

$$\frac{d^2x}{dt^2} + 2\zeta\omega_n \frac{dx}{dt} + \omega_n^2 x = 2\zeta\omega_n \frac{dy}{dt} + \omega_n^2 y$$

$$\frac{d^2x}{d\tau^2} + 2\zeta \frac{dx}{d\tau} + x = 2\zeta \frac{dy}{d\tau} + y \tag{5.76}$$

$$y(\tau) = y_o \sin(\Omega \tau) \tag{5.77}$$

$$\frac{d^2x}{d\tau^2} + 2\zeta \frac{dx}{d\tau} + x = 2\zeta y_o \Omega \cos(\Omega \tau) + y_o \sin(\Omega \tau)$$
 (5.78)

$$x(\tau) = y_o H(\Omega) \sqrt{1 + (2\zeta\Omega)^2} \sin(\Omega\tau - \theta(\Omega) + \varphi)$$
 (5.79)

$$\varphi = \tan^{-1} 2\zeta \Omega$$

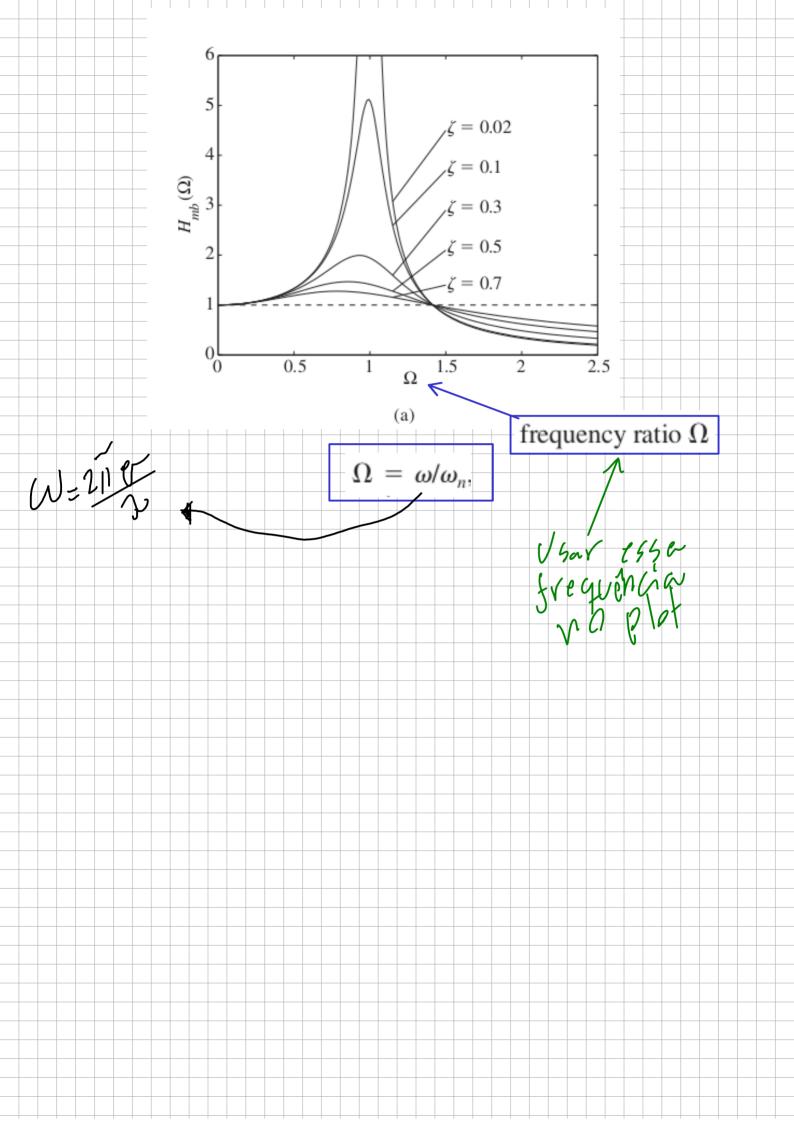
$$x(\tau) = \underbrace{y_o H_{mb}(\Omega)}_{\text{Phase}} \sin(\Omega \tau - \underbrace{\psi(\Omega)}_{\text{Phase}})$$

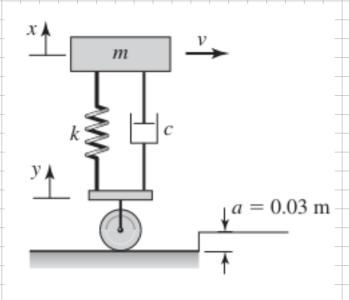
$$H_{mb}(\Omega) = \frac{\sqrt{1 + (2\zeta\Omega)^2}}{\sqrt{(1 - \Omega^2)^2 + (2\zeta\Omega)^2}}$$

$$\psi(\Omega) = \tan^{-1} \frac{2\zeta \Omega^3}{1 + \Omega^2 (4\zeta^2 - 1)}$$

$$v(\tau) = y_o \omega_n \Omega H_{mb}(\Omega) \cos(\Omega \tau - \psi(\Omega))$$

$$a(\tau) = -\Omega^2 \omega_n^2 x(\tau)$$
(5.83)





## FIGURE 6.13

Car suspension encountering a step change in road conditions.

$$\frac{d^2x}{dt^2} + 2\zeta\omega_n \frac{dx}{dt} + \omega_n^2 x = 2\zeta\omega_n \frac{dy}{dt} + \omega_n^2 y$$

$$y(t) = au(t - t_o) (b)$$

(a)

$$\frac{d^2x}{dt^2} + 2\zeta\omega_n \frac{dx}{dt} + \omega_n^2 x = 2\zeta\omega_n a\delta(t - t_o) + a\omega_n^2 u(t - t_o)$$
 (c)

$$dt^2$$
  $dt$   $dt$   $dt$   $dt$ 

$$\frac{du(t-t_o)}{dt} = \delta(t-t_o)$$

$$x(t) = \frac{2\zeta a}{\sqrt{1-\zeta^2}} e^{-\zeta \omega_n(t-t_o)} \sin(\omega_d(t-t_o)) u(t-t_o)$$

$$+a\left[1-\frac{e^{-\zeta\omega(t-t_o)}}{\sqrt{1-\zeta^2}}\sin(\omega_d(t-t_o)+\varphi)\right]u(t-t_o)$$

$$\omega_{n} = \sqrt{\frac{4 \times 10^{5} \text{ N/m}}{1100 \text{ kg}}} = 19.07 \text{ rad/s}$$

$$\omega_{d} = 19.07 \sqrt{1 - 0.358^{2}} = 17.81 \text{ rad/s}$$

$$\varphi = \tan^{-1} \frac{\sqrt{1 - 0.358^{2}}}{0.358} = 1.21 \text{ rad}$$

$$\zeta = \frac{15 \times 10^{3}}{2 \times \sqrt{400 \times 10^{3} \times 1100}} = 0.358$$

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