



**Section 5**

**Sheet 4**

# pointer

```
Void main ()
```

```
{
```

```
    Char x=5;
```

```
    Char * pr;
```

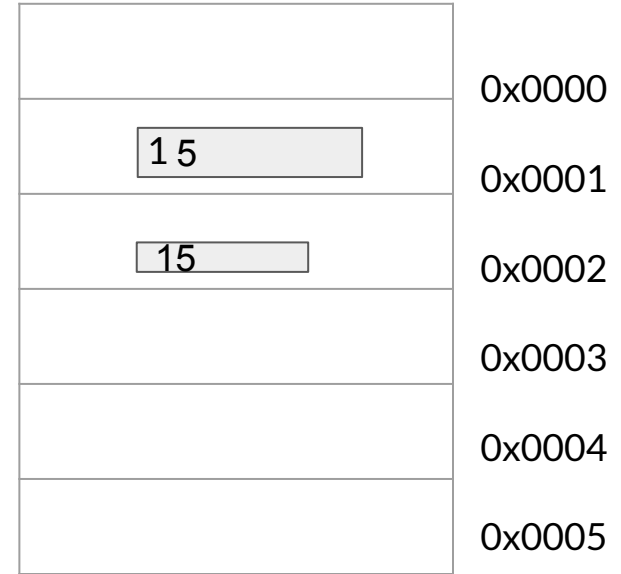
```
    ptr= &x;
```

```
    *ptr=15;
```

```
    ptr++;
```

```
    *ptr=15;
```

```
}
```



mem

~~0x0001~~ 0x0002

# pointer

```
Void main ()  
{
```

```
    Char arr[6]={0,0,0,0,0,0};
```

```
    Char *ptr=arr;
```

```
    for(i=0;i<6;i++)  
        *(ptr+i)=10;
```

```
}
```

//0//	10	0x0000
//0//	10	0x0001
//0//	10	0x0002
//0//	10	0x0003
//0//	10	0x0004
//0//	10	0x0005

mem

0x0000, 0x0001, 0x0002 and so on

# stack

CODE

0xFC4801A4  
0xAC40 0208  
0x1800FFFC

CONST

Startup code

Bootloader

ROM

```
int result =1;
char flag;
int add(int x,int y)
{
    result=x+y;
    return result;
}
int sub(int n1,n2)
{
    if(n1>n2){flag=1;}
    result=n1-n2;
    return result;
}
```

```
Void main()
    result=sub(5,4);
    if(flag==1)
    {
        printf(result);
    }
```

DATA

result

BSS

flag

STACK

x

n1

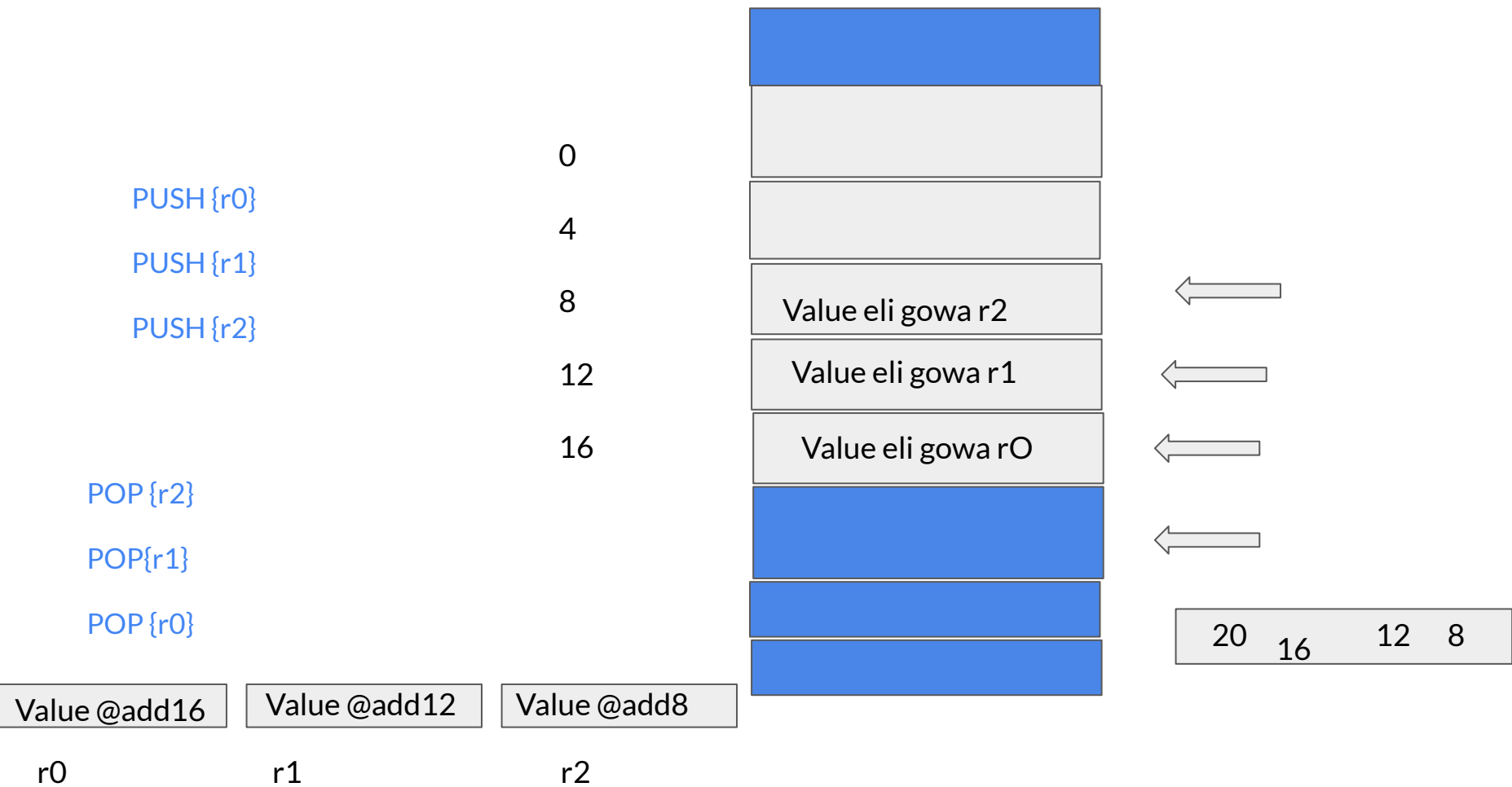
y

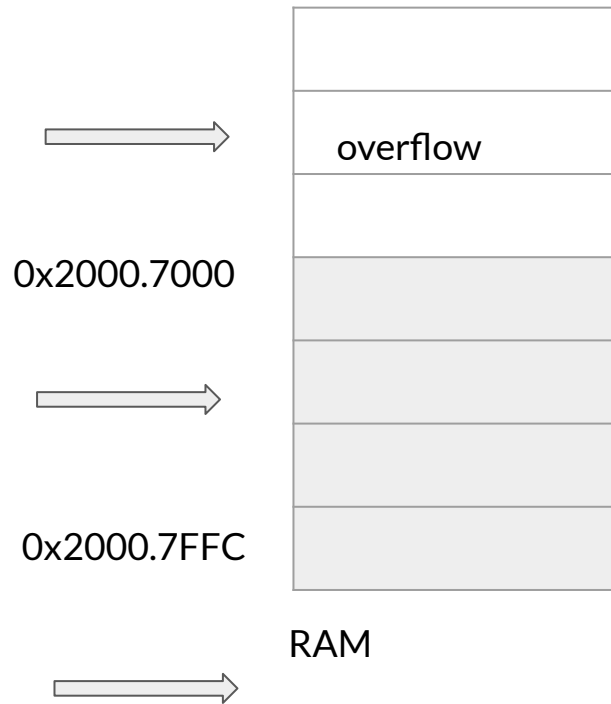
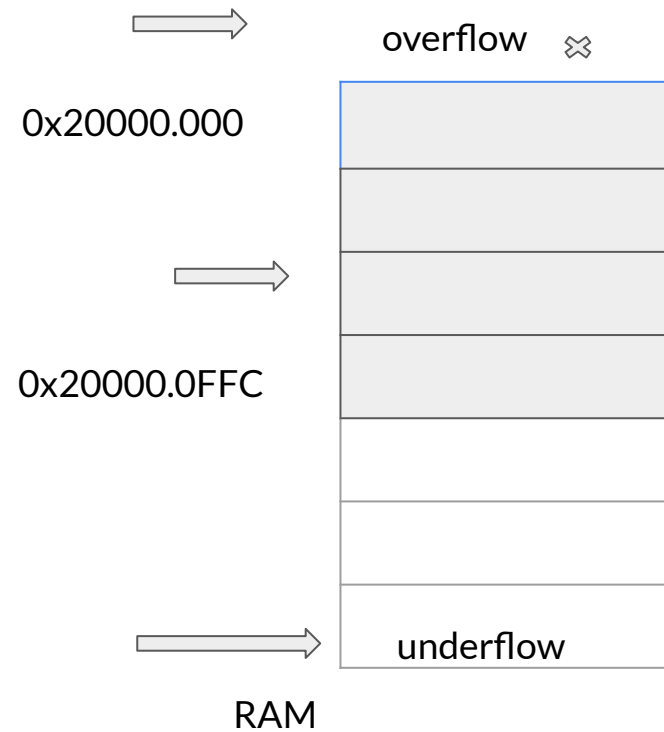
n2

Heap

RAM

# stack





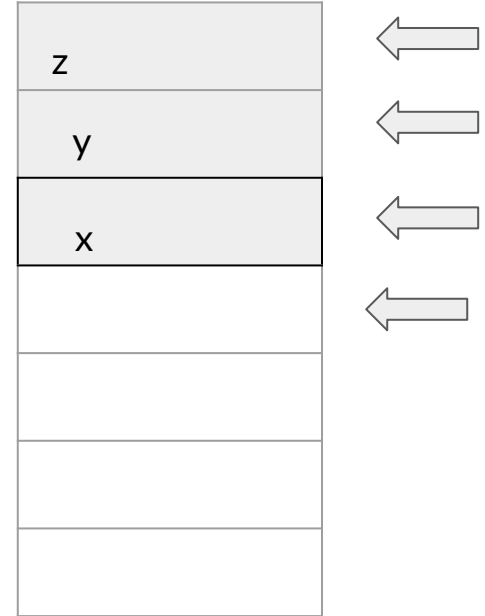
# stack

```
void main
{
  r4=x,r5=y,6=z
  f1()
  r4?
}
```

```
f1()
{
    Push {r6,r5,r4}

    Move r4 #100
    add r5 r5 r6
    Pop{r6}
    Pop{r5}
    pop{4}
}
```

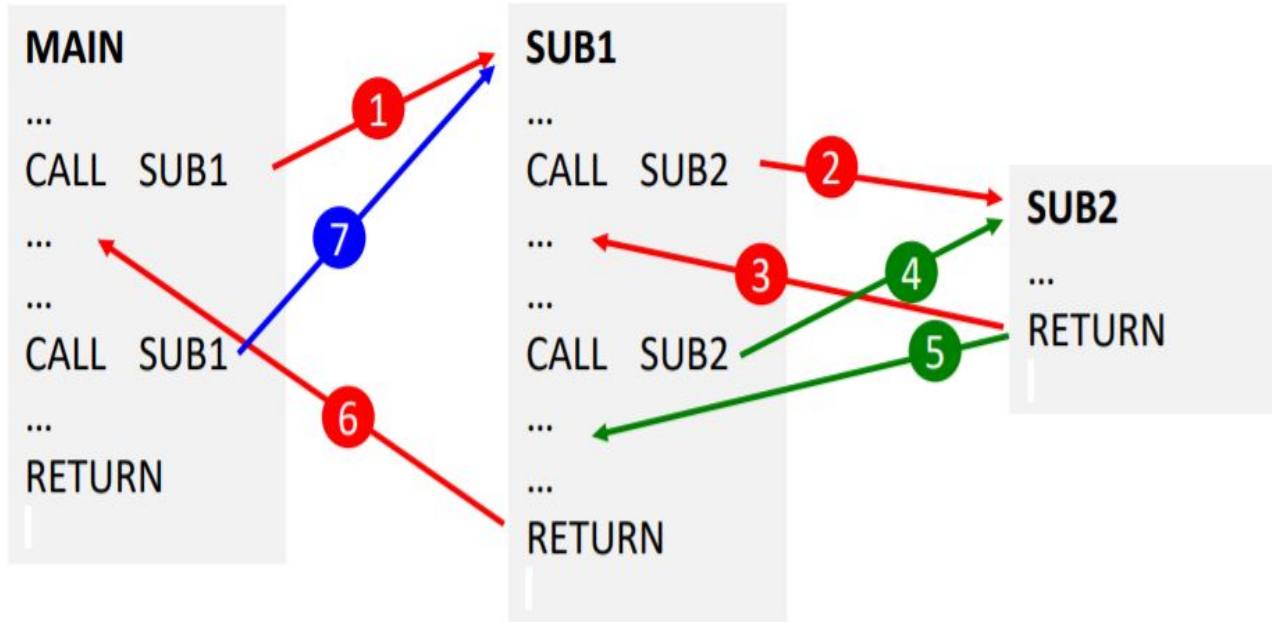
R4	<del>/x/</del> 100
R5	<del>y/</del> 10
r6	z



mem

# Subroutine

a subroutine is a sequence of instructions that performs a particular task  
subroutine called wherever task needs to be performed






# Subroutine

- to call a subroutine use the BL (branch and link) instruction
- saves return address in link register (LR = R14)

0x00000400    BL        SUB1        ; LR = 0x00000404 (return address)

0x00000404    ...                    ;



return address = address of next instruction

to return from a subroutine use BX (branch and exchange) specifying the link register (LR)

BX        LR        ; PC (program counter) = LR

# Subroutine

at the start of every non leaf subroutine, push the contents of LR (link register), which contains the return address, onto the system stack

return from a non leaf subroutine by popping return address from stack and assigning to the PC (program counter)

```
SUB1  PUSH   {LR}    ; push link register onto stack
```

```
...
```

```
...
```

```
POP    {PC}    ; return by popping saved return address into PC
```

# Stack task

Write by c++ stack:

- 1- user can create stack with any size ,push,pop and view content.
- 2- guarantee no stack over flow ,or stack underflow.
- 3- use copy constructor.

```
97 }
98 int main()
99 {
100     Stack s1(3);
101     s1.push(5);
102     s1.push(14);
103     viewcontent(s1);
104     s1.pop();
105     viewcontent(s1);
106
107     return 0;
108 }
109
```

Build messages

File	Line	Message
C:\Users\mo...		=== Build: Debug in iti32 (compiler: GNU GCC Compiler) ===
C:\Users\mo...	97	In member function 'int Stack::stack(Stack&)': warning: no return statement in function returning non-void [-Wreturn-type]

# Sheet 4

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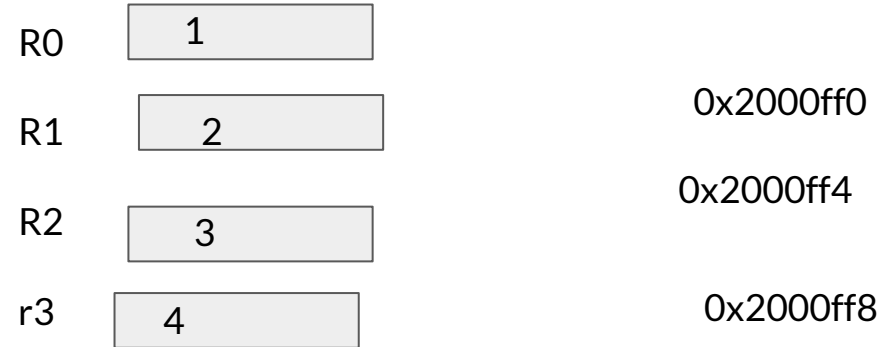
**Q1. When does the LR have to be pushed on the stack?**

When a function calls another function, the LR is saved in the stack to avoid losing the return address of the caller function.

Q2. Show the SP value and the content of stack after executing this instruction PUSH{R4, R6-R8} assuming

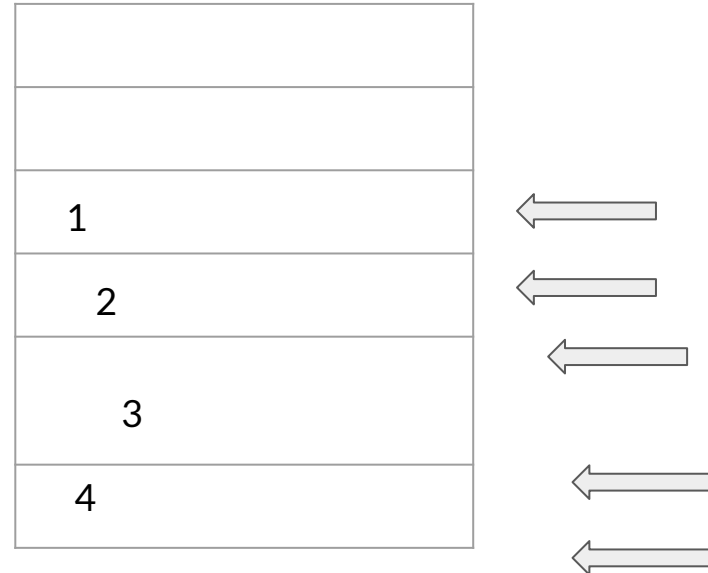
the SP initially equals 0x2000.1000 and R4=1, R6=2, R7=3, R8=4. What will be the values of the registers R0-R4 after executing this instruction

POP{R0-R3}?



R0=1, R1=2, R2=3, R3=4

0x2000.1000  
sp



---

Q3. Explain how does the return from subroutine work in these two functions?

**Function PUSH {R4,LR}**

**;stuff**

**POP {R4,PC}**

**Function2**

**;stuff**

**BX LR**

Q4. Write assembly code that pushes registers R1, R3, and R5 onto the stack.

**Answer**

PUSH {R1}

PUSH {R3}

PUSH {R5}

Q5. What are the addressing modes used in each of the following instructions?

LDR R0, [R1]

Indexed add

LDR R2, [R1, #4]

Indexed add with immediate offset

MOV R3, #100

Immediate value

PUSH {R0}

Push & pop register addressing mode

MOV R0, #1

Immed add

LDRB R0, [PC, #0x30]

Relative address

LDR R0, =1234567

Relative address/immediate address

BL func

pc relative mode



Q6. Write a complete ARM assembly program that calls the procedure func1 which in turn calls a procedure func2. The procedure func2 is defined in Q1 of Sheet 3.

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**Reset\_Handler**

BL func1

DeadLoop B DeadLoop

func1      PUSH {LR}

            BL func2

            POP {LR}

            BX LR