## 数值分析方法

作业2

## Problem 1

```
解: 由题意: f(x) = -x^3 - \cos x, f'(x) = -3x^2 + \sin x 代码如下:
```

```
#include < stdio.h>
   #include < math.h>
3
   int main()
4
5
   {
6
           int i=0;
           double p,p0,delta=1;
8
           scanf("%lf",&p0);
9
           while(i <= 1) {
10
                   p=p0-(-pow(p0,3)-cos(p0))/\
                    (-3*pow(p0,2)+sin(p0));
11
12
                    delta=p-p0;
                    if (delta<0){
13
14
                            delta=-delta;
15
                    }
                    16
17
                    |p-p0| = \%.81f \setminus n",++i,p,delta);
18
                   p0=p;
           }
19
20
    }
```

可得:

n	$p_n$	$ p_n - p_{n-1} $
1	-0.88033290	0.11966710
2	-0.86568416	0.01464874

```
p_2 = -0.86568416
```

: f'(0) = 0

.: 不能使用 $p_0 = 0$ 

解: (i) 由题意:

$$f(x) = b - \frac{1}{x}$$

则:

$$f'(x) = \frac{1}{x^2}$$

由牛顿迭代法:

$$x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)} = x_k - \frac{b - \frac{1}{x_k}}{\frac{1}{x_k^2}} = 2x_k - bx_k^2$$

所以

$$|\epsilon_{k+1}| = \frac{|x - x_{k+1}|}{|x|} = \frac{\left|\frac{1}{b} - x_{k+1}\right|}{\frac{1}{b}} = |1 - bx_{k+1}| = |b^2x_k^2 - 2bx_k + 1| = (bx_k - 1)^2$$

又因为

$$\epsilon_k = \frac{\frac{1}{b} - x_k}{\frac{1}{b}} = 1 - bx_k$$

所以

$$|\epsilon_{k+1}| = \epsilon_k^2$$

证毕.

(ii) 由(i)得:

$$\left| x_{k+1} - \frac{1}{b} \right| = \left| 2x_k - bx_k^2 - \frac{1}{b} \right| = \frac{|2bx_k - b^2x_k^2 - 1|}{b} = \frac{|bx_k - 1|^2}{b}$$
$$\left| x_k - \frac{1}{b} \right| = \frac{|bx_k - 1|}{b}, \quad k = 0, 1, 2 \dots$$

所以

$$\left| x_{k+1} - \frac{1}{b} \right| = \frac{|bx_k - 1|^2}{b}$$

同理可得

$$\left| x_k - \frac{1}{b} \right| = \frac{|bx_k - 1|}{b} = \frac{|bx_{k-1} - 1|^2}{b}$$

所以

$$|bx_k - 1| = |bx_{k-1} - 1|^2$$

$$\left| x_{k+1} - \frac{1}{b} \right| = \frac{|bx_k - 1|^2}{b} = \frac{|bx_{k-1} - 1|^4}{b} = \dots = \frac{|bx_0 - 1|^{2^{k+1}}}{b}$$

由题意:

$$0 < x_0 < \frac{2}{b}$$

則:  $|bx_0 - 1| \in [0, 1)$ 

$$\therefore \lim_{k \to \infty} \left| x_{k+1} - \frac{1}{b} \right| = \lim_{k \to \infty} \frac{|bx_0 - 1|^{2^{k+1}}}{b} = 0$$

即数列 $\{x_k\}_{k=0}^{\infty}$ 收敛到 $\frac{1}{b}$ , 证毕.

解: a. 由题意, 令

$$f_1 = 3x_1 - \cos(x_2 x_3) - \frac{1}{2}$$

$$f_2 = 4x_1^2 - 625x_2^2 + 2x_2 - 1$$

$$f_3 = e^{-x_1 x_2} + 20x_3 + \frac{10\pi - 3}{3}$$

则雅可比矩阵

$$\mathbf{J} = \begin{pmatrix} 3 & x_3 \sin(x_2 x_3) & x_2 \sin(x_2 x_3) \\ 8x_1 & -1250x_2 + 2 & 0 \\ -x_2 e^{-x_1 x_2} & -x_1 e^{-x_1 x_2} & 20 \end{pmatrix}$$

```
#include < stdio.h>
   #include < math.h>
3
   #define e 2.718281828459
5
   #define pi 3.1415926535898
6
7
   int main()
9
             int i = 0;
10
             double f1, f2, f3;
             double x01, x02, x03;
11
12
             double x1,x2,x3;
13
             double y1,y2,y3;
14
             double j1[3],j2[3],j3[3];
15
             double jn1[3], jn2[3], jn3[3];
16
             double det;
             scanf("%lf,%lf,%lf",&x01,&x02,&x03);
17
18
             while (i \le 1)
19
                       f1 = 3 \times x01 - \cos(x02 \times x03) - 0.5;
20
                       f2 = 4*pow(x01, 2) - 625*pow(x02, 2) + 2*x02 - 1;
21
                       f3 = pow(e, -x01*x02) + 20*x03 + (10*pi-3)/3;
22
                       \mathbf{j1} [0] = 3; //Jacobi Matrix
23
                       j1[1]=x03*sin(x02*x03);
24
                       j1[2]=x02*sin(x02*x03);
25
                       j2[0]=8*x01;
26
                       j2[1] = -1250 * x02 + 2;
27
                       j2[2]=0;
28
                       j3[0] = -x02*pow(e, -x01*x02);
29
                       j3[1] = -x01*pow(e, -x01*x02);
```

```
30
                    j3 [2] = 20;
31
                    \det = j1[0]*(j2[1]*j3[2]-j2[2]*j3[1])
32
                    -j2[0]*(j1[1]*j3[2]-j1[2]*j3[1])+
33
                    j3[0]*(j1[1]*j2[2]-j1[2]*j2[1]);
34
                    //the Determinant
35
36
                    jn1[0] = (j2[1]*j3[2]-j2[2]*j3[1])/det;
37
                    jn1[1]=(j1[2]*j3[1]-j1[1]*j3[2])/det;
38
                    jn1[2]=(j1[1]*j2[2]-j1[2]*j2[1])/det;
                    jn2[0]=(j2[2]*j3[0]-j2[0]*j3[2])/det;
39
40
                    jn2[1]=(j1[0]*j3[2]-j1[2]*j3[0])/det;
                    jn2[2]=(j2[0]*j1[2]-j1[0]*j2[2])/det;
41
42
                    jn3[0] = (j2[0]*j3[1]-j2[1]*j3[0])/det;
43
                    jn3[1]=(j1[1]*j3[0]-j1[0]*j3[1])/det;
44
                    jn3[2] = (j1[0]*j2[1]-j2[0]*j1[1])/det;
                    //inverse matrix of the Jacobi Matrix
45
46
47
                    y1=jn1[0]*f1+jn1[1]*f2+jn1[2]*f3;
48
                    y2=jn2[0]*f1+jn2[1]*f2+jn2[2]*f3;
49
                    y3=jn3[0]*f1+jn3[1]*f2+jn3[2]*f3;
50
                    x1=x01-y1;
51
                    x2=x02-y2;
52
                    x3=x03-y3;
                    printf("n = \%d, x1 = \%.8f, x2 = \%.8f\
53
54
   , x3 = \%.8 f \ n'', ++i, x1, x2, x3);
55
                    x01=x1;
                    x02=x2;
56
57
                    x03=x3;
58
            }
59
    }
```

可得:

n	$x_1^{(n)}$	$x_2^{(n)}$	$x_3^{(n)}$
1	0.50000000	0.50000000	-0.52359878
2	0.50016669	0.25080364	-0.51738743

 $\mathbf{x}^{(2)} = (0.50016669, 0.25080364, -0.51738743)^{\mathbf{T}}.$ 

b. 由题意, 令

$$f_1 = x_1^2 + x_2 - 37$$
$$f_2 = x_1 - x_2^2 - 5$$

$$f_3 = x_1 + x_2 + x_3 - 3$$

则雅可比矩阵

$$\mathbf{J} = \begin{pmatrix} 2x_1 & 1 & 0 \\ 1 & -2x_2 & 0 \\ 1 & 1 & 1 \end{pmatrix}$$

```
#include < stdio.h>
2
   #include < math.h>
3
4
   int main()
5
6
             int i = 0;
7
             double f1, f2, f3;
             double x01, x02, x03;
9
             double x1, x2, x3;
             double y1, y2, y3;
10
11
             double j1[3],j2[3],j3[3];
12
             double jn1[3],jn2[3],jn3[3];
13
             double det;
             scanf("%lf,%lf,%lf",&x01,&x02,&x03);
14
15
             while (i \le 1){
16
                      f1 = pow(x01, 2) + x02 - 37;
17
                      f2 = x01 - pow(x02, 2) - 5;
                      f3 = x01 + x02 + x03 - 3;
18
19
                      j1[0]=2*x01;
20
                      j1[1]=1;
21
                      j1[2]=0;
22
                      j2[0]=1;
23
                      j2[1] = -2 * x02;
24
                      j2 [2] = 0;
25
                      j3[0]=1;
26
                      j3[1]=1;
27
                      j3[2]=1;
28
                      \det = j1[0]*(j2[1]*j3[2]-j2[2]*j3[1])
29
                      -j2[0]*(j1[1]*j3[2]-j1[2]*j3[1])+
30
                      j3[0]*(j1[1]*j2[2]-j1[2]*j2[1]);
31
                      //the Determinant
32
33
                      jn1[0] = (j2[1]*j3[2]-j2[2]*j3[1])/det;
```

```
34
                    jn1[1]=(j1[2]*j3[1]-j1[1]*j3[2])/det;
35
                    jn1[2]=(j1[1]*j2[2]-j1[2]*j2[1])/det;
36
                    jn2[0] = (j2[2]*j3[0]-j2[0]*j3[2])/det;
37
                    jn2[1]=(j1[0]*j3[2]-j1[2]*j3[0])/det;
38
                    jn2[2]=(j2[0]*j1[2]-j1[0]*j2[2])/det;
39
                    jn3[0] = (j2[0]*j3[1]-j2[1]*j3[0])/det;
                    jn3[1]=(j1[1]*j3[0]-j1[0]*j3[1])/det;
40
41
                    jn3[2]=(j1[0]*j2[1]-j2[0]*j1[1])/det;
                    //inverse matrix of the Jacobi Matrix
42
43
44
                    y1=jn1[0]*f1+jn1[1]*f2+jn1[2]*f3;
                    y2=jn2[0]*f1+jn2[1]*f2+jn2[2]*f3;
45
                    y3=jn3[0]*f1+jn3[1]*f2+jn3[2]*f3;
46
47
                    x1=x01-y1;
48
                    x2=x02-y2;
49
                    x3=x03-y3;
                    printf("n = \%d, x1 = \%.8f, x2 = \%.8f\
50
   x3 = \%.8 f \ n, ++i, x1, x2, x3);
51
52
                    x01=x1;
53
                    x02=x2;
                    x03=x3;
54
55
            }
56
    }
```

可得:

n	$x_1^{(n)}$	$x_2^{(n)}$	$x_3^{(n)}$
1	0.50000000	37.00000000	-39.00000000
2	4.35087719	18.49122807	-19.84210526

 $\mathbf{x}^{(2)} = (4.35087719, 18.49122807, -19.84210526)^{\mathbf{T}}.$ 

## Problem 4

解: a. 由题意:

$$f_1 = 15x_1 + x_2^2 - 4x_3 - 13$$

$$f_2 = x_1^2 + 10x_2 - x_3 - 11$$

$$f_3 = x_2^3 - 25x_3 + 22$$

$$g(\mathbf{x}) = f_1^2 + f_2^2 + f_3^2$$

令

```
\therefore \nabla g(\mathbf{x}) = \left(\frac{\partial g}{\partial x_1}, \frac{\partial g}{\partial x_2}, \frac{\partial g}{\partial x_3}\right) = 2 \begin{pmatrix} 2x_1^3 + 15x_2^2 - 2x_1x_3 + 20x_1x_2 + 203x_1 - 60x_3 - 195 \\ 10x_1^2 + 2x_2^3 - 3x_2^5 - 66x_2^2 + 74x_2 + 30x_1x_2 - 10x_3 - 110 + 75x_2^2x_3 \\ -x_1^2 - 4x_2^2 - 25x_2^3 - 60x_1 - 10x_2 + 643x_3 - 487 \end{pmatrix}
```

```
#include < stdio.h>
   #include < math.h>
   #include < stdlib.h>
4
   #define e 2.718281828459
   #define pi 3.1415926535898
   int main()
9
10
             int i = 0;
11
             double f1, f2, f3;
12
             double a, a0, a1, a2, a3;
13
             double h1, h2, h3;
             double g,g0,g1=0,g2,g3;
14
15
             double x01, x02, x03;
16
             double z1, z2, z3, z0;
17
             double tol, min=10;
             scanf("%lf, %lf, %lf, %lf", &x01, &x02, &x03, &tol);
18
             while (fabs(min-g1)>=tol){
19
20
                      f1 = 15 * x01 + pow(x02, 2) - 4 * x03 - 13;
21
                      f2 = pow(x01, 2) + 10 * x02 - x03 - 11;
22
                      f3 = pow(x02, 3) - 25 * x03 + 22;
23
                      g1 = f1 * f1 + f2 * f2 + f3 * f3;
24
                      z1=2*(2*x01*x01*x01+15*x02*x02-2*x01*)
25
                         x02+203*x01-60*x03-195);
26
                      z2=2*(10*x01*x01+2*x02*x02*x02-3*)
27
                         pow(x02,5) -66*pow(x02,2) +74*x02
28
                          +30*x01*x02-10*x03-110+
29
                          75*pow(x02,2)*x03);
30
                      z3=2*(-x01*x01-4*x02*x02-25*pow(x02,3))
31
                          -60*x01-10*x02+643*x03-487);
32
                      z0 = sqrt(pow(z1, 2) + pow(z2, 2) + pow(z3, 2));
                      //z0 is the L2-norm of the vector z
33
                      if (z0==0){
34
35
                                printf("failed, z0 = 0, n = \)
```

```
36
   \%d, x1 = \%.8f, x2 = \%.8f, x3 = \%.8f \setminus n, x01, x02, x03;
37
                              exit(0);
38
                     }
39
                     z1/=z0;
                     z2/=z0;
40
41
                     z3/=z0;
42
                     a1=0;
43
                     a3=1;
                     g3=pow((15*(x01-a3*z1)+pow(x02-a3*z2),\
44
                         2) -4*(x03-a3*z3)-13), 2) +pow((pow\
45
                         (x01-a3*z1,2)+10*(x02-a3*z2)-
46
                         (x03-a3*z3)-11),2)+pow((pow)
47
                         (x02-a3*z2,3)-25*(x03-a3*z3)+22),2);
48
                     while (g3>=g1){
49
50
                              a3/=2;
51
                              g3 = pow((15*(x01-a3*z1)+
52
                                 pow(x02-a3*z2,2) - \
                                 4*(x03-a3*z3)-13),2)+
54
                                 pow((pow(x01-a3*z1,2)+
                                  10*(x02-a3*z2)-(x03-a3*z3)
55
                                  -11),2)+pow((pow(x02-a3*z2)
56
57
                                  ,3)-25*(x03-a3*z3)+22),2);
                              if (a3<0.01*tol){
58
59
                                       printf("failed, a3 = \
60
   \%.81f, n = \%d, x1 = \%.81f, x2 = \%.81f, x3 = \%.81f \setminus n",
   a3, i, x01, x02, x03);
61
62
                                       exit(0);
                              }
63
64
                     }
65
                     a2=a3/2;
                     g2=pow((15*(x01-a2*z1)+pow(x02-a2*z2)
66
                         ,2)-4*(x03-a2*z3)-13),2)+pow((pow)
67
68
                         (x01-a2*z1,2)+10*(x02-a2*z2)-
                         (x03-a2*z3)-11),2)+pow((pow\
69
70
                         (x02-a2*z2,3)-25*(x03-a2*z3)+22),2);
71
                     h1=(g2-g1)/a2;
72
                     h2=(g3-g2)/(a3-a2);
73
                     h3=(h2-h1)/a3;
74
                     a0=(a2-h1/h3)/2;
                     g0=pow((15*(x01-a0*z1)+pow(x02-a0*z2)
75
76
                         ,2)-4*(x03-a0*z3)-13),2)+pow((pow)
```

```
(x01-a0*z1,2)+10*(x02-a0*z2)-
77
78
                           (x03-a0*z3)-11),2)+pow((pow\
                           (x02-a0*z2,3)-25*(x03-a0*z3)+22),2);
79
80
                       min=g0;
                       if (g3<min) {
81
82
                                 min=g3;
                       }
84
                       if (min=g0) {
                                 a=a0;
85
                       }
86
                       else {
87
88
                                 a=a3;
                       }
89
                       x01 -= a * z1;
90
                       x02 -= a * z2;
91
92
                       x03 -= a * z3;
                       printf("n = \%d, x1 = \%.81f, x2 = \
93
    \%.81f, x3 = \%.81f, g = \%.81f \setminus n, ++i, x01, x02, x03, min);
94
95
96
    }
```

令 $\mathbf{x} = (1, 1, 1)^{\mathbf{T}}$ ,可得:

n	$x_1^{(n)}$	$x_{2}^{(n)}$	$x_3^{(n)}$	$g^{(n)}$
1	1.05321268	0.99712364	0.91946190	0.71702448
2	1.05481094	0.99718700	0.91937309	0.71640813

二一个近似解为  $\mathbf{x} = (1.05481094, 0.99718700, 0.91937309)^{\mathbf{T}}$ .

## b. 由题意:

$$f_1 = 10x_1 - 2x_2^2 + x_2 - 2x_3 - 5$$
$$f_2 = 8x_2^2 + 4x_3^2 - 9$$
$$f_3 = 8x_2x_3 + 4$$

令

$$g(\mathbf{x}) = f_1^2 + f_2^2 + f_3^2$$

$$\therefore \nabla g(\mathbf{x}) = \left(\frac{\partial g}{\partial x_1}, \frac{\partial g}{\partial x_2}, \frac{\partial g}{\partial x_3}\right) = 2 \left(136x_2^3 - 6x_2^2 + 128x_2x_3^2 - 40x_1x_2 + 8x_2x_3 + 10x_1 - 123x_2 + 30x_3 - 5x_3^2 + 128x_2^2x_3 + 4x_2^2 - 20x_1 + 30x_2 - 68x_3 + 10x_3^2 + 30x_3 - 5x_3^2 + 128x_2^2x_3 + 4x_2^2 - 20x_1 + 30x_2 - 68x_3 + 10x_3^2 + 30x_3^2 + 128x_2^2x_3 + 4x_2^2 - 20x_1 + 30x_2 - 68x_3 + 10x_3^2 + 30x_3^2 +$$

```
#include < stdio.h>
   #include < math.h>
3
   #include < stdlib.h>
4
5
   #define e 2.718281828459
   #define pi 3.1415926535898
6
7
8
   int main()
9
10
             int i = 0;
11
             double f1, f2, f3;
12
             double a, a0, a1, a2, a3;
13
             double h1, h2, h3;
14
             double g,g0,g1=0,g2,g3;
             double x01, x02, x03;
15
16
             double z1, z2, z3, z0;
17
             double tol, min=10;
             scanf("%lf, %lf, %lf, %lf", &x01, &x02, &x03, &tol);
18
19
             while (fabs(min-g1)>=tol){
20
                      f1 = 10 \times x01 - 2 \times pow(x02, 2) + x02 - 2 \times x03 - 5;
21
                      f2 = 8*pow(x02, 2) + 4*pow(x03, 2) - 9;
22
                      f3 = 8 * x02 * x03 + 4;
23
                      g1 = f1 * f1 + f2 * f2 + f3 * f3;
                      z1=2*(100*x01-20*x02*x02+10*x02
24
                          -20*x03-50);
25
26
                      z2=2*(136*x02*x02*x02-6*x02*x02+128*)
27
                          x02*x03*x03-40*x01*x02+8*x02*x03
28
                          +10*x01-123*x02+30*x03-5);
                      z3=2*(32*x03*x03*x03+128*x02*x02*x03+4)
29
                         *pow(x02,2)-20*x01+30*x02-68*x03+10);
30
31
                      z0 = sqrt(pow(z1,2) + pow(z2,2) + pow(z3,2));
32
                      //z0 is the L2-norm of the vector z
33
                      if (z0==0){
34
                                printf("failed, z0 = 0, n = \)
35
   \%d, x1 = \%.8f, x2 = \%.8f, x3 = \%.8f \setminus n, x01, x02, x03;
36
                                exit(0);
37
                      }
                      z1/=z0;
38
39
                      z2/=z0;
40
                      z3/=z0;
41
                      a1=0;
```

```
42
                     a3=1;
43
                     g3 = pow((10*(x01-a3*z1)-2*pow((x02-)
44
                        a3*z2),2)+(x02-a3*z2)-2*(x03-a3*z3)\
45
                        -5),2)+pow((8*pow((x02-a3*z2),2)+\
                        4*pow((x03-a3*z3),2)-9),2)+pow
46
                        ((8*(x02-a3*z2)*(x03-a3*z3)+4),2);
47
48
                     while (g3>=g1){
49
                             a3/=2;
                             g3 = pow((10*(x01-a3*z1)-2*pow()
50
                                 (x02-a3*z2),2)+(x02-a3*z2)
51
                                 -2*(x03-a3*z3)-5),2)+pow(
52
                                 (8*pow((x02-a3*z2),2)+4*
53
54
                                pow((x03-a3*z3),2)-9),2)+
                                pow((8*(x02-a3*z2)*(x03-
55
56
                                a3*z3)+4),2);
57
                             if (a3<0.01*tol){</pre>
58
                                      printf("failed, a3 = \
   \%.81f, n = \%d, x1 = \%.81f, x2 = \%.81f, x3 = \%.81f \setminus n,
59
60
   a3, i, x01, x02, x03);
                                      exit(0);
61
62
                             }
                     }
63
64
                     a2=a3/2;
65
                    g2=pow((10*(x01-a2*z1)-2*pow((x02-)
66
                        a2*z2),2)+(x02-a2*z2)-2*(x03-a2*z3)
67
                        -5),2)+pow((8*pow((x02-a2*z2),2)+\
68
                        4*pow((x03-a2*z3),2)-9),2)+pow(
69
                        (8*(x02-a2*z2)*(x03-a2*z3)+4),2);
70
                    h1=(g2-g1)/a2;
71
                    h2=(g3-g2)/(a3-a2);
72
                     h3=(h2-h1)/a3;
                     a0 = (a2 - h1/h3)/2;
73
74
                    g0=pow((10*(x01-a0*z1)-2*pow((x02)
                        -a0*z2),2)+(x02-a0*z2)-2*(x03-a0*z3)
75
76
                        -5),2)+pow((8*pow((x02-a0*z2),2)+
                        4*pow((x03-a0*z3),2)-9),2)+pow(
77
78
                        (8*(x02-a0*z2)*(x03-a0*z3)+4),2);
79
                    min=g0;
80
                     if (g3<min) {
                             min=g3;
81
82
                     }
```

```
83
                      if(min=g0){
84
                                a=a0;
                       }
85
                       else {
86
87
                                a=a3;
88
                       }
                      x01-=a*z1;
89
                      x02-=a*z2;
90
                      x03-=a*z3;
91
                      printf("n = \%d, x1 = \%.81f, x2 = \
92
   \%.81f, x3 = \%.81f, g = \%.81f \setminus n, ++i, x01, x02, x03, min);
93
94
    }
95
```

令 $\mathbf{x} = (1, 1, 1)^{\mathbf{T}}$ ,可得:

n	$x_1^{(n)}$	$x_2^{(n)}$	$x_3^{(n)}$	$g^{(n)}$
1	0.92753552	0.49999507	0.57970600	81.62449064
2	0.67589563	0.65390087	0.63774376	69.52080786
3	0.52253096	0.89189684	-0.32133767	7.88536591
4	0.51592829	1.03474947	-0.38996809	0.65404290
5	0.53651718	1.02248306	-0.46597604	0.14174062
6	0.52198314	1.00728128	-0.46735906	0.07238155
7	0.51584441	1.01388912	-0.47501960	0.04200303

.:. 一个近似解为  $\mathbf{x} = (0.51584441, \ 1.01388912, \ -0.47501960)^{\mathbf{T}}$ .