Singular Value Decomposition (SVD)

Predictive Modeling & Statistical Learning

Gaston Sanchez

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Introduction

Two Special Decompositions

Last time we talked about the Eigen Value Decomposition (EVD).

In these slides, we'll talk about a closely related decomposition of EVD: the so-called Singular Value Decomposition (SVD)

Recap

Matrix decompositions, also known as matrix factorizations

$$M = AB$$
 or $M = ABC$

are a means of expressing a matrix as a product of usually two or three simpler matrices.

Types of matrices

Two types of matrices

We said that in data analysis we typically concentrate on two types of matrices:

- general rectangular matrices used to represent data tables.
- positive semi-definite matrices used to represent covariance matrices, correlation matrices, and any matrix that results from a crossproduct.

SVD

Singular Value Decomposition

- One of the most important decompositions in matrix algebra
- ► Can be applied to any rectangular matrix
- ► ANY: rectangular or square, singular or nonsigular.

Singular Value Decomposition

An $n \times p$ matrix M can be decomposed as:

$$M = UDV^{\mathsf{T}}$$

where

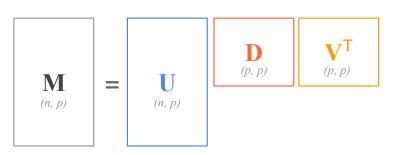
- ▶ U is a $n \times p$ column *orthonormal* matrix containing the left singular vectors
- ▶ D is a $p \times p$ diagonal matrix containing the singular values of M
- ightharpoonup V is a $p \times p$ column **orthonormal** matrix containing the **right singular vectors**

SVD

$$\mathbf{M} = \mathbf{U}\mathbf{D}\mathbf{V}^\mathsf{T}$$

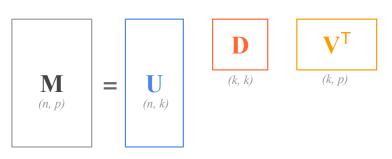
$$\mathbf{M} = \begin{bmatrix} u_{11} & \cdots & u_{1p} \\ u_{21} & \cdots & u_{2p} \\ \vdots & \ddots & \vdots \\ u_{n1} & \cdots & u_{np} \end{bmatrix} \begin{bmatrix} l_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & l_p \end{bmatrix} \begin{bmatrix} v_{11} & \cdots & v_{p1} \\ \vdots & \ddots & \vdots \\ v_{1p} & \cdots & v_{pp} \end{bmatrix}$$

SVD Diagram



When ${f M}$ is of full rank p

SVD Diagram



When \mathbf{M} is of rank k < p

SVD

Singular Value Decomposition

We can think of the SVD structure as the basic structure of a matrix. What do we mean by "basic"? Well, this has to do with what each of the matrices $\mathbf{U}\mathbf{D}\mathbf{V}^\mathsf{T}$ represent.

- ▶ U is the orthonormalized matrix which is the most basic component. It's like the skeleton of the matrix.
- ▶ D is referred to as the *spectrum* and it is a scale component.
- V is an orientation component, also referred to as the rotation matrix.

SVD

▶ U is unitary, and its columns form a basis for the space spanned by the columns of M.

$$\mathbf{U}^\mathsf{T}\mathbf{U} = \mathbf{I}_p$$

ightharpoonup V is unitary, and its columns form a basis for the space spanned by the rows of M.

$$\mathbf{V}^\mathsf{T}\mathbf{V} = \mathbf{I}_p$$

▶ D has non-negative real numbers on the diagonal (assuming M is real).

SVD in R

svd() in R

svd() function

R provides the function svd() to perform a singular value decomposition of a given matrix

svd() output

A list with the following components

- d a vector containing the singular values
- u a matrix whose columns contain the left singular vectors
- v a matrix whose columns contain the right singular vectors

SVD example in R

```
# X matrix
set.seed(22)
X = matrix(rnorm(20), 5, 4)
# singular value decomposition
SVD = svd(X)
# elements returned by svd()
names (SVD)
## [1] "d" "u" "v"
# vector of singular values
(d = SVD$d)
## [1] 3.9516353 2.0223602 1.4748193 0.4324292
```

SVD example in R (con't)

```
# matrix of left singular vectors
(U = SVD\$u)
##
            [,1] [,2] [,3] [,4]
## [1,] -0.4251177 -0.53913435 -0.7232572 0.00979433
## [2,] 0.5268694 -0.76862769 0.2860048 0.05610045
## [3,] 0.5752546 0.04999546 -0.4421464 0.13107213
## [4.] 0.2215220 0.05272644 -0.1702161 -0.95123359
## [5,] -0.4021114 -0.33655016 0.4130778 -0.27337073
# matrix of right singular vectors
(V = SVD\$v)
##
            [,1] [,2] [,3]
                                           Γ.47
## [1,] 0.5708354 -0.7406782 0.33862988 0.1042716
## [2.] -0.2741800 -0.5295008 -0.76797328 0.2338189
## [3.] 0.2772481 0.3206239 -0.04462207 0.9046229
## [4,] 0.7225689 0.2611992 -0.54180782 -0.3407543
```

SVD example in R (con't)

```
# U orthonormal (U'U = I)
t(U) %*% U
              [,1] [,2] [,3] [,4]
##
## [1,] 1.000000e+00 1.387779e-16 2.775558e-17 0.000000e+00
## [2.] 1.387779e-16 1.000000e+00 -2.775558e-17 -8.326673e-17
## [3.] 2.775558e-17 -2.775558e-17 1.000000e+00 5.551115e-17
## [4,] 0.000000e+00 -8.326673e-17 5.551115e-17 1.000000e+00
# V orthonormal (V'V = I)
t(V) %*% V
               [,1] [,2] [,3]
                                                    [.4]
##
## [1,] 1.000000e+00 -1.110223e-16 -5.551115e-17 1.110223e-16
## [2.] -1.110223e-16 1.000000e+00 8.326673e-17 1.942890e-16
## [3,] -5.551115e-17 8.326673e-17 1.000000e+00 -8.326673e-17
## [4,] 1.110223e-16 1.942890e-16 -8.326673e-17 1.000000e+00
```

SVD example in R (con't)

```
\# X equals UD V'
U %*% diag(d) %*% t(V)
##
            [,1] [,2] [,3] [,4]
## [1.] -0.5121391 1.85809239 -0.76390728 -0.9221536
## [2.] 2.4851837 -0.06602641 0.08196190 0.8615624
## [3,] 1.0078262 -0.16276495 0.74302828 2.0029422
## [4.] 0.2928146 -0.19986068 -0.08402219 0.9365510
## [5,] -0.2089594  0.30056173 -0.79289452 -1.6157349
\# compare to X
            [,1] [,2] [,3] [,4]
##
## [1.] -0.5121391 1.85809239 -0.76390728 -0.9221536
## [2.] 2.4851837 -0.06602641 0.08196190 0.8615624
## [3,] 1.0078262 -0.16276495 0.74302828 2.0029422
## [4,] 0.2928146 -0.19986068 -0.08402219 0.9365510
## [5.] -0.2089594  0.30056173 -0.79289452 -1.6157349
```

SVD and Cross-products

Data Matrix

Data

The analyzed data can be expressed in matrix format X:

$$\mathbf{X}_{n \times p} = \begin{bmatrix} x_{11} & x_{12} & \cdots & x_{1p} \\ x_{21} & x_{22} & \cdots & x_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n1} & x_{n2} & \cdots & x_{np} \end{bmatrix}$$

- ightharpoonup n objects in the rows
- p variables in the columns

The cross-product matrix of columns of X can be expressed as:

$$\mathbf{X}^\mathsf{T}\mathbf{X} = \mathbf{V}\mathbf{D}^2\mathbf{V}^\mathsf{T}$$

The cross-product matrix of columns can be expressed as:

$$\mathbf{X}^{\mathsf{T}}\mathbf{X} = (\mathbf{U}\mathbf{D}\mathbf{V}^{\mathsf{T}})^{\mathsf{T}}(\mathbf{U}\mathbf{D}\mathbf{V}^{\mathsf{T}})$$
$$= (\mathbf{V}\mathbf{D}\mathbf{U}^{\mathsf{T}})(\mathbf{U}\mathbf{D}\mathbf{V}^{\mathsf{T}})$$
$$= \mathbf{V}\mathbf{D}(\mathbf{U}^{\mathsf{T}}\mathbf{U})\mathbf{D}\mathbf{V}^{\mathsf{T}}$$
$$= \mathbf{V}\mathbf{D}^{2}\mathbf{V}^{\mathsf{T}}$$

The cross-product matrix of rows of X can be expressed as:

$$\mathbf{X}\mathbf{X}^\mathsf{T} = \mathbf{U}\mathbf{D}^2\mathbf{U}^\mathsf{T}$$

The cross-product matrix of rows can be expressed as:

$$\begin{split} \mathbf{X}\mathbf{X}^\mathsf{T} &= (\mathbf{U}\mathbf{D}\mathbf{V}^\mathsf{T})(\mathbf{U}\mathbf{D}\mathbf{V}^\mathsf{T})^\mathsf{T} \\ &= (\mathbf{U}\mathbf{D}\mathbf{V}^\mathsf{T})(\mathbf{V}\mathbf{D}\mathbf{U}^\mathsf{T}) \\ &= \mathbf{U}\mathbf{D}(\mathbf{V}^\mathsf{T}\mathbf{V})\mathbf{D}\mathbf{U}^\mathsf{T} \\ &= \mathbf{U}\mathbf{D}^2\mathbf{U}^\mathsf{T} \end{split}$$

One of the interesting things about SVD is that \mathbf{U} and \mathbf{V} are matrices whose columns are eigenvectors of product moment matrices that are *derived* from \mathbf{X} . Specifically,

- ▶ U is the matrix of eigenvectors of (symmetric) XX^T of order $n \times n$
- ▶ **V** is the matrix of eigenvectors of (symmetric) $\mathbf{X}^T\mathbf{X}$ of oreder $p \times p$

Of additional interest is the fact that D is a diagonal matrix whose main diagonal entries are the square roots of $\Lambda,$ the common matrix of eigenvalues of XX^T and $X^\mathsf{T}X.$

Relation between EVD and SVD

The EVD of the cross-product matrix of columns (or minor product moment) X^TX can be expressed as:

$$\mathbf{X}^\mathsf{T}\mathbf{X} = \mathbf{V}\boldsymbol{\Lambda}\mathbf{V}^\mathsf{T}$$

in terms of the SVD factorization of X:

$$\mathbf{X}^\mathsf{T}\mathbf{X} = \mathbf{V}\mathbf{D^2}\mathbf{V}^\mathsf{T}$$

Relation between EVD and SVD

The EVD of the cross-product matrix of rows (or major product moment) XX^T can be expressed as:

$$\mathbf{X}\mathbf{X}^\mathsf{T} = \mathbf{U}\boldsymbol{\Lambda}\mathbf{U}^\mathsf{T}$$

in terms of the SVD factorization of X:

$$\mathbf{X}\mathbf{X}^\mathsf{T} = \mathbf{U}\mathbf{D}^2\mathbf{U}^\mathsf{T}$$

Rank Reduction

In terms of the diagonal elements l_1, l_2, \ldots, l_r of \mathbf{D} , the columns $\mathbf{u_1}, \ldots, \mathbf{u_r}$ of \mathbf{U} , and the columns $\mathbf{v_1}, \ldots, \mathbf{v_r}$ of \mathbf{V} , the basic structure of \mathbf{X} may be written as

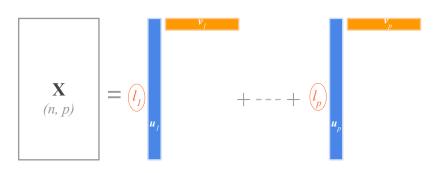
$$\mathbf{X} = l_1 \mathbf{u}_1 \mathbf{v}_1^\mathsf{T} + l_2 \mathbf{u}_2 \mathbf{v}_2^\mathsf{T} + \dots + l_p \mathbf{u}_p \mathbf{v}_p^\mathsf{T}$$

which shows that the matrix X of rank p is a linear combination of r matrices of rank 1.

A very interesting and alternative way to represent the SVD is with the following formula:

$$\mathbf{X} = \sum_{k=1}^{p} l_k \mathbf{u_k} \mathbf{v_k}^\mathsf{T}$$

SVD Diagram



SVD as sum of rank one matrices

SVD alternative formula:

$$\mathbf{X} = \sum_{k=1}^{p} l_k \mathbf{u_k} \mathbf{v_k}^\mathsf{T}$$

- ▶ This expresses the SVD as a sum of p rank 1 matrices.
- ► This result is formalized in what is known as the SVD theorem described by Carl Eckart and Gale Young in 1936, and it is often referred to as the Eckart-Young theorem.
- ► This theorem applies to practily any arbitrary rectangular matrix.

What if you take r < p terms?

$$\hat{\mathbf{X}} = \sum_{k=1}^{r} l_k \mathbf{u_k} \mathbf{v_k}^\mathsf{T}$$

How would $\hat{\mathbf{X}}$ compare to \mathbf{X} ?

The SVD theorem of Eckart and Young is related to the important problem of approximating a matrix.

The basic result says that if X is an $n \times p$ rectangular matrix, then the best r-dimensional approximation \hat{X} to X is obtained by minimizing:

$$min \|\mathbf{X} - \hat{\mathbf{X}}\|^2$$

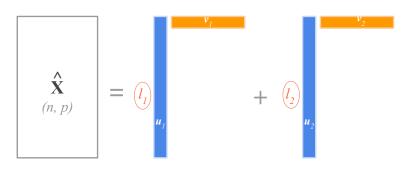
The minimization problem:

$$min \|\mathbf{X} - \hat{\mathbf{X}}\|^2$$

is a special type of approximation: a least squares approximation.

The solution is obtained by taking the first r elements of matrices U, D, V so that $\hat{\mathbf{X}} = \mathbf{U_r} \mathbf{D_r} \mathbf{V_r}^\mathsf{T}$

SVD rank-two approximation



SVD as sum of two rank one matrices

The best 2-rank approximation \hat{X} of X is given by:

$$\hat{\mathbf{X}} = l_1 \mathbf{u_1} \mathbf{v_1}^\mathsf{T} + l_2 \mathbf{u_2} \mathbf{v_2}^\mathsf{T}$$

We can say that the "information" contained in $n \times p$ values is compressed into $n \times 2$ values.

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