

Vehicle lateral activity

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graph TD; A[Vehicle lateral activity] --> B[Going straight]; A --> C[Changing lane]; A --> D[Turning]; A --> E[Swerving]; C --> C1[Left]; C --> C2[Right]; D --> D1[Left]; D --> D2[Right]; E --> E1[Left]; E --> E2[Right];
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Going straight

Changing lane

Turning

Swerving

Left

Right

Left

Right

Left

Right