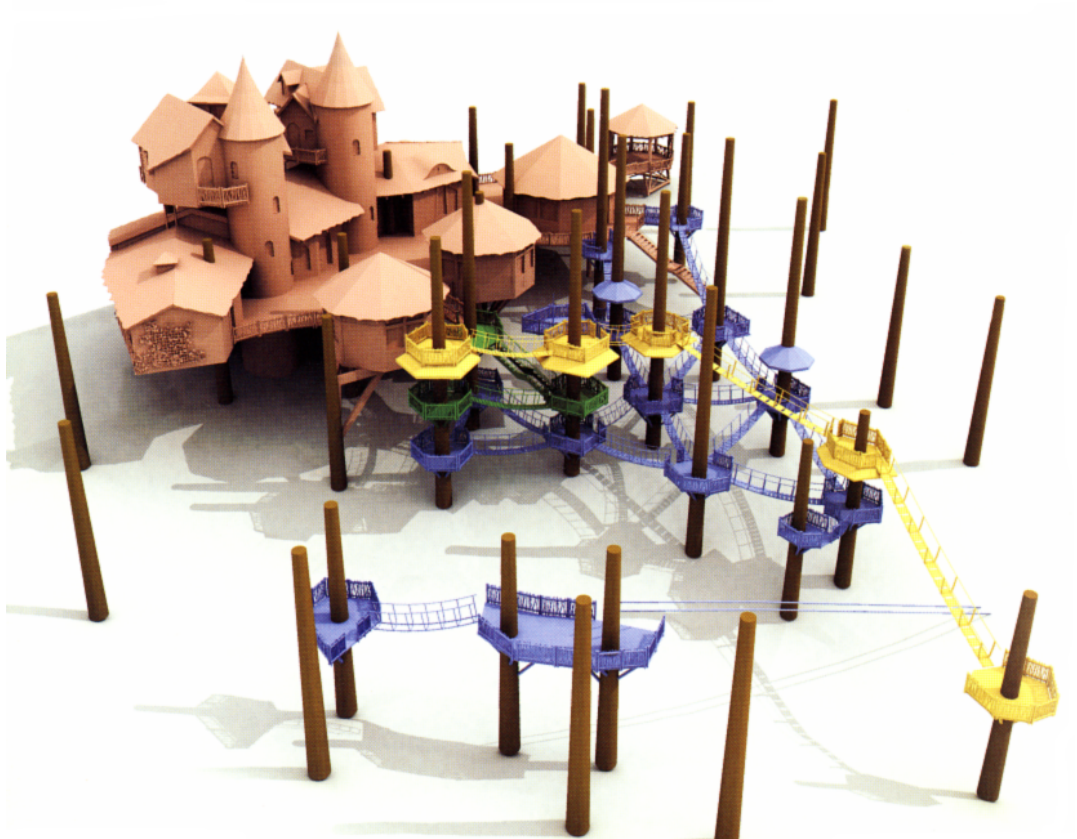


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Planning Procedural Architecture in Tree-like Geometry

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Abstract

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Chapter 1

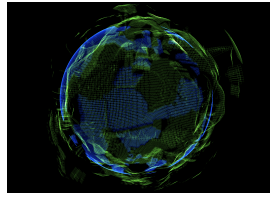
Introduction

Procedural modeling is an exciting research area with tremendous potential for virtual worlds. Virtual worlds range from games, to simulations and virtual communities. These worlds are often very large and with advances in technology and user demand they rapidly grow larger for each new application. The problem is that space in these vast virtual worlds needs to be filled with interesting content. Creating such high amounts of content by hand does provide nice job opportunities, but if we could generate the same content with a set of parameters and the push of a button the choice is rather obvious. However, time and money efficiency are not the only arguments for the development of procedural methods. By studying real world objects or sets of real world objects in order to dynamically synthesise them in virtual worlds we gain a deeper knowledge of the characteristics of these objects and relationships between different objects.

A couple of successful existing procedural modeling implementations are interesting to discuss. In games, procedural methods have been employed for the generation of worlds with restricted sets of environmental elements, such as dungeons and mazes. A good example is the game *Diablo 2*: The game *Spore* was one of the first games that heavily utilized procedural modeling techniques for a considerable part of the content in the game. A very interesting project that is in development at the time of writing, is the game *Love* by Eskil. Procedural generation is used extensively for every part of the game. The following quote and pictures (figure 1) from Eskil's website make *Love* all the more impressive.

Love is being developed by Eskil alone, without funding or support. He is responsible for all code, design, networking, engine, art, pipeline and tools. More than just being an experiment in game design, Love is also an experiment in how games can be developed drastically more efficient using technologies like Verse, procedural generation, new tools and a host of other clever solutions.

This thesis addresses the problem of creating procedural architecture in the special case of restrictions and possibilities enforced by geometric properties of tree-like support-structures. A side goal for this research was to develop methods for intuitive interactive control for this specific procedural modeling method.



(a) World



(b) Ingame Environment

Figure 1.1: Screenshots of the game Love

Visual modeling of plant development is a field which started in 1962, when Ulam applied cellular automata to simulate the development of branching patterns [6]. A formalism for modeling plants was proposed by Lindenmayer in 1968, this formalism was called L-systems since. The following definition of an L-system is given by Przemyslaw [6]:

An L-system is a parallel rewriting system operating on branching structures represented as bracketed strings of symbols with associated parameters, called modules. Matching pairs of square brackets enclose branches. Simulation begins with an initial string called the axiom, and proceeds in a sequence of discrete derivation steps. In each step, rewriting rules or productions replace all modules on the predecessor string by successor modules.

Przemyslaw [6] has employed and extended the l-system formalism for realistic visualisation of entire plant ecosystems. Within a ecosystem organisms interact with each other and this interaction determines many properties for individual organisms; such as growth rate. Since the original L-system formalism does not account for communication between two processes, Przemyslaw proposed *open l-systems* which incorporates *communication modules*.

Since 2001 L-systems also proved to be useful in the field of urban procedural generation [9]. It was then that Muller proposed the use of L-systems for the generation of road networks and building generation.

Techniques for tree generation in this thesis are based on L-systems, however these techniques are simplified to a certain degree since the modeling of plants is not the maintopic of this thesis. We have used the l-system formalism to generate simple branching tree structures. We did not strive to generate visually realistic models of trees since this has already been achieved by many people before me with impressive results. Instead our simplified method generates the main structure of a tree which is then used as input in our method to

It is the case that traditional general purpose modeling software is very time consuming for the creation of complex scenes as a result of the lowlevel tools

they feature. Special purpose modeling tools such as cityEngine [5] (in the case of urban modeling) and speedTree (in the case of modeling plants and trees) provide procedural methods to generate objects within a certain class with very high time efficiency. However the human touch still remains a very important part of the modeling procedure. Eastatics are very hard to turn into a set of formal rules on which an algorithm can operate.

The special purpose modeling tool for the generation of organic geometry and treehouse architecture that was developed for this thesis provides the user with intuitive interaction tools to allow easy manipulation.

1.1 Overview

This thesis is structured as follows. In the next section I will discuss related work. In the related work section I will bring my thesis into context with regard to procedural modeling of trees and architecture. A precise statement of the problem and why it's an interesting problem to solve will follow in section 3.

In section 4 I will present the conceptual system model. The method for the generation of the forest layout and the generation of the tree geometry is presented in section 5.

With the forest geometry in place we are ready to review the planning method which is responsible for the construction of a connected graph representing a tree community. I will conclude the method description with a look at the final stage of the pipeline, translating the symbols from the nodes and edges of the graph to the geometrical architectural elements. Section 7 discusses user interactivity and usability of the proposed system. The last two sections present results and conclusions respectively.

Chapter 2

State of the Art in Procedural Modeling

2.1 Plants and Trees

Algorithmic Beauty of Plants by Lindenmayer and Przemyslaw [7] is the first complete work discussing the generation of plant geometry using procedural methods such as L-systems and fractals. To model and visualise realistic ecosystems, Przemyslaw extended the l-systems concept to a system which allowed communication between systems (open l-systems [6] [3]). Visual editing of procedural plants models is discussed in (author?) [1].

2.2 Road Networks

The foundation for procedural city and building modeling was provided by Parish and Muller (author?) [10] in their paper "*Procedural Modeling of Cities*". The main contribution of this paper is the use of extended L-systems for the generation of city roadmaps. They also propose a method for the texturing of facades. An intuitive editing approach for road networks with the use of tensor fields and bush techniques is presented by Chen et al. (author?) [2].

2.3 Architecture

An attempt was made to use L-systems for the creation of buildings (author?) [10], however this did not prove to be effective. L-systems are designed to handle growth-like processes, it has been acknowledged that the construction process of a building is not a growth like process. Instead, building construction is better expressed by series of partitioning steps. These partitioning steps can be described by another kind of rewriting grammar called *set grammar*. In (author?) [9] Wonka presents a method for the automatic creation of building

using such grammar systems. In this work Wonka introduces the idea of a specialized type of set grammar called *split grammar* which operates on shapes. In (author?) [5] the split rules from the split grammar concept are defined in a grammar system called *CGA Shape*, which was the first procedural system for the creation of detailed buildings with consistent mass models. The process of creating a ruleset in CGA shape for a specific type of building is not straightforward and requires a trained expert. Lipp et al. (author?) [4] introduce a visual method for the editing of the CGA Shape grammar for procedural architecture to simplify the rule building process.

Chapter 3

Problem Statement

The purpose of this thesis is to tackle a specific instance of the problem of planning connected architectural geometric elements into an environment with existing geometry which is to be used as the supporting structure for the architectural elements. We handle the specific case in which the pre-existing geometry is a virtual forest, using the trunks and branches of the trees as supporting structures for architectural elements such as platforms, bridges, stairs and buildings. We propose several heuristics for the generation of a connected 'tree house community' and using these heuristics we propose a planning algorithm. The architectural elements need a large degree of adjustability to be able to incorporate them into the irregular environment, therefore we present procedural methods for the generation of these elements.

Chapter 4

Concept

This section discusses the concept for the proposed procedural modeling method with main focus to the planning algorithm for architectural objects.

Chapter 5

Procedural Forest Generation

5.1 Scattering Techniques for Tree Positions

(author?) [6]

]

(author?) [8]

5.2 Ecosystem Modeling

5.3 Simple Tree Structures

Procedurally generating trees by means of l-systems has had a great amount of succes since the original proposal by Lindenmayer. The L-system formalism is widely applied in academic work and is also succesfully used within commercial applications. This thesis does not focus on the l-system formalism in particular, since it is already a well established theory (author?) [7]. However, the following section will describe the basics of l-systems to establish some basic understanding wich will be needed in following sections.

I am interested in the structure of trees and the possibilities and restrictions it poses for placement of architectural shapes. For the purpose of this thesis the generated trees do not have to be visually convincing, however the basic shape should still be identified as a tree. The geometric properties of a tree model that are to interest of us are those that have effect on the possibilities with respect to the incorporation of architectural man-made structures. The tree geometry functions as the support structure for the building blocks I define in detail in section 6.

In this section we will identify geometric configurations within tree geometry that allow for the construction of the proposed set of architectural elements.

Chapter 6

Architecture

6.1 Background

6.2 Elements for Tree-Based Architecture

In this section we present the set of elements we use for the construction of our treebased architecture. We will first introduce the elements in a broad sense, followed by detailed descriptions of methods to construct each of the elements procedurally.

6.2.1 The Element Vocabulary

We established a set of architectural elements we believe are vital for the generation of tree-based architectural structures. The elements are the following:

1. platform
2. housing
3. bridge
4. stairs

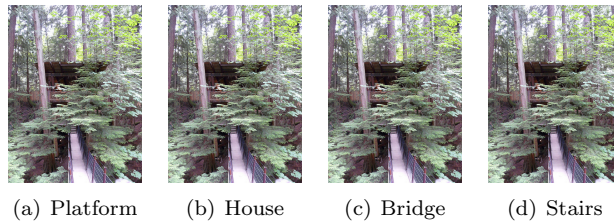


Figure 6.1: Caption of subfigures (a), (b) and (d)

6.2.2 Combining Elements

We construct an architectural structure by combining the elements we have in our element vocabulary. In order to construct logical combinations we need to define for each elements how it can be joined with other elements in our vocabulary.

6.2.3 Platforms

6.2.4 Housing

6.2.5 Bridges

6.2.6 Stairs

I want to implement this as a graph traversing algorithm (using the Boost graph library)

6.3 Scenarios

Here we define one or more scenarios for meaningful architectural planning with a forest scene. The scenarios that are proposed here will be transformed to rules, heuristics and parameters in the next section

6.3.1 Single Family Retreat

6.3.2 Tree Village

6.3.3 Fantasy Tree City

6.4 Formalizing the Scenarios

From the scenarios I discussed in the previous section we can extract a set of parameters and goals for our algorithm.

6.5 Structure Planning

Using the scenarios and architectural elements we have defined in the previous section we will formulate our planning algorithm now. I will first introduce the planning algorithm informally followed by a more formal approach.

6.5.1 Alternative approaches

Chapter 7

User Interaction Tools

7.1 Growing Surfaces

7.2 Vector and tensor fields

Chapter 8

Results

Chapter 9

Conclusion

Appendix A: Implementation

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