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Lab 6 report

Video:

<https://drive.google.com/file/d/1JpMFCrfzEXQnEtRLcaOmZcUzUCCbqKwI/view?usp=sharing>

Description:

In this lab, we were supposed to have our keyboard generate different notes of frequencies. To do this, I set all the columns of the keyboard to inputs using the PortB and all the rows of the keyboard to outputs using PortD. I also set pin C1 as output because I used this pin to connect the Aux to the AVR board. I also set my timer to CTC mode as well. Inside the infinite while loop, I declare a 2D int array that is called key. This will represent every button on the keyboard as an int with button 1 being int 0 and button D being int 15. Then for the following code, I used the same process as the keyboard scan function from lab 4, where you use 2 for loops, one for row and one for column to check if the button is being pressed. Then if the button is pressed, the program will go through the function keypad with that button as the parameter. In the keypad function, I use a switch statement to show what would happen for each button being pressed. Each button will be represented in a case and if that button is pressed, the function will go to that case. In each case, I set the OCR0A value to represent the frequency of that button. I calculated the frequencies of each button through the equation presented in the lab 6 description/slides. Then I set the OCR0B value to represent 50% duty cycle, which will just be $OCR0A * (\frac{1}{2})$. I then set the prescaler for the button that I evaluated through calculation as well. I do this by manipulating the TCCR0B register. Cases 0 through 13 will use a prescaler of 256 but cases 14 and 15 will use a prescaler of 64. Then in each case, I turn C1 on and use a busy while loop to wait for the overflow event of OCR0B. I then reset the overflow flag for OCR0B. This process of using this busy while loop and resetting the overflow flag checks if the timer finishes. Then I turn C1 off and do the whole process again but with OCR0A. This process will utilize the overflow process for the whole cycle. Then I use a break statement to end the case and leave the switch statement.

Result:

After hooking up my keypad to my AVR and hooking up the Aux to my AVR, I plugged my headphones into the Aux. Then I soon pressed the button on the keypad which generated sound at different frequencies. Hence, all the buttons generated slightly different sounds from one another.

Source code:

```
/*  
 * LAB6.c  
 *  
 * Created: 3/20/2020 10:49:34 PM
```

* Author : Ethan

*/

```
#define F_CPU 16000000
```

```
#include <avr/io.h>
```

```
#include <util/delay.h>
```

```
#define BAUD 9600
```

```
#define ON PORTC |= (1<<1);//
```

```
#define OFF PORTC &=~(1<<1);//
```

```
#define MYUBBR ((F_CPU)/(BAUD * 16UL) - 1) //Use UBBR for USART baud rate
```

```
//void init_uart();
```

```
void keypad (int key);
```

```
/*void init_uart() {
```

```
    UBBR0H = (MYUBBR >> 8); //set UBBR high
```

```
    UBBR0L = (MYUBBR); //set UBBR low
```

```
    //UCSR0C = (1 << UCSZ00) | (1 << UCSZ01) | (0 << USBS0); // 8-bit 1-stop bit mode
```

```
    UCSR0B = (1 << TXEN0); //enable transmitter
```

```
}*/
```

```
int main(void)
```

```
{
```

```
    //init_uart();
```

```
    DDRB &=~ (1<<0)&~(1<<1)&~(1<<2)&~(1<<3); //inputs
```

```
    DDRD |= (1<<4|1<<5|1<<6|1<<7); //output
```

```
    PORTB |= (1<<0) | (1<<1) | (1<<2) | (1<<3); //pullups
```

```
    DDRC|= (1<<1); //set C1 as output
```

```
    TCCR0A &= ~(1<<WGM00) &~(1<<WGM02); //set timer to CTC mode
```

```
    TCCR0A |= (1<<WGM01); //set timer to CTC mode
```

```
    while (1)
```

```
    {
```

```
        int key[4][4] = {{0, 1, 2, 3 }, {4, 5, 6, 7}, {8, 9, 10, 11}, {12, 13, 14, 15}}; //keypad buttons
```

```
        PORTD |= (1<<4)|(1<<5)|(1<<6)|(1<<7); //set rows to high
```

```
        for(int r=4; r<8; r++) //loop through rows
```

```
        {
```

```
            PORTD &= ~(1<<r); //set this row to low, to check row
```

```
            for(int c=0; c<4; c++) //loop through column
```

```

        {
            if((PINB & (1<<c))==0)//find key that is pressed
            {
                keypad(key[r-4][c]); //transmit key to GPIO
            }
        }
        PORTD |= (1<<r); //set row back to high
    }

}

}

void keypad (int key)
{
    switch(key)
    {
        case 0:
            OCR0A = 0x8D; //represents 440MHz
            OCR0B = 0x46; //50% duty cycle
            TCCR0B &= ~(1<<CS01) &~ (1<<CS00);
            TCCR0B |= (1<<CS02); //256 prescale
            ON;
            while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B
overflow event
            TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag
            OFF;
            while(TIFR0 & ~(1<<OCF0A))==0){}; //busy while loop, wait for OCR0A
overflow event
            TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag
            break;

        case 1:
            OCR0A = 0x85; //represents 466.16MHz
            OCR0B = 0x42; //50% duty cycle
            TCCR0B &= ~(1<<CS01) &~ (1<<CS00);
            TCCR0B |= (1<<CS02); //256 prescale
            ON;
            while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B
overflow event

```

```

TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag
OFF;
while(TIFR0 & ~(1<<OCF0A)==0){}; //busy while loop, wait for OCR0A
overflow event
TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag
break;

case 2:
OCR0A = 0x7D; //represents 493.88MHz
OCR0B = 0x3E; //50% duty cycle
TCCR0B &= ~(1<<CS01) & ~(1<<CS00);
TCCR0B |= (1<<CS02); //256 prescale
ON;
while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B
overflow event
TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag
OFF;
while( TIFR0 & ~(1<<OCF0A)==0){}; //busy while loop, wait for OCR0A
overflow event
TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag
break;

case 3:
OCR0A = 0x76; //represents 523.3 MHz
OCR0B = 0x3B; //50% duty cycle
TCCR0B &= ~(1<<CS01) & ~(1<<CS00);
TCCR0B |= (1<<CS02); //256 prescale
ON;
while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B
overflow event
TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag
OFF;
while( TIFR0 & ~(1<<OCF0A)==0){}; //busy while loop, wait for OCR0A
overflow event
TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag
break;

case 4:
OCR0A = 0x6F; //represents 554.4 MHz

```

```

OCR0B = 0x37; //50% duty cycle
TCCR0B &= ~(1<<CS01) & ~(1<<CS00);
TCCR0B |= (1<<CS02); //256 prescale
ON;
while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B
overflow event
TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag
OFF;
while( TIFR0 & ~(1<<OCF0A)==0){}; //busy while loop, wait for OCR0A
overflow event
TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag
break;

case 5:
OCR0A = 0x69; //represents 587.3 MHz
OCR0B = 0x34; //50% duty cycle
TCCR0B &= ~(1<<CS01) & ~(1<<CS00);
TCCR0B |= (1<<CS02); //256 prescale
ON;
while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B
overflow event
TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag
OFF;
while( TIFR0 & ~(1<<OCF0A)==0){}; //busy while loop, wait for OCR0A
overflow event
TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag
break;

case 6:
OCR0A = 0x63; //represents 622.3 MHz
OCR0B = 0x31; //50% duty cycle
TCCR0B &= ~(1<<CS01) & ~(1<<CS00);
TCCR0B |= (1<<CS02); //256 prescale
ON;
while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B
overflow event
TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag
OFF;

```

```
while( TIFR0 & ~(1<<OCF0A)==0){};//busy while loop, wait for OCR0A  
overflow event
```

```
TIFR0|= (1<<OCF0A);//reset OCR0A overflow flag  
break;
```

```
case 7:
```

```
OCR0A = 0x5D; //represents 659.25 MHz
```

```
OCR0B = 0x2E;//50% duty cycle
```

```
TCCR0B &= ~(1<<CS01) & ~(1<<CS00);
```

```
TCCR0B |= (1<<CS02);//256 prescale
```

```
ON;
```

```
while((TIFR0 & ~(1<<OCF0B))==0){};//busy while loop, wait for OCR0B  
overflow event
```

```
TIFR0|= (1<<OCF0B);//reset OCR0B overflow flag
```

```
OFF;
```

```
while( TIFR0 & ~(1<<OCF0A)==0){};//busy while loop, wait for OCR0A  
overflow event
```

```
TIFR0|= (1<<OCF0A);//reset OCR0A overflow flag  
break;
```

```
case 8:
```

```
OCR0A = 0x58; //represents 698.46 MHz
```

```
OCR0B = 0x2C;//50% duty cycle
```

```
TCCR0B &= ~(1<<CS01) & ~(1<<CS00);
```

```
TCCR0B |= (1<<CS02);//256 prescale
```

```
ON;
```

```
while((TIFR0 & ~(1<<OCF0B))==0){};//busy while loop, wait for OCR0B  
overflow event
```

```
TIFR0|= (1<<OCF0B);//reset OCR0B overflow flag
```

```
OFF;
```

```
while( TIFR0 & ~(1<<OCF0A)==0){};//busy while loop, wait for OCR0A  
overflow event
```

```
TIFR0|= (1<<OCF0A);//reset OCR0A overflow flag  
break;
```

```
case 9:
```

```
OCR0A = 0x53; //represents 739.99 MHz
```

```
OCR0B = 0x29;//50% duty cycle
```

```
TCCR0B &= ~(1<<CS01) & ~(1<<CS00);
```

```

TCCR0B |= (1<<CS02); //256 prescale
ON;
while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B
overflow event
TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag
OFF;
while( TIFR0 & ~(1<<OCF0A)==0){}; //busy while loop, wait for OCR0A
overflow event
TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag
break;

case 10:
OCR0A = 0x4E; //represents 783.99 MHz
OCR0B = 0x27; //50% duty cycle
TCCR0B &= ~(1<<CS01) & ~(1<<CS00);
TCCR0B |= (1<<CS02); //256 prescale
ON;
while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B
overflow event
TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag
OFF;
while( TIFR0 & ~(1<<OCF0A)==0){}; //busy while loop, wait for OCR0A
overflow event
TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag
break;

case 11:
OCR0A = 0x4A; //represents 830 MHz
OCR0B = 0x25; //50% duty cycle
TCCR0B &= ~(1<<CS01) & ~(1<<CS00);
TCCR0B |= (1<<CS02); //256 prescale
ON;
while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B
overflow event
TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag
OFF;
while( TIFR0 & ~(1<<OCF0A)==0){}; //busy while loop, wait for OCR0A
overflow event
TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag

```

break;

case 12:

OCR0A = 0x46; //represents 800 MHz

OCR0B = 0x23; //50% duty cycle

TCCR0B &= ~(1<<CS01) & ~(1<<CS00);

TCCR0B |= (1<<CS02); //256 prescale

ON;

while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B

overflow event

TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag

OFF;

while(TIFR0 & ~(1<<OCF0A)==0){}; //busy while loop, wait for OCR0A

overflow event

TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag

break;

case 13:

OCR0A = 0x42; //represents 932 MHz

OCR0B = 0x21; //50% duty cycle

TCCR0B &= ~(1<<CS01) & ~(1<<CS00);

TCCR0B |= (1<<CS02); //256 prescale

ON;

while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B

overflow event

TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag

OFF;

while(TIFR0 & ~(1<<OCF0A)==0){}; //busy while loop, wait for OCR0A

overflow event

TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag

break;

case 14:

OCR0A = 0xFC; //represents 988 MHz

OCR0B = 0x7E; //50% duty cycle

TCCR0B |= (1<<CS01) & ~(1<<CS00);

TCCR0B &= ~(1<<CS02); //64 prescale

ON;


```

        while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B
overflow event
    TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag
    OFF;
    while( TIFR0 & ~(1<<OCF0A)==0){}; //busy while loop, wait for OCR0A
overflow event
    TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag
    break;

case 15:
    OCR0A = 0xED; //represents 1047 MHz
    OCR0B = 0x76; //50% duty cycle
    TCCR0B |= (1<<CS01) & ~ (1<<CS00);
    TCCR0B &=~(1<<CS02); //64 prescale
    ON;
    while((TIFR0 & ~(1<<OCF0B))==0){}; //busy while loop, wait for OCR0B
overflow event
    TIFR0|= (1<<OCF0B); //reset OCR0B overflow flag
    OFF;
    while( TIFR0 & ~(1<<OCF0A)==0){}; //busy while loop, wait for OCR0A
overflow event
    TIFR0|= (1<<OCF0A); //reset OCR0A overflow flag
    break;
    }
}

```