

# **AVL Trees, Splay Trees, and Amortized Analysis**

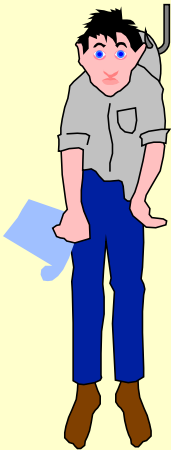
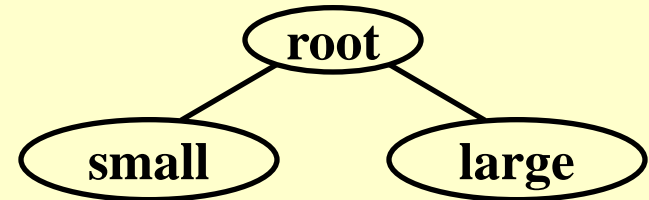
# AVL Trees



Target : **Speed up searching (with insertion and deletion)**

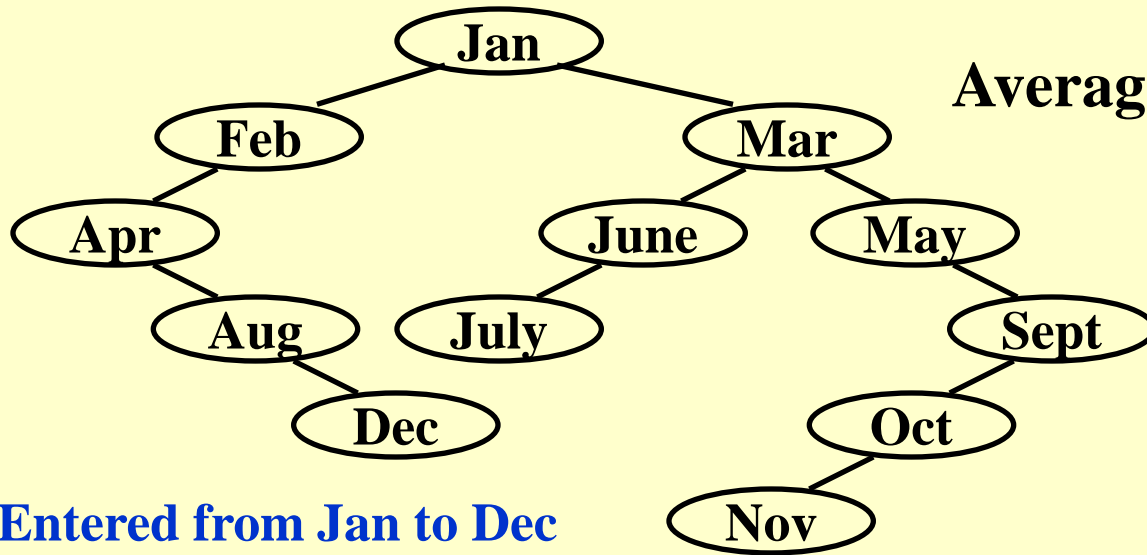


Tool : **Binary search trees**



Problem : **Although  $T_p = O(\text{height})$ , but the height can be as bad as  $O(N)$ .**

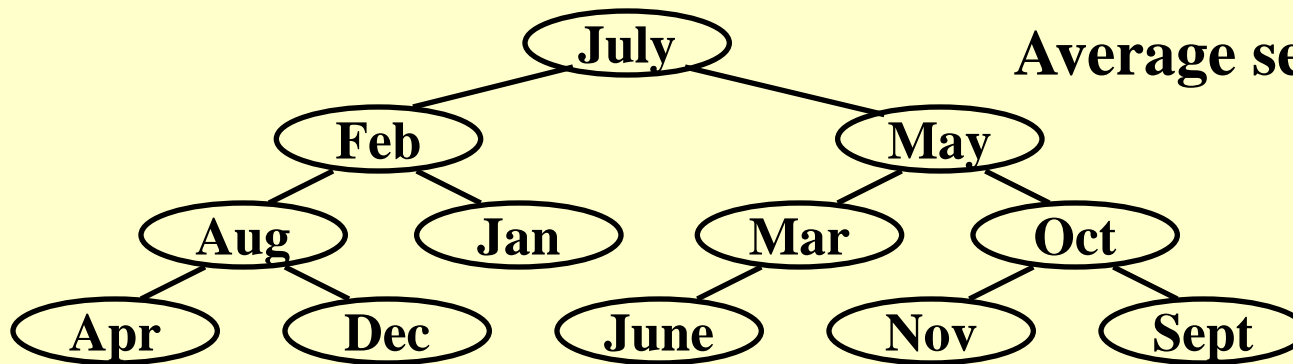
〔Example〕 2 binary search trees obtained for the months of the year



Average search time = 3.5

Average search time of the skew tree = 6.5

Entered from Jan to Dec



Average search time = 3.1

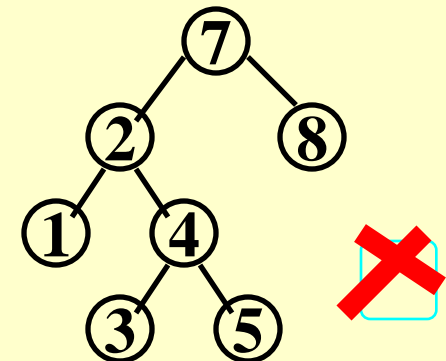
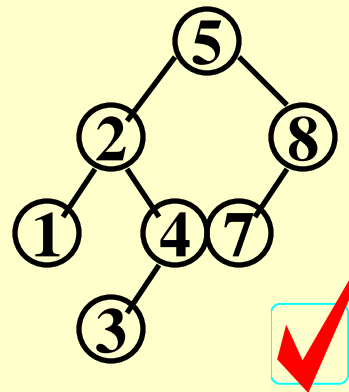
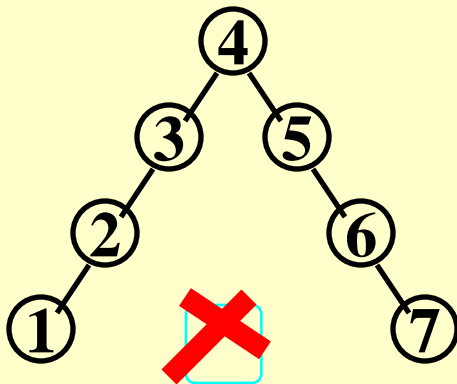
A balanced tree

# Adelson-Velskii-Landis (AVL) Trees (1962)

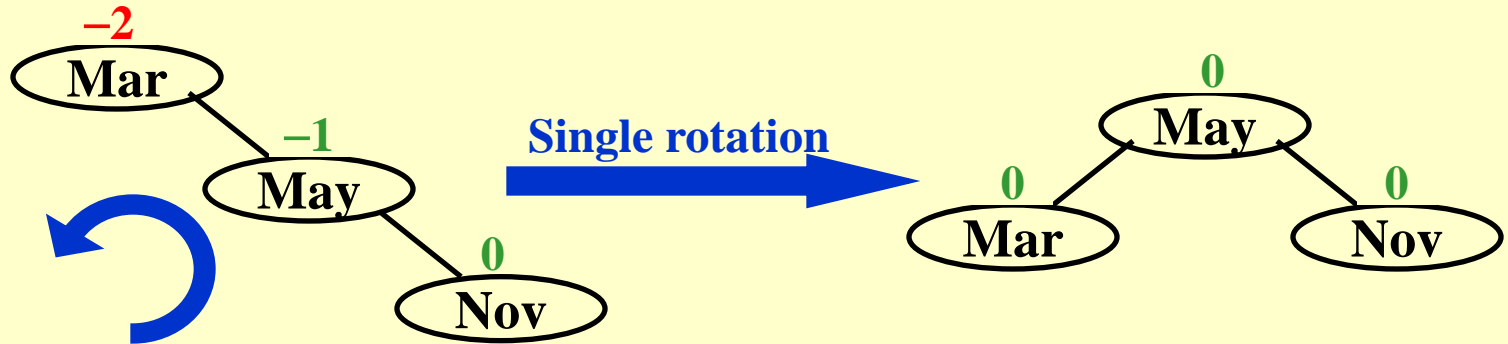
**【Definition】** An empty binary tree is height balanced. If  $T$  is a nonempty binary tree with  $T_L$  and  $T_R$  as its left and right subtrees, then  $T$  is **height balanced** iff

- (1)  $T_L$  and  $T_R$  are height balanced, and
- (2)  $|h_L - h_R| \leq 1$  where  $h_L$  and  $h_R$  are the heights of  $T_L$  and  $T_R$ , respectively.

**【Definition】** The balance factor  $BF(\text{node}) = h_L - h_R$ . In an AVL tree,  $BF(\text{node}) = -1, 0, \text{ or } 1$ .

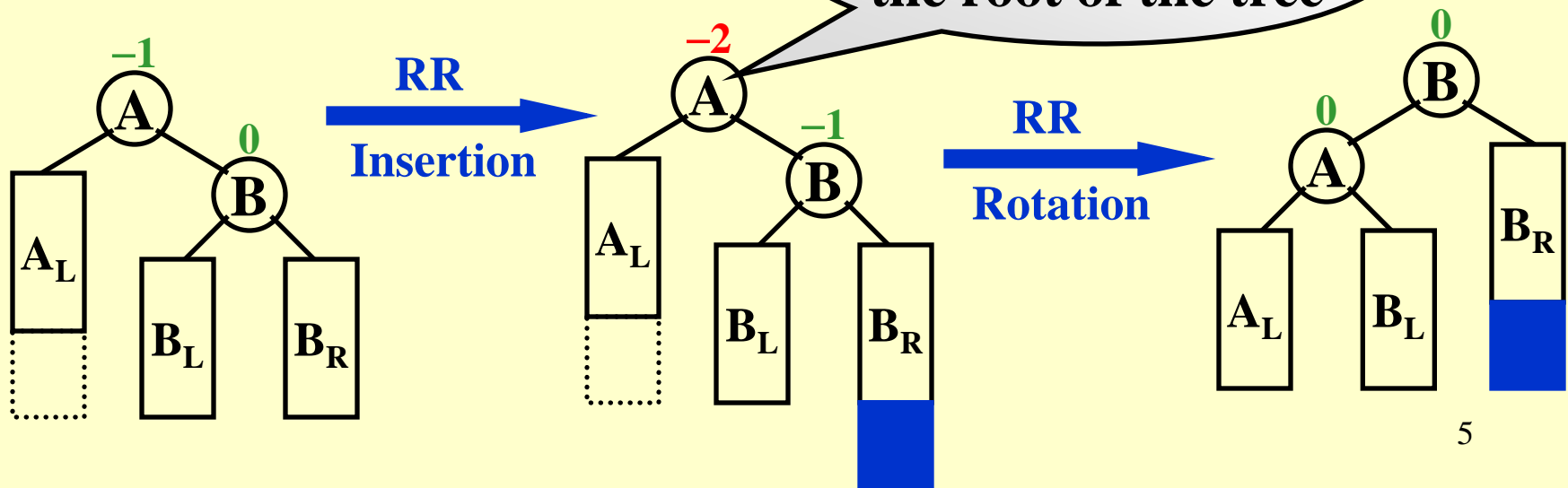


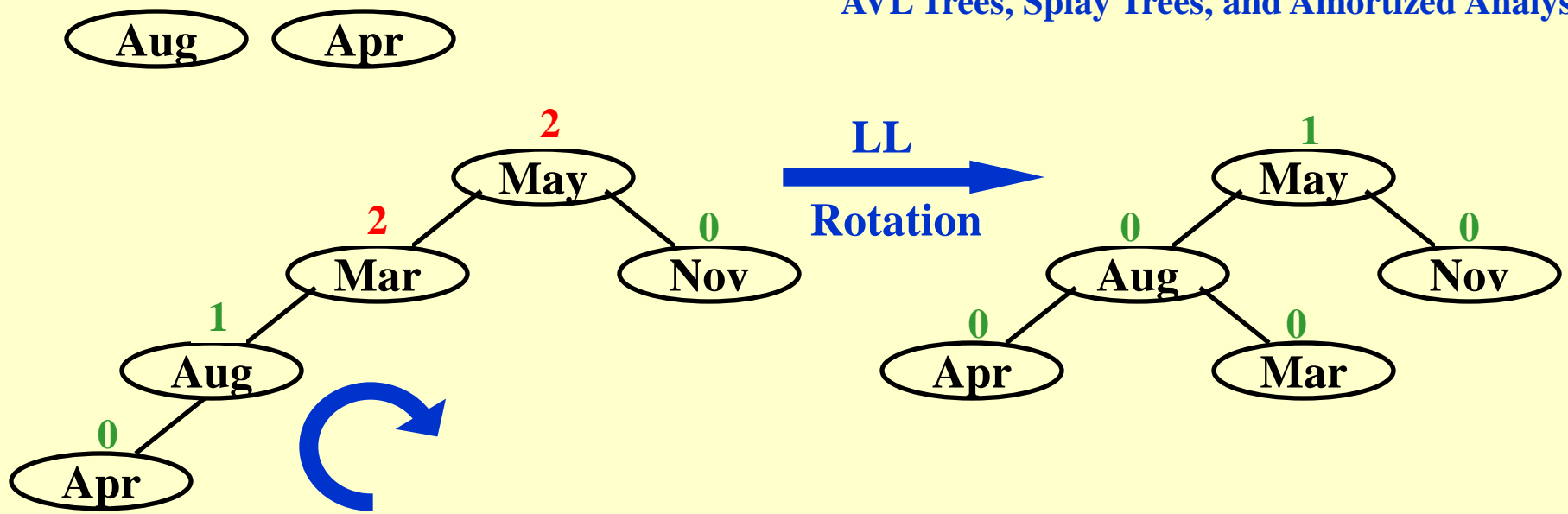
【Example】 Input the months Mar May Nov



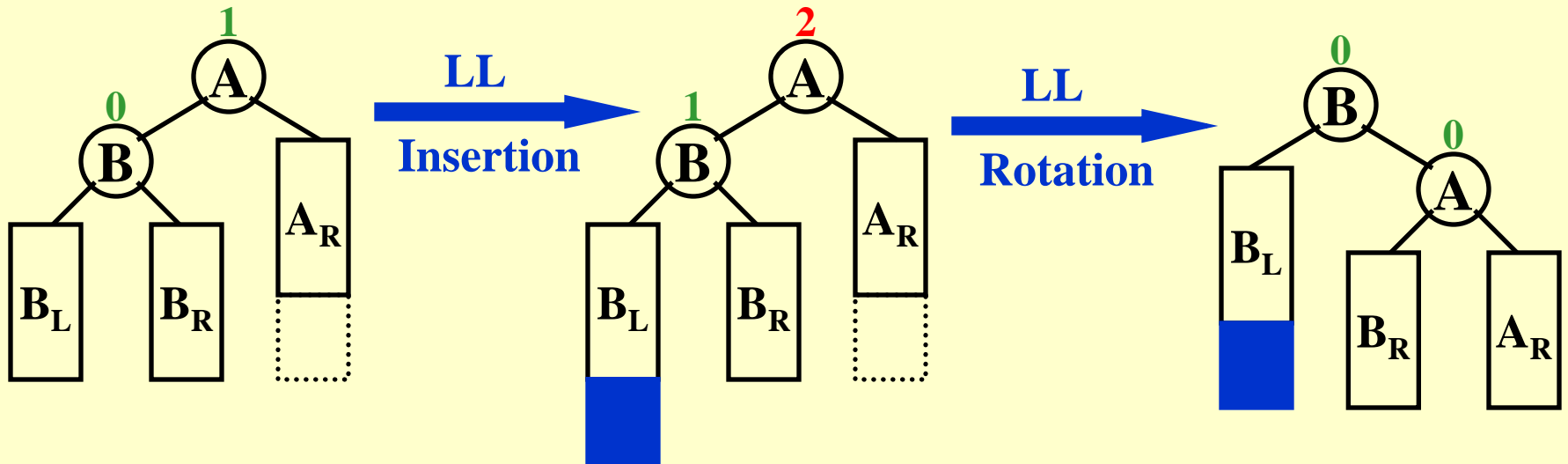
👁 The trouble maker **Nov** is in the **right** subtree's **right** subtree of the trouble finder **Mar**. Hence it is called an **RR rotation**.

In general:

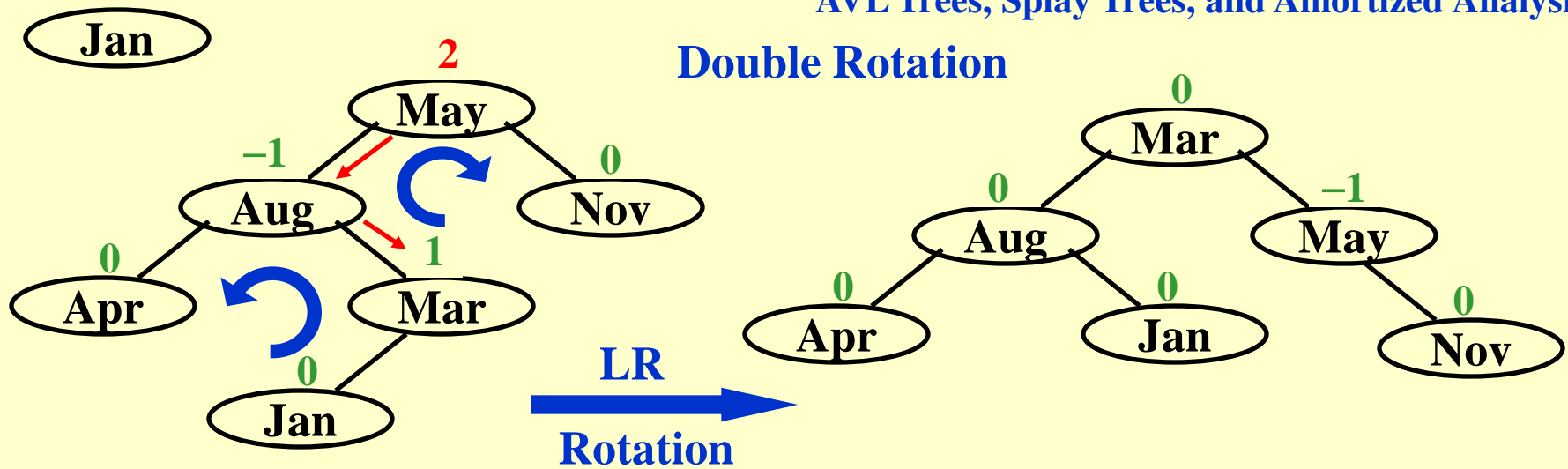




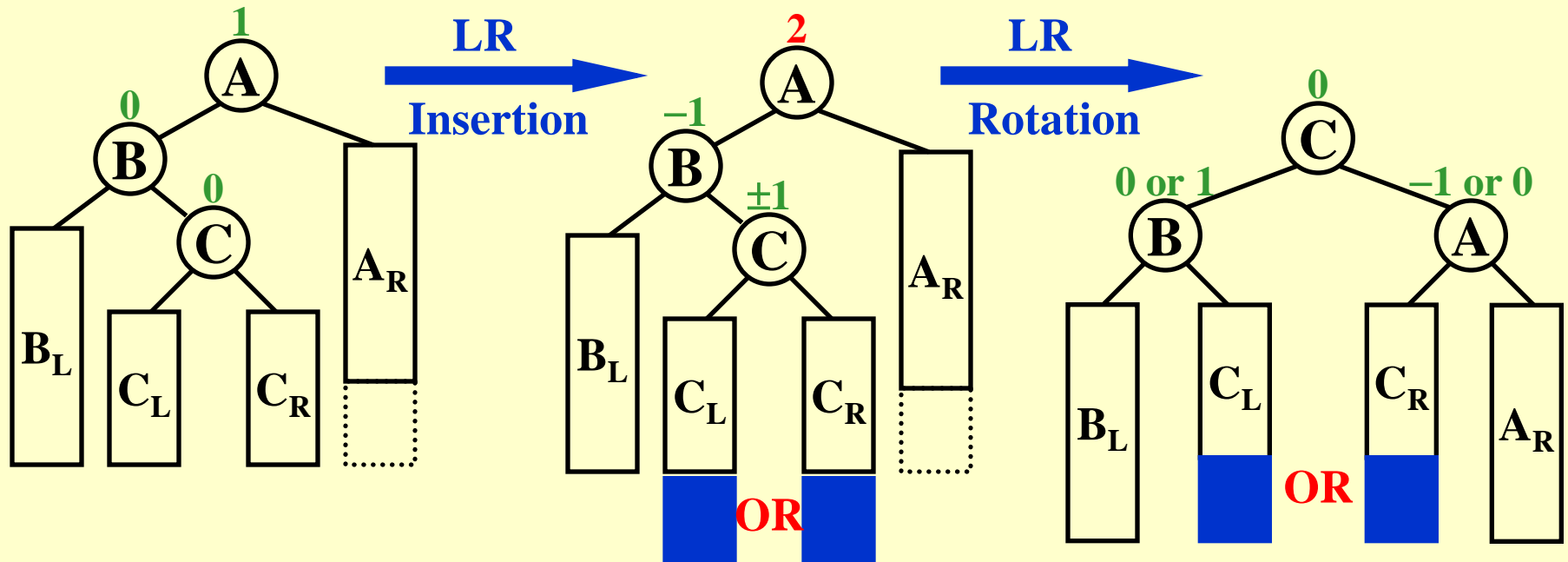
In general:

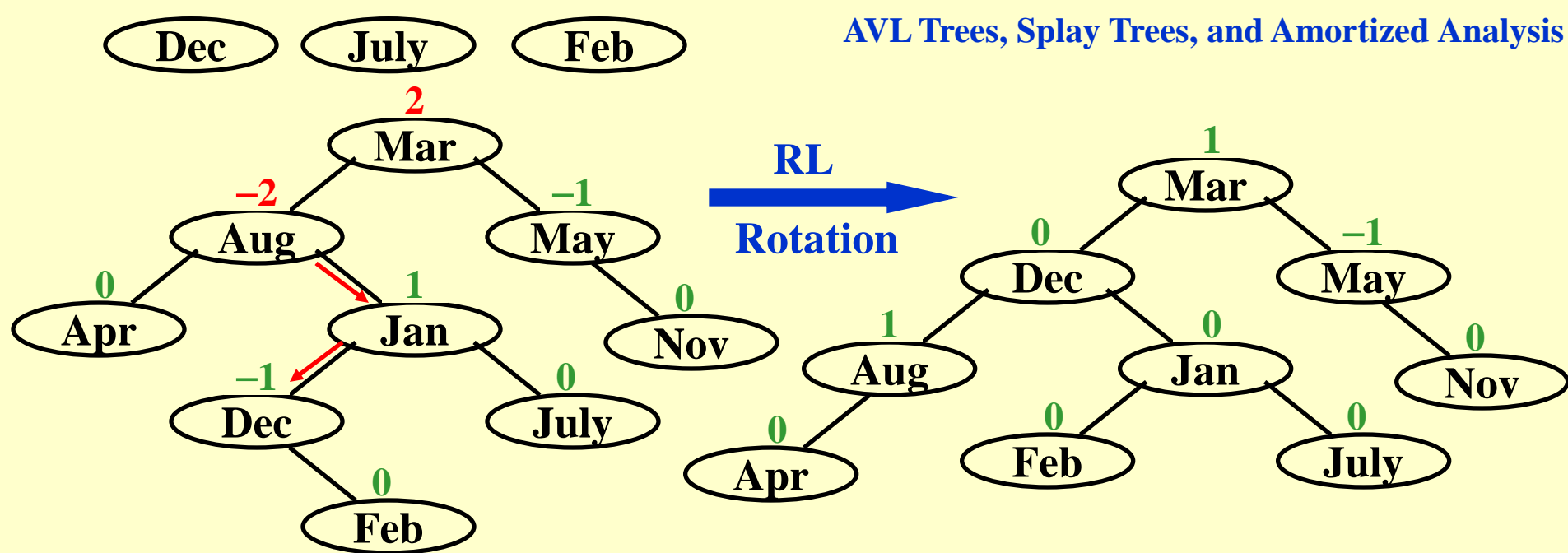


# Double Rotation

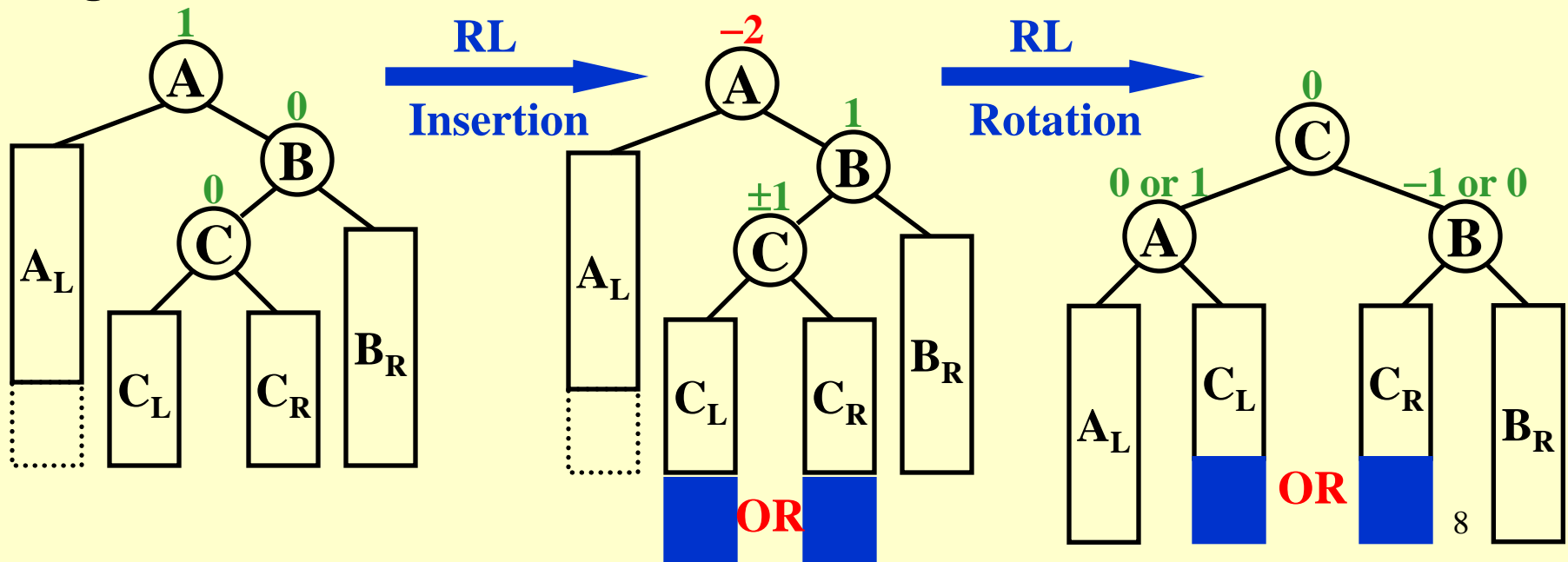


In general:



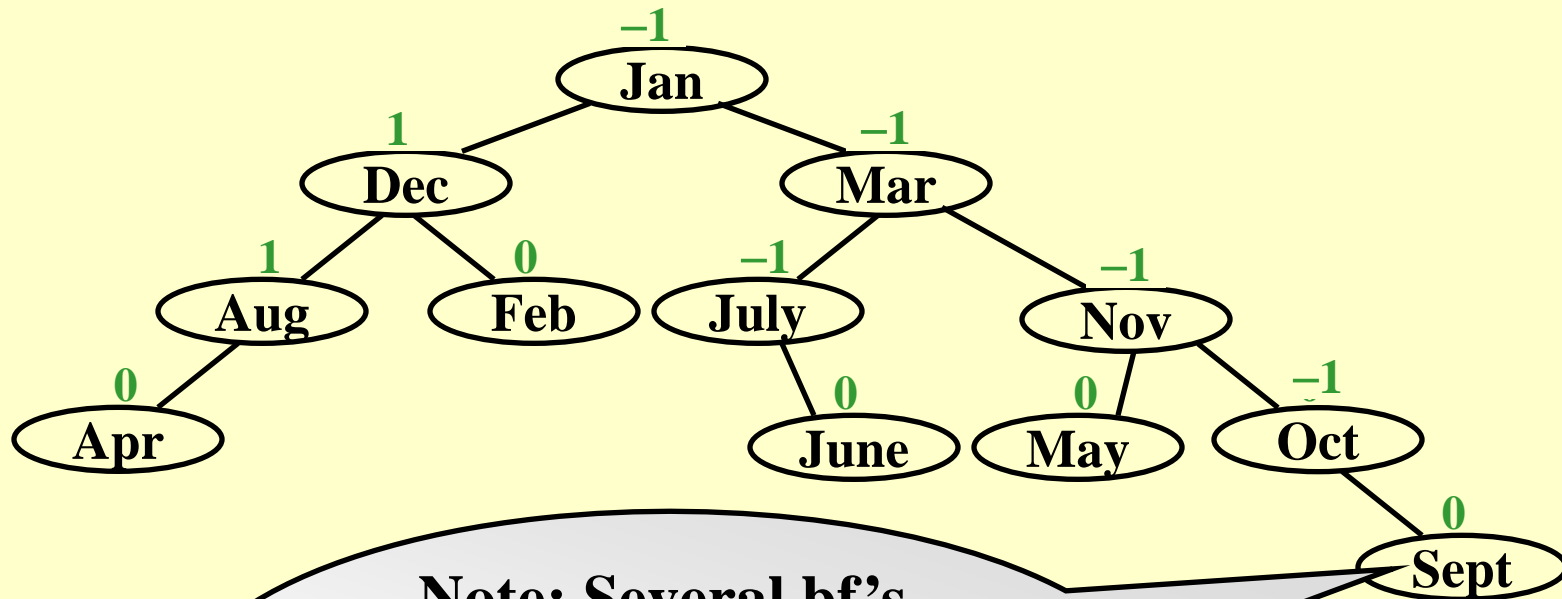


In general:





June      Oct      Sept

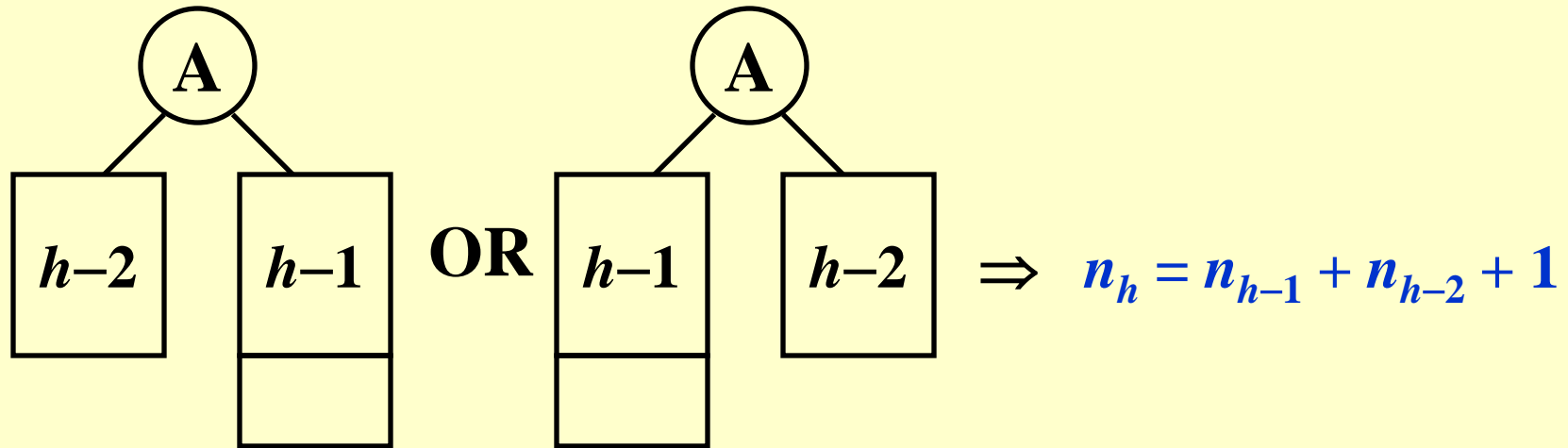


**Note: Several bf's  
might be changed even if  
we don't need to reconstruct  
the tree.**

Another option is to keep a *height* field for each node.

Read the declaration and functions in [1] Figures 4.42 – 4.48

Let  $n_h$  be the minimum number of nodes in a height balanced tree of height  $h$ . Then the tree must look like



**Fibonacci numbers:**

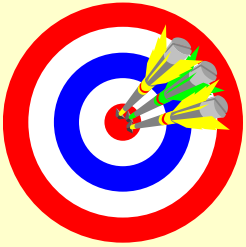
$$F_0 = 0, F_1 = 1, F_i = F_{i-1} + F_{i-2} \text{ for } i > 1$$

$$\Rightarrow n_h = F_{h+2} - 1, \text{ for } h \geq 0$$

Fibonacci number theory gives that  $F_i \approx \frac{1}{\sqrt{5}} \left( \frac{1+\sqrt{5}}{2} \right)^i$

$$\Rightarrow n_h \approx \frac{1}{\sqrt{5}} \left( \frac{1+\sqrt{5}}{2} \right)^{h+2} - 1 \quad \Rightarrow \quad h = O(\ln n)$$

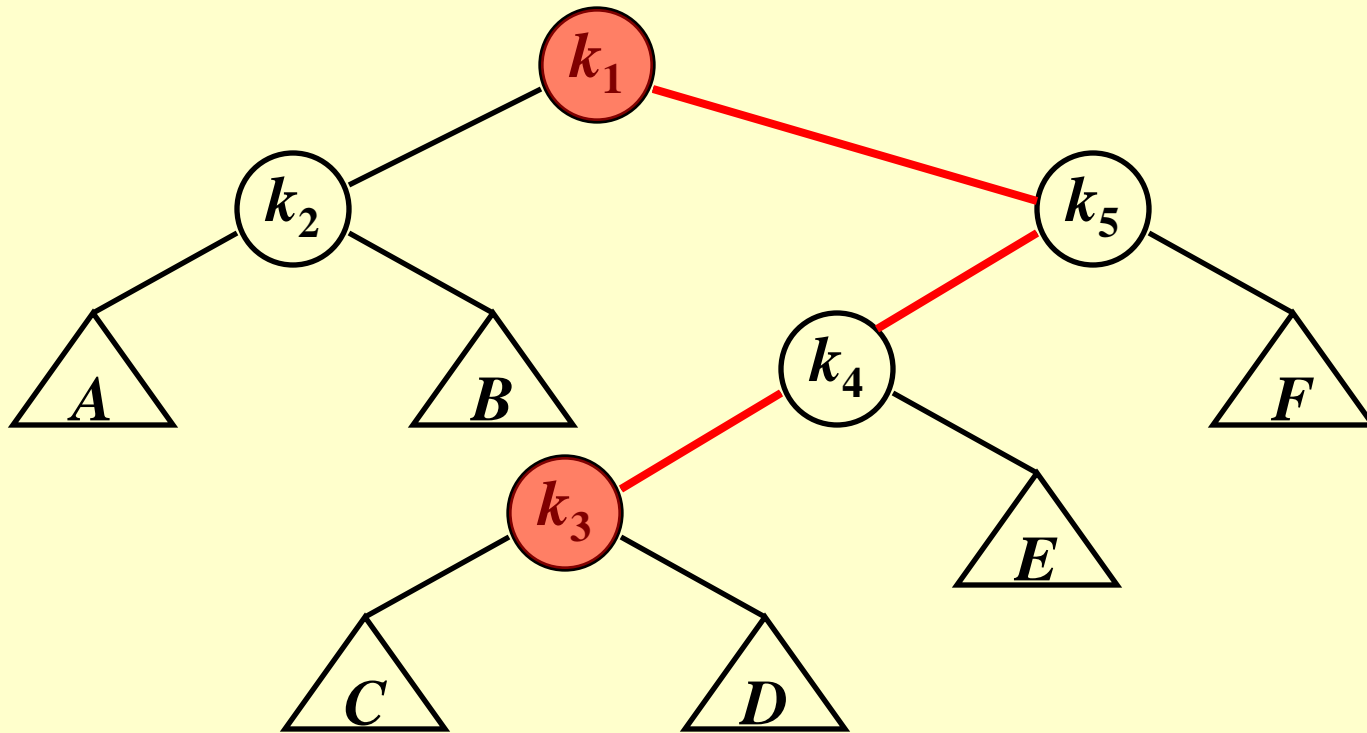
# Splay Trees



**Target :** Any  $M$  consecutive tree operations starting from an empty tree take at most  $O(M \log N)$  time.

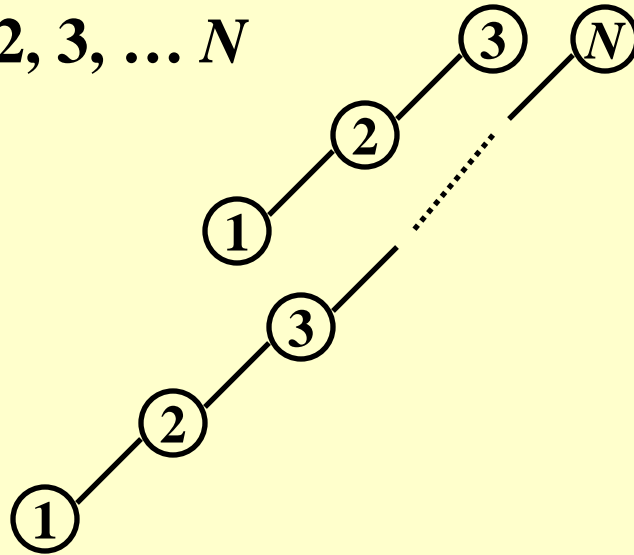
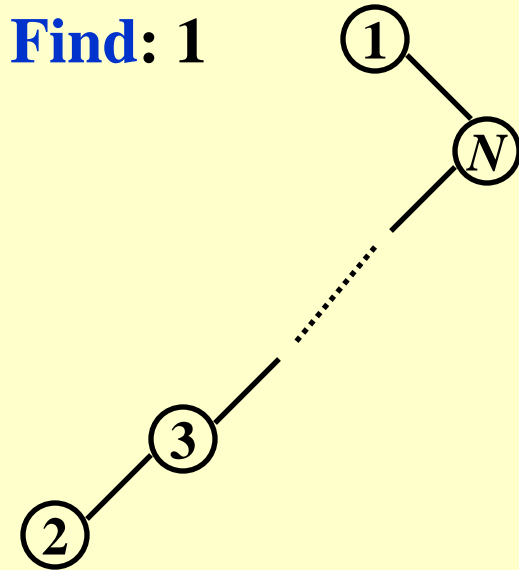
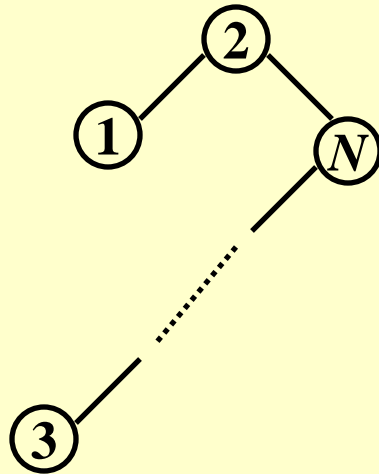
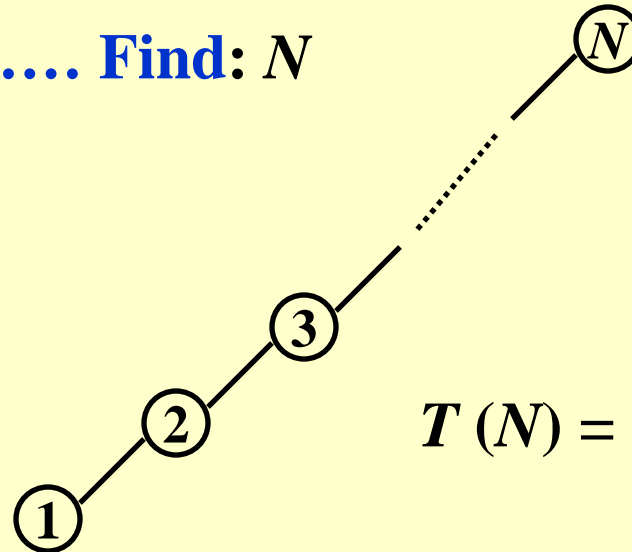


**Idea :** After a node is accessed, it is pushed to the root by a series of AVL tree rotations.



*Does NOT work!*

## An even worse case:

**Insert:** 1, 2, 3, ...  $N$ **Find:** 1**Find:** 2..... **Find:**  $N$ 

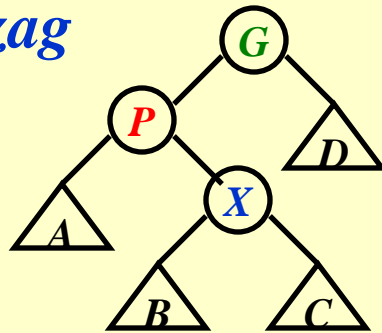
$$T(N) = O(N^2)$$

Try again -- For any nonroot node  $X$ , denote its parent by  $P$  and grandparent by  $G$  :

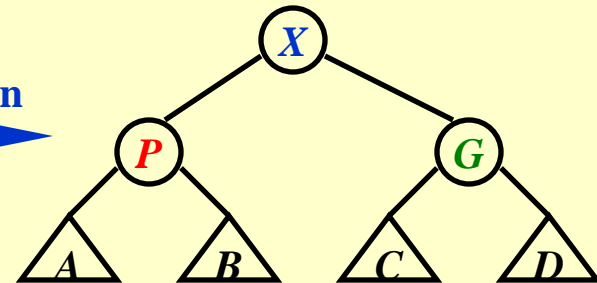
Case 1:  $P$  is the root  $\rightarrow$  Rotate  $X$  and  $P$

Case 2:  $P$  is not the root

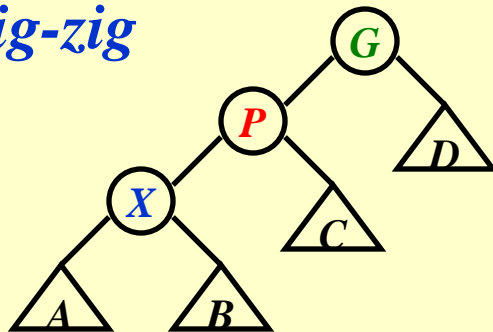
*Zig-zag*



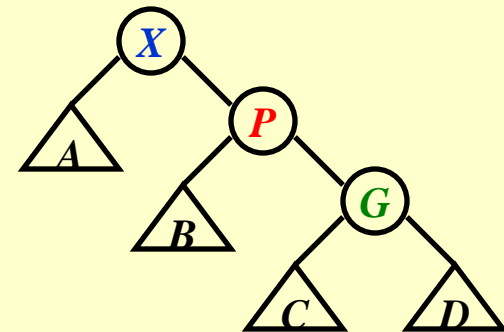
Double rotation



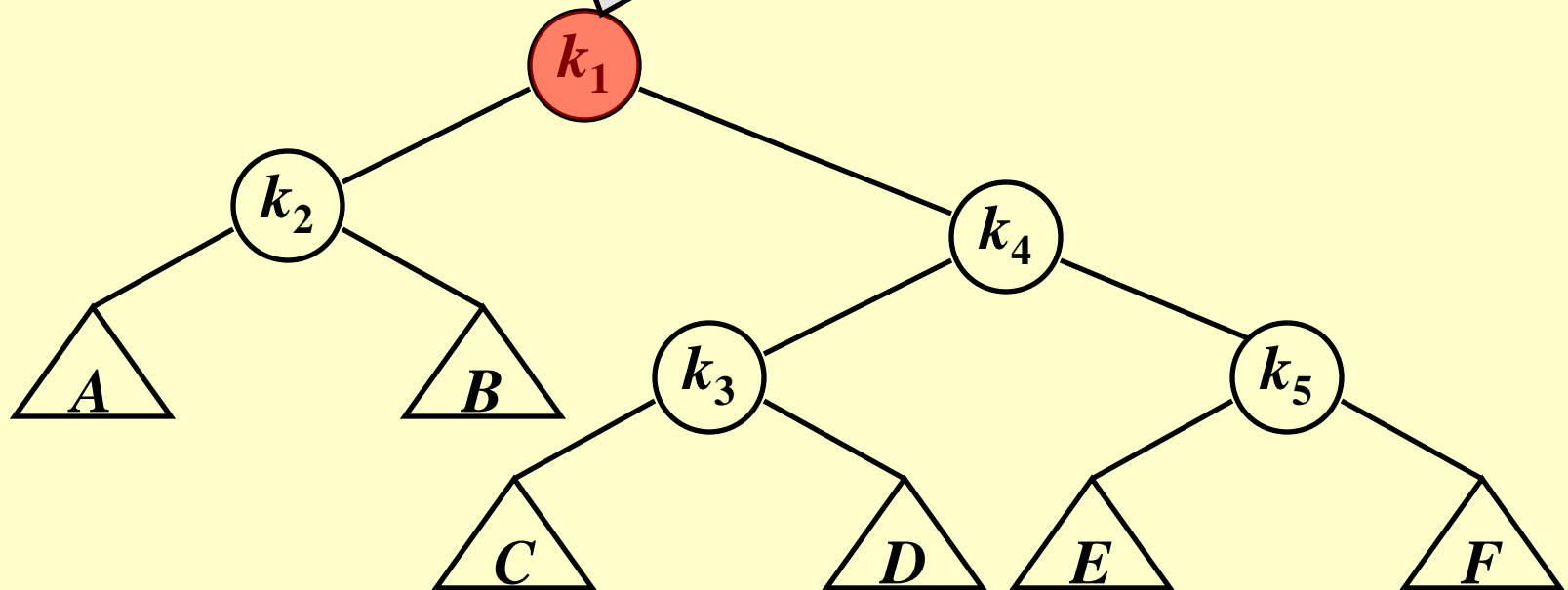
*Zig-zig*

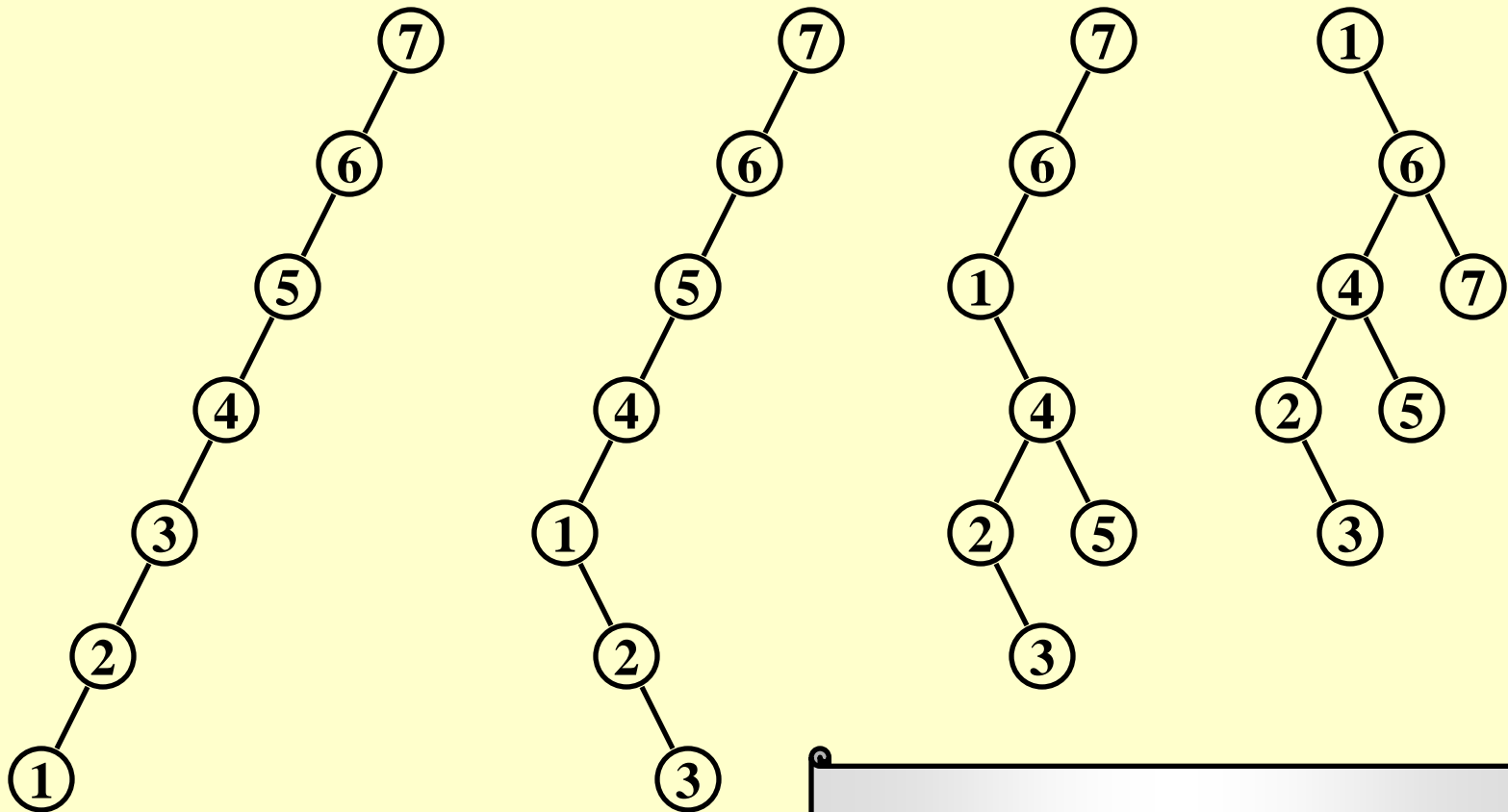


Single rotation



Splaying not only moves the accessed node to the root, but also roughly halves the depth of most nodes on the path.



**Insert: 1, 2, 3, 4, 5, 6, 7****Find: 1**

**Read the 32-node example  
given in Figures 4.52 – 4.60**



## Deletions:

☞ **Step 1:** Find  $X$  ;

$X$  will be at the root.

☞ **Step 2:** Remove  $X$  ;

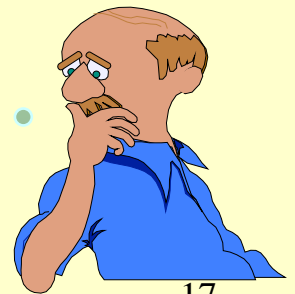
There will be two subtrees  $T_L$  and  $T_R$ .

☞ **Step 3:** FindMax (  $T_L$  ) ;

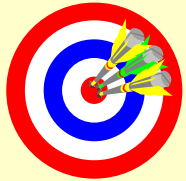
The largest element will be the root of  $T_L$ , and *has no right child*.

☞ **Step 4:** Make  $T_R$  the right child of the root of  $T_L$ .

Are splay trees really better than AVL trees?



# Amortized Analysis



Target: Any  $M$  consecutive operations take at most  $O(M \log N)$  time.

-- *Amortized* time bound

worst-case bound  $\geq$  amortized bound  $\geq$  average-case bound

Probability  
is *not* involved

👉 Aggregate analysis

👉 Accounting method

👉 Potential method

## 👉 Aggregate analysis



Idea: Show that for all  $n$ , a sequence of  $n$  operations takes *worst-case* time  $T(n)$  in total. In the worst case, the average cost, or *amortized cost*, per operation is therefore  $T(n)/n$ .

[[Example]] Stack with **MultiPop**( **int**  $k$ , Stack  $S$  )

```

Algorithm {
  while ( !IsEmpty(S) && k>0 ) {
    Pop(S);
    k - -;
  } /* end while-loop */
}
 $T = \min ( \text{sizeof}(S), k )$ 

```

Consider a sequence of  $n$  **Push**, **Pop**, and **MultiPop** operations on an initially empty stack.

$$\text{sizeof}(S) \leq n$$

$$T_{\text{amortized}} = O(n)/n = O(1)$$

## 👉 Accounting method



Idea: When an operation's *amortized cost*  $\hat{c}_i$  exceeds its *actual cost*  $c_i$ , we assign the difference to specific objects in the data structure as *credit*. Credit can help *pay* for later operations whose amortized cost is less than their actual cost.

**Note:** For all sequences of  $n$  operations, we must have

$$T_{\text{amortized}} = \frac{\sum_{i=1}^n \hat{c}_i}{n} \geq \frac{\sum_{i=1}^n c_i}{n}$$

[[Example]] Stack with **MultiPop**( **int**  $k$ , Stack  $S$  )

$c_i$  for **Push**: 1 ; **Pop**: 1 ; and **MultiPop**:  $\min ( \text{sizeof}(S), k )$

$\hat{c}_i$  for **Push**: 2 ; **Pop**: 0 ; and **MultiPop**: 0

Starting from an empty stack — *Credits* for

**Push**: +1 ; **Pop**: -1 ; and **MultiPop**: -1 for each +1

$\text{sizeof}(S) \geq 0 \Rightarrow \text{Credits} \geq 0$

$$\Rightarrow O(n) = \sum_{i=1}^n \hat{c}_i \geq \sum_{i=1}^n c_i$$

$$\Rightarrow T_{\text{amortized}} = O(n)/n = O(1)$$

## 👉 Potential method



Idea: Take a closer look at the *credit* --

$$\hat{c}_i - c_i = \text{Credit}_i = \Phi(D_i) - \Phi(D_{i-1})$$

*Potential function*

$$\begin{aligned} \sum_{i=1}^n \hat{c}_i &= \sum_{i=1}^n (c_i + \Phi(D_i) - \Phi(D_{i-1})) \\ &= \left( \sum_{i=1}^n c_i \right) + \underbrace{\Phi(D_n) - \Phi(D_0)}_{\geq 0} \end{aligned}$$

In general, a good potential function should always assume its minimum at the start of the sequence.

[[Example]] Stack with **MultiPop**( **int**  $k$ , Stack  $S$  )

$D_i =$  the stack that results after the  $i$ -th operation

$\Phi(D_i) =$  the number of objects in the stack  $D_i$

$$\Phi(D_i) \geq 0 = \Phi(D_0)$$

**Push:**  $\Phi(D_i) - \Phi(D_{i-1}) = (\text{sizeof}(S) + 1) - \text{sizeof}(S) = 1$

$$\Rightarrow \hat{c}_i = c_i + \Phi(D_i) - \Phi(D_{i-1}) = 1 + 1 = 2$$

**Pop:**  $\Phi(D_i) - \Phi(D_{i-1}) = (\text{sizeof}(S) - 1) - \text{sizeof}(S) = -1$

$$\Rightarrow \hat{c}_i = c_i + \Phi(D_i) - \Phi(D_{i-1}) = 1 - 1 = 0$$

**MultiPop:**  $\Phi(D_i) - \Phi(D_{i-1}) = (\text{sizeof}(S) - k') - \text{sizeof}(S) = -k'$

$$\Rightarrow \hat{c}_i = c_i + \Phi(D_i) - \Phi(D_{i-1}) = k' - k' = 0$$

$$\sum_{i=1}^n \hat{c}_i = \sum_{i=1}^n O(1) = O(n) \geq \sum_{i=1}^n c_i \Rightarrow T_{\text{amortized}} = O(n)/n = O(1)$$

[[Example]] Splay Trees:  $T_{amortized} = O(\log N)$

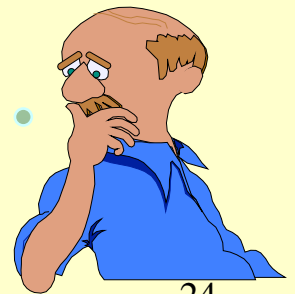
$D_i =$  the root of the resulting tree

$\Phi(D_i) =$  must increase by at most  $O(\log N)$  over  $n$  steps, AND will also cancel out the number of rotations (zig:1; zig-zag:2; zig-zig:2).

$\Phi(T) = \sum_{i \in T} \log S(i)$  where  $S(i)$  is the number of descendants of  $i$  ( $i$  included).

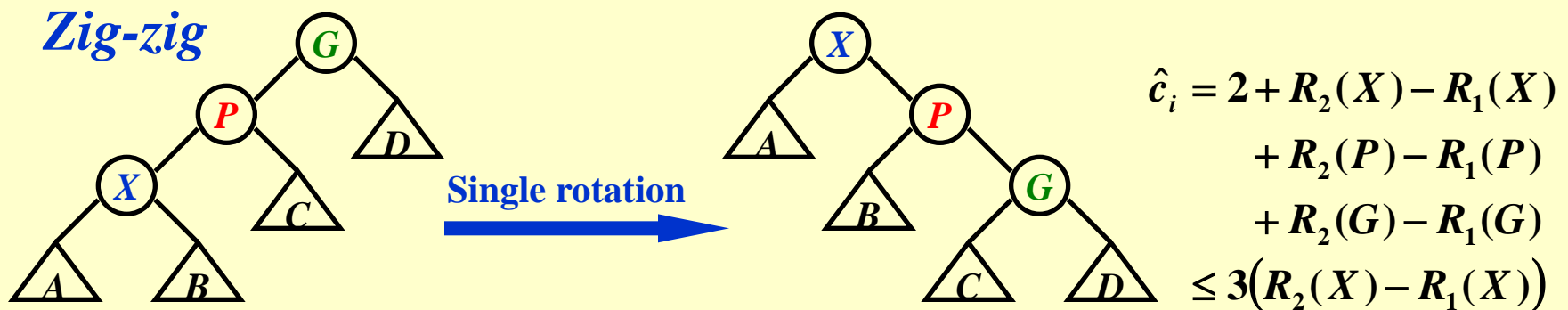
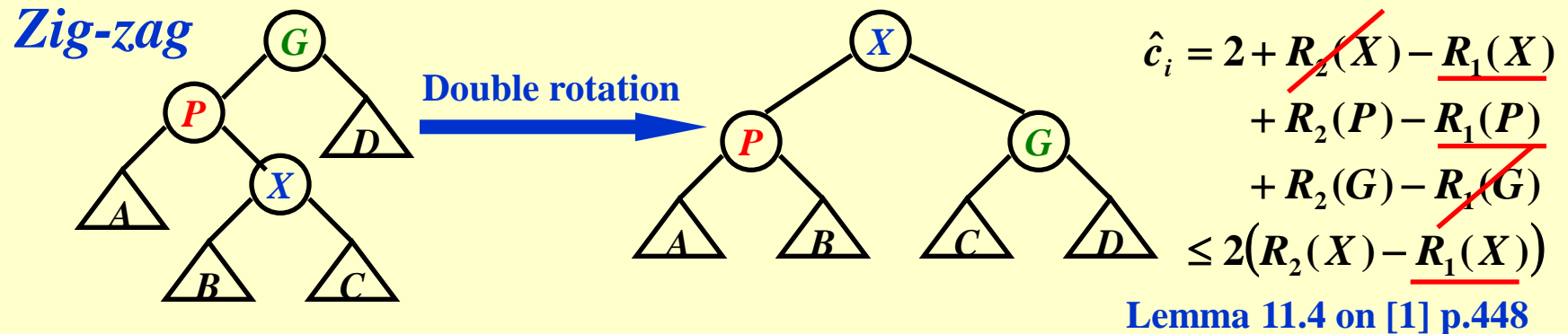
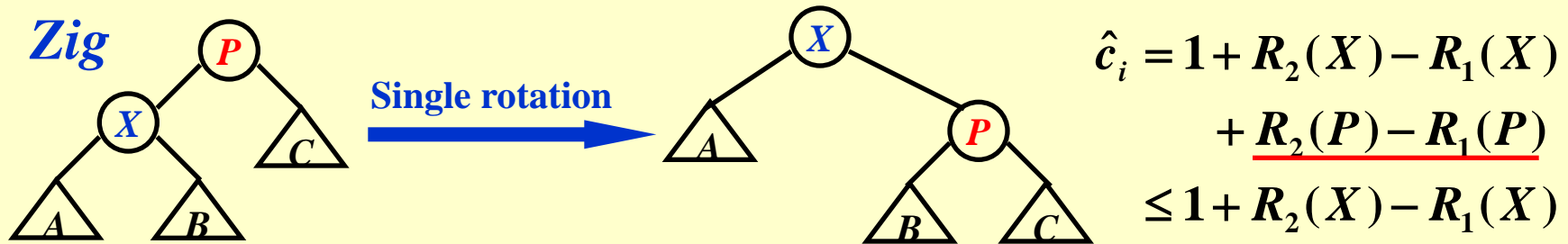
*Rank of the subtree  
 $\approx$  Height of the tree*

Why not simply use the heights  
of the trees?





$$\Phi(T) = \sum_{i \in T} \text{Rank}(i)$$



**【Theorem】** The amortized time to splay a tree with root  $T$  at node  $X$  is at most  $3(R(T) - R(X)) + 1 = O(\log N)$ .

## Reference:

**Data Structure and Algorithm Analysis in C (2<sup>nd</sup> Edition):**  
**Ch.4, p.106-128; Ch.11, p.447-451;** *M.A.Weiss 著、*  
*陈越改编, 人民邮电出版社, 2005*

**Introduction to Algorithms, 3rd Edition: Ch.17, p.**  
**451-478;** *Thomas H. Cormen, Charles E. Leiserson,*  
*Ronald L. Rivest and Clifford Stein. The MIT Press. 2009*