

COMP2038 Group Report

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- 1. Questions on Big-O Analysis. (25 marks)
 - (a) Consider a polynomial function of order k given by $f(n) = a_k n^k + a_{k-1} n^{k-1} + \cdots + a_0$. Formally demonstrate that $f(n) \in O(n^k)$. Full marks for using basic definitions and concepts.

[12 marks]

Big-O Rules: Drop smaller terms

If f(n) = (1 + h(n)) with $h(n) \rightarrow 0$ as $n \rightarrow \infty$. Then, f(n) is O(1). This is because the O(h(n)) is going to be insignificant as n grows bigger.

Big-O Multiplication Rules

Suppose two equations $f_1(n)$ is $O(g_1(n))$ and $f_2(n)$ is $O(g_2(n))$. From the definition, there exists positive constants c_1 , c_2 , c_1 and c_2 such that c_1 such that c_2 such that c_1 such that c_2 such that c_1 such that c_2 such that c_2 such that c_1 such that c_2 such that c_1 such that c_2 such that c_2 such that c_1 such that c_2 such that c_1 such that c_2 such that c_2 such that c_1 such that c_2 such that

Big-O Conventions

Use the smallest (slowest growing) 'reasonable' possible class of functions. As an example, 2n is O(n) instead of $O(n^2)$

Use the simplest expression of the class. As an example, 3n + 5 is O(n) instead of O(3n)

$$f(n) = a_k n^k + a_{k-1} n^{k-1} + \dots + a_0$$

$$f(n) = n^k (a_k + a_{k-1}/n + \dots + a_0/n^k)$$
As $n \to \infty$, $(a_k + a_{k-1}/n + \dots + a_0/n^k) \to (a_k + 0 + \dots + 0) \to a_k$ and $f(n) \to n^k a_k$ by Drop smaller terms.

$$O(n^k) \text{ is trivially } O(n^k) \text{ and } O(a_k) \text{ is } O(1).$$

With Big-O Multiplication Rules, $O(f(n)) = O(n^k a_k) = O(n^k) O(a_k) = O(n^k)O(1) = O(n^k + 1) = O(n^k)$

So, $f(n)$ is $O(n^k)$ or $f(n) \in O(n^k)$.

(b) Refer to the definition of Big-O in the lecture materials. In particular, the condition for which one can state that f(n) is O(g(n)) is defined. Briefly explain why the notation $f(n) \in O(g(n))$ is preferred compared to f(n) = O(g(n)). Full marks for using basic definitions and concepts and mathematical formulation.

[13 marks]

f(n) is O(g(n)) if and only if there exists positive constants c and n_0 such that $f(n) \le cg(n)$ for all $n \ge n_0$. In mathematical notation, $\exists c > 0$, n_0 such that $\forall n \ge n_0$, $f(n) \le cg(n)$.

f: N⁺ -> R⁺ and g: N⁺ -> R⁺ where N⁺ = {1,2,3, ...} and R⁺ = { $x \in R \mid x \ge 0$ } assuming that $f(n) \ge 0$, $\forall n \ge 1$. For convenience, the function is sometimes relaxed to $f(n) \ge 0$, $\forall n \ge N$ for some constant N.

O(n) can be thought of as the set of all functions whose growth is no worse than linear for sufficiently large n. Hence, it can be thought of as the infinite set $\{1, 2, ..., \log n, 2 \log n, ..., n, 2n, 3n, ..., n+1, n+2, ...\}$. So, 3n+5 is O(n) is just the statement that 3n+5 is in this set or $3n+5 \in O(n)$.

We should avoid writing big-O notations in the form f(n) = O(g(n)). As an example, if f(n) is O(n), then f(n) is also $O(n^2)$ because if f(n) grows no worse than linear for sufficiently large n, then f(n) must also grow no worse than quadratic for sufficiently large n. If we write f(n) = O(n) and $f(n) = O(n^2)$. Then this implies that $O(n) = O(n^2)$ which is incorrect as $O(n) = O(n^2)$. Instead, we should write $f(n) \in O(n)$ and $f(n) \in O(n^2)$.

2. Questions on Binary Search Tree, Heap, Balanced Binary Search Tree, Basic Data Structures (stack/queue)

(a)

```
arrayToBST class implementation:
TreeNode class implementation:
   int val
                                                                       In method -type-TreeNode arrayToBST(int array)
   TreeNode left
                                                                           If array length equals 0
   TreeNode right
                                                                              return Null
                                                                           Else
   In the TreeNode constructor (int x)
                                                                               return treeFromArray(array, 0, array.length - 1)
       set val equals x
                                                                       END arrayToBST method
   End constructor
                                                                       In method -type-TreeNode treeFromArray(int array, firstIndex, lastIndex)
   In main method
                                                                           If firstIndex > lastIndex
       arrayToBST arrayToBST = new arrayToBST
                                                                              return Null
       TreeNode root
                                                                           Else
       TreeNode key
                                                                              int midpoint = firstIndex + (lastIndex-firstIndex) / 2
       int array = {//sample array};
                                                                              -type-TreeNode node = new TreeNode(array[midpoint])
       set root equals to arrayToBST method (array)
                                                                              node.left equals recursive call treeFromArray(arr,firstIndex,midpoint-1)
       Print out "Preorder traversal of constructed BST "
                                                                              node.right equals recursive call treeFromArray(arr,midpoint+1, lastIndex)
       call Preorder method (root)
                                                                              return node
       create Scanner object
                                                                       END treeFromArray method
       Print out "Choose a number to search it in the tree "
       int num = number entered by user
       set key equals to search method (root , num)
                                                                       In Preorder method (-type-TreeNode node )
                                                                          If node equals Null
       If key equals null
                                                                              return
           Print out "Number not found in the tree "
                                                                               print out node.val + " "
           Print out "Number is found " + the number
                                                                               recursive call Preorder(node.left)
    End main method
                                                                               recursive call Preorder(node.right)
END TreeNode implementation
                                                                       END Preorder method
                                                                       In method -type-TreeNode search (-type-TreeNode root, int number )
                                                                           If root equals Null OR root.val equals number
                                                                               return root
                                                                           If root.val is LESS THAN number
                                                                              return recursive method search(root.right , number)
                                                                               return recursive method search (root.left , number)
                                                                       END search method
                                                                   END arrayToBST implementation
                                                               endOfFile
```

The pseudocode above represents the following steps to convert a sorted array to a Binary Search Tree (BST):

- 1. Get the middle element of the array and make it as the root (this splits the array into left and right halves)
- 2. Get the middle Element of the left half of the array and make it child of root
- 3. Get the middle Element of the right half of the array and make it child of root
- 4. Recursively repeat 2-3 (inserting child elements)

By successfully constructing a Binary Search Tree from a sorted array, We successfully get O(log n) as time complexity when searching up any element in the tree. That is because every time we search in the tree, we are halving the number of inputs in each search iteration (recursion).

The conditions given can be satisfied by using an AVL Search Tree structure for the software. When doing insertion and Deletion, the process time for an AVL Search Tree will always be O(log n), the procedure for Insertion such as follows:

- 1. Search through the tree for empty node (Search right node if current node alphabetical order is smaller than insert value alphabetical order, else search left node)
- 2. When empty node is found, insert the new value
- 3. Check the balance factor of every single node
- 4. Case 1: If Balance factor is >=-1 and <=1, the insert operation ends
- 5. Case 2: If Balance factor doesn't satisfy the condition in Case 1, rebalance the tree using rotation

The procedure for deletion is similar to Insertion, which is as follows:

- 1. Search through the tree for the value to be deleted
- 2. When the value to be deleted is found, set the node to null and replace with suitable node
- 3. Check the balance factor of every single node
- 4. Case 1: If Balance factor is >=-1 and <=1, the insert operation ends
- 5. Case 2: If Balance factor doesn't satisfy the condition in Case 1, rebalance the tree using rotation

Since the AVL tree for employee names is constructed in alphabetical order, the software can finish the request in O(n) time.

Lastly, the promises can be declared as a global variable which connect to each node so the software is able to process it in O(1) time and everyone will be getting the same value.

Pseudocode:

```
Insertion (NewEmployee, EmployeeList)

SET CurrentNode = EmployeeList.RootNode

WHILE (CurrentNode = EmployeeList.RootNode

WHILE (CurrentNode = EmployeeList.RootNode

WHILE (CurrentNode = CurrentNode.right

ELSE SET CurrentNode = CurrentNode.left

END WHILE

Insert(NewEmployee)

Balance(EmployeeList)

Detetion(ExistingEmployee, EmployeeList)

SET CurrentNode = EmployeeList)

Detetion(ExistingEmployee)

If (CurrentNode = EmployeeList)

Detetion(ExistingEmployee)

If (CurrentNode = EmployeeList)

Detetion(ExistingEmployee)

If (CurrentNode = EmployeeList)

SET CurrentNode = EmployeeList)

ELSE SET CurrentNode = CurrentNode.right

ELSE SET CurrentNode = CurrentNode.left

END WHILE

Remove(CurrentNode)

If (CurrentNode.left != null && CurrentNode.right != null)

SET Successor = findMinNode(CurrentNode.right)

SET CurrentNode = CurrentNode.right != null)

If (CurrentNode.left! = null || CurrentNode.right != null)

SET CurrentNode = CurrentNode.right

CALL Detetion(Successor, EmployeeList)

ELSE || CurrentNode = CurrentNode.right || EmployeeList)

ELSE || CurrentNode = CurrentNode.right || EmployeeList)

ELSE || CurrentNode = CurrentNode.right || CurrentNode.right || EmployeeList)

ELSE || CurrentNode = CurrentNode.right || EmployeeList)

Balance(EmployeeList)

RETURN CurrentNode || EmployeeList)
```

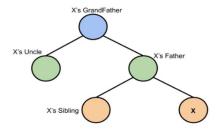
For upgrade requests and cancellation to be in O(log n) time and determine the k highest-priority flyers on the waiting list in O(k log n) time, where n is the number of frequent flyers on the waiting list, the system must traverse nodes to a depth of at most O(log n). For this to be possible, we require the use of a self-balancing binary tree which has a depth of O(log n). Two of the most popular self-balancing binary trees are AVL tree and Red-Black tree. In this instance, we decided to use a Red-Black tree. This is because of program will experience frequent insertion and deletion. Although AVL trees are more balanced, they cause more rotations during insertion and deletion. So, a Red-Black tree is preferred in this case.

Rules That Every Red-Black Tree Follows:

- 1. Every node has a color either red or black.
- 2. The root of the tree is always black.
- 3. There are no two adjacent red nodes (A red node cannot have a red parent or red child).
- 4. Every path from a node (including root) to any of its descendants' NULL nodes has the same number of black nodes.
- 5. All leaf nodes are black nodes.

Interesting points about Red-Black Tree:

- 1. Black height of the red-black tree is the number of black nodes on a path from the root node to a leaf node. Leaf nodes are also counted as black nodes. So, a red-black tree of height h has black height >= h/2.
- 2. Height of a red-black tree with n nodes is $h \le 2 \log_2(n + 1)$.
- 3. All leaves (NIL) are black.
- 4. The black depth of a node is defined as the number of black nodes from the root to that node.



```
searchElement (root, value)
node = root;
While (node != null)

If (value == node.value) //if value is found
    return true;
Else If (value < node.value) //if value is less than current node value
    node = node.left;
Else If (value > node.value) //if value is greater than current node value
    node = node.right;
return false;
```

```
addElement (root, value)
node = root;
ff (searchElement (root, value) == false) //if value does not exist in tree

node = new Node; //node is already pointed at correct position after search
node.value = value;
node.colour = node == root ? black : red; //if node is root then colour black, else colour red

While (node != root && node.parent.colour == red)

If (node.uncle.colour == red) //recolour if both parent and uncle node are red

Node.parent.colour == Rode.uncle.colour == black;
Node.parent.dolour == node.grandfather != root ? red : black
Node == node.grandfather;

Else If (node.uncle.colour == black) //rotation if parent is red and uncle is black

If (node.grandparent.left == node.parent && node.parent.left == node) //ii. case
node.grandparent.colour == black;
node.grandparent.colour == red;
EightStation (node.grandparent)
```

This is the pseudocode for the default search element and add element methods of a red-black tree.

```
Else if (node.parent.right == node.sibling.child.colour == node.sibling.teft == node.sibling.child) //RL case node.sibling.colour.st plack | Fig. |

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If (node.sibling.colour.st plack) | Fig. |

If (
```

This is the pseudocode for the default delete element method of a red-black tree.

For a program using a red-black tree, upgrade and cancellations thus will take $O(\log n)$ time. This is because the program will have to traverse the tree to find the correct position and insert or delete a node. This process takes $O(\log n)$ time because the red-black tree has a depth of $O(\log n)$. To determine the k highest-priority flyers on the waiting list, the process takes $O(k \log n)$ time. This is because the red-black tree has a depth of $O(\log n)$ and the program has to traverse the red-black tree k time. So, $O(k * \log n) = O(k \log n)$. A Java program has been created below using TreeSet which is implemented using a Red-Black Tree. The comparator of the program is designed to move the highest priority passengers to the left of the tree. To get the k highest-priority flyers on the waiting list, we get the leftmost passenger in the tree first.

```
public class FrequentFlyerProgram {
   private final TreeSet<Passenger> treeSet;
   int referenceID;

public FrequentFlyerProgram(){
    this.treeSet = new TreeSet<>(new Passenger());
    this.referenceID = 0;
}
```

This is the public class for our program named FrequentFlyerProgram. The constructor initializes a new TreeSet using the Passenger comparator. TreeSet uses Red-Black Tree in its implementation. The referenceID is also set to 0.

This is the Passenger class and it holds information about the passenger.

Passenger() – Used to initialize the comparator in the TreeSet

The constructor with the 6 parameters creates a new Passenger object with the given parameters which is saved inside the TreeSet.

```
@Override
public int compare(Passenger o1, Passenger o2) {
    if(o1.flyerStatusCode != o2.flyerStatusCode){
        return o2.flyerStatusCode - o1.flyerStatusCode;
    }
    else if (o1.waitingListTime != o2.waitingListTime){
        return o2.waitingListTime - o1.waitingListTime;
    }
    else {
        return o1.referenceID - o2.referenceID;
    }
}
```

This is the comparator for the Passenger class. It is used to compare 2 passenger objects inside the TreeSet. It is used in the search, insert and delete functions of the TreeSet. First, we compare rank, higher rank goes left. If ranks are equal, we compare time, higher time goes left. If rank and time are equal, we compare ref number, lower ref number goes left.

This is the getPassengerList method which returns k passengers with the highest priority.

```
public int getReferenceID() { return referenceID++; }
```

This method returns the current referenceID and increments it by 1 so every passenger has a unique ID. This is to allow passengers with the same rank and waiting time to exist together in the Red-Black Tree.

```
public void addPassenger(String firstName, String lastName, int flyerStatusCode, int waitingListTime) {
   int referenceID = getReferenceID();
   char[] flyerStatusList = {'S','6','P'};
   String flyerCode = String.format("%02d", flyerStatusCode);
   String reference = String.format("%02d", referenceID);
   String waitingTime = String.format("%02d", waitingListTime);
   String confirmationCode = flyerStatusList[flyerStatusCode] + flyerCode + reference + waitingTime;
   boolean notExist = treeSet.add(new Passenger(firstName, lastName, confirmationCode, flyerStatusCode, waitingListTime, referenceID));

if(notExist) {
        System.out.format("Passenger %s %s with Confirmation Code %s has been added to the queue.\n", firstName, lastName, confirmationCode);
    }
   else
        System.out.format("Passenger with Confirmation Code %s already exist in queue.\n",confirmationCode);
}
```

This is the addPassenger method which creates new Passenger object and inserts it into the TreeSet. A unique comfirmation code is also generated for each passenger. As an example, S20110 means the passenger has Silver rank, referenceID of 01 and waitingTime of 10. The new passenger is only inserted if no duplicates exist in the TreeSet.

```
public void removePassenger(String confirmationCode){
  int flyerCode = Integer.parseInt(confirmationCode.substring(1, 2));
  int reference = Integer.parseInt(confirmationCode.substring(2, 4));
  int waitingTime = Integer.parseInt(confirmationCode.substring(4, 6));
  boolean exists = treeSet.remove(new Passenger( firstName: null, lastName: null, confirmationCode, flyerCode, waitingTime, reference));

if(exists) {
    System.out.format("Passenger with Confirmation Code %s has been removed from the queue.\n",confirmationCode);
  }
  else
    System.out.format("Passenger with Confirmation Code %s does not exist in queue.\n",confirmationCode);
}
```

This is the removePassenger method which removes a passenger object from the TreeSet. It converts the confirmationCode of the passenger into rank, referenceID and waitingTime which is used to create a temporary passenger object. The passenger is deleted from the TreeSet if a duplicate is found.

```
Algorithm upgrade(root, k) //k number of seat upgrades

While(k != 0) //while seat upgrades available

checkRecord = root; //set pointer to root of tree

While(checkRecord.left != null) //while not leftmost node

checkRecord = checkRecord.left; //move left

delete(checkRecord) //remove leftmost/highest priority node

k := k - 1; //decrement seat upgrade by 1

balanceTree(); //rebalance tree
```

These are the pseudocode for the upgrade, cancellation and get k highest priority flyer methods of the program.