

Mousetrap validation

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Validation settings

- OpenSesame: version 3.1.6 with legacy backend
- Mousetrap-os plugin: version 1.2.1
- Computer: Windows 7 Professional, Intel Pentium Dual-Core 3 GHz, 4 GB RAM
- External hardware (Henninger, 2017) used to generate predetermined movement patterns
- Cursor position updated at the logging resolution (10 ms)
- Two simulations with 1000 trials each

General preparation

```
# Load libraries
library(readbulk)
library(mousetrap)
library(dplyr)
library(ggplot2)

# Set custom ggplot2 theme
theme_set(theme_classic()+
  theme(
    axis.line = element_line(colour = "black"),
    axis.ticks = element_line(colour = "black"),
    axis.text = element_text(colour = "black"),
    panel.border = element_rect(colour = "black", fill=NA),
    strip.background = element_rect(colour = NA)
  ))

options(width=90)
```

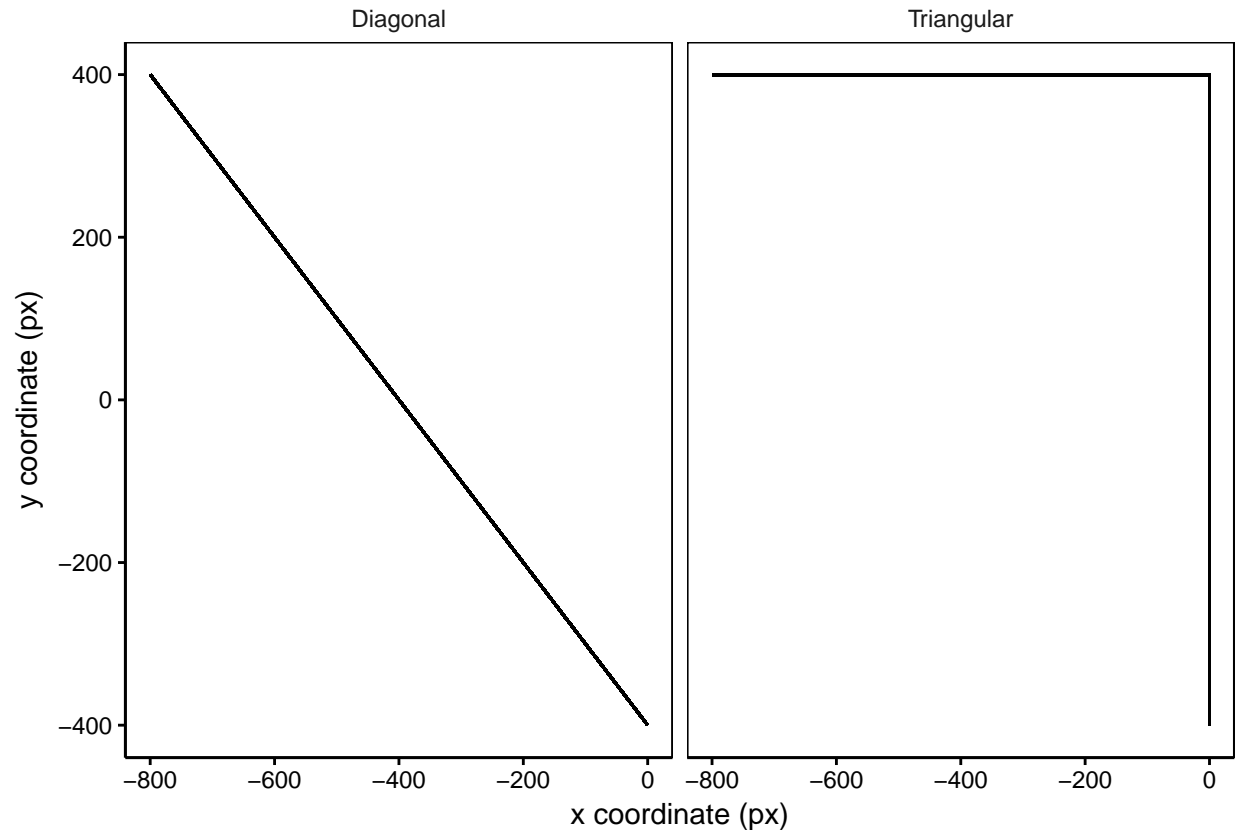
Plot trajectories

```
raw_data <- read_opensesame("validation_data")

## Reading diagonal.csv.gz

## Reading triangular.csv.gz

mt_data <- mt_import_mousetrap(raw_data)
mt_data <- mt_remap_symmetric(mt_data)
mt_data$data$Condition <- factor(mt_data$data$subject_nr, levels=c(1,2),
                                labels=c("Diagonal", "Triangular"))
mt_plot(mt_data, facet_col = "Condition")+
  xlab("x coordinate (px)") + ylab("y coordinate (px)")
```



```
# For vectorized plots, only print one trajectory (looks identical)
# as otherwise rendering takes too much time
# mt_plot(mt_data, facet_col = "Condition", subset=mt_id%in%c("id0001", "id1001"))+
#   xlab("x coordinate (px)") + ylab("y coordinate (px)")

# ggsave("Figure6.pdf", width = 16, height=9, unit="cm")
# ggsave("Figure6.eps", width = 16, height=9, unit="cm")
# ggsave("Figure6.png", width = 16, height=9, unit="cm", dpi=600)
```

Validation 1: Diagonal path

- Start click (0,-400) followed by 110 ms pause
- Every 10 ms cursor moves both one px up and left for 800 px, i.e., for 8000 ms in total
- Cursor pauses at end position (-800,400) for 100 ms and then clicks

Read and preprocess data

```
raw_data <- read_opensesame("validation_data", extension = "diagonal.csv.gz")

## Reading diagonal.csv.gz
mt_data <- mt_import_mousetrap(raw_data)
mt_data <- mt_remap_symmetric(mt_data, remap_xpos = "no")
mt_data <- mt_measures(mt_data)
```

```

mt_data <- mt_derivatives(mt_data, return_delta_time = TRUE,
                          dimensions = "xpos", prefix = "xpos_")
mt_data <- mt_derivatives(mt_data, return_delta_time = TRUE,
                          dimensions = "ypos", prefix = "ypos_")

mt_data_no_reset <- mt_import_mousetrap(raw_data, reset_timestamps = FALSE)

```

Temporal analyses

```

mt_data$data <- mt_data$data %>%
  mutate(
    time_start_click =
      time_get_start_click + response_time_get_start_click,
    delta_click_stimulus =
      time_present_stimulus - time_start_click,
    delta_stimulus_tracking =
      mt_data_no_reset$trajectories[,1,"timestamps"] - time_present_stimulus,
    delta_click_tracking =
      mt_data_no_reset$trajectories[,1,"timestamps"] - time_start_click
  )

summary(select(mt_data$data, starts_with("delta"), response_time), digits = 8)

## delta_click_stimulus delta_stimulus_tracking delta_click_tracking response_time
## Min. :6.000 Min. :0.000 Min. :7.000 Min. :8202.000
## 1st Qu.:6.000 1st Qu.:0.000 1st Qu.:7.000 1st Qu.:8202.000
## Median :7.000 Median :1.000 Median :8.000 Median :8203.000
## Mean :6.936 Mean :0.656 Mean :7.592 Mean :8202.939
## 3rd Qu.:7.000 3rd Qu.:1.000 3rd Qu.:8.000 3rd Qu.:8203.000
## Max. :9.000 Max. :1.000 Max. :9.000 Max. :8206.000

mt_data$data %>%
  select(starts_with("delta"), response_time) %>% summarise_all(c("sd"))

## delta_click_stimulus delta_stimulus_tracking delta_click_tracking response_time
## 1 0.6902031 0.4752787 0.6402702 0.8763829

# mousetrap-os response_time matches mt_measures RT
table(mt_data$data$response_time == mt_data$measures$RT)

##
## TRUE
## 1000

```

Logging resolution

```

mt_check_resolution(mt_data, desired = 10)

## $summary
## Min. 1st Qu. Median Mean 3rd Qu. Max.
## 1.000 10.000 10.000 9.991 10.000 12.000
##
## $sd

```

```
## [1] 0.2533348
##
## $frequencies
## log_diffs
##      1      2      3      4      5      6      10      11      12
##      5    399    453    87    50    5 819852    147     1
##
## $relative_frequencies
## log_diffs
##      1      2      3      4      5      6      10      11      12
## 0.0000 0.0005 0.0006 0.0001 0.0001 0.0000 0.9986 0.0002 0.0000
##
## $frequencies_desired
## log_diffs_class
## smaller desired greater
##      999 819852    148
##
## $relative_frequencies_desired
## log_diffs_class
## smaller desired greater
## 0.0012 0.9986 0.0002
# Percent of lags that lag by 1 ms only
147/148

## [1] 0.9932432
```

Distances between subsequently recorded positions

```
# Frequency of distances converge across both x and y coordinates
table(as.numeric(mt_data$trajectories[,-1,"xpos_dist"]),
      as.numeric(mt_data$trajectories[,-1,"ypos_dist"]))

##
##      0      1      2
## -2      0      0      4
## -1      0 799992      0
##  0  21003      0      0

# Frequency of distances
table(as.numeric(mt_data$trajectories[,-1,"xpos_dist"]))

##
##      -2      -1      0
##      4 799992 21003

# Percent of distances
round(table(as.numeric(mt_data$trajectories[,-1,"xpos_dist"])) /
      sum(!is.na(mt_data$trajectories[,-1,"xpos_dist"])), 6)

##
##      -2      -1      0
## 0.000005 0.974413 0.025582
```

Comparison of expected and observed position

```
# Read in raw data from hardware that generated mouse movements
mouse_coordinates <- read.csv("mouse_diagonal.csv",sep="," ,
                             col.names = c("xpos","ypos","click"))

# Create data frame with expected position for each timestamp
expected <- mouse_coordinates[rep(seq(which(mouse_coordinates$click==1)[1],
                                       which(mouse_coordinates$click==1)[2]),
                                each=10),]
expected$ypos <- (-expected$ypos)

# Set constant for delay between start click and tracking onset
delta_tracking_onset <- 7

# Determine expected position
# (taking delay between start click and tracking onset into account)
mt_data <- mt_add_variables(mt_data,use="trajectories",
                           variables = c("xpos_expected","ypos_expected"))
for (i in rownames(mt_data$trajectories)){
  mt_data$trajectories[i,,"xpos_expected"] <-
    expected[mt_data$trajectories[i,,"timestamps"]+delta_tracking_onset,"xpos"]
  mt_data$trajectories[i,,"ypos_expected"] <-
    expected[mt_data$trajectories[i,,"timestamps"]+delta_tracking_onset,"ypos"]
}

# Correlation between observed and expected position
cor_xpos <- cor(as.vector(mt_data$trajectories[,,"xpos"]),
               as.vector(mt_data$trajectories[,,"xpos_expected"]),
               use="complete.obs")
cor_ypos <- cor(as.vector(mt_data$trajectories[,,"ypos"]),
               as.vector(mt_data$trajectories[,,"ypos_expected"]),
               use="complete.obs")
print(cor_xpos,digits = 15)

## [1] 0.9999999999956697

print(cor_ypos,digits = 15)

## [1] 0.9999999999956697

# Compute difference between expected and observed position
mt_data <- mt_add_variables(mt_data,use="trajectories",variables=list(
  xpos_diff = mt_data$trajectories[,,"xpos_expected"]-mt_data$trajectories[,,"xpos"],
  ypos_diff = mt_data$trajectories[,,"ypos_expected"]-mt_data$trajectories[,,"ypos"]
))

# Frequency of differences between observed and expected positions across both dimensions
# --> differences converge across both dimentions
table(mt_data$trajectories[,,"xpos_diff"],mt_data$trajectories[,,"ypos_diff"])

##
##      0      1
##  -1      0      4
##   0 821995      0
```

```
# Percent of differences
round(table(mt_data$trajectories[,,"xpos_diff"])/
      sum(!is.na(mt_data$trajectories[,,"xpos_diff"])),6)

##
##      -1      0
## 0.000005 0.999995
```

Mouse-tracking indices

```
summary(select(mt_data$measures,MAD,AUC,AD),digits = 8)

##      MAD      AUC      AD
## Min.   :8.038873e-14 Min.   :0   Min.   :5.270548e-16
## 1st Qu.:8.038873e-14 1st Qu.:0   1st Qu.:5.270548e-16
## Median :8.038873e-14 Median :0   Median :5.270548e-16
## Mean   :8.038873e-14 Mean   :0   Mean   :5.270555e-16
## 3rd Qu.:8.038873e-14 3rd Qu.:0   3rd Qu.:5.270548e-16
## Max.   :8.038873e-14 Max.   :0   Max.   :5.276968e-16

mt_data$measures %>% select(MAD,AUC,AD) %>% summarise_all(c("sd"))

##      MAD AUC      AD
## 1      0      0 2.030078e-20
```

Validation 2: Triangular path

- Start click (0,-400) followed by 110 ms pause
- Every 10 ms cursor moves one px up for the first 800 px
- ... and then one px left for the next 800 px, i.e., for 16000 ms in total
- Cursor pauses at end position (-800,400) for 100 ms and then clicks

Read and preprocess data

```
raw_data <- read_opensesame("validation_data",extension = "triangular.csv.gz")

## Reading triangular.csv.gz

mt_data <- mt_import_mousetrap(raw_data)
mt_data <- mt_remap_symmetric(mt_data,remap_xpos = "no")
mt_data <- mt_measures(mt_data)
mt_data <- mt_derivatives(mt_data, return_delta_time = TRUE,
                          dimensions = "xpos", prefix = "xpos_")
mt_data <- mt_derivatives(mt_data, return_delta_time = TRUE,
                          dimensions = "ypos", prefix = "ypos_")

mt_data_no_reset <- mt_import_mousetrap(raw_data,reset_timestamps = FALSE)
```

Temporal analyses

```
mt_data$data <- mt_data$data %>%
  mutate(
    time_start_click =
      time_get_start_click+response_time_get_start_click,
    delta_click_stimulus =
      time_present_stimulus-time_start_click,
    delta_stimulus_tracking =
      mt_data_no_reset$trajectories[,1,"timestamps"]-time_present_stimulus,
    delta_click_tracking =
      mt_data_no_reset$trajectories[,1,"timestamps"]-time_start_click
  )

summary(select(mt_data$data, starts_with("delta"), response_time), digits = 8)

##  delta_click_stimulus delta_stimulus_tracking delta_click_tracking response_time
##  Min.      :6.000      Min.      :0.000      Min.      : 7.000      Min.      :16201.000
##  1st Qu.:6.000      1st Qu.:0.000      1st Qu.: 7.000      1st Qu.:16203.000
##  Median :7.000      Median :1.000      Median : 7.000      Median :16203.000
##  Mean   :6.918      Mean   :0.656      Mean   : 7.574      Mean   :16203.134
##  3rd Qu.:7.000      3rd Qu.:1.000      3rd Qu.: 8.000      3rd Qu.:16203.000
##  Max.   :9.000      Max.   :1.000      Max.   :10.000      Max.   :16205.000

mt_data$data %>%
  select(starts_with("delta"), response_time) %>% summarise_all(c("sd"))

##  delta_click_stimulus delta_stimulus_tracking delta_click_tracking response_time
##  1                0.6750791                0.4752787                0.6457096                0.9396419

# mousetrap-os response_time matches mt_measures RT
table(mt_data$data$response_time==mt_data$measures$RT)

##
## TRUE
## 1000
```

Logging resolution

```
mt_check_resolution(mt_data, desired = 10)

## $summary
##   Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
##  1.000 10.000  10.000   9.996 10.000  25.000
##
## $sd
## [1] 0.1786731
##
## $frequencies
## log_diffs
##      1      2      3      4      5      8      9      10      11      12      13
##    57    310    439    65   114     2     3 1619692    284    12     2
##    14     25
##     2     1
```

```
##
## $relative_frequencies
## log_diffs
##      1      2      3      4      5      8      9     10     11     12     13     14
## 0.0000 0.0002 0.0003 0.0000 0.0001 0.0000 0.0000 0.9992 0.0002 0.0000 0.0000 0.0000
##      25
## 0.0000
##
## $frequencies_desired
## log_diffs_class
## smaller desired greater
##      990 1619692      301
##
## $relative_frequencies_desired
## log_diffs_class
## smaller desired greater
## 0.0006 0.9992 0.0002
# Percent of lags that lag by 1 ms only
284/301

## [1] 0.9435216
```

Distances between subsequently recorded positions

```
# Frequency of distances across both x and y coordinates
table(as.numeric(mt_data$trajectories[,-1,"xpos_dist"]),
      as.numeric(mt_data$trajectories[,-1,"ypos_dist"]))

##
##      0      1      2
## -3      1      0      0
## -2     82      0      0
## -1 799833      0      0
##  0  21143 799848      76

# Frequency of distances for x coordinates
table(as.numeric(mt_data$trajectories[,-1,"xpos_dist"]))

##
##      -3      -2      -1      0
##      1     82 799833 821067

# Percent of distances for x coordinates
round(table(as.numeric(mt_data$trajectories[,-1,"xpos_dist"]))/
      sum(!is.na(mt_data$trajectories[,-1,"ypos_dist"])),6)

##
##      -3      -2      -1      0
## 0.000001 0.000051 0.493425 0.506524

# Frequency of distances for y coordinates
table(as.numeric(mt_data$trajectories[,-1,"ypos_dist"]))

##
##      0      1      2
```



```
## 821059 799848      76
# Percent of distances for y coordinates
round(table(as.numeric(mt_data$trajectories[,-1,"ypos_dist"]))/
      sum(!is.na(mt_data$trajectories[,-1,"ypos_dist"])),6)

##
##      0      1      2
## 0.506519 0.493434 0.000047
```

Comparison of expected and observed position

```
# Read in raw data from hardware that generated mouse movements
mouse_coordinates <- read.csv("mouse_triangular.csv",sep="," ,
                             col.names = c("xpos","ypos","click"))

# Create data frame with expected position for each timestamp
expected <- mouse_coordinates[rep(seq(which(mouse_coordinates$click==1)[1],
                                       which(mouse_coordinates$click==1)[2]),
                                each=10),]

expected$ypos <- (-expected$ypos)

# Set constant for delay between start click and tracking onset
delta_tracking_onset <- 7

# Determine expected position
# (taking delay between start click and tracking onset into account)
mt_data <- mt_add_variables(mt_data,use="trajectories",
                           variables = c("xpos_expected","ypos_expected"))
for (i in rownames(mt_data$trajectories)){
  mt_data$trajectories[i,,"xpos_expected"] <-
    expected[mt_data$trajectories[i,,"timestamps"]+delta_tracking_onset,"xpos"]
  mt_data$trajectories[i,,"ypos_expected"] <-
    expected[mt_data$trajectories[i,,"timestamps"]+delta_tracking_onset,"ypos"]
}

# Correlation between observed and expected position
cor_xpos <- cor(as.vector(mt_data$trajectories[,,"xpos"]),
               as.vector(mt_data$trajectories[,,"xpos_expected"]),
               use="complete.obs")
cor_ypos <- cor(as.vector(mt_data$trajectories[,,"ypos"]),
               as.vector(mt_data$trajectories[,,"ypos_expected"]),
               use="complete.obs")
print(cor_xpos,digits = 15)

## [1] 0.999999992661407
print(cor_ypos,digits = 15)

## [1] 0.999999994872842

# Compute difference between expected and observed position
mt_data <- mt_add_variables(mt_data,use="trajectories",variables=list(
  xpos_diff = mt_data$trajectories[,,"xpos_expected"]-mt_data$trajectories[,,"xpos"],
  ypos_diff = mt_data$trajectories[,,"ypos_expected"]-mt_data$trajectories[,,"ypos"]
```

```

))

# Frequency of differences between observed and expected positions across both dimensions
table(mt_data$trajectories[,,"xpos_diff"],mt_data$trajectories[,,"ypos_diff"])

##
##      -1      0      1
## -2      0      1      0
## -1      0      4      0
##  0    1136 1619213      2
##  1      0    1627      0

# Percent of differences for xpos
round(table(mt_data$trajectories[,,"xpos_diff"])/
      sum(!is.na(mt_data$trajectories[,,"xpos_diff"])),6)

##
##      -2      -1      0      1
## 0.000001 0.000002 0.998994 0.001003

# Percent of differences for ypos
round(table(mt_data$trajectories[,,"ypos_diff"])/
      sum(!is.na(mt_data$trajectories[,,"ypos_diff"])),6)

##
##      -1      0      1
## 0.000700 0.999298 0.000001

```

Mouse-tracking measures

```

# Descriptives
summary(select(mt_data$measures,MAD,AUC,AD),digits = 8)

##      MAD      AUC      AD
## Min.   :565.6854 Min.   :320000 Min.   :279.00550
## 1st Qu.:565.6854 1st Qu.:320000 1st Qu.:279.00637
## Median :565.6854 Median :320000 Median :279.00637
## Mean   :565.6854 Mean   :320000 Mean   :279.00871
## 3rd Qu.:565.6854 3rd Qu.:320000 3rd Qu.:279.00637
## Max.   :565.6854 Max.   :320000 Max.   :279.33641

mt_data$measures %>% select(MAD,AUC,AD) %>% summarise_all(c("sd"))

##      MAD AUC      AD
## 1      0      0 0.02159266

# Expected MAD
.5*sqrt(800^2+800^2)

## [1] 565.6854

# Expected AUC
.5*800^2

## [1] 320000

```

```
# Expected AD  
mean(c(seq(0,800,1),seq(799,0,-1))/sqrt(2))*1601/1622  
  
## [1] 279.0064
```