

January 26th,2022

Course Code: CSE347-CSE345

Time: 2 Hours

Embedded System Design & Real-Time Embedded System Design

The Exam Consists of 5 Questions in 5 Pages

Total Marks: 40 Marks

تنبيه هام جدا: يجب على كل طالب الحل فقط هنا في ورق الاسئلة ولن يلتفت لأي إجابة في الكراسة المرفقة والتي تحتوي على البار كود الخاص بكل طالب

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- This is an answer sheet.
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تعليمات هامة حيازة (المحمول- الساعات الذكية - سماعة الأذن) داخل لجنة

- حياره (المحمول- الساعات الدكية سماعة الدك) داخل لجنا الامتحان يعتبر حالة غش تستوجب العقاب.
- لايسمح بدخول أي كتب أو ملازم أو أوراق داخل اللجنة والمخالفة تعتب حالة غش
- هذه ورقة إجابة أيضا أقرأها أولا جيدا أفترض الناقص إن وجد

Question 1: (7 Marks)

For the following FreeRTOS based application snippet, order the first 7 breakpoints (in designated table) hit while debugging.

BP Order	BP1	BP2	BP3	BP4	BP5	BP6	BP7
Line Number	57	78	67	79	78	68	67

```
int main( void )
53
54 - {
      xTaskCreate( vTask1, NULL, 240, NULL, 1, NULL );
55
      xTaskCreate( vTask2, NULL, 240, NULL, 2, &xTask2Handle );
56
57
      vTaskStartScheduler();
58
      for( ;; );
59
   L
    void vTaskl( void *pvParameters )
60
61 □ {
    unsigned portBASE TYPE uxPriority;
62
63
      unsigned ux;
64
      uxPriority = uxTaskPriorityGet( NULL );
65
      for(;;)
66
        vTaskPrioritySet( xTask2Handle, ( uxPriority + 1 ) );
67
68
69
70
   L
71
    void vTask2( void *pvParameters )
72 - {
    unsigned portBASE TYPE uxPriority;
73
74
        unsigned ux;
      uxPriority = uxTaskPriorityGet( NULL );
75
76
      for( ;; )
77
      £
        vTaskPrioritySet( NULL, ( uxPriority - 2 ) );
78
79
80
      }
81
```

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Question 2: (10 Marks)

Assume the following snippet of code/application that already had all necessary declarations, inclusions, and prototypes. In the given table, order the first 10 break points to be hit, when GO is pressed.

1 st Break Point Hit	2 nd Break Point Hit	3 rd Break Point Hit	4 th Break Point Hit	5 th Break Point Hit
95	95 98		108	115

6 th Break Point Hit	7 th Break Point Hit	8 th Break Point Hit	9 th Break Point Hit	10 th Break Point Hit
116	109	106	99	98

```
82 int main ( void )
 83 - {
         vSemaphoreCreateBinary( xBinarySemaphore );
 84
 85
         if( xBinarySemaphore != NULL )
 86
 87
             prvSetupSoftwareInterrupt();
             xTaskCreate( vHandlerTask, NULL , 240, NULL, 3, NULL );
 88
 89
             xTaskCreate( vPeriodicTask, NULL, 240, NULL, 1, NULL );
 90
             vTaskStartScheduler();
 91
 92 -}
    static void vHandlerTask( void *pvParameters )
 94 🖂 {
         xSemaphoreTake( xBinarySemaphore, 0 );
 95
 96
         for(;;)
 97 E
 98
             xSemaphoreTake( xBinarySemaphore, portMAX DELAY );
 99
             vPrintString( "Handler task - Processing event.\n" );
100
101 |
102 static void vPeriodicTask( void *pvParameters )
103 - {
104
         for( ;; )
105
         {
106
             vTaskDelay( 100 / portTICK RATE MS );
107
             vPrintString( "Periodic task - About to generate an interrupt.\n" );
108
             mainTRIGGER INTERRUPT();
109
             vPrintString( "Periodic task - Interrupt generated.\n\n" );
110
111 |
112 void vSoftwareInterruptHandler( void )
113 - {
114 | portBASE TYPE xHigherPriorityTaskWoken = pdFALSE;
         xSemaphoreGiveFromISR( xBinarySemaphore, &xHigherPriorityTaskWoken );
115
116 |
```

Embedded System Design & Real-Time Embedded System Design

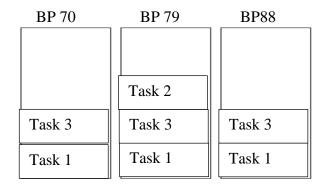
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Question 3: (6 Marks)

Assume the following snippet of code/application that already had all necessary declarations, inclusions, and prototypes. Assume "heap2" FreeRTOS Heap memory algorithm is used. Show in the figures below how Heap memory looks like at designated break points when first hit after starting the schedular.

```
54
55
56
    int main ( void )
57 - {
      xTaskCreate( vTask1, NULL, 240, NULL, 2, NULL);
58
      xTaskCreate( vTask3, NULL, 240, NULL, 3, NULL);
59
      vTaskStartScheduler();
60
61
      for( ;; );
   L
62
    /*-
63
    void vTaskl( void *pvParameters )
65 □ {
66
      for( ;; )
67
        vPrintString( "Taskl is running\n" );
68
69
        xTaskCreate( vTask2, NULL, 240, NULL, 4, NULL);
        vTaskDelay( 200 / portTICK RATE MS );
70
71
  L
72
73
74
    void vTask2( void *pvParameters )
75 🖵 {
76
      for( ;; )
77 🗀
78
        vPrintString( "Task2 is running\n" );
79
        vTaskDelete(NULL);
80
   L
81
82
    void vTask3( void *pvParameters )
84 - {
85
      for( ;; )
86
        vPrintString( "Task3 is running\n" );
87
        vTaskDelay( 200 / portTICK RATE MS );
88
89
90
91
```



Embedded System Design & Real-Time Embedded System Design

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Question 4: (10 Marks)

Assume the following snippet of code/application that already had all necessary declarations, inclusions, and prototypes. In the given table, order the first 8 break points (PB) to be hit, when GO is pressed. At each PB, Define the states of all tasks. (Hint: Sender2 will be the first to execute once Scheduler starts)

Break Point at Line?	State of Sender 1	State of Sender 2	State of Receiver
77	ready	running	ready
78	ready	running	ready
77	running	ready	ready
77	Block	running	ready
86	Block	Block	running
78	running	Block	ready
77	running	Block	ready
87	Block	Block	running
86	Block	Block	running
78	Block	running	ready

```
int main ( void )
60 □ {
        xQueue = xQueueCreate( 1, sizeof( long ) );
62
        if ( xQueue != NULL )
63
          *TaskCreate( vSenderTask, "SENDER1", 240, ( void * ) 100, 3, NULL );
*IaskCreate( vSenderTask, "SENDER2", 240, ( void * ) 200, 3, NULL );
*XTaskCreate( vReceiverTask, NULL, 240, NULL, 2, NULL );
64
65
67
           vTaskStartScheduler();
68
69
        for( ;; );
70
71
     static void vSenderTask( void *pvParameters )
72 🗏 {
     long lValueToSend:
73
74
        1ValueToSend = ( long ) pvParameters;
        for( ;; )
76
           xQueueSendToBack( xQueue, &lValueToSend, 100 / portTICK_RATE_MS );
78
           taskYIELD():
79
   L
81
     static void vReceiverTask( void *pvParameters )
82 🖵 (
83
     long lReceivedValue;
84
       for( ;; )
85
          xQueueReceive( xQueue, &lReceivedValue, 100 / portTICK_RATE_MS );
vPrintStringAndNumber( "Received = ", lReceivedValue );
86
87
88
90
```

Embedded System Design & Real-Time Embedded System Design

The Exam Consists of **5 Questions in 5 Pages**Total Marks: **40 Marks**

5/5

Question 5: (8 Marks)

For the following FreeRTOS based application snippet, **order the first 7 breakpoints** (in designated table) hit while debugging.

BP Order	BP1	BP2	BP3	BP4	BP5	BP6	BP7
Line Number	69	75	76	92	78	94	85

```
66 mint main ( void ) {
      xmutex = xSemaphoreCreateMutex();
      xTaskCreate(vtask1, "Task 1", 200, NULL, 1, NULL);
68
      vTaskStartScheduler();
69
70 -}
71
   void vtaskl(void *pvParameters)
73
      for(;;)
74
75
        xSemaphoreTake(xmutex, portMAX DELAY);
76
        xTaskCreate(vtask3,"Task 3",200, NULL, 3,NULL);
77
        xTaskCreate(vtask2, "Task 2", 200, NULL, 2, NULL);
78
        xSemaphoreGive(xmutex);
79
80
   void vtask2(void *pvParameters)
82 🗏 {
      for(;;)
83
84
        vTaskDelay(200);
85
86
87
   void vtask3(void *pvParameters)
89 🗌 {
90
      for(;;)
91 😑
92
        xSemaphoreTake(xmutex, portMAX DELAY);
        xSemaphoreGive(xmutex);
93
94
        vTaskDelay(200);
95
      3
96 -}
```



تعليمات هامة

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Line Number							

```
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   int main( void )
54 - {
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5.5
      xTaskCreate( vTask2, NULL, 240, NULL, 2, &xTask2Handle );
56
57
      vTaskStartScheduler();
58
      for( ;; );
59
   L
    void vTaskl( void *pvParameters )
60
61 □ {
    unsigned portBASE TYPE uxPriority;
62
63
      unsigned ux;
64
      uxPriority = uxTaskPriorityGet( NULL );
65
      for(;;)
66
        vTaskPrioritySet( xTask2Handle, ( uxPriority + 1 ) );
67
68
69
70
   L
71
    void vTask2( void *pvParameters )
72 - {
    unsigned portBASE TYPE uxPriority;
73
74
        unsigned ux;
      uxPriority = uxTaskPriorityGet( NULL );
75
76
      for( ;; )
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      £
        vTaskPrioritySet( NULL, ( uxPriority - 2 ) );
78
79
80
81
```

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         if( xBinarySemaphore != NULL )
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             xTaskCreate( vPeriodicTask, NULL, 240, NULL, 1, NULL );
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             vTaskStartScheduler();
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 92 -}
    static void vHandlerTask( void *pvParameters )
 94 🖂 {
         xSemaphoreTake( xBinarySemaphore, 0 );
 95
 96
         for(;;)
 97 E
 98
             xSemaphoreTake( xBinarySemaphore, portMAX DELAY );
 99
             vPrintString( "Handler task - Processing event.\n" );
100
101 |
102 static void vPeriodicTask( void *pvParameters )
103 - {
104
         for( ;; )
105
         {
106
             vTaskDelay( 100 / portTICK RATE MS );
107
             vPrintString( "Periodic task - About to generate an interrupt.\n" );
108
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109
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112 void vSoftwareInterruptHandler( void )
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         xSemaphoreGiveFromISR( xBinarySemaphore, &xHigherPriorityTaskWoken );
115
116 |
```

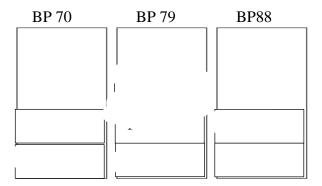
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      xTaskCreate( vTask3, NULL, 240, NULL, 3, NULL);
59
      vTaskStartScheduler();
60
61
      for( ;; );
   L
62
63
    void vTaskl( void *pvParameters )
65 □ {
66
      for( ;; )
67
        vPrintString( "Taskl is running\n" );
68
69
        xTaskCreate( vTask2, NULL, 240, NULL, 4, NULL);
        vTaskDelay( 200 / portTICK RATE MS );
70
71
   L
72
73
74
    void vTask2( void *pvParameters )
75 🗐 {
76
      for( ;; )
77
78
        vPrintString( "Task2 is running\n" );
79
        vTaskDelete(NULL);
80
   L)
81
82
    void vTask3( void *pvParameters )
84 - {
85
      for( ;; )
86 🗀
        vPrintString( "Task3 is running\n" );
87
        vTaskDelay( 200 / portTICK_RATE MS );
88
89
90
91
```



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4/5

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at Line? State of Sender 1 State of Sender 2		State of Receiver		
		-		
	-			
	ļ ·			
		<u> </u>		
	1			

```
59
    int main ( void )
60 □ {
        xQueue = xQueueCreate( 1, sizeof( long ) );
62
        if ( xQueue != NULL )
63
          *TaskCreate( vSenderTask, "SENDER1", 240, ( void * ) 100, 3, NULL );
*IaskCreate( vSenderTask, "SENDER2", 240, ( void * ) 200, 3, NULL );
*XTaskCreate( vReceiverTask, NULL, 240, NULL, 2, NULL );
64
65
67
           vTaskStartScheduler();
68
69
        for( ;; );
70
71
     static void vSenderTask( void *pvParameters )
72 🗏 {
     long lValueToSend:
73
74
        1ValueToSend = ( long ) pvParameters;
        for( ;; )
76
           xQueueSendToBack( xQueue, &lValueToSend, 100 / portTICK_RATE_MS );
78
           taskYIELD():
79
   L
81
     static void vReceiverTask( void *pvParameters )
82 🖵 (
83
     long lReceivedValue:
84
       for( ;; )
85
          xQueueReceive( xQueue, &lReceivedValue, 100 / portTICK_RATE_MS );
vPrintStringAndNumber( "Received = ", lReceivedValue );
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88
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```

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Line Number							

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      xTaskCreate(vtask1, "Task 1", 200, NULL, 1, NULL);
68
69
      vTaskStartScheduler();
70 -}
71
   void vtaskl(void *pvParameters)
73
      for(;;)
74
75
        xSemaphoreTake(xmutex, portMAX DELAY);
76
        xTaskCreate(vtask3,"Task 3",200, NULL, 3,NULL);
77
        xTaskCreate(vtask2, "Task 2", 200, NULL, 2, NULL);
78
        xSemaphoreGive(xmutex);
79
80
   void vtask2(void *pvParameters)
82 🗏 {
      for(;;)
83
84
        vTaskDelay(200);
85
86
87
   void vtask3(void *pvParameters)
89 🗌 {
90
      for(;;)
91 😑
92
        xSemaphoreTake(xmutex, portMAX DELAY);
        xSemaphoreGive(xmutex);
93
94
        vTaskDelay(200);
95
      3
96 -}
```