

وَمَا أُوتِيتُمْ مِنَ الْعِلْمِ إِلَّا قَلِيلًا

## Analog IC Design

### Lecture 09 Frequency Response (2)

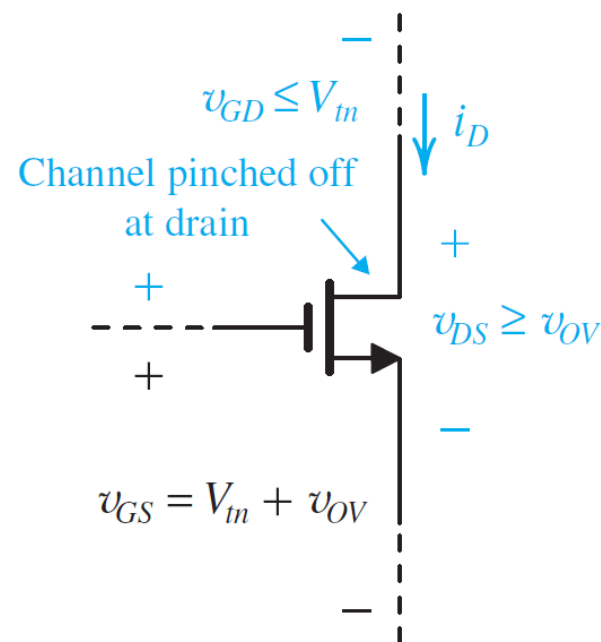
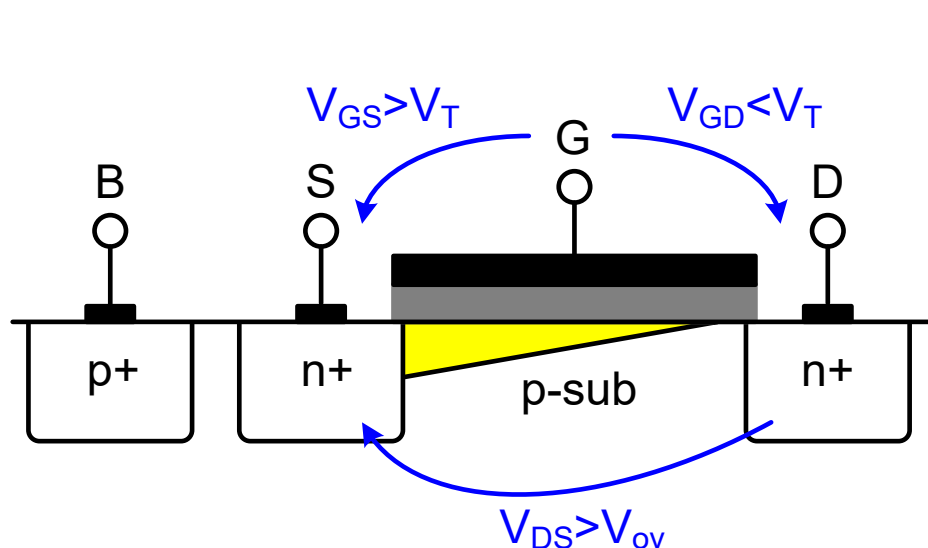
**Dr. Hesham A. Omran**

Integrated Circuits Lab (ICL)  
Electronics and Communications Eng. Dept.  
Faculty of Engineering  
Ain Shams University

# MOSFET in Saturation

- ❑ The channel is pinched off if the difference between the gate and drain voltages is not sufficient to create an inversion layer

$$I_D = \frac{\mu_n C_{ox}}{2} \frac{W}{L} \cdot V_{ov}^2 (1 + \lambda V_{DS})$$



# Regions of Operation Summary

**OFF**  
**(Subthreshold)**

$$V_{GS} < V_T$$

**ON**

$$V_{GS} > V_T$$

**Triode**

$$V_{DS} < V_{ov}$$

Or

$$V_{GD} > V_T$$

**Pinch-Off**  
**(Saturation)**

$$V_{DS} \geq V_{ov}$$

Or

$$V_{GD} \leq V_T$$

$$I_D = \mu C_{ox} \frac{W}{L} \left( V_{ov} V_{DS} - \frac{V_{DS}^2}{2} \right)$$

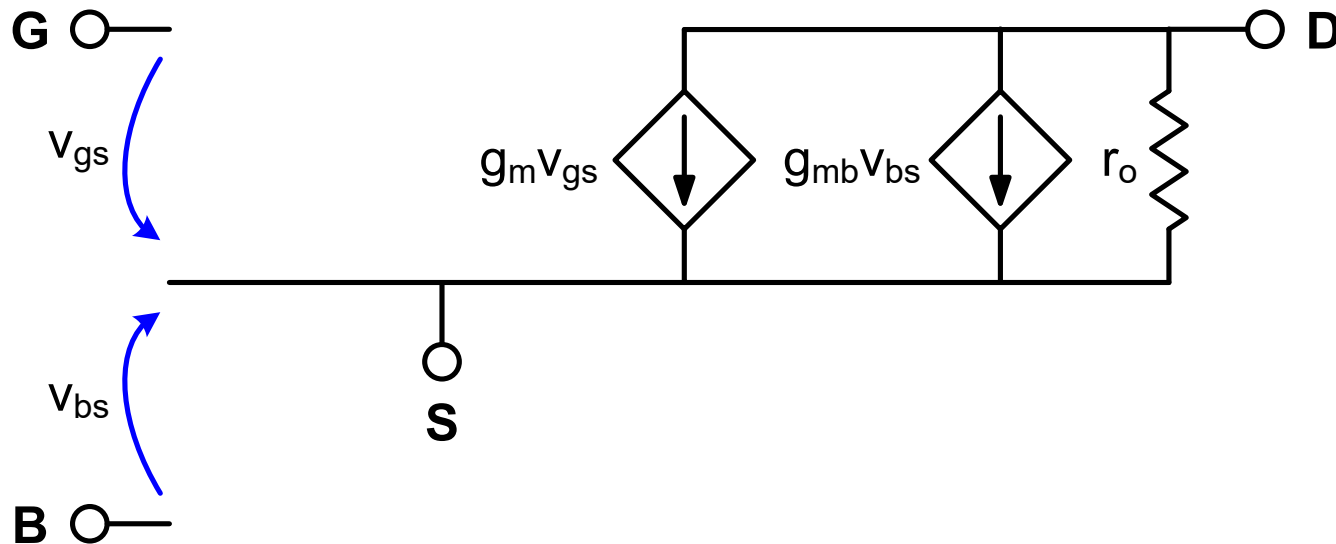
$$I_D = \frac{\mu C_{ox}}{2} \frac{W}{L} V_{ov}^2 (1 + \lambda V_{DS})$$

# Low-Frequency Small-Signal Model

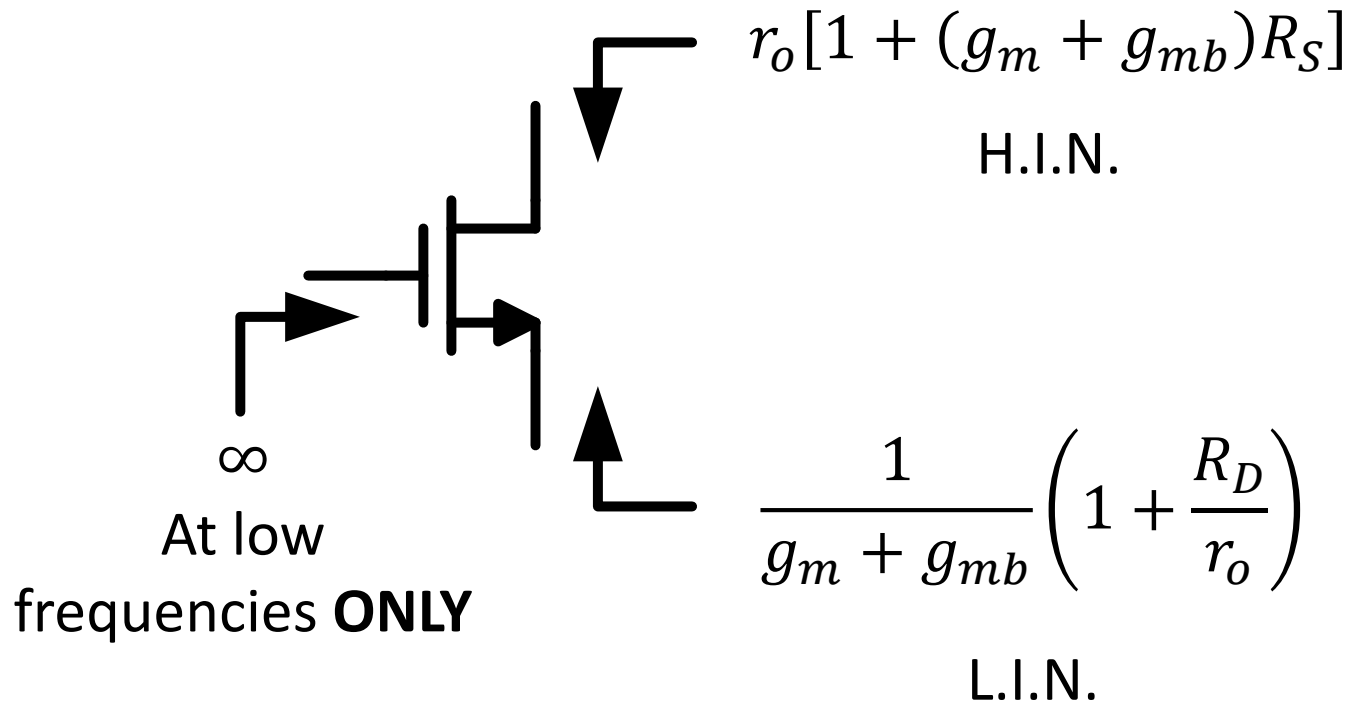
$$g_m = \frac{\partial I_D}{\partial V_{GS}} = \mu C_{ox} \frac{W}{L} V_{ov} = \sqrt{\mu C_{ox} \frac{W}{L} \cdot 2I_D} = \frac{2I_D}{V_{ov}}$$

$$g_{mb} = \eta g_m, \quad \eta \approx 0.1 - 0.25$$

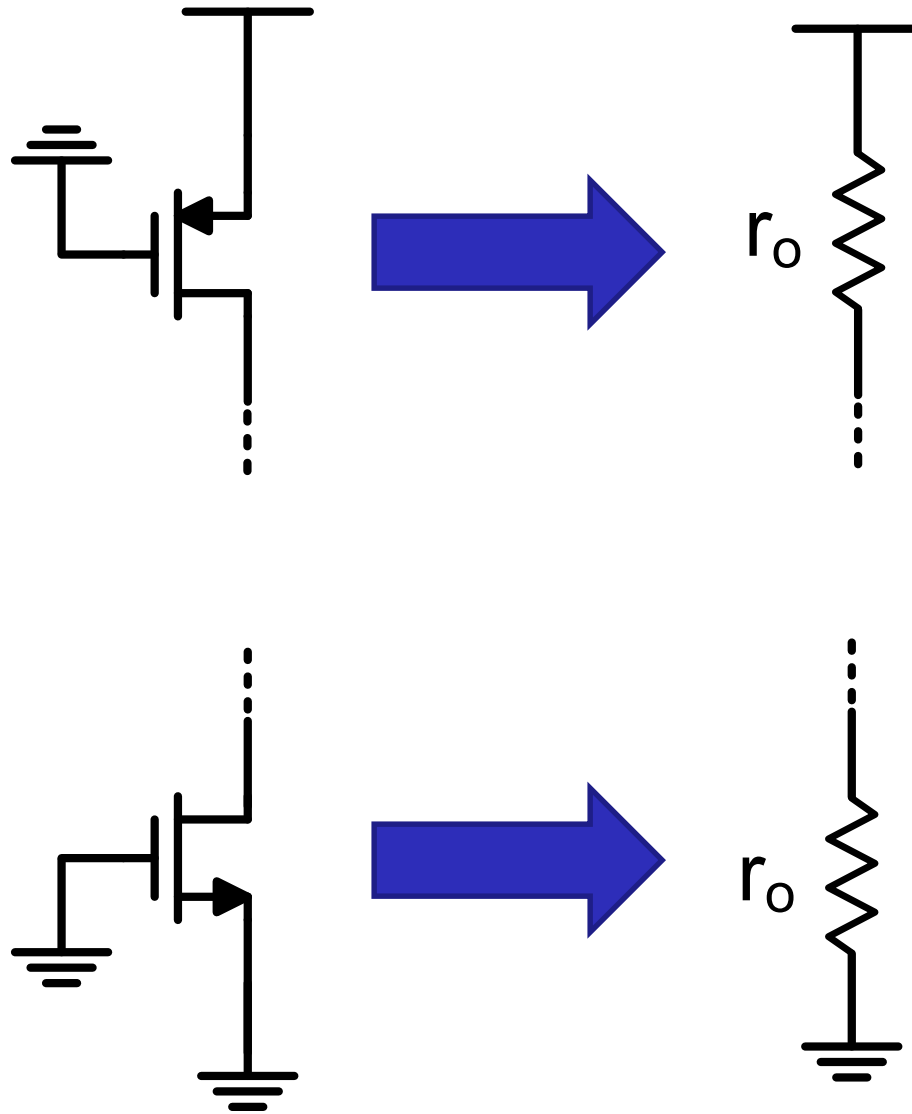
$$r_o = \frac{1}{\frac{\partial I_D}{\partial V_{DS}}} = \frac{1}{\lambda I_D}, \quad \lambda \propto \frac{1}{L}$$



# Rin/out Shortcuts Summary

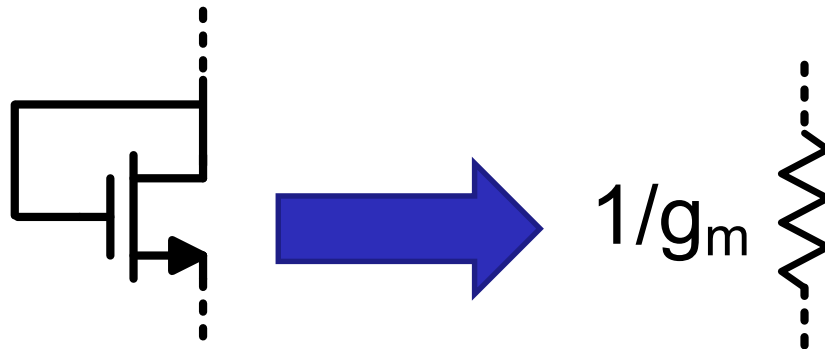
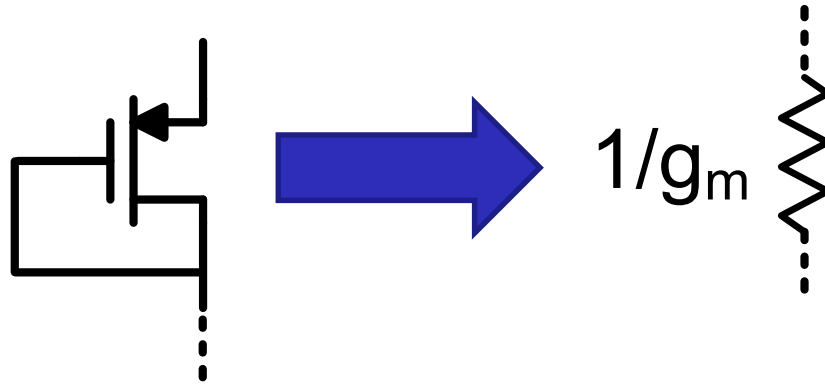


# Active Load (Source OFF)



# Diode Connected (Source Absorption)

- ❑ Always in saturation
- ❑ Bulk effect:  $g_m \rightarrow g_m + g_{mb}$



# Why GmRout?

$$R_{out} = \frac{v_x}{i_x} @ v_{in} = 0$$

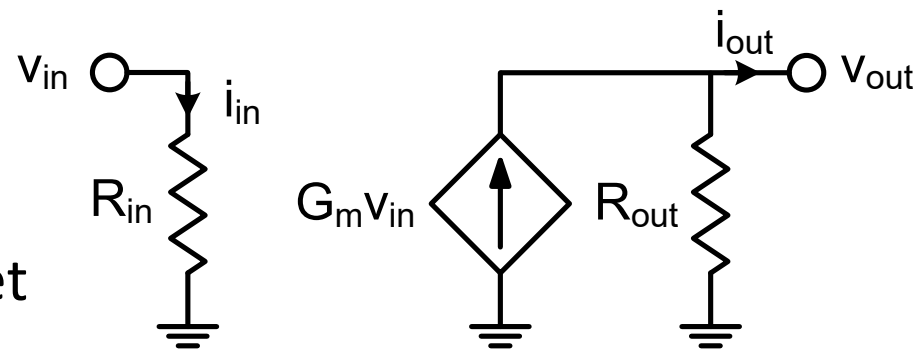
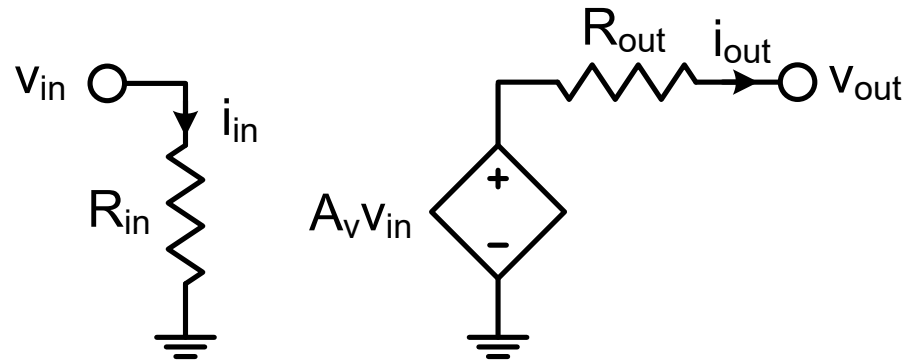
$$G_m = \frac{i_{out,sc}}{v_{in}}$$

$$A_v = G_m R_{out}$$

$$A_i = G_m R_{in}$$

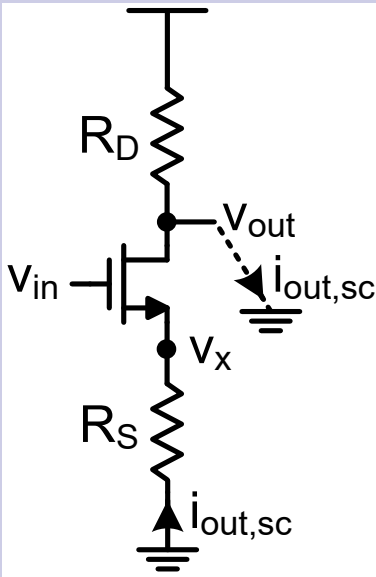
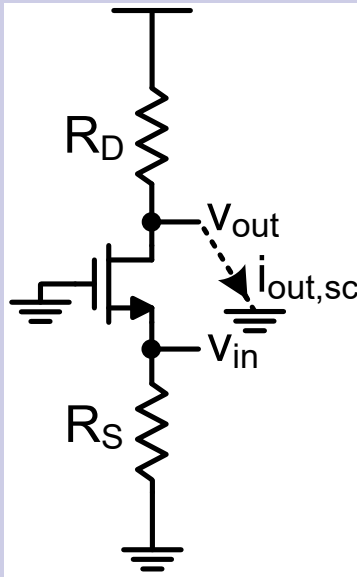
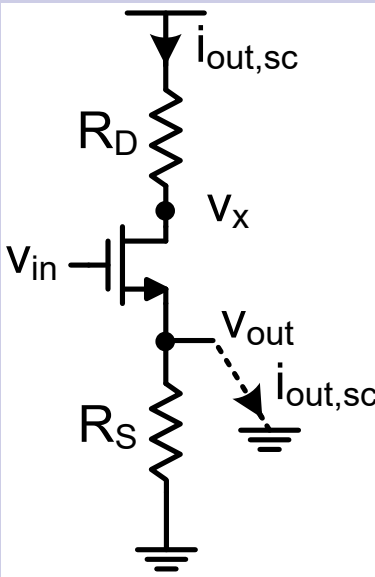
## □ Divide and conquer

- Rout simplified:  $v_{in}=0$
- Gm simplified:  $v_{out}=0$
- We already need  $R_{in/out}$
- We can quickly and easily get  $R_{in/out}$  from the shortcuts



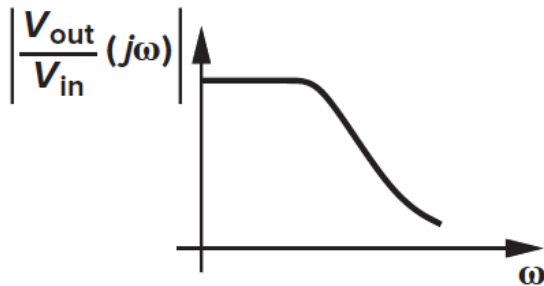


# Summary of Basic Topologies

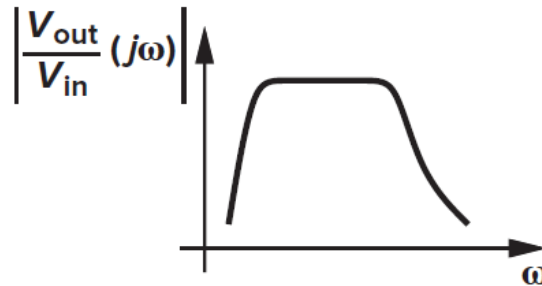
	CS	CG	CD (SF)
			
	Voltage & current amplifier	Current buffer	Voltage buffer
<b>Rin</b>	$\infty$	$R_S // \frac{1}{g_m + g_{mb}} \left( 1 + \frac{R_D}{r_o} \right)$	$\infty$
<b>Rout</b>	$R_D // r_o [1 + (g_m + g_{mb})R_S]$	$R_D // r_o$	$R_S // \frac{1}{g_m + g_{mb}} \left( 1 + \frac{R_D}{r_o} \right)$
<b>Gm</b>	$\frac{-g_m}{1 + (g_m + g_{mb})R_S}$	$g_m + g_{mb}$	$\frac{g_m}{1 + R_D/r_o}$

# Frequency Response

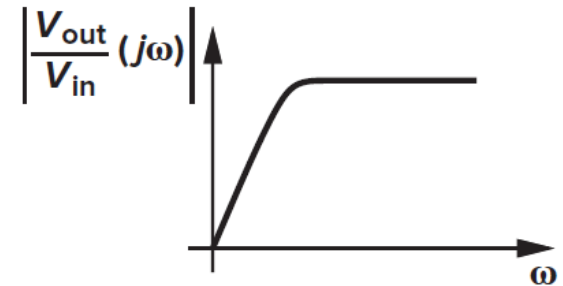
LPF



BPF



HPF



# Poles and Zeros

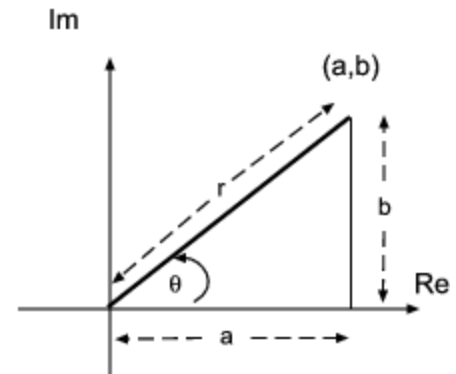
- ❑ Transfer function

$$H(s) = \frac{N(s)}{D(s)}$$

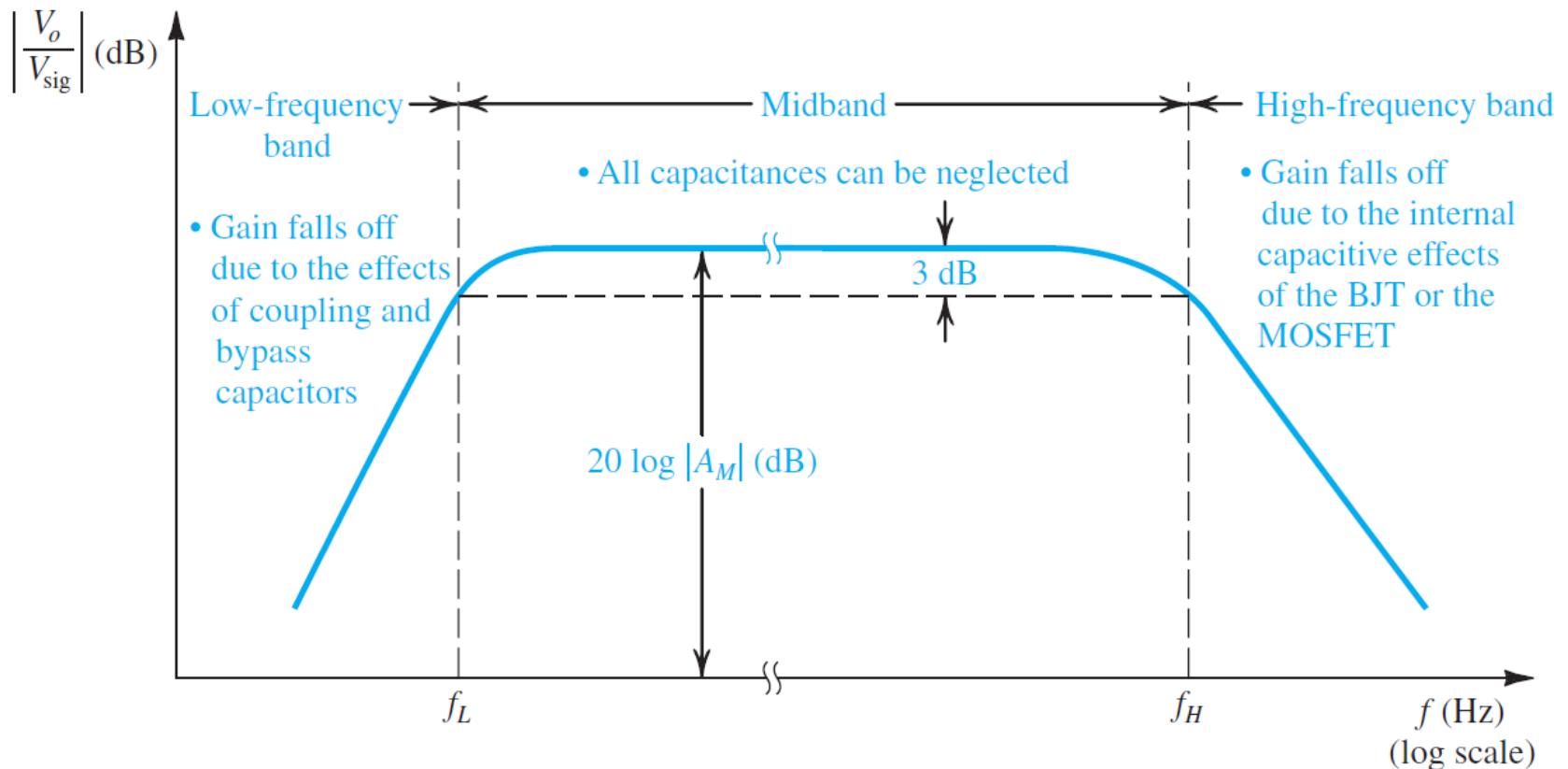
- ❑ Zeros: roots of numerator  $\Rightarrow N(s)$
- ❑ Poles: roots of denominator  $\Rightarrow D(s)$
- ❑ Frequency response:  $s \Rightarrow j\omega$

$$H(j\omega) = \frac{V_{out}(j\omega)}{V_{in}(j\omega)} = |H(j\omega)|e^{j\phi}$$

- ❑ Magnitude( $a + jb$ ) =  $\sqrt{a^2 + b^2}$
- ❑ Phase( $a + jb$ ) =  $\tan^{-1} \frac{b}{a}$



# Frequency Response



Coupling and bypass	✓	S.C.	S.C.
Intrinsic and load	O.C.	O.C.	✓

# SCTC and OCTC Techniques

- ❑ Low-frequency range (LFR) => Not common in IC design
  - Only consider one cap at a time
  - Assume other caps are s.c.
  - s.c. time constant (SCTC) technique
  - $\omega_L \approx \omega_{L1} + \omega_{L2} + \dots$
  - Highest pole dominates (L.I.N. dominates)
- ❑ **High-frequency range (HFR) => More important in IC design**
  - **Only consider one cap at a time**
  - **Assume other caps are o.c.**
  - **o.c. time constant (OCTC) technique**
  - **$\omega_H \approx \omega_{H1} // \omega_{H2} // \dots$**
  - **Lowest pole dominates (H.I.N. dominates)**
- ❑ Both provide good approx if one pole is dominant (and poles are real)

# Calculating Zeros by Inspection

1. Find the value  $s = s_z$  that makes  $H(s) = 0 \Rightarrow v_{out} = 0$

□ Examples:

□  $C_{c1}$ :  $v_o = 0$  if  $Z_{C_1} = \infty$

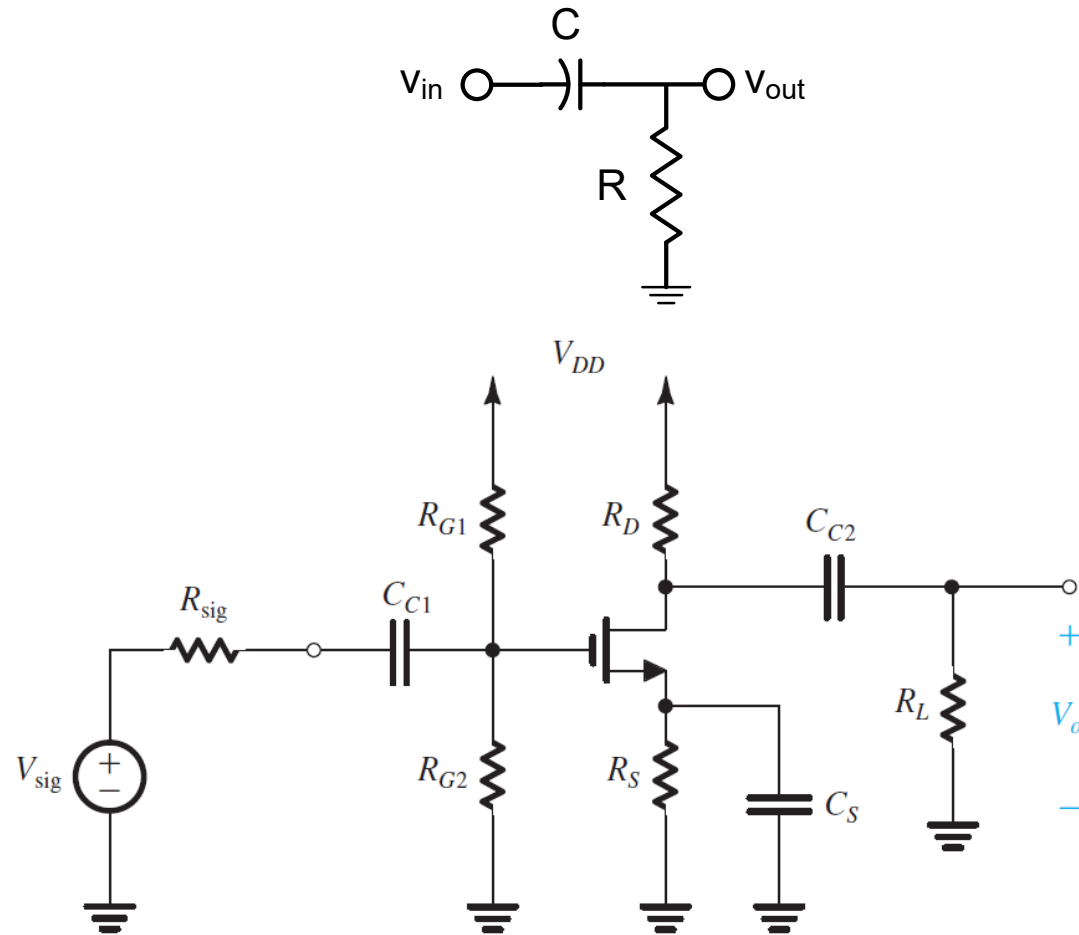
$$- Z_{C_1} = \frac{1}{sC_1}$$

$$- \Rightarrow s_{z1} = 0$$

□  $C_S$ :  $v_o = 0$  if  $Z_S = \infty$

$$- Z_S = \frac{R_S}{1+sR_SC_S}$$

$$- \Rightarrow s_{z2} = -\frac{1}{R_SC_S}$$



# Calculating Poles by Inspection

1. Set  $v_{sig} = 0$
2. Calculate thevenin resistance ( $R_{th,i}$ ) seen by each cap ( $C_i$ )

$$3. s_{p,i} = -\frac{1}{R_{th,i}C_i}$$

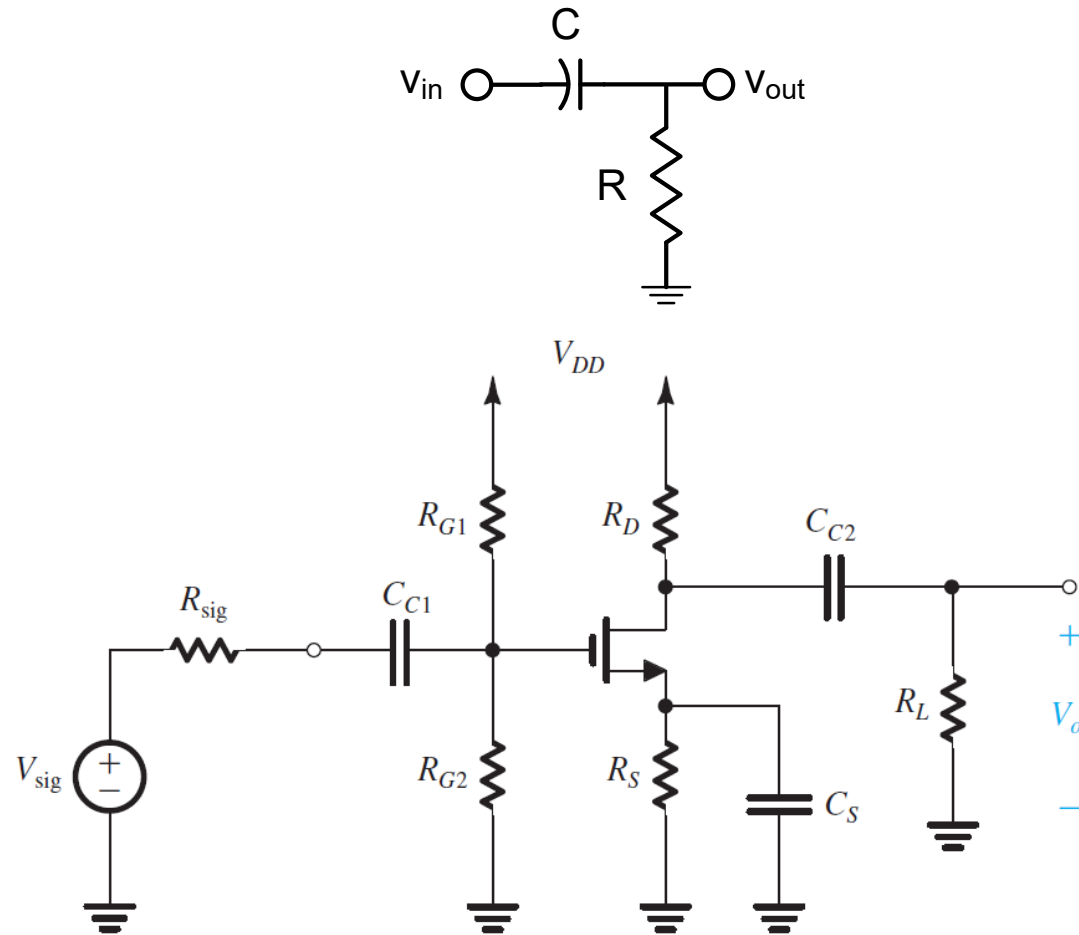
□ Examples:

□  $C_{c1}: R_{th1} = R_{sig} + R_G$

$$\Rightarrow s_{p1} = -\frac{1}{(R_{sig} + R_G)C_{c1}}$$

□  $C_S: R_{th2} \approx R_S // \frac{1}{g_m}$

$$\Rightarrow s_{p2} = -\frac{1}{\left(R_S // \frac{1}{g_m}\right)C_S}$$



# Calculating Poles by Inspection

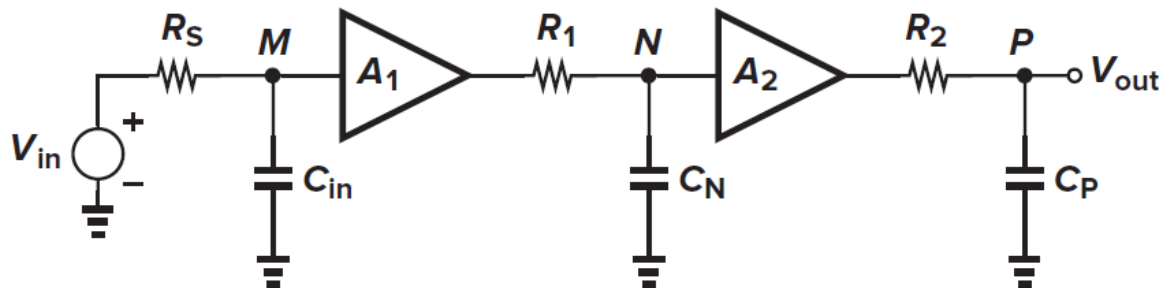
1. Set  $v_{sig} = 0$
2. Calculate thevenin resistance ( $R_{th,i}$ ) seen by each cap ( $C_i$ )

3.  $s_{p,i} = -\frac{1}{R_{th,i}C_i}$

□ Examples:

- Each node is associated with a pole
- H.I.N. dominates

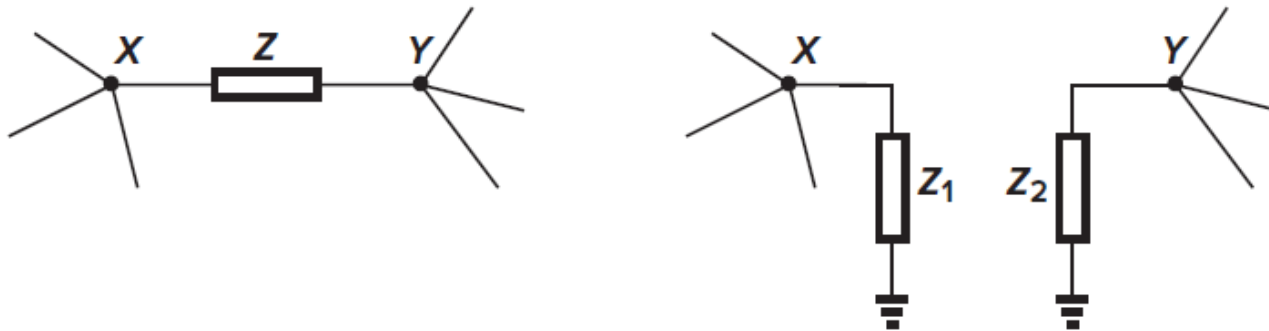
$$\frac{V_{out}}{V_{in}}(s) = \frac{A_1}{1 + R_S C_{in} s} \cdot \frac{A_2}{1 + R_1 C_N s} \cdot \frac{1}{1 + R_2 C_P s}$$





# Miller's Theorem

$$A_v = \frac{V_Y}{V_X}$$
$$\frac{V_X - V_Y}{Z} = \frac{V_X}{Z_1} = -\frac{V_Y}{Z_2}$$
$$Z_1 = \frac{Z}{1 - \frac{V_Y}{V_X}} = \frac{Z}{1 - A_v}$$
$$Z_2 = \frac{Z}{1 - \frac{V_X}{V_Y}} = \frac{Z}{1 - \frac{1}{A_v}}$$



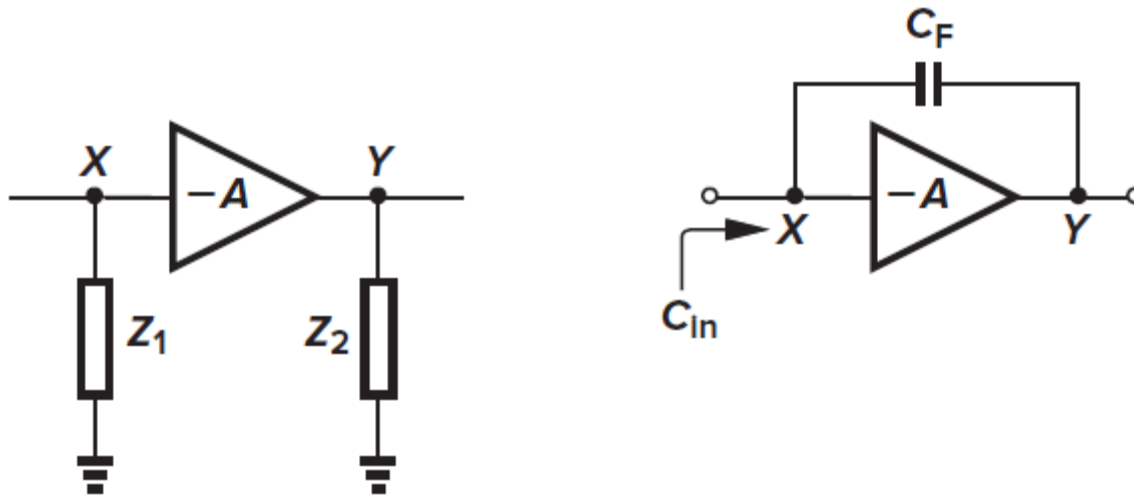
❑ Note: Miller's Theorem cannot be used for  $Z_{out}$  calculation

# Miller Effect

□ Capacitance multiplication:  $Z_F = 1/sC_F$

$$Z_1 = \frac{Z_F}{1 - A_v} \approx \frac{Z_F}{A} = \frac{1}{sAC_F} \Rightarrow C_{in} = AC_F$$

$$Z_2 = \frac{Z_F}{1 - \frac{1}{A_v}} \approx Z_F = \frac{1}{sC_F} \Rightarrow C_{out} \approx C_F$$



# Miller's Approximation

$$Z_1 = \frac{Z}{1 - A_v} \text{ \& } Z_2 = \frac{Z}{1 - \frac{1}{A_v}}$$

- ❑ But  $A_v$  is a function of frequency!
- ❑ Miller's Approximation: Substitute with the low frequency gain
  - $A_v(s) \approx A_o$
  - It does not tell about the feedforward zero (next slide)
  - **Gives good approx ONLY if the i/p pole is dominant**
- ❑ See Example 6.4 in [Razavi, 2017]

# The Feedforward Zero

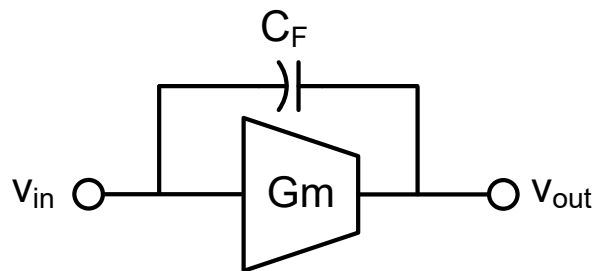
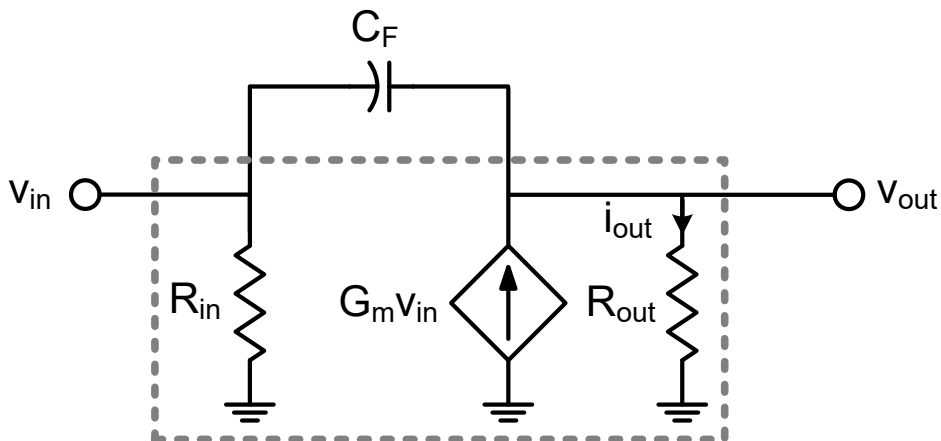
□  $v_{out} = 0 \rightarrow i_{out} = 0$

□  $v_{in} s C_F = -G_m v_{in}$

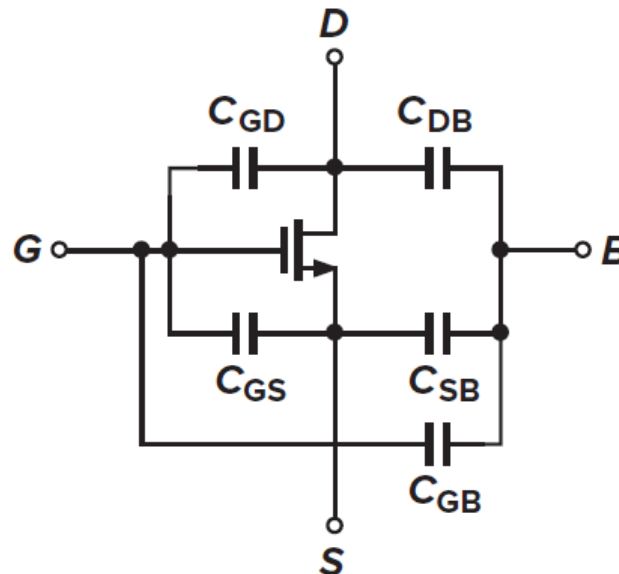
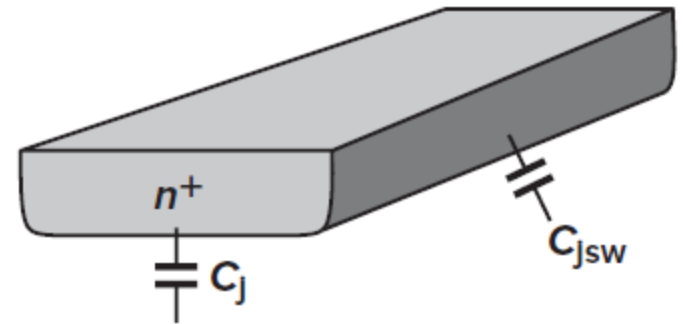
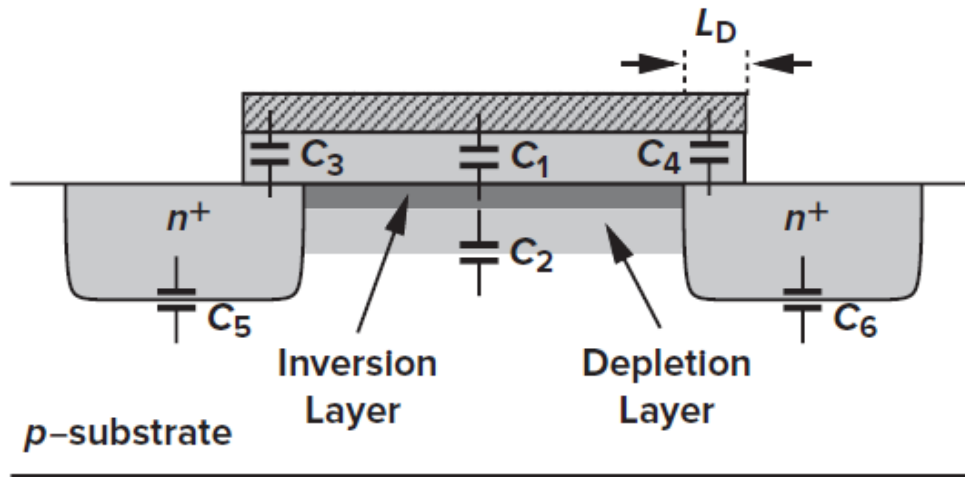
$$s_z = -\frac{G_m}{C_F}$$

□ RHP zero if  $G_m$  is -ve (e.g. CS)

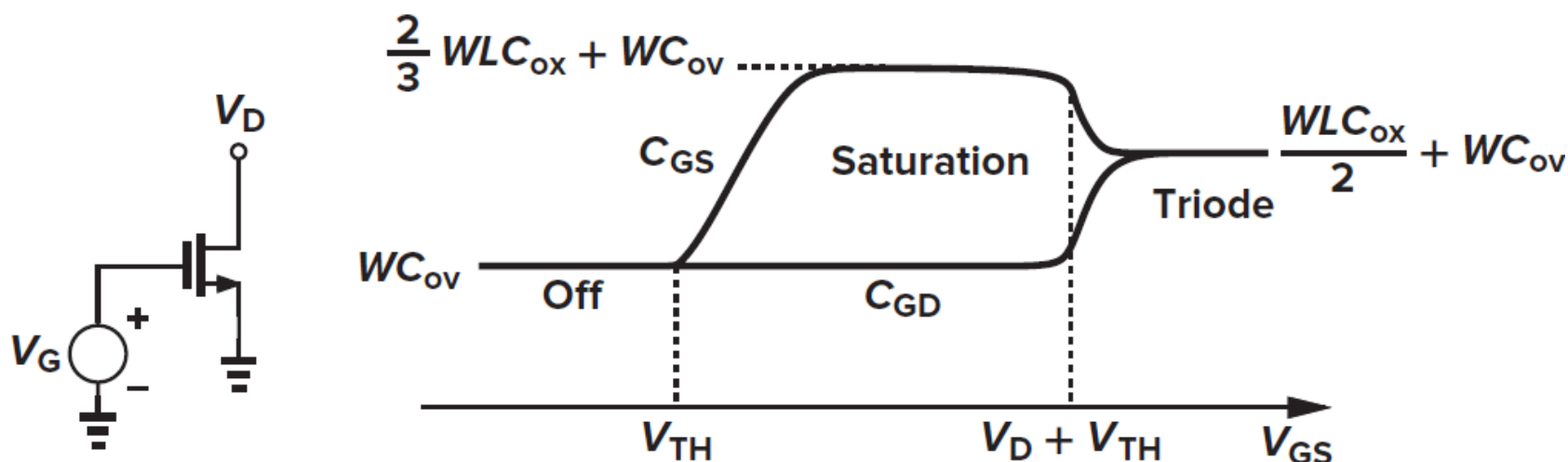
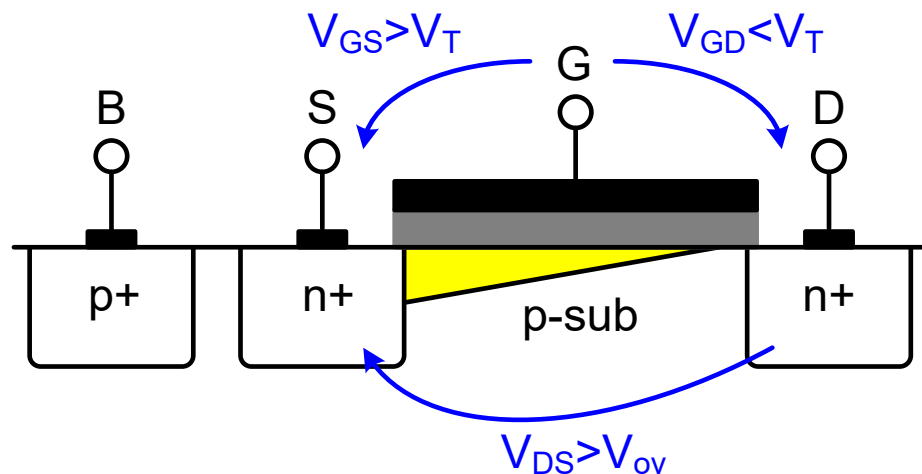
- Mag inc and phase drops
- Very bad for loop stability
- More on this when we study OTAs



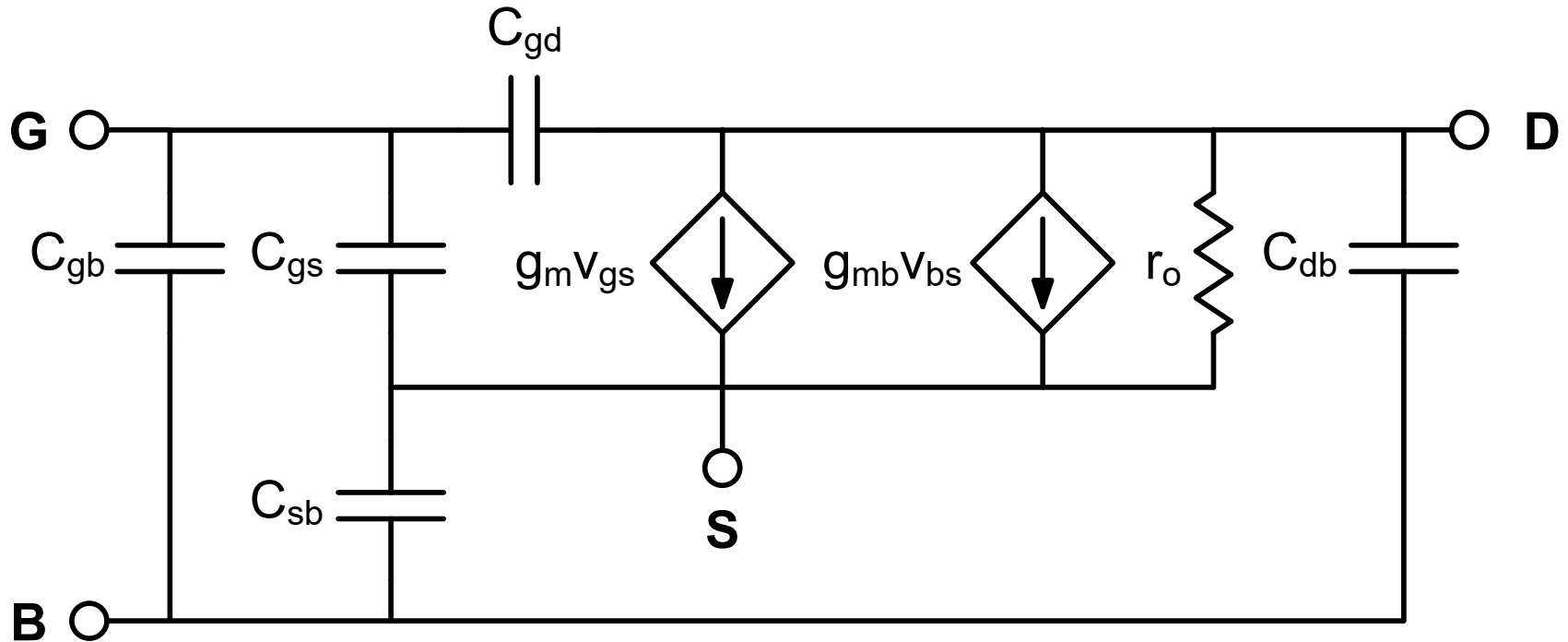
# MOSFET Capacitances



# $C_{gs}$ and $C_{gd}$

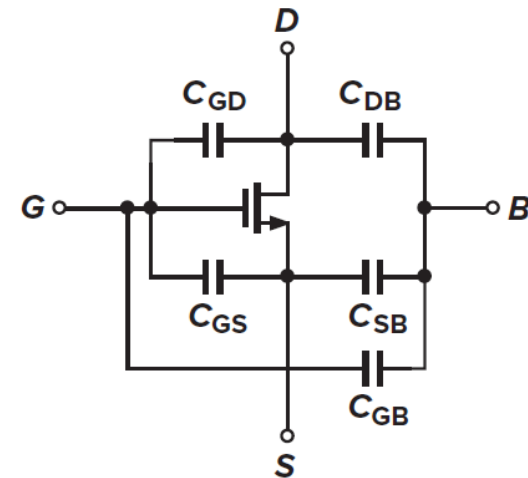
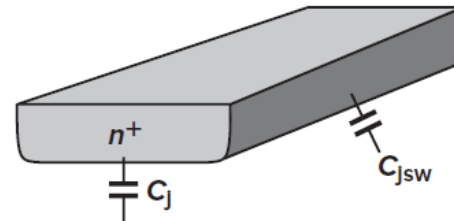
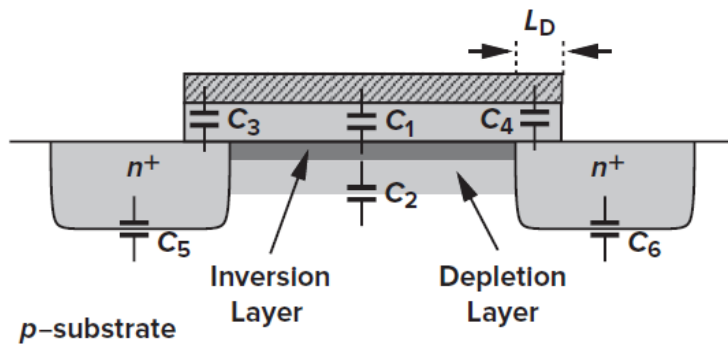


# High Frequency Small Signal Model



# MOSFET Capacitances Summary

- Usually  $C_{gs} \gg C_{gd}$
- Usually  $C_{sb} \gg C_{db}$

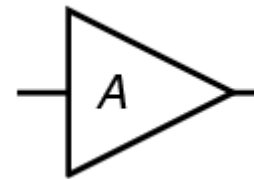
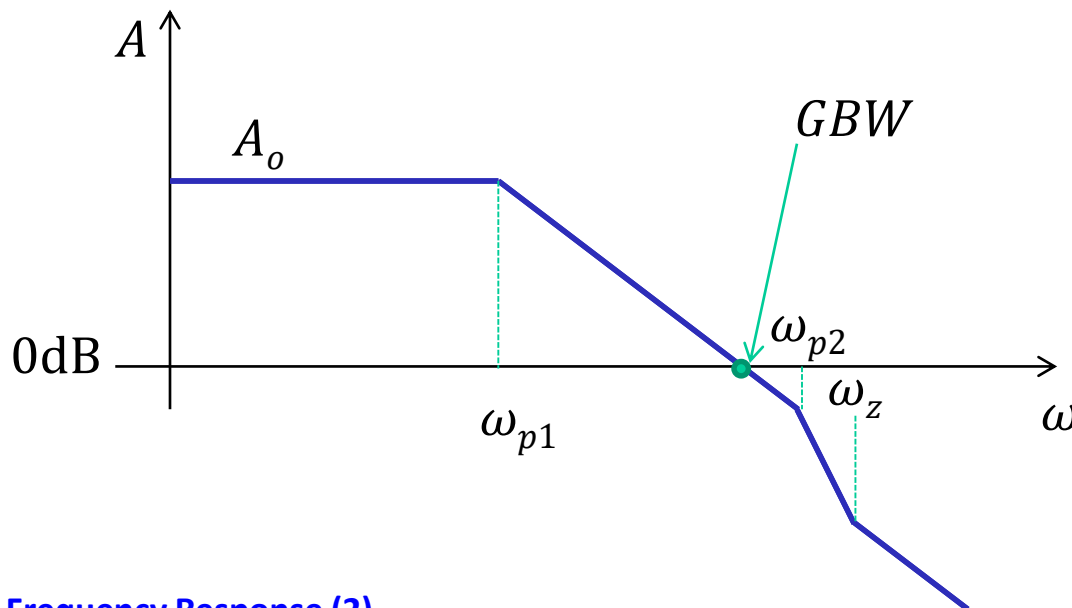


	$C_{gb}$	$C_{gs}$	$C_{gd}$	$C_{sb}$	$C_{db}$
Cutoff	$\leq WLC_{ox}$	$WC_{ov}$	$WC_{ov}$	$A_S C_j + P_S C_{j,SW}$	$A_D C_j + P_D C_{j,SW}$
Triode	0	$\frac{1}{2} WLC_{ox} + WC_{ov}$	$\frac{1}{2} WLC_{ox} + WC_{ov}$	$\left(A_S + \frac{WL}{2}\right) C_j + P_S C_{j,SW}$	$\left(A_D + \frac{WL}{2}\right) C_j + P_D C_{j,SW}$
Saturation	0	$\frac{2}{3} WLC_{ox} + WC_{ov}$	$WC_{ov}$	$(A_S + WL) C_j + P_S C_{j,SW}$	$A_D C_j + P_D C_{j,SW}$



# IC Amplifier Frequency Response

- ❑  $A_o$  is the midband gain (or DC gain) of the amplifier
- ❑  $\omega_{p1}$  is the 3dB bandwidth = BW =  $\omega_{3dB}$
- ❑  $\omega_{p2}$  is the non-dominant pole
- ❑ **Gain-Bandwidth Product (GBW)** is the frequency at which gain is unity (1 = 0dB) (a.k.a. unity gain frequency:  $\omega_u$ )
- ❑ Usually, we design the amplifier such that  $\omega_{p2}$  and  $\omega_z > GBW$



$$\frac{V_{out}}{V_{in}} = \frac{A_o (1 + s / \omega_z)}{(1 + s / \omega_{p1})(1 + s / \omega_{p2})}$$

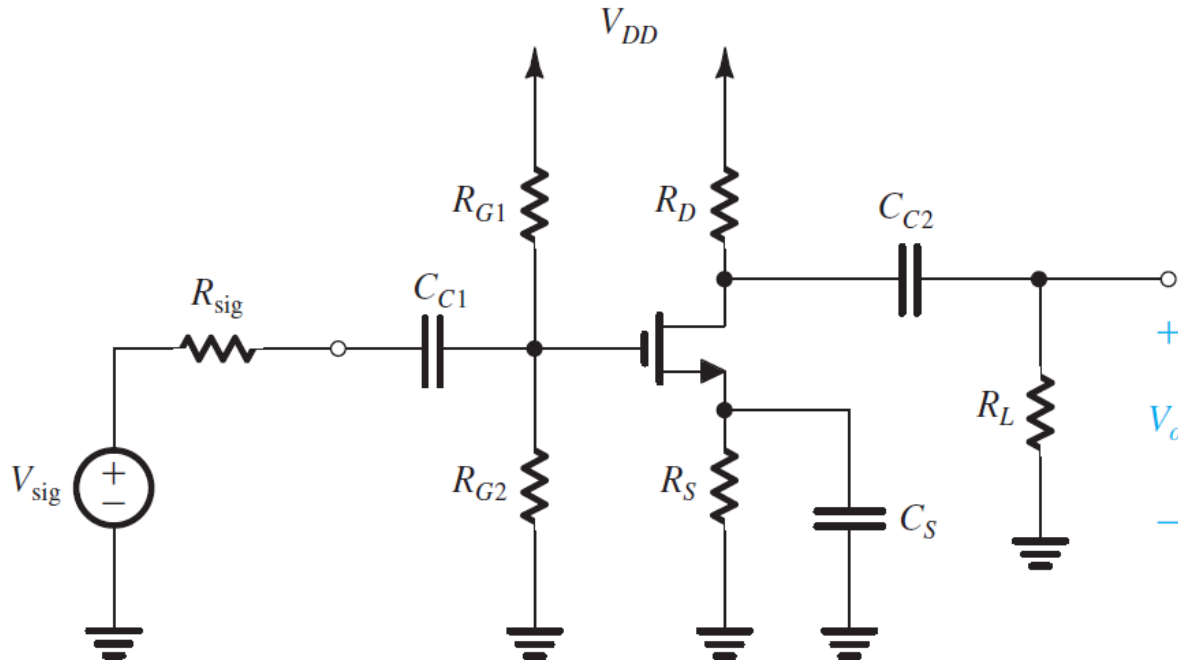
$$GBW = A_o \omega_{p1}$$

# Frequency Response of CS: Midband

$$A_v = \frac{v_{in}}{v_{sig}} \cdot \frac{v_o}{v_{in}}$$

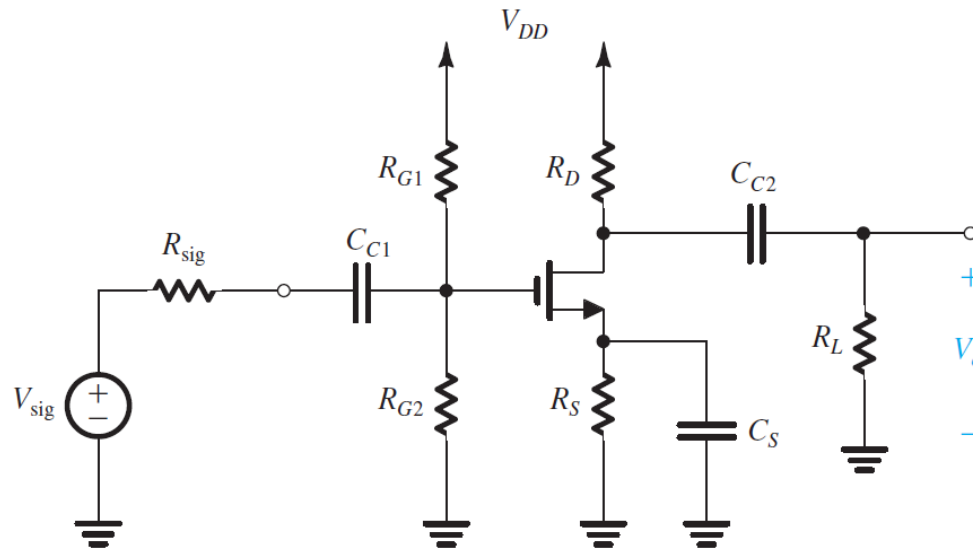
$$\frac{v_o}{v_{in}} = G_m R_{out} = -g_m (R_D || R_L || r_o)$$

$$\frac{v_{in}}{v_{sig}} = \frac{R_{in}}{R_{in} + R_{sig}}, R_{in} = R_G = R_{G1} || R_{G2}$$



# Frequency Response of CS: LFR

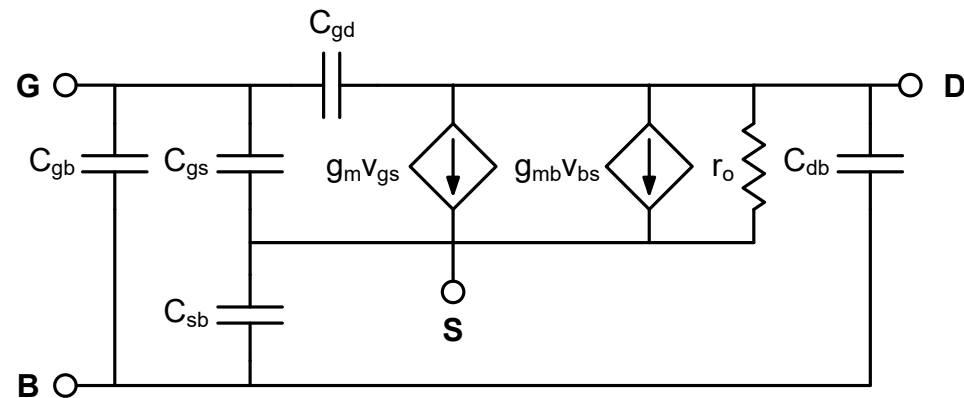
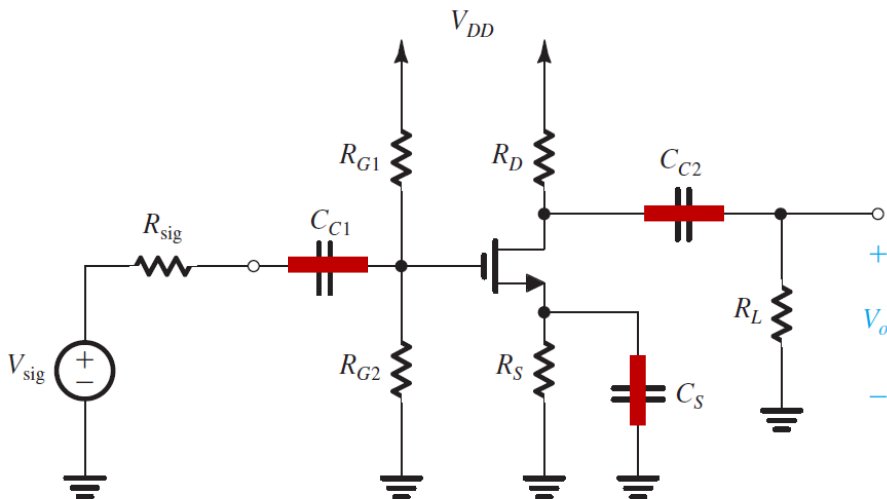
- ❑  $C_{C1}$ :  $R_{th} = R_{sig} + R_G \rightarrow \omega_{p,C_{C1}} = \frac{1}{(R_{sig} + R_G)C_{C1}}$  &  $\omega_{z,C_{C1}} = 0$
- ❑  $C_{C2}$ :  $R_{th} = R_L + R_D || r_o \rightarrow \omega_{p,C_{C2}} = \frac{1}{(R_L + R_D || r_o)C_{C2}}$  &  $\omega_{z,C_{C2}} = 0$
- ❑  $C_S$ :  $R_{th} = R_S || R_{LFS} \rightarrow \omega_{p,C_S} = \frac{1}{(R_S || R_{LFS})C_S}$  &  $\omega_{z,C_S} = \frac{1}{R_S C_S}$
- ❑ Usually  $\omega_{p,C_S}$  is dominant:  $\omega_L \approx \omega_{p,C_S}$  (why?)
- ❑ Note that for ICs we usually use direct coupling (no LFR)



# Frequency Response of CS: HFR

- ❑ Break the feedback capacitance ( $C_{gd}$ ) using Miller
  - Read the exact analysis w/o Miller approx in [Razavi, 2017, S6.2]
- ❑ Each node is associated with a pole
  - i/p node  $\rightarrow$  i/p pole ( $\omega_{p,in}$ ) & o/p node  $\rightarrow$  o/p pole ( $\omega_{p,out}$ )
- ❑ Don't forget the RHP feedforward zero

$$\omega_{z,C_{gd}} = \frac{g_m}{C_{gd}} \rightarrow \text{Usually } \omega_{z,C_{gd}} \text{ is very high (why?)}$$



# Frequency Response of CS: HFR

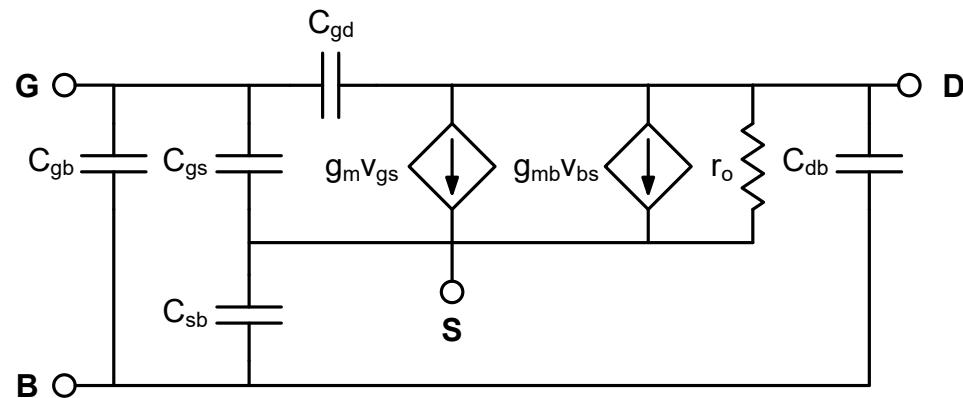
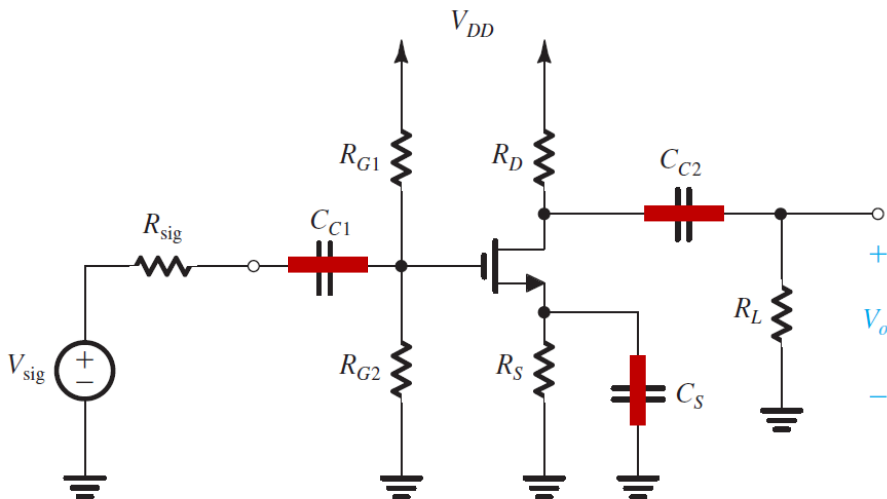
- i/p pole: suffers from Miller effect

$$R_{th,in} = R_{sig} || R_G \rightarrow \omega_{p,in} \approx \frac{1}{(R_{sig} || R_G)(C_{gs} + C_{gd}(1 + A_o))}, A_o = \left| \frac{v_o}{v_{in}} \right|$$

- o/p pole:

$$R_{th,out} = R_L || R_D || r_o \rightarrow \omega_{p,out} \approx \frac{1}{(R_L || R_D || r_o)(C_L + C_{db} + C_{gd}(1 + 1/A_o))}$$

- Usually i/p pole is dominant:  $\omega_H \approx \omega_{p,in}$  (why?), unless  $R_{sig} \downarrow \downarrow$

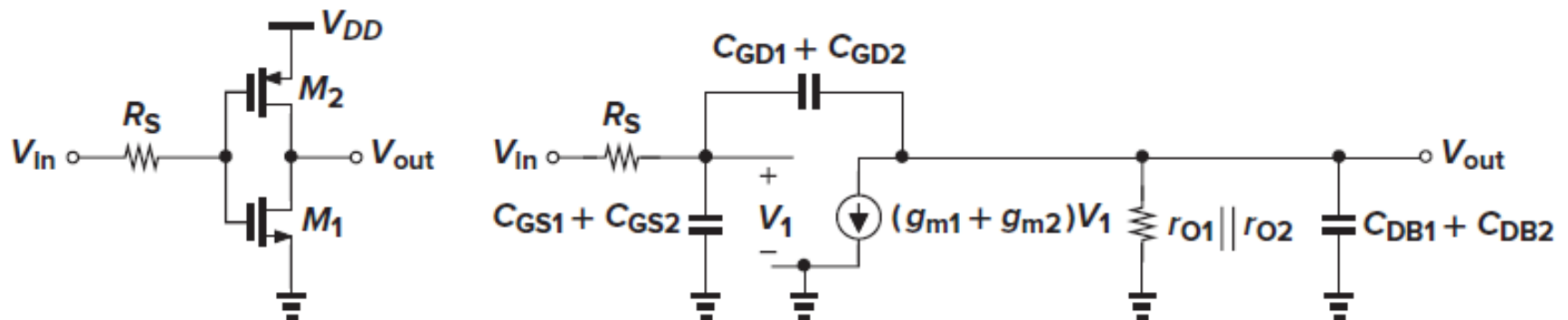


# Frequency Response of CS: HFR

- ❑ If  $\omega_{p,out}$  is dominant (e.g., if  $R_{sig} \downarrow\downarrow$  or  $C_L \uparrow\uparrow$ )
  - Multiplying  $C_{gd}$  by the low frequency gain is **NOT** accurate (why?)
  - $\omega_{p,in} \approx \frac{1}{(R_{sig} || R_G)(C_{gs} + \textcolor{red}{C}_{gd}(1 + A_v))} \approx \frac{1}{(R_{sig} || R_G)(C_{gs} + \textcolor{red}{C}_{gd})}$
  - $\omega_H \approx \omega_{p,out} = \frac{1}{R_{out}C_{out}}$
  - $GBW = A_v\omega_H = G_m R_{out} \cdot \frac{1}{R_{out}C_{out}} = \frac{G_m}{C_{out}} \rightarrow \text{ind. of } R_{out}!$

# Frequency Response of CS: HFR

- Note that we must consider the parasitic capacitors of all transistors in the circuit
- Example:



# Frequency Response of CS: $Z_{in}$

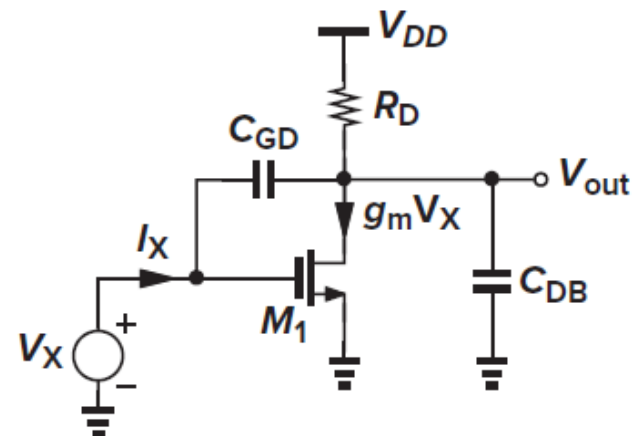
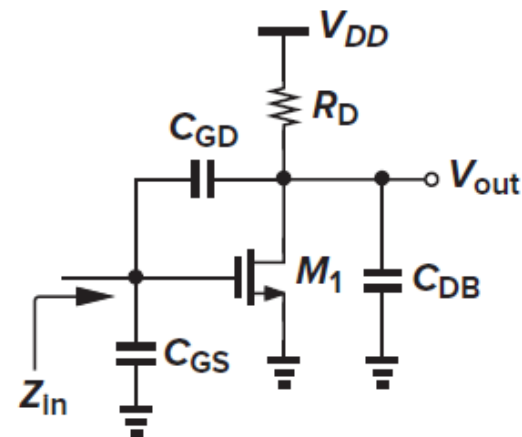
- With Miller approx.

$$Z_{in} = \frac{1}{[C_{GS} + (1 + g_m R_D)C_{GD}]s}$$

- Exact Analysis ( $C_{gs}$  adds in parallel)

$$\frac{V_X}{I_X} = \frac{1 + R_D(C_{GD} + C_{DB})s}{C_{GD}s(1 + g_m R_D + R_D C_{DB}s)}$$

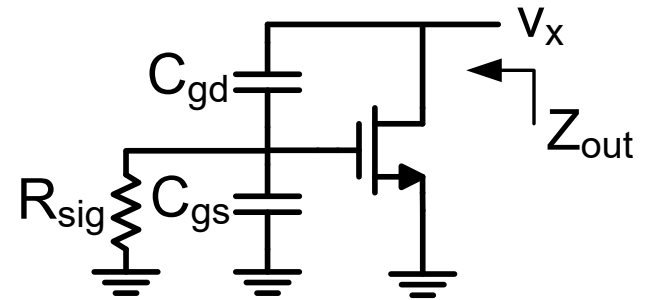
- Extra pole and zero at high frequency
- At relatively low frequency the exact solution reduces to Miller approx.





# Frequency Response of CS: $Z_{out}$

- ❑ Can we use Miller?
- ❑  $i_x = f(v_{gs}) =$
- ❑  $v_x = f(v_{gs}) =$
- ❑  $Z_{out} = \frac{v_x}{i_x} =$
- ❑  $r_o$  and  $C_{db}$  add in parallel
- ❑ Important special case: If we have a large capacitor parallel to  $C_{gd}$ 
  - We will need this case when we study Miller OTA



# Frequency Response of CS: $Z_{out}$

❑ Can we use Miller?

$$\square \quad i_x = f(v_{gs}) = g_m v_{gs} + \frac{v_{gs}(1 + R_{sig}C_{gs})}{R_{sig}}$$

$$\square \quad v_x = f(v_{gs}) = v_{gs} + \frac{v_{gs}(1 + R_{sig}C_{gs})}{sR_{sig}C_{gd}}$$

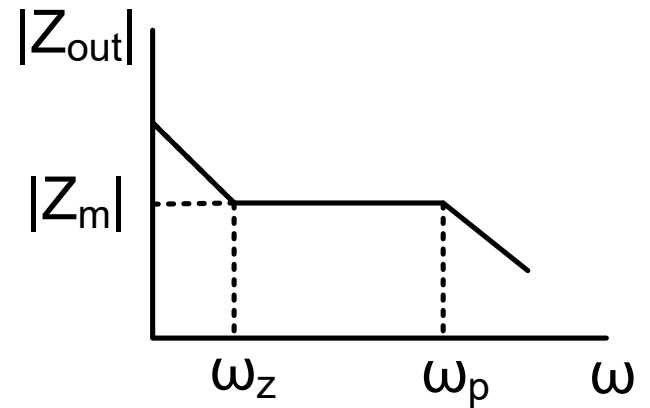
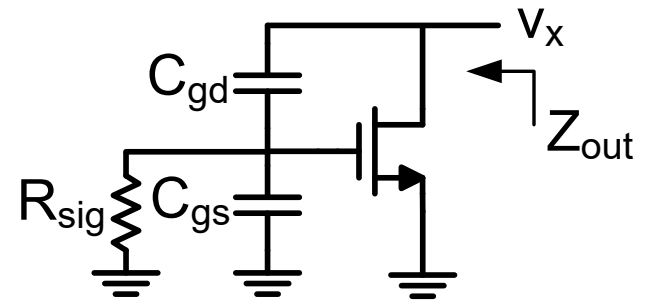
$$\square \quad Z_{out} = \frac{v_x}{i_x} \approx \frac{1 + sR_{sig}(C_{gs} + C_{gd})}{sC_{gd}g_mR_{sig}\left(1 + s\frac{C_{gs}}{g_m}\right)}$$

❑  $r_o$  and  $C_{db}$  add in parallel

❑ Important special case: If we have a large capacitor parallel to  $C_{gd}$

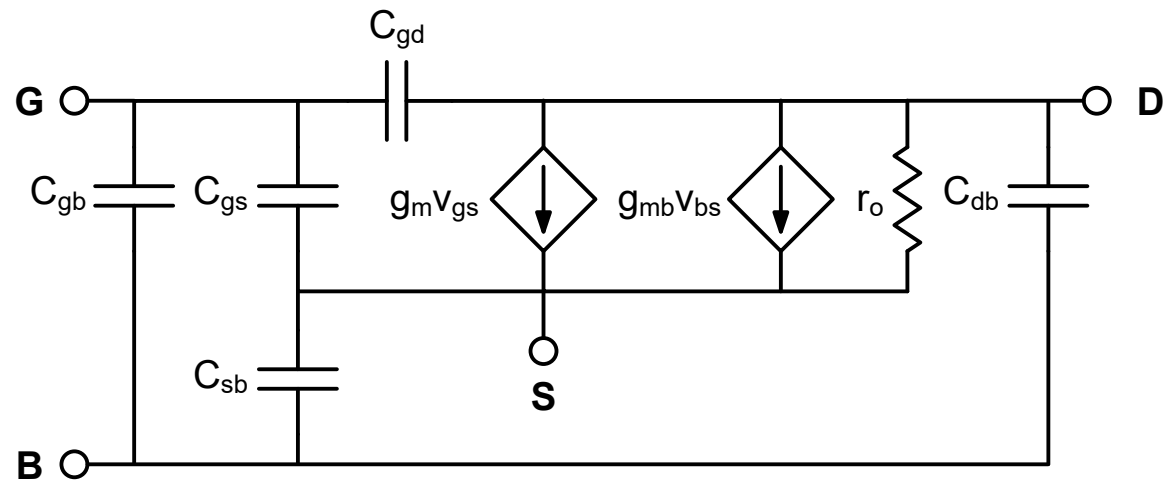
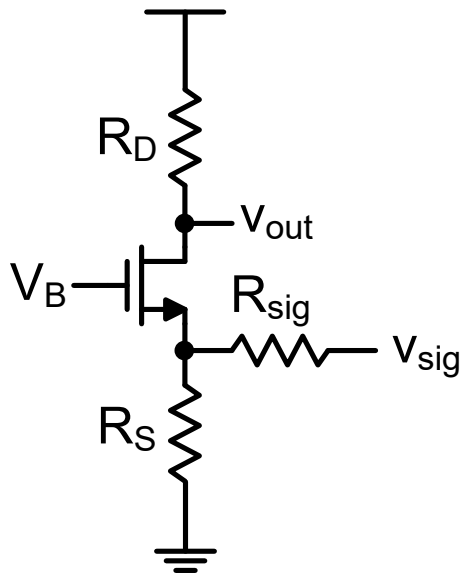
–  $|Z_m| \approx 1/g_m$

– We will need this case when we study Miller OTA



# Frequency Response of CG: HFR

- ❑ i/p pole:  $\omega_{p,in} = \frac{1}{(R_{sig} || R_S || R_{LFS})(C_{gs} + C_{sb})}$
- ❑ o/p pole:  $\omega_{p,out} = \frac{1}{(R_D || R_{LFD})(C_L + C_{db} + C_{gd})}$
- ❑ Usually o/p pole is dominant:  $\omega_H \approx \omega_{p,out}$  (why?)
- ❑ No FB cap  $\rightarrow$  No Miller effect  $\rightarrow$   **$BW_{CG} \gg BW_{CS}$**



# Frequency Response of Cascode: HFR

**Case 1: BW limited by o/p pole ( $R_D \uparrow \uparrow R_{sig} \downarrow \downarrow$ ) (cascode for gain)**

$$\square A_v = \frac{v_{out}}{v_{sig}} \approx (g_{m1}r_{o1})(g_{m2}r_{o2}) = A_{v,CS} \cdot (g_m r_o)$$

$$\square A_{o1} = \left| \frac{v_x}{v_{in}} \right| = g_{m1}(r_{o1} || R_{LFS}), R_{LFS} \neq \infty \text{ (why?)}$$

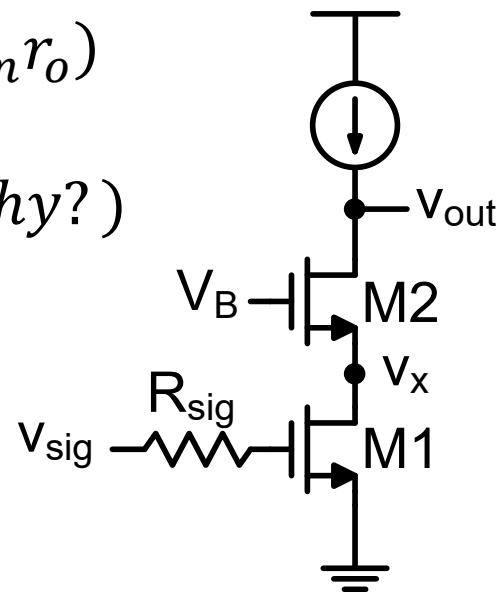
$$\square \omega_{p,in} = \frac{1}{R_{sig}(C_{gs1} + C_{gd1}(1 + A_{o1}))} = \omega_{p,in,CS}$$

– Still a bit suffering from Miller effect

$$\square \omega_{p,x} = \frac{1}{r_{o1}(C_{gs2} + C_{sb2} + C_{db1} + C_{gd1}(1 + 1/A_{o1}))}$$

$$\square \omega_{p,out} \approx \frac{1}{r_{o1}(g_{m2}r_{o2})(C_L + C_{db2} + C_{gd2})} = \frac{\omega_{p,out,CS}}{g_m r_o} \rightarrow \text{Dominant}$$

$$\square GBW = A_v \omega_{p,out} = A_{v,CS} \omega_{p,out,CS} = \frac{G_m}{C_{out}} \rightarrow \text{Same as CS!}$$



# Frequency Response of Cascode: HFR

**Case 2: BW limited by i/p pole ( $R_D \downarrow \downarrow R_{sig} \uparrow \uparrow$ ) (cascode for BW)**

□  $A_v = \frac{v_{out}}{v_{sig}} \approx g_{m1} R_D \approx A_{v,CS} \rightarrow \text{Similar to CS!}$

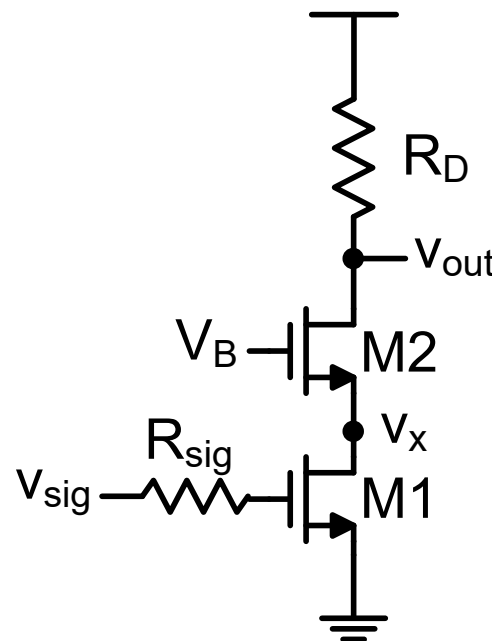
□  $A_{o1} = \left| \frac{v_x}{v_{in}} \right| = g_{m1} (r_{o1} \parallel \frac{1}{g_{m2}}) \approx 1$

□  $\omega_{p,in} \approx \frac{1}{R_{sig}(C_{gs1} + 2C_{gd1})}$   
 – **Miller effect reduced  $\rightarrow$  BW extension!**

□  $\omega_{p,x} \approx \frac{1}{(r_{o1} \parallel \frac{1}{g_{m2}})(C_{gs2} + C_{sb2} + C_{db1} + 2C_{gd1})}$

□  $\omega_{p,out} \approx \frac{1}{R_D(C_L + C_{db2} + C_{gd2})} \approx \omega_{p,out,CS} \rightarrow \text{Similar to CS!}$

□  $GBW = A_v \omega_{p,in} > GBW \text{ of CS}$



# Frequency Response of Cascode: HFR

## Summary

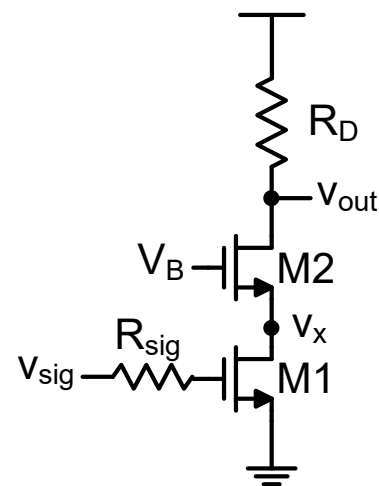
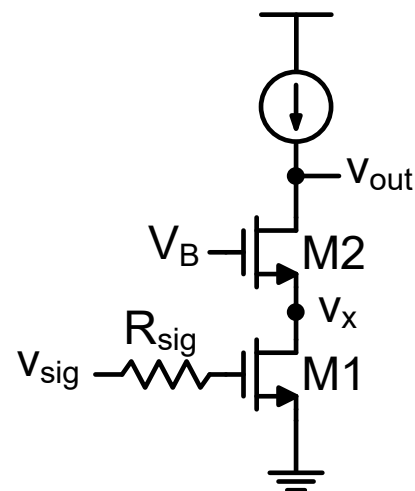
□ If BW is limited by o/p pole

- $GBW = A_v \omega_{p,out} = G_m R_{out} \cdot \frac{1}{R_{out} C_{out}} = \frac{G_m}{C_{out}}$
- Cascode can be used **to trade gain for bandwidth** by modifying  $R_{out}$
- But the GBW remain unchanged @  $\frac{G_m}{C_{out}}$

□ If BW is limited by i/p pole

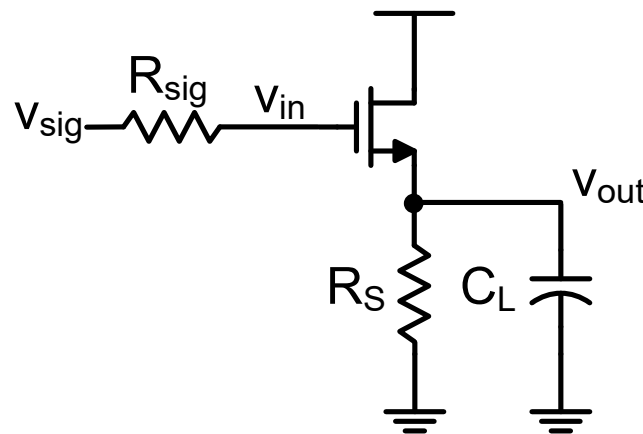
- Cascode can provide higher BW (Miller ↓)
- The gain may be higher as well
- $A_v \omega_{p,out}$  remains unchanged but  $GBW \uparrow$

□ See Example 10.10 in Sedra/Smith 7<sup>th</sup> ed.



# Frequency Response of CD: HFR

- ❑ The poles can be complex and nearby  $\rightarrow$  OCTC cannot be used ☹
  - Simple circuit, but complicated and lengthy analysis!
- ❑ Special case 1:  $R_{sig} = 0$
- ❑ Special case 2:  $R_S \rightarrow IDC$ ,  $C_L = 0$ ,  $g_{mb}$  and  $r_o$  neglected,  $A_v \equiv 1$



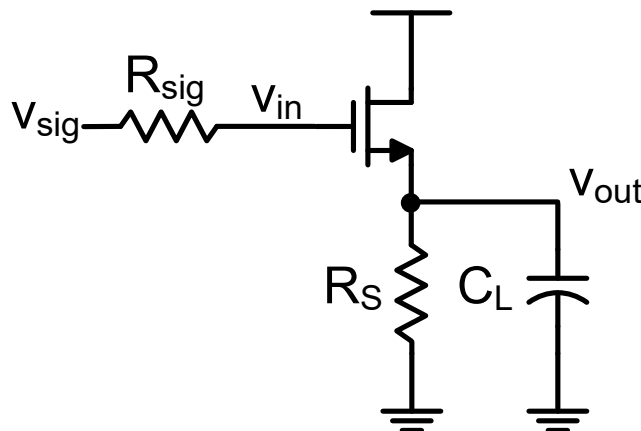
# Frequency Response of CD: HFR

- ❑ Special case 1:  $R_{sig} = 0$ 
  - Only one pole at the output

$$\omega_{p,out} = \frac{1}{\left(R_S // \frac{1}{g_m + g_{mb}}\right)(C_L + C_{gs} + C_{sb})} \rightarrow \text{Large BW (why?)}$$

- ❑ Special case 2:  $R_S \rightarrow IDC$ ,  $C_L = 0$ ,  $g_{mb}$  and  $r_o$  neglected,  $A_v \equiv 1$ 
  - Apply Miller:  $C_{gs}$  is **bootstrapped**

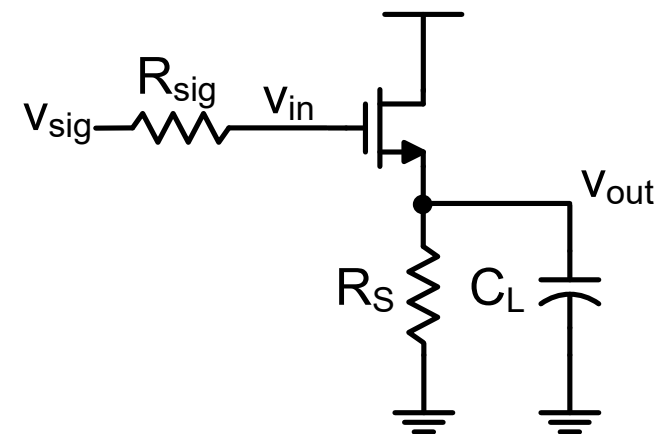
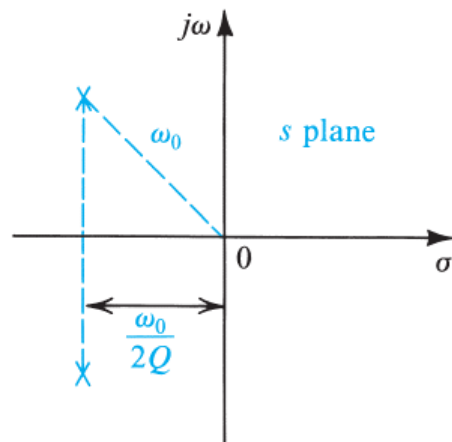
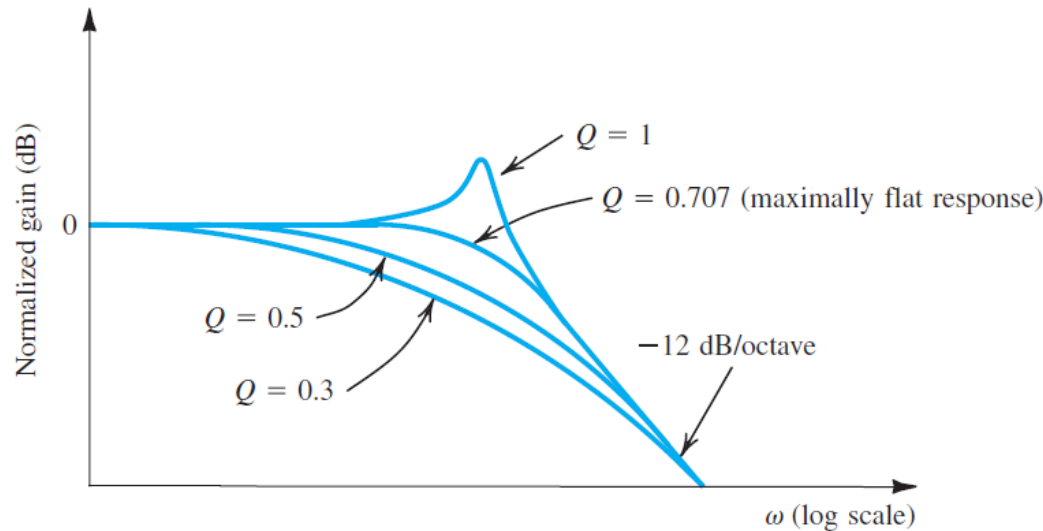
$$\omega_{p,in} = \frac{1}{R_{sig}C_{gd}} \rightarrow \text{Large BW (why?)}$$





# Frequency Response of CD: HFR

- ❑ The poles can be complex and nearby  $\rightarrow$  OCTC cannot be used ☹
  - Simple circuit, but complicated and lengthy analysis!



# Frequency Response of CD: $Z_{in}$

□  $i_{in} = f(v_{gs}) = v_{gs} s C_{gs}$

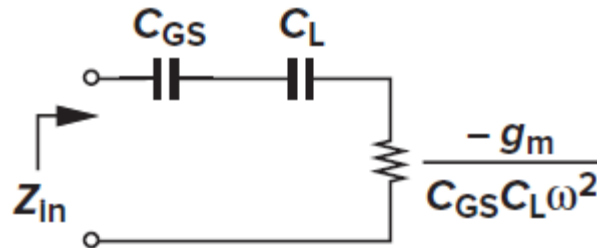
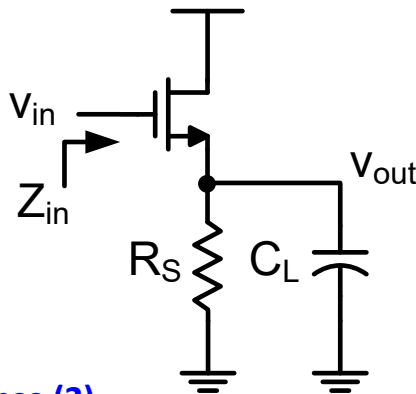
□  $v_{in} = f(v_{gs}) = v_{gs} + (v_{gs} s C_{gs} + g_m v_{gs}) \left( R_S // r_o // \frac{1}{g_{mb}} // \frac{1}{s C_L} \right)$

$$Z_{in} = \frac{v_{in}}{i_{in}} = \frac{1}{s C_{gs}} + \left( 1 + \frac{g_m}{s C_{gs}} \right) \left( R_S // r_o // \frac{1}{g_{mb}} // \frac{1}{s C_L} \right)$$

□ If  $\frac{1}{s C_L}$  is dominant (e.g., CD driving large cap load, or @ high freq)

$$Z_{in} \approx \frac{1}{s C_{gs}} + \frac{1}{s C_L} + \frac{g_m}{s^2 C_{gs} C_L} = \frac{1}{j \omega C_{gs}} + \frac{1}{j \omega C_L} - \frac{g_m}{\omega^2 C_{gs} C_L} \rightarrow \text{-ve res?!}$$

□ Can be used in oscillators, and may make amplifiers unstable!



# Frequency Response of CD: $Z_{out}$

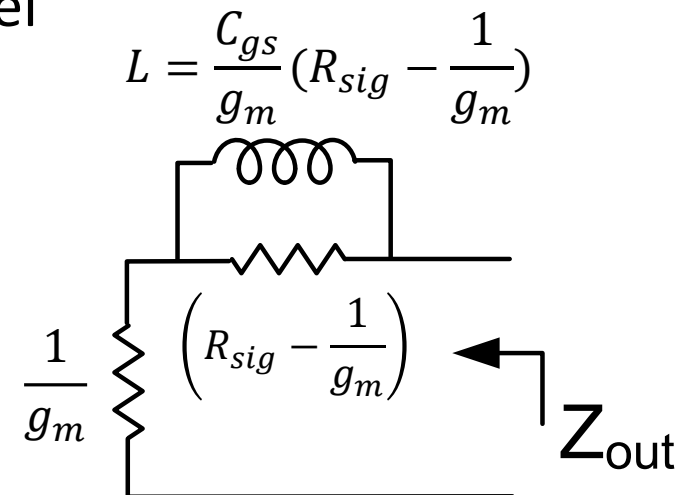
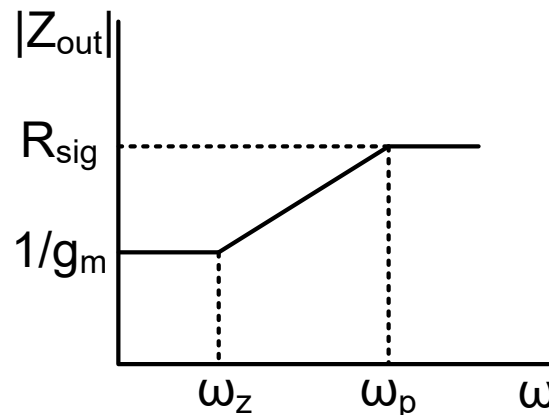
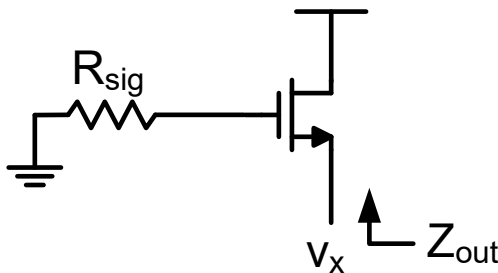
$$\square i_x = f(v_{gs}) = -v_{gs} s C_{gs} - g_m v_{gs}$$

$$\square v_x = f(v_{gs}) = -v_{gs} - v_{gs} s C_{gs} R_{sig}$$

$$Z_{out} = \frac{v_x}{i_x} = \frac{1 + s C_{gs} R_{sig}}{s C_{gs} + g_m} = \frac{1}{g_m} \left( \frac{1 + s R_{sig} C_{gs}}{1 + s \frac{C_{gs}}{g_m}} \right) \rightarrow @ \omega \uparrow\uparrow: Z_{out} \approx R_{sig}$$

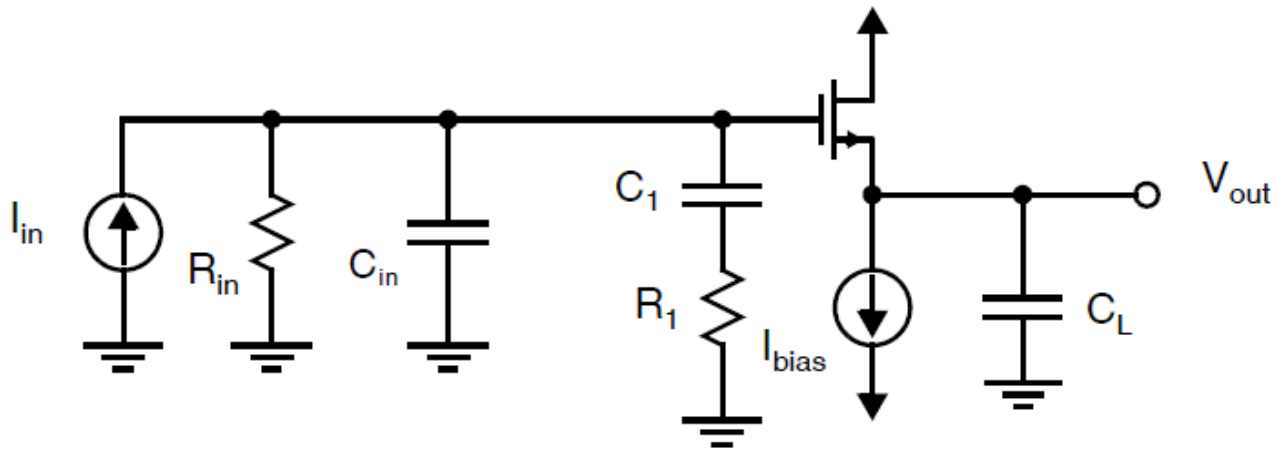
$\square$  Usually  $R_{sig} > \frac{1}{g_m}$  (buffer)  $\rightarrow$  inductive rise

$\square$  Body resistance  $\left(\frac{1}{g_{mb}}\right)$  and  $r_o$  add in parallel



# Frequency Response of CD: HFR

- ❑ A compensation network ( $R_1$  and  $C_1$ ) can be used to compensate for the negative input impedance and prevent overshoots
- ❑ See Johns and Martin Section 4.4 for more details



---

**Thank you!**

# Frequency Response of CD: HFR

$$\frac{v_{out}}{v_{sig}} = A_M \frac{1 + \frac{s}{\omega_z}}{1 + b_1 s + b_2 s^2} = A_M \frac{1 + \frac{s}{\omega_z}}{1 + \frac{1}{Q} \frac{s}{\omega_o} + \frac{s^2}{\omega_o^2}}$$

$$\frac{v_{out}}{v_{sig}} = A_M \frac{1 + \frac{s}{\omega_z}}{\left(1 + \frac{s}{\omega_{p1}}\right) \left(1 + \frac{s}{\omega_{p2}}\right)} = A_M \frac{1 + \frac{s}{\omega_z}}{1 + \left(\frac{1}{\omega_{p1}} + \frac{1}{\omega_{p2}}\right) s + \frac{s^2}{\omega_{p1} \omega_{p2}}}$$

$$\omega_z = \frac{g_m}{C_{gs}}, \omega_o = \frac{1}{\sqrt{b_2}}, Q = \frac{\sqrt{b_2}}{b_1}, R_{Leff} = R_S // r_o // \frac{1}{g_{mb}}$$

$$b_1 = \left( C_{gd} + \frac{C_{gs}}{g_m R_{Leff} + 1} \right) R_{sig} + \left( \frac{C_{gs} + C_L}{g_m R_{Leff} + 1} \right) R_{Leff}$$

$$b_2 = \left( \frac{(C_{gs} + C_{gd}) C_L + C_{gs} C_{gd}}{g_m R_{Leff} + 1} \right) R_{sig} R_{Leff}$$

# Frequency Response of CD: HFR

□ Special case:  $R_{Leff} \uparrow\uparrow$

$$\frac{v_{out}}{v_{sig}} = A_M \frac{1 + \frac{s}{\omega_z}}{1 + b_1 s + b_2 s^2} A_M = \frac{1 + \frac{s}{\omega_z}}{1 + \left( \frac{1}{\omega_{p1}} + \frac{1}{\omega_{p2}} \right) s + \frac{s^2}{\omega_{p1} \omega_{p2}}}$$

$$b_1 = C_{gd} R_{sig} + \frac{C_{gs} + C_L}{g_m}$$
$$b_2 = \left( \frac{(C_{gs} + C_{gd}) C_L + C_{gs} C_{gd}}{g_m} \right) R_{sig}$$

□ If  $C_L = 0$

$$b_1 = C_{gd} R_{sig} + \frac{C_{gs}}{g_m} = \frac{1}{\omega_{p1}} + \frac{1}{\omega_{p2}} \Rightarrow \omega_{p2} = \omega_z$$
$$b_2 = C_{gd} R_{sig} \cdot \frac{C_{gs}}{g_m} = \frac{1}{\omega_{p1}} \frac{1}{\omega_{p2}}$$

# Frequency Response of CD: HFR

□ Special case:  $\omega_{p1}$  is dominant

$$\frac{v_{out}}{v_{sig}} = A_M \frac{1 + \frac{s}{\omega_z}}{1 + b_1 s + b_2 s^2} \approx A_M \frac{1 + \frac{s}{\omega_z}}{1 + \left(\frac{1}{\omega_{p1}}\right) s + \frac{s^2}{\omega_{p1} \omega_{p2}}}$$

$$\omega_{p1} \approx \frac{1}{b_1}$$

$$\omega_{p2} \approx \frac{b_1}{b_2}$$