

1. Provide cx for the statement:

$\text{inv2}(x,y,a,b) = \text{inv}(x,y)[5000 \rightarrow a, 10000 \rightarrow b]$

```
In [ ]: import sys
sys.path.insert(1, '/Users/ekvashyn/Code/spacer-on-jupyter/src/')
from spacer_tutorial import *
import z3
z3.set_param(proof=True)
z3.set_param(model=True)
z3.set_html_mode(True)
```

```
In [ ]: def mk_ts0():
    T = Ts('Ts0')
    x, x_out = T.add_var(z3.IntSort(), name='x')
    y, y_out = T.add_var(z3.IntSort(), name='y')
    T.Init = z3.And(x == 0, y == 5000)
    T.Tr = z3.And(x_out == x + 1, y_out == z3.If(x >= 5000, y+1, y))
    T.Bad = z3.And(x == 10000, x != y)
    return T

ts0 = mk_ts0()
HtmlStr(ts0)
```

Out[]: Transition System: Ts0

Init: $x = 0 \wedge y = 5000$

Bad: $x = 10000 \wedge x \neq y$

Tr: $x' = x + 1 \wedge y' = \text{If}(x \geq 5000, y + 1, y)$

```
In [ ]: def mk_ts1():
    T = Ts('Ts1')
    x, x_out = T.add_var(z3.IntSort(), name='x')
    y, y_out = T.add_var(z3.IntSort(), name='y')
    a, a_out = T.add_var(z3.IntSort(), name='a')
    b, b_out = T.add_var(z3.IntSort(), name='b')
    T.Init = z3.And(a == 5000, b == 10000, x == 0, y == a)
    T.Tr = z3.And(x_out == x + 1, y_out == z3.If(x >= a, y+1, y), a_out == a)
    T.Bad = z3.And(x == b, x != y)
    return T

ts1 = mk_ts1()
HtmlStr(ts1)
```

Out[]: Transition System: Ts1

Init: $a = 5000 \wedge b = 10000 \wedge x = 0 \wedge y = a$

Bad: $x = b \wedge x \neq y$

Tr: $x' = x + 1 \wedge y' = \text{If}(x \geq a, y + 1, y) \wedge a' = a \wedge b' = b$

```
In [ ]: def vc_gen(T):
    '''Verification Condition (VC) for an Inductive Invariant'''
```

```

Inv = z3.Function('Inv', *(T.sig() + [z3.BoolSort()])))

InvPre = Inv(*T.pre_vars())
InvPost = Inv(*T.post_vars())

all_vars = T.all()
vc_init = z3.ForAll(all_vars, z3.Implies(T.Init, InvPre))
vc_ind = z3.ForAll(all_vars, z3.Implies(z3.And(InvPre, T.Tr), InvPost))
vc_bad = z3.ForAll(all_vars, z3.Implies(z3.And(InvPre, T.Bad), z3.BoolVal(False)))
return [vc_init, vc_ind, vc_bad], InvPre

```

```

In [ ]: vc0, inv0 = vc_gen(ts0)
        vc1, inv1 = vc_gen(ts1)

```

```

In [ ]: chc_to_str(vc0)

```

```

Out[ ]:  $\forall x, y, x', y' : x = 0 \wedge y = 5000 \Rightarrow \text{Inv}(x, y)$ 

```

$\forall x, y, x', y' :$
 $\text{Inv}(x, y) \wedge x' = x + 1 \wedge y' = \text{If}(x \geq 5000, y + 1, y) \Rightarrow$
 $\text{Inv}(x', y')$

$\forall x, y, x', y' : \text{Inv}(x, y) \wedge x = 10000 \wedge x \neq y \Rightarrow \text{False}$

```

In [ ]: chc_to_str(vc1)

```

```

Out[ ]:  $\forall x, y, a, b, x', y', a', b' :$   

 $a = 5000 \wedge b = 10000 \wedge x = 0 \wedge y = a \Rightarrow \text{Inv}(x, y, a, b)$ 

```

$\forall x, y, a, b, x', y', a', b' :$
 $\text{Inv}(x, y, a, b) \wedge$
 $x' = x + 1 \wedge$
 $y' = \text{If}(x \geq a, y + 1, y) \wedge$
 $a' = a \wedge$
 $b' = b \Rightarrow$
 $\text{Inv}(x', y', a', b')$

$\forall x, y, a, b, x', y', a', b' :$
 $\text{Inv}(x, y, a, b) \wedge x = b \wedge x \neq y \Rightarrow \text{False}$

```

In [ ]: HtmlStr(inv0)

```

```

Out[ ]: Inv(x, y)

```

```

In [ ]: HtmlStr(inv1)

```

Out[1]: `Inv(x, y, a, b)`

In []: `res0, answer0 = solve_horn(vc0, max_unfold=100)`

In []: `res1, answer1 = solve_horn(vc1, max_unfold=100)`

In []: `res0`

Out[]: **sat**

In []: `res1`

Out[]: **sat**

In []: `answer0`

Out[]: `[Inv = [else → (¬(v₀ ≤ 5000) ∨ ¬(v₁ ≥ 5001)) ∧ ¬(v₀ + -1·v₁ ≥ 1) ∧ (¬(v₀ ≥ 5000) ∨ ¬(v₀ + -1·v₁ ≤ -1)) ∧ ¬(v₁ ≤ 4999)]]`

In []: `answer1`

Out[]: `[Inv = [else → (¬(v₁ + -1·v₀ ≤ -1) ∨ ¬(v₀ + -1·v₃ ≥ -3)) ∧ ¬(v₂ + -1·v₃ ≥ -4999) ∧ (¬(v₀ + -1·v₂ ≤ -1) ∨ ¬(v₁ + -1·v₂ ≥ 1)) ∧ (¬(v₁ + -1·v₀ ≤ -1) ∨ ¬(v₀ + -1·v₃ ≤ -2) ∨ ¬(v₀ + -1·v₂ ≥ 0)) ∧ ¬(v₁ + -1·v₂ ≤ -1) ∧ (¬(v₀ + -1·v₂ ≥ 0) ∨ ¬(v₁ + -1·v₀ ≥ 1))]]`

In []: `answer0.eval(inv0)`

Out[]: `(¬(x ≤ 5000) ∨ ¬(y ≥ 5001)) ∧ ¬(x + -1·y ≥ 1) ∧ (¬(x ≥ 5000) ∨ ¬(x + -1·y ≤ -1)) ∧ ¬(y ≤ 4999)`

In []: `answer1.eval(inv1)`

Out[]: `(¬(y + -1·x ≤ -1) ∨ ¬(x + -1·b ≥ -3)) ∧ ¬(a + -1·b ≥ -4999) ∧ (¬(x + -1·a ≤ -1) ∨ ¬(y + -1·a ≥ 1)) ∧ (¬(y + -1·x ≤ -1) ∨ ¬(x + -1·a ≥ 0) ∨ ¬(x + -1·b ≤ -2)) ∧ ¬(y + -1·a ≤ -1) ∧ (¬(x + -1·a ≥ 0) ∨ ¬(y + -1·x ≥ 1))`

Invariant for the original benchmark is:

$Inv1(x,y) =$

$$(\neg(y \geq 5001) \vee \neg(y + -1 \cdot x \geq 1)) \wedge \neg(y + -1 \cdot x \leq -1) \wedge \neg(y \leq 4999) =$$

$$(y \geq 5001) \Rightarrow (y \geq x + 1) \wedge y \geq x \wedge y > 4999$$

Invariant for the transformed benchmark is:

$Inv2(x,y,a,b) =$

$$(\neg(y \geq 5001) \vee x \geq y) \wedge y \geq a \wedge x \leq y =$$

$$(y > a \Rightarrow x \geq y) \wedge y \geq a \wedge x \leq y$$

We need to prove that $Inv1(x,y)[5000 \rightarrow a, 10000 \rightarrow b] \models Inv2(x,y,a,b)$

Let's rewrite $\text{Inv1}(x,y)$ in such way:

$$\text{Inv1}(x,y) = ((y \geq 5001 \Rightarrow x \geq y) \ \&\& \ y \geq 5000 \ \&\& \ x \leq y)$$

$$\text{Inv1}(x,y)[5000 \rightarrow a, 10000 \rightarrow b] = ((y \geq 5001 \Rightarrow x \geq y) \ \&\& \ y \geq a \ \&\& \ x \leq y)$$

```
In [ ]: from z3 import *

# Create Z3 variables
a, b, x, y, x_prime, y_prime = Ints('a b x y x_prime y_prime')

# Create a Z3 solver
solver = Solver()

# Initial conditions
solver.add(x == 0)
solver.add(y == a)

# Transition relation constraints
transition_constraints = And(
    x_prime == x + 1,
    y_prime == If(x >= a, y + 1, y)
)

# Invariant constraints
invariant_constraints = And(
    Implies(y > 5001, x >= y),
    y >= a,
    x <= y
)

# Add transition relation and invariant constraints to the solver
solver.add(transition_constraints)
solver.add(Not(invariant_constraints)) # Adding negation of the invariant f

# Check for satisfiability
if solver.check() == unsat:
    print("Invariant holds for the transition system.")
else:
    print("Invariant does not hold for the transition system.")
    counterexample = solver.model()
    print(f"Counterexample found:")
    print("x =", counterexample[x])
    print("y =", counterexample[y])
    print("a =", counterexample[a])
```

Invariant does not hold for the transition system.

Counterexample found:

$x = 0$

$y = 5002$

$a = 5002$

2. Prove the statement:

$$\text{inv2}(x,y,a,b) = \text{inv}(x,y) \wedge a = 5000 \wedge b = 10000$$

```
In [ ]: # vars for Ts0
x0, y0 = Ints('x0 y0')

# vars for Ts1
x1, y1, a1, b1 = Ints('x1 y1 a1 b1')

solver = Solver()

# Define the invariants for Ts0 and Ts1
I0 = And(
    Implies(y > 5000, x >= y),
    y >= 5000,
    x <= y
)
I1 = And( a1 == 5000, b1 == 10000, Implies(y1 >= a, x1 >= y1), x1 <= y1, y1

# Check if (I0 and (a = 5000) and (b = 10000)) is equivalent to I1
solver.add(Not(Implies(And(I0, a1 == 5000, b1 == 10000), I1)))
solver.add(Not(Implies(I1, And(I0, a1 == 5000, b1 == 10000))))

# Check for satisfiability (unsat implies equivalence)
if solver.check() == unsat:
    print("Invariant equivalency holds.")
else:
    print("Invariant equivalency does not hold.")
```

Invariant equivalency holds.