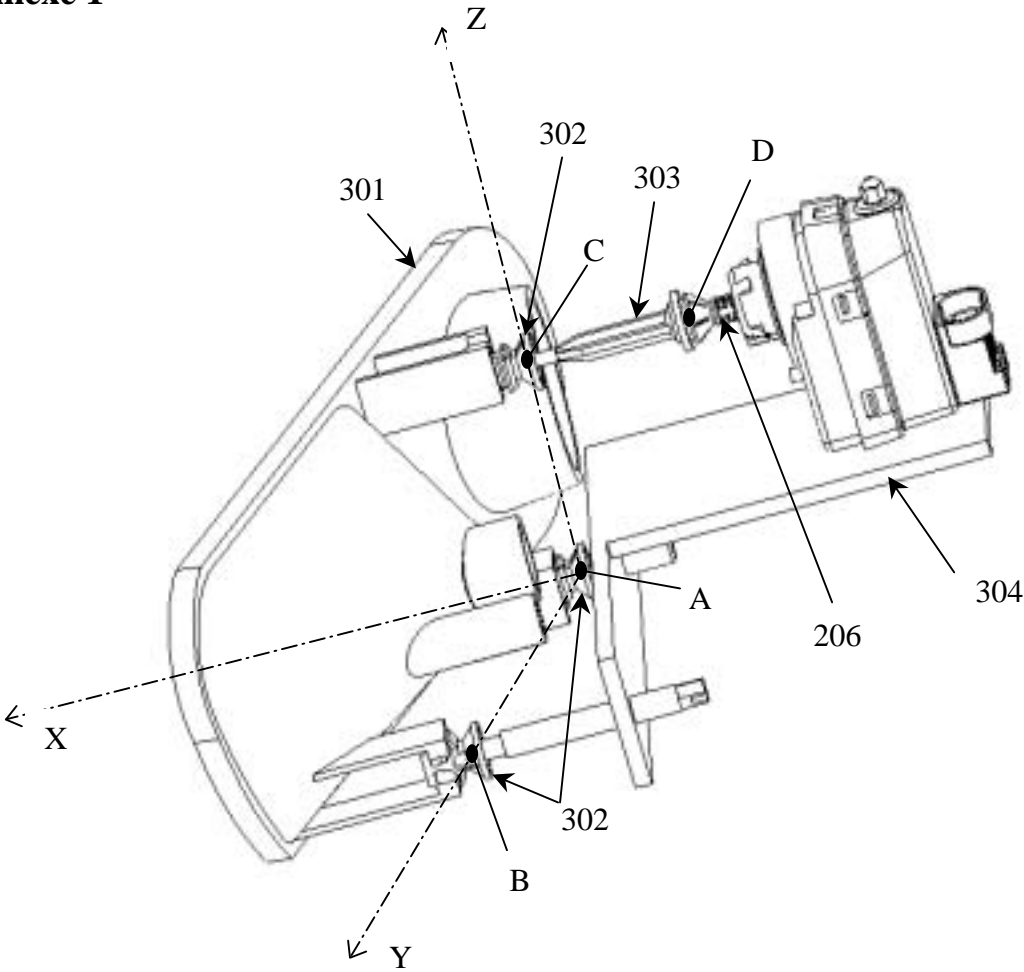
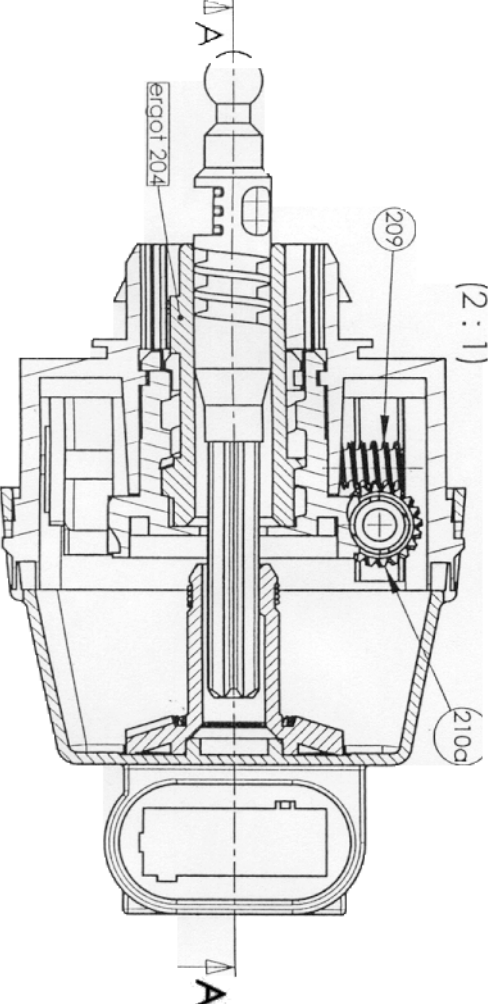
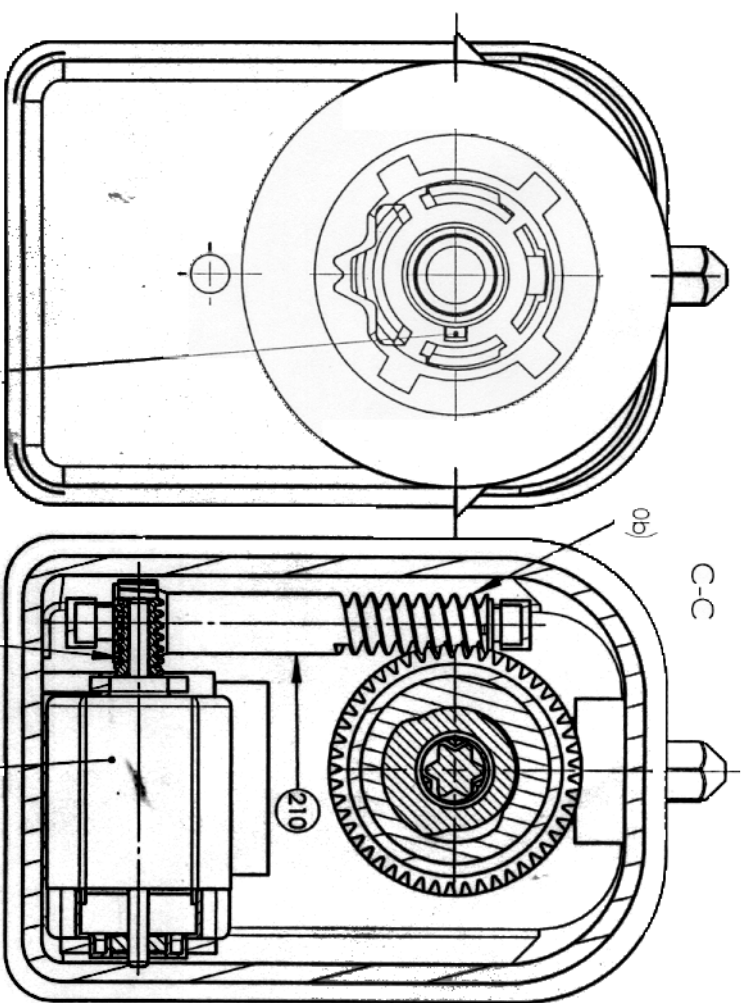
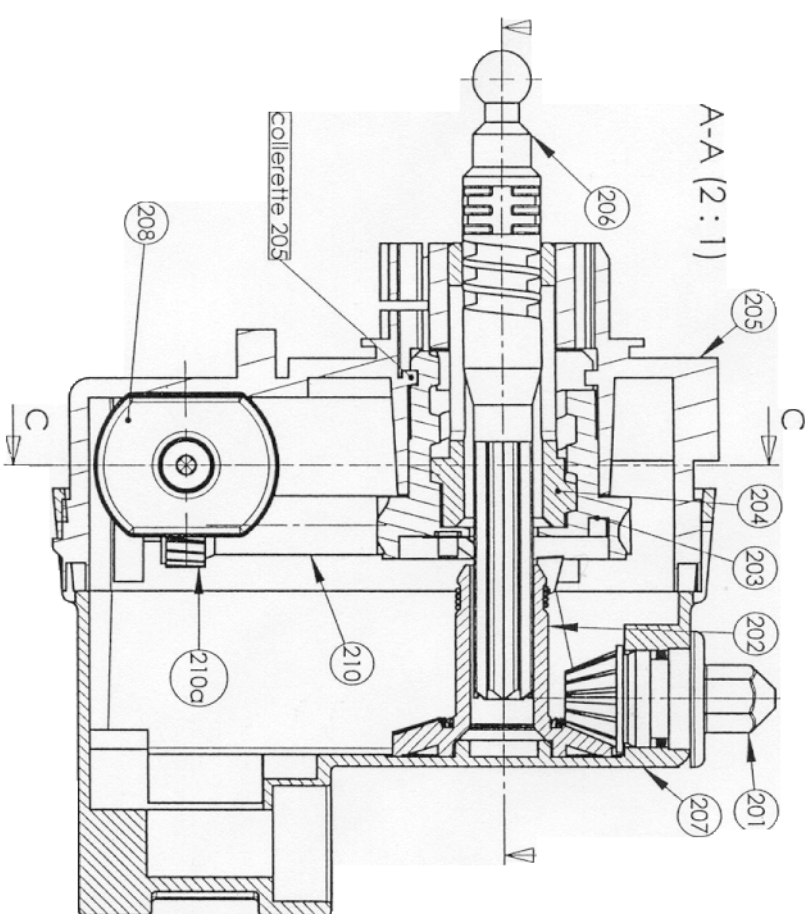


Annexe 1



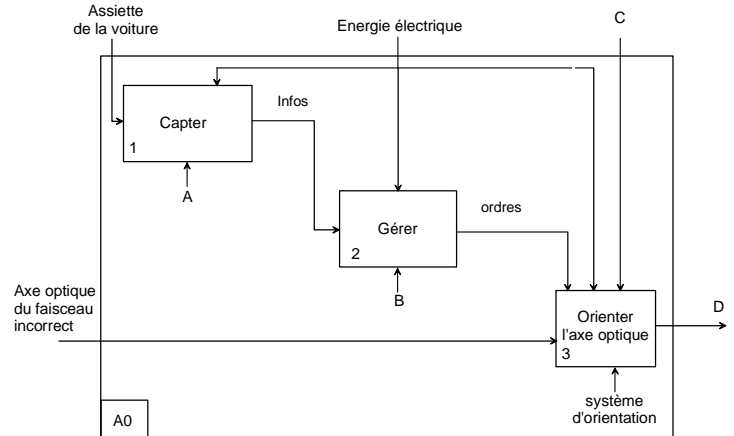
Rep.	Nbr.	Désignation	Observations
304	1	Bâti fixe	
303	1	Biellette de poussée	
302	3	Rotule femelle	
301	1	Bloc d'orientation	
206	1	Axe de sortie	
Système d'orientation			



Rep.	Nbr.	Désignation	Observations
209	1	Vis sans fin	Z <sub>209</sub> = 2 filets Z <sub>209</sub> = 20 dents
208	1	Moteur 12 Vcc	Z <sub>208</sub> = 1 filet
207	1	Boîtier droit	
206	1	Axe de sortie	Usure 20/20 pas P <sub>2</sub> = 2.5mm, 1 filet
205	1	Boîtier gauche	
204	1	Marchon fileté	Usure 20/20 pas P <sub>2</sub> = 2.5mm, 1 filet
203	1	Roue dentée	Z <sub>203</sub> = 49 dents Usure 20/20 pas P <sub>1</sub> = 6mm, 1 filet
202	1	Roue de renvoi	Z <sub>202</sub> = 32 dents
201	1	Bouton de réglage manuel	Z <sub>201</sub> = 12 dents

## Annexe 3

SADT niveau A0



SADT niveau A3

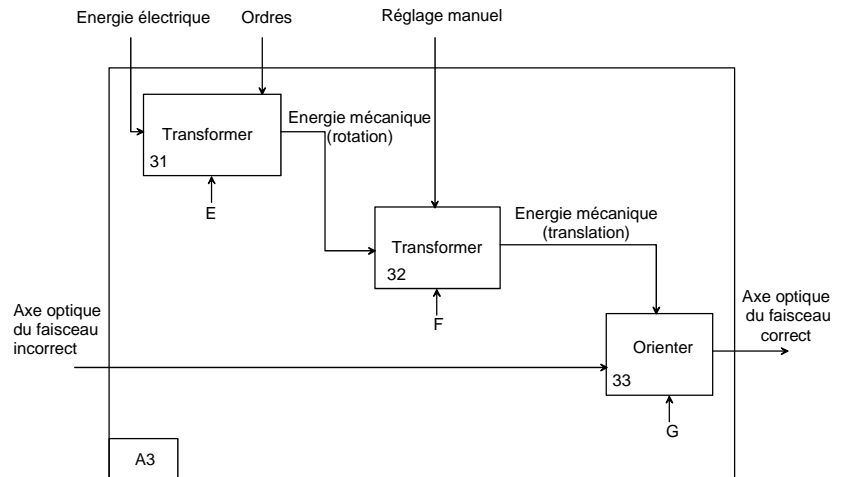
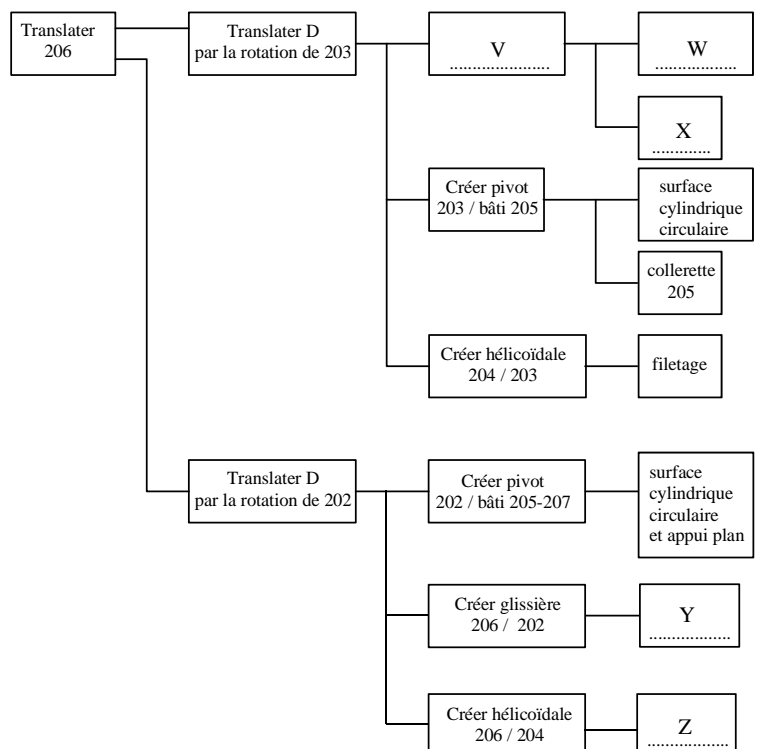


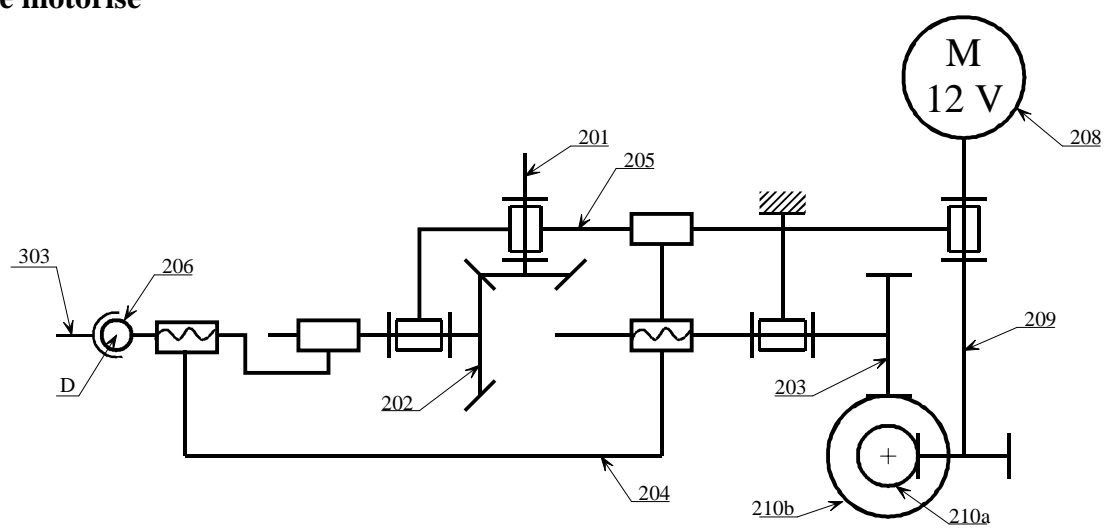
diagramme FAST



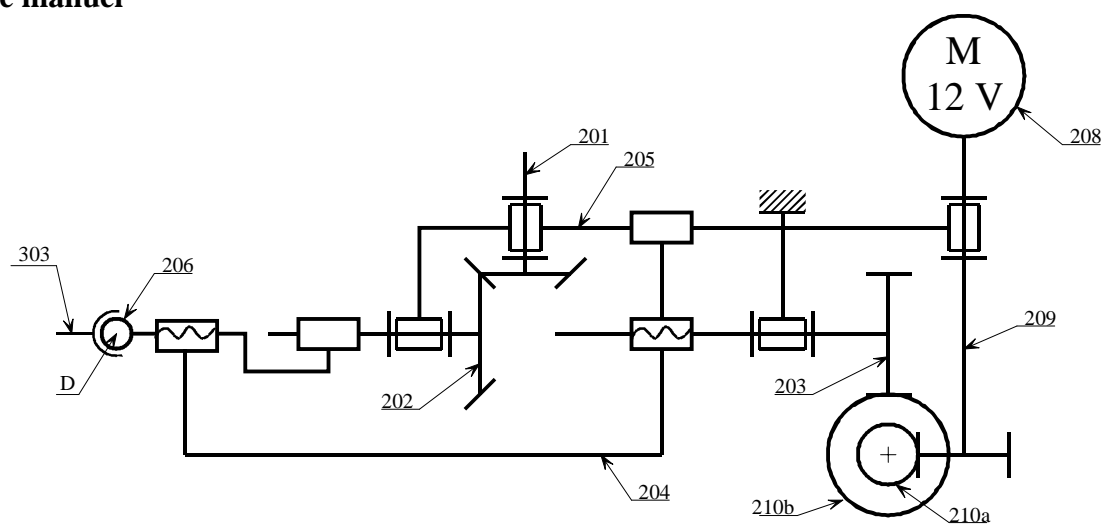
**Fin de l'annexe.**

**Document réponse 1**

**réglage motorisé**

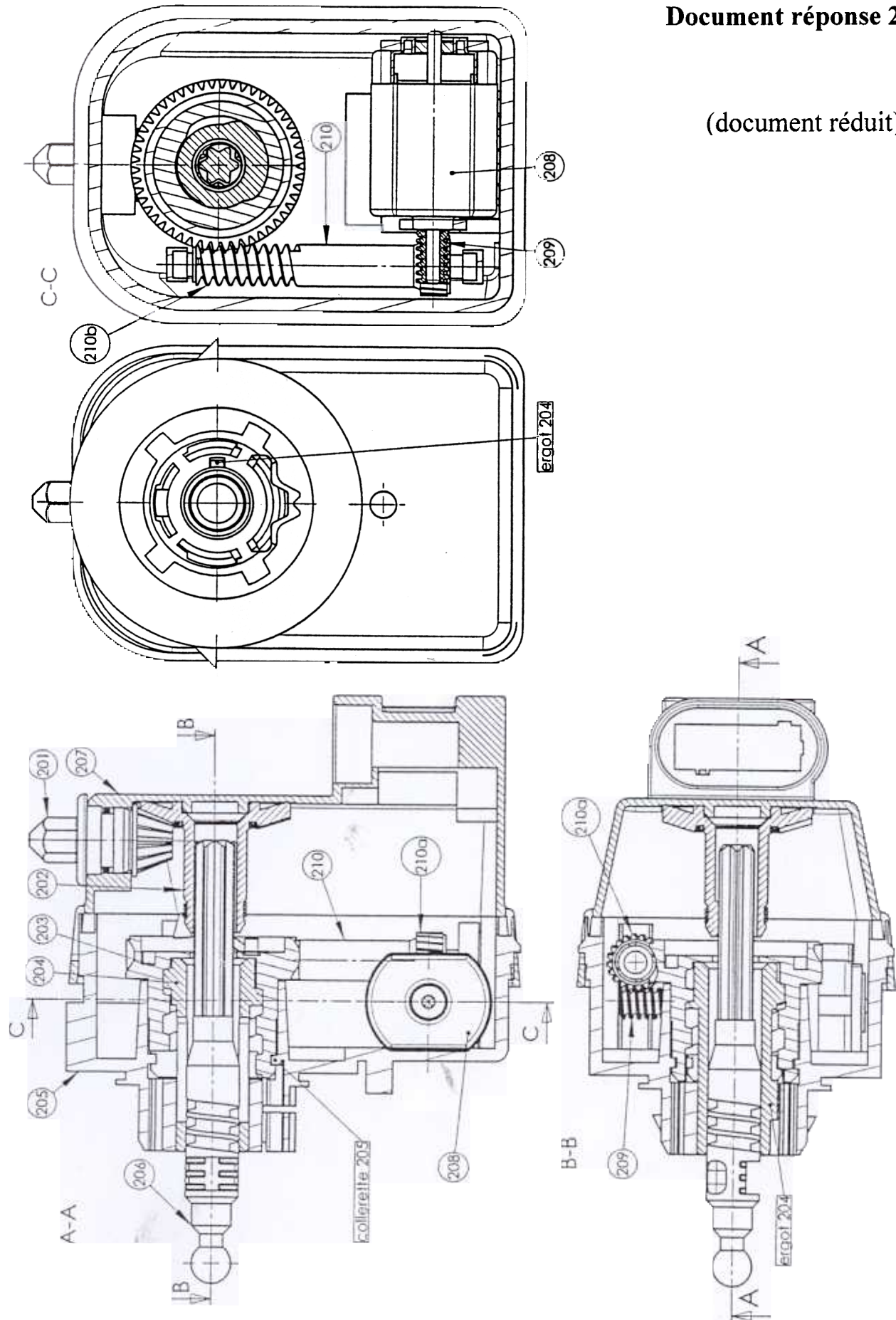


**réglage manuel**

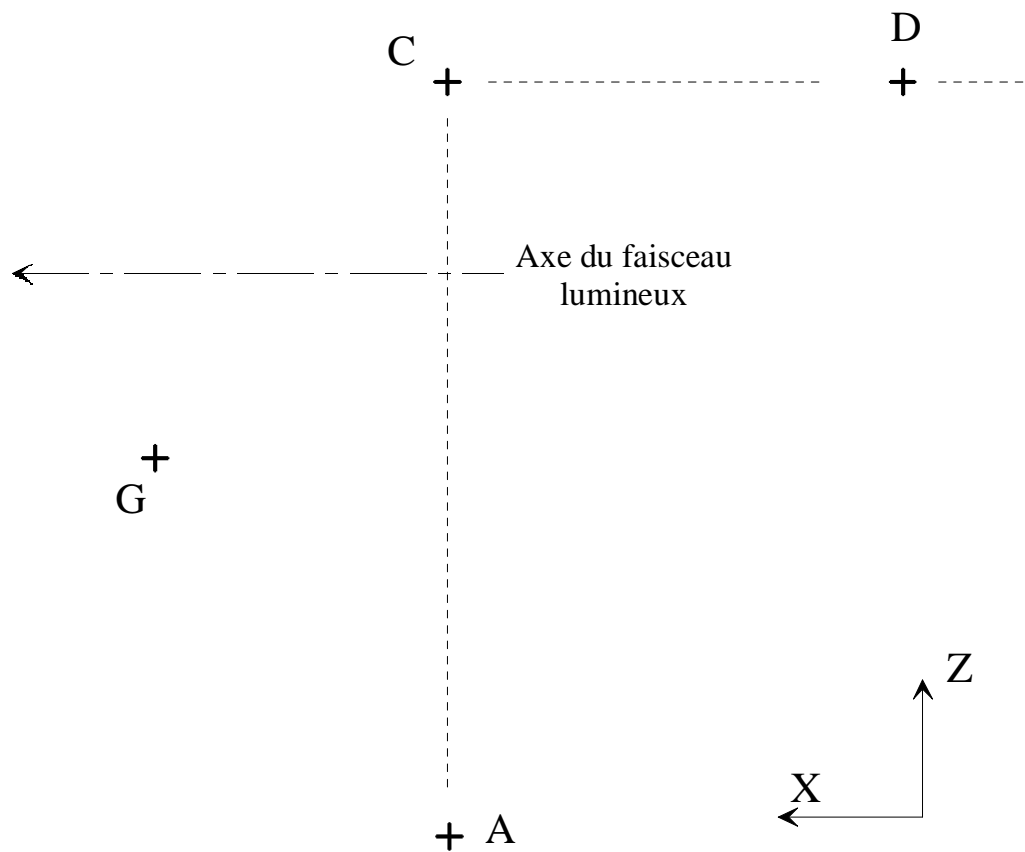


## Document réponse 2

(document réduit)



### Document réponse 3



N.B. : le point G est ramené dans le plan  $(A, \vec{x}, \vec{z})$ .

Echelle impérative : 10 mm pour 1  $mm/s$ .