# 

# 

### 

## 

## **A Supplementary Material - Correctness**

In this section, we prove Oak's correctness. Since the rebalancer is orthogonal to our contribution, we omit it from the discussion of Oak's correctness. We only assume that RB1-3 hold. We note that a similar rebalance was fully proven in [17].

#### A.1 Preliminaries

We consider a shared memory system consisting of a collection of shared variables accessed by threads, which also have local variables. An algorithm defines the behaviors of threads as deterministic state machines, where state transitions are associated with either an instance of a shared variable primitive (read, write, CAS, etc.) or a local step affecting the thread's local variables. A configuration describes the current state of all local and shared variables. An initial configuration is one where all variables hold an initial value. A data structure implementation provides a set of operations, each with possible parameters. We say that operations are invoked and return or respond. The invocation of an operation leads to the execution of an algorithm by a thread. Both the invocation and the return are local steps of a thread. A run of algorithm  $\mathcal{A}$  is an alternating sequence of configurations and steps, beginning with some initial configuration, such that configuration transitions occur according to  $\mathcal{A}$ . We say that two operations are *concurrent* in a run r if both are invoked in r before either returns. We use the notion of time tduring a run r to refer to the configuration reached after the  $t^{th}$  step in r. An interval of a run r is a sub-sequence that starts with a step and ends with a configuration. The interval of an operation op starts with the invocation step of op and ends with the configuration following the return from op or the end of r, if there is no such return.

An implementation of concurrent data structure is *linearizable* [33] (a correctness condition for concurrent objects) if it provides the illusion that each invoked operation takes effect instantaneously at some point, called the *linearization point* (l.p.), inside its interval. A *linearization* of a run r (lin(r)) is the sequential run constructed by serially executing each operation at its l.p.

#### A.2 Linearizability proof

**Definition 1.** If there is an entry e in Oak that points to key k and handle h, (i.e., lookUp(k) returns e s.t.

h = handles[entries[e].hi]) and h.deleted = false, we say that h is associated with k.

Claim 2. If an Oak operation searches for key k and finds a non-deleted handle h (h.deleted = false), then h is associated with k.

*Proof.* If an operation searches for k and finds h, then there is an entry e that points to k, since Oak ensures that there is at most one entry that points to k, and k is found only if there is such entry. This also means that e points to handle h

(by handle index hi). Assume that e does not point to handle h, then the handle index is now  $hi' \neq hi$ . If  $hi' = \bot$  then the handle index can be set only by a non-insertion operation using a CAS. According to Algorithm 3 this is only possible when h in handles [hi] is already deleted, but h is not deleted. Otherwise,  $hi' \neq hi$  and  $hi' \neq \bot$ , then the handle index can be set only by an insertion operation using a CAS. According to Algorithm 2 this is only possible when h in handles [hi] is already deleted, which is not the case. Therefore, there is an entry e that points to e and e and e and e deleted e false, so by Definition 1 e is associated with e.

**Claim 3.** Assume handle h is associated with key k at time t in a run r. Then, h is associated with k at time (t+1) in r if and only if the  $(t+1)^{st}$  step in r is not the l.p. of a successful remove(k) operation.

*Proof.* Assume that h is not associated with k at time (t+1). If there is no handle associated with k at time t+1, then by Definition 1 either h. deleted = true or the entry's handle index (hi) is  $\bot$ . In the first case, the only possible step that marks a handle as deleted is the l.p. of a successful remove(k). In the second case, only non-insertion operations turn hi to  $\bot$  by using CAS (lines 56 and 74), and according to Algorithm 3 this is only possible when the handle is deleted. However, at time t, h is still associated with k. Therefore, the entry's handle index (hi) is not  $\bot$ .

Otherwise, there is a different handle  $h' \neq h$  that is associated with k at time t+1 ( $h' \neq \bot$ ). This change can only be done by an insertion operation using CAS (line 38). According to Algorithm 2 an insertion operation reaches that CAS only if the handle (h) is already deleted (line 21). However, at time t, h is still associated with k, and so there is no different handle that is associated with k.

Therefore, as long as the  $(t+1)^{st}$  step is not the l.p. of a successful remove(k), then h is still associated with k at time t+1 in r, and there is no handle associated with k at time t+1 if the  $(t+1)^{st}$  step is a l.p. of a successful remove(k), as required.

**Claim 4.** Assume no handle is associated with key k at time t in a run r. Then, no handle is associated with k at time t+1 in r if and only if the  $(t+1)^{st}$  step in r is not the l.p. of a successful insertion operation of k.

*Proof.* If no handle is associated at time t, and at time t+1 there is an associated handle, then according to Definition 1 either a handle's deleted flag turned from false to true, or the entry's handle index turned from  $\bot$  to a valid one. The former is not possible because the handles are initialized as not deleted and only become deleted by a remove; no operation turns a deleted handle to a non-deleted one. In the second case, this can only be done by a successful insertion operation, at its l.p. (line 38), as required.

Look at the linearization lin(r) of run r using l.p.s defined in Section 4.5. From Claims 3 and 4, by induction on the steps of a run, we get:

**Corollary 5.** At any point in a concurrent run r, the set of keys associated with handles is exactly the same as the set of inserted keys and not removed keys, associated with the same handles, in lin(r) up to that point.

**Claim 6** (Get). In run r, if get(k) returns h then the corresponding get(k) in lin(r) returns h, and if get(k) returns null then the corresponding get(k) in lin(r) returns null.

Proof. There are three cases for get's l.p.:

- Get(k) finds a non-deleted handle h (line 6), then get(k) returns h and by Claim 2 h is associated with k. By Corollary 5, in lin(r) k is inserted and not removed (the map holds k) and since this is the l.p. of get then the corresponding get(k) in lin(r) returns h as well.
- 2. LookUp(k) by get(k) (line 3) returns  $\bot$  or if get(k) reads that the handle index is  $\bot$  (line 4), then there is no handle associated with key k, and get(k) returns null. By Corollary 5, in lin(r) the map does not hold k, and since this is the l.p. of get then the corresponding get(k) in lin(r) returns null as well.
- 3. Get(k) finds a deleted handle h at time  $t_2$  (line 6) and returns null. Then its l.p. is the later between the read of handle index hi by get(k) at time  $t_1 < t_2$  (line 4) and immediately after the set of deleted = true by remove(k) at some time  $t < t_2$ . Again there are two cases:
  - a. If  $t > t_1$  then the l.p. is immediately after the set of deleted = true then there is no handle associated with key k, and by Corollary 5, in lin(r) the map does not hold k, and the corresponding get(k) in lin(r) returns null as well.
- b. If  $t_1 > t$  then the l.p. is the read of handle index hi by get(k) (line 4) at time  $t_1$ , after the set of deleted = true at time t. We need to show that at no time between t and  $t_1$  the handle index changed to  $hi' \neq hi$  and now it does not point to a deleted handle. Notice that only an insertion operation l.p. can change hi to hi'. Assume by contradiction that the l.p. of such an operation occurs between t and  $t_1$ . Then when get sees hi at time  $t_1$ , it is already hi' and not hi. A contradiction. Hence, at the l.p. of get(k), there is no handle associated with key k, and by Corollary 5, in lin(r) the map does not hold k, so the corresponding get(k) in lin(r) returns null as required.

**Claim 7** (PutIfAbsent). In run r, if putIfAbsent(k) returns true then the corresponding putIfAbsent(k) in lin(r) returns true, and if putIfAbsent(k) returns false then in lin(r) the corresponding putIfAbsent(k) returns false.

*Proof.* If putIfAbsent(k) finds a non-deleted handle h (line 21), then putIfAbsent(k) returns false and by Claim 2 h is associated with k. By Corollary 5, in lin(r) k is inserted and not removed (the map holds k) and since this is the l.p. of putIfAbsent then the corresponding putIfAbsent(k) in lin(r) returns false as well.

Otherwise, if putIfAbsent(k) performs a successful CAS of handle index from  $\bot$  (line 38), then putIfAbsent(k) returns true and by Definition 1 there was no handle associated with k just before the CAS. By Corollary 5, in lin(r) the map does not hold k, and since this is the l.p. of putIfAbsent then the corresponding putIfAbsent(k) in lin(r) returns true as required.

**Claim 8** (ComputeIfPresent). In run r, if computeIfPresent(k) returns true then in lin(r) the corresponding computeIfPresent(k) returns true, and if computeIfPresent(k) returns false then the corresponding computeIfPresent(k) in lin(r) returns false.

*Proof.* If computeIfPresent(k) finds a non-deleted handle k and there is a successful nested call to handle compute (line 50), then computeIfPresent(k) returns true and by Claim 2 k is associated with k. By Corollary 5, in lin(r) k is inserted and not removed (the map holds k) and since this is the l.p. of computeIfPresent then the corresponding computeIfPresent(k) in lin(r) returns true as well.

If lookUp(k) by computeIfPresent(k) returns  $\bot$ , or if computeIfPresent(k) reads that the handle index is  $\bot$  (line 47), then there is no handle associated with key k, and computeIfPresent(k) returns false. By Corollary 5, in lin(r) the map does not hold k, and since this is the l.p. of computeIfPresent then the corresponding computeIfPresent(k) in lin(r) returns false as required.

Otherwise, a successful CAS of handle index to  $\bot$  is performed by computeIfPresent(k) (line 56), from a handle index pointing to a deleted handle (line 49). Then computeIfPresent(k) returns false and by Definition 1 there is no handle associated with k just before the CAS and right after it. By Corollary 5, in lin(r) the map does not hold k, and since this is the l.p. of computeIfPresent then the corresponding computeIfPresent(k) in lin(r) returns false.

**Claim 9** (Put). In run r, if put(k) inserts k and returns then in lin(r) the corresponding put(k) inserts k and returns, and if put(k) replaces k's value and returns then in lin(r) the corresponding put(k) replaces k's value and returns.

*Proof.* If put(k) finds a non-deleted handle h and there is a successful nested call to handle put (line 23), then put(k) replaces k's value and returns, and by Claim 2 h is associated with k. By Corollary 5, in lin(r) the map holds k and since this is the l.p. of put then the corresponding put(k) in lin(r) replaces k's value and returns as well.

Otherwise,  $\operatorname{put}(k)$  performs a successful CAS of handle index (line 38) from  $\bot$ , and inserts k and returns. By Definition 1 there is no handle associated with k just before the CAS, and there is one right after the CAS (the handle is initialized as non-deleted). Since this is the l.p. of put, and by Corollary 5 in lin(r) the map does not hold k before the l.p. and does after. Therefore, the corresponding  $\operatorname{put}(k)$  in lin(r) inserts k and returns as required.

Claim 10 (PutIfAbsentComputeIfPresent). In run r, if putIfAbsentComputeIfPresent(k) inserts k and returns then in lin(r) the corresponding putIfAbsentComputeIfPresent(k) inserts k and returns, and if putIfAbsentComputeIfPresent(k) updates k's value and returns then in lin(r) the corresponding putIfAbsentComputeIfPresent(k) updates k's value and returns.

*Proof.* If putIfAbsentComputeIfPresent(k) performs a successful CAS of handle index (line 38) from  $\bot$ , then it inserts k and returns. By Definition 1 there is no handle associated with k just before the CAS, and there is one right after the CAS (the handle is initialized as non-deleted). Since this is the l.p. of putIfAbsentComputeIfPresent, and by Corollary 5 in lin(r) the map does not hold k before the l.p. and does after. Therefore, the corresponding putIfAbsentComputeIfPresent(k) in lin(r) inserts k and returns as required.

Otherwise, putIfAbsentComputeIfPresent(k) finds a non-deleted handle h and there is a successful nested call to handle compute (line 25), then putIfAbsentComputeIfPresent(k) updates k's value and returns, and by Claim 2 h is associated with k. By Corollary 5, in lin(r) the map holds k and since this is the l.p. of putIfAbsentComputeIfPresent then the corresponding putIfAbsentComputeIfPresent(k) in lin(r) updates k's value and returns as well.

**Claim 11** (Remove). In run r, if remove(k) removes k and returns then in lin(r) the corresponding remove(k) removes k and returns, and if remove(k) returns unsuccessfully (without removing any key) then in lin(r) the corresponding remove(k) returns unsuccessfully.

*Proof.* If remove(k) finds a non-deleted handle h and a successful nested call to handle remove occurs, setting the handle to deleted (line 52), then remove(k) removes k and returns. By Claim 2 h is associated with k before and there is no handle associated with k right after (by Definition 1). Since this is the l.p. of remove, and by Corollary 5 in lin(r) the map does hold k before the l.p. and does not after. Therefore, the corresponding remove(k) in lin(r) removes k and returns as required.

If lookUp(k) by remove(k) returns  $\bot$ , or if remove(k) reads that the handle index is  $\bot$  (line 47), then there is no handle associated with key k, and remove(k) returns unsuccessfully. By Corollary 5, in lin(r) the map does not hold k, and since this is the l.p. of remove then the corresponding remove(k) in lin(r) returns unsuccessfully as required.

Otherwise, a successful CAS of handle index to  $\bot$  is performed by remove(k) (line 56), from a handle index pointing to a deleted handle (line 49). Then remove(k) returns and by Definition 1 there is no handle associated with k just before the CAS and right after it. By Corollary 5, in lin(r) the map does not hold k, and since this is the l.p. of remove then the corresponding remove(k) in lin(r) returns unsuccessfully.

Having shown that all of Oakâ $\check{A}$ Źs operations behave the same way in a run r and its linearization lin(r), we can conclude the following theorem:

**Theorem 12.** Oak is linearizable with the l.p.s defined in Section 4.5.