



Summer 2020

MAT 216

Solutions

Problem Sheet - 2

1. (i) The domain and codomain of the given expression: \mathbb{R}^3 and \mathbb{R}^2 respectively, that is

$\mathbb{R}^3 \rightarrow \mathbb{R}^2$. The transformation is linear.

- (ii) The domain and codomain of the given expression: \mathbb{R}^2 and \mathbb{R}^3 respectively, that is

$\mathbb{R}^2 \rightarrow \mathbb{R}^3$. The transformation is nonlinear.

2. The standard matrix for T is

$$\begin{bmatrix} 3 & 5 & -1 \\ 4 & -1 & 1 \\ 3 & 2 & -1 \end{bmatrix}.$$

We know that $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is multiplying by A and it is important to state that A is the standard matrix for T , then the linear transformation $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ by $T_A : \mathbb{R}^n \rightarrow \mathbb{R}^m$,

thus $T_A(x) = Ax$, where the vector x in \mathbb{R}^n is expressed as a column matrix.

$$T_A(x) = \begin{bmatrix} 3 & 5 & -1 \\ 4 & -1 & 1 \\ 3 & 2 & -1 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \\ 4 \end{bmatrix} = \begin{bmatrix} 3 \\ -2 \\ -3 \end{bmatrix}$$

$$T(-1, 2, 4) = (3, -2, -3).$$

3. The standard basis vectors e_1, e_2 and e_3 are

$$e_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, e_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, e_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}.$$

$$(i) \quad T_A(e_1) = Ae_1 = \begin{bmatrix} -1 & 3 & 0 \\ 2 & 1 & 2 \\ 4 & 5 & -3 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 4 \end{bmatrix}, T_A(e_2) = Ae_2 = \begin{bmatrix} -1 & 3 & 0 \\ 2 & 1 & 2 \\ 4 & 5 & -3 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ 5 \end{bmatrix}$$

$$T_A(e_3) = Ae_3 = \begin{bmatrix} -1 & 3 & 0 \\ 2 & 1 & 2 \\ 4 & 5 & -3 \end{bmatrix} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ -3 \end{bmatrix}.$$

$$(ii) \quad T_A(e_1 + e_2 + e_3) = T_A(e_1) + T_A(e_2) + T_A(e_3) = \begin{bmatrix} 2 \\ 5 \\ 6 \end{bmatrix}.$$

$$(iii) \quad T_A(7e_3) = 7T_A(e_3) = \begin{bmatrix} 0 \\ 14 \\ -21 \end{bmatrix}.$$

4. Let $u_1 = \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix}$ & $u_2 = \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix}$

Then $u_1 + u_2 = \begin{pmatrix} x_1 + x_2 \\ y_1 + y_2 \\ z_1 + z_2 \end{pmatrix}$

$$T(u_1 + u_2) = \begin{pmatrix} x_1 + x_2 - y_1 - y_2 \\ x_1 + x_2 - z_1 - z_2 \end{pmatrix} = \begin{pmatrix} x_1 - y_1 \\ x_1 - z_1 \end{pmatrix} + \begin{pmatrix} x_2 - y_2 \\ x_2 - z_2 \end{pmatrix} = T(u_1) + T(u_2).$$

If c is a scalar then $cu_1 = c \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} = \begin{pmatrix} cx_1 \\ cy_1 \\ cz_1 \end{pmatrix}$

$$T(cu_1) = T\begin{pmatrix} cx_1 \\ cy_1 \\ cz_1 \end{pmatrix} = \begin{pmatrix} cx_1 - cy_1 \\ cx_1 - cz_1 \end{pmatrix} = c\begin{pmatrix} x_1 - y_1 \\ x_1 - z_1 \end{pmatrix} = cT(u_1).$$

Therefore, T is a linear transformation.

$$5. \text{ Let } u_1 = \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} \text{ \& } u_2 = \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix}$$

$$\text{Then } u_1 + u_2 = \begin{pmatrix} x_1 + x_2 \\ y_1 + y_2 \\ z_1 + z_2 \end{pmatrix}$$

$$T(u_1) = \begin{pmatrix} 3x_1 - 2y_1 + z_1 \\ x_1 - 3y_1 - 2z_1 \end{pmatrix}, \quad T(u_2) = \begin{pmatrix} 3x_2 - 2y_2 + z_2 \\ x_2 - 3y_2 - 2z_2 \end{pmatrix}$$

$$T(u_1 + u_2) = \begin{pmatrix} 3(x_1 + x_2) - 2(y_1 + y_2) + (z_1 + z_2) \\ (x_1 + x_2) - 3(y_1 + y_2) - 2(z_1 + z_2) \end{pmatrix} = \begin{pmatrix} 3x_1 - 2y_1 + z_1 \\ x_1 - 3y_1 - 2z_1 \end{pmatrix} + \begin{pmatrix} 3x_2 - 2y_2 + z_2 \\ x_2 - 3y_2 - 2z_2 \end{pmatrix} = T(u_1) + T(u_2)$$

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$$\text{If } c \text{ is a scalar then } cu_1 = c\begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} = \begin{pmatrix} cx_1 \\ cy_1 \\ cz_1 \end{pmatrix}$$

$$T(cu_1) = T\begin{pmatrix} cx_1 \\ cy_1 \\ cz_1 \end{pmatrix} = \begin{pmatrix} 3cx_1 - 2cy_1 + cz_1 \\ cx_1 - 3cy_1 - 2cz_1 \end{pmatrix} = c\begin{pmatrix} 3x_1 - 2y_1 + z_1 \\ x_1 - 3y_1 - 2z_1 \end{pmatrix} = cT(u_1)$$

Therefore, T is a linear transformation.

$$6. \text{ (i) Since } T = (0, 0, 0) = (1, 1) \neq (0, 0)$$

Hence T is not a linear transformation.

(ii) T is a linear transformation.

7. (i) The system of linear equations is:

$$3x + 0y - 2z = 5$$

$$7x + y + 4z = -3$$

$$0x - 2y + z = 7$$

(ii) The system of linear equations is:

$$x = 7$$

$$y = -2$$

$$z = 3$$

$$w = 4$$

8. (a) Since the general solution: $x = 5 + 2t$, $y = t$.

So, the linear equation is: $x - 2y = 5$.

(b) Since $x - 2y = 5$ Let $x = t$, $2y = x - 5$, so, $y = \frac{1}{2}t - \frac{5}{2}$.

9. Given that

$$x - y = 3$$

$$2x - 2y = k$$

$$\text{So, } 0 = 6 - k, \therefore 6 - k = 0$$

If $k \neq 6$, the system has no solutions.

If $k = 6$, the system has many solutions.

No value of k yields one solution.