

Programming with Big Data in R

Package Examples and Demonstrations

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Warning: This document is written to explain the main functions of **pbdDEMO** (Schmidt *et al.*, 2012b), version 0.1-0. Every effort will be made to ensure future versions are consistent with these instructions, but features in later versions may not be explained in this document.

Information about the functionality of this package, and any changes in future versions can be found on website: “Programming with Big Data in R” at <http://r-pbd.org/>.

Part I

Preliminaries

1.1 What is pbd?

The “Programming with Big Data in R” project ([Ostrouchov *et al.*, 2012](#)) (pbd or pbdR for short) is a project that aims to elevate the statistical programming language R ([R Core Team, 2012](#)) to leadership-class computing platforms. Figure 1.1 shows the current state of pbdR packages and how they utilize proven, high-performance, scalable libraries and visualization tools. More explicitly, the current pbdR packages are:

- **pbdMPI** — an efficient interface to MPI with a focus on Single Program/Multiple Data (SPMD) parallel programming style.
- **pbdSLAP** — bundles scalable dense linear algebra libraries in double precision for **R**, based on ScaLAPACK version 2.0.2 ([Blackford *et al.*, 1997](#))..
- **pbdNCDF4** — Interface to Parallel Unidata NetCDF4 format data files ([NetCDF Group, 2008](#)).
- **pbdBASE** — base distributed classes and methods for the pbdR Project.
- **pbdDMAT** — distributed matrix computational methods, with a focus on linear algebra.
- **pbdDEMO** — set of package demonstrations and examples, and this unifying vignette.

In this vignette, we offer many examples using the above pbdR packages. Many of the examples are high-level applications and may be commonly found in basic Statistics. The purpose is to show how to reuse the pre-existing functions and utilities of pbdR to create minor extensions which can quickly solve problems in an efficient way. The reader is encouraged to reuse and repurpose these functions.

The **pbdDEMO** package consists of two main parts. The first is a collection of roughly 15 package demos. These offer example uses of the various pbdR packages. The second is this vignette, which attempts to offer detailed explanations for the demos, as well as sometimes providing some mathematical or statistical insight. A list of all of the package demos can be

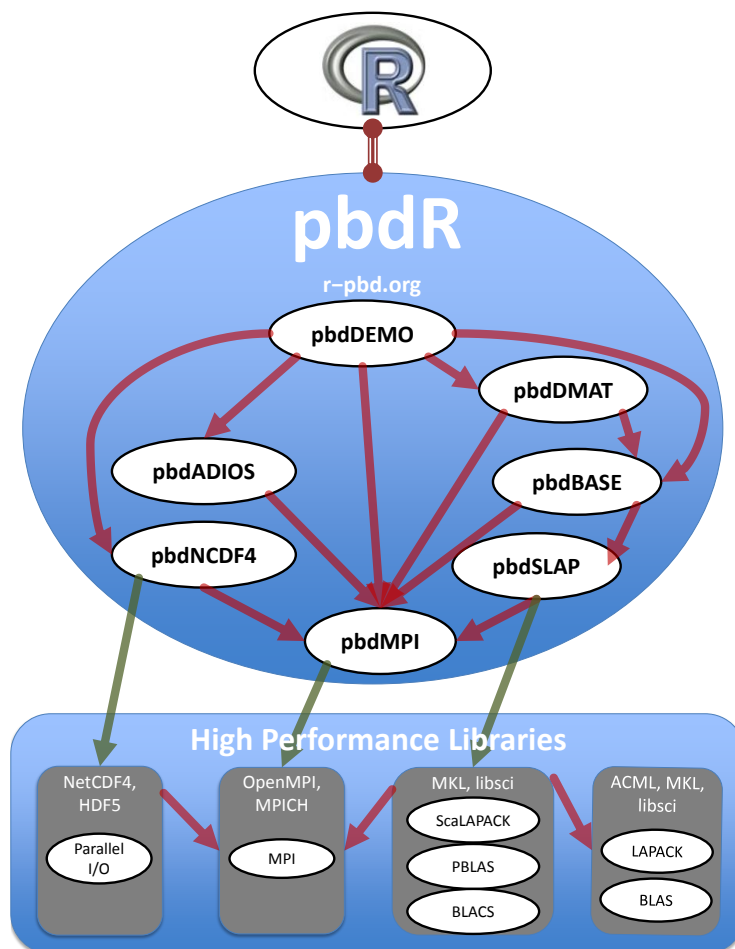


Figure 1.1: pbdR Packages and Their Relationships with Scalable Libraries

found in Section 1.4.

1.2 Why Parallelism? Why pbdR?

It is common, in a document such as this, to justify the need for parallelism. Generally this process goes:

Blah blah blah Moore's Law, blah blah Big Data, blah blah blah Concurrency.

How about this? Parallelism is cool. Any boring nerd can use one computer, but using 10,000 at once is another story. We don't call them *supercomputers* for nothing.

But unfortunately, lots of people who would otherwise be thrilled to do all kinds of cool stuff with massive behemoths of computation — computers with names like **KRAKEN** and **TITAN** — are burdened by an unfortunate reality: it's really, really hard. Enter pbdR. Through our project, we put a shiny new set of clothes on high-powered compiled code, making massive-scale

computation accessible to a wider audience of data scientists than ever before. Analytics in supercomputing shouldn't just be for the elites.

1.3 Installation

One can download **pbdDEMO** from CRAN at <http://cran.r-project.org>, and the installation can be done with the following commands

```
tar zxvf pbdDEMO_0.1-0.tar.gz
R CMD INSTALL pbdDEMO
```

Since **pbdDEMO** depends on other pbdR packages, please read the corresponding vignettes if installation of any of them is unsuccessful.

1.4 List of Demos

A full list of demos contained in the **pbdDEMO** package is provided below.

Shell Script

```
### (Use Rscript.exe for windows system)

# ----- #
# II Direct MPI Methods #
# ----- #

### Chapter 5
# Monte carlo simulation
mpiexec -np 4 Rscript -e "demo(monte_carlo, package='pbdDMAT', ask=F,
    echo=F)"
# Sample mean and variance
mpiexec -np 4 Rscript -e "demo(sample_stat, package='pbdDMAT', ask=F,
    echo=F)"
# Binning
mpiexec -np 4 Rscript -e "demo(binning, package='pbdDMAT', ask=F,
    echo=F)"
# Quantile
mpiexec -np 4 Rscript -e "demo(quantile, package='pbdDMAT', ask=F,
    echo=F)"
# OLS
mpiexec -np 4 Rscript -e "demo(ols, package='pbdDMAT', ask=F, echo=F)"

# ----- #
# III Reading and Managing Data #
# ----- #
```

```

### Chapter 6
# Random matrix generation
mpiexec -np 4 Rscript -e "demo(randmat_global, package='pbdDMAT',
    ask=F, echo=F)"
mpiexec -np 4 Rscript -e "demo(randmat_local, package='pbdDMAT', ask=F,
    echo=F)"

### Chapter 7
# Reading csv
mpiexec -np 4 Rscript -e "demo(read_csv, package='pbdDMAT', ask=F,
    echo=F)"
# Reading sql
mpiexec -np 4 Rscript -e "demo(read_sql, package='pbdDMAT', ask=F,
    echo=F)"
# Reading netcdf4
mpiexec -np 4 Rscript -e "demo(read_ncdf, package='pbdDMAT', ask=F,
    echo=F)"

### Chapter 8
# Load/unload balance
mpiexec -np 4 Rscript -e "demo(balance, package='pbdDMAT', ask=F,
    echo=F)"
# SPMD to DMAT
mpiexec -np 4 Rscript -e "demo(spmd_dmat, package='pbdDMAT', ask=F,
    echo=F)"
# Distributed matrix redistributions
mpiexec -np 4 Rscript -e "demo(reblock, package='pbdDMAT', ask=F,
    echo=F)"

                                # ----- #
                                # IV Distributed Matrix Methods #
                                # ----- #

### Chapter 9
# Verify solveing  $Ax=b$  at scale
mpiexec -np 4 Rscript -e "demo(verify, package='pbdDMAT', ask=F,
    echo=F)"
# PCA compression
mpiexec -np 4 Rscript -e "demo(pca, package='pbdDMAT', ask=F, echo=F)"
# OLS and predictions
mpiexec -np 4 Rscript -e "demo(ols_dmat, package='pbdDMAT', ask=F,
    echo=F)"

```

2.1 Notation

Note that we tend to use suffix `.spmd` for an object when we wish to indicate that the object is distributed. This is purely for pedagogical convenience, and has no semantic meaning. Since the code is written in SPMD style, you can think of such objects as referring to either a large, global object, or to a processor's local piece of the whole (depending on context). This is less confusing than it might first sound.

We will not use this suffix to denote a global object common to all processors. As a simple example, you could imagine having a large matrix with (global) dimensions $m \times n$ with each processor owning different collections of rows of the matrix. All processors might need to know the values for m and n ; however, m and n do not depend on the local process, and so these do not receive the `.spmd` suffix. In many cases, it may be a good idea to invent an S4 class object and a corresponding set of methods. Doing so can greatly improve the usability and readability of your code, but is never strictly necessary. However, these constructions are the foundation of the **pbdBASE** (Schmidt *et al.*, 2012a) and **pbdDMAT** (Schmidt *et al.*, 2012c) packages.

On that note, depending on your requirements in distributed computing with R, it may be beneficial to you to use higher pbdR toolchain. If you need to perform dense matrix operations, or statistical analyses which depend heavily on matrix algebra (linear modeling, principal components analysis, ...), then the **pbdBASE** and **pbdDMAT** packages are a natural choice. The major hurdle to using these tools is getting the data into the appropriate **ddmatrix** format, although we provide many tools to ease the pains of doing so. Learning how to use these packages can greatly improve code performance, and take your statistical modeling in R to previously unimaginable scales.

Again for the sake of understanding, we will at times append the suffix `.dmat` to objects of class **ddmatrix**. As with `.spmd`, this carries no semantic meaning, and is merely used to improve the readability of example code (especially when managing both `.spmd` and **ddmatrix** objects).

2.2 Timing Jobs

Measuring run time is a fundamental performance measure in computing. However, in parallel computing, not all “parallel components” (e.g. threads, or MPI processes) will take the same amount of time to complete a task, even when all tasks are given completely identical jobs. So measuring “total run time” begs the question, run time of what?

To help, we offer a timing function `demo.timer()` which can wrap segments of code much in the same way that `system.time()` does. However, the three numbers reported by `demo.timer()` are: (1) the minimum elapsed time measured across all processes, (2) the average elapsed time measured across all processes, and (3) the maximum elapsed time across all processes. The code for this function is listed below:

Timer Function

```
demo.timer <- function(timed)
{
  ltime <- system.time(timed)[3]
  barrier()

  mintime <- allreduce(ltime, op='min')
  maxtime <- allreduce(ltime, op='max')

  meantime <- allreduce(ltime, op='sum') / comm.size()

  return( c(min=mintime, mean=meantime, max=maxtime) )
}
```

SPMD Programming with R

Throughout this document, we will be using the “Single Program/Multiple Data”, or SPMD, paradigm for distributed computing. Writing programs in the SPMD style is a very natural way of doing computations in parallel, but can be somewhat difficult to properly describe. As the name implies, only one program is written, but the different processors involved in the computation all execute the code independently on different portions of the data. The process is arguably the most natural extension of running serial codes in batch.

Unfortunately, executing jobs in batch is a somewhat unknown way of doing business to the typical R user. While details and examples about this process will be provided in the chapters to follow, the reader is encouraged to see the **pbdMPI** package’s vignette ([Chen *et al.*, 2012b](#)) first. Ideally, readers should run the demos of the **pbdMPI** package, going through the code step by step.

Part II

Direct MPI Methods

Cicero once said that “If you have a garden and a library, you have everything you need.” So in that spirit, for the next two chapters we will use the MPI library to get our hands dirty and root around in the dirt of low-level MPI programming.

4.1 MPI Basics

In a sense, Cicero (in the above tortured metaphor) was quite right. MPI is all that we *need* in the same way that I might only *need* bread and cheese, but really what I *want* is a pizza. MPI is somewhat low-level and can be quite fiddley, but mastering it adds a very powerful tool to the repertoire of the parallel R programmer, and is essential for anyone who wants to do large scale development of parallel codes.

“MPI” stands for “Message Passing Interface”. How it really works goes *well* beyond the scope of this document. But at a basic level, the idea is that the user is running a code on different compute nodes that (usually) can not directly modify objects in each others’ memory. In order to have all of the nodes working together on a common problem, data and computation directives are passed around over the network (often over a specialized link called infiniband).

The general process for directly — or indirectly — utilizing MPI goes something like this:

1. Initialize communiator(s).
2. Have each process read in its portion of the data.
3. Perform computations.
4. Communicate results.
5. Shut down the communicator(s).

Some of the above steps may be swept away under a layer of abstraction for the user, but the need may arise where directly interfacing with MPI is not only beneficial, but necessary.

More details and numerous examples using MPI with R are available in the sections to follow, as well as in the **pbdMPI** vignette.

4.2 pbdMPI vs Rmpi

There is another package on the CRAN which the R programmer may use to interface with MPI, namely **Rmpi** (Yu, 2012). There are several issues one must consider when choosing which package to use if one were to only use one of them.

1. (+) **pbdMPI** is easier to install than **Rmpi**
2. (+) **pbdMPI** is easier to use than **Rmpi**
3. (+) **pbdMPI** can often outperform **Rmpi**
4. (+) **pbdMPI** integrates with the rest of pbd
5. (−) **Rmpi** can be used with **foreach** (Analytics, 2012) via **doMPI** (Weston, 2010)
6. (−) **Rmpi** can be used in the master/worker paradigm

We do not believe that the above can be reduced to a zero-sum game with unambiguous winner and loser. Ultimately the needs of the user (or developer) are paramount. We believe that pbd makes a very good case for itself, but it can not satisfy everyone. However, for the remainder of this section, we will present the case for several of the, as yet, unsubstantiated pluses above.

In the case of ease of use, **Rmpi** uses bindings very close to the level as they are used in C’s MPI API. Specifically, whenever performing, for example, a reduction such as allreduce, you must specify the type of your data. For example, using **Rmpi**’s API

```
mpi.allreduce(x, type = 1)
```

would perform the sum allreduce if the object **x** consists of integer data, while

```
mpi.allreduce(x, type = 2)
```

would be used if **x** consists of doubles. However, with **pbdMPI**

```
allreduce(x)
```

is used for both by making use of R’s S4 system of object oriented programming. This is not mere code golfing¹ that we are engaging in. The concept of what “type” your data is in R is fairly foreign to most R users, and misusing the **type** argument in **Rmpi** is a very easy way to

¹See https://en.wikipedia.org/wiki/Code_golf

crash your program. Instead, we take the approach of adding a small abstraction layer on top (which we intend to show does not negatively impact performance in general) so that the user need not worry about such details.

In terms of performance, **pbdMPI** can greatly outperform **Rmpi**. We present here the results of a benchmark we performed comparing the allgather operation between the two packages ([Schmidt et al., 2012e](#)). The benchmark consisted of calling the respective allgather function from each package on a randomly generated $10,000 \times 10,000$ distributed matrix with entries coming from the standard normal distribution, using different numbers of processors. Table 4.1 shows the

Table 4.1: Runtimes (seconds) for **Rmpi** and **pbdMPI**.

Cores	Rmpi	pbdMPI	Speedup
32	24.6	6.7	3.67
64	25.2	7.1	3.55
128	22.3	7.2	3.10
256	22.4	7.1	3.15

results for this test, and in each case, **pbdMPI** is the clear victor.

Whichever package you choose, whichever your favorite, for the remainder of this document we will be using (either implicitly or explicitly) **pbdMPI**.

Basic Statistics Examples

This section introduces five simple examples and explains a little about computing with distributed data directly over MPI. These implemented examples/functions are partly selected from the Cookbook of HPSC website ([Chen and Ostrouchov, 2011](http://thirteen-01.stat.iastate.edu/snoweye/hpsc/?item=cookbook)) at <http://thirteen-01.stat.iastate.edu/snoweye/hpsc/?item=cookbook>. Please see more details there.

5.1 Monte Carlo Simulation

Example: Compute a numerical approximation for π .

The demo command is

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpiexec -np 4 Rscript -e "demo(monte_carlo,'pbdDEMO',ask=F,echo=F)"
```

This is a simple Monte Carlo simulation example for numerically estimating π . Suppose we sample N uniform observations (x_i, y_i) inside (or perhaps on the border of) the unit square $[0, 1] \times [0, 1]$, where $i = 1, 2, \dots, N$. Then

$$\pi \approx 4 \frac{L}{N} \quad (5.1)$$

where $0 \leq L \leq N$ is the number of observations sampled satisfying

$$x_i^2 + y_i^2 \leq 1 \quad (5.2)$$

The intuitive explanation for this is strategy which is sometimes given belies a misunderstanding of infinite cardinalities, and infinite processes in general. We are not *directly* approximating an area through this sampling scheme, because to do so with points would be madness requiring a transfinite process. Indeed, let S_N be the collection of elements satisfying (5.2). Then note that for each $N \in \mathbb{N}$ that the area of S_N is precisely 0. Whence,

$$\lim_{N \rightarrow \infty} \text{Area}(S_N) = 0$$

This bears repeating. Finite sampling of an uncountable space requires uncountably many such sampling operations to “fill” the infinite space. For a proper treatment of set theoretic constructions, including infinite cardinals, see (Kunen, 1980).

One could argue that we are evaluating a ratio of integrals with each using the counting measure, which satisfies technical correctness but is far from clear. Now yes, indeed, certain facts of area are involved here, but some care should be taken in the discussion as to what exactly justifies our claim in (5.1).

In reality, we are evaluating the probability that someone throwing a 0-dimensional “dart” at the unit square will have that “dart” also land below the arc of the unit circle contained within the unit square. Formally, let U_1 and U_2 be random uniform variables, each from the closed unit interval $[0, 1]$. Define the random variable

$$X := \begin{cases} 1, & U_1^2 + U_2^2 \leq 1 \\ 0, & \text{otherwise} \end{cases}$$

Let $V_i = U_i^2$ for $i = 1, 2$. Then the expected value

$$\begin{aligned} E[X] &= P(V_1 + V_2 \leq 1) \\ &= \int_0^1 \int_0^{1-V_1} p(V_1, V_2) dV_2 dV_1 \\ &= \int_0^1 \int_0^{1-V_1} \left(\frac{1}{2\sqrt{V_1}} \right) \left(\frac{1}{2\sqrt{V_2}} \right) dV_2 dV_1 \\ &= \frac{1}{2} \int_0^1 \left(\frac{1-V_1}{V_1} \right)^{1/2} dV_1 \\ &= \frac{1}{2} \left[V_1 \left(\frac{1-V_1}{V_1} \right)^{1/2} - \frac{1}{2} \arctan \left(\frac{\left(\frac{1-V_1}{V_1} \right)^{1/2} (2V_1 - 1)}{2(V_1 - 1)} \right) \right]_{V_1 \rightarrow 0}^{V_1 \rightarrow 1} \\ &= \frac{1}{2} \left[\frac{\pi}{4} + \frac{\pi}{4} \right] \end{aligned}$$

and by sampling observations X_i for $i = 1, \dots, N$, by the Strong Law of Large Numbers

$$\bar{X}_N \xrightarrow{a.s.} \frac{\pi}{4} \quad \text{as } N \rightarrow \infty$$

In other words,

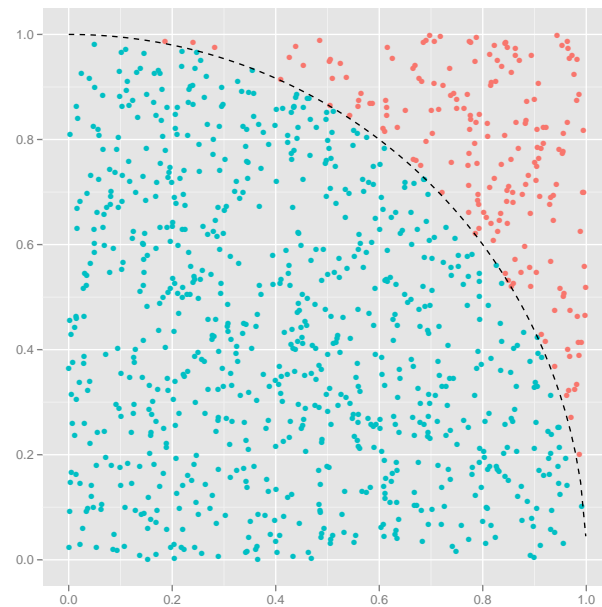
$$P \left(\lim_{N \rightarrow \infty} \bar{X}_N = \frac{\pi}{4} \right) = 1$$

Whence,

$$\frac{L}{N} \xrightarrow{a.s.} \frac{\pi}{4} \quad \text{as } N \rightarrow \infty$$

But because no one is going to read that, and if they do they’ll just call me a grumpy old man, the misleading picture you desire can be found in Figure 5.1. And to everyone who found this looking for a homework solution, you’re welcome.

The key step of the demo code is in the following block:

Figure 5.1: Approximating π by Monte Carlo methods

R Code

```

N.spmd <- 1000
X.spmd <- matrix(runif(N.spmd * 2), ncol = 2)
r.spmd <- sum(rowSums(X.spmd^2) <= 1)
ret <- allreduce(c(N.spmd, r.spmd), op = "sum")
PI <- 4 * ret[2] / ret[1]
comm.print(PI)

```

In line 1, we specify sample size in `N.spmd` for each processor, and $N = D \times \text{N.spmd}$ if D processors are executed. In line 2, we generate samples in `X.spmd` for every processor. In line 3, we compute how many of radii are less than or equal to 1 for each processors. In line 4, we call `allreduce()` to obtain total numbers across all processors. In line 5, we use the Equation (5.1). Since SPMD, `ret` is common on all processors, and so is `PI`.

5.2 Sample Mean and Sample Variance

Example: Compute sample mean/variance for distributed data.

The demo command is

```

### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpirexec -np 4 Rscript -e "demo(sample_stat,'pbdDEMO',ask=F,echo=F)"

```

Suppose $\mathbf{x} = \{x_1, x_2, \dots, x_N\}$ are observed samples, and N is potentially very large. We can distribute \mathbf{x} in 4 processors, and each processor receives a proportional amount of data. One simple way to compute sample mean \bar{x} and sample variance s_x is based on the formulas:

$$\begin{aligned}\bar{x} &= \frac{1}{N} \sum_{n=1}^N x_n \\ &= \sum_{n=1}^N \frac{x_n}{N}\end{aligned}\tag{5.3}$$

and

$$\begin{aligned}s_x &= \frac{1}{N-1} \sum_{n=1}^N (x_n - \bar{x})^2 \\ &= \frac{1}{N-1} \sum_{n=1}^N x_n^2 - \frac{2\bar{x}}{N-1} \sum_{n=1}^N x_n + \frac{1}{N-1} \sum_{n=1}^N \bar{x}^2 \\ &= \sum_{n=1}^N \left(\frac{x_n^2}{N-1} \right) - \frac{N\bar{x}^2}{N-1}\end{aligned}\tag{5.4}$$

where expressions (5.3) and (5.4) are one-pass algorithms, which are potentially faster than the first expressions, especially for large N . Here, only the first and second moments are implemented, while the extension of one-pass algorithms to higher order moments is also possible.

The demo generates random data on 4 processors, then utilizes the `mpi.stat()` function:

R Code

```
mpi.stat <- function(x.spmd){
  ### For mean(x).
  N <- allreduce(length(x.spmd), op = "sum")
  bar.x.spmd <- sum(x.spmd / N)
  bar.x <- allreduce(bar.x.spmd, op = "sum")

  ### For var(x).
  s.x.spmd <- sum(x.spmd^2 / (N - 1))
  s.x <- allreduce(s.x.spmd, op = "sum") - bar.x^2 * (N / (N -
    1))

  list(mean = bar.x, s = s.x)
} # End of mpi.stat().
```

where `allreduce()` in `pbdMPI` (Chen *et al.*, 2012a) can be utilized in this examples to aggregate local information across all processors.

5.3 Binning

Example: Find binning counts for distributed data.

The demo command is

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpiexec -np 4 Rscript -e "demo(binning, 'pbdDEMO', ask=F, echo=F) "
```

Binning is a classical problem in statistics which helps to quickly summarize the data structure by setting some “breaks” between the minimum and maximum values. This is a particularly useful tool for constructing histograms, as well as categorical data analysis.

The demo generates random data on 4 processors, then utilizes the `mpi.bin()` function:

R Code

```
mpi.bin <- function(x.spmd, breaks = pi / 3 * (-3:3)){
  bin.spmd <- table(cut(x.spmd, breaks = breaks))
  bin <- as.array(allreduce(bin.spmd, op = "sum"))
  dimnames(bin) <- dimnames(bin.spmd)
  class(bin) <- class(bin.spmd)
  bin
} # End of mpi.bin().
```

This simple implementation utilizes R’s own `table()` function to obtain local counts, then calls `allreduce()` to obtain global counts.

5.4 Quantile

Example: Compute sample quantile order statistics for distributed data.

The demo command is

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpiexec -np 4 Rscript -e "demo(quantile, 'pbdDEMO', ask=F, echo=F) "
```

Another fundamental tool in the statistician’s toolbox is finding quantiles. Quantiles are points taken from the cumulative distribution function which are taken in evenly-spaced periods. The most common usage is the “2-quantile”, or the median, though others are of course many others which are useful in summarizing distributions.

This example can be extended to construct Q-Q plots, compute cumulative density function estimates and nonparametric statistics, as well as solve maximum likelihood estimators.

This is perhaps an inefficient implementation to approximate a quantile and is not equivalent to

the original `quantile()` function in R. But in some sense, it should work well at a large scale. The demo generates random data on 4 processors, then utilizes the `mpi.quantile()`:

R Code

```
mpi.quantile <- function(x.spmd, prob = 0.5){
  if(sum(prob < 0 | prob > 1) > 0){
    stop("prob should be in (0, 1)")
  }

  N <- allreduce(length(x.spmd), op = "sum")
  x.max <- allreduce(max(x.spmd), op = "max")
  x.min <- allreduce(min(x.spmd), op = "min")

  f.quantile <- function(x, prob = 0.5){
    allreduce(sum(x.spmd <= x), op = "sum") / N - prob
  }

  uniroot(f.quantile, c(x.min, x.max), prob = prob[1])$root
} # End of mpi.quantile().
```

Here, a numerical function is solved by using `uniroot()` to find out the appropriate value where the cumulative probability is less than or equal to the specified quantile. This simple example shows that with just a little effort, direct MPI methods are greatly applicable on large scale data analysis and likelihood computing.

Note that in the way that the `uniroot()` call is used above, we are legitimately operating in parallel and on distributed data. Other optimization functions such as `optim()` and `nlm()` can be utilized in the same way.

5.5 Ordinary Least Squares

Example: Compute ordinary least square solutions for SPMD distributed data.

The demo command is

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpirexec -np 4 Rscript -e "demo(ols,'pbdDEMO',ask=F,echo=F)"
```

Ordinary least squares (OLS) is perhaps *the* fundamental tool of the statistician. The goal is to find a solution β such that

$$\|X\beta - y\|_2^2 \quad (5.5)$$

which is minimized. In statistics, we tend to prefer to think of the problem as being of the form

$$y = X\beta + \epsilon \quad (5.6)$$

where \mathbf{y} is $N \times 1$ observed vector, \mathbf{X} is $N \times p$ designed matrix which is full rank and $N \gg p$, β is the interested parameters and unknown to be estimated, and ϵ is errors and to be minimized in norm.

Note that above, we do indeed mean (in fact, stress) a solution to the linear least squares problem. The full story is somewhat complicated. The short explanation is that for many applications a statistician will face, expression (5.5) will actually have a unique solution. But this is not always the case. Indeed, it may occur that there is an infinite family of solutions. So typically we go further and demand that a solution β be such that $\|\beta\|_2$ is at least as small as the corresponding norm of any other solution (although even this does not guarantee uniqueness).

A properly thorough treatment of the problems involved here go beyond the scope of this document, and require the reader have in-depth familiarity with linear algebra. For our purposes, the concise explanation above will suffice.

The classical Maximum Likelihood solution is given by:

$$\hat{\beta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} \quad (5.7)$$

This example can be also generalized to weighted least square (WLS), and linear mixed effect models (LME).

The implementation is straight forward as

R Code

```
mpi.ols <- function(y.spmd, X.spmd){
  if(length(y.spmd) != nrow(X.spmd)){
    stop("length(y.spmd) != nrow(X.spmd)")
  }

  t.X.spmd <- t(X.spmd)
  A <- allreduce(t.X.spmd %*% X.spmd, op = "sum")
  B <- allreduce(t.X.spmd %*% y.spmd, op = "sum")

  solve(matrix(A, ncol = ncol(X.spmd))) %*% B
} # End of mpi.ols().
```

While this is a fine demonstration of the power of “getting your hands dirty”, this approach is only efficient for small N and small p . Worse, directly computing the product

$$\mathbf{X}^T \mathbf{X}$$

is often numerically non-stable. Instead, it is generally better (although much slower) to take an orthogonal factorization of the data matrix. Typically, the QR-decomposition is used to this end. Here $\mathbf{X} = \mathbf{Q}\mathbf{R}$, where \mathbf{Q} is orthogonal and \mathbf{R} is upper trapezoidal. This is beneficial,

because orthogonal matrices are norm-preserving, and whence

$$\begin{aligned} \|\mathbf{X}\boldsymbol{\beta} - \mathbf{y}\|_2 &= \|\mathbf{QR}\boldsymbol{\beta} - \mathbf{y}\|_2 \\ &= \left\| \mathbf{Q}^T \mathbf{QR}\boldsymbol{\beta} - \mathbf{Q}^T \mathbf{y} \right\|_2 \\ &= \left\| \mathbf{R}\boldsymbol{\beta} - \mathbf{Q}^T \mathbf{y} \right\|_2 \end{aligned}$$

The (arguably) much more well-known Singular Value Decomposition can also be used to develop yet another algebraically identical solution which is quite elegant. Here, if we take $\mathbf{X} = \mathbf{U}\Sigma\mathbf{V}^T$, then it can be shown that “the” desired solution is given by

$$\boldsymbol{\beta} = \mathbf{V}\Sigma^+ \mathbf{U}^T \mathbf{y}$$

where Σ^+ is the Moore-Penrose pseudoinverse of Σ . However, this approach is handily the most computationally intensive.

The method utilizing QR to find a minimum norm solution has been implemented in **pbdDMAT** for objects of class **ddmatrix**. For larger problems, and especially those where numerical accuracy is important, it may be more convenient to simply convert `y.spmd` and `X.spmd` into block-cyclic format as in the Part [IV](#) and to utilize **pbdBASE** and **pbdDMAT** for all matrix computation.

Part III

Reading and Managing Data

Random Distributed Matrices

The **pbdBASE** and **pbdDMAT** packages offer a distributed matrix class, `ddmatrix`, as well as a collection of high-level methods for performing common matrix operations. For example, if you want to compute the mean of an R matrix `x`, you would call

```
mean(x)
```

That's exactly the same command you would issue if `x` is no longer an ordinary R matrix, but a distributed matrix. These methods range from simple, embarrassingly parallel operations like sums and means, to tightly coupled linear algebra operations like matrix-matrix multiply and singular value decomposition.

Unfortunately, these higher methods come with a different cost: getting the data into the right format, namely the distributed matrix class. This can be especially frustrating because we assume that the any object of class `ddmatrix` is *block cyclically distributed*. This concept is discussed at length in the **pbdBASE** vignette (Schmidt *et al.*, 2012d), and we do not intend to discuss the concept of a block cyclic data distribution at length herein. However, we will demonstrate several examples of getting data into and out of the distributed block cyclic matrix format.

However, once the hurdle of getting the data into the “right format” is out of the way, these methods offer very simple syntax (designed to mimic R as closely as possible) with the ability to scale computations on very large distributed machines. So the process of getting the data into the correct format must be addressed. We begin dealing with this issue in the simplest way possible, namely by using randomly generated data.

6.1 Fixed Global Dimension

Example: randomly generate distributed matrices with random normal data of specified global dimension.

The demo command is

Shell Command

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpiexec -np 4 Rscript -e "demo(randmat_global,'pbdDEMO',ask=F,echo=F)"
```

This demo shows 3 separate ways that one can generate a random normal matrix with specified global dimension. The first two generate the matrix in full on at least one processor and distributes the data, while the last method generates locally only what is needed. As such, the first two can be considered demonstrations with what to do when you have data read in on one processor and need to distribute it out to the remaining processors, but for the purposes of using a randomly generated distributed matrix, they are not particularly efficient strategies.

The basic idea is as follows. If I have a matrix `x` stored on processor 0 and `NULL` on the others, then I can distribute it out as an object of class `ddmatrix` via the command `as.ddmatrix()`. For example

```
if (comm.rank()==0){
  x <- matrix(rnorm(100), nrow=10, ncol=10)
} else {
  x <- NULL
}

dx <- as.ddmatrix(x)
```

will distribute the required data to the remaining processors. We note for clarity that this is not equivalent to sending the full matrix to all processors and then throwing away all but what is needed. Only the required data is communicated to the processors.

That said, having all of the data on all processors can be convenient while testing, if only for being more minimalistic in the amount of code/thinking required. To do this, one need only do the following:

```
x <- matrix(rnorm(100), nrow=10, ncol=10)

dx <- as.ddmatrix(x)
```

Now, this assumes you are using the same seed on each processor. This can be managed using the **pbdMPI** function `comm.set.seed()`, as in the demo script. For more information, see that package's documentation.

Finally, you can generate locally only what you need. The demo script does this via the **pbd-DEMO** package's `Hnorm()` or "huge normal" function. There are two others provided, namely `Hconst()` and `Hunif()`. The naming convention was chosen because the latter most function name makes me laugh.

Internally, these “huge” functions rely on a much stronger working knowledge of the underlying data structure than most will be comfortable with. However, for the sake of completeness, we will briefly examine `Hnorm()`.

`Hnorm()`

```
Hnorm <- function(dim, bldim, mean=0, sd=1, ICTXT=0)
{
  if (length(bldim)==1L)
    bldim <- rep(bldim, 2L)

  ldim <- base.numroc(dim=dim, bldim=bldim, ICTXT=ICTXT,
    fixme=FALSE)

  if (any(ldim < 1L)){
    xmat <- matrix(0)
    ldim <- c(1, 1)
  }
  else
    xmat <- matrix(rnorm(prod(ldim), mean=mean, sd=sd),
      nrow=ldim[1L], ncol=ldim[2L])

  dx <- new("ddmatrix", Data=xmat,
    dim=dim, ldim=ldim, bldim=bldim, CTXT=ICTXT)

  return(dx)
}
```

The concise explanation is that the `base.numroc()` utility determines the size of the local storage. This is all very well documented in the **pbdBASE** documentation, but since no one even pretends to read that stuff, NUMROC is a ScaLAPACK tool, which means “NUMber of Rows Or Columns.” The function `base.numroc()` is an implementation in R which calculates the number of rows *and* columns at the same time (so it is a bit of a misnomer, but preserved for historical reasons).

More precisely, it calculates the local storage requirements given a global dimension `dim`, a blocking factor `bldim`, and a BLACS context number `ICTXT`. The extra argument `fixme` determines whether or not the lowest value returned should be 1. If `fixme==FALSE` and any of the returned local dimensions are less than 1, then that processor does not actually own any of the global matrix — it has no local storage. But something must be stored, and so we default this to `matrix(0)`, the 1×1 matrix with single entry 0.

6.2 Fixed Local Dimension

Example: randomly generate distributed matrices with random normal data of specified local dimension.

The demo command is

Shell Command

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpiexec -np 4 Rscript -e "demo(randmat_local,'pbdDEMO',ask=F,echo=F)"
```

This is similar to the above, but with a critical difference. Instead of specifying a fixed *global* dimension and then go determine what the local storage space is, instead we specify a fixed *local* dimension and then go figure out what the global dimension should be. This can be useful for testing for weak scaling of an algorithm, where different numbers of cores are compared but with similar ram usage.

To this end, the demo script utilizes the `Hnorm.local()` function, which has the user specify a local dimension size that all the processors should use, as well as a blocking factor and BLACS context value.

Hnorm.local()

```
Hnorm.local <- function(ldim, bldim, mean=0, sd=1, ICTXT=0)
{
  if (length(bldim)==1L)
    bldim <- rep(bldim, 2L)

  blacs_ <- base.blacs(ICTXT=ICTXT)
  nprows <- blacs_$NPROW
  npcols <- blacs_$NPCOL

  dim <- c(nprows*ldim[1L], npcols*ldim[2L])

  if (any( (dim %% bldim) != 0 )){
    comm.cat("WARNING : at least one margin of 'bldim' does not
             divide the global dimension.\n", quiet=T)

    bldim[1L] <- nbd(dim[1L], bldim[1L])
    bldim[2L] <- nbd(dim[2L], bldim[2L])
    comm.cat(paste("Using bldim of ", bldim[1L], "x", bldim[2L],
                  "\n\n", sep=""), quiet=T)
  }

  Data <- matrix(rnorm(prod(ldim), mean=mean, sd=sd),
                nrow=ldim[1L], ncol=ldim[2L])

  dx <- new("ddmatrix", Data=Data,
            dim=dim, ldim=ldim, bldim=bldim, CTXT=ICTXT)

  return(dx)
}
```

Now here things get somewhat tricky, because in order for this matrix to exist at all, each margin of the blocking factor must divide (as an integer) the corresponding margin of the global dimension. To better understand why this is so, the reader is suggested to read the **pbdBASE** vignette. But if you already understand or are merely willing to take it on faith, then you surely grant that this is a problem.

So here, we assume that the local dimension is chosen appropriately, but it is possible that a bad blocking factor is supplied by the user. Rather than halt with a stop error, we attempt to find the next best blocking factor possible. We do this with a simple “next best divisor” function:

nbd()

```
nbd <- function(n, d)
{
  if (n < d)
    stop("'n' may not be smaller than 'd'")

  ret <- .Fortran("NBD",
                  as.integer(n), as.integer(d),
                  PACKAGE="pbdDEMO")$D

  return( ret )
}
```

which is just a shallow wrapper on the Fortran code:

NBD

```
SUBROUTINE NBD(N, D)
  INTEGER N, D, I, TEST

  DO 10 I = D+1, N-1, 1
    TEST = MOD(N, I)
    IF (TEST.EQ.0) THEN
      D = I
      RETURN
    END IF
  10 CONTINUE

  D = N
  RETURN
END
```

Even those who don’t know Fortran should easily be able to see what is going on here. We are given integers N and D, and we loop over the integers inbetween these two until we find one which divides N.

So going back to the `Hnorm.local()` function, the second `if` block contains the readjusting (as necessary) of the blocking factors. Then the local data matrix is generated and wrapped up in

its class before being returned — everything else is just sugar.

Reading Data

As we mentioned at the beginning of the discussion on distributed matrix methods, most of the hard work in using these tools is getting the data into the right format. Once this hurdle has been overcome, the syntax will magically begin to look like native R syntax. Some insights into this difficulty can be seen in the previous section, but now we tackle the problem head on: how do you get real data into the distributed matrix format?

7.1 CSV Files

Example: Read data from a csv directly into a distributed matrix.

The demo command is

Shell Command

```
### At the shell prompt, run the demo with 4 processors by  
### (Use Rscript.exe for windows system)  
mpiexec -np 4 Rscript -e "demo(read_csv,'pbdDEMO',ask=F,echo=F)"
```

It is simple enough to read in a csv file serially and then distribute the data out to the other processors. This process is essentially identical to one of the random generation methods in Section 6.1. For the sake of completeness, we present a simple example here:

```
if (comm.rank()==0){ # only read on process 0  
  x <- read.csv("myfile.csv")  
} else {  
  x <- NULL  
}  
  
dx <- as.ddmatrix(x)
```

However, this is inefficient, especially if the user has access to a parallel file system. In this case, several processes should be used to read parts of the file, and then distribute that data out to the larger process grid. Although really, the user should not be using csv to store large amounts of data because it always requires a sort of inherent “serialness”. Regardless, a demonstration of how this is done is useful. We can do so via the **pbdDEMO** package’s function `read.csv.ddmatrix` on an included dataset:

Reading a CSV with Multiple Readers

```
dx <- read.csv.ddmatrix("../extra/data/x.csv",
                        sep=",", nrows=10, ncols=10,
                        header=TRUE, bldim=4,
                        num.rdrs=2, ICTXT=0)

print(dx)
```

The code powering the function itself is quite complicated, going well beyond the scope of this document. To understand it, the reader should see the advanced sections of the **pbdBASE** vignette.

7.2 SQL Databases

Example: Read data from a sql database directly into a distributed matrix.

The demo command is

Shell Command

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpiexec -np 4 Rscript -e "demo(read_sql,'pbdDEMO',ask=F,echo=F)"
```

Just as above, we can use a SQL database to read in our data, powered by the **sqldf** package (Grothendieck, 2012). Here it is assumed that the data is stored in the database in a structure that is much the same as a csv is stored on disk. Internally, the query performed is:

```
sqldf(paste("SELECT * FROM ", table, " WHERE rowid = 1"),
      dbname=dbname)
```

To use a more complicated query for a database with differing structure, it should be possible (no promises) to substitute this line of the `read.sql.ddmatrix()` function for the desired query. However, as before, much of the rest of the tasks performed by this function go beyond the scope of this document. However, they are described in the **pbdBASE** package vignette.

7.3 NetCDF4 Files

Example: Read data from a netcdf4 file, perform matrix computations, and write results to disk.

The demo command is

Shell Command

```
### At the shell prompt, run the demo with 4 processors by  
### (Use Rscript.exe for windows system)  
mpiexec -np 4 Rscript -e "demo(red_ncdf,'pbdDEMO',ask=F,echo=F)"
```

WORK IN PROGRESS

Redistribution Methods

One final challenge similar to, but distinct from reading in data is managing data which has already been read into the R processes. Throughout this chapter, we will be making reference to several particulars to the block-cyclic data type used for objects of class `ddmatrix`. As such, the reader is *strongly* encouraged to be familiar with the content of the **pbdBASE** vignette before proceeding.

8.1 Distributed Matrix Redistributions

Example: Convert between different distributed matrix distributions.

The demo command is

Shell Command

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpiexec -np 4 Rscript -e "demo(reblock,'pbdDEMO',ask=F,echo=F)"
```

The distributed matrix class `ddmatrix` has two components which can be specified, and modified, by the user to drastically affect the composition of the distributed matrix. In particular, these are the object's block-cyclic blocking factor `bldim`, and the BLACS communicator number `CTXT` which controls how the data is block-cycled across the 2-dimensional processor grid.

Thankfully, redistributing is a fairly simple process; though we would emphasize that **this is not free of cost**. Reshaping data, especially at scale, can be much more expensive in total than even computation time. That said, sometimes data must move. It is better to get the job done slowly than to “take your ball and go home” with no results. But we caution that if redistribution can be avoided, then it should, at all costs.

The demo relies on a utility from the **pbdBASE** package, namely `redistribute()`. As the name implies, this method is for “reshaping” a block-cyclically distributed matrix of one kind to another. Specifically, this takes an object of class `ddmatrix` as both an input and an output; i.e.,

and to emphasize the title of the chapter, this is not a method of *distribution* but *redistribution*.

For example, if I have a distributed matrix `dx` and I wish to reshape the distributed matrix so that it now has blocking dimension `newbldim` and is distributed across BLACS context `newCTXT`, then I need merely call:

```
dy <- redistribute(dx, bldim=newbldim, ICTXT=newCTXT)
```

8.2 Load Balance and Unload Balance

Example: Load balancing (and unbalancing) distributed data.

The demo command is

Shell Command

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpiexec -np 4 Rscript -e "demo(balance, 'pbdDEMO', ask=F, echo=F) "
```

Suppose we have an unbalanced, distributed input matrix `X.spmd`. We can call `balance.info()` on this object to store some information about how to balance the data load across all processors. This can be useful for tracking data movement, as well as for “unbalancing” later, if we so choose. Next, we call `load.balance()` to obtain a load-balanced object `new.X.spmd`. We can also now undo this entire process and get back to `X.spmd` by calling `unload.balance()` on `new.X.spmd`.

All together, the code looks something like:

R Code

```
bal.info <- balance.info(X.spmd)
new.X.spmd <- load.balance(X.spmd, bal.info)
org.X.spmd <- unload.balance(new.X.spmd, bal.info)
```

The details of this exchange are depicted in the example in Figure 8.2. Here, `X.spmd` is unbalanced, and `new.X.spmd` is a balanced version of `X.spmd`.

The function `balance.info()` is extremely useful, because it will return the information used to load balance the given data `X.spmd`. The return of `balance.info()` is a list consisting of two dataframes, `send` and `recv`, as well as two vectors, `N.allspmd` and `new.N.allspmd`.

Here, `send` records the original processor rank and the destination processor rank of the unbalanced data (that which is to be transmitted by that processor). The `load.balance()` function uses this table to move the data via `pbdMPI`'s `isend()` function. If any “destination rank” is not the “original rank”, then the corresponding data row will be moved to the appropriate processor. On the other hand, `recv` records the original processor rank and the destination rank of balanced data (that which is received by that processor).

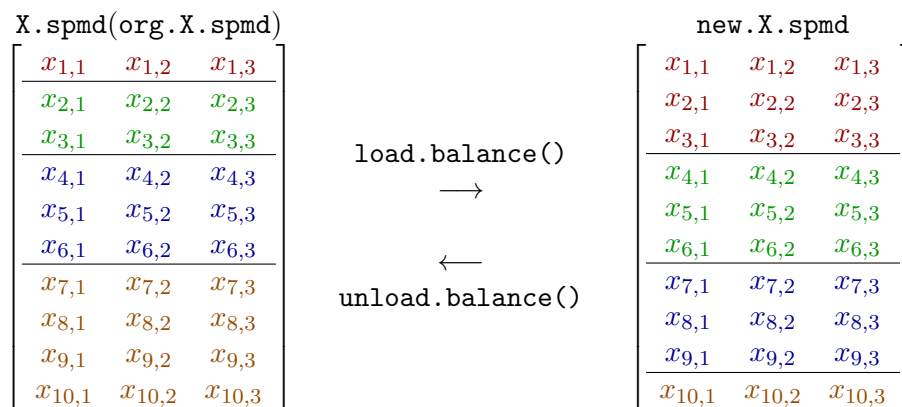


Figure 8.1: \mathbf{X} is distributed in `X.spmd(org.X.spmd)` and `new.X.spmd`. Both are distributed by row in 4 processors where colors represents processor 0, 1, 2, and 3.

The `N.allspmd` and `new.N.allspmd` objects both have length equal to the communicator containing all numbers of rows of `X.spmd` before and after the balancing. This is for double checking and avoiding a 0-row matrix issue.

For `unload.balance`, the process amounts to reversing `bal.info` and passing it to `load.balance`.

8.3 Convert Between SPMD and DMAT

Example: Convert between SPMD and DMAT formats.

The demo command is

Shell Command

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpirun -np 4 Rscript -e "demo(spmd_dmat, 'pbdDEMO', ask=F, echo=F) "
```

As usual serial R, it is intuitively to read data in parallel for each processor. We assume the input method is in SPMD to yield data in `X.spmd`, and convert it into `ddmatrix` format in `X.dmat`, then convert again to a R object in `X` which is common on all processors, as in the next. The Figure 8.3 illustrates an `X.spmd` and `X.dmat` conversion. For more details about the block-cyclic data format used for class `ddmatrix`, see the **pbdBASE** vignette.

R Code

```
X.dmat <- spmd2dmat(X.spmd)
X <- as.matrix(X.dmat)
new.X.spmd <- dmat2spmd(X.dmat)
```

Note that we also provide a reversed function `dmat2spmd` for `spmd2dmat`.

Here, the `spmd2dmat` function does the following:

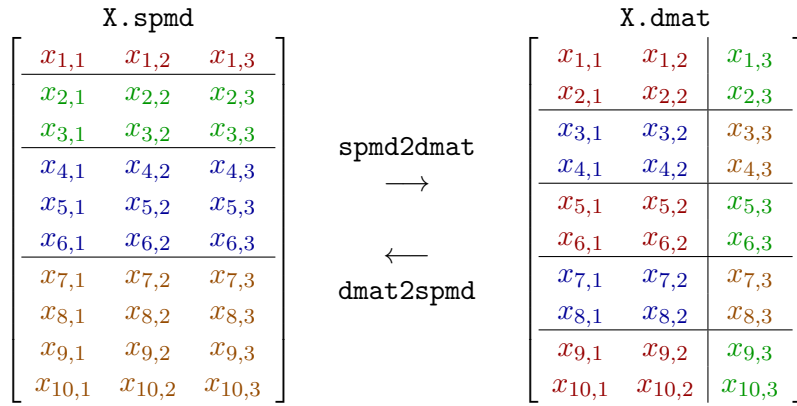


Figure 8.2: \mathbf{X} is distributed in $\mathbf{X.spmd}$ and $\mathbf{X.dmat}$. Both are distributed in 4 processors where colors represents processor 0, 1, 2, and 3. Note that $\mathbf{X.dmat}$ is in block-cyclic format of 2×2 grid with 2×2 block dimension.

1. Check numbers of columns of $\mathbf{X.spmd}$, all processors should be the same.
2. Row balance the SPMD matrix, since number of rows of $\mathbf{X.spmd}$ may vary in different processors.
3. Call `new` on the balanced matrix to yield a `ddmatrix` object, says $\mathbf{X.dmat}$, in block context 2 (`ICTXT = 2`).
4. Convert the $\mathbf{X.dmat}$ to other block contexts (default `ICTXT = 0`) via `base.reblock`.

Note that the first step is done by the `load.balance` function (Section 8.2) which is particular useful to balance SPMD matrix and yield performance even the matrix is not in block-cyclic format.

Part IV

Distributed Matrix Methods

Advanced Statistics Examples

The **pbdDMAT** package contains many useful methods for doing computations with distributed matrices. For comprehensive (but shallow) demonstrations of the distributed matrix methods available, see the **pbdDMAT** package's vignette and demos.

Here we showcase a few more advanced things that can be done by chaining together R and pbdR code seamlessly.

9.1 Verification of Distributed System Solving

Example: Solve a system of equations and verify that the solution is correct.

The demo command is

Shell Command

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpiexec -np 4 Rscript -e "demo(verify,'pbdDEMO',ask=F,echo=F)"
```

The **pbdDEMO** contains a set of verification routines, designed to test for validity of the numerical methods at any scale. Herein we will discuss the verification method for solving systems of linear equations, `verify.solve()`.

The process is simple. The goal is to solve the equation (in matrix notation)

$$Ax = b$$

for $n \times n$ matrix A and $n \times 1$ matrix b . However, here we start with A and x and use these to produce b . We then forget we ever knew what x was and solve the system. Finally, we remember what x really should be and compare that with our numerical solution.

More specifically, we take the matrix A to be random normal generated data and the true

solution x to be a constant vector. We then calculate

$$b := Ax$$

and finally the system is solve for a now (pretend) unknown x , so that we can compare the numerically determined x to the true constant x . All processes are timed, and both success/failure and timing results are printed for the user at the completion of the routine. This effectively amounts to calling:

Verifying Distributed System Solving

```
# generating data
timer({
  x <- Hnorm(dim=c(nrows, nrows))
  truesol <- Hconst(dim=c(nrows, 1))
})

timer({
  rhs <- x %*% truesol
})

# solving
timer({
  sol <- solve(x, rhs)
})

# verifying
timer({
  iseq <- all.equal(sol, truesol)
  iseq <- as.logical(allreduce(iseq, op='min'))
})
```

with some added window dressing.

9.2 Compression with Principal Components Analysis

Example: Take PCA and retain only a subset of the rotated data.

The demo command is

Shell Command

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpiexec -np 4 Rscript -e "demo(pca,'pbdDEMO',ask=F,echo=F)"
```

Suppose we wish to perform a principal components analysis and retain only some subset of the columns of the rotated data. One of the ways this is often done is by using the singular

values — the standard deviations of the components — as a measure of variation retained by a component. However, the first step is to get the principal components data. Luckily this is trivial. If our data is stored in the distributed matrix object `dx`, then all we need to is issue the command:

```
pca <- prcomp(x=dx, retx=TRUE, scale=TRUE)
```

Now that we have our PCA object (which has the same structure as that which comes from calling `prcomp()` on an ordinary R matrix), we need only decide how best to throw away what we do not want. We might want to retain at least as many columns as would be needed to retain 90% of the variation of the original data:

```
prop_var <- cumsum(pca$sdev)/sum(pca$sdev)
i <- min(which(prop_var > 0.9))

new_dx <- pca$x[, 1:i]
```

Or we might want one fewer column than the number that would give us 90%:

```
prop_var <- cumsum(pca$sdev)/sum(pca$sdev)
i <- max(min(which(prop_var > 0.9)) - 1, 1)

new_dx <- pca$x[, 1:i]
```

9.3 Predictions with Linear Regression

Example: Fit a linear regression model and use it to make a prediction on new data.

The demo command is

Shell Command

```
### At the shell prompt, run the demo with 4 processors by
### (Use Rscript.exe for windows system)
mpiexec -np 4 Rscript -e "demo(ols_dmat,'pbdDEMO',ask=F,echo=F)"
```

Suppose we have some predictor variables stored in the distributed $n \times p$ matrix `dx` and a response variable stored in the $n \times 1$ distributed matrix `dy`, and we wish to use the ordinary least squares model from (5.6) to make a prediction about some new data, say `dy.new`. Then this really amounts to just a few simple commands, namely:

```
mdl <- lm.fit(dx, dy)

pred <- dx.new %*% mdl$coefficients

comm.print(submatrix(pred), quiet=T)
```

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