AIN SHAMS UNIVERSITY FACULTY OF ENGINEERING

ICHEP; Mechatronics Engineering Program



August --th, 2021 Course Code: CSE 347 Time: 1 Hour

Mid Term; Embedded System Design

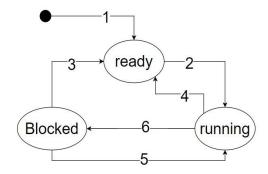
The Exam Consists of <u>4</u> Questions in <u>4 Pages</u>

Total Marks: 25 Marks

Question 1: (6 marks)

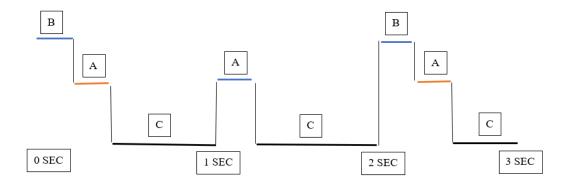
Match a transition-number with the sentence that is suitable to change the task state as it shown:

- A. Task is unblocked but is not the highest priority task (3)
- B. Task has the highest priority (2)
- C. Task no longer has the highest priority (4)
- D. Task is unblocked and it's the highest priority task (5)
- E. Task is waiting for an event (6)
- F. Task is initialized and activated (1)



Question 2: (3 marks)

In a FreeRTOS project, three short tasks were created (Task A, Task B and Task C). Task A and Task B are having the periods 1Sec and 2Sec, respectively. Task C is a continuous task. Their priorities are 2, 3, and 1, respectively. Sketch tasks timing diagram for the first 3 Seconds. Vertical axe is the priority level while the horizontal axe is the time in seconds.



Prof. Dr. Sherif Hammad Exam. Time: 8 May 2021/11:00

Embedded System Design

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Question 3: (9 marks)

Assume the following snippet of code/application that already had all necessary declarations, inclusions, and prototypes. In the given table, order the first 9 break points to be hit, when GO is pressed.

```
54 int main( void )
55 □ {
56
57
     xTaskCreate( vTask1, "Task 1", 240, NULL, 2, NULL);
     xTaskCreate( vTask2, "Task 2", 240, NULL, 1, &xTask2Handle );
58
59
     vTaskStartScheduler();
60
     for(;;);
61 L}
64 void vTask1 (void *pvParameters)
     unsigned portBASE TYPE uxPriority;
67
     uxPriority = uxTaskPriorityGet( NULL );
     for(;;)
68
69 🖨
       vPrintString( "Task1 is running\n" );
70
       vPrintString( "About to raise the Task2 priority\n" );
71
       vTaskPrioritySet(xTask2Handle, (uxPriority + 1));
73
74
   }
75
78 void vTask2( void *pvParameters )
79 ⊟ {
80
     unsigned portBASE TYPE uxPriority;
     uxPriority = uxTaskPriorityGet( NULL );
81
82
     for(;;)
84
       vPrintString( " Hi \n" );
       vPrintString( "About to lower the Task2 priority\n" );
85
       vTaskPrioritySet( NULL, ( uxPriority - 2 ) );
       vPrintString( " Bye \n" );
87
88
89 L}
```

1 st Break Point Hit	2 nd Break Point Hit	3 rd Break Point Hit	4 th Break Point Hit	5 th Break Point Hit
70	72	84	86	70

6 th Break Point Hit	7 th Break Point Hit	8 th Break Point Hit	9 th Break Point Hit
72	87	84	86

Question 4: (7 marks)

2/4

Embedded System Design

The Exam Consists of 4 Questions in 4 Pages Total Marks: 25 Marks

3/4

Assume the following snippet of code/application that already had all necessary declarations, inclusions, and prototypes. In the given table, order the first 9 break points to be hit, when GO is pressed.

```
59 int main( void )
\bowtie
     60 ⊟ {
            xQueue = xQueueCreate( 5, sizeof( long ) );
     61
          if( xQueue != NULL )
     63 ⊨
            xTaskCreate( vSenderTask, "Sender", 240, ( void * ) 100, 1, NULL );
     64
            xTaskCreate( vReceiverTask, "Receiver", 240, NULL, 2, NULL);
     65
            vTaskStartScheduler();
     66
          }
     67
     68
          else
     /* The queue could not be created. */
     70
     71
    72
          for(;;);
    73 }
     76 static void vSenderTask( void *pvParameters )
     77 □ {
     78
          long lValueToSend;
     79
          portBASE TYPE xStatus;
          lValueToSend = ( long ) pvParameters;
     80
     81
          for(;;)
     82 白
            xStatus = xQueueSendToBack( xQueue, &lValueToSend, 0 );
     83
            if( xStatus != pdPASS )
     84
     85 🖨
     86
              vPrintString( "Could not send to the queue.\r\n" );
     87
     88
          }
     89 L}
```

Total Marks: 25 Marks

Embedded System Design

The Exam Consists of <u>4</u> Questions in <u>4</u> Pages

4/4

```
92 static void vReceiverTask( void *pvParameters )
 93 □ {
      long lReceivedValue;
 94
 95
       portBASE TYPE xStatus;
       const portTickType xTicksToWait = 100 / portTICK RATE MS;
 97
       for(;;)
 98 🖨
 99
         if( uxQueueMessagesWaiting( xQueue ) != 0 )
100 🖨
          vPrintString( "Queue should have been empty!\r\n" );
101
102
         xStatus = xQueueReceive( xQueue, &lReceivedValue, xTicksToWait );
103
104
105
         if( xStatus == pdPASS )
106 🖨
107
          vPrintStringAndNumber( "Received = ", lReceivedValue );
108
         }
109
         else
110 🖨
111
           vPrintString( "Could not receive from the queue.\r\n" );
112
113
      }
114 |
```

1 st Break Point Hit	2 nd Break Point Hit	3 rd Break Point Hit	4 th Break Point Hit	5 th Break Point Hit
103	83	105	103	84

6 th Break Point Hit	7 th Break Point Hit	
83	105	