

Lecture 13 Vector Geometry of Linear Models

Objectives

- Simple Linear regression in terms of **Linear vector geometry**
- **Linear model** and **Fitted Linear** model visualization
- Variables in **Mean deviation form**

Simple Linear Regression can be represented as a vector by the following equation:

$$y = \alpha 1_n + \beta x + \varepsilon \dots\dots\dots 1$$

$$\text{Where } y = [Y_1, Y_2, \dots, Y_n]' \quad x = [x_1, x_2, x_3, \dots, x_n]' \quad \varepsilon = [\varepsilon_1, \varepsilon_2, \dots, \varepsilon_n]', \quad 1_n = [1, 1, \dots, 1]'$$

The aforementioned is the equation for the population with the same assumptions as:

$$\varepsilon \sim N_n(0, \sigma_\varepsilon^2 I_n) \dots\dots\dots 2$$

The **Fitted Model** can be represented as follows:

$$y = A 1_n + Bx + e \dots\dots\dots 3$$

Where

$$e = [E_1, E_2, \dots, E_n] \quad A \text{ and } B \text{ are least square regression coefficient.}$$

$$E(y) = A 1_n + Bx \dots\dots\dots 4$$

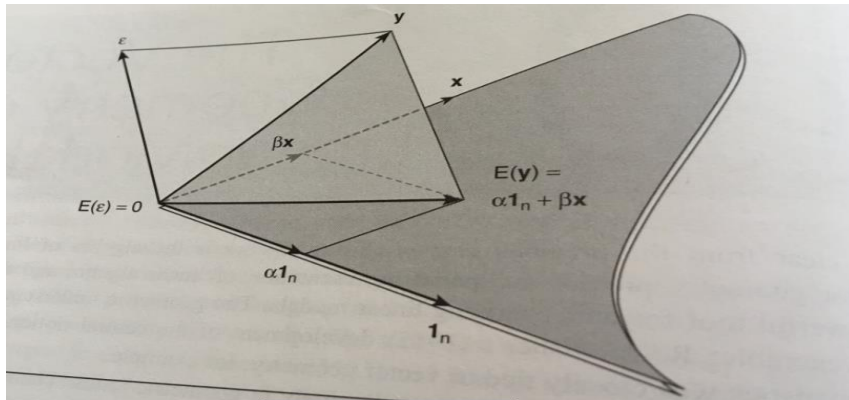
and

$$\hat{y} = A 1_n + Bx \dots\dots\dots 5$$

For representing this we require an **n dimension space**. The visualization of **n dimensional space** cannot be depicted therefore a sub space composed of three dimensional space is used to showcase /conceptualize the **geometric properties** of of the **simple regression model**.

The subspace is spanned by **x, y, 1_n**. **y is a random variable that varies from sample to sample therefore here we are only considering one sample.**

$$E(y) = A 1_n + Bx \text{ is a } \textbf{linear combination} \text{ of } 1_n \text{ and } x \text{ therefore lies in the plane } \{1_n, x\}.$$

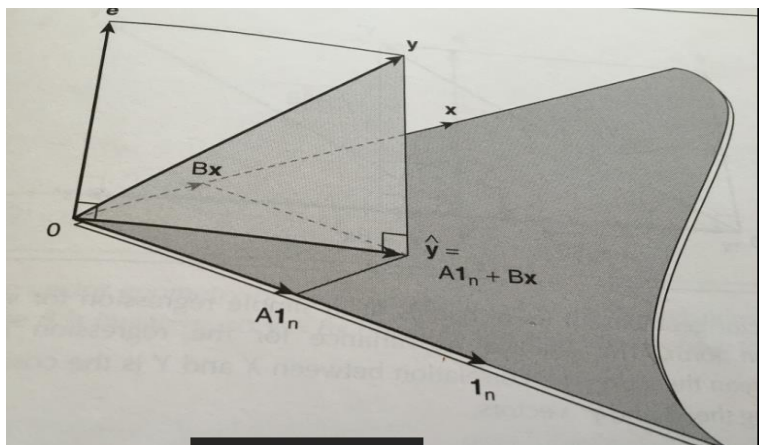


LEAST SQUARE MODEL (Population)

$\epsilon = y - \alpha 1_n - \beta x$ is non zero in the sample but $E(\epsilon) = 0$ over many samples.....6

The Simple Linear Regression model is composed of a three dimensional vector space spanned by vectors $x, y, 1_n$. The $E(y)$ expected value of y lies in the plane spanned by 1_n and x because the expected error is zero ie $E(\epsilon) = 0$.

The square regression model can be depicted by the following graph:



Linear Least Square Fit

The fitted value \hat{y} is a linear combination of x and 1_n therefore it lies in the plane spanned by 1_n and x ie $\{1_n, x\}$. Residual in terms of a vector ie the residual error can be mathematically interpreted as

$e = y - \hat{y}$ has the length (Euclidean norm) in n dimensions $\|e\| = \sqrt{\sum E_i^2}$ 7

Remember we are always trying to minimize the Residual sum of square therefore we will endeavor to do this geometrically as well.

Therefore geometrically we try to minimize $\|e\| = \sqrt{\sum E_i^2}$

The error is $e = y - \hat{y}$ is the length between y and \hat{y} . The minimum length is the orthogonal projection of y onto the plane $\{1, x\}$ which is \hat{y} . This minimizes $\|e\| = \sqrt{\sum E_i^2}$

Remember the normal equations are :

$$\sum_{i=1}^n (A + BX_i - Y_i) = 0$$

$$A \sum_{i=1}^n 1 + B \sum_{i=1}^n X_i - \sum_{i=1}^n Y_i = 0$$

This can be written in vector form by the knowledge that the inner product between two orthogonal vectors = 0 as well as that $\langle u, v \rangle = \sum_{i=1}^n u_i v_i$

$$\langle \vec{1} A + B \vec{X} - \vec{Y}, \vec{1} \rangle = 0$$

$$\text{I.e } \langle e, \vec{1} \rangle = 0$$

The second normal equation can be written as

$$\sum_{i=1}^n X_i (Y_i - A - BX_i) = 0$$

$$\sum_{i=1}^n X_i A + \sum_{i=1}^n X_i^2 B - \sum_{i=1}^n X_i Y_i = 0$$

This can be written in vector form by the knowledge that the inner product between two orthogonal vectors = 0 as well as that $\langle u, v \rangle = \sum_{i=1}^n u_i v_i$

$$\langle \vec{1} A + B \vec{X} - \vec{Y}, X_i \rangle = 0$$

$$\langle e, X \rangle = 0$$

Therefore these equations are called normal equations.

Setting $y^* \equiv Y_i - \bar{Y}$ and $x^* \equiv x_i - \bar{x}$ in equation 10

$$y^* = Bx^* + e \dots\dots\dots 11$$

Remember The **fitted value** is the deviation of the data from the mean of the data (response variable).

$$\hat{y}^* \equiv \hat{Y}_i - \bar{Y} \text{ is a multiple of } x^* \text{ (look at the equation 11).}$$

The length of e is minimized by taking an projection of y^* on x^* . This orthogonal projection is \hat{y}^*

By The formula for orthogonality:

If u and v are vectors then the u^* is the projection then

$$u^* = \frac{u \cdot v}{\|v\|^2} v$$

$$Bx^* = \frac{x^* \cdot y^*}{\|x^*\|^2} x^*$$

$$B = \frac{x^* \cdot y^*}{\|x^*\|^2} = \frac{\sum (x_i - \bar{x})(Y_i - \bar{Y})}{\sum (x_i - \bar{x})^2}$$

$$RSS = \sum E_i^2 = \|e\|^2$$

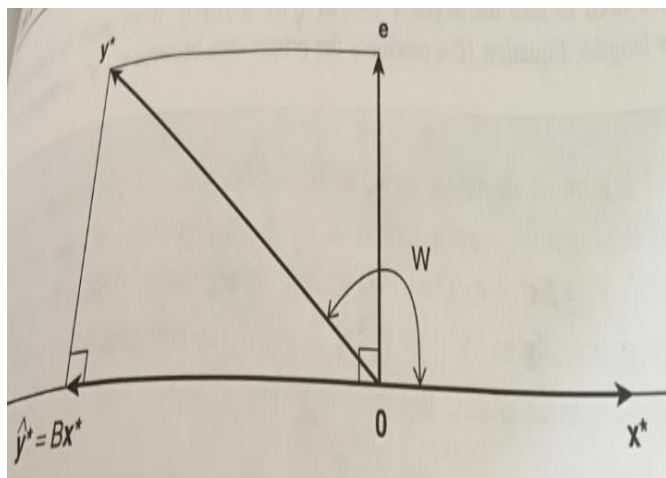
$$TSS = \sum (Y_i - \bar{Y})^2 = \|y^*\|^2$$

$$\text{And RegSS} = \sum (\hat{Y}_i - \bar{Y})^2 = \|\hat{y}^*\|^2$$

$$TSS = \text{RegSS} + RSS$$

Correlation Coefficient:

$$r = \sqrt{\frac{\text{RegSS}}{TSS}} = \frac{\|\hat{y}^*\|}{\|y^*\|}$$



$$r = \frac{x^* y^*}{\|x^*\| \|y^*\|} = \frac{\sum (x_i - \bar{x})(Y_i - \bar{y})}{\sqrt{\sum (x_i - \bar{x})^2 \sum (Y_i - \bar{Y})^2}}$$