

وَمَا أُوتِيتُمْ مِنَ الْعِلْمِ إِلَّا قَلِيلًا

Analog IC Design

Lecture 11 Differential Amplifiers

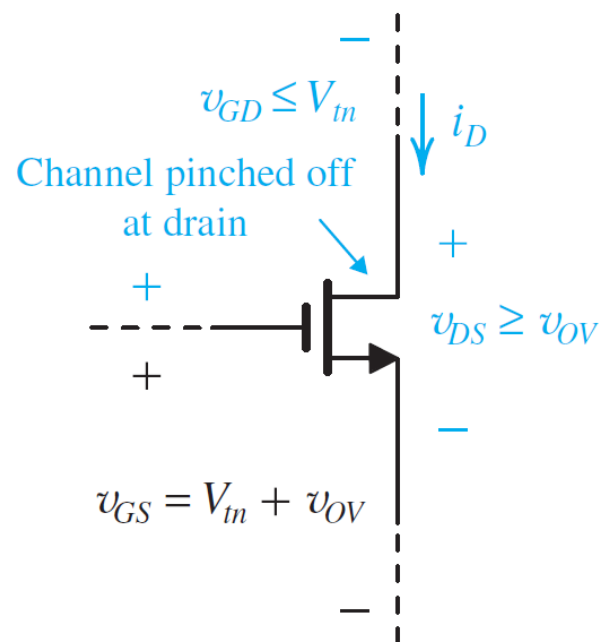
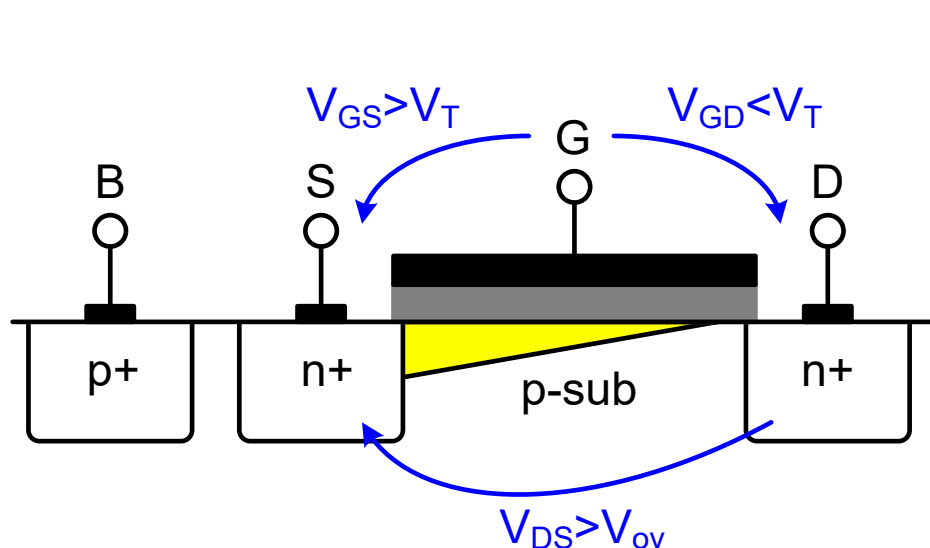
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Ain Shams University

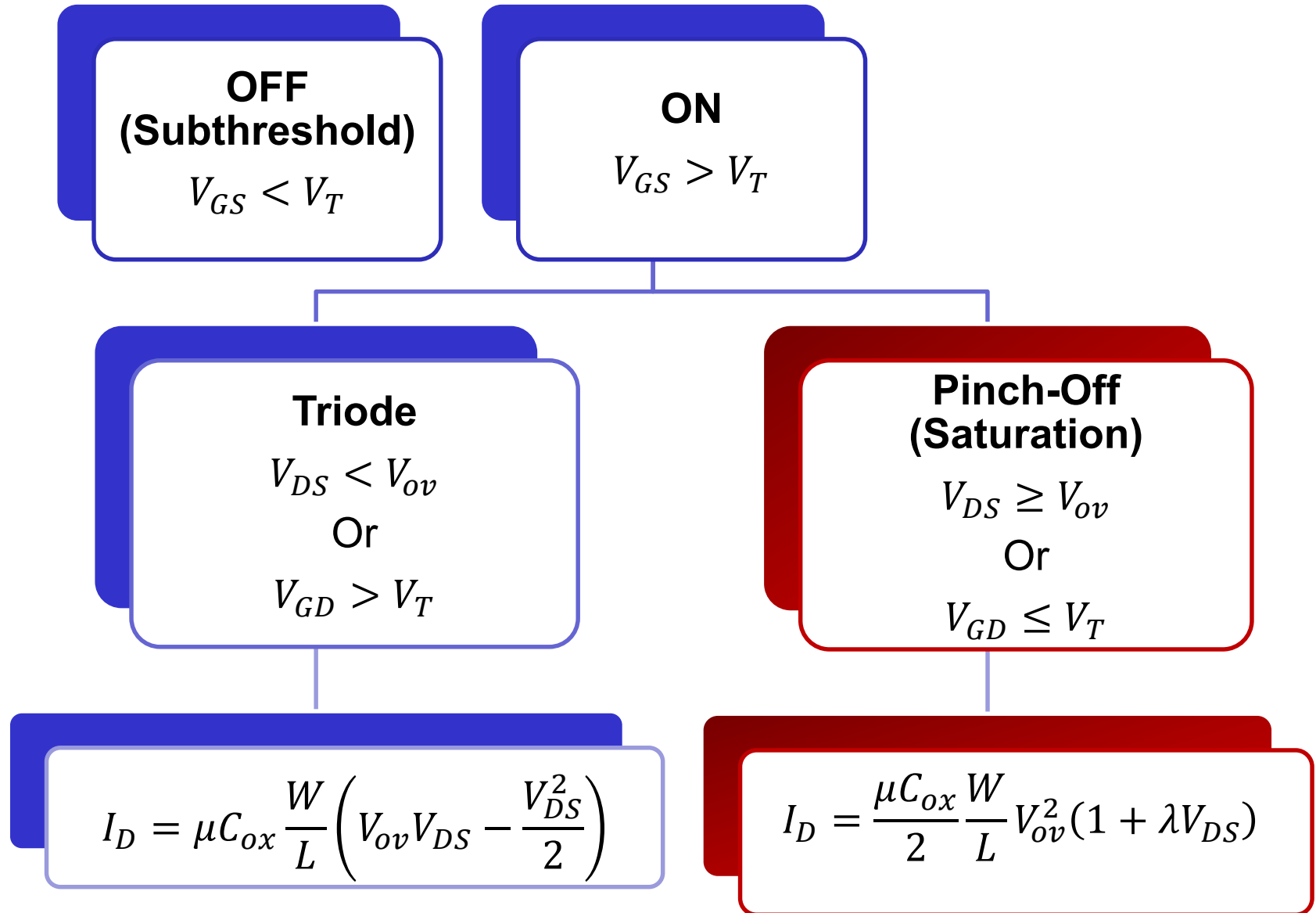
MOSFET in Saturation

- ❑ The channel is pinched off if the difference between the gate and drain voltages is not sufficient to create an inversion layer

$$I_D = \frac{\mu_n C_{ox}}{2} \frac{W}{L} \cdot V_{ov}^2 (1 + \lambda V_{DS})$$



Regions of Operation Summary

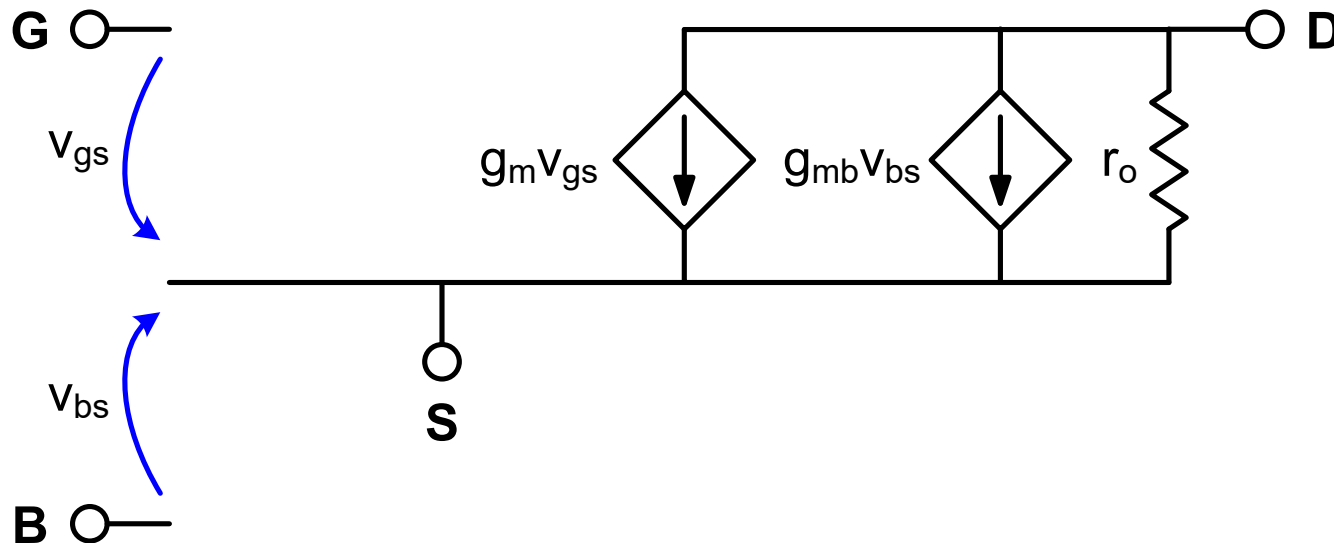


Low-Frequency Small-Signal Model

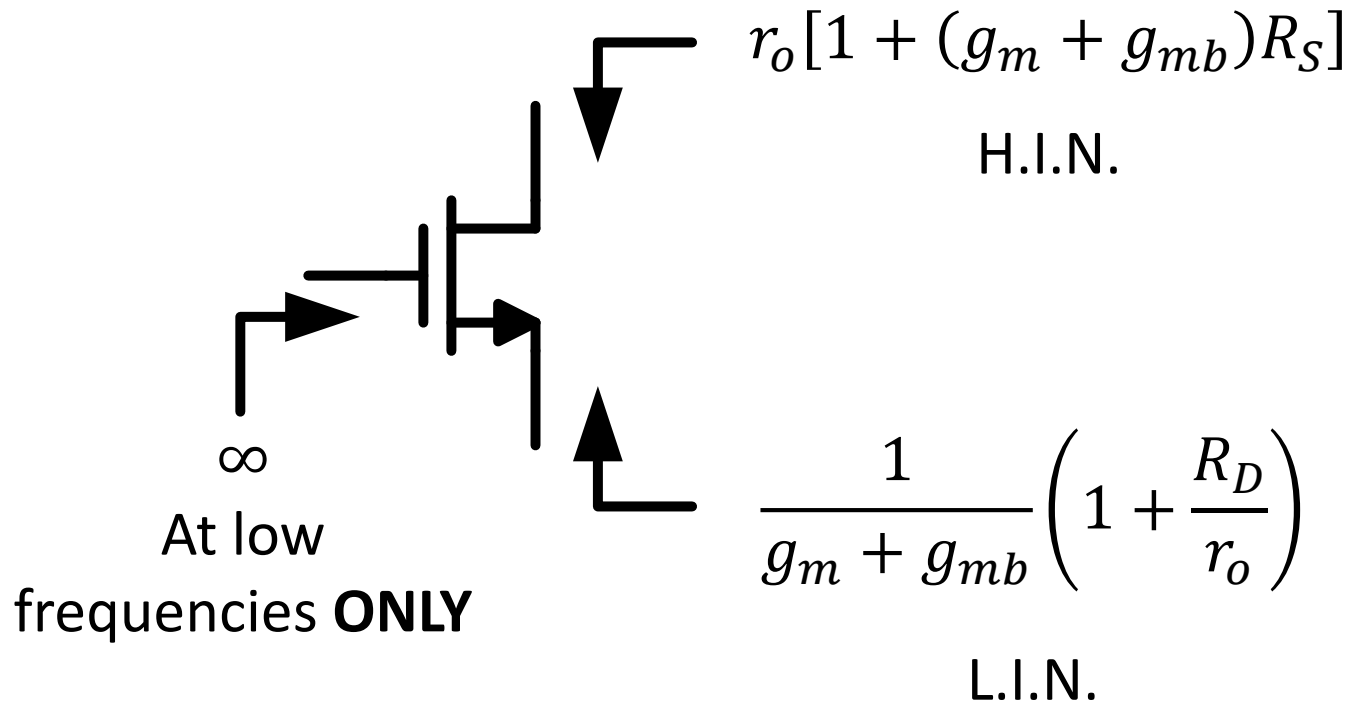
$$g_m = \frac{\partial I_D}{\partial V_{GS}} = \mu C_{ox} \frac{W}{L} V_{ov} = \sqrt{\mu C_{ox} \frac{W}{L} \cdot 2I_D} = \frac{2I_D}{V_{ov}}$$

$$g_{mb} = \eta g_m, \quad \eta \approx 0.1 - 0.25$$

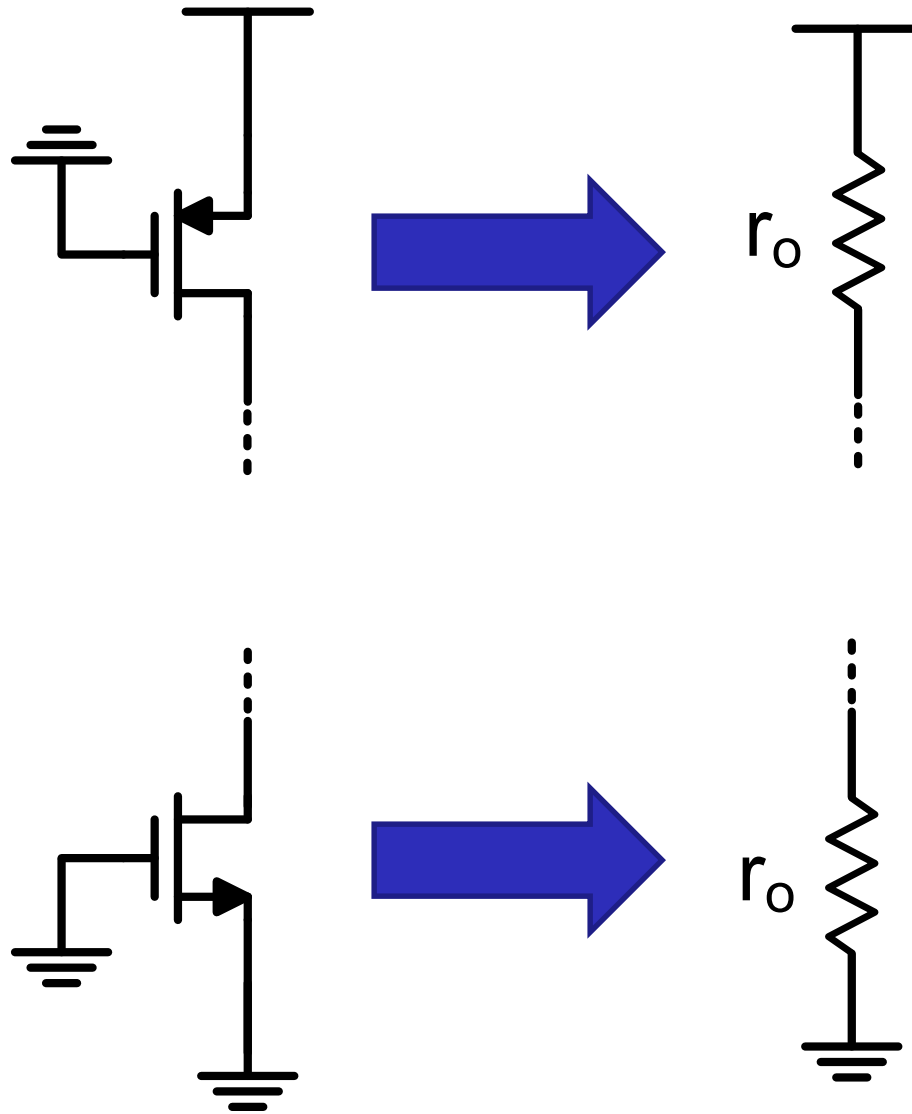
$$r_o = \frac{1}{\frac{\partial I_D}{\partial V_{DS}}} = \frac{1}{\lambda I_D}, \quad \lambda \propto \frac{1}{L}$$



Rin/out Shortcuts Summary

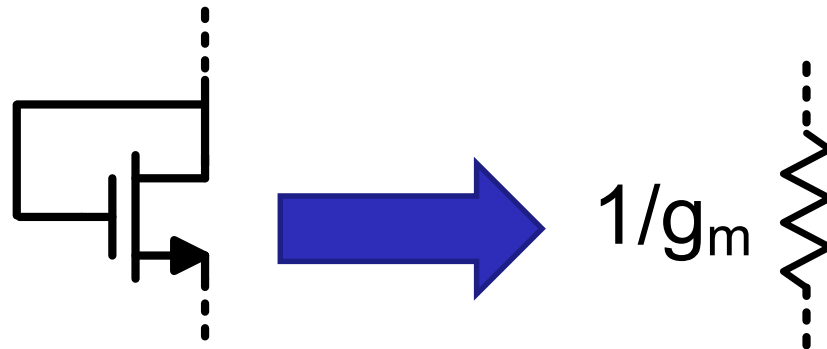
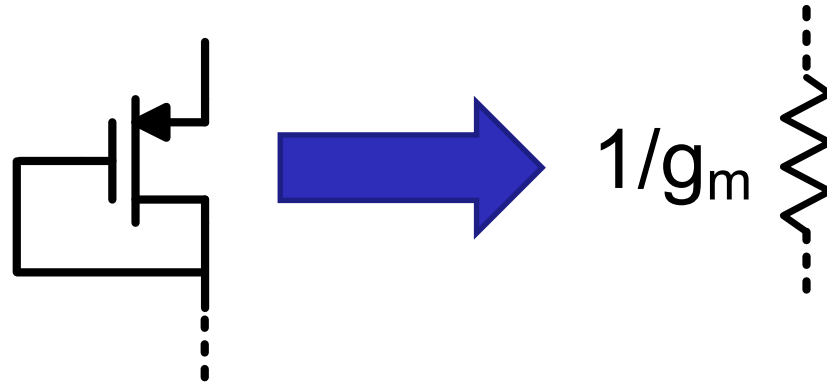


Active Load (Source OFF)



Diode Connected (Source Absorption)

- ❑ Always in saturation
- ❑ Bulk effect: $g_m \rightarrow g_m + g_{mb}$



Why GmRout?

$$R_{out} = \frac{v_x}{i_x} @ v_{in} = 0$$

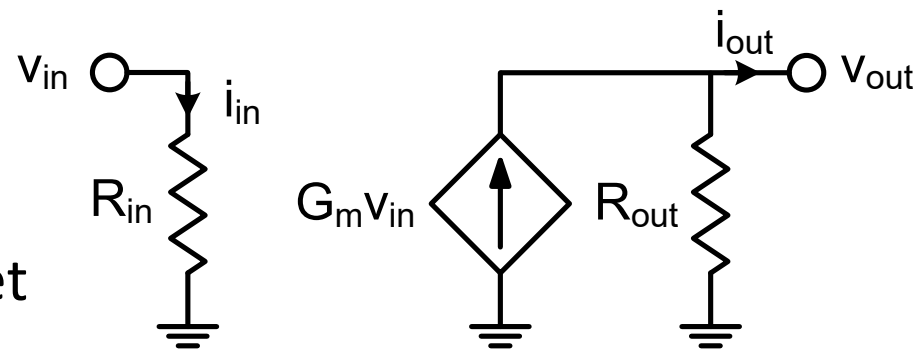
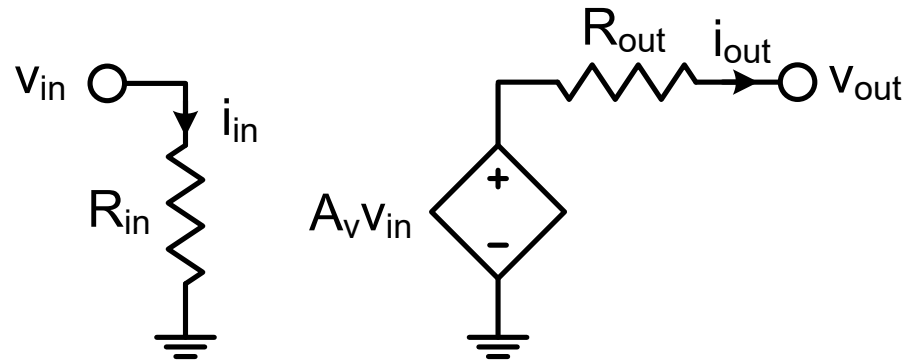
$$G_m = \frac{i_{out,sc}}{v_{in}}$$

$$A_v = G_m R_{out}$$

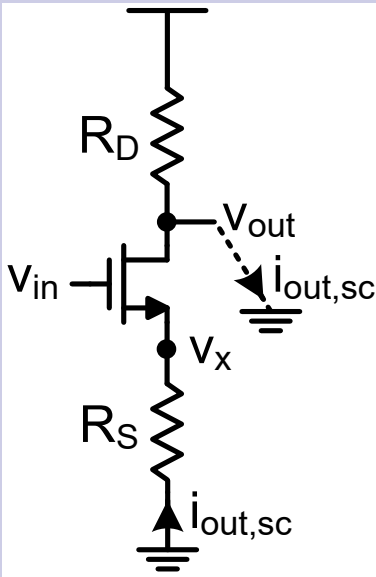
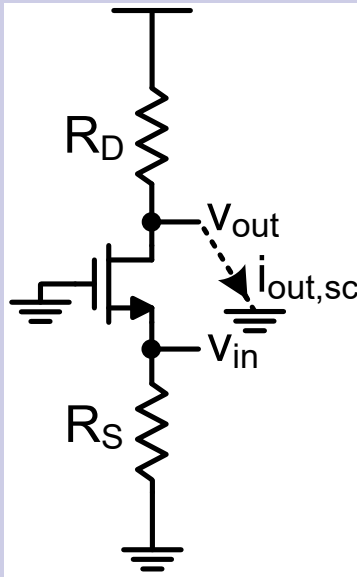
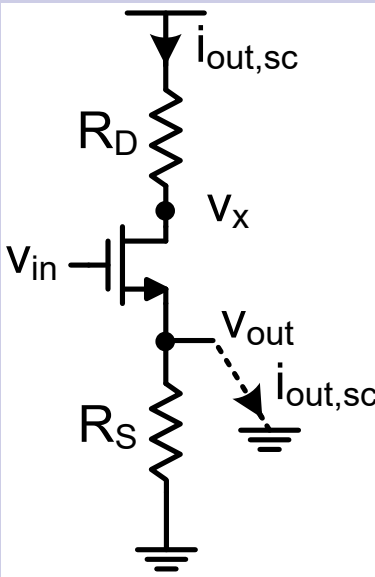
$$A_i = G_m R_{in}$$

□ Divide and conquer

- Rout simplified: $v_{in}=0$
- Gm simplified: $v_{out}=0$
- We already need Rin/out
- We can quickly and easily get Rin/out from the shortcuts

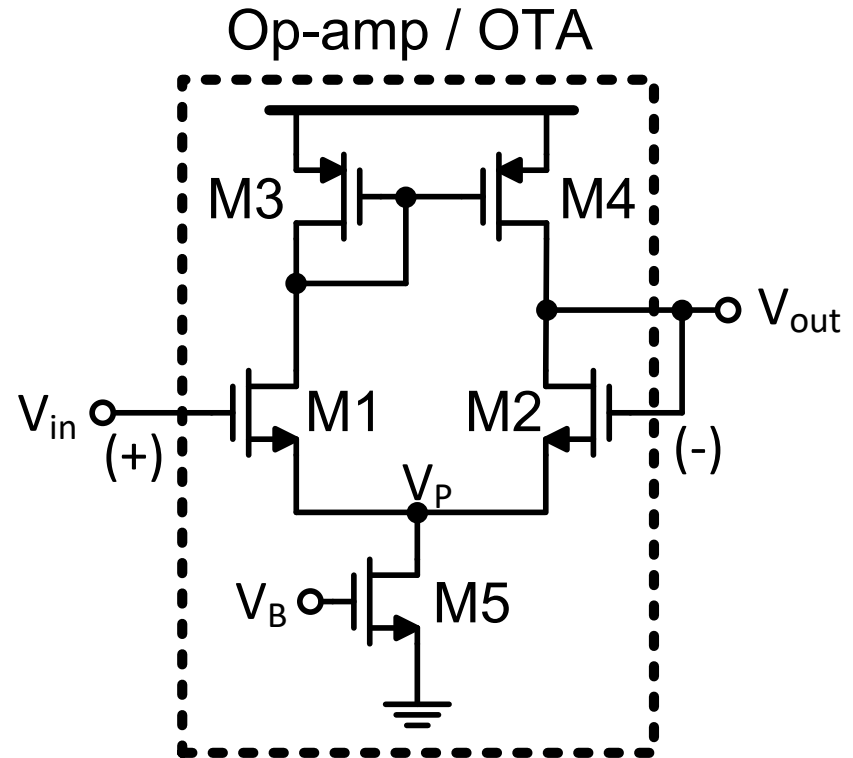
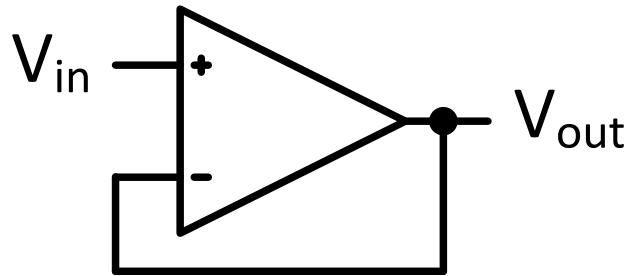


Summary of Basic Topologies

	CS	CG	CD (SF)
			
	Voltage & current amplifier	Current buffer	Voltage buffer
Rin	∞	$R_S // \frac{1}{g_m + g_{mb}} \left(1 + \frac{R_D}{r_o} \right)$	∞
Rout	$R_D // r_o [1 + (g_m + g_{mb})R_S]$	$R_D // r_o$	$R_S // \frac{1}{g_m + g_{mb}} \left(1 + \frac{R_D}{r_o} \right)$
Gm	$\frac{-g_m}{1 + (g_m + g_{mb})R_S}$	$g_m + g_{mb}$	$\frac{g_m}{1 + R_D/r_o}$

Have You Seen a Diff Amp Before?

- ❑ An op-amp is simply a high gain differential amplifier
- ❑ The gain can be increased by using cascodes and multi-stage amplifiers



Single-Ended (SE) vs Differential

- SE: measured with respect to a fixed potential (usually the ground)

$$v_{out,SE} = V_o \sin \omega t + V_{CM}$$

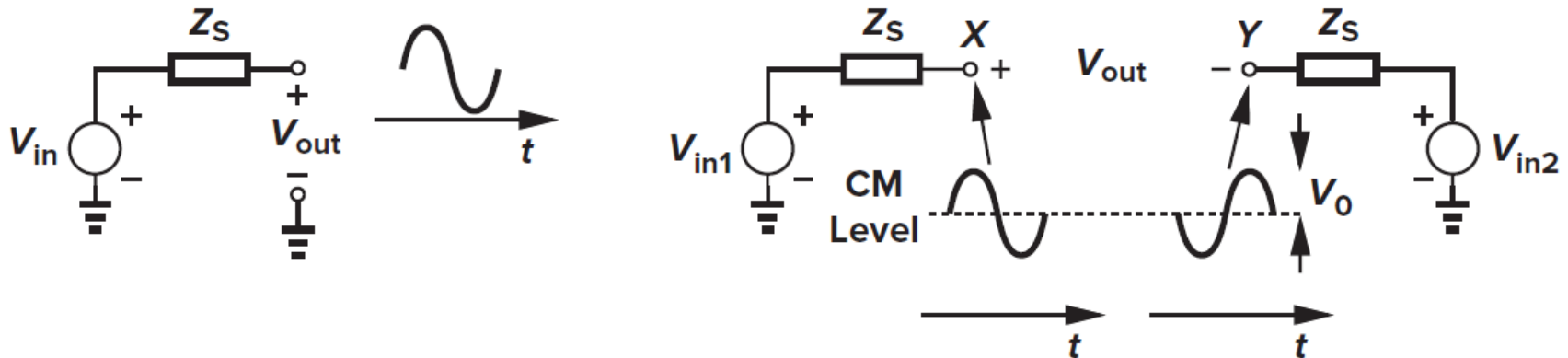
- Single-ended peak-to-peak swing is $2V_o$

- Diff: measured between two nodes that have *equal* and *opposite* signal around a common-mode (CM) level

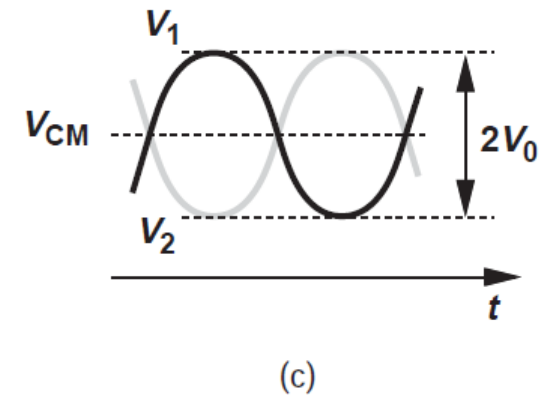
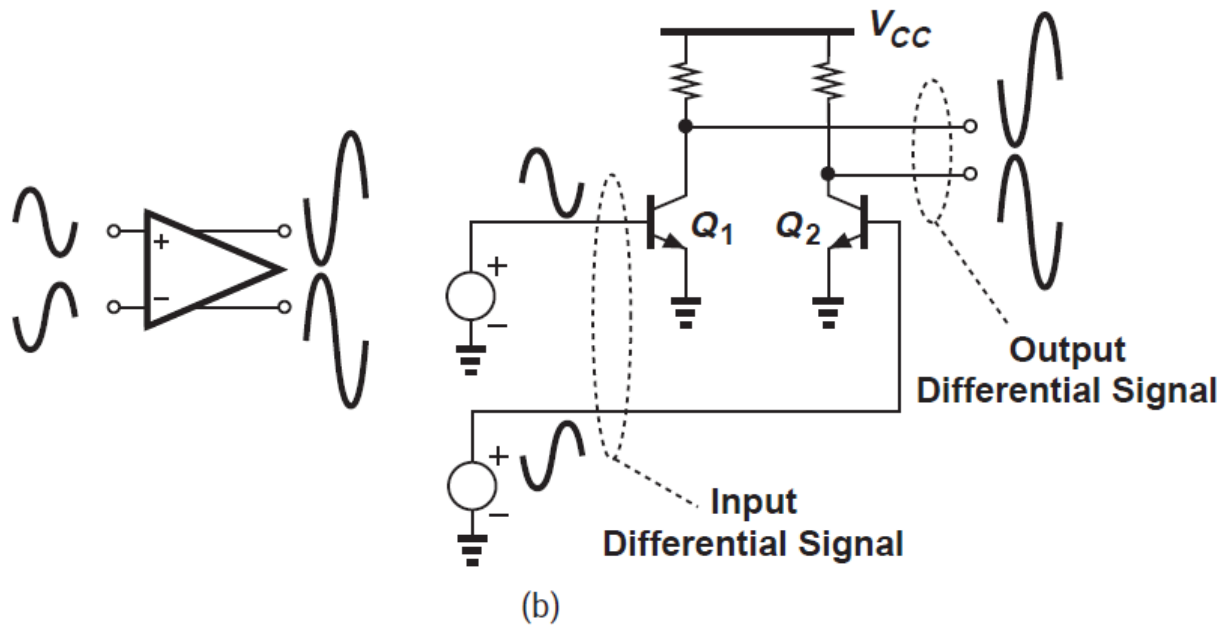
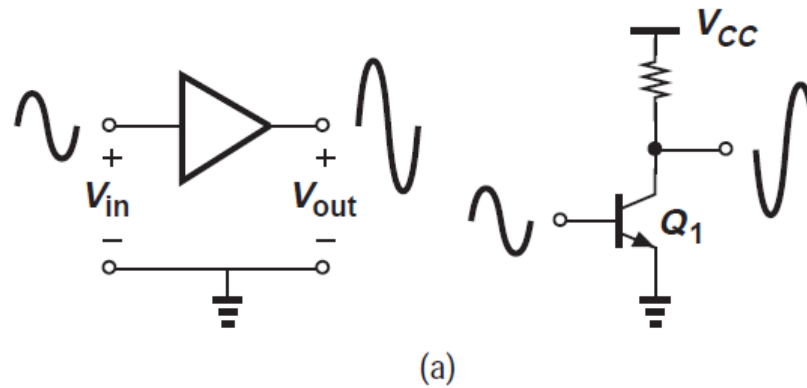
$$v_{out,diff} = v_x - v_y$$

$$= (V_o \sin \omega t + V_{CM}) - (-V_o \sin \omega t + V_{CM})$$

- Differential peak-to-peak swing is $4V_o$



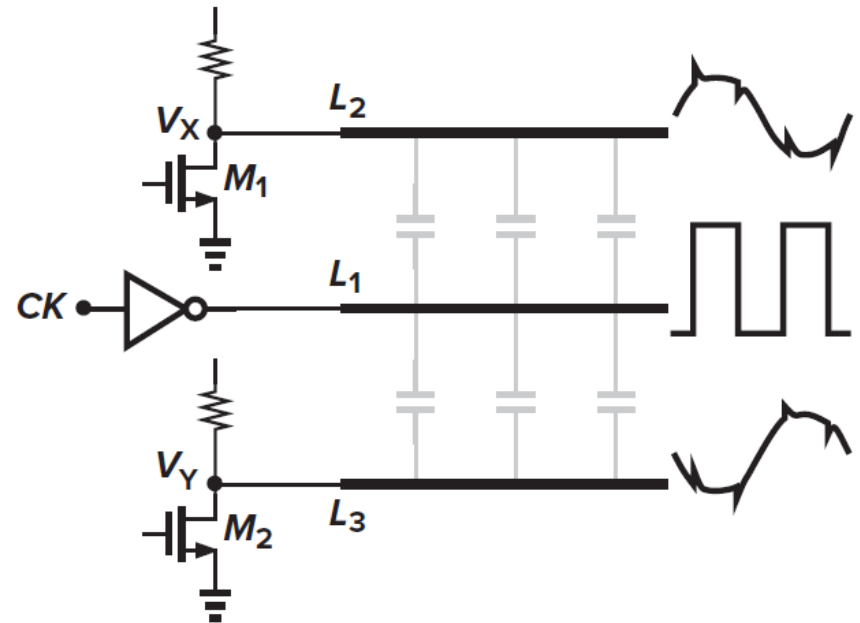
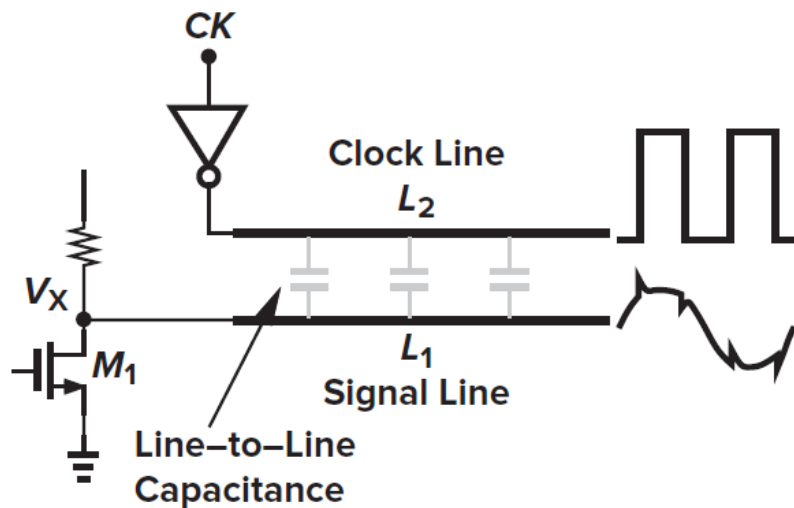
Single-Ended (SE) vs Differential



Why Differential?

$$v_{out,SE} = V_o \sin \omega t + V_{CM} + V_{CMnoise}$$

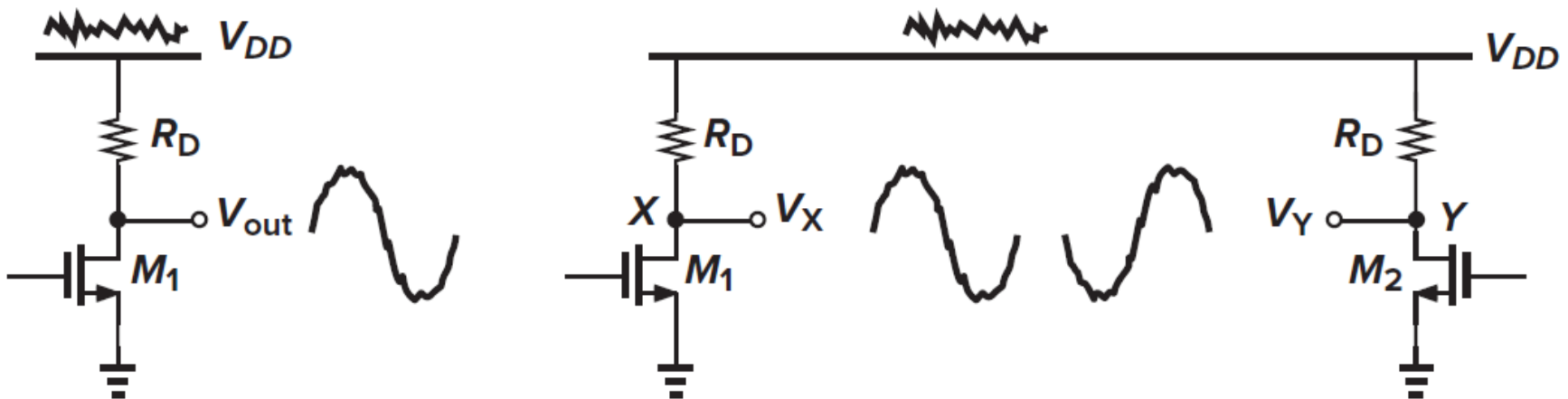
$$\begin{aligned} v_{out,diff} &= v_x - v_y \\ &= (V_o \sin \omega t + V_{CM} + V_{CMnoise}) - (-V_o \sin \omega t + V_{CM} + V_{CMnoise}) \\ &= 2V_o \sin \omega t \end{aligned}$$



Why Differential?

$$v_{out,SE} = V_o \sin \omega t + V_{CM} + V_{CMnoise}$$

$$\begin{aligned} v_{out,diff} &= v_x - v_y \\ &= (V_o \sin \omega t + V_{CM} + V_{CMnoise}) - (-V_o \sin \omega t + V_{CM} + V_{CMnoise}) \\ &= 2V_o \sin \omega t \end{aligned}$$



Why Differential?

❑ Pros

- **Common-mode (CM) noise rejection**
- Larger maximum signal swing
- Simpler biasing (no need for bypass or coupling capacitors)
- Higher linearity (H.W.: Read Section 14.1.2 in Razavi)

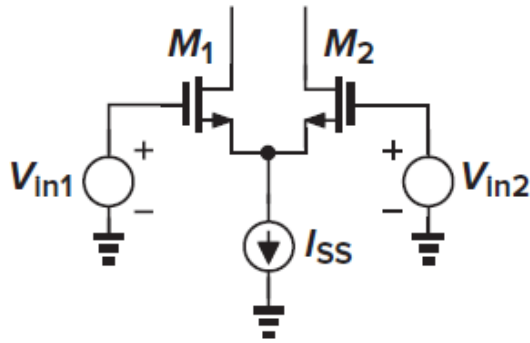
❑ Cons

- Doubling the area
- Doubling the power consumption

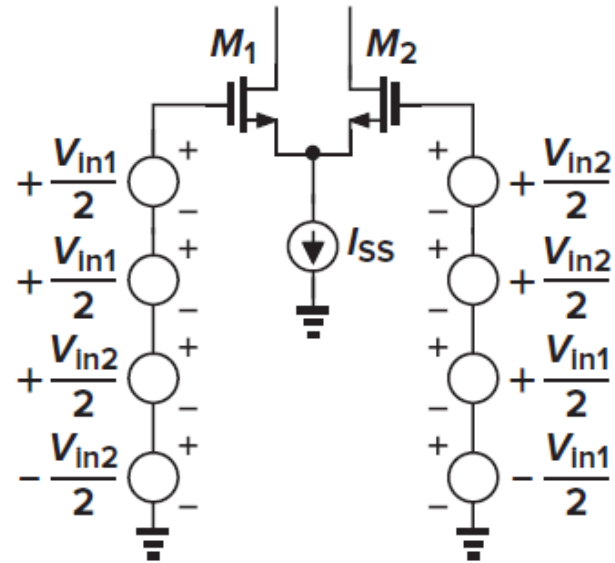
❑ The advantages of differential operation by far outweigh the disadvantages

❑ Differential operation has become the de facto choice in today's high-performance analog and mixed-signal circuits

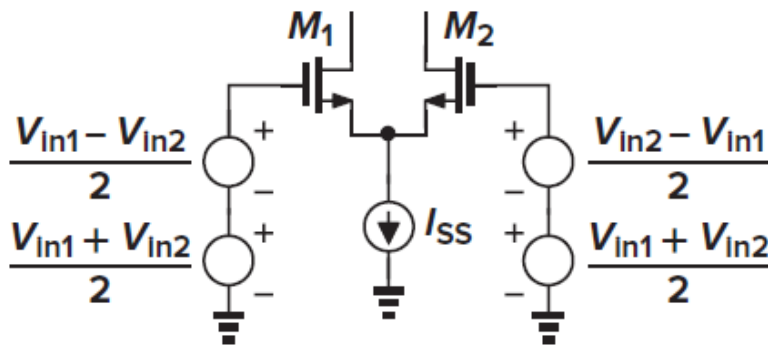
Diff Amp with Arbitrary Inputs



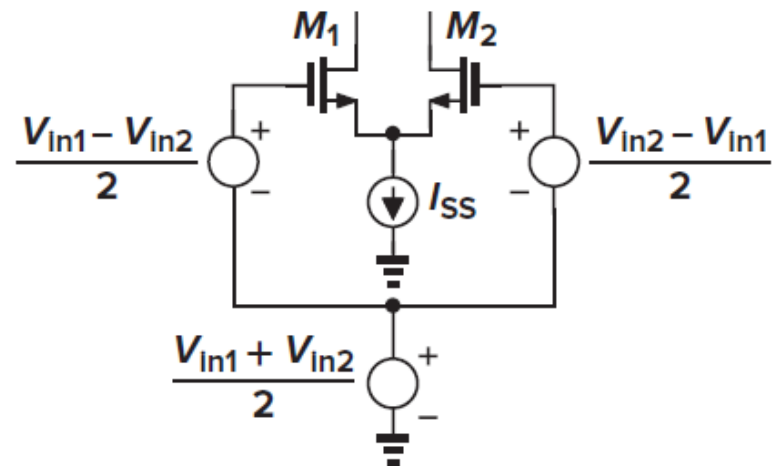
(a)



(b)



(c)



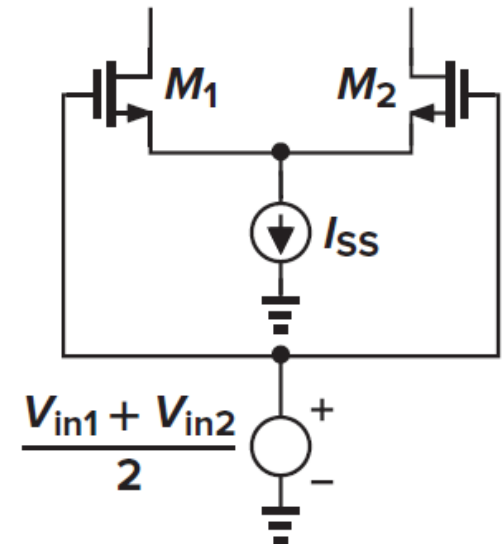
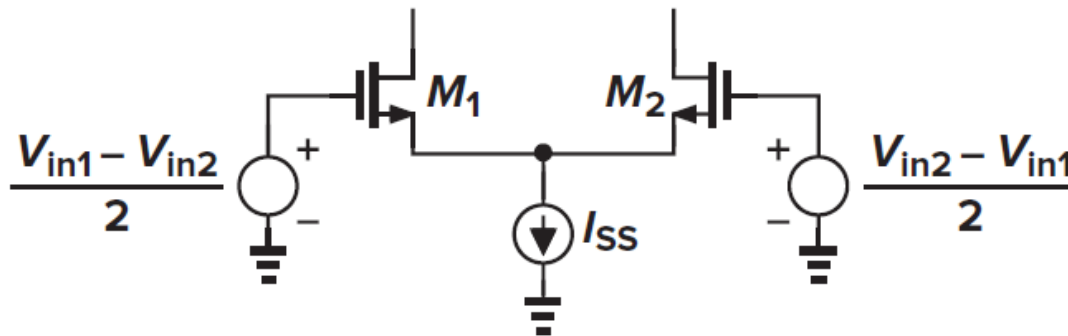
(d)

Separate CM and Diff by Superposition

$$v_{id} = v_{in1} - v_{in2}$$

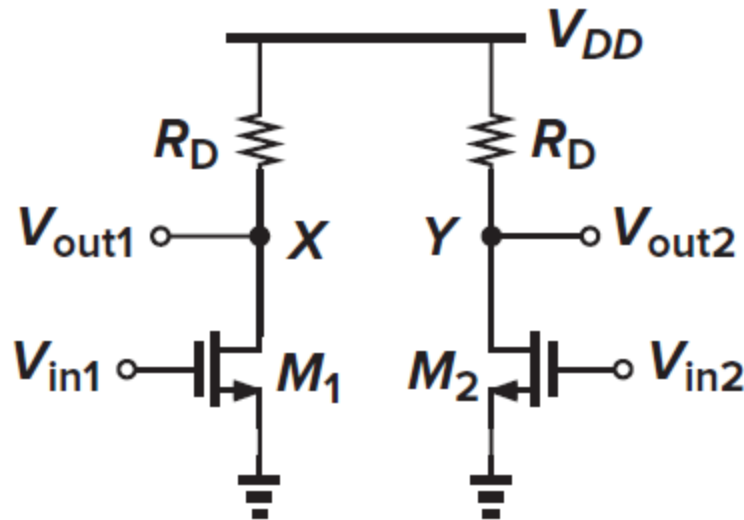
$$v_{id1} = \frac{v_{id}}{2} \quad \text{and} \quad v_{id2} = -\frac{v_{id}}{2}$$

$$v_{iCM} = \frac{v_{in1} + v_{in2}}{2}$$



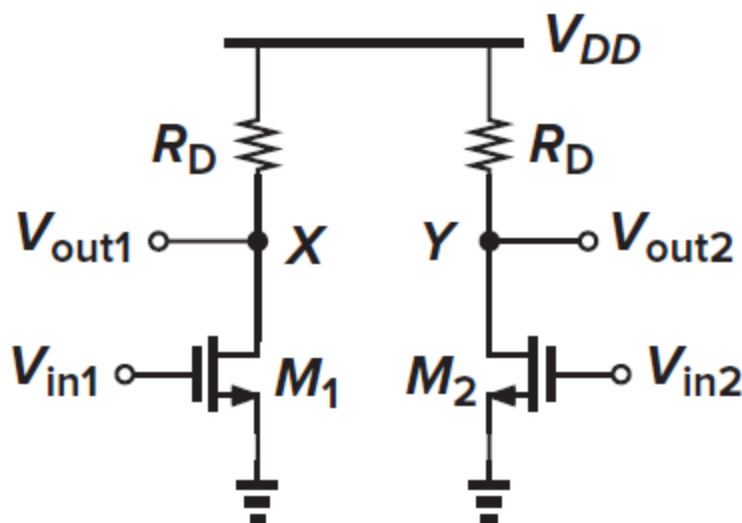
“Pseudo” Diff Amp Analysis

- A. Small signal analysis
 - 1. Diff small signal analysis
 - 2. CM small signal analysis
- B. Large signal analysis
 - 1. Diff large signal analysis
 - 2. CM large signal analysis



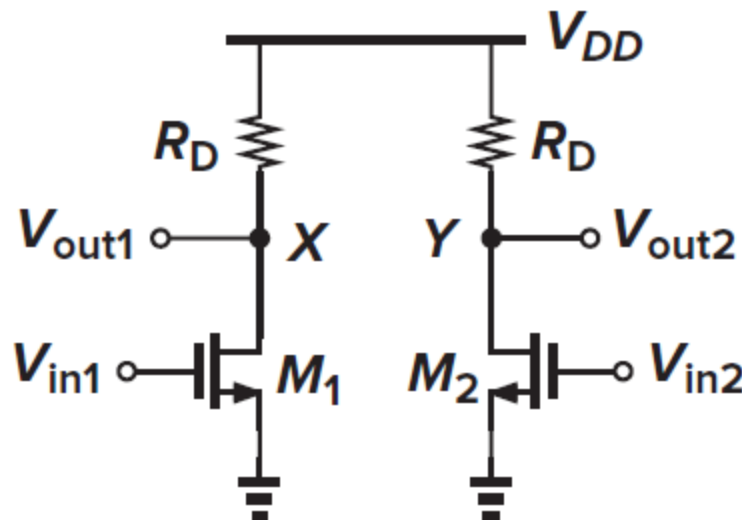
A1. Diff Small Signal Analysis

- ❑ $v_{in1} = \frac{v_{id}}{2}$ and $v_{in2} = -\frac{v_{id}}{2}$
- ❑ $v_{out1} = -g_m R_D \left(\frac{v_{id}}{2} \right)$ and $v_{out2} = -g_m R_D \left(-\frac{v_{id}}{2} \right)$
- ❑ $v_{od} = v_{out1} - v_{out2} = -g_m R_D (v_{id})$
- ❑ $A_{vd} = \frac{v_{od}}{v_{id}} = -g_m R_D = \frac{v_{out1}}{v_{in1}} = \frac{v_{out2}}{v_{in2}} = A_{v,SE}$



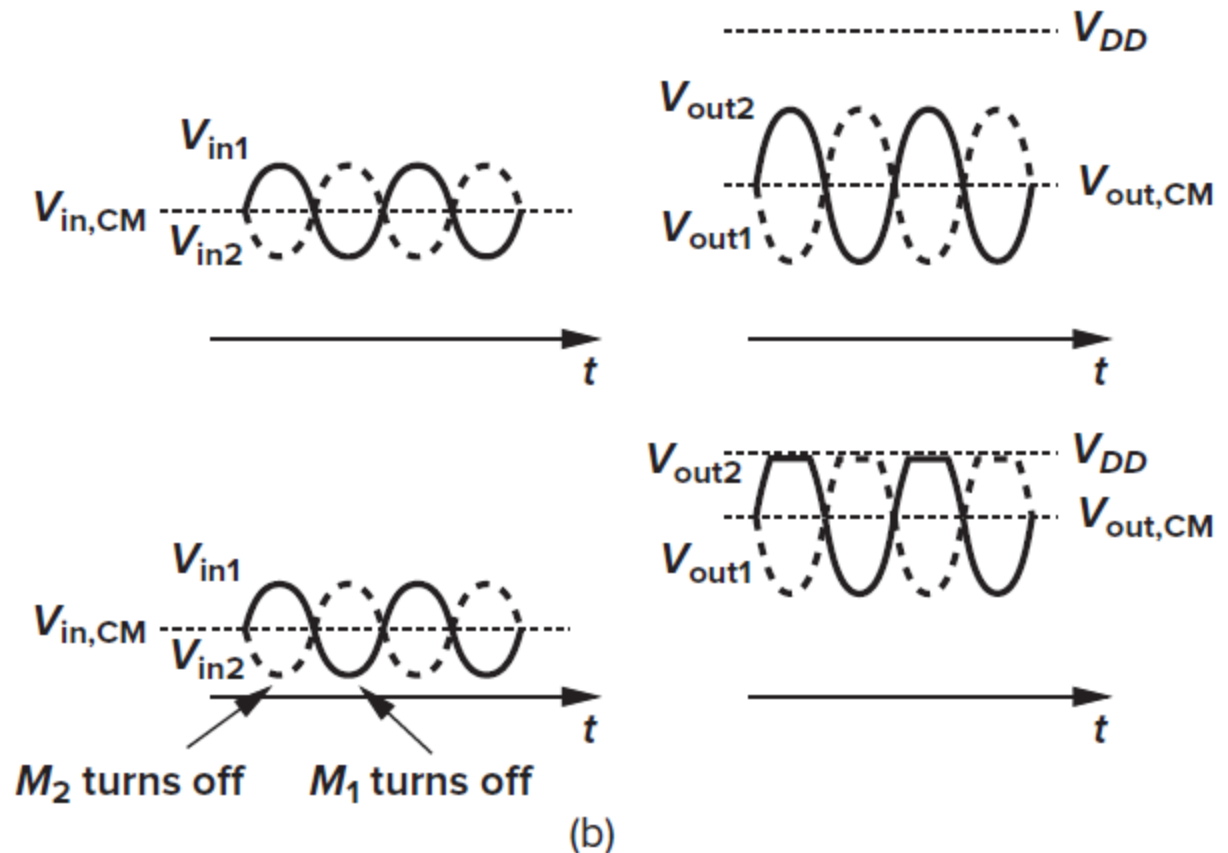
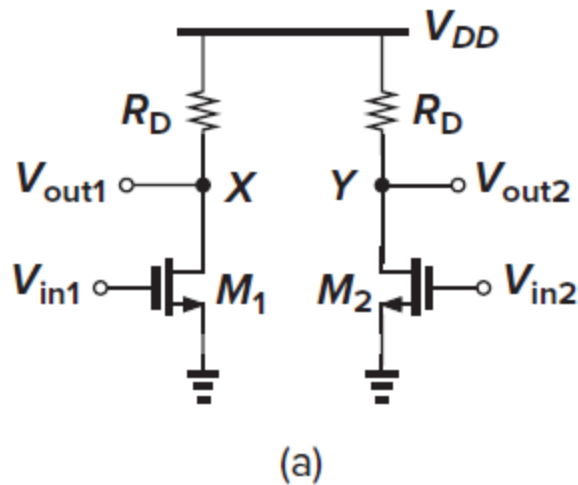
A2. CM Small Signal Analysis

- ❑ $v_{in1} = v_{iCM}$ and $v_{in2} = v_{iCM}$
- ❑ $v_{out1} = -g_m R_D (v_{iCM})$ and $v_{out2} = -g_m R_D (v_{iCM})$
- ❑ $v_{oCM} = \frac{v_{out1} + v_{out2}}{2} = -g_m R_D (v_{iCM})$
- ❑ $A_{vCM} = \frac{v_{oCM}}{v_{iCM}} = -g_m R_D = A_{vd} \rightarrow A_{vd}/A_{vCM} = 1$
- ❑ The output CM level is sensitive to the input CM level
- ❑ CM input is not “completely” rejected



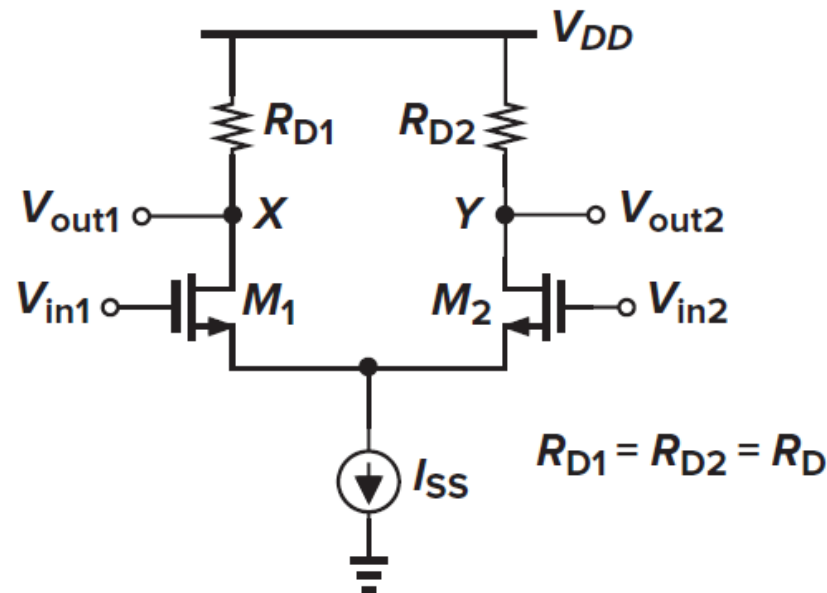
B2. CM Large Signal Analysis

- ❑ The transistors are biased by the input CM level
- ❑ The OP point is sensitive to the input CM level



“True” Diff Amp (Diff Pair) Analysis

- A. Small signal analysis
 - 1. Diff small signal analysis
 - 2. CM small signal analysis
- B. Large signal analysis
 - 1. Diff large signal analysis
 - 2. CM large signal analysis



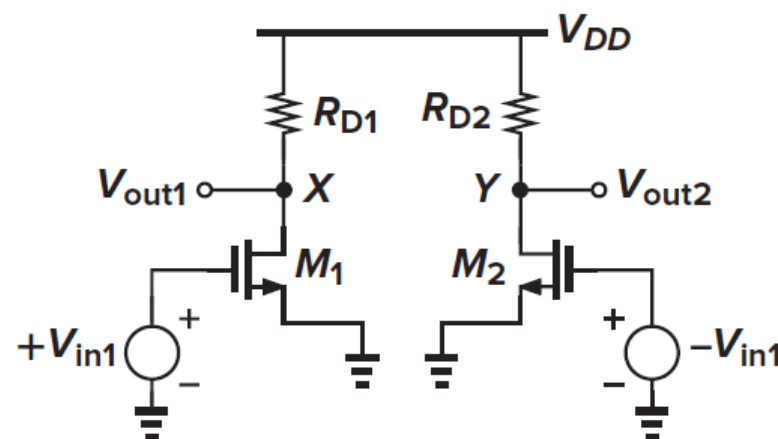
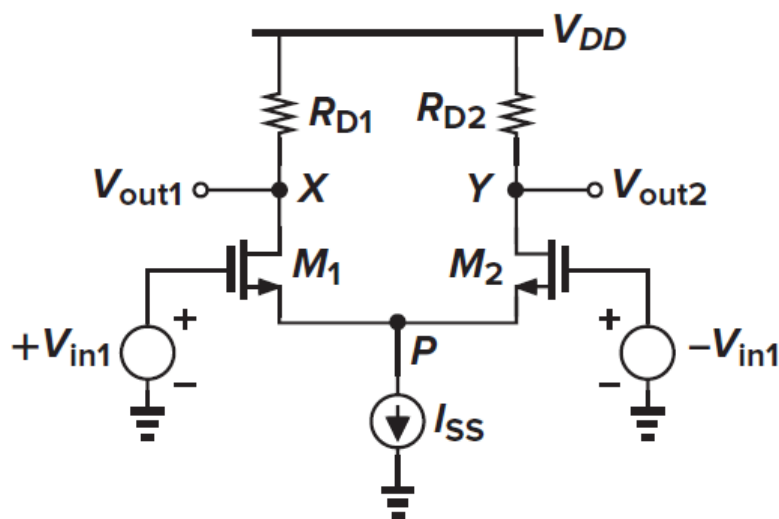
A1. Diff Small Signal Analysis

❑ METHOD #1: Half-Circuit Principle (exploit symmetry)

❑ $v_{out1} = -g_m R_D \left(\frac{v_{id}}{2} \right)$ and $v_{out2} = -g_m R_D \left(-\frac{v_{id}}{2} \right)$

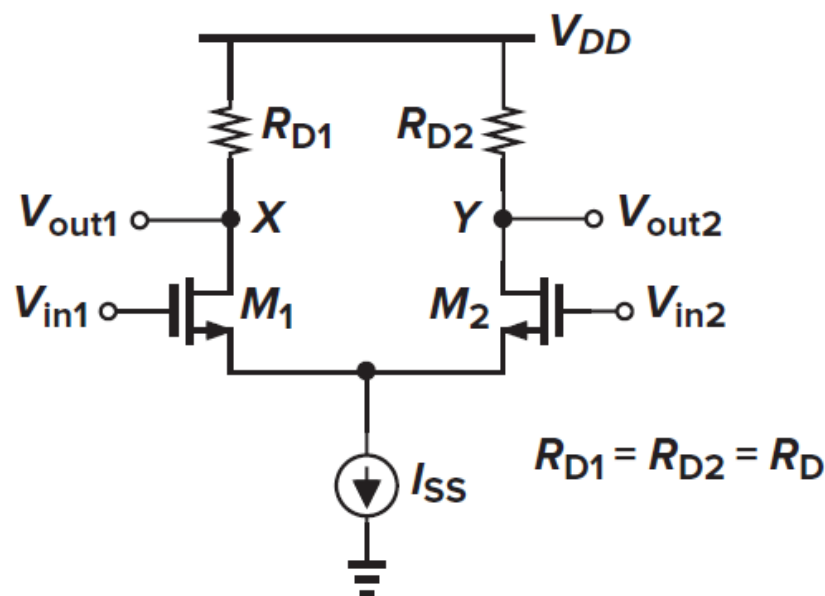
❑ $v_{od} = v_{out1} - v_{out2} = -g_m R_D (v_{id})$

❑ $A_{vd} = \frac{v_{od}}{v_{id}} = -g_m R_D = \frac{v_{out1}}{v_{in1}} = \frac{v_{out2}}{v_{in2}} = A_{v,half-circuit} = A_{v,SE}$



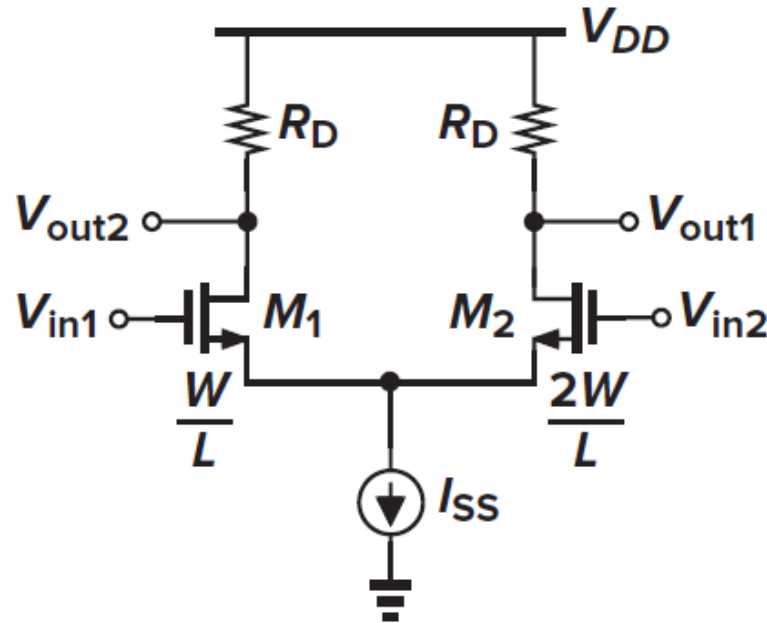
A1. Diff Small Signal Analysis

- ❑ METHOD #2: **Super-position (H.W.)**
- ❑ For v_{in1} to v_{out1} : CS (M1) degenerated by M2
- ❑ For v_{in1} to v_{out2} : CD (M1) + CG (M2)
- ❑ Similarly for v_{in2}
- ❑ Same result as half-circuit principle (H.W.)
- ❑ Lengthy analysis! (but may be necessary if not symmetric)



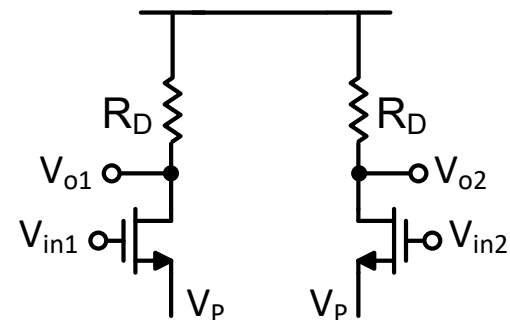
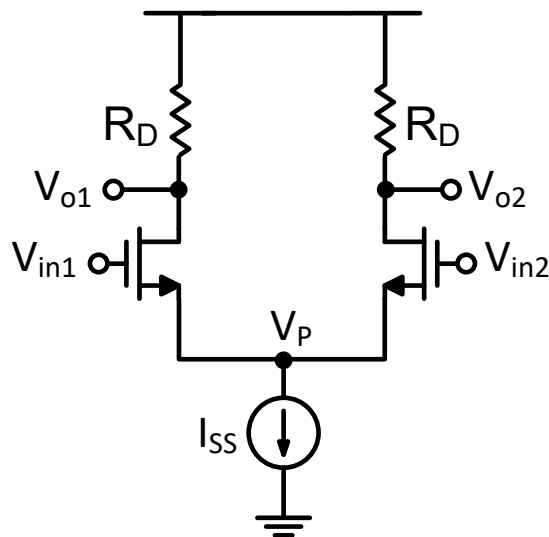
A1. Diff Small Signal Analysis

- ❑ Half-circuit principle does not work in this case



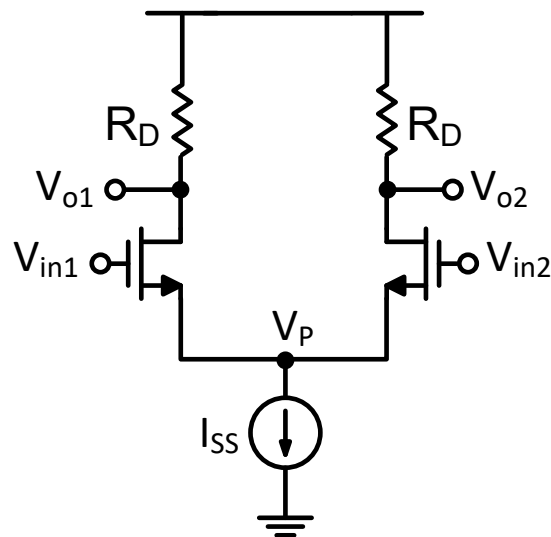
A2. CM Small Signal Analysis

- ❑ METHOD #1: Half-Circuit Principle (exploit symmetry)
- ❑ $v_{out1} = 0$ and $v_{out2} = 0$
- ❑ $v_{oCM} = \frac{v_{out1} + v_{out2}}{2} = 0$
- ❑ $A_{vCM} = \frac{v_{oCM}}{v_{iCM}} = 0 = A_{v, half-circuit} \rightarrow A_{vd}/A_{vCM} \rightarrow \infty$
- ❑ The output CM level is NOT sensitive to the input CM level
- ❑ CM input is “completely” rejected (compare with pseudo diff amp)



A2. CM Small Signal Analysis

- ❑ METHOD #2: **Super-position (H.W.)**
- ❑ For v_{in1} to v_{out1} : CS (M1) degenerated by M2
- ❑ For v_{in1} to v_{out2} : CD (M1) + CG (M2)
- ❑ Similarly for v_{in2}
- ❑ Same result as half-circuit principle (H.W.)
- ❑ Lengthy analysis! (but may be necessary if not symmetric)



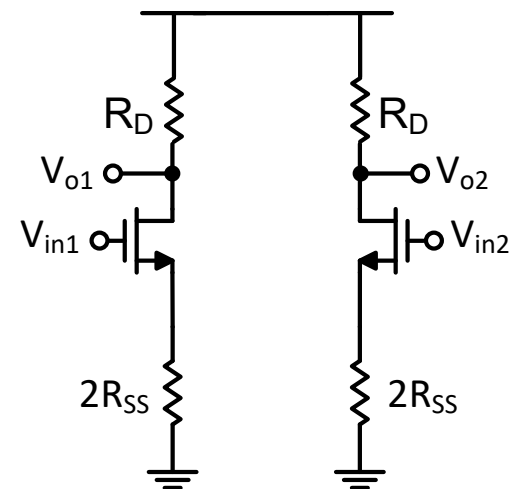
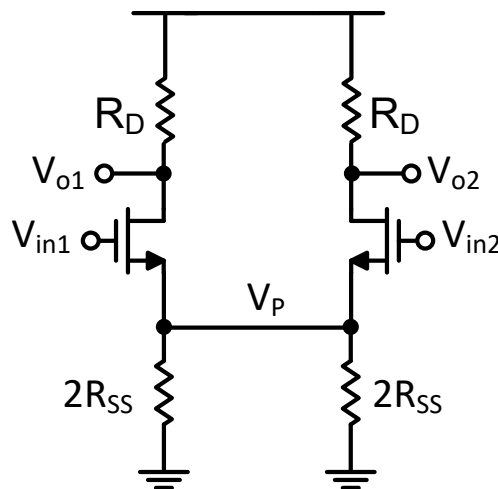
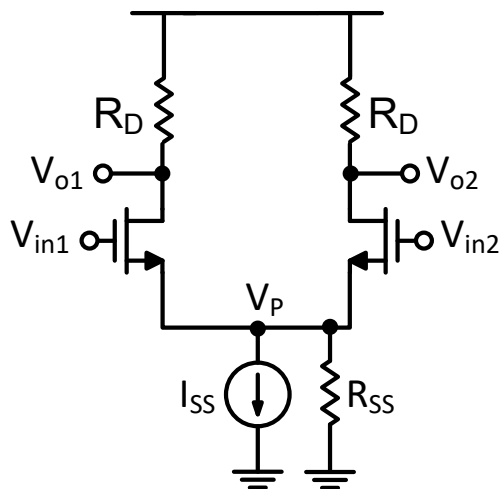
A2. CM Small Signal Analysis

❑ METHOD #1: Half-Circuit Principle (exploit symmetry)

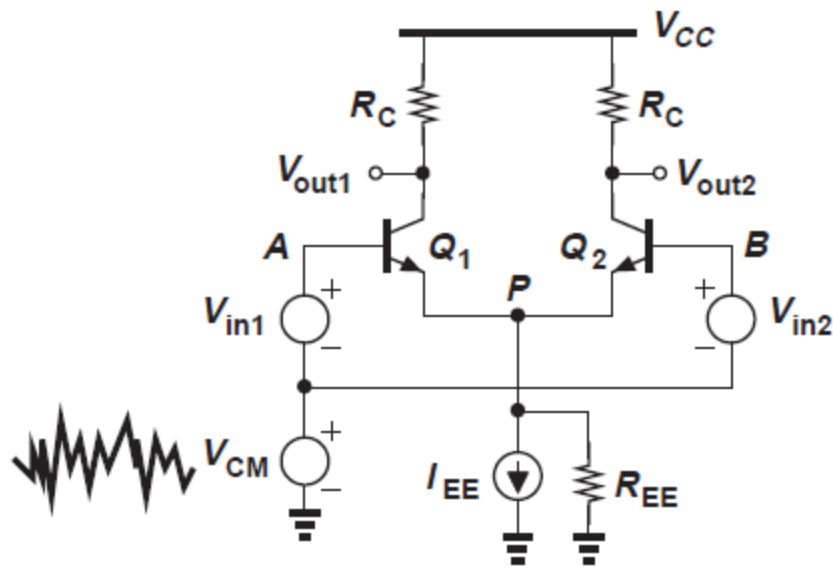
$$\square A_{vCM} = \frac{v_{oCM}}{v_{iCM}} = \frac{-g_m R_D}{1 + 2(g_m + g_{mb})R_{SS}} = A_{v, half-circuit}$$

$$\square A_{vd}/A_{vCM} \approx 2(g_m + g_{mb})R_{SS} \gg 1$$

❑ CM input is “partially” rejected (compare with pseudo diff amp)

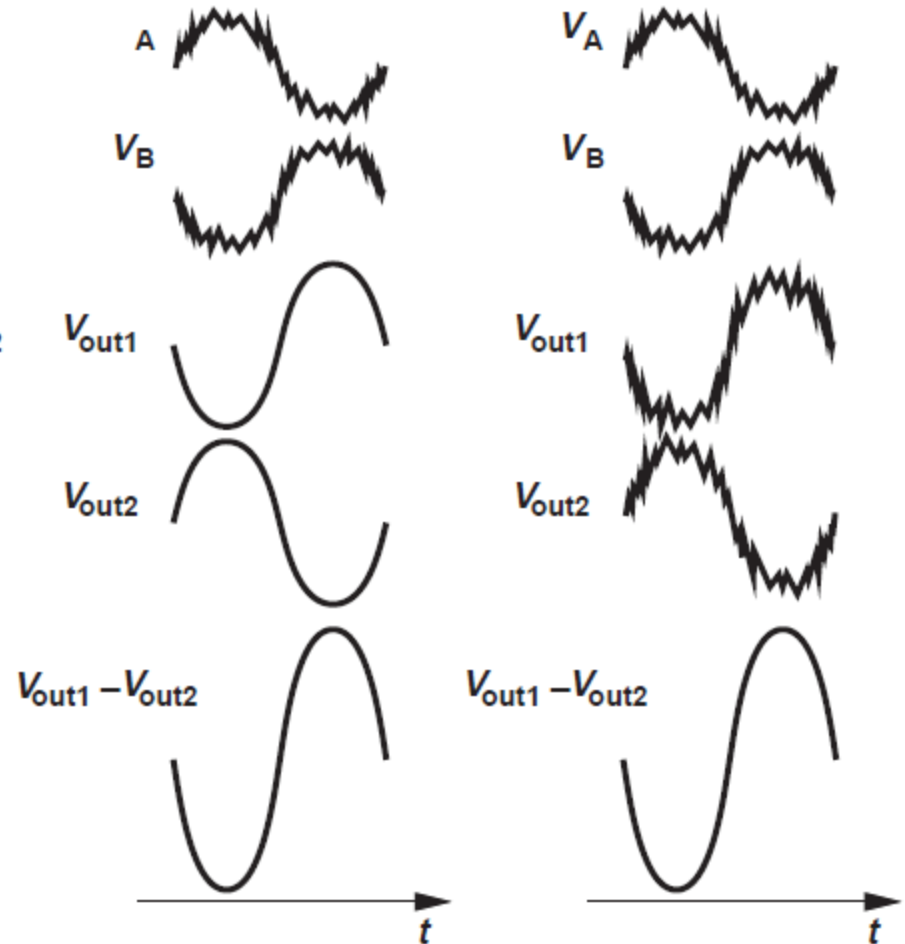


A2. CM Small Signal Analysis



$R_{EE} \rightarrow \infty$

Finite R_{EE}

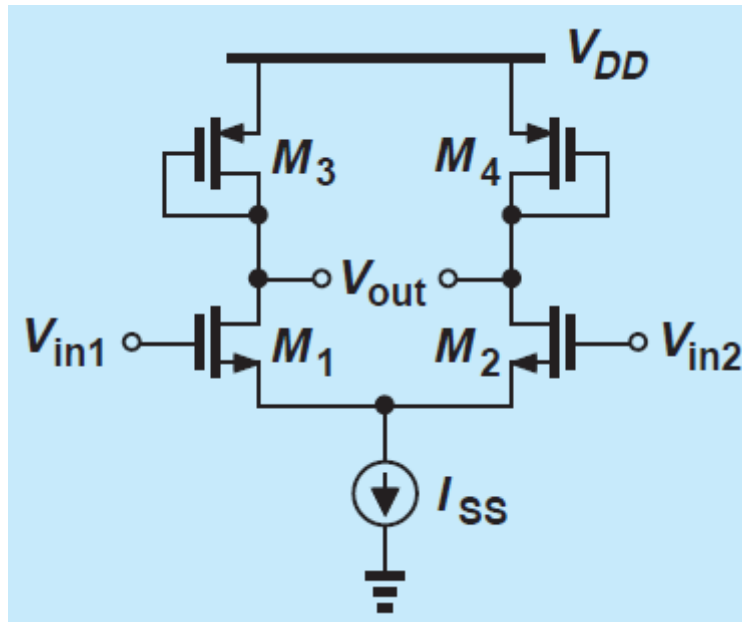


Recapping Small Signal Analysis

	Pseudo Diff Amp	Diff Pair (w/ ideal CS)	Diff Pair (w/ R_{SS})
A_{vd}	$-g_m R_D$	$-g_m R_D$	$-g_m R_D$
A_{vCM}	$-g_m R_D$	0	$\frac{-g_m R_D}{1 + 2(g_m + g_{mb})R_{SS}}$
A_{vd}/A_{vCM}	1	∞	$2(g_m + g_{mb})R_{SS} \gg 1$

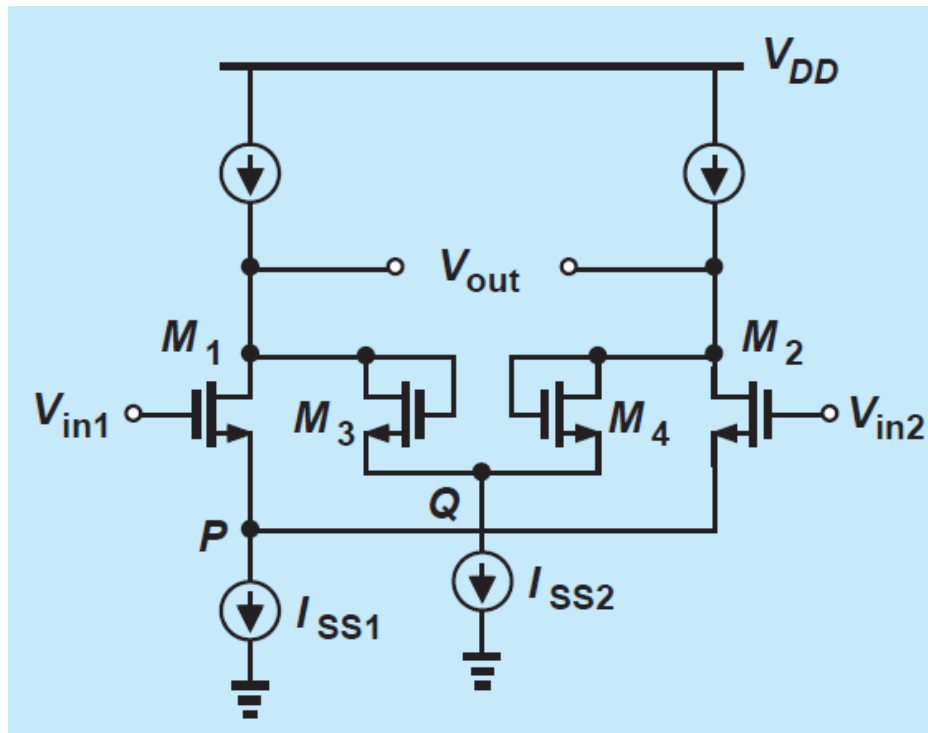
Bonus Question

- Assume symmetry and neglect body effect. Calculate A_{vd} .



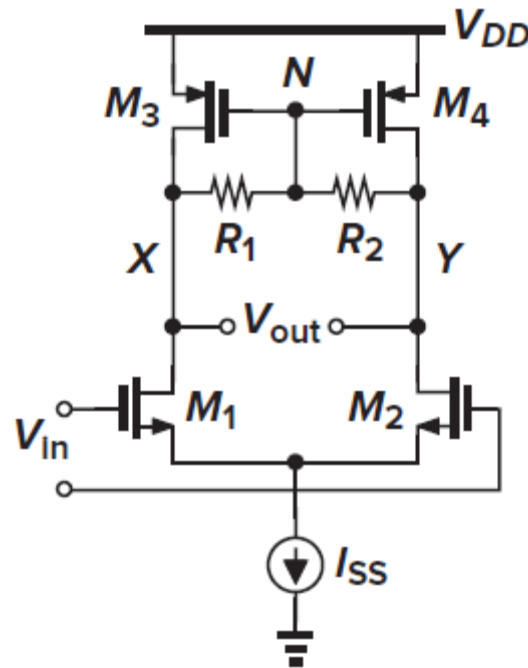
Bonus Question

- Assume symmetry and neglect body effect. Calculate A_{vd} .



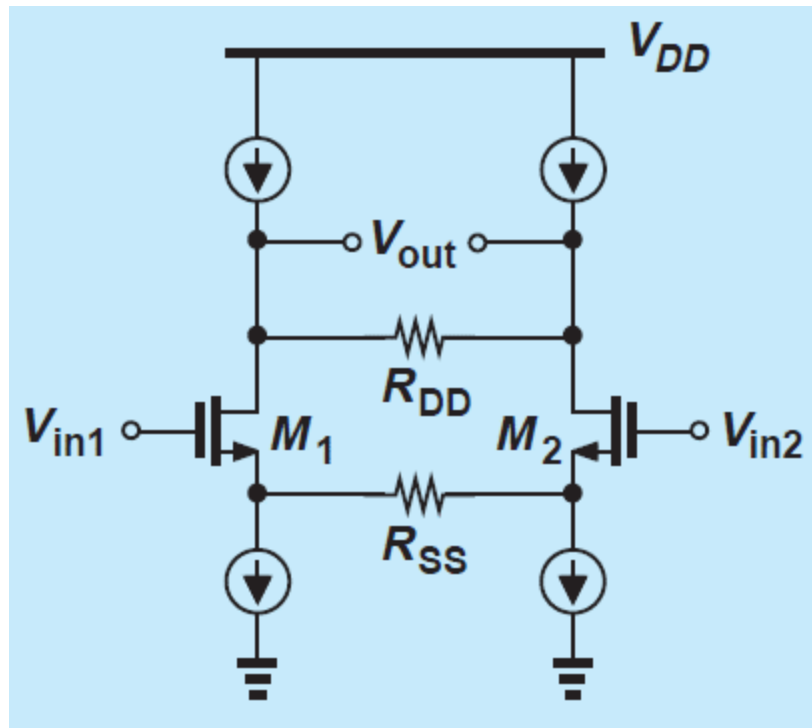
Bonus Question

- Assume symmetry and neglect Channel Length Modulation (CLM) (ro). Calculate A_{vd} .



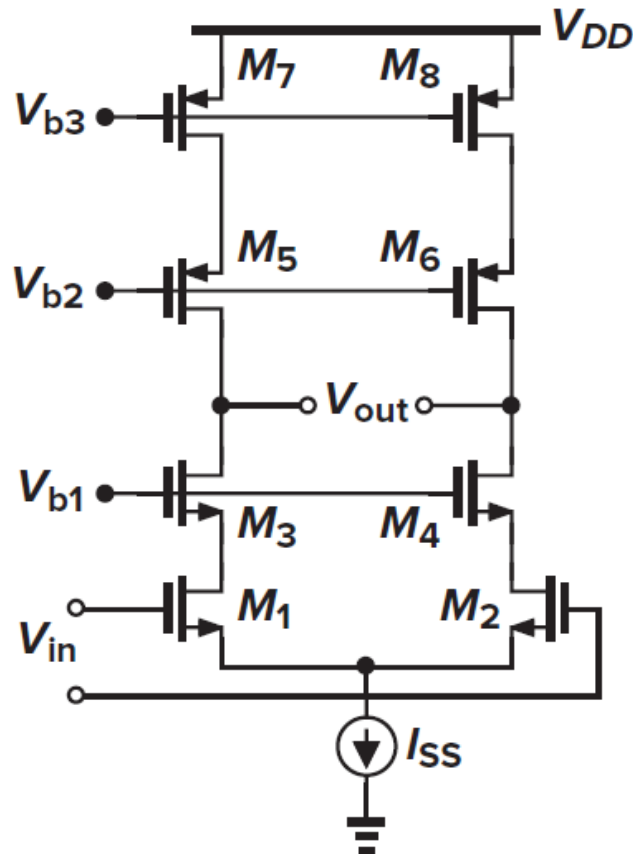
Bonus Question

- Assume symmetry, assume R_{SS} is large, and neglect CLM (ro). Calculate A_{vd} .

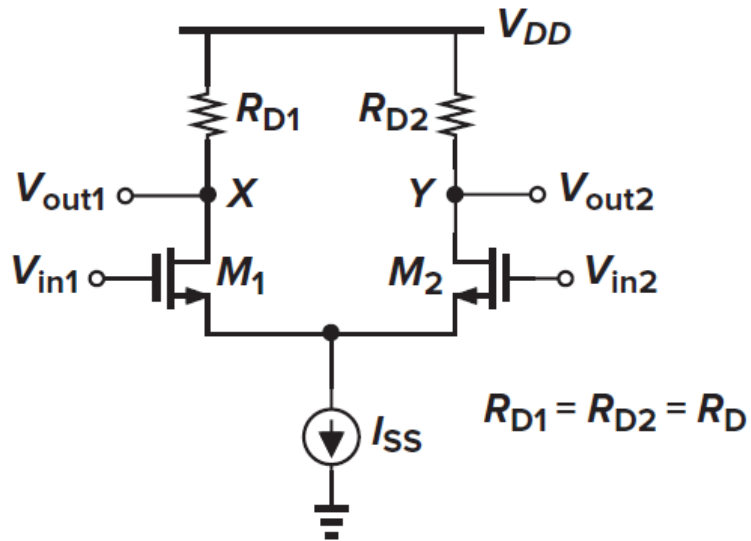


Bonus Question

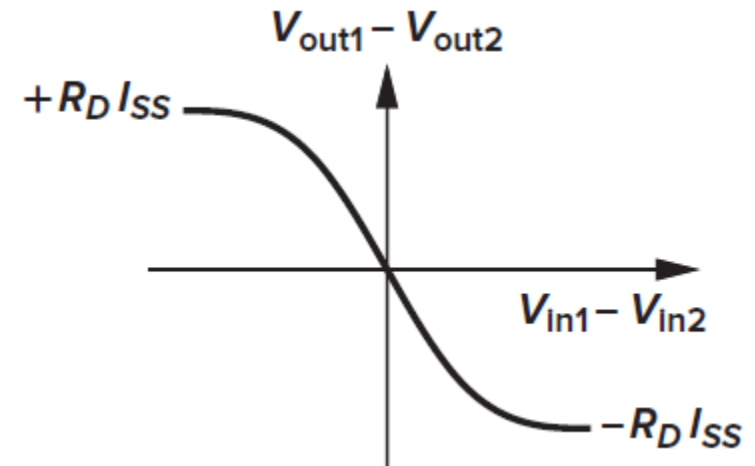
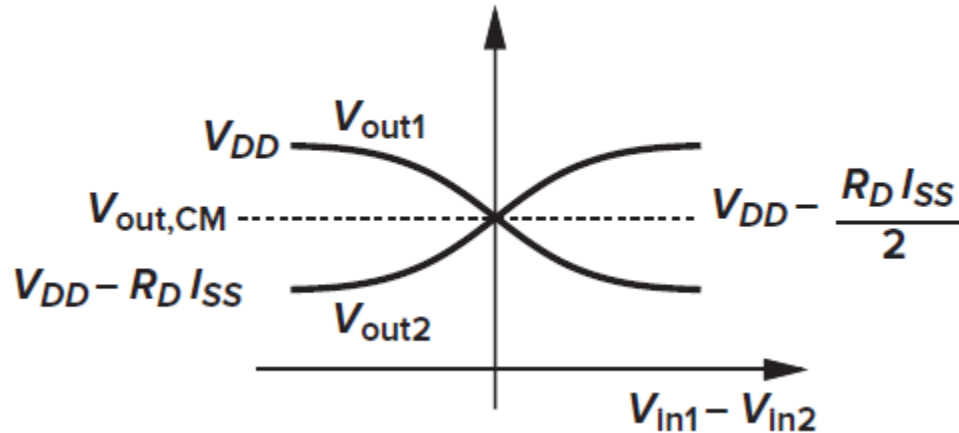
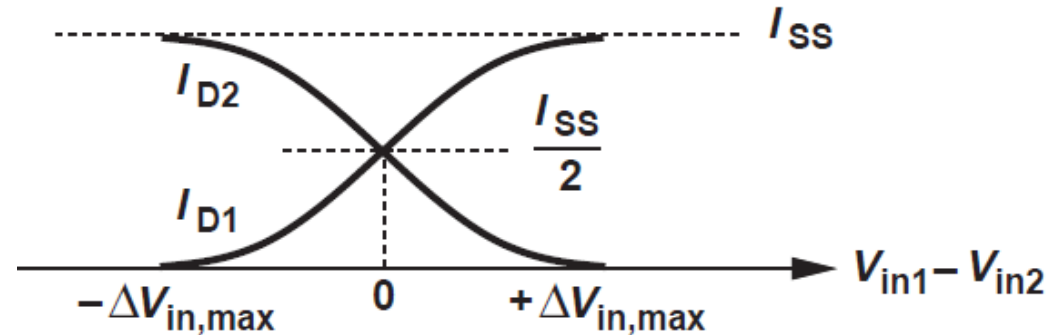
- Assume symmetry, and assume all transistors have the same g_m and r_o . Calculate A_{vd} .



B1. Diff Large Signal Analysis



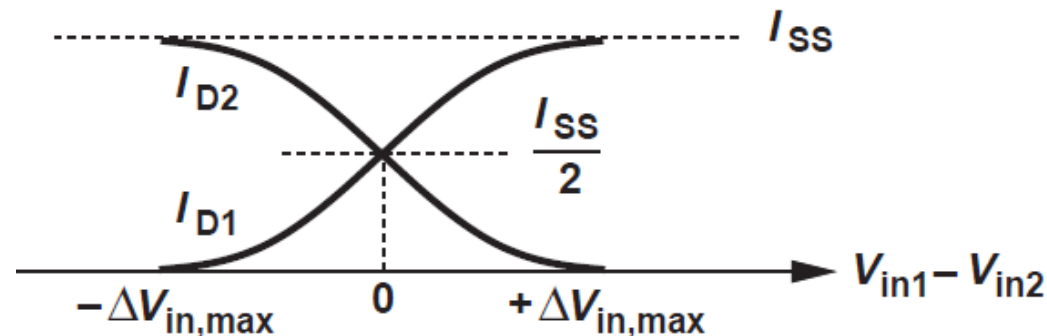
$$\Delta V_{in,max} = \sqrt{2}V_{ov,eq}$$



B1. Diff Large Signal Analysis

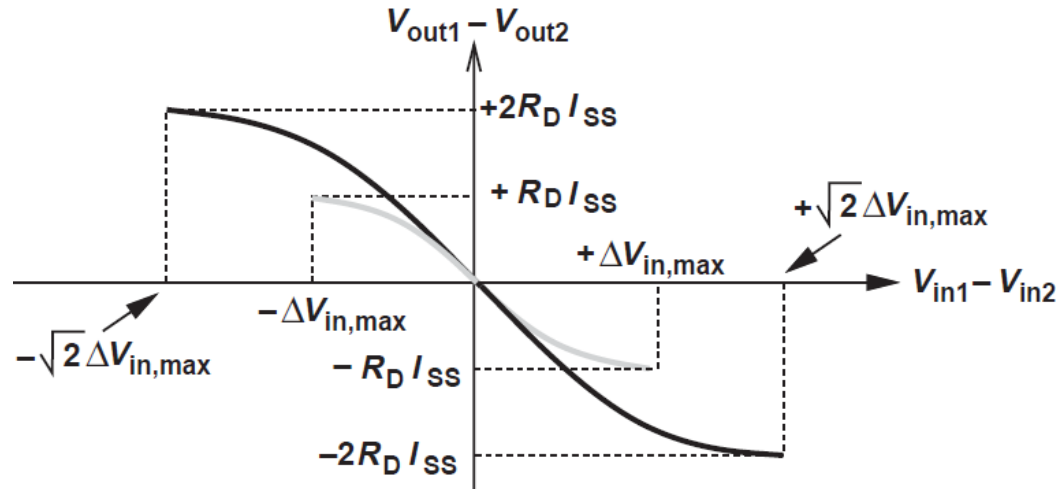
- Analysis using square law (H.W., see Razavi Section 4.2.2)

$$I_{D1} = \frac{I_{SS}}{2} + \frac{V_{id}}{4} \sqrt{\mu C_{ox} \frac{W}{L} \left(4I_{SS} - \mu C_{ox} \frac{W}{L} V_{id}^2 \right)}$$
$$I_{D2} = \frac{I_{SS}}{2} - \frac{V_{id}}{4} \sqrt{\mu C_{ox} \frac{W}{L} \left(4I_{SS} - \mu C_{ox} \frac{W}{L} V_{id}^2 \right)}$$
$$\Delta V_{in,max} = \sqrt{2} V_{ov,eq}$$

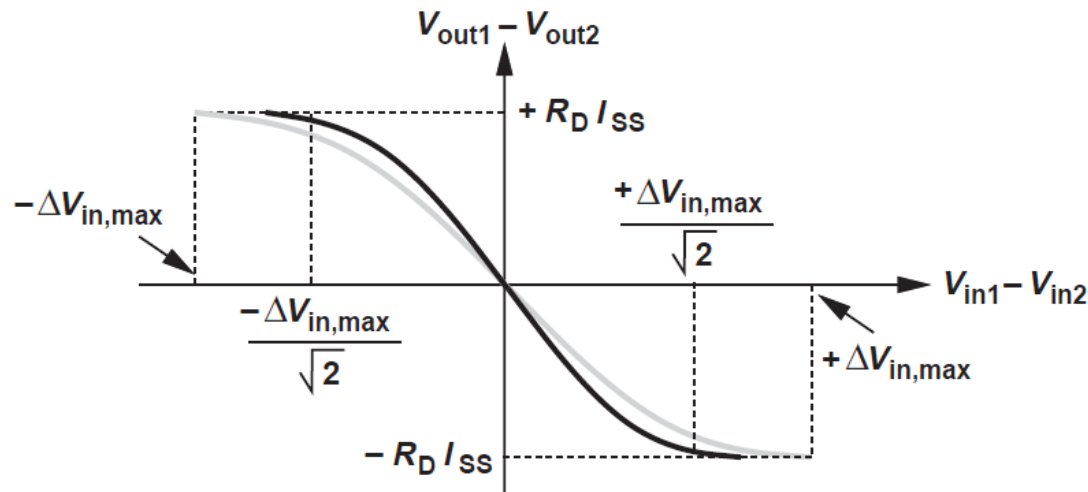


B1. Diff Large Signal Analysis

- If tail current is doubled



- If aspect ratio is doubled

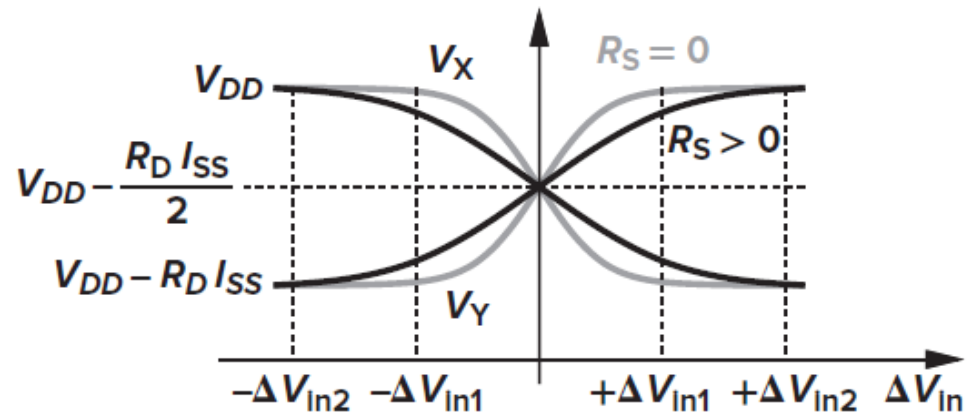
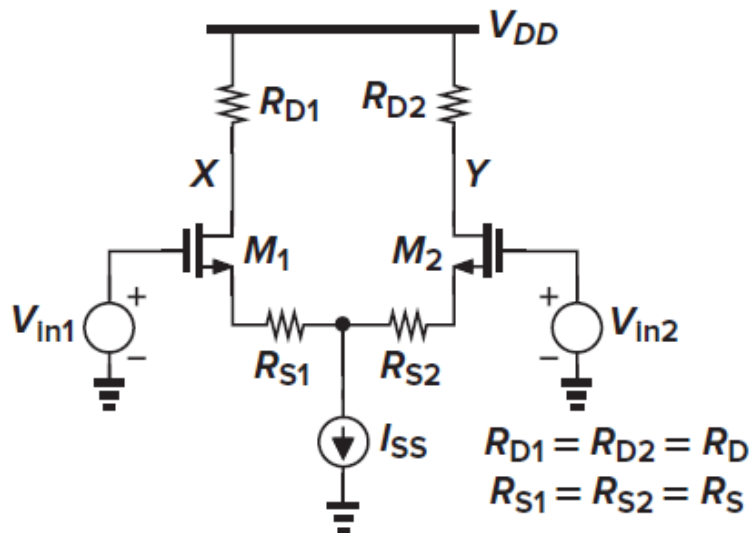


B1. Diff Large Signal Analysis

- Degeneration extends linear range

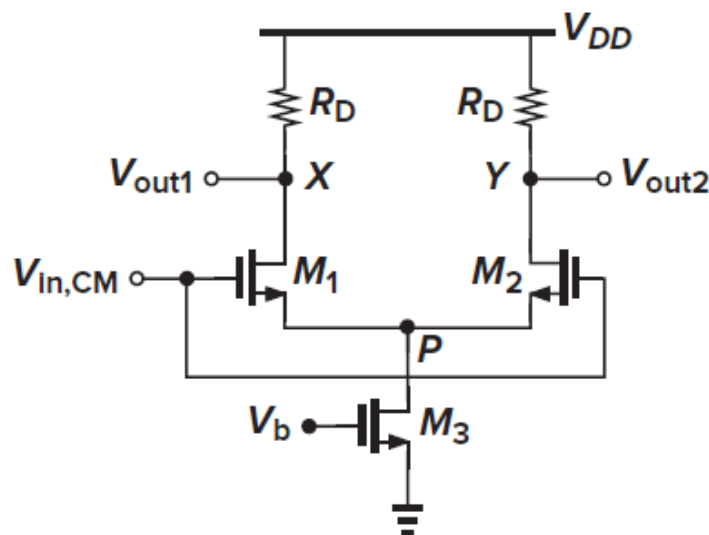
$$\Delta V_{in2} = \Delta V_{in1} + I_{SS} R_S$$

- But headroom is reduced



B2. CM Large Signal Analysis

- ❑ The tail current source suppresses the effect of input CM level variations on OP point of M1 and M2 and output CM level
 - But all transistors must be in saturation



- ❑ M3 in sat

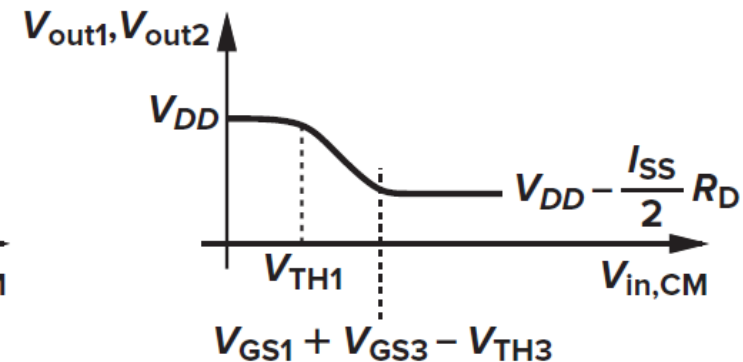
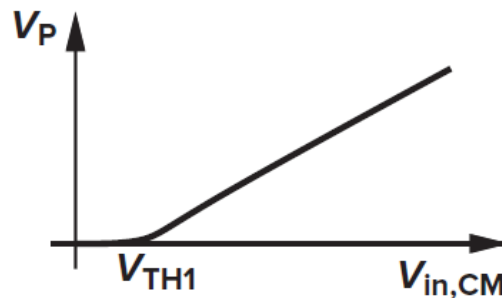
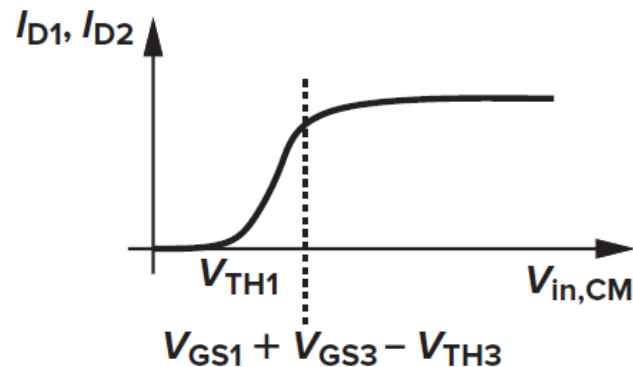
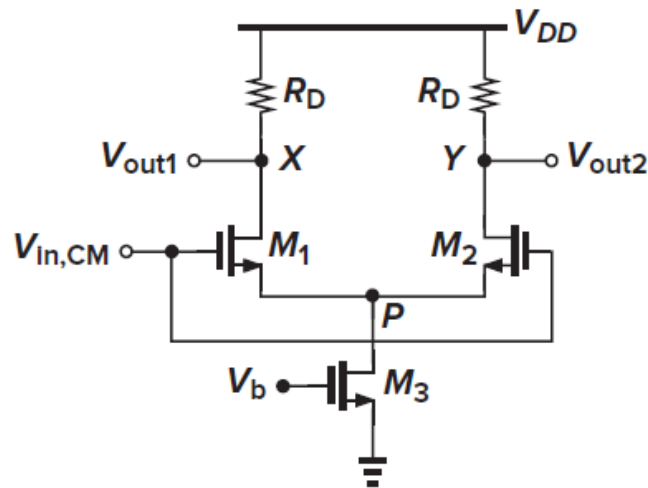
$$V_{inCM} \geq V_{TH} + V_{ov1} + V_{ov3}$$

- ❑ M1,2 in sat

$$V_{inCM} \leq V_{DD} - \frac{I_{SS}}{2} R_D + V_{TH}$$

B2. CM Large Signal Analysis

- ❑ The tail current source suppresses the effect of input CM level variations on OP point of M1 and M2 and output CM level
 - But all transistors must be in saturation

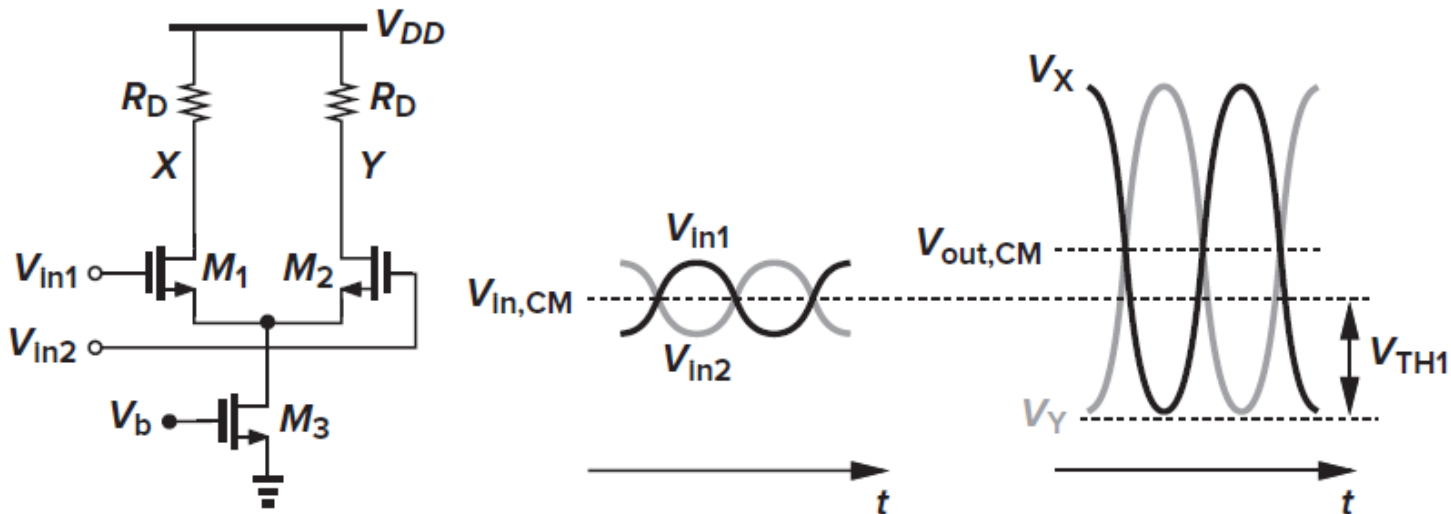


Max Allowable Signal Swing

- ❑ Max output is V_{DD} , min output is set by keeping M1,2 in sat

$$\text{max pk2pk swing} = 2 \times (V_{DD} - (V_{inCM} - V_{TH}))$$
- ❑ If V_{inCM} is set to its min value: $V_{inCM} = V_{TH} + V_{ov1} + V_{ov3}$

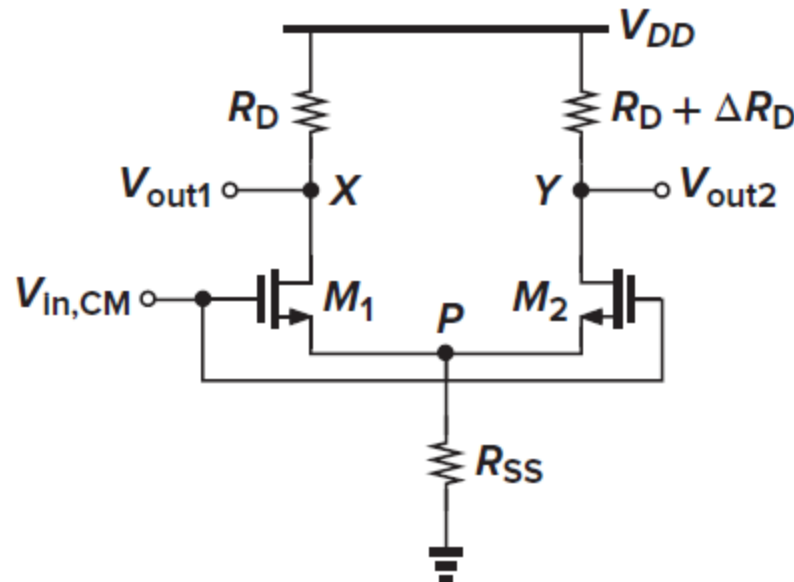
$$\text{max pk2pk swing} = 2 \times (V_{DD} - V_{ov1} - V_{ov3})$$
 - Can be deduced intuitively by noting that M1 and M3 are vertically stacked
- ❑ For SE amp: $\text{max pk2pk swing} = (V_{DD} - V_{ov1})$



Effect of Mismatch (in Load)

- ❑ Most dangerous effect: CM to diff conversion
- ❑ Example #1: Mismatch in load resistance

$$\begin{aligned} A_{v_{CM2d}} &= \frac{v_{od}}{v_{iCM}} = \frac{v_{out1} - v_{out2}}{v_{iCM}} = - \left(\frac{g_m R_D}{1 + 2g_m R_{SS}} - \frac{g_m (R_D + \Delta R_D)}{1 + 2g_m R_{SS}} \right) \\ &= \frac{g_m \Delta R_D}{1 + 2g_m R_{SS}} \approx \frac{\Delta R_D}{2R_{SS}} \end{aligned}$$



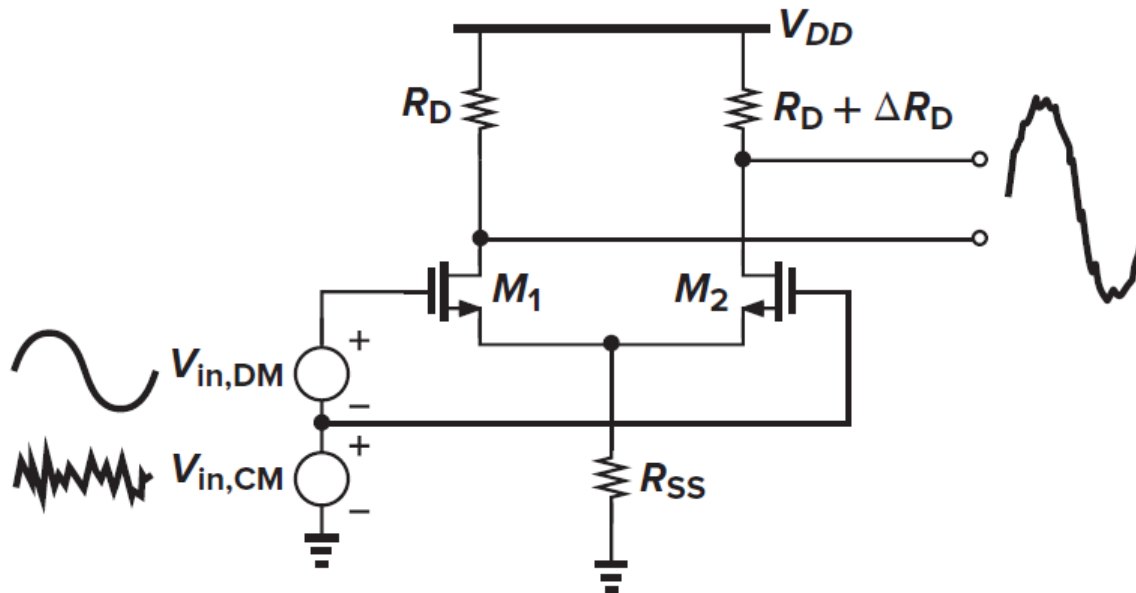
Effect of Mismatch (in Load)

- Example #1: Mismatch in load resistance

$$A_{vCM2d} \approx \frac{\Delta R_D}{2R_{SS}}$$

- Common-mode rejection ration (CMRR) (@low frequency!)

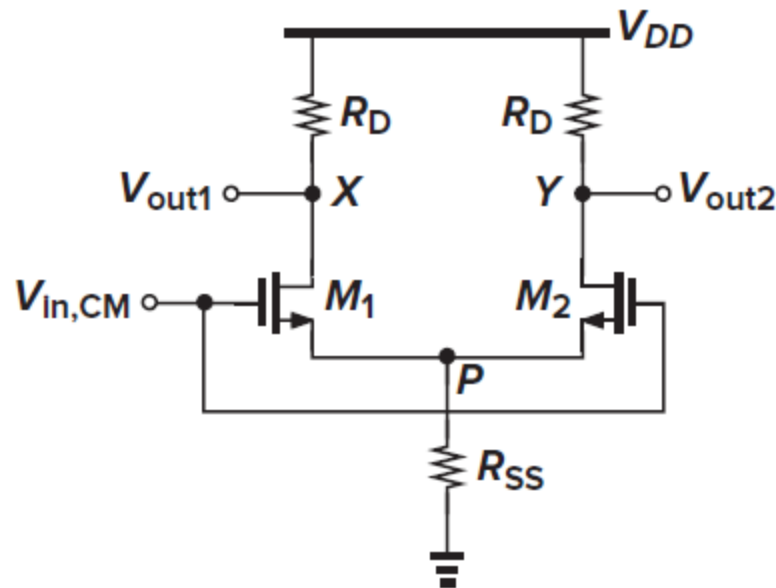
$$CMRR = \frac{A_{vd}}{A_{vCM2d}} \approx 2g_m R_{SS} \frac{R_D}{\Delta R_D}$$



Effect of Mismatch (in Input Pair)

- ❑ Most dangerous effect: CM to diff conversion
- ❑ Example #2: Mismatch in input pair (M1 and M2)

$$\begin{aligned} A_{vCM2d} &= \frac{v_{od}}{v_{iCM}} = \frac{v_{out1} - v_{out2}}{v_{iCM}} = -\frac{g_{m1}R_D}{1 + g_{m1}\left(\frac{1}{g_{m2}} \parallel R_{SS}\right)} + \frac{g_{m2}R_D}{1 + g_{m2}\left(\frac{1}{g_{m1}} \parallel R_{SS}\right)} \\ &= -\frac{\Delta g_m R_D}{1 + (g_{m1} + g_{m2})R_{SS}} \approx -\frac{\Delta g_m R_D}{(g_{m1} + g_{m2})R_{SS}} \end{aligned}$$



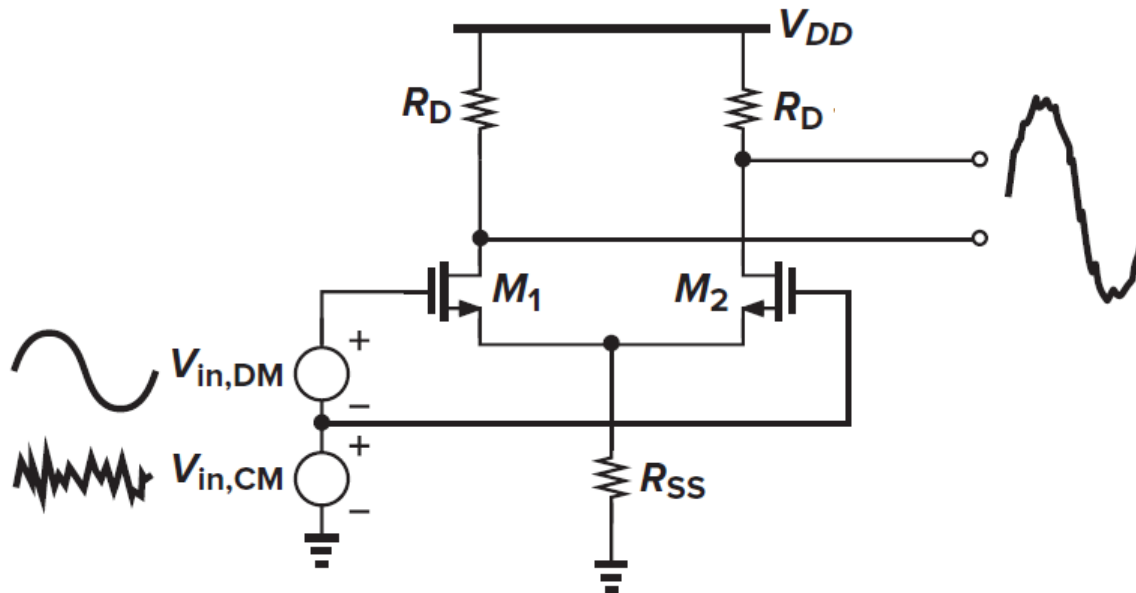
Effect of Mismatch (in Input Pair)

- ❑ Example #2: Mismatch in input pair (M1 and M2)

$$A_{vCM2d} \approx \frac{\Delta g_m R_D}{(g_{m1} + g_{m2}) R_{SS}}$$

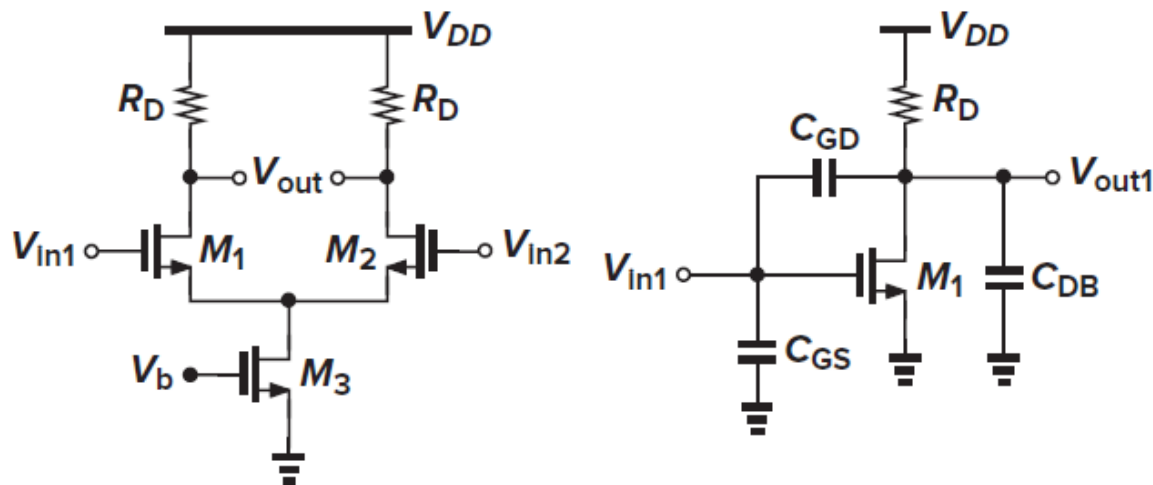
- ❑ Common-mode rejection ration (CMRR) (@low frequency!)

$$CMRR = \frac{A_{vd}}{A_{vCM2d}} \approx 2g_m R_{SS} \frac{g_m}{\Delta g_m}$$



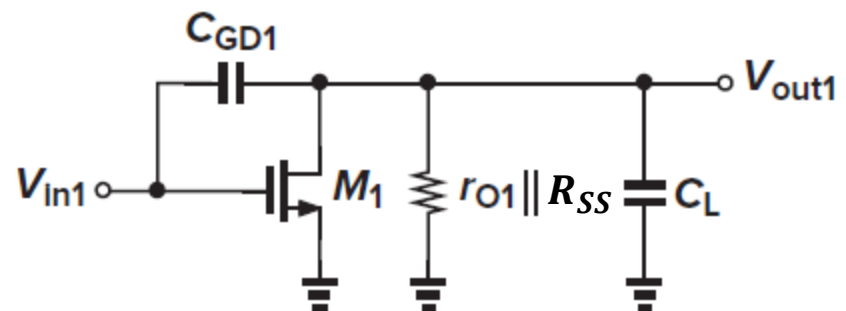
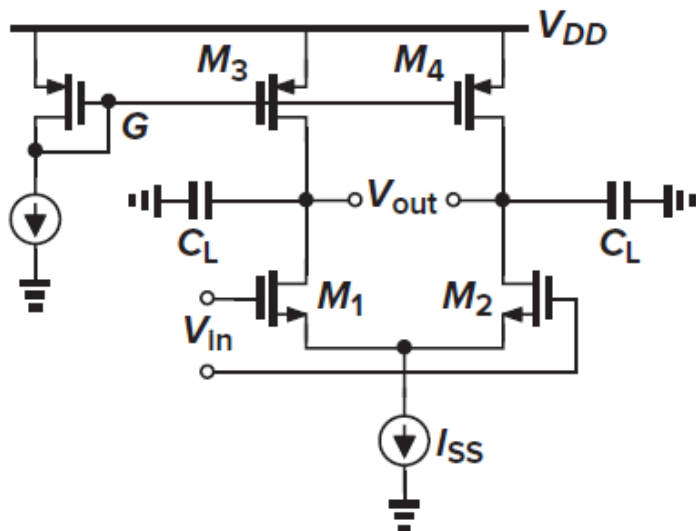
Diff Frequency Response

- ❑ The freq response of the diff amp is itself the freq response of the half-circuit
- ❑ Note that the number of poles/zeros in the diff amp is the same as the number of poles/zeros in the half-circuit
 - The two halves are added, not multiplied
 - Ex: $A(s) = \frac{A_o}{1+\frac{s}{\omega_p}} + \frac{A_o}{1+\frac{s}{\omega_p}} = \frac{2A_o}{1+\frac{s}{\omega_p}}$ (what if there is mismatch?)



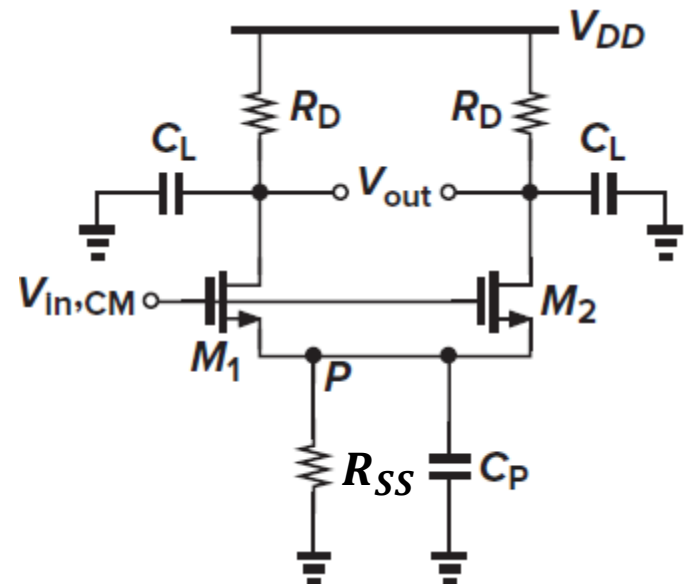
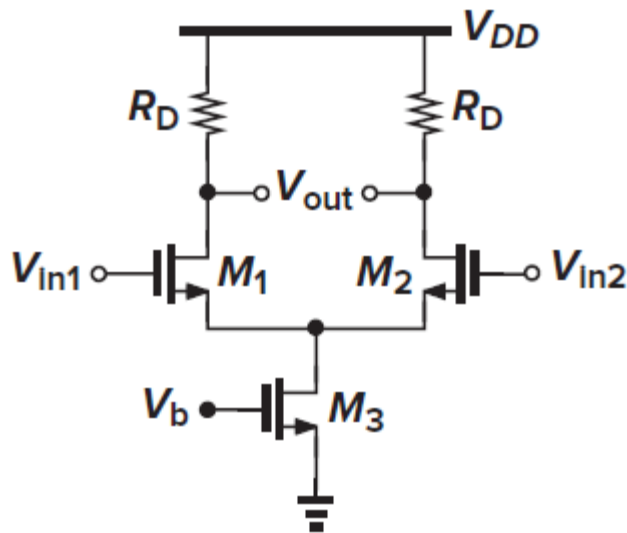
Diff Frequency Response

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CM Frequency Response

- ❑ C_P degrades tail CS impedance at high frequency
- ❑ $C_P \approx C_{db3} + C_{gd3} + C_{sb1} + C_{sb2}$
- ❑ Trade-off between headroom and CMRR
 - M1-M3 are made wide to decrease V_{ov} and increase headroom
 - But C_P increases, and degrades CMRR

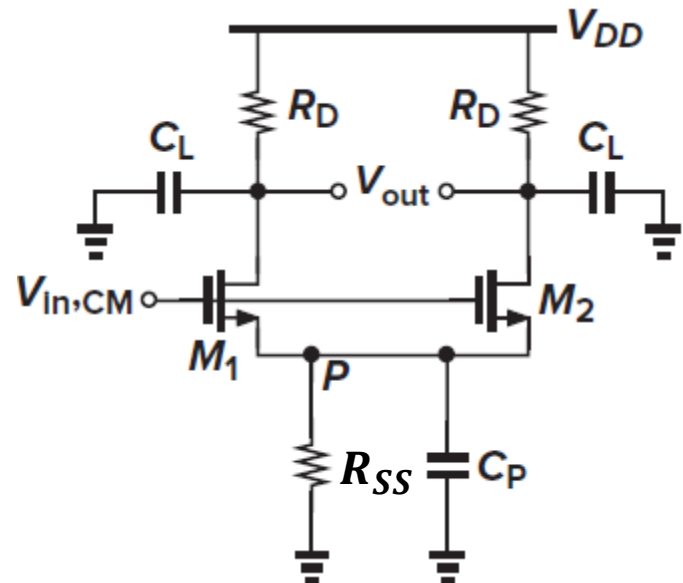
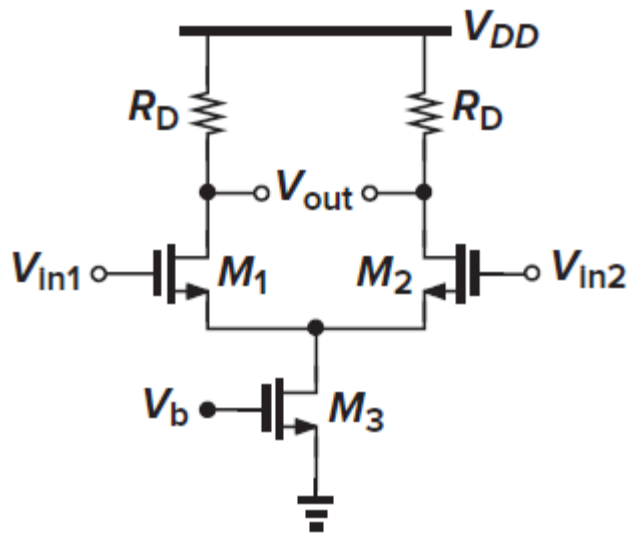


CM Frequency Response

- ❑ Mismatch in input pair (M1 and M2)

@Low frequency: $A_{vCM2d} \approx \frac{\Delta g_m R_D}{1 + (g_{m1} + g_{m2}) R_{SS}}$

@High frequency: $A_{vCM2d} \approx \frac{\Delta g_m \left(R_D // \frac{1}{sC_L} \right)}{1 + (g_{m1} + g_{m2}) \left(R_{SS} // \frac{1}{sC_P} \right)}$

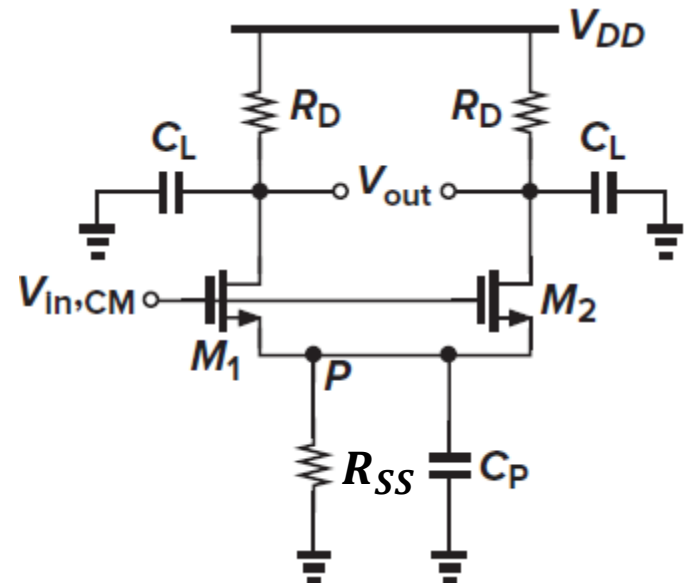
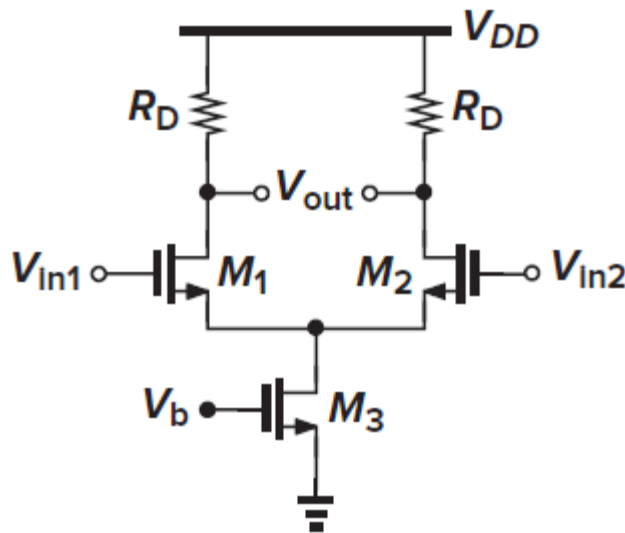


CM Frequency Response

❑ Mismatch in input pair (M1 and M2)

@Low frequency: $CMRR = \frac{A_{vd}}{A_{vCM2d}} \approx (1 + 2g_m R_{SS}) \frac{g_m}{\Delta g_m}$

@High frequency: $CMRR = \frac{A_{vd}(s)}{A_{vCM2d}(s)} \approx \left[1 + 2g_m \left(R_{SS} // \frac{1}{sC_P} \right) \right] \frac{g_m}{\Delta g_m}$



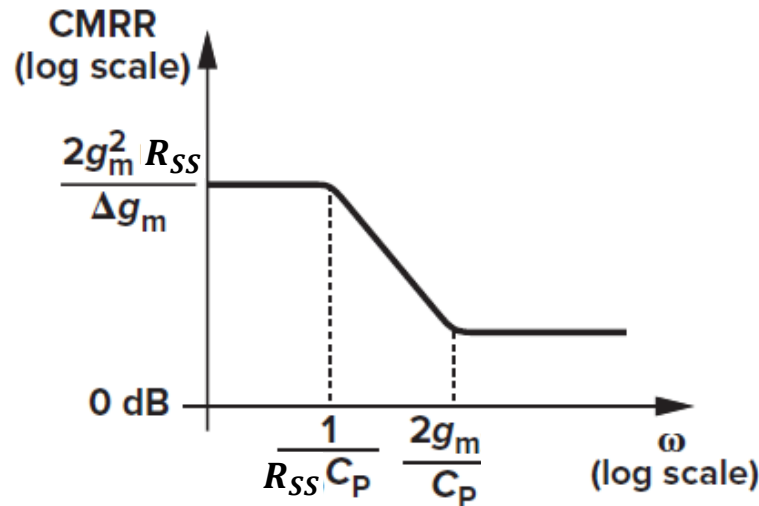
CM Frequency Response

- ❑ Mismatch in input pair (M1 and M2)

$$CMRR = \frac{A_{vd}(s)}{A_{vCM2d}(s)} \approx \left[1 + 2g_m \left(R_{SS} // \frac{1}{sC_P} \right) \right] \frac{g_m}{\Delta g_m}$$

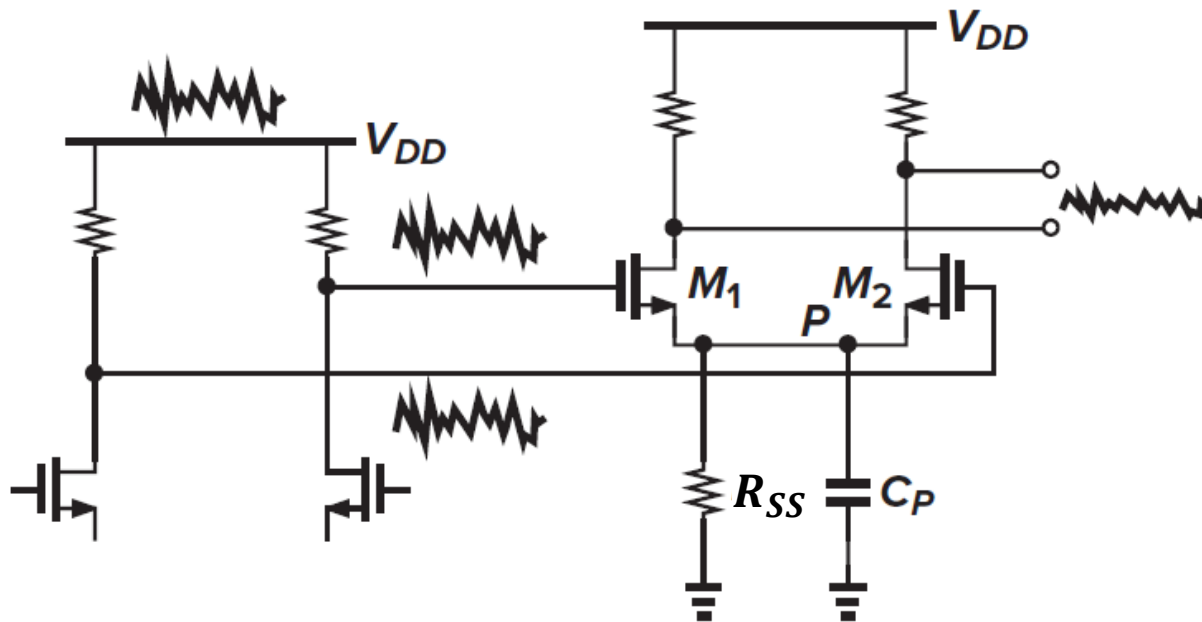
$$\approx \frac{1 + s \frac{C_P}{2g_m}}{1 + sR_{SS}C_P} \cdot 2g_m R_{SS} \frac{g_m}{\Delta g_m}$$

- ❑ @ $\omega \uparrow\uparrow$: $CMRR \approx \frac{g_m}{\Delta g_m}$



CM Frequency Response

- ❑ High frequency supply noise is a very serious issue
- ❑ Again: There is a trade-off between headroom and CMRR
 - More serious for low supply voltage



Thank you!