AIN SHAMS UNIVERSITY FACULTY OF ENGINEERING Interdisciplinary Engineering Programs



June 19^{th.}, 2019 Course Code: CSE345 & CSE347 Time: 3 Hours

Real Time - Embedded System Design

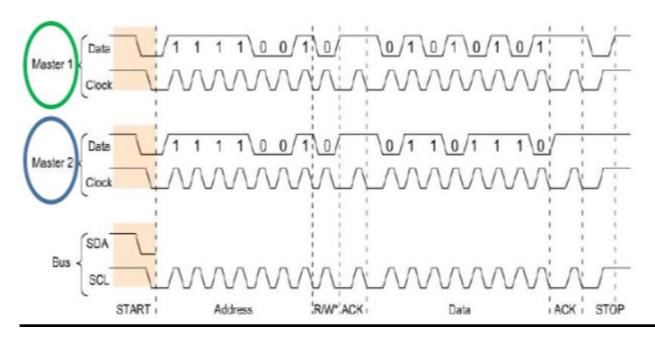
The Exam Consists of 6 Questions in 4 Pages

Total Marks: 40 Marks

1/4 هذه ورقة إجابة أيضا – على كل طالب تدبيسها من الناحية اليسرى في الغلاف الرسمي المعد لذلك – وكتابة بيانات الطالب عليه

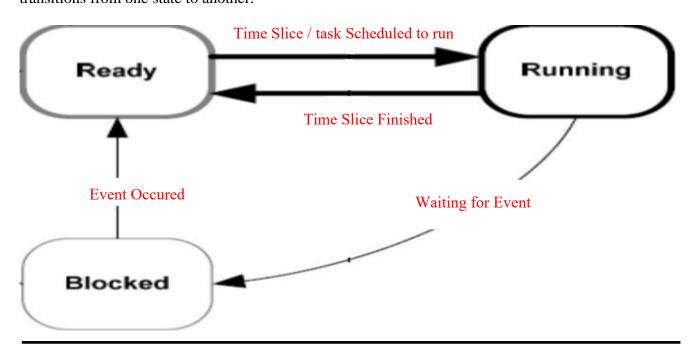
Question (1): (7 Marks)

In the figure below, there are two masters communicating on an I2C bus. Complete the SDA line bits switching.



Question (2): (7 Marks)

The figure below shows a subset of RTOS task state machine. On "Cut" arrows, give all conditions of transitions from one state to another.



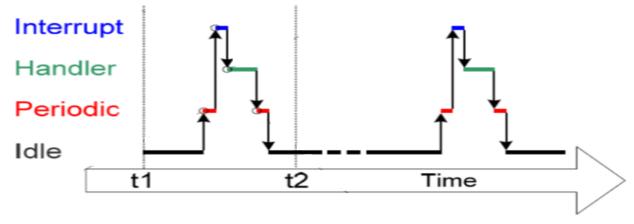
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Question (3): (7 Marks)

The following figure is the timing diagram of a FreeRTOS application. Write the C-code that could achieve this interrupt handling. Assume any missing data if any.



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Question (4): (7 Marks) (Assume Missing Data if Any)

Write the code to reproduce the following "Dead Lock" scenario where Task A and Task B both need to acquire mutex X and mutex Y in order to perform an action:

- 1. Task A executes and successfully takes mutex X.
- 2. Task A is pre-empted by Task B.
- 3. Task B successfully takes mutex Y before attempting to also take mutex X
- 4. If Task A continues executing, it will attempt to take mutex Y

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Question (5): (5 Marks) Complete the following:

- a) Normally, queues are used as -FIFO---- buffers where data is written to ----- of the queue and removed from ------ of the queue.
- b) A task, that is blocked on queue read, will be moved automatically from the to the ----READY----- if the BLOCK-TIME EXPIRED before data becomes available.
- c) If the queue-blocked tasks have equal priority, and the chance comes, then the task that HAS BEEN WAITING-THE-LONGEST will be unblocked.
 - d) During "queue write", the block time is the maximum time the task should be held in the BLOCKED- state to wait for SPACE TO BECOME AVAILABLE- on the queue, should the queue already be ---FULL.

Question (6): (7 Marks)

The figure below is a snap shot from a debugging session. In the following table, document your expectation of the hitting-order of Breakpoints (designated by line numbers; 75, 86 and 87), and the content of designated heap.

```
59
    int main ( void )
60 □ {
      xQueue = xQueueCreate( 2, sizeof( long ) );
61
      xTaskCreate( vSenderTask, "Sender1", 240, ( void * ) 100, 2, NULL );
xTaskCreate( vSenderTask, "Sender2", 240, ( void * ) 200, 2, NULL );
62
63
      xTaskCreate( vReceiverTask, "Receiver", 240, NULL, 1, NULL );
64
65
      vTaskStartScheduler();
66
    static void vSenderTask( void *pvParameters )
67
68 🖵 {
69
    long lValueToSend;
    portBASE TYPE xStatus;
70
    const portTickType xTicksToWait = 100 / portTiCk RATE MS;
71
72
      lValueToSend = ( long ) pvParameters;
73
       for( ;; )
74
75
         xStatus = xQueueSendToBack( xQueue, &lValueToSend, xTicksToWait );
76
         taskYIELD();
77
      1
   L
78
79
    static void vReceiverTask( void *pvParameters )
80 🖵 {
    long lReceivedValue;
81
    portBASE TYPE xStatus;
82
    const portTickType xTicksToWait = 100 / portTICK_RATE_MS;
83
84
      for( ;; )
85 🖨
86
        xStatus = xQueueReceive( xQueue, &lReceivedValue, xTicksToWait );
87
        vPrintStringAndNumber( "Received = ", lReceivedValue );
88
89 -
```

| Hit Order | Break Point No. | Content of Designated Heap | |
|-----------|-----------------|----------------------------|--|
| 1 | 75 | 00000000 00000000 | |
| 2 | 75 | C8000000 00000000 | |
| 3 | 75 | C8000000 64000000 | |
| 4 | 75 | C8000000 64000000 | |
| 5 | 86 | C8000000 64000000 | |
| 6 | 75 | C8000000 64000000 | |
| 7 | 87 | C8000000 64000000 | |

End of Questions