Comparing different data structures in merging efficiency.

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1 Introduction

A data structure is a way to store and organize data in order to facilitate access and modifications (Cormen, Leiserson, Rivest, & Stein, 2022). Designing and choosing more efficient data structures has always been a great persuit for computer scientists, for optimal data structures can save huge amount of computing resources, especially in face of large amount of data. Basic data structures include ordered data structures like arrays, linked lists and binary search trees and unordered data structures like hashtables.

For ordered data structures, merging two or more instances of them while maintaining its ordered property may be frequently used in practice. For example, to investigate the factors affacting the school grade, data from different schools may be grouped and merged according to various factors. The efficiency of combination varies significantly based on the data structure itself and the algorithm used in the process.

This essay will focus on investigating the theoratical time complexity (need definitions aa) and actual performance of merging algorithms of different data structures, namely arrays, and BSTs, which are the most commonly used data structure in real life.

Research question: How does different algorithm affect the efficiency of merging two instances of ordered data structures?

2 Theory

2.1 Data structure terminology

When a homogeneous relation (a binary relation between two elements) \leq on a set of elements X satisfies:

1. Antisymmetry: $\forall u, v \in X, (u \le v \land v \le u) \Leftrightarrow u = v.$

2. Totality: $\forall u, v \in X, u \leq v \lor v \leq u$.

3. Transitivity: $\forall u, v, w \in X, (u \le v \land v \le w) \Rightarrow u \le w.$

We say $P = (X, \leq)$ is a total order. For example $P = (\mathbb{R}, \leq)$, where \leq is numerical comparison, is a total order. But $P = (\{S : S \subset \mathbb{R}\}, \subset)$ is not a total order.

Ordered data structures can store elements that satisfies a total order while maintaining their order.

2.2 Optimality

When merging two instances of size n and m respectively, there are in total $\binom{n+m}{n}$ possible outcomes. According to the decision tree theory, each of them corresponds to a decision tree leaf node. Since the merging algorithm is comparison based, the decision tree has to be a binary tree (i.e. Each node has at most two children). The height of the decision tree is therefore no lower than $O(\log_2(\binom{n+m}{n}))$.

According to Sterling's approximation,

$$n! \approx \sqrt{2\pi n} \left(\frac{n}{e}\right)^n \tag{1}$$

which means

$$O(\log(n!)) = O(\frac{1}{2}\log(2\pi n) + n\log n - n\log e) = O(n\log n)$$
 (2)

Using the definition of combination number,

$$\binom{n+m}{n} = \frac{(n+m)!}{n!m!} \tag{3}$$

which is approximately $O(n \log_2{(\frac{n}{m})})$ (provided $n \leq m$).

Appendix

Listing 1: VectorSet

```
#include <vector>
#include <algorithm>

template <typename T>
class VectorSet {
private:
   std::vector<T> elements;
```

```
public:
      VectorSet() = default;
      VectorSet(const std::vector<T>& vec, bool sorted = 0){
11
          elements = vec;
12
          if(!sorted)
              std::sort(elements.begin(), elements.end());
      }
16
      // Inserts an element into the set if not already present
17
      void insert(const T& value) {
18
          auto it = std::lower_bound(elements.begin(), elements.end
19
              (), value);
          if (it == elements.end() || *it != value) {
              elements.insert(it, value);
          }
22
      }
23
24
      // Removes an element from the set if present
      void erase(const T& value) {
          auto it = std::lower_bound(elements.begin(), elements.end
              (), value);
          if (it != elements.end() && *it == value) {
              elements.erase(it);
          }
30
31
      // Checks if an element exists in the set
33
      bool contains(const T& value) const {
          return std::binary_search(elements.begin(), elements.end()
              , value);
      }
36
37
      // Returns the number of elements in the set
38
      size_t size() const {
39
          return elements.size();
40
      }
41
      // Checks if the set is empty
43
      bool empty() const {
44
          return elements.empty();
45
```

```
}
46
47
      // Allows iteration over the elements (read-only)
48
      typename std::vector<T>::const_iterator begin() const {
49
          return elements.begin();
      }
51
52
      typename std::vector<T>::const_iterator end() const {
53
          return elements.end();
54
      }
56
      // Clear all elements from the set
      void clear() {
          elements.clear();
      }
60
61
       // Merge another VectorSet into this one (union operation)
62
       void merge(const VectorSet<T>& other) {
63
          std::vector<T> merged;
          merged.reserve(elements.size() + other.elements.size());
          auto it1 = elements.begin(), end1 = elements.end();
          auto it2 = other.elements.begin(), end2 = other.elements.
              end();
69
          while (it1 != end1 && it2 != end2) {
70
              if (*it1 < *it2) {</pre>
71
                  merged.push_back(*it1);
                  ++it1;
73
              } else if (*it2 < *it1) {</pre>
74
                  merged.push_back(*it2);
75
                  ++it2;
76
              } else { // Equal elements
                  merged.push_back(*it1);
                  ++it1;
                  ++it2;
              }
          }
82
83
          // Add remaining elements from either vector
84
```

```
merged.insert(merged.end(), it1, end1);
          merged.insert(merged.end(), it2, end2);
86
87
          elements = std::move(merged);
88
      }
      // Merge-and-assign operator
      VectorSet<T>& operator+=(const VectorSet<T>& other) {
92
          merge(other);
93
          return *this;
94
      }
95
  };
```

Listing 2: AvlSet

```
#include <vector>
#include <algorithm>
#include <memory>
4 #include <list>
  #include <functional>
  #include <stack>
  template <typename T, typename Compare = std::less<T>>
  class AVLSet {
  private:
      struct Node {
11
          T key;
          Node* left;
13
          Node* right;
14
          int height;
16
          template <typename... Args>
17
          Node(Args&&... args)
              : key(std::forward<Args>(args)...),
                left(nullptr),
                right(nullptr),
               height(1) {}
22
      };
23
24
      Node* root;
25
      size_t size;
```

```
Compare comp;
27
28
      // Memory pool management
29
      std::list<Node> node_storage;
30
      std::vector<Node*> free_nodes;
      // Memory pool operations
33
      Node* create_node(const T& key) {
34
          if (!free_nodes.empty()) {
              Node* node = free_nodes.back();
36
              free_nodes.pop_back();
              *node = Node(key);
              return node;
          }
          node_storage.emplace_back(key);
41
          return &node_storage.back();
42
      }
43
44
      Node* create_node(T&& key) {
45
          if (!free_nodes.empty()) {
              Node* node = free_nodes.back();
              free_nodes.pop_back();
              *node = Node(std::move(key));
49
              return node;
50
          node_storage.emplace_back(std::move(key));
          return &node_storage.back();
53
      }
55
      void recycle_node(Node* node) {
56
          free_nodes.push_back(node);
57
      }
58
59
      // Helper functions for merging
60
      int height(Node* node) const {
          return node ? node->height : 0;
      }
63
64
      void update_height(Node* node) {
65
          node->height = 1 + std::max(height(node->left), height(
66
```

```
node->right));
67
68
        Node* rotate_right(Node* y) {
69
           Node* x = y \rightarrow left;
           Node* T2 = x->right;
72
            x->right = y;
73
            y \rightarrow left = T2;
74
            update_height(y);
76
            update_height(x);
            return x;
79
        }
80
81
        Node* rotate_left(Node* x) {
82
            Node* y = x->right;
83
           Node* T2 = y->left;
            y \rightarrow left = x;
            x->right = T2;
            update_height(x);
89
            update_height(y);
90
92
            return y;
       }
94
        int balance_factor(Node* node) const {
95
            return node ? height(node->left) - height(node->right) :
96
                0;
        }
97
98
        Node* balance(Node* node) {
            update_height(node);
            int bf = balance_factor(node);
101
102
            // Left Heavy
103
            if (bf > 1) {
104
```

```
if (balance_factor(node->left) < 0)</pre>
                   node->left = rotate_left(node->left);
106
               return rotate_right(node);
107
           }
108
           // Right Heavy
           if (bf < -1) {</pre>
               if (balance_factor(node->right) > 0)
                   node->right = rotate_right(node->right);
112
               return rotate_left(node);
113
           }
114
           return node;
115
       }
116
117
       template <typename Func>
118
       void traverse_in_order(Node* node, Func f) const {
119
           if (!node) return;
120
           traverse_in_order(node->left, f);
           f(node->key);
122
           traverse_in_order(node->right, f);
123
       }
124
       void insert_merge(const T& key) {
126
           if (!root) {
127
               root = create_node(key);
               size++;
129
               return;
130
           }
131
           std::vector<Node*> path;
133
           std::vector<Node*> successor;
134
           Node* current = root;
           bool inserted = false;
136
137
           // Climb up to find the insertion path
138
           while (true) {
               path.push_back(current);
               if (comp(key, current->key)) {
                   if (!current->left) break;
142
                   successor.push_back(current);
143
                   current = current->left;
144
```

```
} else if (comp(current->key, key)) {
145
                   if (!current->right) break;
146
                   current = current->right;
147
               } else {
148
                   // Duplicate, do not insert
                   return;
151
           }
152
153
           // Insert the new node
154
           Node* newNode = create_node(key);
           if (comp(key, current->key)) {
               current->left = newNode;
157
           } else {
158
               current->right = newNode;
159
160
           size++;
161
162
           // Retrace the path to update heights and balance
163
           while (!path.empty()) {
               Node* node = path.back();
               path.pop_back();
166
               node = balance(node);
167
168
               if (!path.empty()) {
169
                   if (path.back()->left == node) {
                       path.back()->left = node;
171
                   } else {
                       path.back()->right = node;
173
                   }
174
               } else {
175
                   root = node;
               }
           }
178
       }
179
180
   public:
181
       AVLSet() : root(nullptr), size(0), comp(Compare()) {}
182
183
       // Move operations
184
```

```
AVLSet(AVLSet&& other) noexcept
185
           : root(other.root),
186
             size(other.size),
187
             node_storage(std::move(other.node_storage)),
             free_nodes(std::move(other.free_nodes)) {
           other.root = nullptr;
           other.size = 0;
191
       }
192
193
       AVLSet& operator=(AVLSet&& other) noexcept {
194
           if (this != &other) {
195
               clear();
               root = other.root;
197
               size = other.size;
198
               node_storage = std::move(other.node_storage);
199
               free_nodes = std::move(other.free_nodes);
200
               other.root = nullptr;
201
               other.size = 0;
202
           }
203
           return *this;
204
       }
206
       // Disable copy operations
207
       AVLSet(const AVLSet&) = delete;
208
       AVLSet& operator=(const AVLSet&) = delete;
209
210
       void clear() {
211
           node_storage.clear();
           free_nodes.clear();
213
           root = nullptr;
214
           size = 0;
215
216
217
       bool empty() const {
218
           return size == 0;
219
       }
220
       size_t get_size() const {
222
           return size;
223
224
```

```
225
       template <typename Func>
226
       void traverse_in_order(Func f) const {
227
           traverse_in_order(root, f);
228
       }
230
       void merge(AVLSet&& other) {
231
           if (other.empty()) return;
232
233
           if (size < other.size) {</pre>
234
               // Swap to merge smaller into larger
235
               std::swap(root, other.root);
               std::swap(size, other.size);
               std::swap(node_storage, other.node_storage);
               std::swap(free_nodes, other.free_nodes);
239
           }
240
241
           // Insert all elements from the smaller tree (now 'other')
242
                into this
           other.traverse_in_order([this](const T& key) {
243
               this->insert_merge(key);
           });
246
           other.clear();
247
       }
248
249
       private:
250
       // Example of modified insert implementation
       Node* insert(Node* node, const T& key) {
252
           if (!node) {
253
               size++;
254
               return create_node(key);
           }
256
257
           if (comp(key, node->key)) {
               node->left = insert(node->left, key);
           } else if (comp(node->key, key)) {
260
               node->right = insert(node->right, key);
261
           } else {
262
               return node;
263
```

```
}
264
265
           return balance(node);
266
       }
267
       // Example of modified remove implementation
       Node* remove(Node* node, const T& key) {
           if (!node) return nullptr;
271
272
           if (comp(key, node->key)) {
273
               node->left = remove(node->left, key);
274
           } else if (comp(node->key, key)) {
               node->right = remove(node->right, key);
           } else {
               // Node deletion with recycling
278
               if (!node->left || !node->right) {
279
                   Node* temp = node->left ? node->left : node->right
280
                   recycle_node(node);
281
                   size--;
                   node = temp;
               } else {
284
                   Node* temp = findMin(node->right);
285
                   node->key = std::move(temp->key);
286
                   node->right = remove(node->right, temp->key);
287
               }
           }
289
           return node ? balance(node) : nullptr;
291
       }
292
293
       public:
       void insert(const T& val){
295
           insert(root, val);
296
       }
       void remove(const T& val){
           remove(root, val);
       }
300
   };
301
```

References

Cormen, T. H., Leiserson, C. E., Rivest, R. L., & Stein, C. (2022). *Introduction to algorithms* (Fourth ed.). MIT Press.