

First Annual Progression Report

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1 Introduction

This Annual Progress Report, the first of our PhD programme, serves to detail the work we have done in the first year of our research. We first outline the research title we have worked under and outline the structure of the discussion to follow.

1.1 Thesis Statement

Our working research title is *game-theoretic and probabilistic methods applied to spatial network models of contagion*. Over the past year, we have spent a large portion of time reading and developing ideas related to graph models of contagion, such as FIREFIGHTER and similar games on graphs that are already used to model contagion (or could fit in such a context easily). We have also explored game theory to understand optimal strategies and probabilistic methods in order to adapt the games we have studied to stochastic contexts. Such a broad approach has meant that we have a wide range of tools available to us in understanding and developing models of disease and other contagions.

1.2 Report Roadmap

Our research over the past year has focused into two main strands: a formal, mathematical approach and an experimental approach. Our motivation for this two-pronged *modus operandi* is to ultimately develop a model for disease spread formally, using dynamical system and graph theoretic approaches, which we then use an experimental implementation to algorithmically explore different approaches to the model, for instance in examining candidates for theoretically optimal public health strategies in the context of a disease. To explain this work in detail, we will begin this report by discussing the literature examined in the past year, with particular focus on any papers that have proved foundational to our own work. This literature review section will provide background to our research so far, which is discussed in the section that follows it. We will then outline the direction we hope to take this initial work moving forward and detail milestones we hope to reach in the coming year.

2 Literature Review

We begin by discussing The Firefighter Problem and explain how it can be adapted to a rudimentary model of disease; we then discuss Percolation Theory and its use in a graph-theoretic context; we end by discussing compartmental graph models of disease, in particular examining the differential equations required to describe such models exactly.

2.1 The Firefighter Problem

The Firefighter Problem, which we refer to as simply FIREFIGHTER, was first introduced by Hartnell [5] and models an outbreak of fire with a firefighter strategically blocking its path. FIREFIGHTER has been the primary foundation for our approaches to modelling over the last year.

We formalise FIREFIGHTER as follows: at $t = 0$, a fire breaks out at some vertex v_0 of graph G . The firefighter then ‘protects’ another vertex¹ of G . A protected vertex is protected for the remainder of the game; it is inflammable *ad infinitum*. Similarly, a vertex that has been on fire is ‘burnt’ for the rest of the game and cannot ignite again. The fire spreads to any immediate

¹This has been extended to n vertices in some research, but here we wish to illustrate for simplicity the original single-vertex outbreak form of the problem.

neighbouring vertices that are neither protected nor burnt. Then, the firefighter may protect another vertex, the fire spreads again and so on.

Common questions to ask in FIREFIGHTER include: how do we minimise the number of vertices that will be burnt? In a given class of trees, what is the average number of burnt vertices? Is the problem NP-complete?

If we let each vertex be an individual and let the edges between them represent social contact. This is a simple model for disease infection, which is where our interest in the game enters. There are many natural contextualisations of FIREFIGHTER beyond modelling disease spread, which we may choose to apply our work to in future - for instance, we may think of edges representing virtual contact between individuals on social media, yielding a model for the spread of viral internet memes [9].

2.2 Percolation Theory

Widely known and used in physics, statistics and mathematics, Percolation theory involves modelling scenarios as n -dimensional graphs, so application to FIREFIGHTER is not entirely unexpected. Hence, we will now examine percolation theory in order to later explain the utility we have found it may yield in extending and expanding modelling work from FIREFIGHTER.

In percolation, the edges between vertices in the graph can be either ‘open’ or ‘closed’ with probability p and $1 - p$ respectively. We can think of percolation problems as liquid being poured onto a porous material and whether there is a path from hole to hole along open paths through the material. Note that removing more and more edges moves us towards a critical point at which removing further edges would cause the graph to fall apart into smaller clusters of vertices and edges that have no access to each other [3]. This is known as ‘bond’ percolation, as edges correspond to bonds in many of its applications.

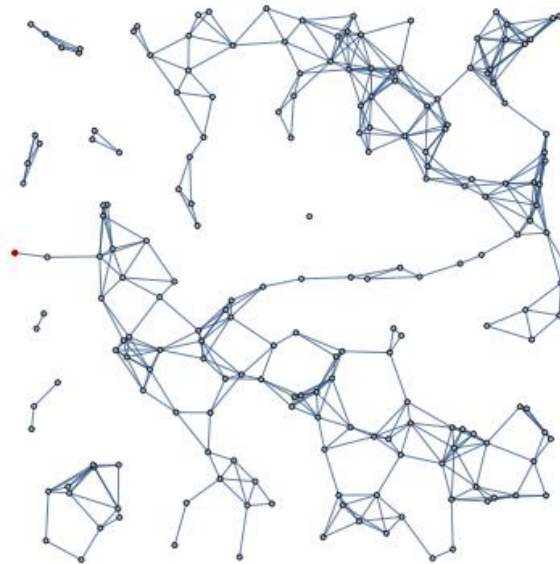


Figure 1: A graph that has been subject to percolation.

Several authors have suggested percolation as a possible approach to FIREFIGHTER [2]. In this context, we could determine the critical point to see how we might contain the fire to a smaller cluster that cannot spread to the wider graph. For FIREFIGHTER, site percolation is more applicable: rather than considering open or closed *edges* (‘bonds’) between vertices as in bond percolation, we consider each *vertex* (‘site’) as being ‘occupied’ or ‘unoccupied’ with probability p and $1 - p$ respectively.

Formally, we consider a point lattice \mathbb{L} and denote the open cluster as $C(x)$, where $x \in \mathbb{L}$ is the local origin of the cluster. This cluster $C(x)$ is defined as the set of all vertices that can be reached from open paths beginning at the nucleation site, x . Then, we are particularly interested in the *percolation probability*:

$$\theta(p) = \mathbb{P}_p(|C(0)| = \infty),$$

and the *critical probability* (or *percolation threshold*):

$$p_c = \sup\{p \mid \theta(p) = 0\}.$$

Here, \mathbb{P}_p is the product measure given by:

$$\mathbb{P}_p = \prod_{v \in \mathbb{L}^d} \mu_v$$

where μ_v is the *Bernoulli measure*, which returns p when v is open and $1 - p$ when v is closed [8, p. 28]. Analytically, others have shown that in the case of a two-dimensional regular point lattice, the critical probability is $p_c = 1/2$ [6].

2.3 Markovian SIR epidemics on networks

In the past year, we have also spent significant time understanding, applying and expanding results around equations describing Markovian *SIR* graph models of disease exactly [7] so we will now provide a review of the key work in this area and its utility. We will go on to detail the work done so far in extending the results from this paper in the following section.

In [7], the authors note that there are generally three approaches to compartmental models of disease. We can:

1. Take averages at population level,
2. Maintain a probabilistic view by considering the full state space, or
3. Begin modelling at the level of vertices and build up to larger structures from there.

The second of the three approaches has been the focus of much of our work, as will be seen in the following section. The latter of these three approaches is the one used in the work on Markovian *SIR* graph epidemics being discussed currently: begin by considering equations for single vertices, then consider dependencies on pairs, then triples and so on until we reach the full system size. Such equations are well defined and consistent, which is not difficult to see.

The work presented has two aims. Firstly, to provide an exact, deterministic representations of Markovian *SIR* epidemics on graphs with and without loops. Secondly, to identify a link between the structural properties of the graphs and the viability of closures that can be used to write down exact systems of equations that can be numerically evaluated. In particular, the authors show this structural link is founded on cut-vertices and bridges. Cut-vertices are vertices that, if removed from a connected graph, result in the formation of two (or more) disconnected sub-graphs. Bridges are edges that lie between two cut-vertices.

The authors spend significant time expanding intuitions on the identification of closures, which allow us to approximate or even exactly specify higher-order moments in terms of lower-order moments. They claim this is well known to be feasible for tree-like graphs and for graphs with loops starting from some specific initial conditions. They present some examples to develop the intuition that “loops cannot be closed by breaking them down to their component parts.”

The main result of the work reveals an important relation between structure of the graph used in the epidemic model and types of closures that are feasible using cut-vertices and bridges.

They also prove an impressively general result: if a graph with N vertices and E edges has T triangles and no larger loops than size 3 (meaning also that triangles cannot have overlapping edges), an upper bound on the size of the system of equations describing the system dynamics can be calculated:

$$2N + 3E + 7T \leq 10N$$

The authors also provide a “recipe-like” approach to establish the feasibility of writing down an exact representation for a given graph even more generally. They use this to provide an upper bound for the number of equations required to describe epidemic dynamics exactly:

$$N_{EQ}(G) = \sum_{i=1}^P m_i f_i - 2 \sum_{j=1}^L (\text{Ind}(v_{i_j}) - 1).$$

where P is the number of distinct sub-graphs produced when the original graph is spliced into independent sub-graphs through cut-vertices, m_i represents the number of equations required to describe the corresponding sub-graph i , f_i is the frequency or count of the sub-graph G_i and $\text{Ind}(v_{i_j})$ is the number of sub-graphs to which the cut-vertex v_{i_j} belongs.

This takes a sum across the number of equations for all sub-graphs and adjusts to account for unnecessary multiplications caused by cut-vertices being part of multiple sub-graphs, which is a move made in illustrative examples throughout the work.

3 Work done so far

3.1 Uses of Percolation in The Firefighter Problem

We have identified three main avenues that may be pursued in FIREFIGHTER using Percolation:

- the firefighter may use percolation in order to defend the graph,
- the fire might spread with percolation probability p or
- we might use percolation on the graph to form a more useful model (i.e. one that can more accurately represent an irregular population density).

The first of these options might be used when the firefighter can save more than one vertex at each turn, or (as will be seen further on in this section) defence is a stochastic process; the third of the three options may be more useful when modelling disease spread.

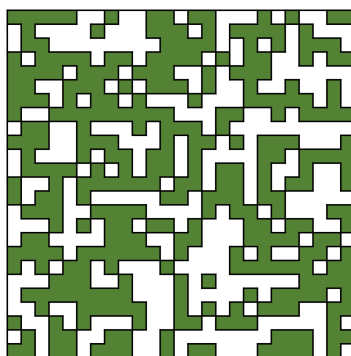


Figure 2: A regular (25×25) graph, percolated with probability $p = 2/3$.

3.1.1 Better than random

One potential use for the firefighter using percolation as a method of defence would be as a baseline test: in most scenarios, a method for obtaining defence strategies should be at least as effective as a random defence sequence. We could find such a random sequence using percolation for comparison purposes. Consider a sequence of vertices in graph G , written as d_1, d_2, \dots, d_t . An optimal defence sequence could be found using integer programming as provided by Finbow and MacGillivray [2]:

$$\begin{aligned} & \text{Maximise} && \sum_{v \in V(G)} d_v w(v) && \text{for each level } i \\ & \text{subject to} && d_v + \sum_{\text{level}(v)=i} d_v \leq 1 && \text{for each level } i \\ & && d_v + \sum_{\substack{u \succ v \\ u \in T}} d_u \leq 1 && \text{for every outer vertex } v \text{ of } T, \\ & && d_v \in \{0, 1\}. \end{aligned}$$

where $u \succ v$ indicates that u is an ancestor of v . The optimal strategies provided for different classes and densities of graphs here will provide an upper bound (which may indeed be impossible to attain in some cases) for success of a given strategy. We can find a lower bound using percolation, and so we have a range of success values as a starting point: if some strategy is better than random percolation, then it is worth considering, but below the particular expected optimal solution from integer programming and we can, in principle, improve or find a better strategy.

We conjecture that, at the lowest graph densities, the random strategy will be very close to the optimal strategy and thus finding an improvement is at once difficult and lacking in great utility. At the very highest graph densities, while random strategies will have a very low expected best-case scenario, as will most strategies as the constraint on the firefighter that they have only one vertex to save per turn does not go as far when vertices are much better connected. Thus, finding improvements on random will again not prove very useful as random and best-case scenarios serve to show us that there is a small range of possible, not good outcomes.

3.1.2 Reproduction rate

We now focus our attention on the fire spread being determined by percolation (rather than the firefighter's defence sequence). Diseases, when there is a large enough sample size, have a basic reproduction rate associated with them, denoted R_0 : for instance, measles has a basic reproduction rate $12 \leq R_0 \leq 18$ [4] and the Influenza strain responsible for the 1918 pandemic has a basic reproduction rate of $1.4 \leq R_0 \leq 2.8$ [1]. These baseline, theoretical values can be implemented as an internal probability to a propagating fire: to formulate a stochastic version of FIREFIGHTER, we let the fire propagate with some probability (which could be determined by reproduction rate of a real infectious disease) in a percolation-like process and examine the change to optimal defence.

Where we wish to consider vertices as individuals and edges as the connections between them, percolation may give us a more useful model for disease spread when we do not assume the population is well mixed and instead introduce probability functions to correspond to the likelihood one vertex is connected to another.

3.1.3 Irregular population density

A great deal of the literature surrounding FIREFIGHTER assumes a regular graph - that is, in the context of disease we assume a well-mixed population where everyone has equal probability

of coming into contact with their neighbours. Of course, this is a significant simplification of reality: some individuals are very well connected and have lots of contact with others, whereas some people have significantly less contact with others. In the context of a forest fire, the density of a forest is irregular and there is a probability in the unit interval that fire can spread between two trees depending on their proximity (among other factors): an example of this can be seen in figure 2. Thus, percolation on regular grids to more closely resemble populations or forest density could lead to far more useful and realistic modelling results.

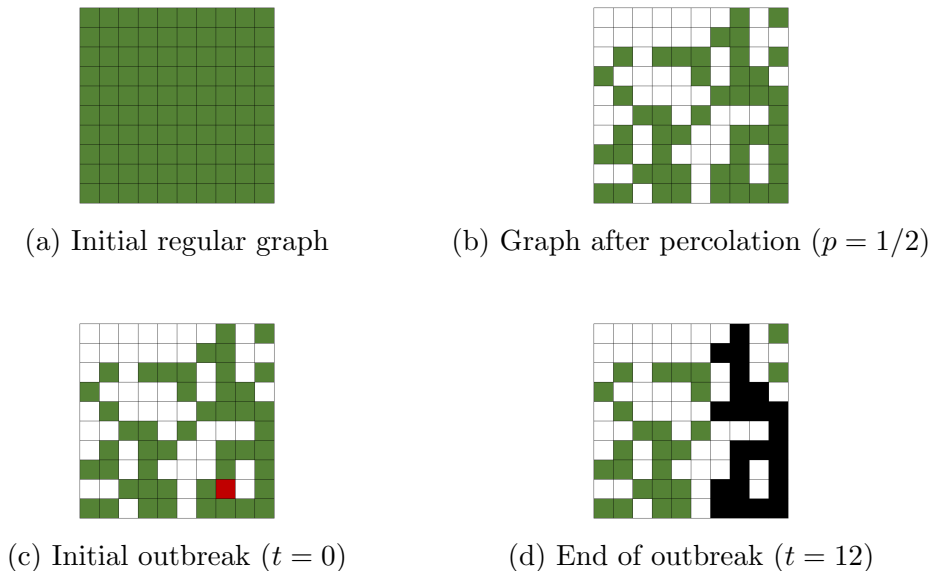


Figure 3: Outbreak of fire on a percolated graph

To illustrate this idea, we will consider a similar (perhaps precursor) to FIREFIGHTER, called The Firebreak Problem or simply FIREBREAK. Rather than have a firefighter reactively combatting the fire on each turn, we begin with an allocated amount of funding with which to mitigate the expected damage of the fire, and spend all of that before the fire begins. Generally, this means we have a number of edges to remove (trees to cut down or place a barrier in between) before the fire begins. Figure 3 depicts the use of percolation on a graph to model a forest fire. We can see that the model would have little utility if we began the outbreak on the graph in 3a (all of the graph would be burnt), but percolation has made this a more instructive and realistic model in figure 3b. We can see where the fire has spread in 3d, and we can see where - if we had a finite amount of resources - we must focus our efforts and funding in introducing a firebreak.

If, for instance, we could only remove two vertices as a firebreak, we ought to make those three the ones shown in yellow in figure 4. This is an example of how percolating a graph for use in FIREFIGHTER (and indeed FIREBREAK) can assist in generating a more realistic and useful model for contagion. There is much interest in the regular graph examples, but our modelling contexts of interest call for a more sporadic graph density and so we, in future research, will try and prove conjectures regarding the minimum number of vertex defences required in FIREBREAK for percolated graphs of given percolation threshold and dimension (or infinite graphs) and analogous questions in FIREFIGHTER.

3.2 Agency-oriented modelling

One of the key deficiencies in existing approaches to compartmental models of disease, as described in Section 2, is the lack of agency in individuals. To address this, we have designed and implemented (in Java) a compartmental graph model of infectious disease.

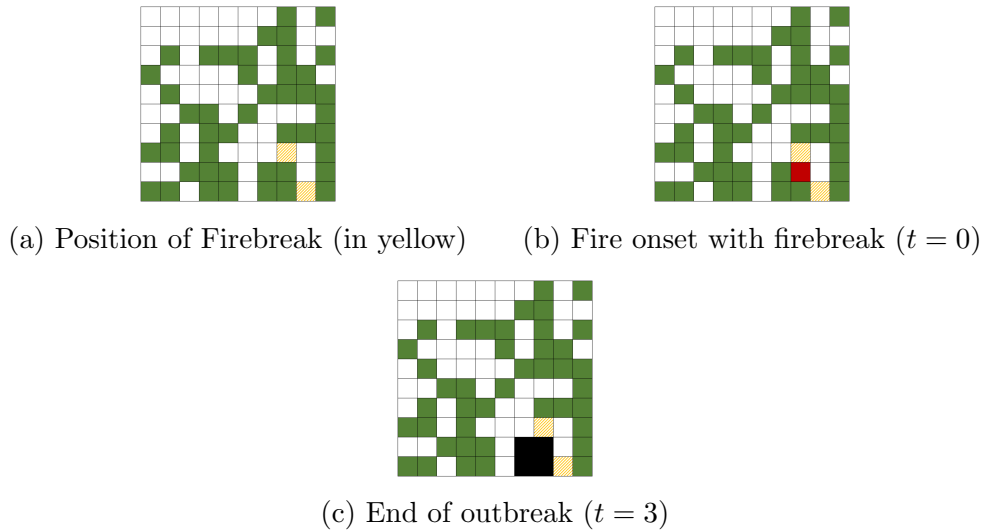


Figure 4: Outbreak of fire on a defended percolated graph

In our implemented model, we begin with a graph. This graph has a particular number of vertices and edges and can be generated using code we have written for several random graph types, for instance Erdős Rényi Barabási–Albert-generated preferential attachment graphs.

We then assign an agent to each vertex, meaning there is a particular set of agency-related characteristics for each vertex. These characteristics correspond to proximity to infection, their current (compartmental) state and intrinsic inclination towards protection. Agents can be in a number of states, which at the moment are ‘susceptible’ (could contract), ‘infected’ (currently has the infection and is infectious), ‘recovered’ (previously had the infection, may now have some degree of immunity in certain contexts) and ‘protected’ (cannot contract the infection). The final protection-related agent attribute is a novel introduction to the field that we have taken a large amount of time to vary, study and reassess: we term this the ‘protection rating’ of the given vertex. For context, in some infection scenarios this may correspond to how strict the person is with mitigating behaviours to avoid contracting a disease such as hand hygiene, personal protective equipment usage and so on. We can assign this rating purely randomly, based upon proximity to infection or a combination of the two approaches.

Once these agents are initialised, an outbreak (source) vertex is selected from the graph and the agent at that location is moved to the ‘infected’ compartment of the model. Then, a defensive move is made, which is adapted to account for the inherent individual protection ratings. Currently, there are three main defence strategies that are deployed and two further strategies that can be deployed for comparisons.

3.3 Graph-based compartmental models

Compartmental models are mathematical ways of simulating how compartments of a population interact. This involves systems of equations describing the behaviour of each compartment and then seeing how each compartment interacts with the others. These compartments can describe many states an individual (typically a person or an animal) can be in - for instance, we could use predator/prey compartments to simulate a hunting situation or susceptible/infected/recovered compartments to model disease spread.

3.3.1 Standard *SIR* model with fixed population

The SIR Model is a compartmental epidemiological model with three compartments (generally referred to as ‘states’) related to an epidemic: *susceptible*, *infected* and *recovered*. We define

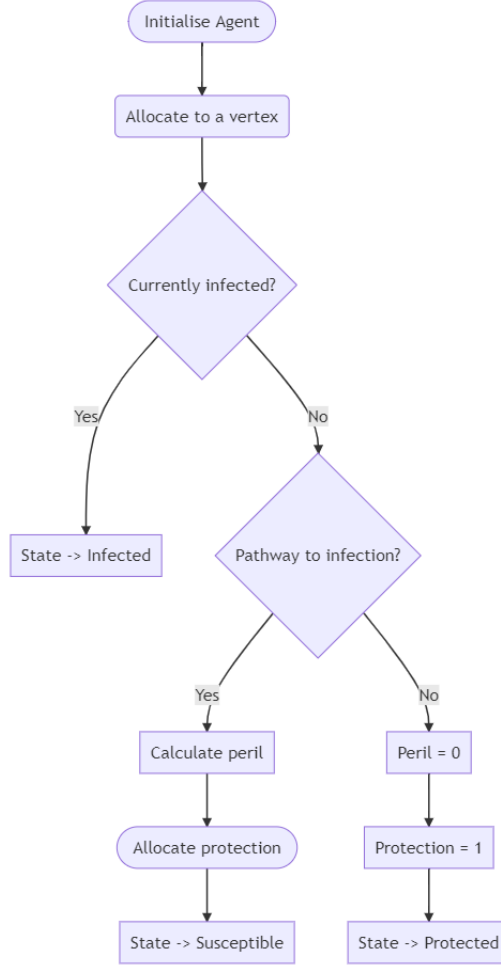


Figure 5: Agency initialisation

$S(t)$ as the number of people who do not currently have but are able to contract the infection at time t , $I(t)$ as individuals who currently have the disease and are infectious and finally $R(t)$ as those who have had the disease and subsequently recovered, granting them at least some level of immunity in certain contexts. For a fixed population N , we have that $S(t) + I(t) + R(t) = N$ - that is, we assume a fixed population where we do not wish to consider vital dynamics, usually when an epidemic is short-lived. Then, for β and γ the rates of infection and recovery respectively, the standard SIR model without vital dynamics (birth and death rates) is given as follows:

$$\frac{dS}{dt} = -\beta \frac{SI}{N} \quad (1)$$

$$\frac{dI}{dt} = \beta \frac{SI}{N} - \gamma I \quad (2)$$

$$\frac{dR}{dt} = \gamma I - \mu R \quad (3)$$

We generally aren't much interested in the expression for $\langle \dot{R} \rangle$, since we require that $\langle \dot{S} \rangle + \langle \dot{I} \rangle + \langle \dot{R} \rangle = 0$ meaning we can always find the third probability as the complement of the sum of the other two probabilities. In much of the literature, the convention is for this reason to only give the first two equations.

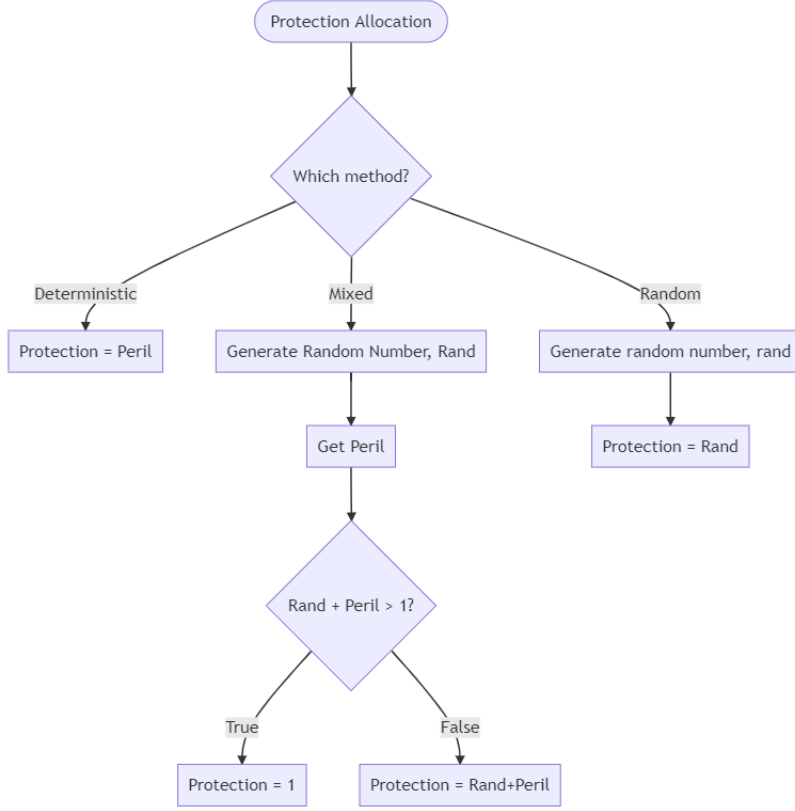


Figure 6: Protection allocation

3.3.2 Extending the *SIR* model to graphs

In order to extend our *SIR* model to network graphs, we first examine the probability of an agent being in a given class: let $\langle A_i \rangle$ represent the time-independent probability of person i being in state A , meaning that the expression of the form $\langle A_i B_i \rangle$ represents the (again, time-independent) probability of individuals i and j being in states A and B respectively [7]. We begin with a contact network, where vertices represent individuals and the edges between them represent social contact which may serve as an infection pathway. Then, the adjacency matrix G of this network is constructed by assigning $G_{ij} = 1$ when i and j share an edge and $G_{ij} = 0$ otherwise.² Then, we extend this contact network to a transmission network: let β_i represent the per-link infection rate for individual i and γ_i represent the recovery rate for i . For the transmission matrix T , we assign $T_{ij} = \beta_i$ if there is a route of infection between i and j and $T_{ij} = 0$ otherwise. Often, we will consider unweighted and undirected graphs, but in general T_{ij} may not equal T_{ji} .

We now note that we can replace β_i with a term involving such a transmission matrix of a network in order to begin extending the usual *SIR* model into a network realm. Using the substitution $\beta_i \frac{SI}{N} = \sum_{j=1}^N T_{ij} \langle S_i I_j \rangle$, the equations become

$$\begin{aligned}
 \langle \dot{S}_i \rangle &= - \sum_{j=1}^N T_{ij} \langle S_i I_j \rangle \\
 \langle \dot{I}_i \rangle &= \sum_{j=1}^N T_{ij} \langle S_i I_j \rangle - \gamma_i \langle I \rangle \\
 \langle \dot{R}_i \rangle &= \gamma_i \langle I \rangle,
 \end{aligned}$$

²Because we are infrequently interested in self-transmission, we often set $G_{ii} = 0$.

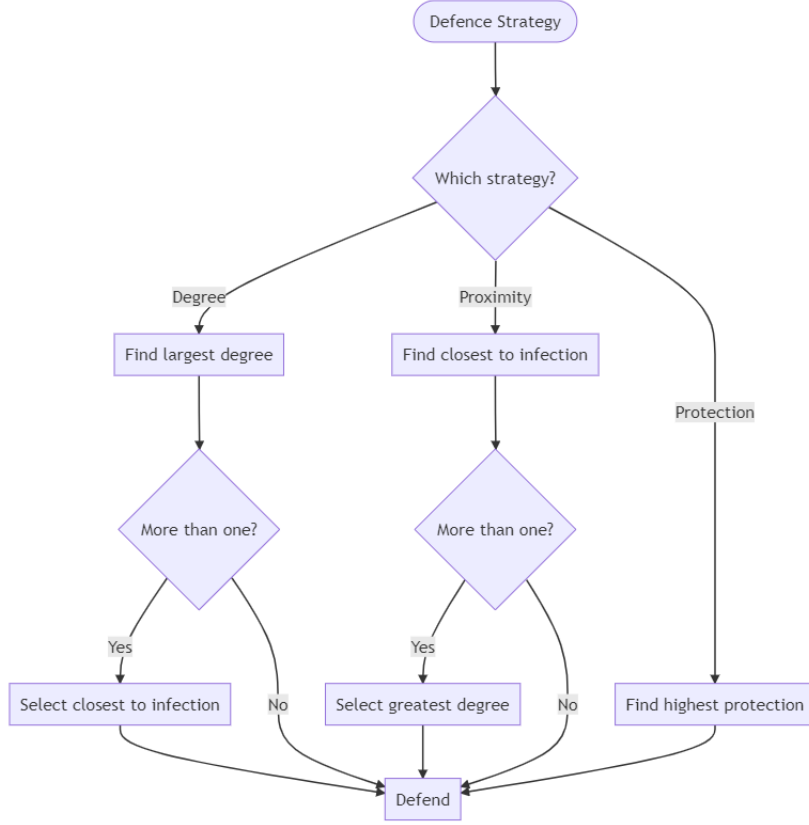


Figure 7: Defence strategies

which are the evolution equations given in [7].

3.3.3 Adding a new state to the model

Let ζ_i be the probability that we defend individual i . This can be determined in a number of different ways and we propose that a good candidate for this would be an algorithmic approach.³ Similarly, let α_i represent the efficacy of the protection measure for individual i , which may decay over time and vary from person to person (for instance, the protection could be more effective in certain age groups than in others). Using these rates of protection and effectiveness, for fixed population size the differential equations become:

$$\langle \dot{S}_i \rangle = \alpha_i \langle P_i \rangle - \sum_{j=1}^N T_{ij} \langle S_i I_j \rangle - \zeta_i \langle S_i \rangle \quad (4)$$

$$\langle \dot{I} \rangle = \sum_{j=1}^N T_{ij} \langle S_i I_j \rangle - \gamma_i \langle I \rangle \quad (5)$$

$$\langle \dot{R}_i \rangle = \gamma_i \langle I \rangle \quad (6)$$

$$\langle \dot{P}_i \rangle = \zeta_i \langle S_i \rangle - \alpha_i \langle P_i \rangle. \quad (7)$$

³That is, determine the best candidates for defence each turn and distribute some given probability across them by the expected benefit in containing the infection gained by defending each vertex.

Accounting for vital dynamics, with a birth and death rate (for simplicity) of μ , these equations are:

$$\langle \dot{S}_i \rangle = \alpha_i \langle P_i \rangle - \sum_{j=1}^N T_{ij} \langle S_i I_j \rangle + \mu N - \mu \langle S_i \rangle - \zeta_i \langle S_i \rangle \quad (8)$$

$$\langle \dot{I} \rangle = \sum_{j=1}^N T_{ij} \langle S_i I_j \rangle - \gamma_i \langle I \rangle - \mu \langle I_i \rangle \quad (9)$$

$$\langle \dot{R}_i \rangle = \gamma_i \langle I \rangle + \mu \langle R_i \rangle \quad (10)$$

$$\langle \dot{P}_i \rangle = \zeta_i \langle S_i \rangle - \alpha_i \langle P_i \rangle - \mu \langle P_i \rangle. \quad (11)$$

3.3.4 Results for total system of equations

As an example, we consider the ‘triangle network’ - a loop of three nodes. The equations required to precisely express the system *SIR* dynamics of this network are as follows [7]:

$$6 \text{ singles: } \langle \dot{S}_1 \rangle, \langle \dot{S}_2 \rangle, \langle \dot{S}_3 \rangle, \langle \dot{I}_1 \rangle, \langle \dot{I}_2 \rangle, \langle \dot{I}_3 \rangle. \quad (12)$$

$$6 \text{ doubles: } \langle \dot{S}_1 I_2 \rangle, \langle \dot{I}_1 S_2 \rangle, \langle \dot{S}_1 I_3 \rangle, \langle \dot{I}_1 S_3 \rangle, \langle \dot{S}_2 I_3 \rangle, \langle \dot{I}_2 S_3 \rangle. \quad (13)$$

$$6 \text{ triples: } \langle \dot{S}_1 I_2 I_3 \rangle, \langle \dot{S}_1 I_2 S_3 \rangle, \langle \dot{S}_1 S_2 I_3 \rangle, \langle \dot{I}_1 S_2 S_3 \rangle, \langle \dot{I}_1 I_2 S_3 \rangle, \langle \dot{I}_1 S_2 I_3 \rangle. \quad (14)$$

Now, using the equations for the *SIRP* model, we have the following equation requirements:

$$9 \text{ singles: } (12) \text{ and } \langle \dot{P}_1 \rangle, \langle \dot{P}_2 \rangle, \langle \dot{P}_3 \rangle.$$

$$18 \text{ doubles: } (13) \text{ and } \langle \dot{S}_1 P_2 \rangle, \langle \dot{P}_1 S_2 \rangle, \langle \dot{I}_1 P_2 \rangle, \langle \dot{P}_1 I_2 \rangle, \langle \dot{S}_1 P_3 \rangle, \langle \dot{P}_1 S_3 \rangle, \\ \langle \dot{I}_1 P_3 \rangle, \langle \dot{P}_1 I_3 \rangle, \langle \dot{S}_2 P_3 \rangle, \langle \dot{P}_2 S_3 \rangle, \langle \dot{I}_2 P_3 \rangle, \langle \dot{P}_2 I_3 \rangle.$$

$$24 \text{ triples: } (14) \text{ and } \langle \dot{S}_1 S_2 P_3 \rangle, \langle \dot{S}_1 P_2 S_3 \rangle, \langle \dot{S}_1 I_2 P_3 \rangle, \langle \dot{S}_1 P_2 I_3 \rangle, \langle \dot{S}_1 P_2 P_3 \rangle, \langle \dot{I}_1 S_2 P_3 \rangle, \\ \langle \dot{I}_1 P_2 S_3 \rangle, \langle \dot{I}_1 I_2 P_3 \rangle, \langle \dot{I}_1 P_2 I_3 \rangle, \langle \dot{I}_1 P_2 P_2 \rangle, \langle \dot{P}_1 S_2 S_3 \rangle, \langle \dot{P}_1 S_2 I_3 \rangle, \\ \langle \dot{P}_1 I_2 S_3 \rangle, \langle \dot{P}_1 I_2 I_3 \rangle, \langle \dot{P}_1 P_2 I_3 \rangle, \langle \dot{P}_1 P_2 S_3 \rangle, \langle \dot{P}_1 S_2 P_3 \rangle, \langle \dot{P}_1 I_2 P_3 \rangle.$$

Note that the reason we dispense with the cases of all three vertices being in the same state is that this would not result in any dynamics - no vertices would ever change state in this case.

3.3.5 Implementation

We have been working on an implementation of the above work in equations generation. Our goal is to produce code that can accept a particular graph, for instance as a CSV file, and determine the number of equations that could be required to fully describe a compartmental model (for instance, *SIR* or *SIRP*) on that graph. This could be by providing an upper and a lower bound, if the exact graph structure is unknown, or by providing the exact number of equations if the graph is small enough for this to be exactly calculated. Then, with this information, the user can then request the software prints the full list of differential equations that exactly describe the epidemic dynamics using an algorithmic approach to generation. This work is not currently completed, but we aim to have completed this in the coming months when the nuances of closures is fully understood and algorithmically implemented.

4 Research Plan

4.1 Goals

Over the next year, we hope to extend the two strands of work we have been pursuing with a number of goals and milestones in mind. In the more formal, mathematical side of our work, we aim to achieve the following:

- Formalise a probabilistic graph model that can be implemented in the PRISM model checking language.
- Complete and verify the equations generation work that we have started over the last year.
- Write down the algorithmic approach used in generating required differential equations for Markovian compartmental epidemic graph models.

Further, in the experimental side of our work, we aim to achieve the following:

- Further generalise the current implementation to accept further parameters and output requested results.
- Use the large computing capabilities of the FATA nodes to run many more models and analyse results.
- Implement, test and explore further defence strategies in the implementation, using this to reason about optimal defence candidates in different contexts.
- Write down a series of (provable) statements regarding defence strategies in this implementation on various graph classes.
- Use real-world data to model different epidemic scenarios and contextualise defence strategies.
- Explore integer programming approaches, such as provided in Finbow and MacGillivray [2], and identify similar approaches for our extended model.

4.2 Resources required

4.3 Measures of success

4.4 Timeline

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