Machine Learning Formulae

Notations

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m = Number of training examples.
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n = Number of features.

 $x^{(i)}$ = The features of the i_{th} training example, which is an n+1 vector.

 $y^{(i)}$ = The Target value of the i_{th} training example, which is a number.

 $(x^{(i)}, y^{(i)})$ = The i_{th} training example.

 $\boldsymbol{x}_{j}^{(i)}$ = The j_{th} feature of the i_{th} training example, which is a number.

 α = Learning rate

Multivariate Linear Regression

Hypothesis

 $h_x(\theta) = \sum_{i=0}^n \theta_i x_i \; x_0$ is always equal to 1.

Cost Function

$$J(heta) = rac{1}{2m} \sum_{i=1}^{m} (h_{ heta}(x^{(i)}) - y^{(i)})^2)$$

Gradient Desecnt

Repeat{

$$\theta_j := \theta_j - \alpha \frac{\partial}{\partial \theta_i} J(\theta)$$

 $(j = 0, 1, 2, \dots, n)$, α stands for learning rate.

}

Calculate the $\frac{\partial}{\partial \theta_i} J(\theta)$, which means the partial derivative respect to θ_j :

Repeat{

$$heta_j := heta_j - lpha rac{1}{m} \sum_{i=1}^m (h_ heta(x^{(i)}) - y^{(i)}) x_j^{(i)}$$

Feature Scaling

Replace every x with:

$$\frac{x-\mu}{\epsilon}$$

 μ stands for the average of x's, and s stands for the standard deviation of x's.

Normal Equation

Define the feature vector of the \boldsymbol{i}_{th} training example:

$$x^{(i)} = egin{bmatrix} x_0^{(i)} \ x_1^{(i)} \ & \ddots \ x_n^{(i)} \end{bmatrix} x^{(i)} ext{ is an } n+1 ext{ vector.}$$

Define **design matrix** X:

$$X = egin{bmatrix} (x^{(1)})^T \ (x^{(2)})^T \ & \dots \ (x^{(m)})^T \end{bmatrix} X$$
 is an $m imes (n+1)$ matrix.

Define the target value vector:

$$y=egin{bmatrix} y^{(1)} \ y^{(2)} \ \dots \ y^{(m)} \end{bmatrix}$$
 y is an $m imes(n+1)$ vector.

Then, we can calculate θ :

$$heta = (X^TX)^{-1}X^Ty\, heta$$
 Is an $n+1$ vector.

Logistic Regression

Hypothesis

Define:

$$heta = \left[egin{array}{c} heta_0 \ heta_1 \ heta_1 \ heta_n \end{array}
ight] x = \left[egin{array}{c} x_0 \ x_1 \ heta_1 \ heta_n \end{array}
ight]$$

Hypothesis:

$$h_{ heta}(x) = g(heta^T x)$$

$$g(z) = \frac{1}{1 + e^{-z}}$$
 (sigmoid/logistic function)

which means:

$$h_{ heta}(x) = rac{1}{1+e^{- heta^Tx}} \in (0,1)$$

Cost Function

$$J(\theta) = \frac{1}{m} \sum_{i=1}^{m} Cost(h_{\theta}(x^{(i)}), y^{(i)})$$

$$Cost(h_{\theta}(x^{(i)}), y^{(i)}) = \begin{cases} -log(1 - h_{\theta}(x)), & y = 0 \\ -log(h_{\theta}(x)), & y = 1 \end{cases} \iff Cost(h_{\theta}(x^{(i)}), y^{(i)}) = -ylog(h_{\theta}(x)) - (1 - y)log(1 - h_{\theta}(x))$$

Gradient Descent

Repeat {
$$heta_j:= heta_j-lpharac{1}{m}\sum_{i=1}^m(h_ heta(x^{(i)})-y^{(i)})x_j^{(i)}$$
 }

Multiclass Classification

Train a logistic regression classifier $h_{\theta}^{(i)}(x)$ for each class i to predict the probability that y=i. On a new input x, to make a prediction, pick the class i that maximizes $h_{\theta}^{(i)}(x)$.

Regularized Linear Regression

Cost Function

$$J(heta) = rac{1}{2m} [\, \sum_{i=1}^m (h_ heta(x^{(i)}) - y^{(i)})^2 + \lambda \sum_{i=1}^n heta_j^2 \,]$$

Gradient Descent

Repeat {
$$heta_0 := heta_0 - lpha rac{1}{m} \sum_{i=1}^m (h_{ heta}(x^{(i)}) - y^{(i)}) x_0^{(i)}$$
 $heta_j := heta_j - lpha [rac{1}{m} \sum_{i=1}^m (h_{ heta}(x^{(i)}) - y^{(i)}) x^{(j)} + rac{\lambda}{m} heta_j]$ $(j=1,2,3,\ldots,n)$ }

Normal Equation

$$heta = (X^TX + \lambda egin{bmatrix} 0 & 0 & 0 & 0 & \dots & 0 \ 0 & 1 & 0 & 0 & \dots & 0 \ 0 & 0 & 1 & 0 & \dots & 0 \ 0 & 0 & 0 & 1 & \dots & 0 \ & & & & & & \ 0 & 0 & 0 & 0 & \dots & 1 \end{bmatrix})^{-1}X^Ty$$

Regularized Logistic Regression

Cost Function

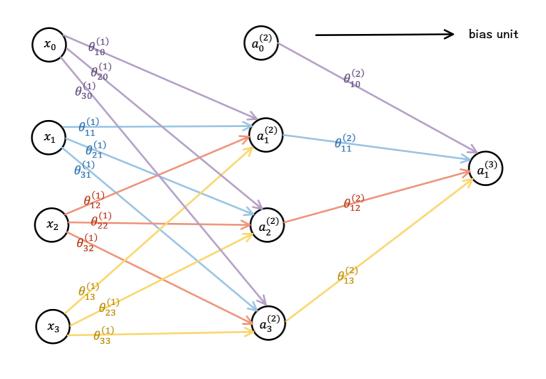
$$J(heta) = -[\,rac{1}{m}\sum_{i=1}^m y^{(i)}logh_ heta(x^{(i)}) + (1-y^{(i)})log(1-h_ heta(x^{(i)}))\,] + rac{\lambda}{2m}\sum_{j=1}^n heta_j^2$$

Gradient Desecnt

Repeat { $heta_0 := lpha rac{1}{m} \sum_{i=1}^m (h_{ heta}(x^{(i)}) - y^{(i)}) x_0^{(i)}$ $heta_j := heta_j - lpha [rac{1}{m} \sum_{i=1}^m (h_{ heta}(x^{(i)}) - y^{(i)}) x_j^{(i)} + rac{\lambda}{m} heta_j]$ $(j=1,2,3,\ldots,n)$ }

Neural Network

Architecture



Layer1 Layer2 Layer3
(input layer) (hidden layer) (output layer)

 $a_i^{(j)}$ = activation of unit i in layer j

 $\theta^{(j)}$ = matrix of weights controlling function mapping from layer j to layer j+1

E.g.

$$\mathbf{X} = \begin{bmatrix} x_0 \\ x_1 \\ x_2 \\ x_3 \end{bmatrix} \boldsymbol{\theta}^{(1)} = \begin{bmatrix} \theta_{10}^{(1)} & \theta_{11}^{(1)} & \theta_{12}^{(1)} & \theta_{13}^{(1)} \\ \theta_{20}^{(1)} & \theta_{21}^{(1)} & \theta_{22}^{(1)} & \theta_{23}^{(1)} \\ \theta_{30}^{(1)} & \theta_{31}^{(1)} & \theta_{32}^{(1)} & \theta_{33}^{(1)} \end{bmatrix} \in R^{3 \times 4}$$

$$\begin{split} a_1^{(2)} &= g(\theta_{10}^{(1)}x_0 + \theta_{11}^{(1)}x_1 + \theta_{12}^{(1)}x_2 + \theta_{13}^{(1)}x_3) \text{ Define: } z_1^{(2)} = \theta_{10}^{(1)}x_0 + \theta_{11}^{(1)}x_1 + \theta_{12}^{(1)}x_2 + \theta_{13}^{(1)}x_3 \\ a_2^{(2)} &= g(\theta_{20}^{(1)}x_0 + \theta_{21}^{(1)}x_1 + \theta_{22}^{(1)}x_2 + \theta_{23}^{(1)}x_3) \text{ Define: } z_2^{(2)} = \theta_{20}^{(1)}x_0 + \theta_{21}^{(1)}x_1 + \theta_{22}^{(1)}x_2 + \theta_{23}^{(1)}x_3 \\ a_3^{(2)} &= g(\theta_{30}^{(1)}x_0 + \theta_{31}^{(1)}x_1 + \theta_{32}^{(1)}x_2 + \theta_{33}^{(1)}x_3) \text{ Define: } z_3^{(2)} = \theta_{30}^{(1)}x_0 + \theta_{31}^{(1)}x_1 + \theta_{32}^{(1)}x_2 + \theta_{33}^{(1)}x_3 \\ &\iff a^{(2)} = g(\theta^{(1)}X) \iff a^{(2)} = g(z^{(2)}) \end{split}$$

Cost Function

L = total number of layers in network

 S_l = number of units(not counting bias unit) in lay l.

 $h_{ heta}(x) \in R^K$ (which means there are K units in the output layer)

$$(h_{\theta}(x))_i = i^{th}$$
 output

$$J(heta) = -rac{1}{m}[\sum_{i=1}^{m}\sum_{k=1}^{K}y_{k}^{(i)}log(h_{ heta}(x^{(i)}))_{k} + (1-y_{k}^{(i)})log(1-(h_{ heta}(x^{(i)}))_{k})] + rac{\lambda}{2m}\sum_{l=1}^{L-1}\sum_{i=1}^{S_{l}}\sum_{j=1}^{S_{l+1}}(heta_{ji}^{(l)})^{2}$$

Back Propagation

Intuition: $\delta_j^{(l)}$ = error of node j in layer l

Suppose L=4, that is, there are 4 layers in the network in total:

For each output unit(l = 4):

$$\delta_{j}^{(4)} = a_{j}^{(4)} - y_{j}$$

Vectorization: $\delta^{(4)} = a^{(4)} - y$

For other layers:

$$\delta^{(3)} = (\theta^{(3)})^T \delta^{(4)} \cdot *g^{'}(z^{(3)}) = a^{(3)} \cdot *(1 - a^{(3)})$$

$$\delta^{(2)} = (heta^{(2)})^T \delta^{(3)} . * g^{'}(z^{(2)}) = a^{(2)} . * (1 - a^{(2)})$$

•••

Algorithm:

Training set
$$\{(x^{(1)}, y^{(1)}), (x^{(2)}, y^{(2)}), \dots, (x^{(m)}, y^{(m)})\}$$

Set
$$\Delta_{ij}^{(l)} = 0$$
 (for all l, i, j)

For i = 1 to m

Set
$$a^{(1)} = x^{(i)}$$

Perform forwar propagation to compute $a^{(l)}$ for l = 1, 2, 3..., L

Using
$$y^{(i)}$$
 , compute $\delta^{(L)} = a^{(L)} - y^{(i)}$

Compute
$$\delta^{(L-1)}, \delta^{(L-2)}, \dots, \delta^{(2)}$$

$$\begin{split} &\Delta_{ij}^{(l)} := \Delta_{ij}^{(l)} + a_j^{(l)} \delta_i^{(l+1)} \\ &\text{Define } D_{ij}^{(l)} = \frac{\partial}{\partial \theta_{ij}^{(l)}} J(\theta) \Longleftrightarrow D_{ij}^{(l)} = \begin{pmatrix} \frac{1}{m} \Delta_{ij}^{(l)} + \lambda \theta_{ij}^{(l)} & \text{if } j \neq 0 \\ \frac{1}{m} \Delta_{ij}^{(l)} & \text{if } j = 0 \end{pmatrix} \\ &\theta_{ij}^{(l)} := \theta_{ij}^{(l)} - \alpha D_{ij}^{(l)} \end{split}$$