stationery Office london; 161 pp. QA76.5.W53
- [42] Wilkinson J.H. and Reinsch V. (1971) Hanbook for automatic computation. Volume linear algebra. springer-verlag. Berlin;439 pp. QA251.W67
- [43] Wilkinson J.H. (1965) The algebraic eigenvalue problem. clarendon pres.oxford; 64 pp.QA218.W5
- [44] Winograd S. (1978) "On computing the discrete fourier transform" mathematics computation, 32, 175-199
- [45] Young D.M. and Gregory R.T. (1972) A survey of numerical mathematics vol. addison-wesley; reading.mass, 533 pp. QA297.Y63.
- [46] Young D.M. (1971) Iterative solution of large linear systems. academic pres, New York; 5 pp. QA195.Y68
- [47] Ypma T.J. (1983) "Finding a multiple zero by transformation and Newton –like methods SIAM Review, 25, No.3, 365-378
- [48] Zienkiewicz O. (1977) The finite-element method in engineering science. McGraw-hill london; 787 pp.TA640.2.Z5.