

Figure 11 : Sous-ensembles principaux du robot

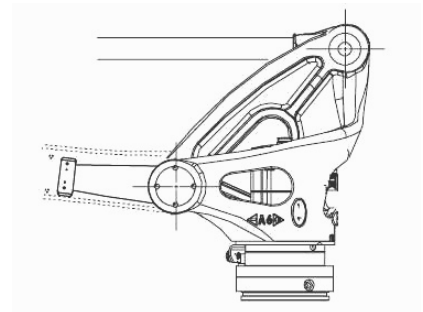


Figure 12 : Bride de fixation

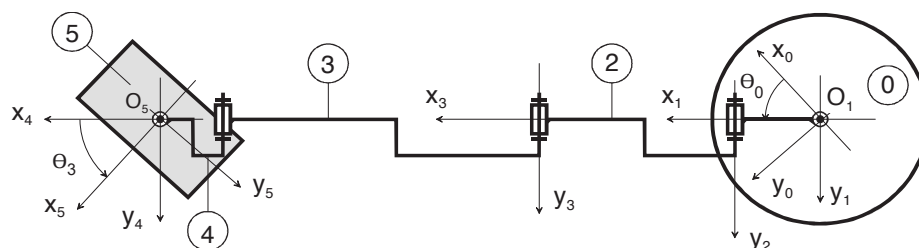
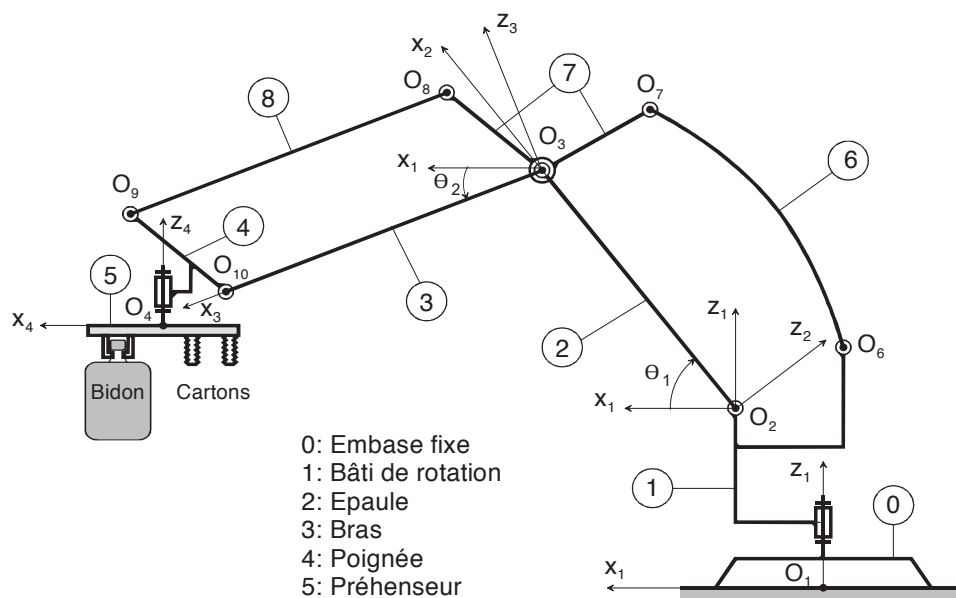


Figure 13 : Schéma cinématique du robot Kuka