

1. **Perform basic Image Handling and processing operations on the image. • Read an image in python and Convert an Image to Grayscale**

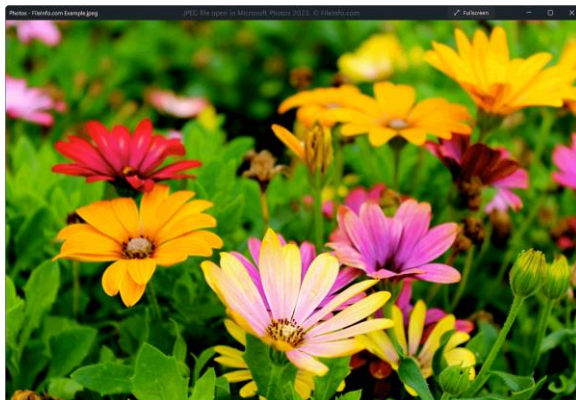
AIM:

To Perform Basic Operations to Read Image and Convert to Grayscale using Python

PROGRAM:

```
import cv2
import numpy as np
kernel = np.ones((5,5),np.uint8)
print(kernel)
path="C:/Users/91824/OneDrive/flower.jpeg"
img =cv2.imread(path)
imgGray = cv2.cvtColor(img,cv2.COLOR_BGR2GRAY)
cv2.imshow("GrayScale",imgGray)
cv2.waitKey(0)
```

INPUT:



OUTPUT:



2. **Perform basic Image Handling and processing operations on the image.**• Read an image in python and Convert an Image to Blur using GaussianBlur.

AIM:

To Perform Basic Operations to Read Image and Convert to Blur using **GaussianBlur**.

PROGRAM:

```
import cv2
import numpy as np
kernel = np.ones((5,5),np.uint8)
print(kernel)
path="C:/Users/91824/OneDrive/forest.jpeg"
img =cv2.imread(path)
imgGray = cv2.cvtColor(img,cv2.COLOR_BGR2GRAY)
imgBlur = cv2.GaussianBlur(imgGray,(7,7),0)
cv2.imshow("Img Blur",imgBlur)
cv2.waitKey(0)
```

INPUT:



OUTPUT:



3. **Perform basic Image Handling and processing operations on the image• Read an image in python and Convert an Image to show outline using Canny function**

AIM:

To Perform Basic Operations to Convert image to show outline Canny function in Python

PROGRAM:

```
import cv2
import numpy as np
kernel = np.ones((5,5),np.uint8)
print(kernel)
path = "C:/Users/91824/OneDrive/river.jpeg"
img =cv2.imread(path)
imgGray = cv2.cvtColor(img,cv2.COLOR_BGR2GRAY)
imgBlur = cv2.GaussianBlur(imgGray,(7,7),0)
imgCanny = cv2.Canny(imgBlur,100,200)
cv2.imshow("Img Canny",imgCanny)
cv2.waitKey(0)
```

INPUT:



OUTPUT:



4. **Perform basic Image Handling and processing operations on the image**• Read an image in python and Dilate an Image using Dilate function

AIM:

To Perform Basic Operations to Read Image and Dilate an Image using Python

PROGRAM:

```
import cv2
import numpy as np
kernel = np.ones((5,5),np.uint8)
print(kernel)
path = "C:/Users/91824/OneDrive/trees.jpeg"
img =cv2.imread(path)
imgGray = cv2.cvtColor(img,cv2.COLOR_BGR2GRAY)
imgBlur = cv2.GaussianBlur(imgGray,(7,7),0)
imgCanny = cv2.Canny(imgBlur,100,200)
imgDilation = cv2.dilate(imgCanny,kernel , iterations = 10)
imgEroded = cv2.erode(imgDilation,kernel,iterations=2)
cv2.imshow("Img Erosion",imgEroded)
cv2.waitKey(0)
```

INPUT:



OUTPUT:



5. Perform basic Image Handling and processing operations on the image• Read an image in python and Erode an Image using erode function

AIM:

The Aim of the experiment is to Read an image in python and Erode an Image using erode function

PROGRAM:

```
import cv2
import numpy as np
kernel = np.ones((5,5),np.uint8)
print(kernel)
path = "C:/Users/91824/OneDrive/nature.jpg"
img =cv2.imread(path)
imgGray = cv2.cvtColor(img,cv2.COLOR_BGR2GRAY)
imgBlur = cv2.GaussianBlur(imgGray,(7,7),0)
imgCanny = cv2.Canny(imgBlur,100,200)
imgDilation = cv2.dilate(imgCanny,kernel , iterations = 10)
imgEroded = cv2.erode(imgDilation,kernel,iterations=2)
cv2.imshow("Img Erosion",imgEroded)
cv2.waitKey(0)
```

INPUT:



OUTPUT:



6. **Perform basic video processing operations on the captured video• Read captured video in python and display the video, in slow motion and in fast motion.**

AIM:

The Aim of the Experiment is to Read captured video in python and display the video, in slow motion and in fast motion

PROGRAM:

```
import cv2
import numpy as np
cap = cv2.VideoCapture("C:/Users/91824/Videos/@Team_Hevc - Pathu Thala (2023) 1080p HQ HDRip Multi ESu.mkv")
if (cap.isOpened()== False):
    print("Error opening video file")
while(cap.isOpened()):
    ret, frame = cap.read()
    if ret == True:
        cv2.imshow('Frame', frame)
        if cv2.waitKey(250) & 0xFF == ord('q'):
            break
    else:
        break
cap.release()
cv2.destroyAllWindows()
```

INPUT:

OUTPUT:



7. **Capture video from web Camera and Display the video, in slow motion and in fast motion operations on the captured video**

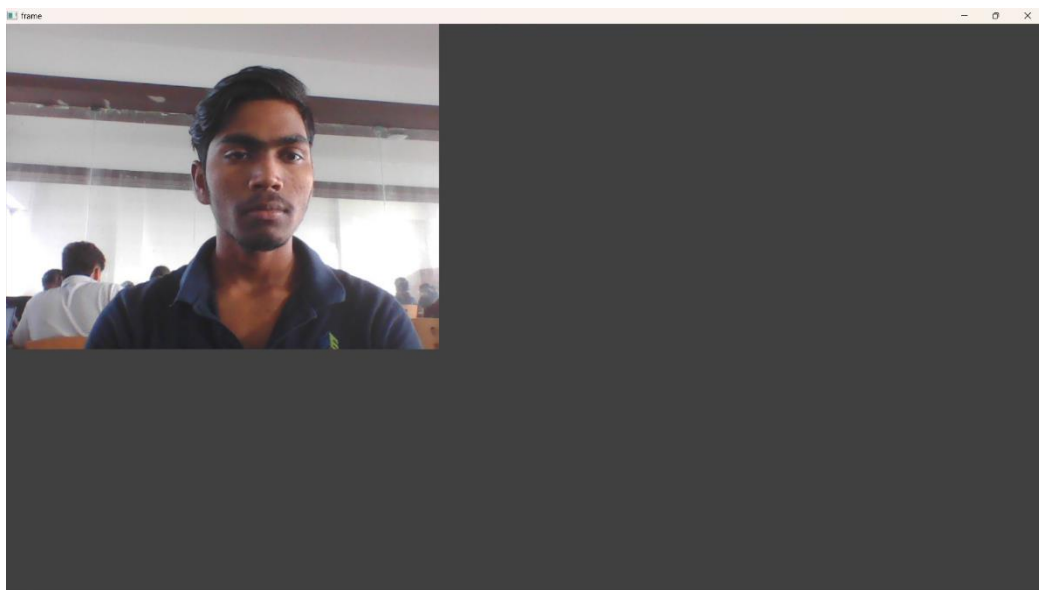
AIM:

The Aim is to Capture video from web Camera and Display the video, in slow motion and in fast motion operations on the captured video

PROGRAM:

```
import cv2
cap = cv2.VideoCapture(0)
height = int(cap.get(cv2.CAP_PROP_FRAME_HEIGHT))
width = int(cap.get(cv2.CAP_PROP_FRAME_WIDTH))
fps = cap.get(cv2.CAP_PROP_FPS)
path = "output.mp4"
fourcc = cv2.VideoWriter_fourcc(*'mp4v')
output = cv2.VideoWriter(path, fourcc, 2, (width, height))
while True:
    ret, frame = cap.read()
    cv2.imshow("frame", frame)
    output.write(frame)
    k = cv2.waitKey(24)
    if k == ord("q"):
        break
cap.release()
output.release()
cv2.destroyAllWindows()
```

OUTPUT:



8. Scaling an image to its Bigger and Smaller sizes.

AIM:

The Aim is resize the image from bigger to smaller size

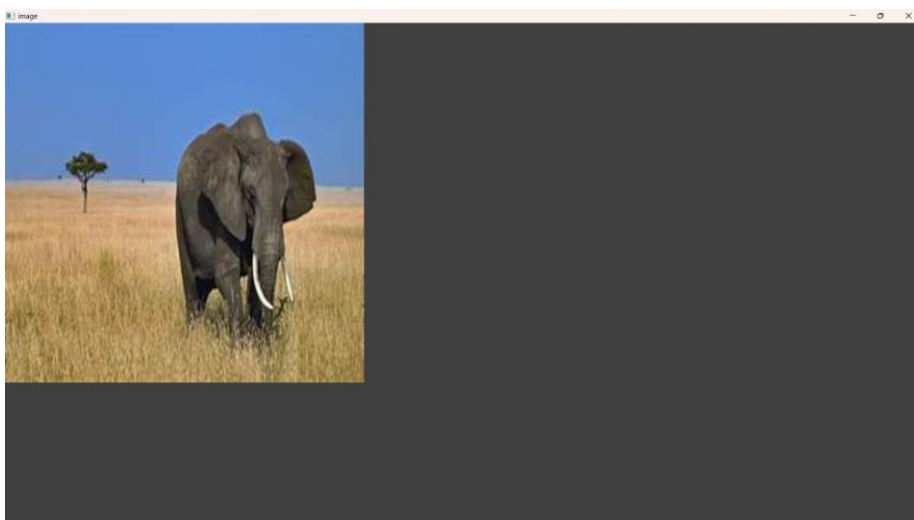
PROGRAM:

```
import cv2
import numpy as np
kernel = np.ones((5,5),np.uint8)
img = cv2.imread("C:/Users/91824/OneDrive/eswar.jpeg",cv2.IMREAD_COLOR)
img = cv2.resize(img,(600,600))
cv2.imshow("image",img)
cv2.waitKey(0)
```

INPUT:



OUTPUT:



9. Perform Rotation of an image to clockwise and counter clockwise direction.

ROTATION 90 ALONG DEGREE:

AIM :

The Aim of the Experiment is to perform Rotation of an image along 90 degree

PROGRAM:

```
import cv2
path = "C:/Users/91824/Downloads/trees.jpeg"
src = cv2.imread(path)
window_name = 'Image'
image = cv2.rotate(src, cv2.ROTATE_180)
cv2.imshow(window_name, image)
cv2.waitKey(0)
```

INPUT:



OUTPUT:



ROTATION ALONG 180 DEGREE

AIM:

The Aim of the Experiment is to perform Rotation of an image along 180 degree

PROGRAM:

```
import cv2
path ="C:/Users/91824/Downloads/trees.jpeg"
src = cv2.imread(path)
window_name = 'Image'
image = cv2.rotate(src, cv2.ROTATE_90_COUNTERCLOCKWISE)

cv2.imshow(window_name, image)
cv2.waitKey(0)
```

OUTPUT:



10. ROTATION ALONG 270 DEGREE

AIM :

The Aim of the Experiment is to perform Rotation of an image along 270 degree

PROGRAM:

```
import cv2
path = "C:/Users/91824/Downloads/trees.jpeg"
src = cv2.imread(path)
image_rotated_270 = cv2.rotate(src, cv2.ROTATE_90_CLOCKWISE)
cv2.imshow('Rotated Image 270', image_rotated_270)
cv2.waitKey(0)
cv2.destroyAllWindows()
```

OUTPUT:

